

Common Graph Theory Problems

William Fiset

Common Graph Theory Problems

For the upcoming problems ask yourself:

Is the graph directed or undirected?

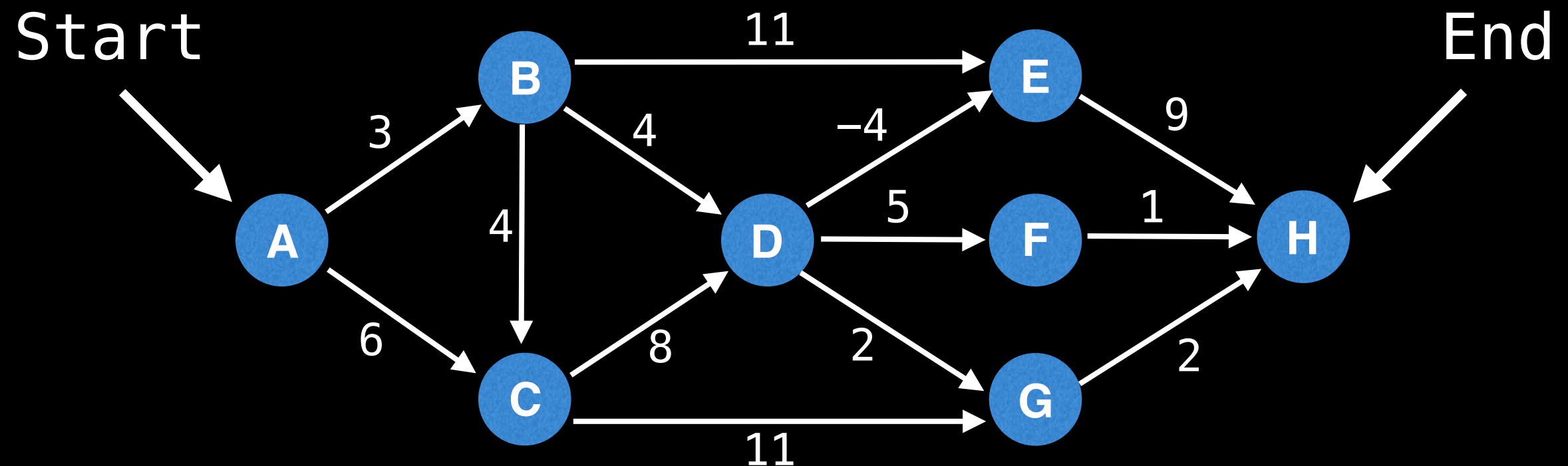
Are the edges of the graph weighted?

Is the graph I will encounter likely to be sparse or dense with edges?

Should I use an adjacency matrix, adjacency list, an edge list or other structure to represent the graph efficiently?

Shortest path problem

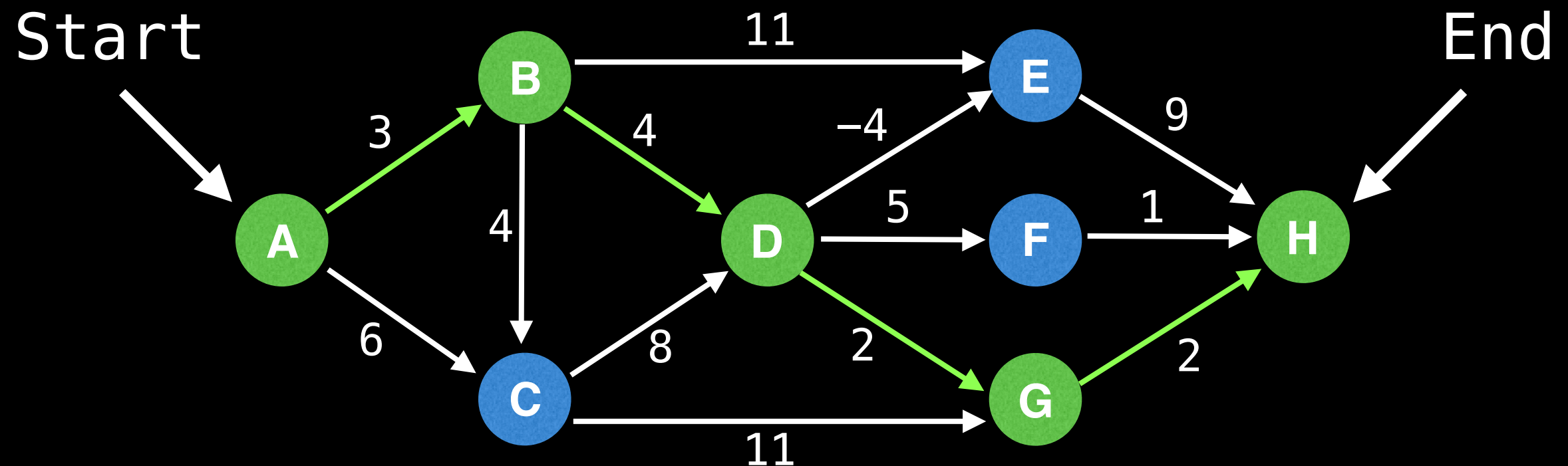
Given a weighted graph, find the shortest path of edges from node A to node B.



Algorithms: BFS (unweighted graph), Dijkstra's, Bellman-Ford, Floyd-Warshall, A*, and many more.

Shortest path problem

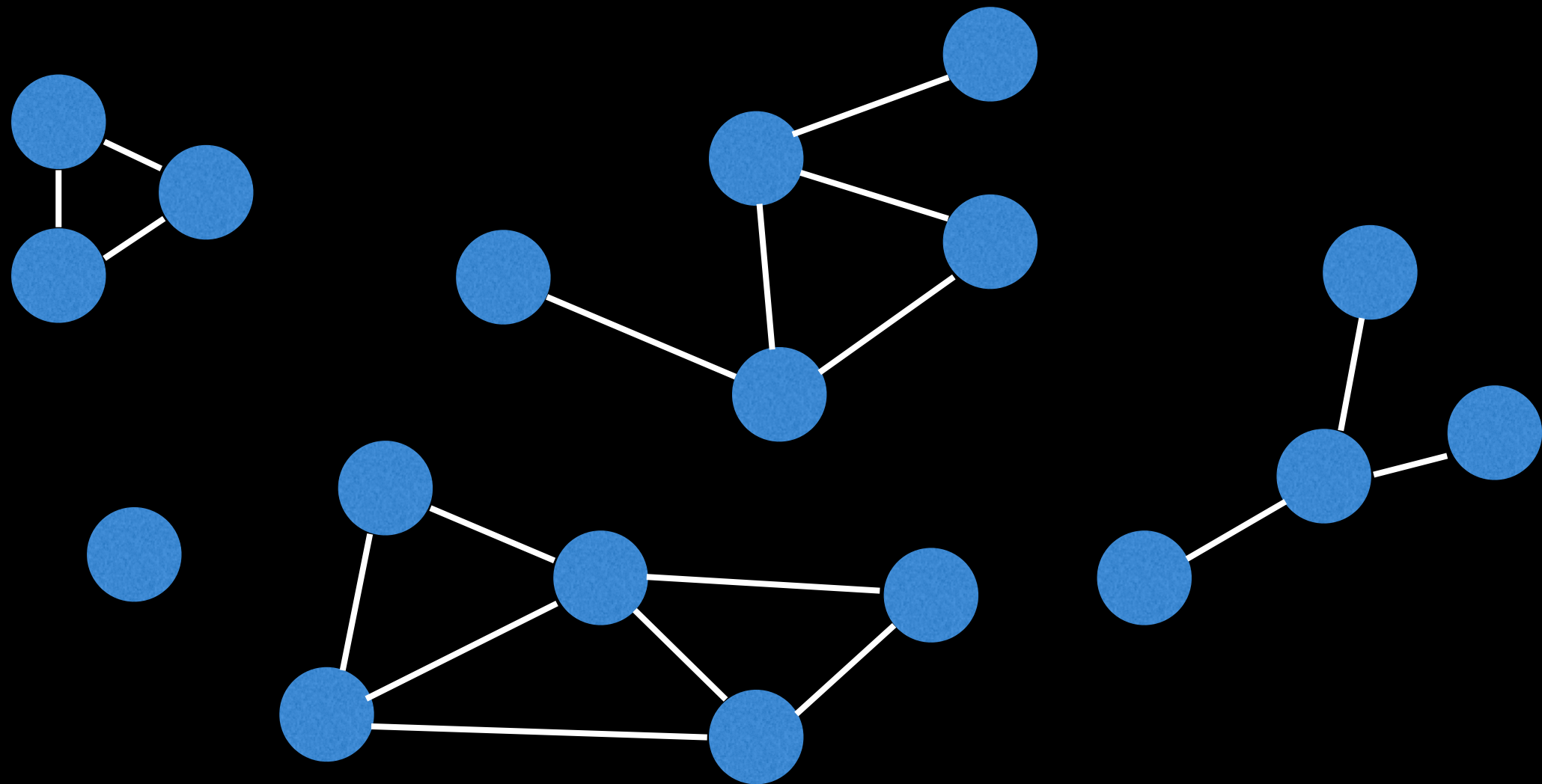
Given a weighted graph, find the shortest path of edges from node A to node B.



Algorithms: BFS (unweighted graph), Dijkstra's, Bellman-Ford, Floyd-Warshall, A*, and many more.

Connectivity

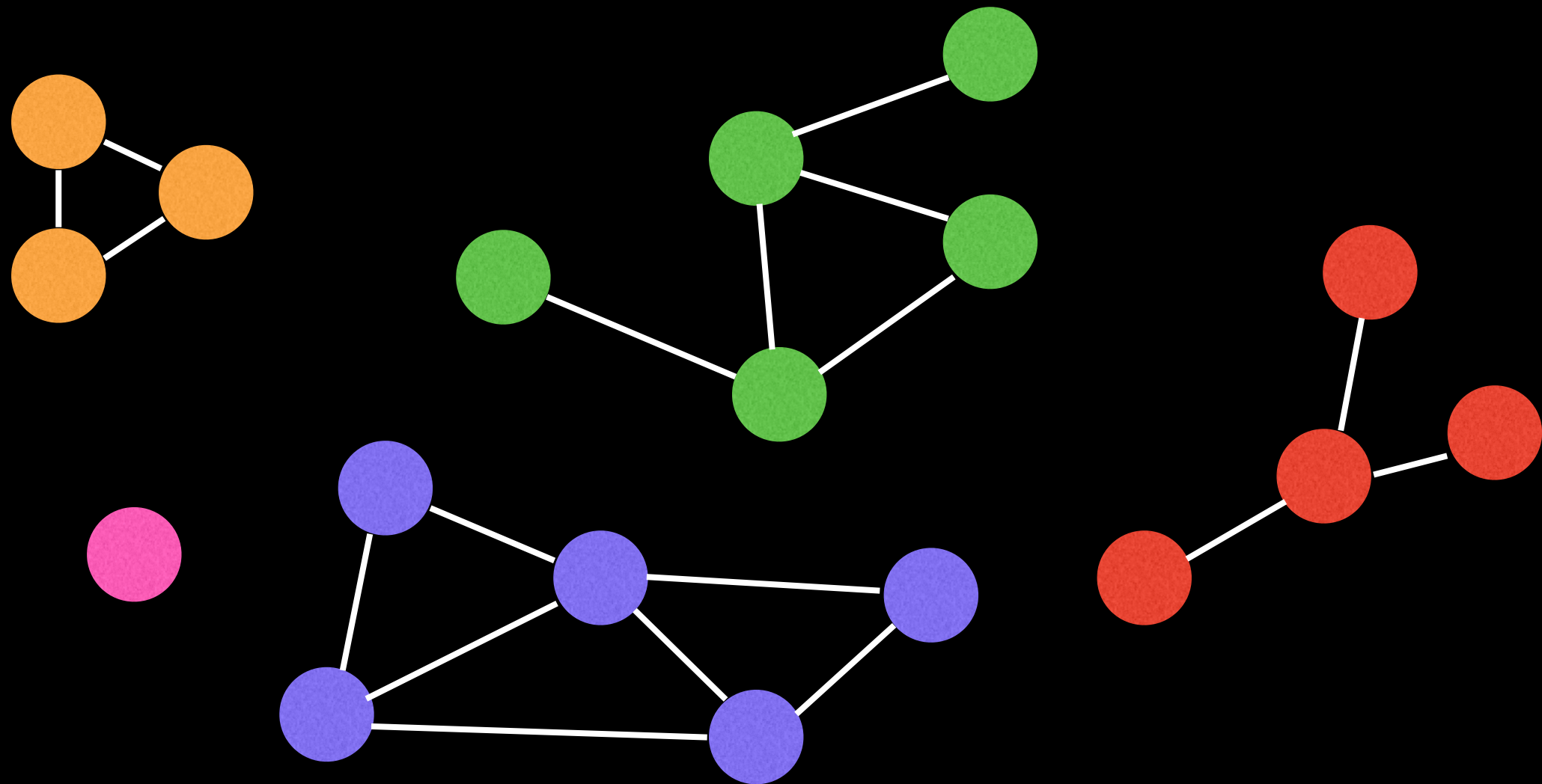
Does there exist a path between
node A and node B?



Typical solution: Use union find data
structure or any search algorithm (e.g DFS).

Connectivity

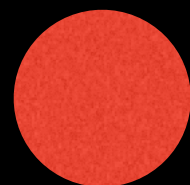
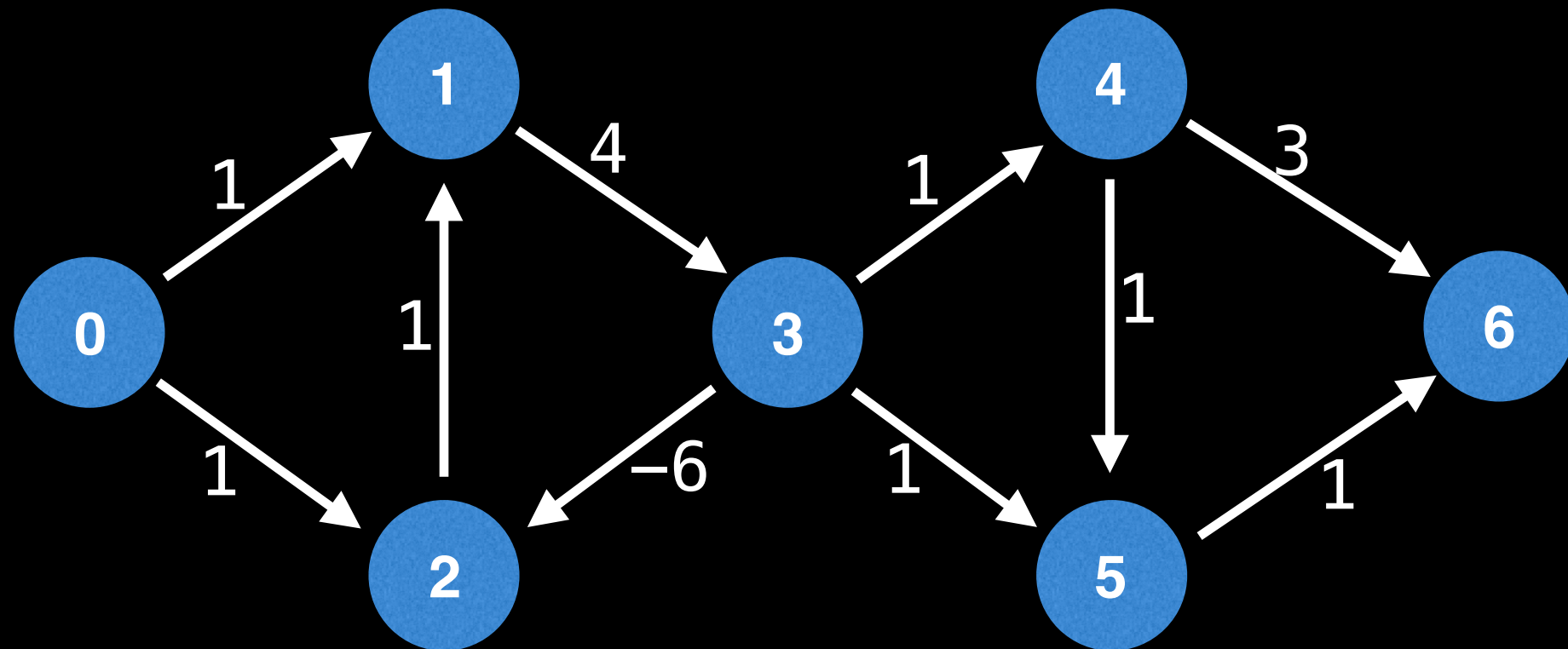
Does there exist a path between
node A and node B?



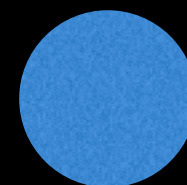
Typical solution: Use union find data
structure or any search algorithm (e.g DFS).

Negative cycles

Does my weighted digraph have any negative cycles? If so, where?



**Directly in
negative cycle**

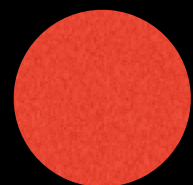
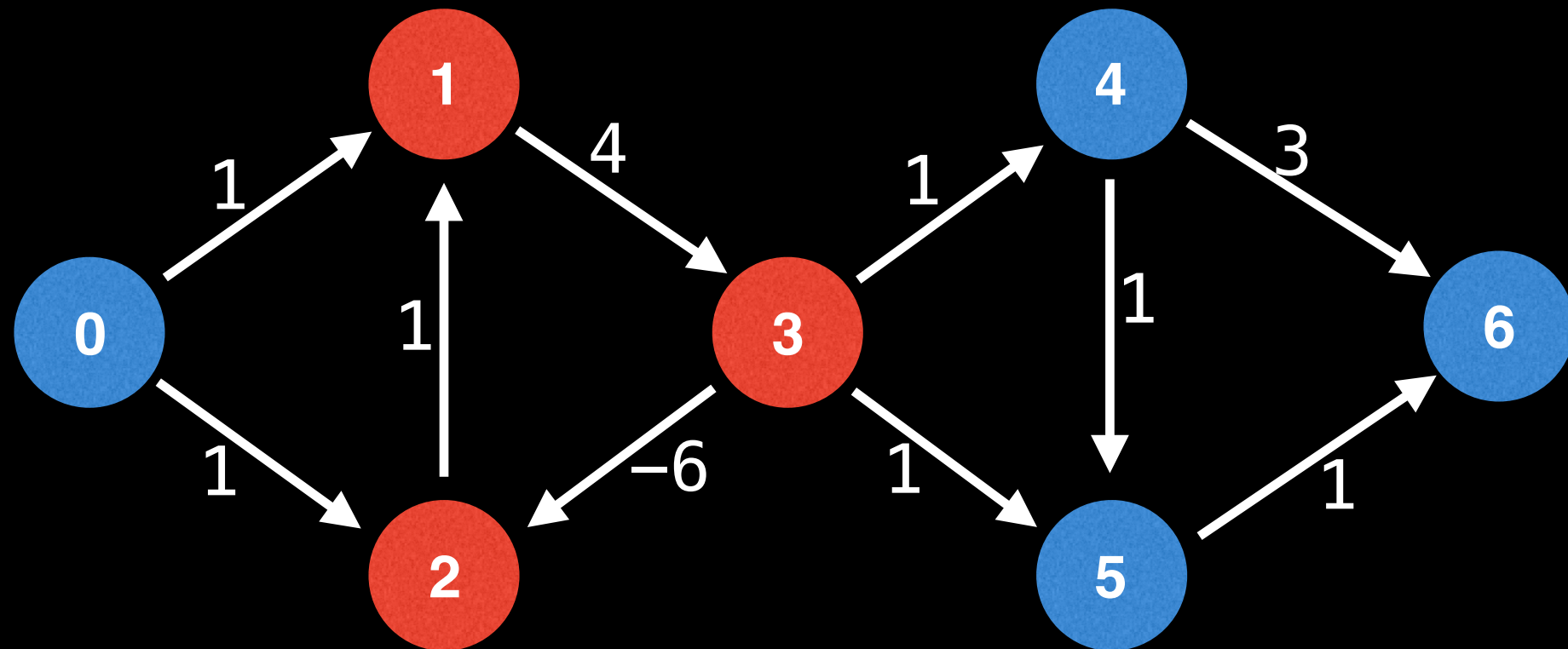


**Unaffected
node**

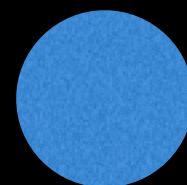
Algorithms: Bellman–Ford and Floyd–Warshall

Negative cycles

Does my weighted digraph have any negative cycles? If so, where?



Directly in
negative cycle

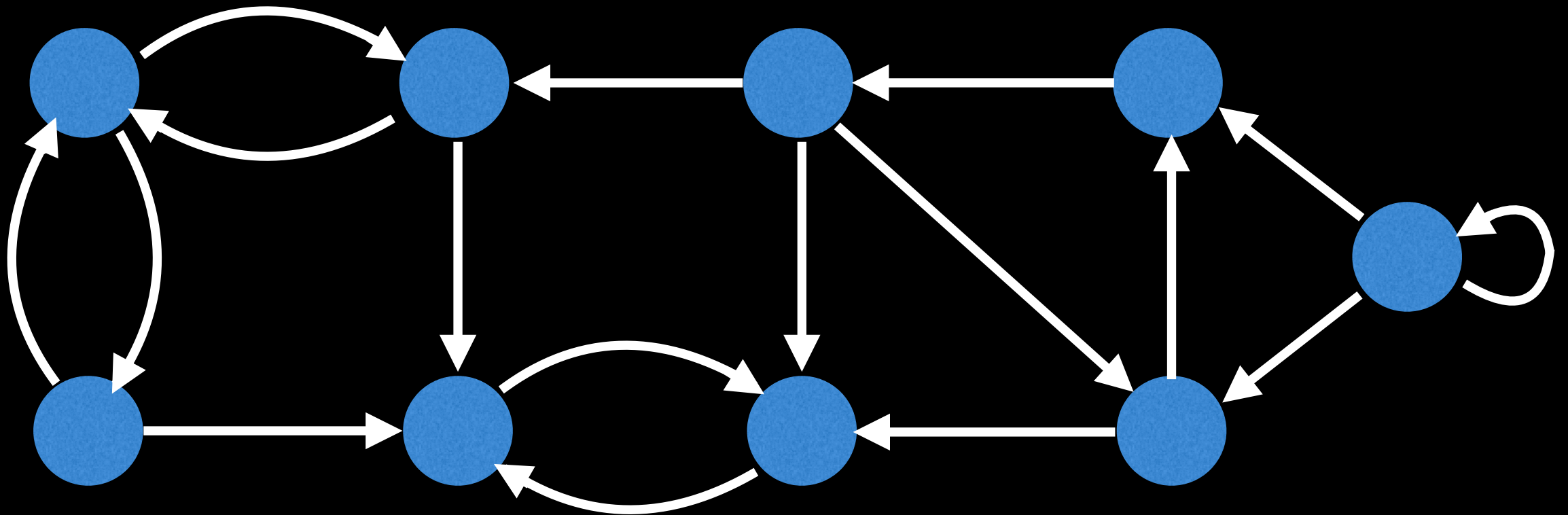


Unaffected
node

Algorithms: Bellman-Ford and Floyd-Warshall

Strongly Connected Components

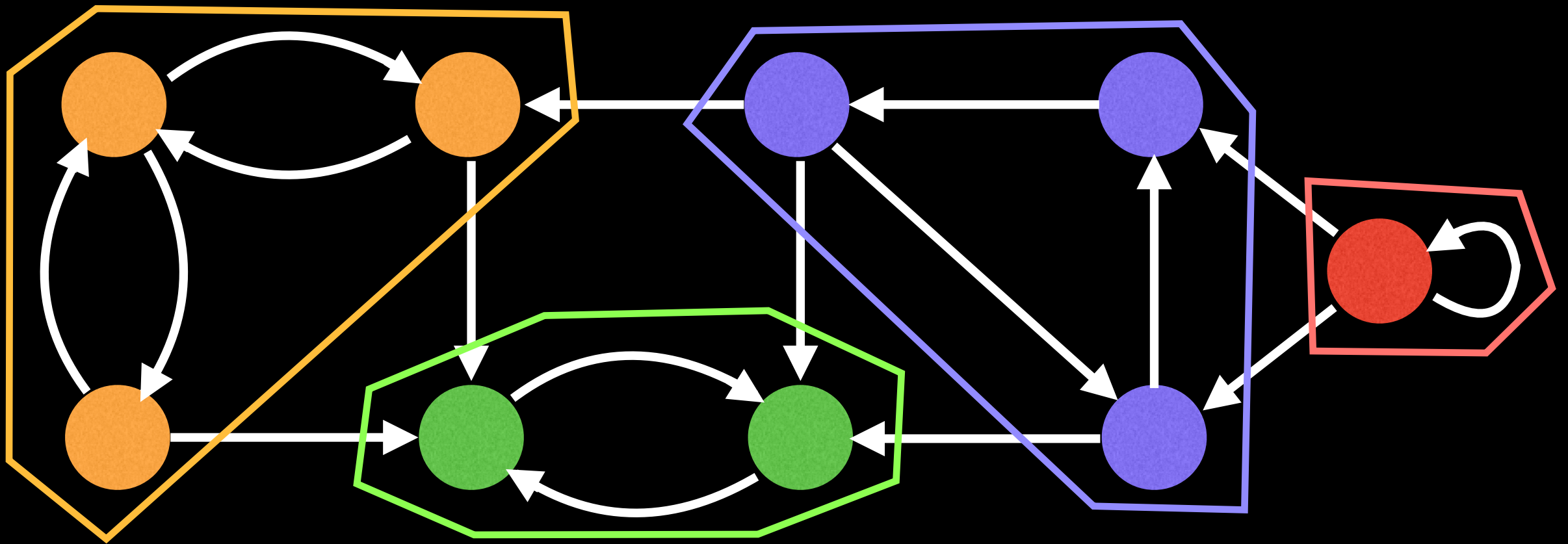
Strongly Connected Components (SCCs) can be thought of as **self-contained cycles** within a **directed graph** where every vertex in a given cycle can reach every other vertex in the same cycle.



Algorithms: Tarjan's and Kosaraju's algorithm

Strongly Connected Components

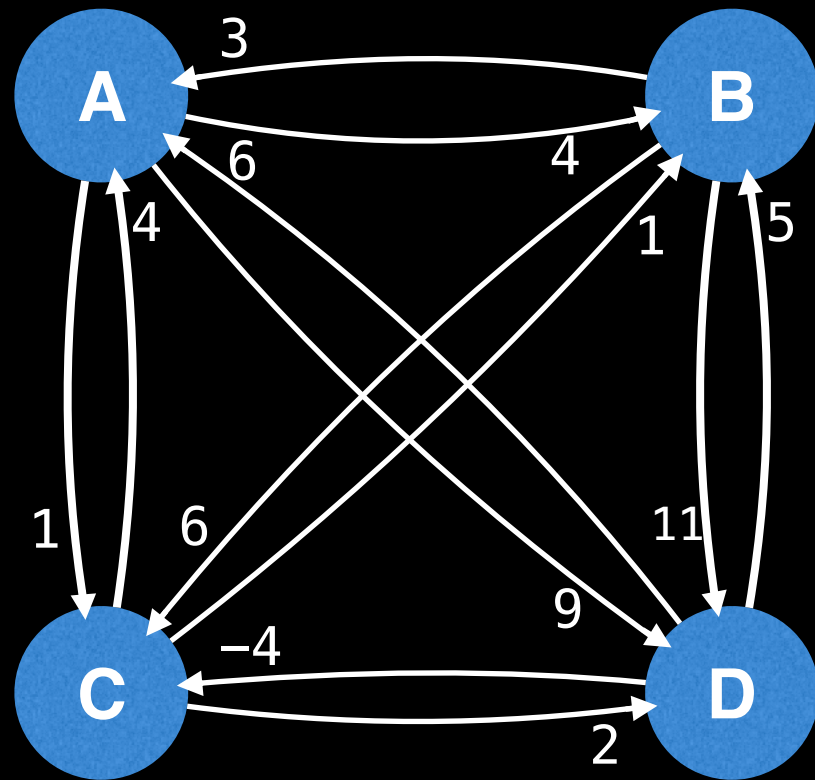
Strongly Connected Components (SCCs) can be thought of as **self-contained cycles** within a **directed graph** where every vertex in a given cycle can reach every other vertex in the same cycle.



Algorithms: Tarjan's and Kosaraju's algorithm

Traveling Salesman Problem

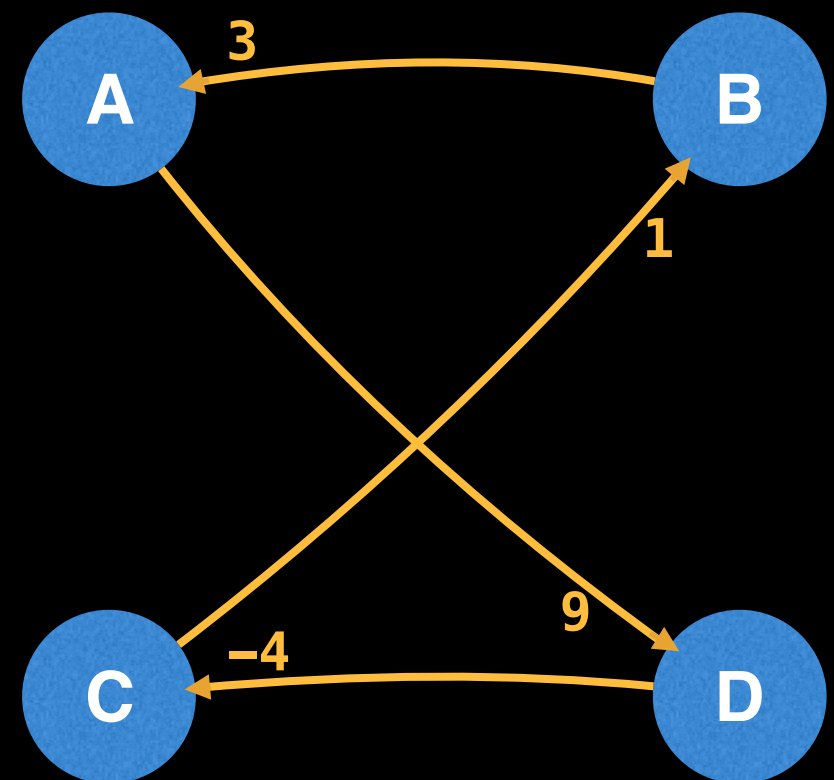
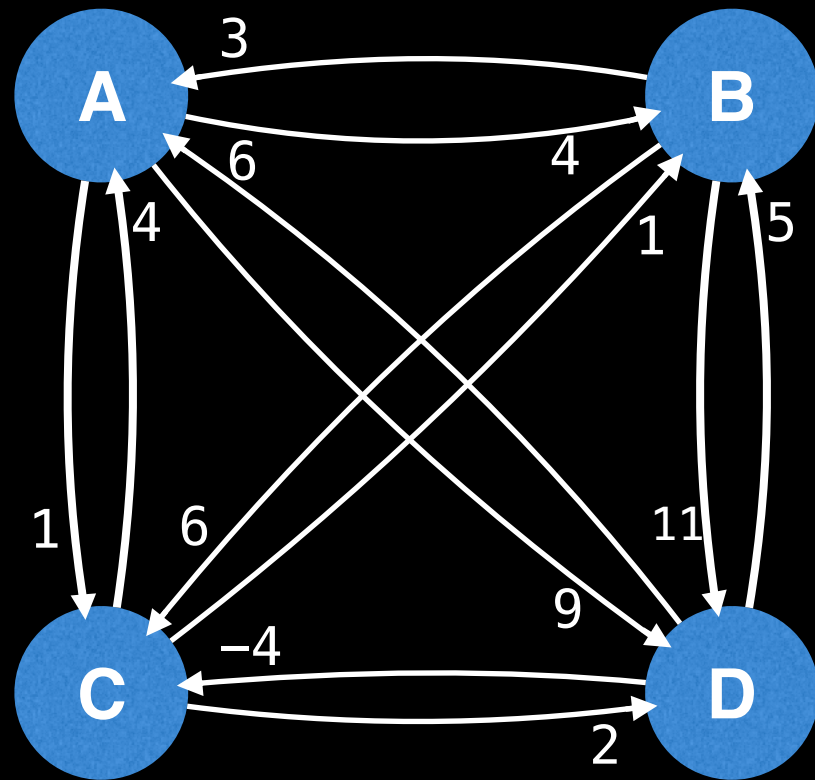
"Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city exactly once and returns to the origin city?" – Wiki



Algorithms: Held–Karp, branch and bound and many approximation algorithms

Traveling Salesman Problem

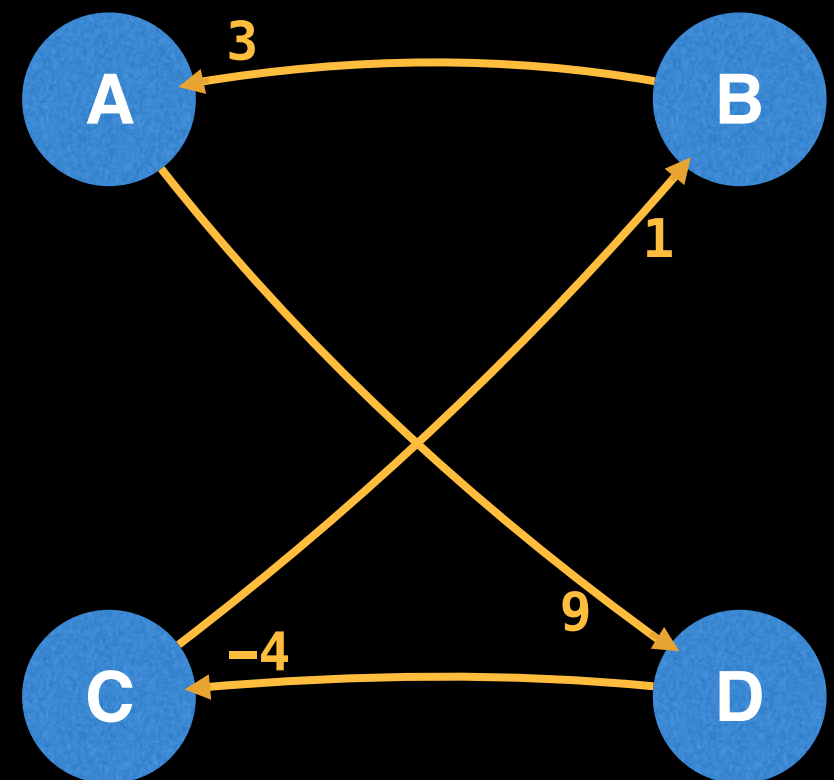
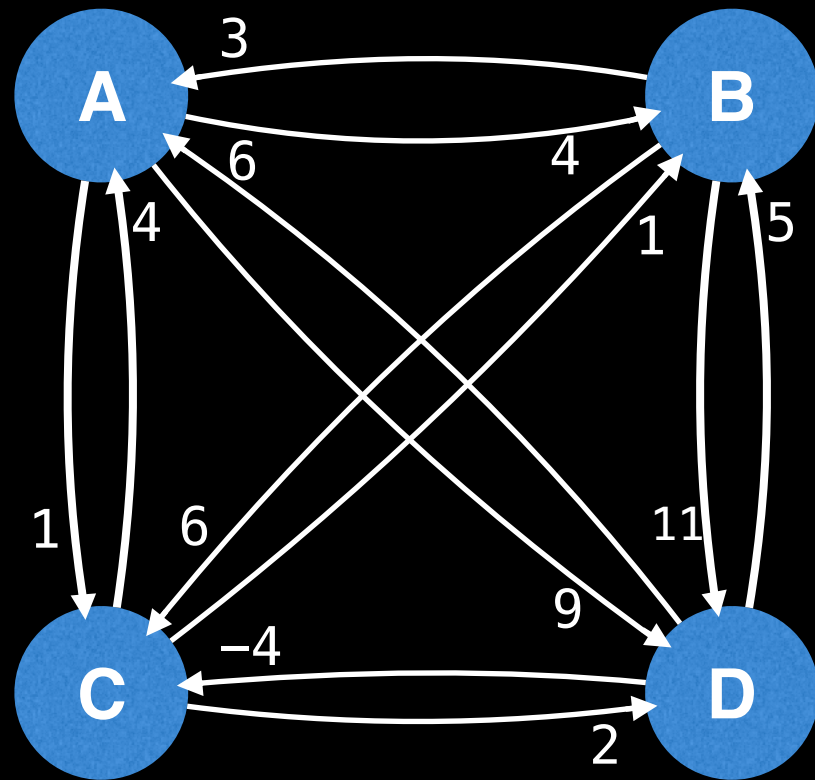
"Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city exactly once and returns to the origin city?" – Wiki



Algorithms: Held–Karp, branch and bound and many approximation algorithms

Traveling Salesman Problem

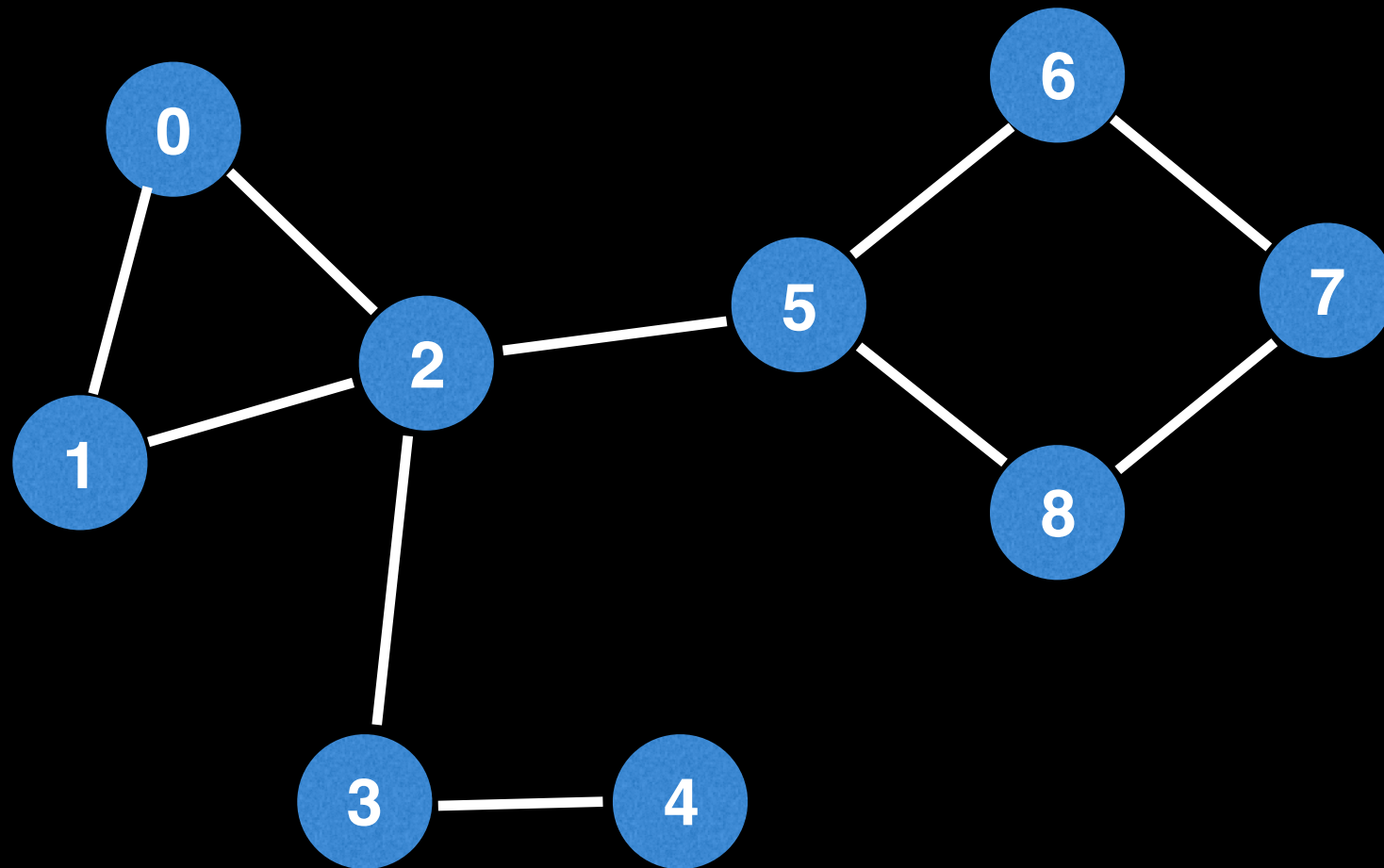
The TSP problem is NP-Hard meaning it's a very computationally challenging problem. This is unfortunate because the TSP has several very important applications.



Algorithms: Held-Karp, branch and bound and many approximation algorithms

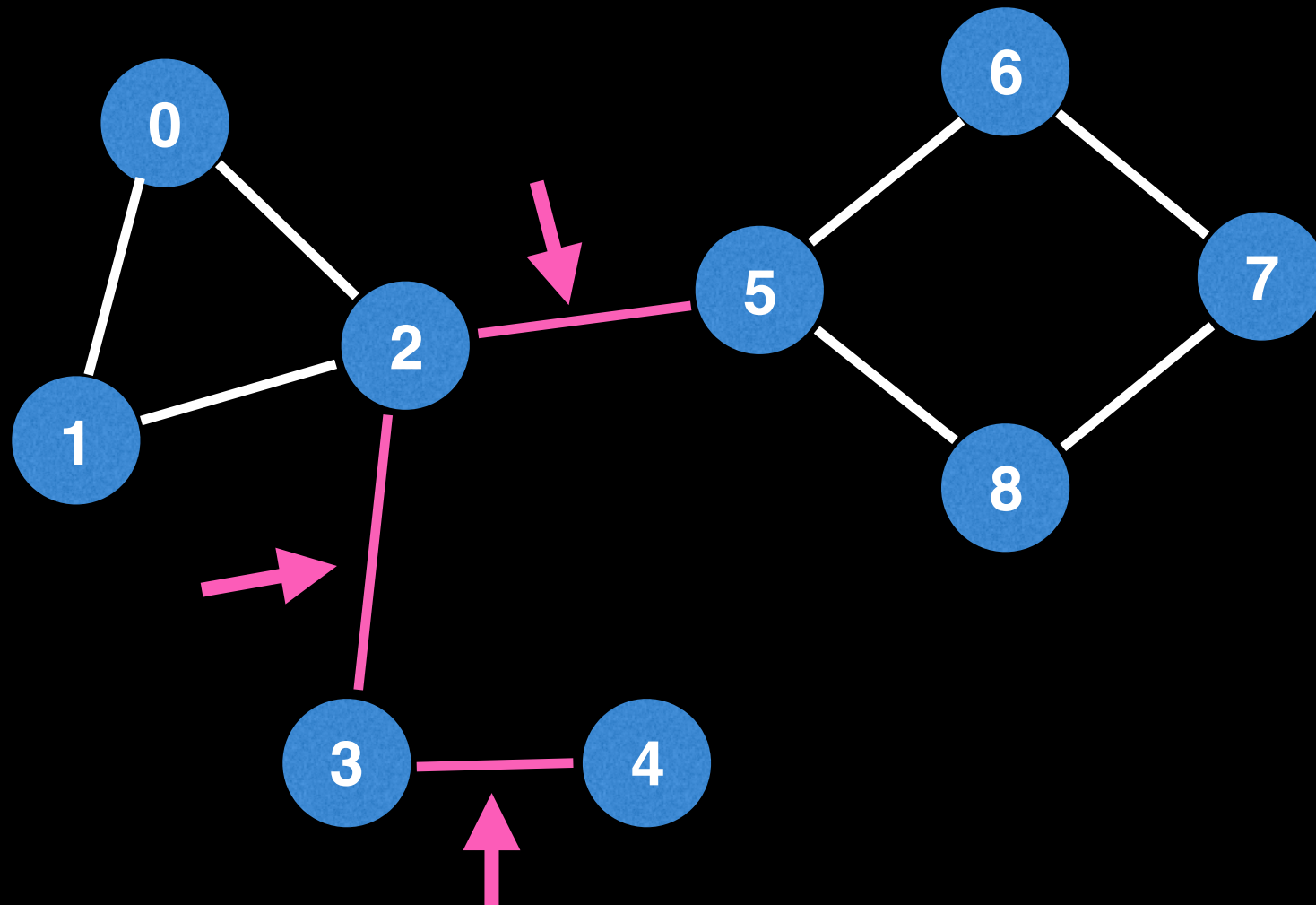
Bridges

A **bridge / cut edge** is any edge in a graph whose removal increases the number of connected components.



Bridges

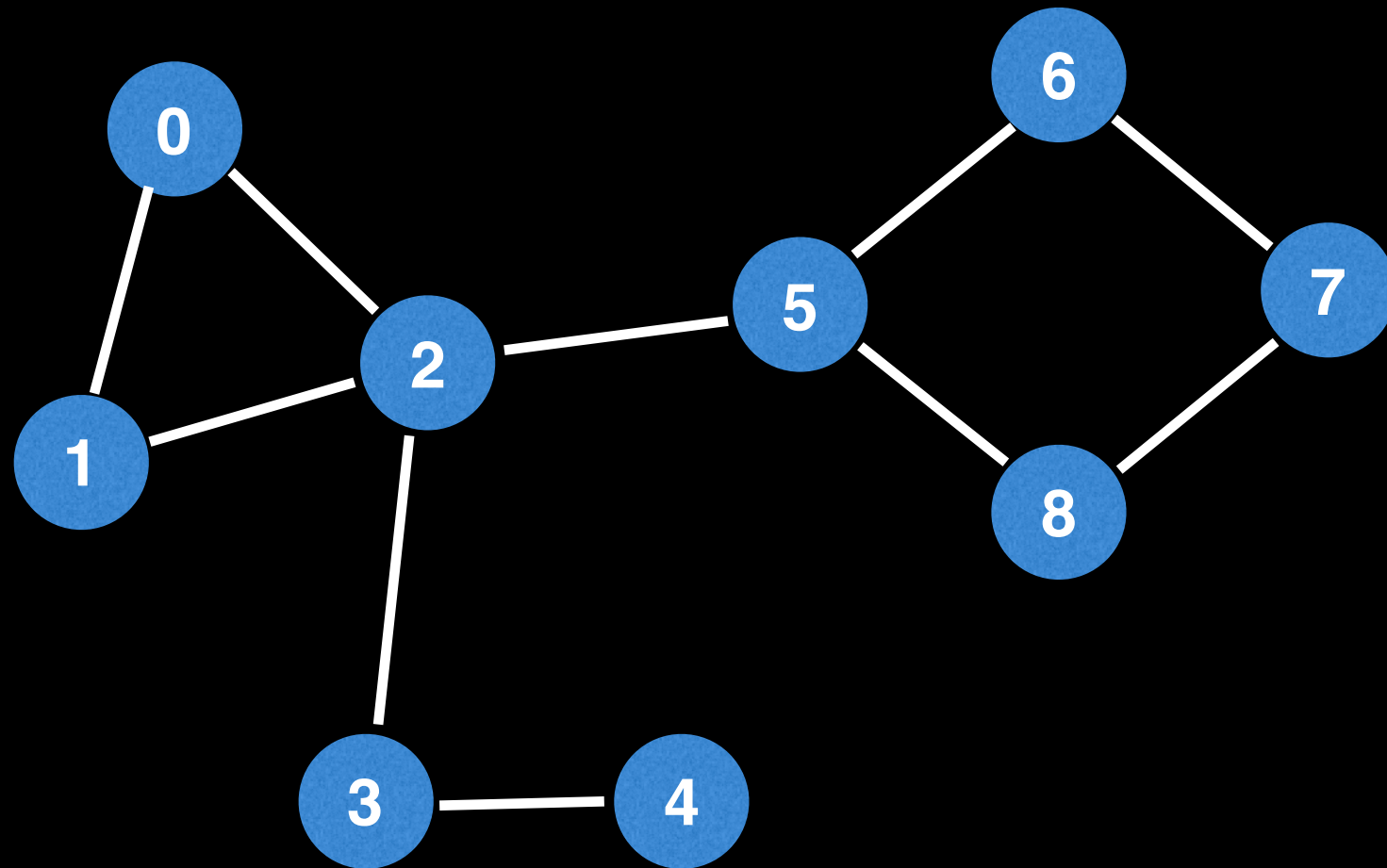
A **bridge / cut edge** is any edge in a graph whose removal increases the number of connected components.



Bridges are important in graph theory because they often hint at weak points, bottlenecks or vulnerabilities in a graph.

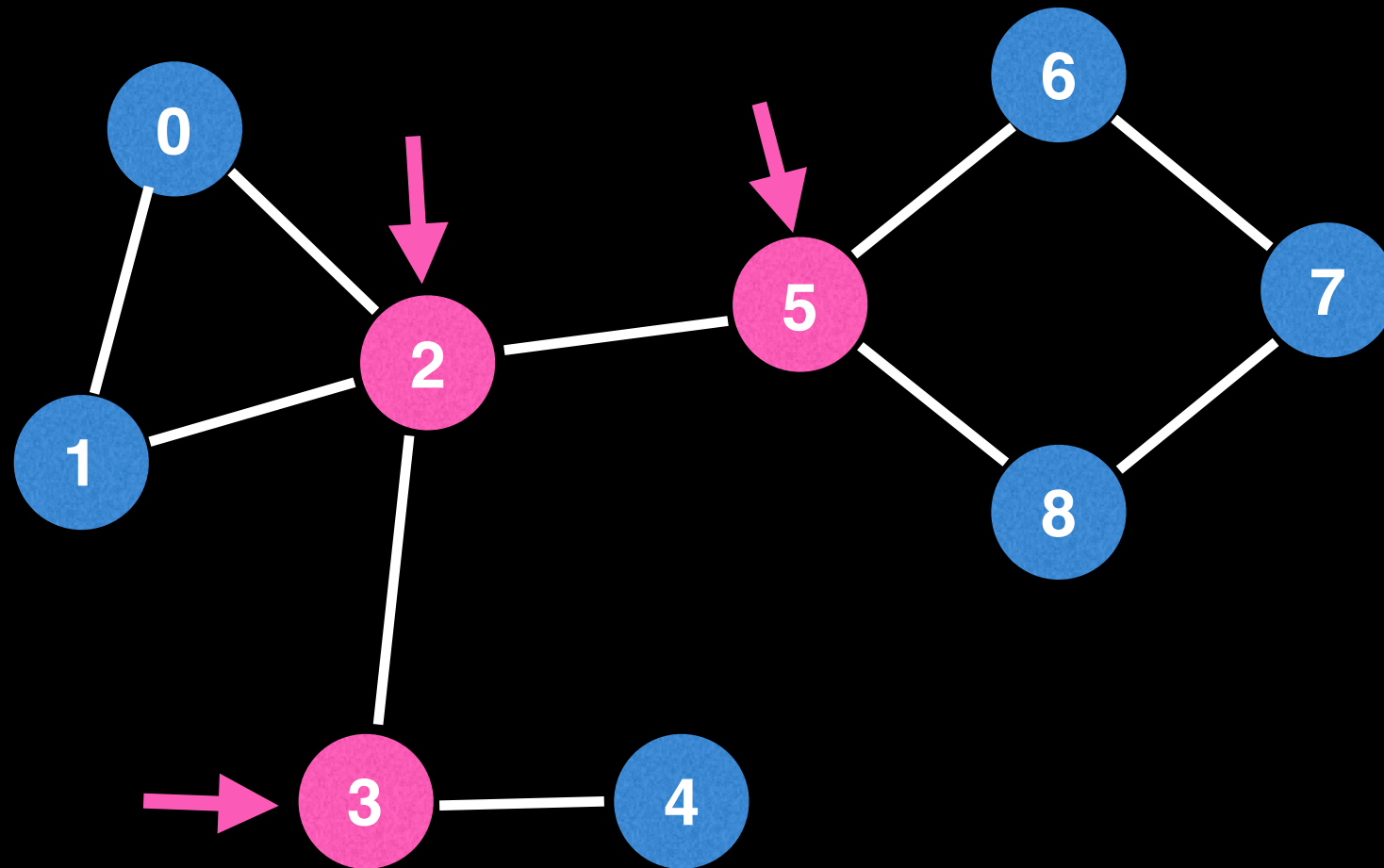
Articulation points

An **articulation point** / **cut vertex** is any node in a graph whose removal increases the number of connected components.



Articulation points

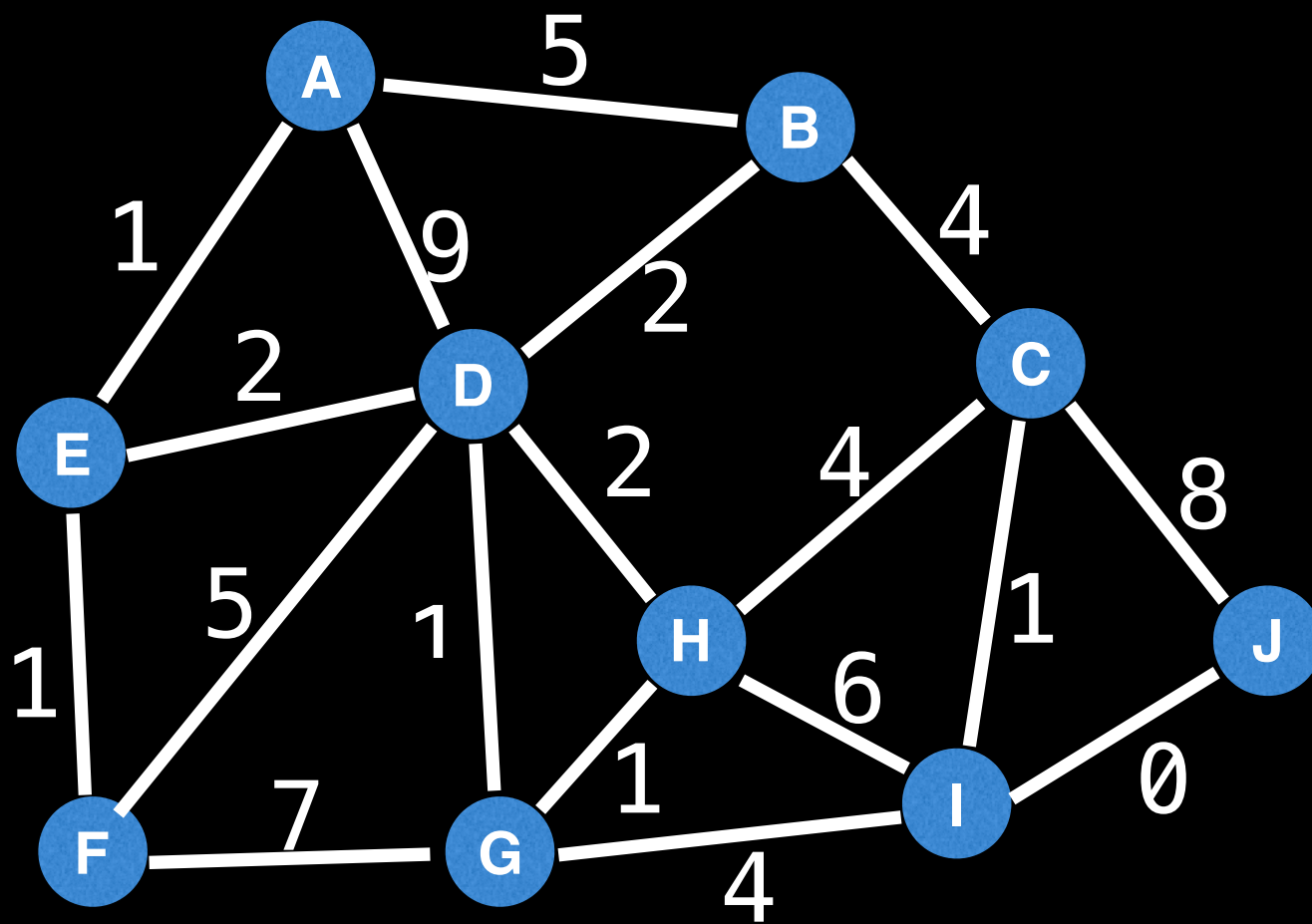
An **articulation point** / **cut vertex** is any node in a graph whose removal increases the number of connected components.



Articulation points are important in graph theory because they often hint at weak points, bottlenecks or vulnerabilities in a graph.

Minimum Spanning Tree (MST)

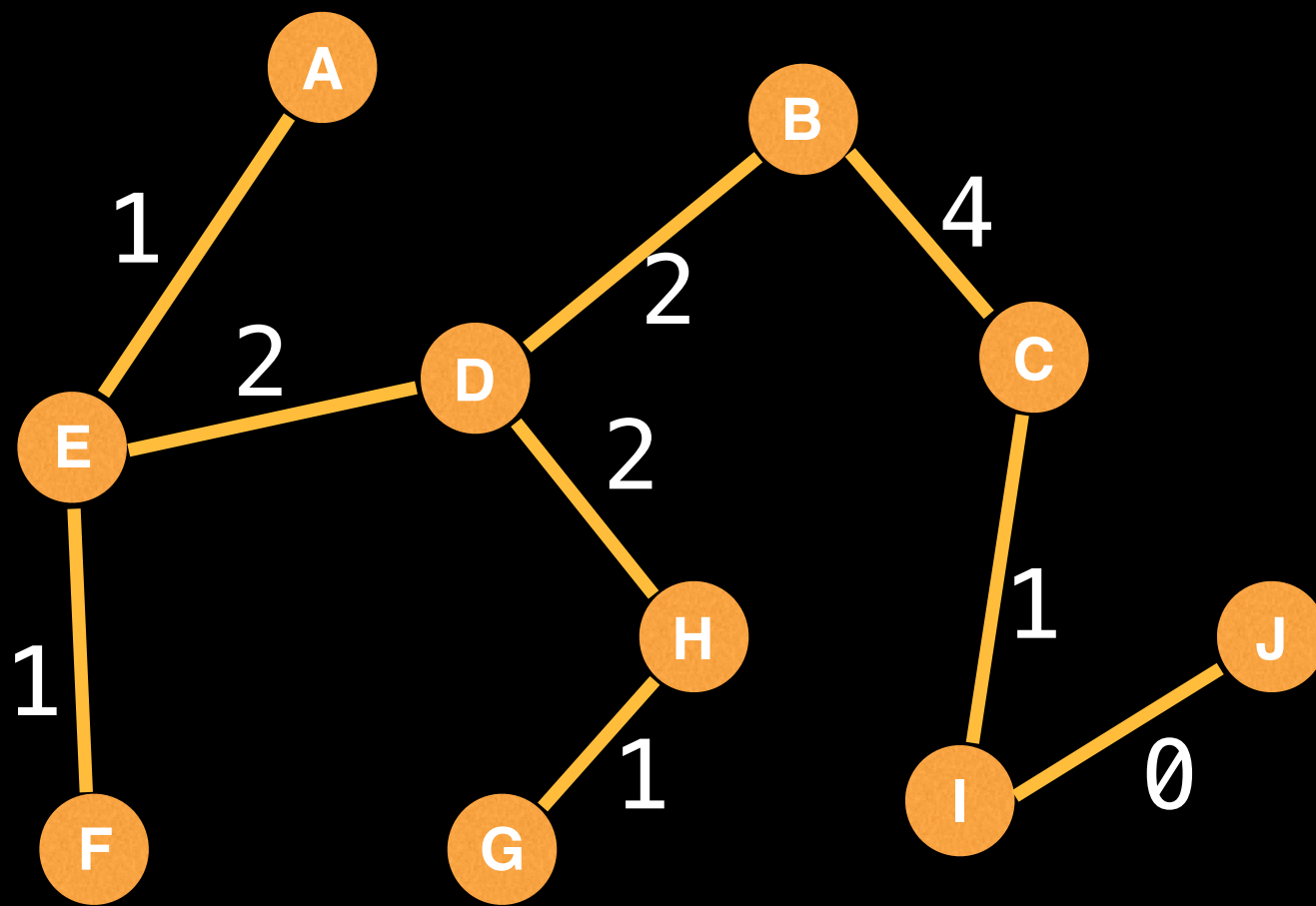
A **minimum spanning tree (MST)** is a subset of the edges of a connected, edge-weighted graph that connects all the vertices together, without any cycles and with the minimum possible total edge weight. – Wiki



Algorithms: Kruskal's, Prim's & Borůvka's algorithm

Minimum Spanning Tree (MST)

A **minimum spanning tree (MST)** is a subset of the edges of a connected, edge-weighted graph that connects all the vertices together, without any cycles and with the minimum possible total edge weight. – Wiki

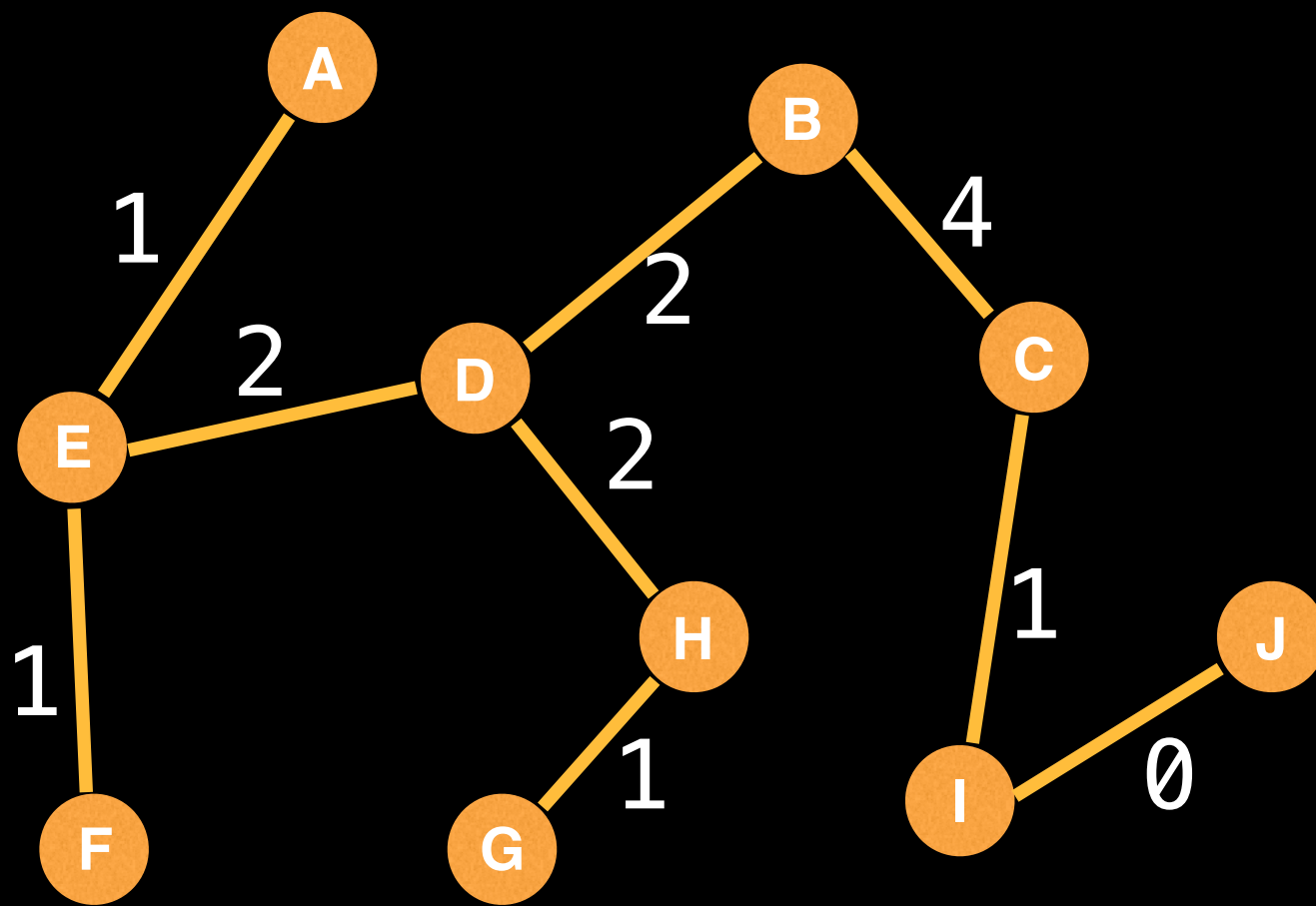


This MST has a total weight of 14. Note that MSTs on a graph are not always unique.

Algorithms: Kruskal's, Prim's & Borůvka's algorithm

Minimum Spanning Tree (MST)

MSTs are seen in many applications including:
Designing a least cost network, circuit design, transportation networks, and etc..

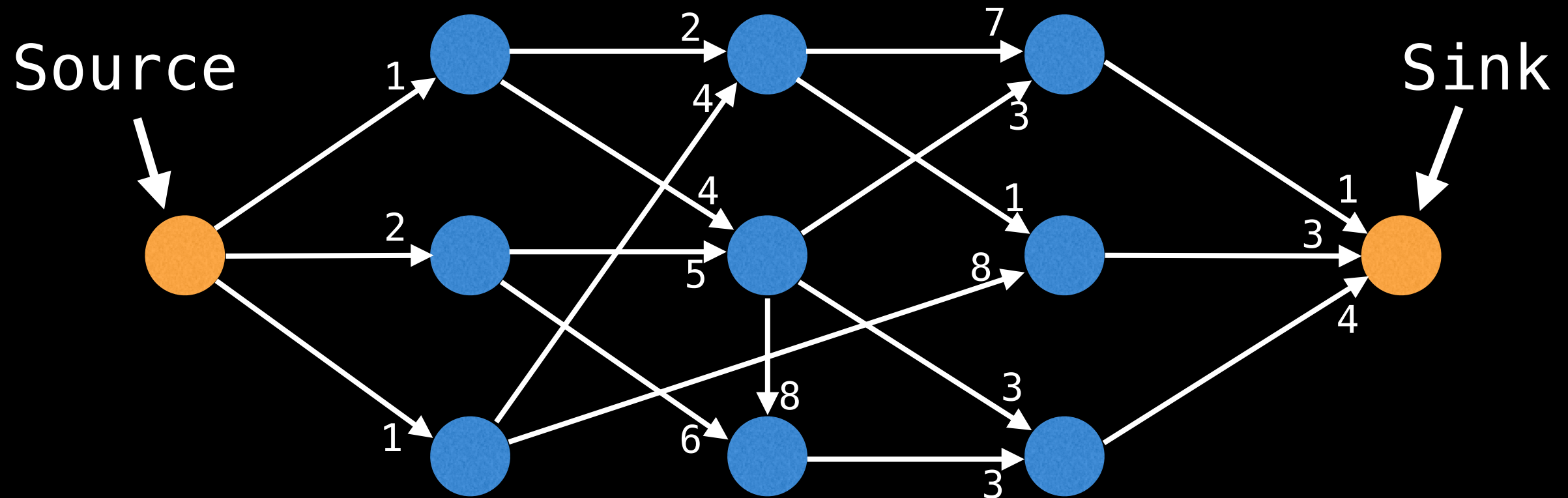


This MST has a total weight of 14. Note that MSTs on a graph are not always unique.

Algorithms: Kruskal's, Prim's & Borůvka's algorithm

Network flow: max flow

Q: With an infinite input source how much “flow” can we push through the network?



Suppose the edges are roads with cars, pipes with water or hallways with packed with people. Flow represents the volume of water allowed to flow through the pipes, the number of cars the roads can sustain in traffic and the maximum amount of people that can navigate through the hallways.

Algorithms: Ford–Fulkerson, Edmonds–Karp & Dinic’s algorithm

Next Video: Depth First Search