CS 60002: Distributed Systems

T10: Distributed Mutual Exclusion

Department of Computer Science and **Engineering**



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Mutual Exclusion (Mutex)

- A program object to prevent simultaneous access to the shared resources, used in concurrent programming with a **critical section** (a part of code where processes access shared resources)
 - Well understood in case of shared memory systems
 - Reader-Writer: Two processes can read simultaneously, but read-write or write-write cannot happen simultaneously

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Requirements:

- At most one process should execute the critical section (Safety)
- If more than one processes request to execute the critical section, at least one of them enters (liveness)
- A process executes the critical section for a finite time (no starvation)
- The requests are granted in some order (fairness)

Distributed Mutual Exclusion

- Permission-based Algorithms
 - A process takes permission from all other processes (or a subset of that) before entering the critical section
 - Permission from all: Costly, good for small systems
 - **Permission from subset:** scalable, widely used; however, the main challenge is how to choose the subset for each process?

Distributed Mutual Exclusion

Permission-based Algorithms

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Token-based Algorithms

- Single token in the system
- A process enters the critical section if it has a token
- There are different algorithms based on how the token is circulated across different requesting processes

Adaptive vs Non-adaptive Algorithms

Less requests for entering the critical section → Low load

 Performance of a distributed mutual exclusion algorithm under low load should be better than that under high load

An algorithm is called adaptive if the performance is dependent on the load

• But, how do we measure the performance?

Metrics for Performance Measurements

• Message complexity -- Number of messages per critical section entry

 Synchronization delay – Time required to enter the critical section after a process leaves the critical section

• Response time – The time interval a request waits for its critical section execution to be over after its request messages have been sent out

• **Throughput** – The rate at which critical sections are executed, computed as 1/(synchronization delay + critical section execution time)

Permission-based Algorithms

- Permission from all, contention-based algorithm
 - Processes contend with each other to enter the critical section
- Uses logical clock to order the messages
 - Indeed, the algorithm was given as an example of the use of Logical clocks
- System model: Asynchronous, Completely-connected topology, Reliable and FIFO channel

- Every process maintains a queue of pending requests for entering critical section in that order
 - The requests in the queue is ordered based on the logical clock timestamp
 - Total order is enforced by including process IDs in the timestamp

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Process i requests to enter the critical section

- Send timestamped REQUEST (ts_i, i) to ALL other processes
- Put (ts_i, i) in its own queue

On receiving a request (ts_i, i)

- Send timestamped REPLY to the requesting node i, requests are granted in the order of timestamp
- Put the REQUEST (ts_i, i) in the queue

- Process i enters the critical section if
 - (ts_i, i) is at the top of its own queue
 - Process i has received a message (REQUEST or REPLY) with a timestamp larger than ts_i from ALL other processes

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 i removes the request from its own queue and sends a timestamped RELEASE message to ALL other processes

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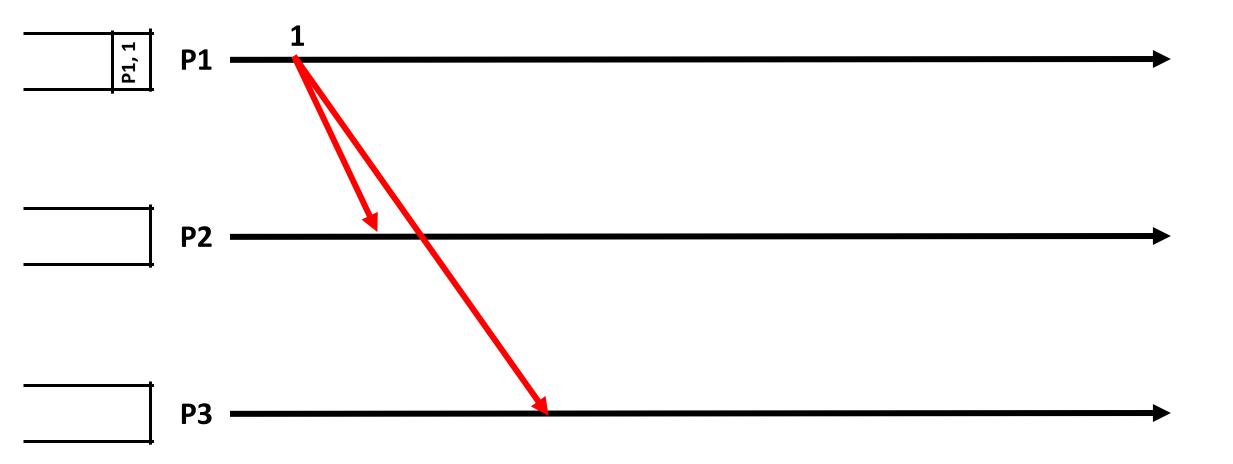
Process i releases the critical section

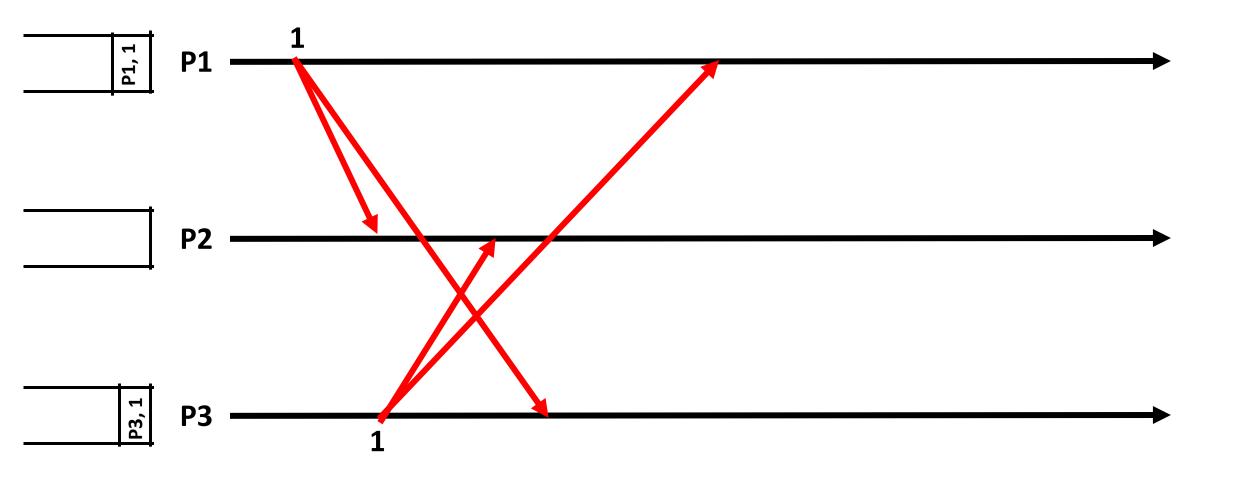
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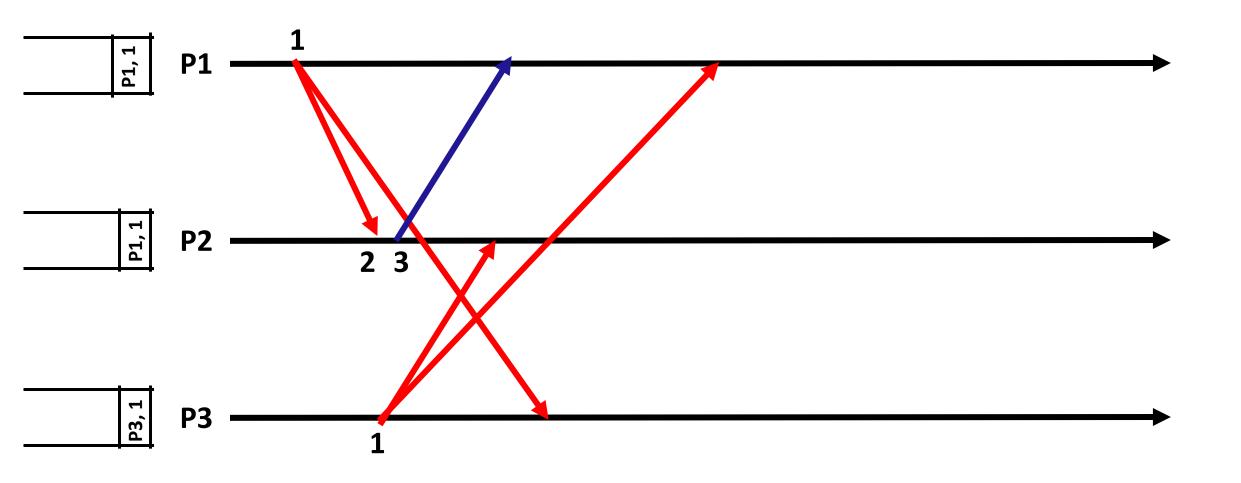
On receiving a RELEASE message from i

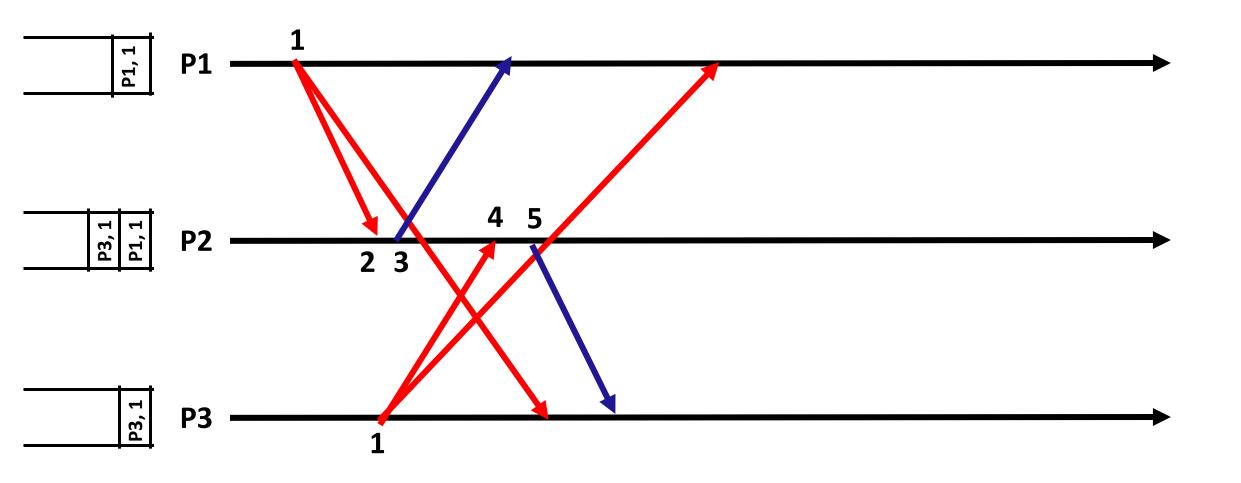
• i's request is removed from the local request queue

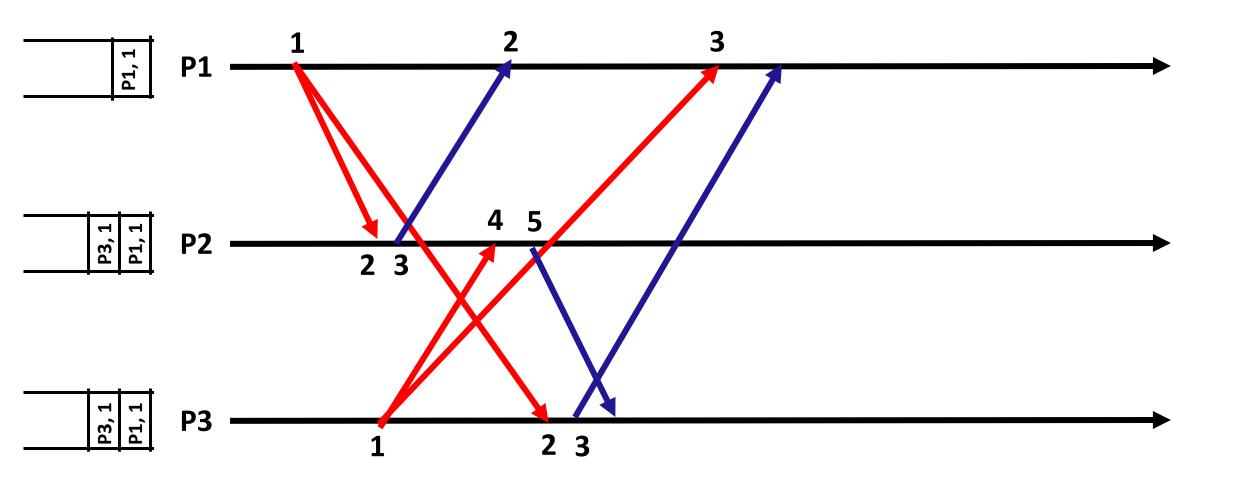


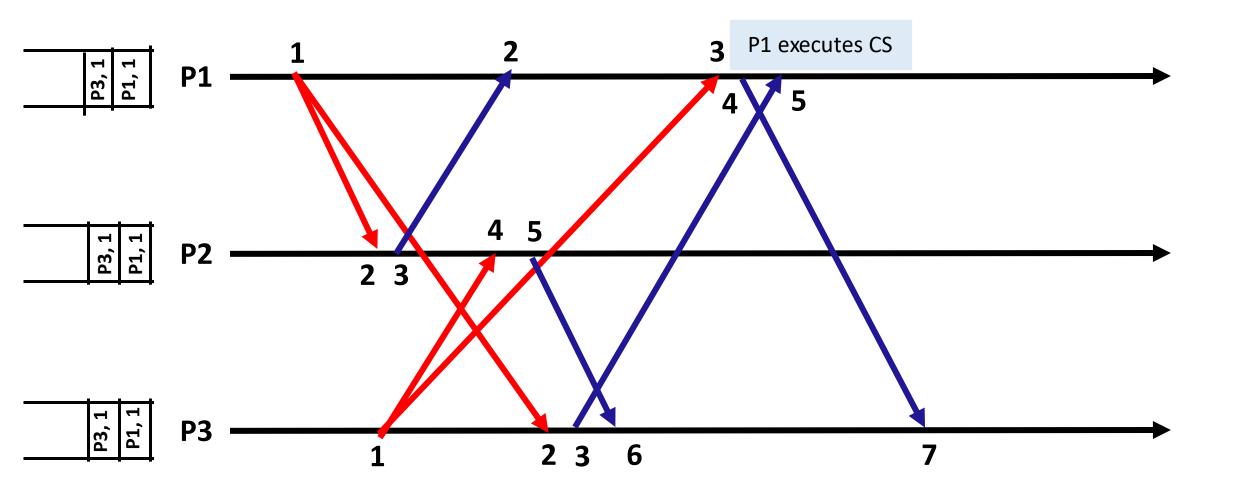


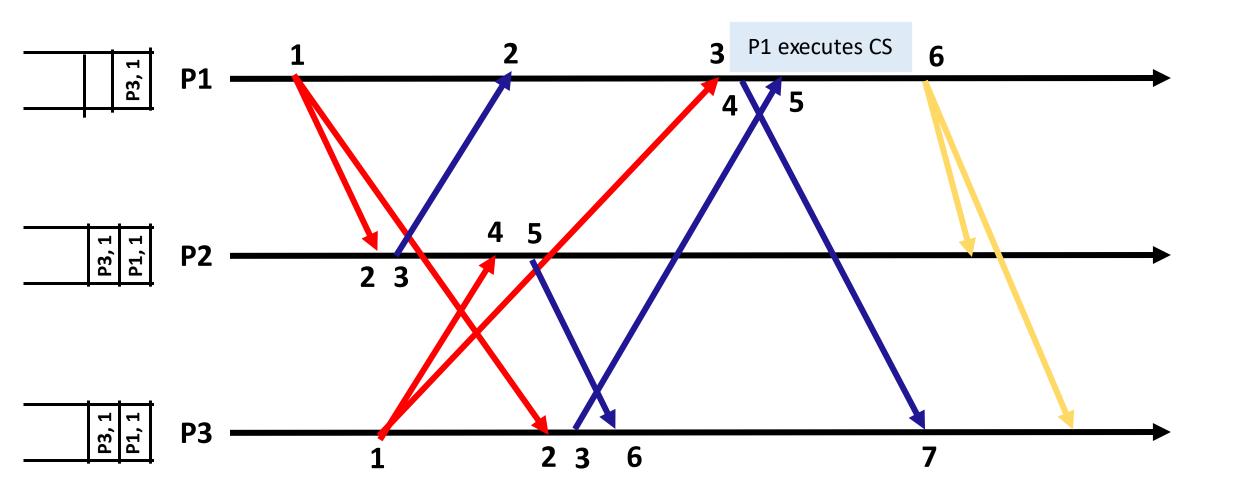


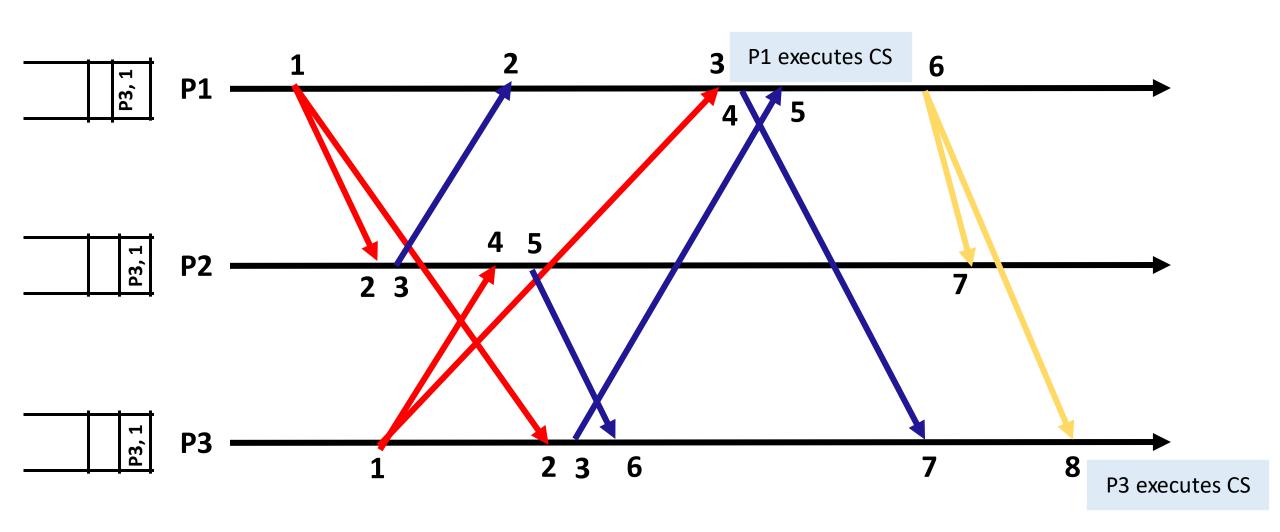












Some Observations

 Timestamp of a REPLY message is greater than the timestamp of the corresponding REQUEST message

- The REPLY message from process i to process j ensures that j knows of all requests of i prior to sending the REPLY
 - This ensures that j knows any possible requests from i with a lower timestamp
 - Requires FIFO channel
- Requests are granted in the order of increasing timestamp

Performance Metrics

- 3(n-1) messages are required per critical section invocation
 - (n-1) REQUEST messages
 - (n-1) REPLY messages
 - (n-1) RELEASE messages
- Synchronization delay equals to maximum message transmission time

- Improvement over Lamport's Algorithm
 - Developed by Glenn Ricart and Ashok Agrawala
 - Ricart, Glenn; Agrawala, Ashok K. (1981). "An optimal algorithm for mutual exclusion in computer networks". Communications of the ACM. 24 (1): 9–17

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• Core Idea:

- Process i has a request timestamp of ts_i and process j has a request timestamp of ts_i
- ts_i < ts_i → i cannot enter the critical section before j
- Process j needs not send a REPLY immediately to process i in this case
- Process j sends the REPLY after it completes its critical section
- No separate RELEASE message is needed

- To Request the Critical Section:
 - Send timestamped REQUEST message (ts_i, i)
- On receiving Request (ts_i, i) at j:
 - Send REPLY to i if
 - j is neither requesting nor executing critical section or
 - if j is requesting and i's request timestamp is smaller than j's request timestamp.
 - Otherwise, defer the request.

- To enter critical section:
 - i enters critical section on receiving REPLY from all nodes
- To release critical section:
 - Send REPLY to all deferred requests

Analysis of the Algorithm

- Requests are granted in order of increasing timestamps
- Does not require FIFO, but requires knowledge of all other processes in the network
- 2(n-1) messages per critical section invocation
- Synchronization delay equals to the maximum message transmission time
- Failure of a process may cause starvation needs separate fault detection algorithm

Maekawa's Algorithm

- Permission is obtained from a subset of other processes
 - The subset is called the Request Set (or Quorum Set)
 - Separate request set R_i for each process i

Maekawa's Algorithm

- Permission is obtained from a subset of other processes
 - The subset is called the Request Set (or Quorum Set)
 - Separate request set R_i for each process i
- Requirements for the Quorum Set:
 - For all i, j: R_i ∩ R_i ≠ Ø
 - For all i: i ∈ R_i
 - For all i: |R_i| = K for some K
 - Any process i is contained in exactly D quorum sets, for some D
- K = D
- K ≥ sqrt(N-1)

Maekawa's Algorithm – A Simple Version

To request critical section:

i sends REQUEST message to all processes in its quorum set R_i

On receiving a REQUEST message

- Send a REPLY message if no REPLY message has been sent since the last RELEASE message is received.
- Update status to indicate that a REPLY has been sent.
- Otherwise, queue up the REQUEST

Maekawa's Algorithm – A Simple Version

To enter critical section:

i enters critical section after receiving REPLY from all processes in R_i

To release critical section:

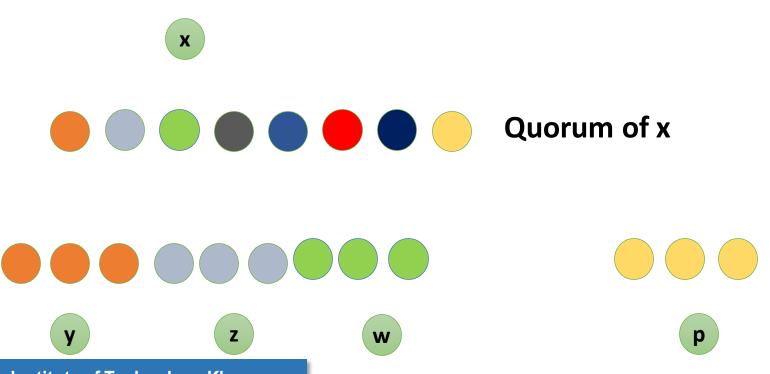
- Send RELEASE message to all processes in R_i
- On receiving a RELEASE message, send REPLY to next process in the queue and delete the process from the queue.
- If queue is empty, update status to indicate no REPLY message has been sent since last RELEASE is received.

Maekawa's Algorithm - Analysis

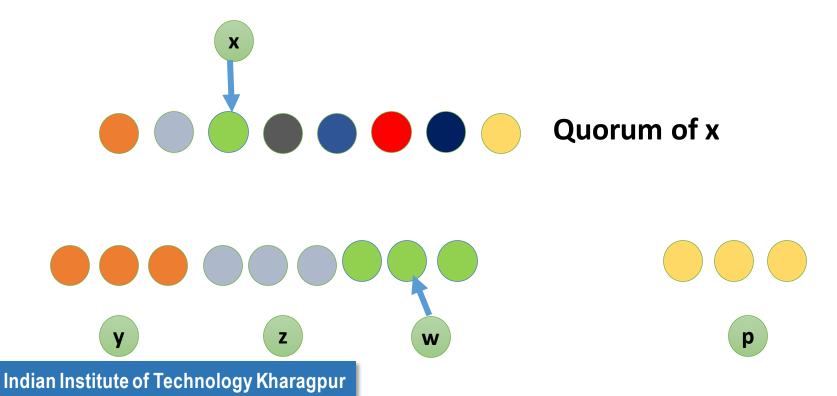
- The REPLY message works like a vote
 - To enter the critical section, every process needs to obtain the vote from ALL the processes in its quorum set
- Safety: Any two quorum set has at least one process in common
 - The common processes ensure the total ordering of requesting processes
- Message Complexity: 3 x sqrt (N)
- Synchronization delay = 2 message transmission delays
- A major issue with the algorithm: deadlock is possible
 - $i \in R_i$, $j \in R_i$, i waits for the reply from j, j waits for the reply from i
 - Try to solve this problem with additional messages and logical clock timestamp (indeed, Maekawa's algorithm already does that)
- How do we build the quorum set?

- The set of Quorums is called a **Coterie**. The following properties must hold for quorums in a coterie.
- Intersection: For every quorum Q1 and Q2 in C, Q1 \cap Q2 \neq Ø.
 - For example, {1, 2, 3}, {3, 4, 5} and {7, 8, 9} cannot be quorums in a coterie
- Minimality: There should not be any two quorums Q1 and Q2 in C, such that $Q1 \subseteq Q2$.
 - For example, {1, 2, 3} and {1, 2} cannot be quorums of a coterie
 - Ensure efficiency rather than correctness

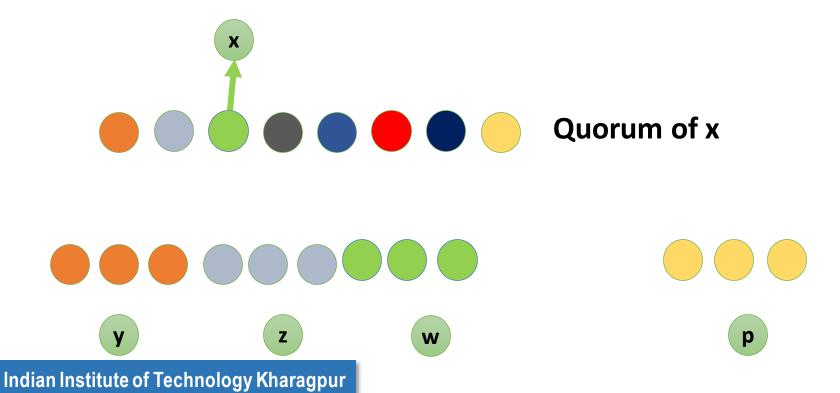
- Let x is process in quorum Q. If x wants to invoke mutual exclusion, the **Intersection property** ensures that, there is at least one process in the quorum Q that is common to the quorum of every other processes
 - These common processes send permission to only one processes at a time, thus ensuring mutual exclusion



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Maekawa's Algorithm – Building the Quorum Set

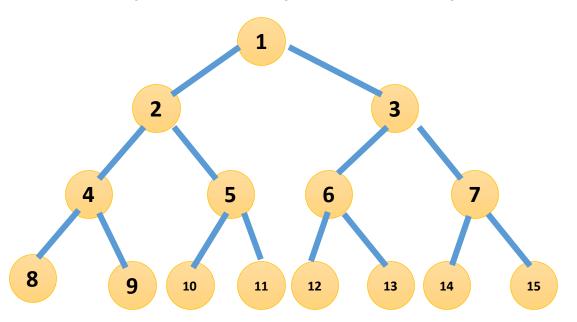
- One possible solution is to use a 2-D grid
 - Need 2*sqrt(N) votes and 6*sqrt(N) messages

```
123456789101112131415161718192021222324252627282930313233343536
```

Agarwal-El Abbadi Algorithm

• Uses 'tree-structured' quorums – All the processes are logically organized in a complete binary tree

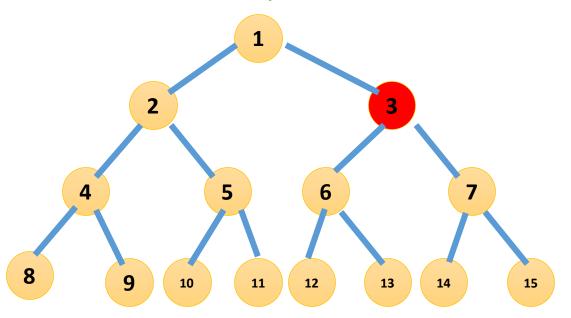
Each quorum represents a path from the root to the leaf



- Eight quorums
 - {1, 2, 4, 8}
 - {1, 2, 4, 9}
 - {1, 2, 5, 10}
 - {1, 2, 5, 11}
 - {1, 3, 6, 12}
 - {1, 3, 6, 13}
 - {1, 3, 7, 14}
 - {1, 3, 7, 15}

Agarwal-El Abbadi Algorithm

- Number of processes in a quorum: log n
- Handle process failures till log n
 - If any process fails, the algorithm substitutes for that process two possible paths starting from the process's two children and ending in leaf nodes.
 - Cannot form quorums when failure is more than log n



- Eight quorums when process 3 fails
 - {1, 2, 4, 8}
 - {1, 2, 4, 9}
 - {1, 2, 5, 10}
 - {1, 2, 5, 11}
 - {1, 6, 12, 7, 14}
 - {1, 6, 13, 7, 15}
 - {1, 6, 13, 7, 14}
 - {1, 6, 12, 7, 15}

Token-based Algorithms

Broad Idea

- A single token circulates in the system; a process enters the critical section when it has the token
- Obvious mutual exclusion no more than one process can possess the token at any point in time
- Algorithms differ in how to find and get the token
 - Token circulates, processes use it when it passes through them
 - Token stays at the process that used it last, other processes request for it when needed need to differentiate between old and current requests

- Broadcast a request for the token
- Process with the token sends it to the requestor if it does not need it

• Issues:

- Current vs Outdates requests
- Determining processes with pending requests
- Deciding which process to give the token to

- The token (called the PRIVILEGE message in the algorithm):
 - Queue (FIFO) Q of requesting processes
 - LN[1...n]: Sequence number of requests that j executed most recently
- The request message:
 - REQUEST(i, k): Request message from process i for its kth critical section execution
- Other data structures:
 - RN_i[1...n] for each node i, where RN_i[j] is the largest sequence number received so far
 by i in a REQUEST message from j

- To request critical section:
 - If i does not have the token, increment RN_i[i] and send REQUEST(i, RN_i[i]) to all processes
 - If i has the token already, enter critical section if the token is idle (no pending requests in token Q), else follow rule to release critical section
- On receiving REQUEST(i, sn) at j:
 - set RN_i[i] = max(RN_i[i], sn)
 - If j has the token and the token is idle, send it to i if RN_j[i] = LN[i] + 1. If token is not idle, follow rule to release critical section.

- To enter critical section:
 - Enter Critical Section if the token is received after sending REQUEST
- To release critical section:
 - set LN[i] = RN_i[i]
 - For every process j which is not in Q (in token), add process j to Q if RN_i[j] = LN[j] + 1
 - If Q is non-empty after the above, delete the first process from Q and send the token to that process

Suzuki Kasami Algorithm - Analysis

- Message complexity: zero if node holds the token already and token is idle, notherwise
- Synchronization delay: zero (node has the token) or max. message delay (token is elsewhere)
- No starvation

