This Notebook computes and displays various processing algorithms on an image captured with a webcam. Processing is done mainly using OpenCV. The processing includes:

- 1. Capturing photo with webcam
- 2. Decomposing to R,G,B values
- 3. Converting to grayscale
- 4. Face and eye detection
- 5. Blurring
- 6. Sharpening
- 7. Denoising
- 8. Edge detection
- 9. Calculating the histogram

In [144]: import

import cv2
import numpy as np
from matplotlib import pyplot as plt
%matplotlib inline
import matplotlib.image as mpimg

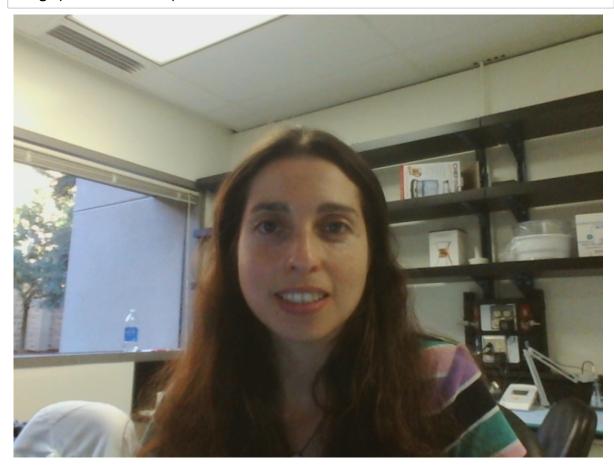
```
In [145]:
          # Camera 0 is the integrated web cam on my netbook
          camera_port = 0
          #Number of frames to throw away while the camera adjusts to light levels
          ramp frames = 30
          # Now we can initialize the camera capture object with the cv2. VideoCapt
          ure class.
          # All it needs is the index to a camera port.
          camera = cv2.VideoCapture(camera_port)
          # Captures a single image from the camera and returns it in PIL format
          def get image():
           # read is the easiest way to get a full image out of a VideoCapture obj
          ect.
           retval, im = camera.read()
           return im
          # Ramp the camera - these frames will be discarded and are only used to
          allow v4l2
          # to adjust light levels, if necessary
          for i in xrange(ramp_frames):
           temp = get_image()
          print("Taking image...")
          # Take the actual image we want to keep
          camera capture = get image()
          file = "C:\Users\orly\Documents\Stanford\Courses\CME193 scientific pytho
          n\project\webcam orly.png"
          # A nice feature of the imwrite method is that it will automatically cho
          ose the
          # correct format based on the file extension you provide. Convenient!
          cv2.imwrite(file, camera_capture)
          # You'll want to release the camera, otherwise you won't be able to crea
          te a new
          # capture object until your script exits
          del(camera)
```

Taking image...

In [146]:

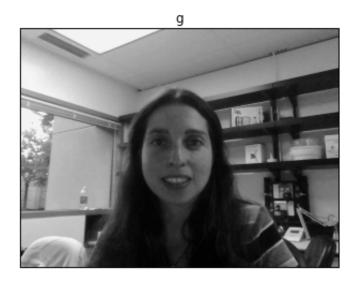
file = "C:\Users\orly\Documents\Stanford\Courses\CME193 scientific pytho
n\project\webcam_orly.png"
from IPython.display import Image
Image(filename=file)

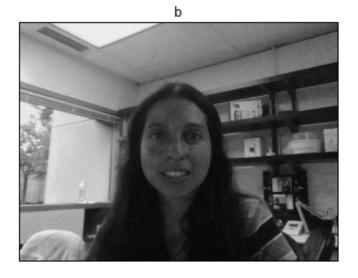
Out[146]:



```
In [147]: file = "C:\Users\orly\Documents\Stanford\Courses\CME193 scientific pytho
          n\project\webcam_orly.png"
          img = cv2.imread(file)
          b,g,r = cv2.split(img)
          plt.imshow(r, cmap = 'gray', interpolation = 'bicubic')
          plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
          plt.title('r')
          plt.show()
          plt.imshow(g, cmap = 'gray', interpolation = 'bicubic')
          plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
          plt.title('g')
          plt.show()
          plt.imshow(b, cmap = 'gray', interpolation = 'bicubic')
          plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
          plt.title('b')
          plt.show()
```







```
In [148]: def rgb2gray(rgb):
    return np.dot(rgb[...,:3], [0.299, 0.587, 0.144])
gray = rgb2gray(img)
plt.imshow(gray, cmap = 'gray', interpolation = 'bicubic')
plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
plt.title('gray')
plt.show()
```



```
In [149]:
          # img = cv2.imread(file)
          # img = cv2.imread("C:\Users\orly\Dropbox\Photos\Orly portraite\orly 5-2
          8-14.jpg")
          file = "C:\Users\orly\Documents\Stanford\Courses\CME193 scientific pytho
          n\project\webcam orly.png"
          # print file
          img = cv2.imread(file,1)
          # print ima
          plt.imshow(cv2.cvtColor(img, cv2.COLOR BGR2RGB))
          plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
          plt.title('Color image')
          plt.show()
          gray = cv2.cvtColor(img,cv2.COLOR BGR2GRAY)
          plt.imshow(gray,cmap = 'gray')
          plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
          plt.title('Gray image')
          plt.show()
          cascPath = 'C:\Users\orly\Documents\Stanford\Courses\EE368\OpenCV\source
          s\data\haarcascades\haarcascade_frontalface_default.xml'
          faceCascade = cv2.CascadeClassifier(cascPath)
          faces = faceCascade.detectMultiScale(
              gray,
              scaleFactor=1.1,
              minNeighbors=5,
              minSize=(30, 30),
              flags = cv2.cv.CV_HAAR_SCALE_IMAGE
          print faces
          cascPath = 'C:\Users\orly\Documents\Stanford\Courses\EE368\OpenCV\source
          s\data\haarcascades\haarcascade eye.xml'
          eye cascade = cv2.CascadeClassifier(cascPath)
          for (x,y,w,h) in faces:
              img2 = cv2.rectangle(img,(x,y),(x+w,y+h),(0,0,0),2)
              roi_gray = gray[y:y+h, x:x+w]
              roi_color = img[y:y+h, x:x+w]
              eyes = eye_cascade.detectMultiScale(roi_gray)
              for (ex,ey,ew,eh) in eyes:
                   img2 = cv2.rectangle(roi_color,(ex,ey),(ex+ew,ey+eh),(0,25
          5,0),2)
          plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))
          plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
          plt.title('face detection')
          plt.show()
```

Color image

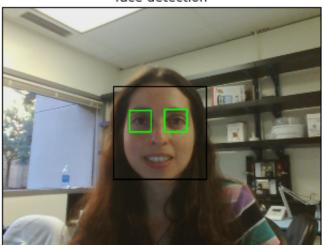


Gray image



[[223 161 186 186]]

face detection



In [150]: print np.shape(img)

cv2.imwrite("C:\Users\orly\Documents\Stanford\Courses\CME193 scientific

python\project\webcam_orly_face_detection.png", img)

(480L, 640L, 3L)

Out[150]: True

In [151]: file = "C:\Users\orly\Documents\Stanford\Courses\CME193 scientific pytho n\project\webcam_orly.png" img = cv2.imread(file) kernel = np.ones((5,5),np.float32)/25dst = cv2.filter2D(img,-1,kernel) unsharp = cv2.add(cv2.subtract(img,dst),img) plt.subplot(121),plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB)),plt.ti tle('Original') plt.xticks([]), plt.yticks([]) plt.subplot(122),plt.imshow(cv2.cvtColor(dst, cv2.COLOR_BGR2RGB)),plt.ti tle('Averaging') plt.xticks([]), plt.yticks([]) plt.show() plt.imshow(cv2.cvtColor(unsharp, cv2.COLOR_BGR2RGB)) plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis plt.title('unsharp mask') plt.show() cv2.imwrite("C:\Users\orly\Documents\Stanford\Courses\CME193 scientific python\project\webcam_orly_blurred.png", dst) cv2.imwrite("C:\Users\orly\Documents\Stanford\Courses\CME193 scientific python\project\webcam_orly_unsharp_mask.png", unsharp)

Original

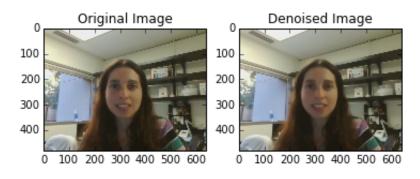


Averaging



unsharp mask





Out[152]: True

Original Image



Edge Image



Edges



