```
#include <SPI.h>
#include <MFRC522.h>
#include <Servo.h>
#include <Wire.h>
#include <LiquidCrystal I2C.h>
LiquidCrystal_I2C lcd(0x3f, 16, 2);
#define RST_PIN 9 // Configurable, see typical pin layout above
#define SS PIN 10 // Configurable, see typical pin layout above
const int button_one = 1;
const int button_two = 2;
const int ServoPin1 = 5;
const int ServoPin2 = 7;
Servo s1;
Servo s2;
int servo position = 0;
MFRC522 mfrc522(SS_PIN, RST_PIN); // Create MFRC522 instance
*******//
void setup() {
 pinMode(button_one, INPUT);
 pinMode(button_two, INPUT);
 s1.attach(ServoPin1);
 s2.attach(ServoPin2);
 Serial.begin(9600); // Initialize serial communications with the PC
 lcd.init();
 lcd.backlight();
 lcd.clear();
 lcd.setCursor(0, 0);
 lcd.print(" Note to Coin");
 lcd.setCursor(0, 1);
 lcd.print("
             System ");
 delay(6000);
 lcd.clear();
 SPI.begin();
                                                      // Init SPI bus
 mfrc522.PCD_Init();
                                                      // Init MFRC522
card
 Serial.println(F("Read personal data on a MIFARE PICC:")); //shows in
serial that it is ready to read
 lcd.clear();
 lcd.setCursor(0, 0);
 //lcd.print(" Scanning...");
*******//
```

```
void loop() {
  lcd.setCursor(0, 0);
  lcd.print(" Scanning...
                              ");
  lcd.setCursor(0, 1);
  lcd.print("
                              ");
  // Prepare key - all keys are set to FFFFFFFFFF at chip delivery from the
factory.
  MFRC522::MIFARE_Key key;
  for (byte i = 0; i < 6; i++) key.keyByte[i] = 0xFF;</pre>
  // Look for new cards
  if (!mfrc522.PICC_IsNewCardPresent()) {
    return;
  }
  // Select one of the cards
  if (!mfrc522.PICC_ReadCardSerial()) {
    return;
  }
  Serial.println(F("**Card Detected:**"));
  lcd.clear();
  lcd.setCursor(0, 0);
  lcd.print(" Note Detected...");
  delay(2000);
  Serial.print("UID tag :");
  String content = "";
  byte letter;
  for (byte i = 0; i < mfrc522.uid.size; i++) {</pre>
    Serial.print(mfrc522.uid.uidByte[i] < 0x10 ? " 0" : " ");</pre>
    Serial.print(mfrc522.uid.uidByte[i], HEX);
    content.concat(String(mfrc522.uid.uidByte[i] < 0x10 ? " 0" : " "));</pre>
    content.concat(String(mfrc522.uid.uidByte[i], HEX));
  }
  Serial.println();
  Serial.print("Message : ");
  content.toUpperCase();
```

```
if (content.substring(1) == "22 7F 85 21") //change here the UID of the
card/cards that you want to give access. 20 Rupees Note
    Serial.println("Authorized access");
    lcd.clear();
    lcd.setCursor(0, 0);
    lcd.print("20 RS NOTE");
    delay(2000);
    lcd.clear();
    lcd.setCursor(0, 0);
    lcd.print("Select Coins");
    delay(5000);
    if (digitalRead(button_one) == HIGH) {
     Serial.println("button_one pressed");
     lcd.clear();
      lcd.setCursor(0, 0);
      lcd.print("
                  5rs Coin");
     lcd.setCursor(0, 1);
                  Selected");
     lcd.print("
     delay(1000);
     F1();
     F1();
     F1();
     F1();
     // F1();
     delay(1000);
    }
    if (digitalRead(button two) == HIGH){
      Serial.println("button_two pressed");
      lcd.clear();
      lcd.setCursor(0, 0);
      lcd.print(" 20rs Coin ");
      lcd.setCursor(0, 1);
     lcd.print(" Selected");
     delay(1000);
     F2();
   }
```

```
else if(content.substring(1) == "63 C5 36 00") //10 Rupees Note
 Serial.println("Authorized access");
  lcd.clear();
  lcd.setCursor(0, 0);
  lcd.print("10 RS NOTE");
  delay(2000);
  lcd.clear();
  lcd.setCursor(0, 0);
  lcd.print("Select Coins");
  delay(5000);
  if (digitalRead(button_one) == HIGH) {
   Serial.println("button_one pressed");
   lcd.clear();
   lcd.setCursor(0, 0);
   lcd.print(" 5rs Coin");
   lcd.setCursor(0, 1);
   lcd.print(" Selected");
   delay(1000);
   F1();
   F1();
   //F1();
   //F1();
   // F1();
   delay(1000);
  }
  if (digitalRead(button_two) == HIGH)
  {
   Serial.println("button_two pressed");
   lcd.clear();
   lcd.setCursor(0, 0);
   lcd.print(" 10rs Coin ");
   lcd.setCursor(0, 1);
   lcd.print(" Selected");
   F2();
   //F2();
   //F2();
  }
}
```

```
else{
   Serial.println(" Access denied");
    lcd.clear();
    lcd.setCursor(0, 0);
   lcd.print("Invalid Note");
   delay(3000);
}
}
//Functions to rotate Servo Motor
 void F1() {
    s1.write(90);
   delay(1000);
   s1.write(0);
   delay(1000);
  }
 void F2() {
    s2.write(90);
   delay(1000);
   s2.write(0);
   delay(1000);
  }
```