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# Inference about the change-point in a sequence of random variables

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#### SUMMARY

Inference is considered about the point in a sequence of random variables at which the probability distribution changes. In particular, we examine a normal distribution with changing mean. The asymptotic distribution of the maximum likelihood estimate is derived and also the asymptotic distribution of the likelihood ratio statistic for testing hypotheses about the change-point. These asymptotic distributions are compared with some finite sample empirical distributions.

# 1. Introduction

Given a sequence  $(x_1, ..., x_T)$  of observations on the variables  $(X_1, ..., X_T)$ , there are available many techniques for detecting underlying patterns or relationships, most of which assume that a single model is valid for the whole range of the sample. Often the model is of the form

 $X_t = \theta(t) + \epsilon_t \quad (t = 1, ..., T),$ 

where  $\{e_t\}$  is a sequence of uncorrelated error terms with zero mean and  $\theta(t)$  is a continuous mean function. In practice, however, a single model is sometimes inappropriate. It may be strongly suspected that the model valid near t=1 is not valid near t=T. It is then relevant to consider models of the form

$$X_t = \theta_0(t) + \epsilon_t \quad (t = 1, ..., \tau),$$

$$X_t = \theta_1(t) + \epsilon_t \quad (t = \tau + 1, ..., T),$$

$$(1 \cdot 1)$$

where the change-point  $\tau$  is unknown. Experimental and scientific grounds may force us to consider (1·1), or even its generalization to (p+1) submodels with p unknown change-points.

Two simple but interesting and important special cases of (1·1) are (a) two constant means  $\theta_0$  and  $\theta_1$ , and (b) two intersecting regressions  $\theta_i(t) = \alpha + \beta_i(z_t - \gamma)$  (i = 0, 1), where  $z_t$  is an independent variable and  $z_\tau \leqslant \gamma < z_{\tau+1}$ . In both cases it is usual to assume the error terms  $e_t$  to be  $N(0, \sigma^2)$ . Maximum likelihood estimation and inference in the regression case (b) have been discussed in detail by Hudson (1966) and Hinkley (1969). In case (a) the emphasis of published work, in particular that of Page (1954, 1955, 1957) on cumulative sum schemes, has been on testing the null hypothesis  $H_0$ :  $\theta_0 = \theta_1$  against the two-mean alternative. Chernoff & Zacks (1964) and Bhattacharyya & Johnson (1968) have discussed the same problem within a Bayesian framework. The present paper is concerned primarily with estimating and making inference about the change-point  $\tau$  in this two-mean case.

We consider initially (§ 2) a generalization of case (a) where  $X_t$  has an arbitrary continuous probability density function  $f(x,\theta)$  with  $\theta$  changing from  $\theta_0$  to  $\theta_1$  after index  $\tau$ . The asymptotic distribution of the maximum likelihood estimate  $\hat{\tau}$  is derived for  $\theta_0$  and  $\theta_1$  known.

In § 3 we discuss the computation of the asymptotic distribution in the normal case, and show that the asymptotic distribution is unchanged when  $\theta_0$  and  $\theta_1$  are unknown. The asymptotic distribution of the likelihood ratio statistic for testing hypotheses about  $\tau$  is also derived (§ 4). Tables of these distributions are given, and in § 5 we compare the asymptotic results with some empirical finite sample results.

# 2. Distribution of the maximum likelihood estimate: $\theta_0$ and $\theta_1$ known

In this section we derive the maximum likelihood estimate  $\hat{\tau}$  for a general probability density function  $f(x,\theta)$  of the random variable  $X_t$  and find its asymptotic distribution; that is, for both  $\tau$  and  $T-\tau$  indefinitely large. No explicit form for  $\hat{\tau}$  exists, but it is conveniently defined by variables associated with random walks, whose properties we use to get the asymptotic distribution of  $\hat{\tau}$  in a form suitable for computation.

#### 2.1. Exact results

Let  $(X_1,...,X_T)$  be a sequence of independent continuous random variables such that  $X_i$  has probability density function  $f(x,\theta_0)$   $(i=1,...,\tau)$  and  $X_i$  has probability density function  $f(x,\theta_1)$   $(i=\tau+1,...,T)$ , where  $\theta_0$  and  $\theta_1$  are known  $(\theta_0 \neq \theta_1)$  but  $\tau$  is unknown. To obtain the maximum likelihood estimate  $\hat{\tau}$  from a sample,  $x_1,...,x_T$ , we have to maximize the log likelihood function

$$L(t) = \sum_{i=1}^{t} \log f(x_i, \theta_0) + \sum_{i=t+1}^{T} \log f(x_i, \theta_1)$$
 (2·1)

over admissible values of t, namely t = 1, ..., T-1 since we assume at least one observation to come from each distribution.

A more convenient form for L(t) is obtained by defining the log likelihood increments

$$U_j = \log f(X_j, \theta_0) - \log f(X_j, \theta_1). \tag{2.2}$$

Then  $(2\cdot1)$  becomes

$$L(t) = \sum_{j=1}^{t} u_j + \sum_{j=1}^{T} \log f(x_j, \theta_1),$$

where  $u_j$  is the observed value of  $U_j$ , so that the maximum likelihood estimate  $\hat{\tau}$  is the value of t which maximizes the sequence of partial sums

$$V_t = \sum_{j=1}^t U_j$$
  $(t = 1, ..., T-1).$ 

The  $U_j$ 's are independent because of the independence of the  $X_j$ 's. It is not difficult to see that the differences  $V_t - V_\tau$  define two independent random walks, namely

$$\mathbf{W} = \left\{ 0, \ -\sum_{j=0}^{k} U_{\tau-j} \quad (k = 0, 1, ..., \tau - 1) \right\},$$

$$\mathbf{W}' = \left\{ 0, \sum_{j=0}^{k} U_{\tau+1+j} \quad (k = 0, 1, ..., T - \tau - 2) \right\},$$
(2·3)

each random walk having independent, identically distributed increments with negative mean. Thus W represents the log likelihood for integers less than  $\tau$ , and W' likewise for integers greater than  $\tau$ , relative to the log likelihood of  $\tau$  itself. To determine  $\hat{\tau}$  we must find the larger of the two random walk maxima; if each maximum is zero, then  $\hat{\tau} = \tau$ .

Now let  $Y_j = -U_{\tau-j+1}$  and  $Y'_j = U_{\tau+j}$  (j = 1, 2, ...), so that (2·3) becomes

$$\mathbf{W} = \left\{0, Y_{1}, Y_{1} + Y_{2}, \dots, \sum_{j=1}^{\tau-1} Y_{j}\right\},$$

$$\mathbf{W}' = \left\{0, Y'_{1}, Y'_{1} + Y'_{2}, \dots, \sum_{j=1}^{T-\tau-1} Y'_{j}\right\}.$$
(2·4)

Also let M and M' be the respective maxima of W and W'. The finite sample distribution of  $(\hat{\tau} - \tau)$  depends implicitly on  $\tau$  and  $(T - \tau)$  because M and M' do, but we shall assume both  $\tau$  and  $(T - \tau)$  to be infinitely large and derive the asymptotic distribution of  $(\hat{\tau} - \tau)$  using properties of the random walks W and W'.

We can now express events involving  $\hat{\tau}$  in terms of events involving M and M': we have seen already that  $\hat{\tau} = \tau$  is equivalent to M = M' = 0. Further,  $\hat{\tau} = \tau + k$  is equivalent to  $M' = Y'_1 + \ldots + Y'_k > 0$  and M' > M, and similarly for the event  $\hat{\tau} = \tau - k$ . The event M = M' > 0 has zero probability because the random variables are continuous. To simplify the analysis let

$$I=\inf\Big(k\colon M=\sum\limits_{j=1}^kY_j\Big),\quad I=0\quad ext{if}\quad M=0,$$
  $I'=\inf\Big(k\colon M'=\sum\limits_{j=1}^kY_j'\Big),\quad I'=0\quad ext{if}\quad M'=0.$ 

Thus I and I' are the indices of the maxima of W and W'. It follows by the independence of W and W' that

Now define, for k = 0, 1, ... and  $x \ge 0$ , the probability measures

$$\beta_k(x) dx = \operatorname{pr} (I = k, x \leq M < x + dx), \quad \beta_k'(x) dx = \operatorname{pr} (I' = k, x \leq M' < x + dx), \quad (2 \cdot 6)$$

$$\alpha(x) = \operatorname{pr}(M \leqslant x), \quad \alpha'(x) = \operatorname{pr}(M' \leqslant x), \tag{2.7}$$

where the prime distinguishes **W** and **W**' and never means differentiation. Note that, since I=0 implies M=0 and I'=0 implies M'=0,  $\beta_0(x)=\alpha(0)\,\delta(x)$  and  $\beta_0'(x)=\alpha'(0)\,\delta(x)$ , where  $\delta(0)=1$  and  $\delta(x)=0$  ( $x\neq 0$ ). We omit the dependence of  $\alpha(.)$ , ... on  $\theta_0$ ,  $\theta_1$  and f for simplicity of notation.

With the definitions (2.6) and (2.7), the probabilities (2.5) become, again using the independence of **W** and **W**',  $\operatorname{pr}(\hat{\tau} = \tau) = \alpha(0) \alpha'(0), \tag{2.8}$ 

$$pr(\hat{\tau} = \tau + k) = \int_0^\infty \beta'_k(x) \, \alpha(x) \, dx \quad (k = 0, 1, ...),$$
 (2.9)

$$pr(\hat{\tau} = \tau - k) = \int_0^\infty \beta_k(x) \, \alpha'(x) \, dx \quad (k = 0, 1, ...).$$
 (2·10)

It is easy to verify that  $\alpha(.)$  and  $\alpha'(.)$  satisfy integral equations. For example, if the probability density function of  $Y_j$  is g(.), then

$$\alpha(x) = \int_0^\infty \alpha(y) g(x - y) dy. \tag{2.11}$$

The densities  $\beta_k(.)$  and  $\beta'_k(.)$  also satisfy integral equations, but of a recursive type. However, the integral equations do not have explicit solutions, except in trivial cases. We therefore derive a method for calculating the integrals in (2.9) and (2.10) which does not involve an explicit solution for  $\alpha(.)$ , ....

An important result, deduced from Feller (1966, Chap. 18), is that if the sequence of independent identically distributed random variables  $Y'_1, Y'_2, \dots$  satisfies

$$\sum_{n=1}^{\infty} \frac{1}{n} \operatorname{pr} \left( \sum_{j=1}^{n} Y_j' > 0 \right) < \infty, \tag{2.12}$$

then

$$E(z^{I'}\,e^{-\omega M'})=\sum\limits_{n=0}^{\infty}z^{n}\int_{0}^{\infty}e^{-\omega x}\,\beta_{n}^{\,\prime}(x)\,dx$$

$$= \exp\left\{ \sum_{n=1}^{\infty} \frac{z^n c_n'(\omega)}{n} - \sum_{n=1}^{\infty} \frac{c_n'(0)}{n} \right\}, \tag{2.13}$$

where

$$c'_n(\omega) = \int_{0+}^{\infty} e^{-\omega x} \operatorname{pr}\left(x \leqslant \sum_{j=1}^{n} Y'_j < x + dx\right) \quad (n = 1, 2, ...),$$
 (2·14)

 $|z| \leq 1$  and  $\mathcal{R}(\omega) > 0$ . A similar result holds for I and M with  $c'_n(\omega)$  replaced by

$$c_n(\omega) = \int_{0+}^{\infty} e^{-\omega x} \operatorname{pr}\left(x \leqslant \sum_{j=1}^{n} Y_j < x + dx\right) \quad (n = 1, 2, \ldots).$$

The marginal distributions of I' and M' are derived by setting  $\omega = 0$  and z = 1 respectively in (2·13). In particular we find that

$$\sum_{k=0}^{\infty} z^k \operatorname{pr}(I' = k) = \exp\left\{ \sum_{n=1}^{\infty} \frac{(z^n - 1) \, c_n'(0)}{n} \right\} \quad (|z| \leqslant 1), \tag{2.15}$$

$$\alpha'(0) = \exp\left\{-\sum_{n=1}^{\infty} \frac{c_n'(0)}{n}\right\},\tag{2.16}$$

with corresponding results for I and M.

Now consider the probabilities pr  $(\hat{\tau} = \tau + k)$  in (2.9). In principle, we can obtain the generating function of these probabilities explicitly. For (2.9) can be written as

$$\operatorname{pr}(\hat{\tau} = \tau + k) = \int_{0}^{\infty} \beta_{k}'(x) \, dx - \int_{0}^{\infty} \beta_{k}'(x) \left\{1 - \alpha(x)\right\} dx, \tag{2.17}$$

and hence

$$\sum_{k=0}^{\infty} z^k \operatorname{pr} (\hat{\tau} = \tau + k) = \sum_{k=0}^{\infty} z^k \operatorname{pr} (I' = k) - \int_0^{\infty} \sum_{k=0}^{\infty} z^k \beta_k'(x) \{1 - \alpha(x)\} dx.$$
 (2·18)

The two functions in the integral of  $(2\cdot18)$  are integrable, assuming  $(2\cdot12)$ , with Laplace transforms determined explicitly from  $(2\cdot13)$ . Hence we can apply the Parseval relation to transform the integral in  $(2\cdot18)$  into the integral in the  $\omega$  plane of the product of two Laplace transforms. Unfortunately, however, the resulting complex integral does not appear to have an explicit form. But the result  $(2\cdot13)$  and its corollaries can be used to derive an approximation to  $(2\cdot17)$  which is suitable for computation.

The corresponding results hold for pr  $(\hat{\tau} = \tau - k)$  by applying the same arguments to  $(2 \cdot 10)$ , simply interchanging  $\alpha(.)$  and  $\alpha'(.)$ ,  $\beta'_k(.)$  and  $\beta_k(.)$ .

# 2.2. Approximation to the distribution

The approximation to (2·17) is based on approximating  $\{1-\alpha(.)\}$  by a sum of exponential terms. For suppose that

$$1 - \alpha(x) = \sum_{r=1}^{R} a_r e^{-\omega_r x} \quad (x \ge 0), \tag{2.19}$$

where R is possibly infinite. Then (2.17) becomes

$$pr(\hat{\tau} = \tau + k) = q'_k - \sum_{r=1}^{R} a_r \tilde{\beta}'_k(\omega_r) \quad (k = 0, 1, ...),$$
 (2.20)

where

$$q'_k = \int_0^\infty \beta'_k(x) dx = \operatorname{pr}(I' = k),$$

$$\tilde{\beta}_{\,k}^{\,\prime}(\omega) = \int_{\,0}^{\,\infty} e^{-\omega x} \, \beta_{\,k}^{\,\prime}(x) \, dx, \label{eq:beta-kappa}$$

which are respectively the coefficients of  $z^k$  in (2·15) and (2·13). Computation of (2·20) is straightforward because  $q'_k$  and  $\beta'_k(\omega)$  satisfy simple recurrence relations. In fact both (2·15) and (2·13) are equations of the type

 $\textstyle\sum\limits_{n=0}^{\infty}\rho_{n}z^{n}=A\exp\left(\sum\limits_{n=1}^{\infty}\frac{z^{n}\sigma_{n}}{n}\right),$ 

 $\rho_0 = A$ ,

whose solution is

$$\rho_{n+1} = \frac{1}{n+1} \sum_{j=0}^{n} \sigma_{n+1-j} \rho_j \quad (n = 0, 1, ...).$$
 (2.21)

In general,  $(2\cdot19)$  with R finite will be an approximation, so that  $(2\cdot20)$  will be an approximation also. The way in which we get the approximation  $(2\cdot19)$  is to fit the series of exponential terms by least squares to numerical values of  $\{1-\alpha(x)\}$ , which are obtained by numerical solution of  $(2\cdot11)$ . For this solution it is convenient to consider  $(2\cdot11)$  in the form

$$1 - \alpha(x) = \int_{x}^{\infty} g(u) \, du + \int_{0}^{\infty} \{1 - \alpha(u)\} g(x - u) \, du. \tag{2.22}$$

Then numerical values of  $\{1-\alpha(x)\}$  are obtained by taking a discrete, finite version of  $(2\cdot 22)$ . That is, we take a finite set of x values,  $0=x_0< x_1< \ldots < x_n$  with  $x_{i+1}-x_i=d$ , say, and approximate  $(2\cdot 22)$  by

$$1 - \alpha(x_i) = \int_{x_i}^{\infty} g(u) \, du + d \sum_{j=0}^{n} h_j \{1 - \alpha(x_j)\} g(x_i - x_j) \quad (i = 0, 1, ..., n),$$
 (2.23)

where  $h_0 = h_n = \frac{1}{2}$  and  $h_j = 1$  (j = 1, ..., n-1). This system of equations is linear and is easily solved. Both d and n can be varied until satisfactory accuracy is obtained. A detailed description of this numerical solution is given in §3 for the normal case.

In some cases, for example, that of normal probability density functions discussed in  $\S 3$ , a theoretical analysis of  $(2\cdot 22)$  will give useful information about one or more dominant exponential terms in the series  $(2\cdot 19)$ .

# 2·3. General remarks

A necessary condition for the moments of  $(\hat{\tau} - \tau)$  to exist is that  $(2 \cdot 12)$  holds for both  $\{Y_i\}$  and  $\{Y_i'\}$ . Expressed in terms of  $f(x, \theta)$  this condition is that

$$\sum_{n=1}^{\infty} \frac{1}{n} \operatorname{pr} \left\{ \prod_{j=1}^{n} \frac{f(X_{j}, \theta_{1})}{f(X_{j}, \theta_{0})} > 1 \big| X_{j} \text{ has probability density function } f(x, \theta_{0}) \right\} < \infty,$$

and similarly with  $\theta_0$  and  $\theta_1$  interchanged. Roughly speaking, this means that whether or not the moments of  $(\hat{\tau} - \tau)$  are finite depends on the power of the likelihood ratio test to distinguish between the alternatives  $\theta = \theta_0$  and  $\theta = \theta_1$  in samples from one population.

One awkward property of  $\hat{\tau}$  is that it is not consistent, since as  $\tau$  and  $(T-\tau)$  tend to infinity all existing moments of  $(\hat{\tau}-\tau)$  have nonzero limits. This property is to be expected because observations distant from the change-point give negligible information about  $\tau$ . Consistent estimation of  $\tau$  could only follow from consistent classification of observations.

For  $\hat{\tau}$  to be symmetrically distributed about  $\tau$  it is necessary and sufficient that  $Y_j$  and  $Y'_j$  be identically distributed. In terms of  $f(x, \theta)$  this implies that

$$\operatorname{pr}\{f(X,\theta_0) \leqslant yf(X,\theta_1) \mid \theta = \theta_1\} = \operatorname{pr}\{f(X,\theta_1) \leqslant yf(X,\theta_0) \mid \theta = \theta_0\}. \tag{2.24}$$

It is easy to see that  $(2\cdot 24)$  holds when  $f(x,\theta)$  is symmetric and  $\theta$  is a location parameter only, or if any (1,1) continuous transformation of X has such a probability density function. Thus, for example,  $(2\cdot 24)$  holds for the normal distribution with mean  $\theta$  and the corresponding log normal distribution, but not for the exponential density  $\theta e^{-\theta x}$ .

We have assumed in this section that  $\tau$  is the only unknown parameter; that is, that  $\theta_0$  and  $\theta_1$  are known. But it is not difficult to see that the asymptotic distribution of  $\hat{\tau}$  will be unchanged when  $\theta_0$  and  $\theta_1$  are unknown, provided that the maximum likelihood estimates of  $\theta_0$  and  $\theta_1$  conditional on  $\tau=t$  are consistent. In § 3·2 we show that this is so for the particular case of normally distributed random variables.

# 3. THE NORMAL CASE

We now apply the results of § 2 to the case where  $\theta_0$  and  $\theta_1$  are mean values of normal distributions with constant variance  $\sigma^2$ . The computation of the asymptotic distribution of  $\hat{\tau}$  is discussed in detail and some numerical results are given. We also show that the same asymptotic distribution holds when  $\theta_0$  and  $\theta_1$  are unknown and when  $\sigma^2$  is unknown.

3.1. 
$$\theta_0$$
 and  $\theta_1$  known

Let  $f(x, \theta_{\nu})$  be the probability density function of the  $N(\theta_{\nu}, \sigma^2)$  ( $\nu = 0, 1$ ) distribution with  $\theta_0$  and  $\theta_1$  known. If  $\sigma^2$  is also known we can follow the results of § 2 directly, where now the log likelihood increments  $U_i$  defined in (2·2) are given by

$$U_i = [(\theta_0 - \theta_1)\{X_i - \frac{1}{2}(\theta_0 + \theta_1)\}]/\sigma^2. \tag{3.1}$$

If  $\sigma^2$  is unknown the likelihood of  $(X_1,...,X_T)$  maximized over  $\sigma^2$  conditional on  $\tau=t$  is proportional to  $\left\{\sum_{t=1}^T (X_t-\theta_1)^2 - \sigma^2 \sum_{t=1}^t U_t\right\}^{-\frac{1}{2}T} \quad (t=1,...,T-1),$ 

so that  $\hat{\tau}$  is the value of t which maximizes  $\sigma^2 \sum_{i=1}^t U_i$ . Hence the results of § 2 also apply when  $\sigma^2$  is unknown.

Now the random walk increments  $Y_i$  and  $Y_i'$  are, by (3·1), identically distributed  $N(-2\Delta^2, 4\Delta^2)$ , where  $\Delta = |\theta_1 - \theta_0|/(2\sigma)$ . The distribution of  $\hat{\tau}$  will be unchanged if both  $Y_i$  and  $Y_i'$  are rescaled by a factor  $(2\Delta)^{-1}$ . Therefore, without loss of generality we can take  $Y_i$  and  $Y_i'$  to be  $N(-\Delta, 1)$ . Further, the distribution of  $\hat{\tau}$  is symmetric about  $\tau$  since  $Y_i$  and  $Y_i'$  are identically distributed, so we can omit the redundant prime superfix used in § 2 and consider only the distribution of  $\hat{\tau}$  for  $\hat{\tau} \geqslant \tau$ . To emphasize their dependence on  $\Delta$ , the functions  $\alpha(.), \beta_k(.), ...$  will be denoted by  $\alpha(., \Delta), \beta_k(., \Delta), ...$ 

First we summarize the exact results of § 2·1 for this special case. Let

$$p_k(\Delta) = \operatorname{pr}(\hat{\tau} = \tau \pm k; \Delta).$$

Then we have immediately from (2.8) and (2.22) that

$$p_0(\Delta) = \{\alpha(0, \Delta)\}^2, \tag{3.2}$$

$$1 - \alpha(x, \Delta) = 1 - \Phi(x + \Delta) + \int_0^\infty \left\{ 1 - \alpha(u, \Delta) \right\} \phi(x - u + \Delta) \, du, \tag{3.3}$$

where  $\phi$  and  $\Phi$  are respectively the standard normal density function and integral. Also, by (2·17) and the symmetry of  $\hat{\tau}$ ,

$$p_k(\Delta) = q_k(\Delta) - \int_0^\infty \left\{ 1 - \alpha(u, \Delta) \right\} \beta_k(u, \Delta) \, du, \tag{3.4}$$

where  $q_k(\Delta) = \operatorname{pr}(I = k; \Delta)$ . It is not difficult to see from (2·14), (2·15), (2·16) and (2·21) that when  $Y_j$  is  $N(-\Delta, 1)$ ,  $q_k(\Delta)$  satisfies the recurrence relation

$$q_{k+1}(\Delta) = \frac{1}{k+1} \sum_{j=0}^{k} q_{j}(\Delta) \Phi\{-\Delta \sqrt{(k+1-j)}\} \quad (k \geqslant 1)$$
 (3.5)

with  $q_0(\Delta) = \alpha(0, \Delta)$ .

We use the technique outlined in §2·2 for approximating to the distribution (3·4), first approximating  $\{1 - \alpha(x, \Delta)\}$  by

$$\sum_{r=1}^{R} a_r(\Delta) \exp\left\{-\omega_r(\Delta)x\right\},\tag{3.6}$$

as in (2·19). Then the approximation to (3·4) is, by (2·20),

$$p_k(\Delta) = q_k(\Delta) - \sum_{r=1}^{R} \alpha_r(\Delta) \tilde{\beta}_k \{ \omega_r(\Delta), \Delta \}.$$
 (3.7)

The Laplace transforms  $\tilde{\beta}_k(\omega, \Delta)$  satisfy a recurrence relation which we deduce from (2·13), (2·14), (2·16) and (2·21) to be

$$\tilde{\beta}_{k+1}(\omega, \Delta) = \frac{1}{k+1} \sum_{j=0}^{k} \tilde{\beta}_{j}(\omega, \Delta) c_{k+1-j}(\omega, \Delta) \quad (k \geqslant 1)$$
(3.8)

with  $\tilde{\beta}_0(\omega, \Delta) = \alpha(0, \Delta)$  and

$$c_{\nu}(\omega, \Delta) = \exp\left(k\Delta\omega + \frac{1}{2}k\omega^2\right) \Phi\{-(\omega + \Delta)/k\}. \tag{3.9}$$

It remains only to derive the coefficients in the series approximation (3.6).

In this particular case it is easy to deduce from the integral equation (3·3) that as x tends to infinity  $1 - \alpha(x, \Delta) \sim a_1(\Delta) e^{-2\Delta x}.$ 

as may be verified by substitution in (3.3). This asymptotic solution is the first term in (3.6).

The constant  $a_1(\Delta)$  is determined numerically from the numerical solution of (3·3), which follows the outline given in § 2·2.

It is worth describing the numerical solution of (3·3) in some detail. The discrete version of the integral equation in (2·23) implicitly assumed  $\{1-\alpha(x,\Delta)\}$  to be zero for  $x>x_n$  by the necessary truncation, but here this assumption can be removed by substituting

$$1 - \alpha(x, \Delta) = a_1(\Delta) e^{-2\Delta x} \quad (x > x_n)$$

in  $(3\cdot3)$  before taking the discrete approximation to the integral. The discrete equation corresponding to  $(2\cdot23)$  then becomes

where

$$1 - \alpha(jd, \Delta) = \psi(jd + \Delta) + d\sum_{k=0}^{n} h_k \{1 - \alpha(kd, \Delta)\} \phi\{(j-k)d + \Delta\}, \tag{3.10}$$

$$\psi(jd+\Delta) = 1 - \Phi(jd+\Delta) + a_1(\Delta) e^{-2jd\Delta} \left[1 - \Phi\{(n-j)d+\Delta\}\right] \quad (j=0,1,...,n),$$

 $h_0=h_n=\frac{1}{2}$  and  $h_k=1$  otherwise. Here  $a_1(\Delta)$  is unknown, but using successive trial values for  $a_1(\Delta)$  we can determine the correct value by iteration. As an example consider the case  $\Delta=1\cdot 0$  and let  $d=0\cdot 1$  and n=100. The solutions to  $(3\cdot 10)$  for trial values  $a_1(\Delta)=0$  and 1 are given in the first two columns of Table  $3\cdot 1$  in terms of  $\{1-\alpha(x,\Delta)\}\exp(2\Delta x)$ . Both solutions become stable around x=4, but then diverge toward the assumed value of  $a_1(\Delta)$ . The next trial value suggested by these solutions is  $a_1(\Delta)=0\cdot 34$ , and in two more iterations we

Table 3·1. Values of  $\{1 - \alpha(x, \Delta)\} \exp(2\Delta x)$  from (3·10) for three trial values of  $a_1(\Delta)$  with  $\Delta = 1·0$ 

| $x^{a_1(\Delta)}$ | 0             | 1             | 0.32037       |
|-------------------|---------------|---------------|---------------|
| 0                 | 0.19946       | 0.29509       | 0.19939       |
| <b>2</b>          | $\cdot 32396$ | ·38415        | ·32403        |
| 4                 | $\cdot 32039$ | $\cdot 36452$ | ·32035        |
| 6                 | $\cdot 32035$ | $\cdot 36429$ | ·32036        |
| 8                 | $\cdot 31848$ | $\cdot 36799$ | $\cdot 32037$ |
| 10                | $\cdot 25638$ | $\cdot 49121$ | •32037        |
| >10               | .00000        | 1.00000       | $\cdot 32037$ |

Table 3.2. Comparison of exact and approximate values of  $\{1 - \alpha(x, \Delta)\}$  using (3.10) and (3.11):  $\Delta = 1.0$ 

| $\boldsymbol{x}$ | Exact         | Approximate   |
|------------------|---------------|---------------|
| 0.0              | 0.1994        | 0.1988        |
| 0.5              | $\cdot 0969$  | $\cdot 0978$  |
| 1.0              | $\cdot 0414$  | $\cdot 0400$  |
| 1.5              | $\cdot 0161$  | .0154         |
| $2 \cdot 0$      | $\cdot 00593$ | $\cdot 00578$ |
| $3 \cdot 0$      | $\cdot 00079$ | $\cdot 00079$ |

get the final solution in Table  $3\cdot 1$  with  $a_1(\Delta) = 0\cdot 32037$ . Note that this solution reaches its asymptotic form before  $x_n$ . The value of  $x_n$ , in this case  $10\cdot 0$ , is chosen so that this happens, since only then can we be satisfied that the final solution is the solution to  $(3\cdot 3)$ . For advice on this method of solution I am indebted to Dr Morven Gentleman.

To obtain further terms in the series (3.6) it is convenient to remove the first term and work with  $\gamma(x,\Delta) = e^{2\Delta x} \{1 - \alpha(x,\Delta)\} - a_1(\Delta)$ 

rather than  $\{1-\alpha(x,\Delta)\}$ . Numerical solution for  $\gamma(x,\Delta)$  proceeds in the same way as for

Table 3·3. Asymptotic distribution of \(\tau\) in the normal case

|                           | •                              |   |             |             |             |             |             |             |             |             |             | •           | _           |             |             |             |             |             |
|---------------------------|--------------------------------|---|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|
| 1.5                       | $\overrightarrow{P_k(\Delta)}$ | 0.928   | 886.        | .997        |             |             |             |             |             |             |             |             |             |             |             |             |             |             |
|                           |                                |   |             |             |             |             |             |             |             |             |             |             |             |             |             |             |             |             |
|                           | $\overrightarrow{P_k(\Delta)}$ | 0.913   | $\cdot 985$ | $966 \cdot$ |             |             |             |             |             |             |             |             |             |             |             |             |             |             |
|                           | 1.4                            | $\widehat{p_k(\Delta)} \stackrel{\bigcap}{P_k(\Delta)}$         | 0.825       | .070        | $\cdot 013$ |             |             |             |             |             |             |             |             |             |             |             |             |             |
|                           | ſ                              | $\overrightarrow{P_k(\Delta)}$                                  | 0.894       | $\cdot 975$ | $\cdot 663$ | 866.        |             |             |             |             |             |             |             |             |             |             |             |             |
|                           | 1.3                            | $p_k(\Delta) = P_k(\Delta)$                                     | 0.788       | $\cdot 081$ | $\cdot 018$ | $\cdot 005$ |             |             |             |             |             |             |             |             |             |             |             |             |
|                           |                                | $p_k(\Delta) = P_k(\Delta)$                                     | 0.873       | $\cdot 965$ | 886.        | $966 \cdot$ |             |             |             |             |             |             |             |             |             |             |             |             |
|                           | 1.2                            | $p_k(\Delta)$   | 0.746       | $\cdot 092$ | $\cdot 024$ | .007        |             |             |             |             |             |             |             |             |             |             |             |             |
|                           |                                |   |             |             |             |             | .997        |             |             |             |             |             |             |             |             |             |             |             |
|                           | <u>.</u>                       | $\widehat{p_k(\Delta)} \ \widehat{P_k(\Delta)}$                 | 969.0       | $\cdot 103$ | $\cdot 030$ | $\cdot 010$ | $\cdot 004$ |             |             |             |             |             |             |             |             |             |             |             |
| .o.1                      |                                | $\overrightarrow{P_k(\Delta)}$                                  | 0.820       | $\cdot 933$ | $\cdot 971$ | -987        | $\cdot 993$ | .997        |             |             |             |             |             |             |             |             |             |             |
| $\triangle = 0.9(0.1)1.9$ | 0.1                            | $\widehat{p_k(\Delta)} \stackrel{\bigoplus}{P_k(\Delta)}$       | 0.641       | $\cdot 113$ | $\cdot 038$ | $\cdot 015$ | $\cdot 007$ | $\cdot 003$ |             |             |             |             |             |             |             |             |             |             |
| 1                         |                                | $\overrightarrow{P_k(\Delta)}$                                  | 0.40        | $\cdot 911$ | -957        | -977        | 886.        | $\cdot 663$ | $966 \cdot$ |             |             |             |             |             |             |             |             |             |
|                           | 6.0                            | $\widehat{p_k(\Delta)} \stackrel{P_k(\Delta)}{\longrightarrow}$ | 0.579       | $\cdot 121$ | $\cdot 046$ | $\cdot 021$ | $\cdot 010$ | $\cdot 002$ | .003        |             |             |             |             |             |             |             |             |             |
|                           |                                |   |             |             |             |             |             |             |             | $\cdot 995$ | $966 \cdot$ |             |             |             |             |             |             |             |
|                           | 8·0                            | $p_k(\Delta) egin{cases} P_k(\Delta) \end{cases}$               | 0.511       | .127        | $\cdot 054$ | .027        | $\cdot 015$ | 600.        | $\cdot 005$ | $\cdot 003$ | $\cdot 005$ |             |             |             |             |             |             |             |
|                           |                                |   |             |             |             |             |             |             |             |             |             | $\cdot 994$ | 966         |             |             |             |             |             |
|                           | 0.7                            | $p_k(\Delta)$ $P_k(\Delta)$                                     | 0.438       | .128        | $\cdot 061$ | $\cdot 034$ | $\cdot 020$ | $\cdot 013$ | 800.        | $\cdot 005$ | $\cdot 004$ | $\cdot 003$ | $\cdot 002$ |             |             |             |             |             |
| 9.0 9.9                   | $\overrightarrow{P_k(\Delta)}$ | 0.680   | ·804        | .870        | $\cdot 910$ | .936        | .953        | .965        | .974        | $\cdot 981$ | .985        | 686.        | .993        | $966 \cdot$ |             |             |             |             |
|                           | $p_k(\Delta)$                  | 0.360   | $\cdot 124$ | $990 \cdot$ | .040        | $\cdot 026$ | $\cdot 018$ | $\cdot 012$ | $600 \cdot$ | $900 \cdot$ | $\cdot 005$ | $\cdot 004$ | $\cdot 005$ | $\cdot 001$ |             |             |             |             |
|                           |                                | $\overrightarrow{P_k(\Delta)}$                                  | 0.640       | .754        | $\cdot 821$ | .865        | 968         | $\cdot 919$ | .935        | .948        | $\cdot 958$ | $996 \cdot$ | .973        | .982        | .987        | $\cdot 991$ | $\cdot 994$ | $966 \cdot$ |
|                           | }·0 \                          | $p_k(\Delta)$   | 0.280       | .114        | 067         | .044        | $\cdot 031$ | $\cdot 023$ | .017        | $\cdot 013$ | $\cdot 010$ | 800.        | 900·        | .004        | $\cdot 003$ | $\cdot 005$ | $\cdot 001$ | $\cdot 001$ |
|                           | 7                              | 18  | 0           | Н           | 61          | က           | 4           | 70          | 9           | 7           |             | 6           | 01          | 12          | 14          | $^{16}$     | 18          | 20          |
|                           |                                |   |             |             |             |             |             |             |             |             |             |             |             |             |             |             |             |             |

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 $\{1-\alpha(x,\Delta)\}$  with obvious changes. Now truncation at  $x_n$  has negligible effect if we have chosen  $x_n$  correctly. A detailed analysis of  $\gamma(x,\Delta)$  is given by Dr Gentleman in an unpublished Bell Telephone Laboratories Memorandum, but in the present context a satisfactory approximation to  $\{1-\alpha(x,\Delta)\}$  is achieved by fitting a single exponential term to numerical values of  $\gamma(x,\Delta)$  using unweighted least squares. The approximation (3.6) is then

$$1 - \alpha(x, \Delta) = \alpha_1(\Delta) \exp\left\{-\omega_1(\Delta)x\right\} + \alpha_2(\Delta) \exp\left\{-\omega_2(\Delta)x\right\},\tag{3.11}$$

where  $\omega_1(\Delta) = 2\Delta$  and  $\alpha_1(\Delta)$ ,  $\alpha_2(\Delta)$  and  $\omega_2(\Delta)$  are determined numerically. Table 3·2 compares the exact numerical solution of (3·10) with values computed from (3·11) in the case  $\Delta = 1$ . Looking back to (2·9) we can clearly see that the relative error of the approximation (3·7) is no greater than the maximum relative error in the approximation to  $\alpha(x, \Delta)$ , which is less than 0·3 % in this case.

Extensive calculations of (3·7) have been done by the above method for  $0.5 \le \Delta \le 1.5$ ; that is, for a change in normal mean between one and three standard deviations. In each case the values d=0.1 and n=100 were used in (3·10), the relative error of the resulting approximation to  $\alpha(x,\Delta)$  in (3·11) being consistently less than 0.3%. The computed approximations to  $p_k(\Delta)$  are given in Table 3·3 for  $\Delta=0.5(0.1)1.5$  together with the cumulative probabilities

 $P_k(\Delta) = \operatorname{pr}\left(\hat{\tau} \leqslant \tau + k; \Delta\right) = \frac{1}{2} + \frac{1}{2}p_0(\Delta) + \sum_{j=1}^k p_j(\Delta).$ 

The error relative to the values given is estimated to be less than 0.2%. For  $\Delta > 1.5$  the distribution of  $\hat{\tau}$  is heavily concentrated at  $\tau$ : Table 3.4 gives some values of  $p_0(\Delta)$  for  $1.75 \le \Delta \le 3.00$ . When  $\Delta$  is very large,  $\alpha(0,\Delta)$  is close to  $\Phi(\Delta)$ , as can be deduced from the integral equation (3.3); agreement to three figures occurs for  $\Delta > 2.0$ . Consequently

$$p_{0}(\Delta) \sim \{\Phi(\Delta)\}^{2}$$

for large  $\Delta$ . For  $\Delta < 0.5$  the numerical computation of the asymptotic distribution is difficult to handle. We have not derived the limiting distribution of  $\hat{\tau}$  as  $\Delta \rightarrow 0$ .

Table 3·4. Values of 
$$p_0(\Delta)$$
:  $\Delta = 1.75 (0.25) 3.00$   
 $\Delta = 1.75 (0.25) 3.00$   
 $\Delta = 0.00 (0.00) 0.916 (0.953) 0.975 (0.988) 0.994 (0.997)$ 

3.2. 
$$\theta_0$$
 and  $\theta_1$  unknown

In many situations the two means  $\theta_0$  and  $\theta_1$  will be unknown. Here we show that the asymptotic distribution of § 3·1 remains valid. For convenience we assume the variance  $\sigma^2$  to be known and equal to one. The log likelihood of the observed sequence  $(x_1, ..., x_T)$  is, apart from a constant,

$$L(x_1, ..., x_T | \theta_0, \theta_1, \tau) = -\frac{1}{2} \left\{ \sum_{i=1}^{\tau} (x_i - \theta_0)^2 + \sum_{i=\tau+1}^{T} (x_i - \theta_1)^2 \right\}. \tag{3.12}$$

The maximum likelihood estimators for  $\theta_0$  and  $\theta_1$  conditional on  $\tau = t$  are

$$\begin{split} \tilde{\theta}_{0t} &= \frac{1}{t} \sum_{i=1}^{t} x_i = \overline{x}_t, \\ \tilde{\theta}_{1t} &= \frac{1}{T-t} \sum_{i=t+1}^{T} x_i = \overline{x}_t^*, \end{split}$$

say. Then the log likelihood, (3·12), maximized over  $\theta_0$  and  $\theta_1$  conditional on  $\tau=t$ , becomes

$$L(t) = -\frac{1}{2} \left\{ \sum_{i=1}^T \left( x_i - \overline{x}_T \right)^2 - t(T-t) \left( \overline{x}_t - \overline{x}_t^* \right)^2 / T \right\},$$

so that  $\hat{\tau}$  is the value of t which maximizes the observed value  $z_t^2$  of  $Z_t^2$ , say, where

$$Z_t^2 = t(T-t)(\bar{X}_t - \bar{X}_t^*)^2/T \quad (t=1,...,T-1).$$
 (3.13)

It is not difficult to see that this is also true when  $\sigma^2$  is unknown. Note that  $\hat{\tau}$  is the value of t giving the most significant difference between conditional estimates of  $\theta_0$  and  $\theta_1$ .

Now suppose  $\theta_0 > \theta_1$ , then  $(\overline{X}_t - \overline{X}_t^*)$  is positive with probability tending to 1 as t and (T-t) increase indefinitely, so that we can take  $Z_t$  as asymptotically equivalent to  $Z_t^2$  in order to find the distribution of  $\hat{\tau}$ . The sequence  $\{Z_t\}$  is an autocorrelated sequence with complicated covariance and mean structure, but from (3·13) we obtain the autoregressive representation

 $Z_{t+1} = a_{t+1} Z_t + b_{t+1} (X_{t+1} - \overline{X}_T) \quad (t = 1, ..., T-2), \tag{3.14}$ 

where

$$\begin{split} a_t &= \left\{ \frac{\left(t-1\right)\left(T-t+1\right)}{t\left(T-t\right)} \right\}^{\frac{1}{2}}, \\ b_t &= \left\{ \frac{T}{t\left(T-t\right)} \right\}^{\frac{1}{2}}. \end{split}$$

 $O_t = \left\langle \overline{t(T-t)} \right
angle \; .$ 

We shall show that asymptotically (3·14) defines a random walk with a negligible superimposed term. Let  $\tau = \lambda T$  and assume  $\tau$  and  $(T - \tau)$  to be large. Then if  $(t - \tau)$  is o(T),

$$\begin{split} a_t &= 1 - \frac{(1 - 2\lambda)}{2\lambda(1 - \lambda)T} + o(T^{-1}), \\ b_t &= \{\lambda(1 - \lambda)T\}^{-\frac{1}{2}} + o(T^{-1}). \end{split} \tag{3.15}$$

It follows from (3·14) and (3·15) that

$$Z_{\tau+1} - Z_{\tau} = -\frac{(1-2\lambda)}{2\lambda(1-\lambda)T}Z_{\tau} + \frac{X_{\tau+1} - \overline{X}_T}{\{\lambda(1-\lambda)T\}^{\frac{1}{2}}} + \epsilon, \tag{3.16}$$

where  $E(\epsilon) = 0$  and  $\operatorname{var}(\epsilon) = O(T^{-2})$ , since  $\operatorname{var}(Z_{\tau}) = 1$  and  $\operatorname{var}(X_{\tau+1} - \overline{X}_T) = O(1)$ . Then writing  $Z_{\tau} = E(Z_{\tau}) + \eta$ ,  $\overline{X}_T = E(\overline{X}_T) + \xi$ ,

it is not difficult to see that (3·16) becomes

$$Z_{\tau+1}-Z_{\tau}=Y_1+\epsilon',$$

where  $Y_1$  is normally distributed with mean  $-\Delta\{\lambda(1-\lambda)T\}^{-\frac{1}{2}}$  and variance  $\{\lambda(1-\lambda)T\}^{-1}$ ,  $E(\epsilon')=o(T^{-1})$  and  $\mathrm{var}(\epsilon')=O(T^{-2})$ . Similarly we find that, to order  $T^{-2}$ ,

$$Z_{\tau+k} - Z_{\tau} = \sum_{j=1}^{k} Y_j + k\epsilon' \quad (k = 1, 2, ...),$$
 (3.17)

where the  $Y_j$  are identically distributed. Rescaling by a factor  $\{\lambda(1-\lambda)T\}^{\frac{1}{2}}$ , we find that  $(3\cdot17)$  defines a random walk with  $N(-\Delta,1)$  increments plus a linear term whose coefficient has mean  $o(T^{-\frac{1}{2}})$  and variance  $O(T^{-1})$ . A similar representation exists for  $(Z_{\tau-k}-Z_{\tau})$  (k=1,2,...) and we deduce that the asymptotic distribution of  $\hat{\tau}$  is determined by the random walks alone; that is, the results of § 3·1 hold.

When  $\theta_0$  and  $\theta_1$  are unknown, we are also interested in estimating their difference. Since the distribution of  $\hat{\tau}$  depends on  $\Delta = |\theta_1 - \theta_0|/(2\sigma)$ , we are specifically interested in estimating  $\Delta$ . The maximum likelihood estimate  $\hat{\Delta}$  is then given by

$$\hat{\Delta} = |\hat{\theta}_1 - \hat{\theta}_0|/(2\sigma),$$

assuming  $\sigma^2$  to be known, where  $\hat{\theta}_{\nu} = \tilde{\theta}_{\nu\hat{\tau}}$  ( $\nu = 0, 1$ ). Now the distribution of  $(\hat{\tau} - \tau)$  has moments of order 1, therefore it follows that asymptotically

$$\hat{\Delta} = |\tilde{\theta}_{0\tau} - \tilde{\theta}_{1\tau}|/(2\sigma),$$

and hence that  $\hat{\Delta}$  is asymptotically  $N(\Delta, \sigma_{\Lambda}^2)$ , with

$$\sigma_{\Delta}^2 = rac{T}{4 au(T- au)}.$$

For finite T,  $\hat{\Delta}$  will have a positive bias because  $\hat{\tau}$  is obtained by finding the most significant difference  $(\hat{\theta}_{0t} - \hat{\theta}_{1t})$ . In fact it is not difficult to see from the random-walk representation of  $\{Z_t\}$  that  $E(\hat{\theta}_0 - \hat{\theta}_1) = \theta_0 - \theta_1 + \{\lambda(1-\lambda)T\}^{-1}E\{\max(M, M')\} + o(T^{-1})$ , M and M' both having the distribution  $\alpha(x, \Delta)$  as in § 3·1. Thus the bias in  $\hat{\Delta}$  to order  $T^{-1}$  can be computed.

# 3.3. $\theta_0$ known and $\theta_1$ unknown

To complete the analysis of the normal case we look at the situation where one of the means is known, but the other unknown. In practice it will usually happen that  $\theta_0$  is known rather than  $\theta_1$ , therefore we assume that this is so. Then to find the maximum likelihood estimate  $\hat{\tau}$  we note that the log likelihood of  $\tau$  is (3·12) with  $\tilde{\theta}_{1\tau} = \bar{x}_{\tau}^*$  replacing  $\theta_1$ . Hence  $\hat{\tau}$  is the value of t which maximizes

$$S_t^2 = t(\overline{X}_t^* - \theta_0)^2 \quad (t = 1, ..., T - 1),$$

corresponding to  $Z_t^2$  in § 3·2. For  $\theta_1 > \theta_0$ ,  $\hat{\tau}$  is asymptotically equivalent to the value of t which maximizes  $S_t$ , which we can write as

$$S_t = t^{-\frac{1}{2}} \sum_{j=T-t+1}^{T} (X_j - \theta_0).$$

Then by arguments similar to those of §  $3\cdot 2$  we again find that the asymptotic distribution of  $\hat{\tau}$  is that of §  $3\cdot 1$ .

In this case the maximum likelihood estimate  $\hat{\Delta}$  is given by

$$|\theta_0\!-\!\widetilde{\theta}_{1\hat{\tau}}|/(2\sigma)$$

when  $\sigma$  is known, and  $\hat{\Delta}$  is asymptotically  $N(\Delta, \sigma_{\Delta}^2)$  with

$$\sigma_{\Delta}^2 = \frac{1}{4(T- au)}.$$

#### 4. Inference about au

In most situations we not only want to estimate the change-point, but also to make inference about it in the form of a confidence interval or a significance test. For convenience assume that we want to test  $H_0^*$ :  $\tau = \tau_0$  with either the one-sided alternative  $H_1^*$ :  $\tau > \tau_0$  or

the two-sided alternative  $H_2^*$ :  $\tau = \tau_0$ . If  $\theta_0$  and  $\theta_1$  are known, we can use the distribution of  $\hat{\tau}$  to calculate the significance of a sample value of  $\hat{\tau}$ . The likelihood ratio test, however, is easier to apply and is more efficient because  $\hat{\tau}$  is not sufficient, even asymptotically. Only the observations themselves are sufficient and the likelihood ratio test uses all the information.

#### 4.1. General results

Consider the two-sided test of  $H_0^*$  with alternative  $H_2^*$ , and assume  $\theta_0$  and  $\theta_1$  to be known. Then in the notation of § 2 the likelihood ratio test statistic  $\Lambda_2$ , say, is given by

$$\Lambda_2 = L(\hat{\tau}) - L(\tau_0) = \sum_{j=1}^{\hat{\tau}} U_j - \sum_{j=1}^{\tau_0} U_j. \tag{4.1}$$

We reject  $H_0^*$  when the sample value of  $\Lambda_2$  is greater than l, where l is determined by the required test size. Under the null hypothesis  $H_0^*$  we see by (4·1) and the definitions of M and M' in § 2 that  $\Lambda_2 = \max(M, M')$ 

and hence the asymptotic distribution of  $\Lambda_2$  under  $H_0^*$  is

$$P_2(x) = \operatorname{pr}(\Lambda_2 \leqslant x) = \alpha(x)\alpha'(x), \tag{4.2}$$

since M and M' are independent. This distribution is easier to compute than that of  $\hat{\tau}$  since it only requires solution of the integral equations for  $\alpha(x)$  and  $\alpha'(x)$ .

For the one-sided test of  $H_0^*$  with alternative  $H_1^*$  the log likelihood ratio test statistic is

$$\Lambda_1 = \max_{t \ge \tau_0} \left( \sum_{i=1}^t U_i \right) - \sum_{i=1}^{\tau_0} U_i, \tag{4.3}$$

which under  $H_0^*$  becomes  $\Lambda_1 = M'$ . Hence the asymptotic distribution of  $\Lambda_1$  is

$$P_1(x) = \operatorname{pr}(\Lambda_1 \leqslant x) = \alpha'(x). \tag{4.4}$$

# 4.2. The normal case

For the normal case discussed in § 3 with  $\theta_0$ ,  $\theta_1$  and  $\sigma^2$  known the increments  $U_i$  are given by (3·1). Then using the notation of § 3 we find that (4·1) and (4·2) become

$$\Lambda_2 = \left( (\theta_0 - \theta_1) \left[ \sum_{i=1}^{\hat{\tau}} \left\{ X_i - \frac{1}{2} (\theta_0 + \theta_1) \right\} - \sum_{i=1}^{\tau_0} \left\{ X_i - \frac{1}{2} (\theta_0 + \theta_1) \right\} \right] \right) / \sigma^2, \tag{4.5}$$

$$P_2(x,\Delta) = [\alpha\{x/(2\Delta), \Delta\}]^2.$$

Similarly (4.3) and (4.4) become

$$\Lambda_1 = \left( (\theta_0 - \theta_1) \left[ \max_{t \geqslant \tau_0} \sum_{i=1}^t \left\{ X_i - \frac{1}{2} (\theta_0 + \theta_1) \right\} - \sum_{i=1}^{\tau_0} \left\{ X_i - \frac{1}{2} (\theta_0 + \theta_1) \right\} \right] \right) / \sigma^2, \tag{4.6}$$

$$P_1(x, \Delta) = \alpha\{x/(2\Delta), \Delta\}.$$

From computed values of  $\alpha(x, \Delta)$ , we can easily obtain quantiles of  $P_1(x, \Delta)$  and  $P_2(x, \Delta)$ , which we have done for  $\Delta = 0.5(0.1) 1.5$ . Table 4.1 gives the 95, 98 and 99% quantiles of both  $P_1(x, \Delta)$  and  $P_2(x, \Delta)$ , with the notation

$$P_{\nu}(l_{\nu,p},\Delta) = p/100 \quad (\nu = 1,2).$$

If either or both of  $\theta_0$  and  $\theta_1$  are unknown and the variance  $\sigma^2$  is known, the asymptotic distributions  $P_1(x,\Delta)$  and  $P_2(x,\Delta)$  are still appropriate. The log likelihood ratio statistics for  $\theta_0$  and  $\theta_1$  both unknown are

$$\Lambda_1 = rac{1}{2\sigma^2} \max_{t\geqslant au_0} \left(Z_t^2 - Z_{ au_0}^2
ight),$$

$$\Lambda_2 = rac{1}{2\sigma^2} (Z_{\hat{ au}}^2 \! - \! Z_{ au_0}^2),$$

with

$$Z_t^2 = t(T-t) (\bar{X}_t - \bar{X}_t^*)^2 / T$$

as in § 3.2. Similarly if  $\theta_0$  is known but  $\theta_1$  unknown, we hav

$$\Lambda_1 = rac{1}{2\sigma^2} \max_{t \, > \, au_0} \, (S_t^2 - S_{ au_0}^2),$$

$$\Lambda_2 = \frac{1}{2\sigma^2} (S_{\hat{\tau}}^2 - S_{\tau_0}^2),$$

with

$$S_t^2 = t(\overline{X}_t^* - \theta_0)^2$$

as in § 3·3. The asymptotic distributions  $P_1(x, \Delta)$  and  $P_2(x, \Delta)$  for  $\Lambda_1$  and  $\Lambda_2$  can be verified by arguments similar to those of § 3·2.

Table 4·1. The 95, 98 and 99 % quantiles for statistics  $\Lambda_1$  and  $\Lambda_2$ ;  $\Delta = 0.5(0.1)1.5$ 

| Δ           | $l_{	exttt{1,95}}$ | $l_{	exttt{1,98}}$ | $l_{	exttt{1,99}}$ | $l_{ m 2,95}$ | $l_{2, 98}$  | $l_{ m 2,99}$ |
|-------------|--------------------|--------------------|--------------------|---------------|--------------|---------------|
| 0.5         | $2 \cdot 42$       | 3.32               | 4.02               | 3.09          | $4 \cdot 02$ | 4.72          |
| 0.6         | $2 \cdot 32$       | 3.21               | 3.91               | 2.98          | 3.91         | 4.60          |
| 0.7         | $2 \cdot 20$       | 3.10               | 3.80               | 2.88          | 3.79         | 4.48          |
| 0.8         | 2.08               | 2.99               | 3.69               | $2 \cdot 77$  | 3.69         | 4.37          |
| 0.9         | 1.94               | 2.88               | 3.58               | 2.66          | 3.58         | 4.27          |
| 1.0         | 1.79               | 2.76               | 3.47               | 2.53          | 3.48         | 4.17          |
| $1 \cdot 1$ | 1.62               | 2.63               | 3.35               | $2 \cdot 38$  | 3.37         | 4.06          |
| $1 \cdot 2$ | 1.41               | $2 \cdot 48$       | 3.23               | $2 \cdot 22$  | 3.25         | 3.95          |
| 1.3         | 1.18               | $2 \cdot 33$       | 3.11               | $2 \cdot 04$  | 3.10         | 3.84          |
| $1 \cdot 4$ | 0.92               | $2 \cdot 13$       | 2.97               | 1.82          | 2.94         | 3.71          |
| 1.5         | 0.62               | 1.89               | 2.78               | 1.59          | 2.74         | 3.56          |

When the variance  $\sigma^2$  is unknown, the statistics  $\Lambda_1$  and  $\Lambda_2$  are defined as above but with  $\sigma^2$  replaced by its maximum likelihood estimate under the relevant alternative hypothesis,  $H_1^*$  or  $H_2^*$ . For example, if  $\theta_0$  and  $\theta_1$  are known,  $\Lambda_2$  is given by

$$\Lambda_2 = \left( (\theta_0 - \theta_1) \left[ \sum_{i=1}^{\hat{\tau}} \left\{ X_i - \tfrac{1}{2} (\theta_0 + \theta_1) \right\} - \sum_{i=1}^{\tau_0} \left\{ X_i - \tfrac{1}{2} (\theta_0 + \theta_1) \right\} \right] \right) \! / \hat{\sigma}^2,$$

where

$$\hat{\sigma}^2 = \frac{1}{T} \left[ \sum_{i=1}^T (X_i - \theta_1)^2 - (\theta_0 - \theta_1) \sum_{i=1}^{\hat{\tau}} \{X_i - \frac{1}{2}(\theta_0 + \theta_1)\} \right].$$

Although we have not discussed  $\hat{\sigma}^2$  before, it is clearly a consistent estimate and hence the asymptotic distributions of  $\Lambda_1$  and  $\Lambda_2$  are unchanged.

We have shown that the asymptotic distributions of  $\Lambda_1$  and  $\Lambda_2$  are always  $P_1(x, \Delta)$  and  $P_2(x, \Delta)$  as given by (4·5) and (4·6). But if any one of  $\theta_0$ ,  $\theta_1$  and  $\sigma^2$  is unknown the parameter

 $\Delta$  is unknown, so that we cannot compute the relevant significance probabilities exactly. It is possible to obtain bounds for  $P_{\nu}(x,\Delta)$  ( $\nu=1,2$ ) using confidence limits for  $\Delta$  derived from  $\hat{\Delta}$ , but in general these bounds are unsatisfactory particularly for tail probabilities. One direct approach is to estimate  $P_{\nu}(x,\Delta)$  using  $\hat{\Delta}$ . For example, if  $\theta_0$  and  $\theta_1$  are unknown and  $\sigma^2$  is known, it is easy to show that an unbiased estimate of  $P_2(x,\Delta)$  to order  $T^{-1}$  is

$$P_2(x,\hat{\Delta}) - \frac{1}{2}\sigma_{\Delta}^2 \frac{d^2 P_2(x,\hat{\Delta})}{d\Delta^2},$$

where  $\sigma_{\Delta}$  is the variance of  $\hat{\Delta}$  under the hypothesis  $H_0^*$ . This estimate should have a distribution closer to the uniform distribution on (0,1) than  $P_2(x,\hat{\Delta})$ . The notion of uniformity stems from the Neyman-Pearson theory, and is a property we want our analogue of  $P_2(x,\Delta)$  to have. The problem is similar to that of testing a normal mean with unknown variance, except that here we do not have a pair of sufficient statistics: only the observations themselves are sufficient.

The distributions of  $\Lambda_1$  and  $\Lambda_2$  under the alternative  $\tau=\tau_1 \neq \tau_0$  have not been derived, although in the normal case it is easy to show that they depend on absorption probabilities in W and W' with nontrivial boundaries. We have not obtained a solution suitable for computation.

## 5. Empirical results

To see how well the asymptotic results of §§ 3 and 4 work in finite sample situations, we carried out an extensive empirical study of the distributions of  $\hat{\tau}$ ,  $\hat{\Delta}$  and  $\Lambda_2$ . A summary of these results is given here. For several values of T,  $\tau$  and  $\Delta$ , we generated 500 samples of observations using pseudo random normal deviates for the error terms  $\epsilon_i$  in the model

$$X_i = \begin{cases} \theta_0 + e_i & (i=1,\ldots,\tau), \\ \theta_1 + e_i & (i=\tau+1,\ldots,T). \end{cases}$$

To see how the finite sample distributions vary according as  $\theta_0$  and/or  $\theta_1$  are known or unknown, we calculated the empirical distributions under the three assumptions: (i)  $\theta_0$  and  $\theta_1$  both unknown; (ii)  $\theta_0$  known,  $\theta_1$  unknown; (iii)  $\theta_0$  and  $\theta_1$  both known, in the same samples. The estimate  $\hat{\Delta}$  is redundant under assumption (iii).

Inspection of the empirical results showed that agreement between empirical and asymptotic distributions depends on the value of  $D=\Delta/\sigma_{\Delta}$  when  $\Delta$  is unknown. If D is large the two means are easily distinguished, in which case we would expect the asymptotic properties of  $\hat{\tau}$  and  $\Lambda_2$  to be good approximations. Table 5·1 contains the empirical and asymptotic means and variances of  $\hat{\tau}$  and  $\hat{\Delta}$  for four cases with  $\Delta=0$ ·5. On the basis of all the empirical results it seems safe to take cases with D greater than 6 as well defined in the sense of practical validity of the asymptotic results. For example, the ill-defined case T=50 and  $\tau=25$  with  $\theta_1$  unknown in Table 5·1 gives variances of  $\hat{\tau}$  and  $\hat{\Delta}$  which are appreciably larger than the asymptotic values. Probability plots of the asymptotic and empirical distributions reinforce these conclusions. When both  $\theta_0$  and  $\theta_1$  are known the agreement between empirical and asymptotic distributions is good provided that the asymptotic distribution of  $\hat{\tau}$  is concentrated between 1 and T.

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Table 5·1. Comparison of empirical and asymptotic moments of  $\hat{\tau}$  and  $\hat{\Delta}$ . (i)  $\theta_0$  and  $\theta_1$  unknown, (ii)  $\theta_0$  known,  $\theta_1$  unknown, and (iii)  $\theta_0$  and  $\theta_1$  known.  $\Delta = 0.5$ 

|                 | Emp                      | oirical   | Asymptotic                                  | $\mathbf{Emp}$    | pirical                                 | Asymptotic                         |  |
|-----------------|--------------------------|---|---|-------------------|---|------------------------------------|--|
| Case            | $E\left(\hat{	au} ight)$ | $\overline{\mathrm{Var}\left(\hat{	au}\right)}$ | $\operatorname{Var}\left(\hat{\tau}\right)$ | $E(\hat{\Delta})$ | $\overline{\mathrm{Var}(\hat{\Delta})}$ | $\operatorname{Var}(\hat{\Delta})$ |  |
| $T=50,\tau=15$  |                          |   |   |                   |   |                                    |  |
| (i) $D = 3.2$   | 20.3                     | 83.6  | $24 \cdot 1$                                | 0.56              | 0.054                                   | 0.024                              |  |
| (ii) $D = 5.9$  | 14.8                     | 19.5  | $24 \cdot 1$                                | •50               | $\cdot 0095$                            | $\cdot 0072$                       |  |
| (iii)           | 15.0                     | $23 \cdot 2$                                    | $24 \cdot 1$                                | _                 | _                                       |                                    |  |
| $T=50,\tau=25$  |                          |   |   |                   |   |                                    |  |
| (i) $D = 3.5$   | $25 \cdot 5$             | 41.7  | $24 \cdot 1$                                | •59               | .037                                    | .020                               |  |
| (ii) $D = 5.0$  | $24 \cdot 8$             | 31.4  | $24 \cdot 1$                                | •51               | .015                                    | .010                               |  |
| (iii)           | $25 \cdot 4$             | 25.5  | $24 \cdot 1$                                | —                 |   |                                    |  |
| $T=100,\tau=25$ |                          |   |   |                   |   |                                    |  |
| (i) $D = 4.3$   | $25 \cdot 4$             | 60.5  | $24 \cdot 1$                                | .56               | .019                                    | .013                               |  |
| (ii) $D = 8.6$  | $25 \cdot 3$             | 25.0  | $24 \cdot 1$                                | •51               | $\cdot 0035$                            | $\cdot 0033$                       |  |
| (iii)           | $25 \cdot 3$             | 21.6  | $24 \cdot 1$                                | _                 |   |                                    |  |
| $T=200,\tau=50$ |                          |   |   |                   |   |                                    |  |
| (i) $D = 6.1$   | $50 \cdot 4$             | $31 \cdot 1$                                    | $24 \cdot 1$                                | •51               | .0065                                   | .0067                              |  |
| (ii) $D = 12.3$ | 50.0                     | $26 \cdot 3$                                    | $24 \cdot 1$                                | •50               | .0018                                   | .0017                              |  |
| (iii)           | 50.0                     | $24 \cdot 3$                                    | $24 \cdot 1$                                |                   | -                                       | _                                  |  |

#### 6. Further developments

The empirical results described in § 5 show that the asymptotic distributions of  $\hat{\tau}$ ,  $\Lambda_1$ ,  $\Lambda_2$  and  $\hat{\Delta}$  are poor approximations in small samples, or more precisely in ill-defined cases. Analysis of the finite sample distributions is needed, but appears to be difficult. For  $\theta_0$  and  $\theta_1$  known, a finite sample version of (2·13) exists but is very complicated; see Feller (1966, Chap. 18). In the normal case with unknown means (§ 3·2) the exact finite sample distributions involve extremely complicated multivariate normal integrals.

It is not difficult to verify that the results of §§ 3 and 4 also apply to inference about  $\tau$  in the parallel line regression model

$$X_t = \alpha_0 + \beta v_t + e_t \quad (t = 1, \dots, \tau),$$
  
$$X_t = \alpha_1 + \beta v_t + e_t \quad (t = \tau + 1, \dots, T),$$

where z is an independent variable and the  $e_t$  are independent  $N(0, \sigma^2)$ . For if  $\alpha_0, \alpha_1, \beta$  and  $\sigma^2$  are known, the log likelihood increments  $U_i$  corresponding to (3·1) are given by

$$U_i = [(\alpha_1 - \alpha_0) \{X_i - \frac{1}{2}(\alpha_0 + \alpha_1) - \beta v_i\}]/\sigma_2$$

and the asymptotic results of §§ 3·1 and 4·2 hold with  $\Delta = |\alpha_1 - \alpha_0|/(2\sigma)$ . If  $\alpha_0$ ,  $\alpha_1$  and  $\beta$  are unknown, the results of §§ 3·2 and 4·2 hold with

$$Z_t^2 = [t(T-t)\{\overline{X}_t - \overline{X}_t^* - \widetilde{\beta}_t(\overline{v}_t - \overline{v}_t^*)\}^2]/T,$$

where  $\tilde{\beta}_t$  is the maximum likelihood estimate of  $\beta$  conditional on  $\tau = t$ ; see, for example, (3·13).

The arguments of §§ 2 and 3 are directly relevant to the asymptotic distribution of the

cumulative sum scheme estimate of  $\tau$ , which is the significant turning-point in the cumulative sum plot (Page, 1957). A detailed account of this problem is given in the author's unpublished Ph.D. thesis and will be published elsewhere.

The results of § 2 are, of course, applicable to nonnormal distributions. In fact they can be generalized to include discrete distributions, the simplest case being that of binary data with changing binomial parameter. Nor are the arguments of § 2 restricted to problems with one distribution  $f(x, \theta)$ . It is just as easy to deal with the case of a change in distribution from  $f_0(x, \theta)$  to  $f_1(x, \phi)$ .

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