# ECON675: Assignment 2

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### 1 Question 1: Kernel Density Estimation

#### 1.1 Density derivatives

I follow the derivation in Hansen's notes. We are interested in estimating

$$f^{(s)}(x) = \frac{d^s}{dx^s} f(x).$$

The natural estimator is

$$\hat{f}^{(s)}(x) = \frac{d^s}{dx^s} \hat{f}(x)$$

Now, we know that  $\hat{f}(x) = \frac{1}{nh} \sum_{i} K\left(\frac{X_i - x}{h}\right)$ . Thus,

$$\hat{f}^{(1)}(x) = \frac{-1}{nh^2} \sum_{i=1}^n K^{(1)} \left( \frac{X_i - x}{h} \right),$$

$$\hat{f}^{(2)}(x) = \frac{1}{nh^3} \sum_{i=1}^n K^{(2)} \left( \frac{X_i - x}{h} \right),$$

:

$$\hat{f}^{(s)}(x) = \frac{(-1)^s}{nh^{1+s}} \sum_{i=1}^n K^{(s)} \left( \frac{X_i - x}{h} \right).$$

Now,

$$\mathbb{E}[\hat{f}^{(s)}(x)] = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}\left[\frac{(-1)^{s}}{h^{1+s}} K^{(s)} \left(\frac{X_{i} - x}{h}\right)\right]$$

$$= \mathbb{E}\left[\frac{(-1)^{s}}{h^{1+s}} K^{(s)} \left(\frac{X_{i} - x}{h}\right)\right], \text{ since } X_{i} \text{ are iid.}$$

$$= \int_{-\infty}^{\infty} \frac{(-1)^{s}}{h^{1+s}} K^{(s)} \left(\frac{z - x}{h}\right) f(z) dz$$

Next, we want to use integration by parts:  $\int u dv = uv - \int v du$ . Define

$$dv = \frac{(-1)^s}{h^s} \frac{1}{h} K^{(s)} \left( \frac{z - x}{h} \right) \implies v = \frac{(-1)^s}{h^s} K^{(s-1)} \left( \frac{z - x}{h} \right)$$

And

$$u = f(z) \implies du = f^{(1)}(z).$$

Thus,

$$\begin{split} \mathbb{E}[\hat{f}^{(s)}(x)] &= \left[\frac{(-1)^s}{h^s} K^{(s-1)} \left(\frac{z-x}{h}\right) f^{(1)}(z)\right]_{-\infty}^{\infty} - \int_{-\infty}^{\infty} \frac{(-1)^s}{h^s} K^{(s-1)} \left(\frac{z-x}{h}\right) f^{(1)}(z) dz \\ &= - \int_{-\infty}^{\infty} \frac{(-1)^s}{h^s} K^{(s-1)} \left(\frac{z-x}{h}\right) f^{(1)}(z) dz \end{split}$$

Repeating this s times give

$$\mathbb{E}[\hat{f}^{(s)}(x)] = (-1)^s \int_{-\infty}^{\infty} \frac{(-1)^s}{h} K\left(\frac{z-x}{h}\right) f^{(s)}(z) dz$$
$$= \int_{-\infty}^{\infty} \frac{1}{h} K\left(\frac{z-x}{h}\right) f^{(s)}(z) dz$$

Next, use the following change of variables:  $u = \frac{z-x}{h}$ , which implies  $z = x + hu \implies dz = hdu$ . Thus,

$$\mathbb{E}[\hat{f}^{(s)}(x)] = \int_{-\infty}^{\infty} K(u)f^{(s)}(x+hu)du \tag{1}$$

The next step is to take a Taylor expansion of  $f^{(s)}(x + hu)$  around x + hu = x, which is valid if  $h \to 0$ . We get

$$f^{(s)}(x+hu) = f^{(s)}(x) + f^{(s+1)}(x)hu + \frac{1}{2}f^{(s+2)}(x)h^2u^2 + \dots + \frac{1}{P!}f^{(s+P)}(x)h^Pu^P + o(h^P).$$

Substituting this expression back into (1), integrating over each term, and using the fact that  $\int_{-\infty}^{\infty} K(u)du = 1$  and the notation

$$\mu_{\ell}(K) = u^{\ell}K(u)$$

gives

$$\mathbb{E}[\hat{f}^{(s)}(x)] = f^{(s)}(x) + f^{(s+1)}(x)h\mu_1(K) + \frac{1}{2}f^{(s+2)}(x)h^2\mu_2(K) + \dots + \frac{1}{P!}f^{(s+P)}(x)h^P\mu_P(K) + o(h^P).$$

Finally, noting that since K is a P-order kernel,  $\mu_{\ell}(K) = 0$  for all  $\ell < P$ , gives the desired result

$$\mathbb{E}[\hat{f}^{(s)}(x)] = f^{(s)}(x) + \frac{1}{P!} f^{(s+P)}(x) h^P \mu_P(K) + o(h^P). \tag{2}$$

Next we consider the variance of the derivative estimator.

$$\mathbb{V}[\hat{f}^{(s)}(x)] = \mathbb{V}\left[\frac{(-1)^s}{nh^{1+s}} \sum_{i=1}^n K^{(s)}\left(\frac{X_i - x}{h}\right)\right]$$
$$= \frac{1}{nh^{2+2s}} \mathbb{V}\left[K^{(s)}\left(\frac{X_i - x}{h}\right)\right],$$

since  $\{X_i\}$  are iid there are no covariance terms and each term has the same variance. Continuing,

$$\mathbb{V}[\hat{f}^{(s)}(x)] = \frac{1}{nh^{2+2s}} \left\{ \mathbb{E}\left[K^{(s)}\left(\frac{X_i - x}{h}\right)^2\right] - \mathbb{E}\left[K^{(s)}\left(\frac{X_i - x}{h}\right)\right]^2 \right\}$$

$$= \frac{1}{nh^{2+2s}} \mathbb{E}\left[K^{(s)}\left(\frac{X_i - x}{h}\right)^2\right] - \frac{1}{n} \mathbb{E}\left[\frac{1}{h^{1+s}}K^{(s)}\left(\frac{X_i - x}{h}\right)\right]^2 \tag{3}$$

Now, from above we know that

$$\mathbb{E}\left[\frac{1}{h^{1+s}}K^{(s)}\left(\frac{X_i - x}{h}\right)\right] = f^{(s)}(x) + \frac{1}{P!}f^{(s+P)}(x)h^P\mu_P(K) + o(h^P)$$
$$= f^{(s)}(x) + o(1)$$

since the remainder goes to zero as  $h \to 0$ . Thus, the second term in (3) is  $O(\frac{1}{n})$ ; i.e. the same order as 1/n. Furthermore  $O(\frac{1}{n})$  is of smaller order than  $O(\frac{1}{nh^{1+2s}})$  since  $h \to 0$  and  $n \to \infty$ . Accordingly, we can write

$$\mathbb{V}[\hat{f}^{(s)}(x)] = \frac{1}{nh^{2+2s}} \mathbb{E}\left[K^{(s)} \left(\frac{X_i - x}{h}\right)^2\right] + o\left(\frac{1}{nh^{1+2s}}\right),$$

Thus,

$$\mathbb{V}[\hat{f}^{(s)}(x)] = \frac{1}{nh^{1+2s}} \int_{-\infty}^{\infty} \frac{1}{h} K^{(s)} \left(\frac{z-x}{h}\right)^2 f(z) dz + o\left(\frac{1}{nh^{1+2s}}\right)$$

Again we use the change of variables  $u = \frac{z-x}{h}$  so that

$$\mathbb{V}[\hat{f}^{(s)}(x)] = \frac{1}{nh^{1+2s}} \int_{-\infty}^{\infty} K^{(s)}(u)^2 f(x+hu) du + o\left(\frac{1}{nh^{1+2s}}\right)$$

With the usual Taylor expansion of f(x + hu) we can write

$$\mathbb{V}[\hat{f}^{(s)}(x)] = \frac{1}{nh^{1+2s}} \int_{-\infty}^{\infty} K^{(s)}(u)^{2} (f(x) + O(h)) du + o\left(\frac{1}{nh^{1+2s}}\right)$$

$$= \frac{f(x)}{nh^{1+2s}} \int_{-\infty}^{\infty} K^{(s)}(u)^{2} du + o\left(\frac{1}{nh^{1+2s}}\right)$$

$$= \frac{1}{nh^{1+2s}} f(x) \vartheta_{s}(K) + o\left(\frac{1}{nh^{1+2s}}\right),$$

where  $\vartheta_s(K) = \int_{-\infty}^{\infty} K^{(s)}(u)^2 du$  as required.

#### 1.2 Optimal bandwidth

We have

$$AIMSE[h] = \int_{-\infty}^{\infty} \left[ \left( h^P \mu_P(K) \cdot \frac{f^{(P+s)}(x)}{P!} \right)^2 + \frac{1}{nh^{1+2s}} \vartheta_s(K) f(x) \right] dx$$
$$= h^{2P} \left( \frac{\mu_P(K)}{P!} \right)^2 \vartheta_{s+P}(f) + \frac{1}{nh^{1+2s}} \vartheta_s(K),$$

since f(x) integrates to 1 and where  $\vartheta_{s+P}(f) = \int (f^{(P+s)}(x))^2 dx$ . Thus,

$$\frac{d}{dh} \text{AIMSE}[h] = 2Ph^{2P-1} \left(\frac{\mu_P(K)}{P!}\right)^2 \vartheta_{s+P}(f) - (1+2s) \frac{1}{nh^{2+2s}} \vartheta_s(K) = 0$$

$$\implies 2Ph^{1+2P+2s} \left(\frac{\mu_P(K)}{P!}\right)^2 \vartheta_{s+P}(f) = (1+2s) \frac{1}{n} \vartheta_s(K),$$

which gives the optimal bandwidth

$$h^* = \left\lceil \frac{1+2s}{2Pn} \left( \frac{P!}{\mu_P(K)} \right)^2 \frac{\vartheta_s(K)}{\vartheta_{s+P}(f)} \right\rceil^{\frac{1}{1+2P+2s}}.$$

A fully data-driven method for estimating  $h^*$  is cross-validation. This procedure attempts to directly estimate the mean-squared error, and then choose the bandwidth which minimizes this estimate. From the lecture notes the cross-validation bandwidth is the value h which minimizes the criteria

$$\hat{h}_{CV} = \arg\min_{h} CV(h) = \frac{1}{n^2 h} \sum_{i=1}^{n} \sum_{j=1}^{n} (K * K) \left( \frac{X_i - X_j}{h} \right) - \frac{2}{n} \sum_{i=1}^{n} \hat{f}_{(i)}(X_i)$$

where  $\hat{f}_{(i)}(x_i)$  is the density estimate computed without observation  $X_i$ .

### 1.3 Monte Carlo experiment

(a) First, we want to compute the theoretically optimal bandwidth for s = 0, n = 1000, using the Epanechnikov kernel (P = 2), with the following Gaussian DGP:

$$x_i \sim 0.5\mathcal{N}(-1.5, -1.5) + 0.5\mathcal{N}(1, 1)$$

From Table 1 in Hansen's notes,  $\mu_2(K) = 1/5$  and  $\vartheta(K) = 3/5$  for the Epanechnikov kernel. Thus, the only other ingredient we need is  $\vartheta_2(f) = \int [f^{(2)}(x)]^2 dx$  for the above DGP. Note that the second derivative of the normal density with mean  $\mu$  and variance  $\sigma^2$  is

$$\phi_{\mu,\sigma^2}^{(2)}(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{\sigma^2}\right) \left[\left(\frac{x-\mu}{\sigma^2}\right)^2 - \frac{1}{\sigma^2}\right]$$

Since differentiation is a linear operation, we have

$$\vartheta_2(f) = \int_{-\infty}^{\infty} [0.5 \times \phi_{-1.5,1.5}^{(2)}(x) + 0.5 \times \phi_{1,1}^{(2)}(x)]^2 dx \approx 0.0388.$$

Finally, we get the theoretically optimal bandwidth

$$h^* = \left[ \frac{1}{2 \times 2 \times 1000} \left( \frac{2!}{1/5} \right)^2 \frac{3/5}{\vartheta_2(f)} \right]^{\frac{1}{1+2 \times 2}} \approx 0.827.$$

### 2 Linear smoothers, cross-validation and series

#### 2.1 Local polynomial and series estimation as linear smoothers

We are interested in estimating the regression function  $e(x) = \mathbb{E}[y_i|x_i = x]$ . The idea of local polynomial regression is to approximate e(x) locally by a polynomial of degree p, and estimate this local approximation by weighted least squares. For each x we solve

$$\hat{\beta}(x) = \arg\min_{\beta \in \mathbb{R}^{p+1}} \sum_{i=1}^{n} [y_i - \beta_0 - \beta_1(x_i - x) - \beta_2(x_i - x)^2 - \dots - \beta_p(x_i - x)^p]^2 K\left(\frac{x_i - x}{h}\right).$$

where

$$\hat{e}(x) = \hat{\beta}_0$$

Note that this is motivated by a Taylor expansion of the true regression function  $e(x_i)$  around x. And note that the kernel is just a 'smooth' way of weighting observations that are close to the evaluation point x.

More compactly, we write

$$\hat{\boldsymbol{\beta}}_{LP}(x) = \arg\min_{\beta \in \mathbb{R}^{p+1}} \sum_{i=1}^{n} [y_i - \boldsymbol{r}_p(x_i - x)'\boldsymbol{\beta}]^2 K\left(\frac{x_i - x}{h}\right)$$

where  $\mathbf{r}_p(u)$  is an operator such that  $\mathbf{r}_p(u) = (1, u, u^2, ..., u^p)'$ .

From the lecture notes, we know that

$$\hat{\boldsymbol{\beta}}(x) = (\boldsymbol{R}_p' \, \boldsymbol{W} \, \boldsymbol{R}_p)^{-1} \boldsymbol{R}_p' \, \boldsymbol{W} \, \boldsymbol{y}$$

where

$$\mathbf{R}_{p} = \begin{bmatrix} 1 & (x_{1} - x) & (x_{1} - x)^{2} & \dots & (x_{1} - x)^{p} \\ 1 & (x_{2} - x) & (x_{2} - x)^{2} & \dots & (x_{2} - x)^{p} \\ \vdots & \vdots & \dots & \ddots & \vdots \\ 1 & (x_{n} - x) & (x_{n} - x)^{2} & \dots & (x_{n} - x)^{p} \end{bmatrix}$$

and  $\mathbf{W} = \operatorname{diag}\left(K\left(\frac{x_1-x}{h}\right), K\left(\frac{x_2-x}{h}\right), ..., K\left(\frac{x_n-x}{h}\right)\right)$ .

Then

$$\hat{\boldsymbol{e}}(x) = \boldsymbol{e}_1' \hat{\boldsymbol{\beta}}(x) 
= \boldsymbol{e}_1' (\boldsymbol{R}_p' \boldsymbol{W} \boldsymbol{R}_p)^{-1} \boldsymbol{R}_p' \boldsymbol{W} \boldsymbol{y}$$

where  $e_1$  the first standard basis vector of length (1+p) (i.e. it has a 1 in the first entry and zeros in the remaining p entries). I think in summation form we can write

$$\hat{\boldsymbol{e}}(x) = \boldsymbol{e}'_1 (\sum_{i=1}^n \boldsymbol{r}_p(x_i - x) \boldsymbol{r}_p(x_i - x)' w_i)^{-1} (\sum_{i=1}^n \boldsymbol{r}_p(x_i - x) w_i y_i)$$

where  $w_i = K\left(\frac{x_i - x}{h}\right)$ .

Next we consider series estimation of the regression function e(x). A series approximation to e(x) is a global approximation, unlike the local polynomial regression. A series approximation that uses a polynomial basis (c.f. splines) takes the form

$$\hat{\boldsymbol{\beta}}_{\mathtt{Series}} = \arg\min_{eta \in \mathbb{R}^{p+1}} \sum_{i=1}^n (y_i - \boldsymbol{r}_p(x_i)' \boldsymbol{\beta})^2$$

where  $\mathbf{r}_p(x_i) = (1, x_i, x_i^2, ..., x_i^p)$ . And

$$\hat{e}(x) = \boldsymbol{r}_p(x)' \hat{\boldsymbol{\beta}}_{\mathtt{Series}}$$

Accordingly, we have

$$\hat{oldsymbol{eta}}_{ exttt{Series}} = \left(oldsymbol{R}_p^\prime oldsymbol{R}_p
ight)^{-1} oldsymbol{R}_p oldsymbol{y}$$

where

$$\mathbf{R}_{p} = \begin{bmatrix} 1 & (x_{1}) & (x_{1})^{2} & \dots & (x_{1})^{p} \\ 1 & (x_{2}) & (x_{2})^{2} & \dots & (x_{2})^{p} \\ \vdots & \vdots & \dots & \ddots & \vdots \\ 1 & (x_{n}) & (x_{n})^{2} & \dots & (x_{n})^{p} \end{bmatrix}$$

And,

$$\hat{e}(x) = \boldsymbol{r}_p(x)' \left(\boldsymbol{R}_p' \boldsymbol{R}_p\right)^{-1} \boldsymbol{R}_p \boldsymbol{y},$$

which is of the linear smoother form. In summation form

$$\hat{e}(x) = \boldsymbol{r}_p(x)' (\sum_{i=1}^n \boldsymbol{r}_p(x_i) \boldsymbol{r}_p(x_i)')^{-1} (\sum_{i=1}^n \boldsymbol{r}_p(x_i) y_i).$$

#### 2.2 Cross validation

The idea of cross-validation is to choose the tuning parameter (e.g. bandwidth, etc.) that minimizes the mean squared leave-one-out error

$$\hat{c} = \arg\min_{c} \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{e}_{(i)}(x_i; c))^2$$

where  $\hat{e}_{(i)}(x_i)$  is the estimator of the regression function that "leaves out"  $x_i$ .

From the above results we know that both the local polynomial and series estimators can be written as

$$\hat{\boldsymbol{e}}(x) = \boldsymbol{S}\boldsymbol{y}$$

where S is the 'smoothing' matrix. Note that for local polynomial and series estimators the smoothing matrix is constant preserving in the sense S1 = 1. That is, the rows of S sum to one. In leave-one-out cross validation, we want to use the same smoother with the i-th row and column deleted to be an  $(n-1) \times (n-1)$  smoother matrix. Accordingly, we must renormalize the rows to sum to one. Let  $w_{ij}$  denote the elements of S. When we delete the i-th column, then the i-th row now sums to  $1 - w_{ii}$ . So, we divide by to renormalize. Accordingly, the leave-one-out estimator is

$$\hat{e}_{(i)}(x_i) = \frac{1}{1 - w_{ii}} \sum_{j=1, j \neq i}^{n} w_{ij} y_i$$

And note that

$$\hat{e}(x_i) = \sum_{j=1}^n w_{ij} y_i.$$

From the above expression we get

$$\hat{e}_{(i)}(x_i)(1 - w_{ii}) = \sum_{j=1, j \neq i}^{n} w_{ij} y_i$$

$$\hat{e}_{(i)}(x_i) = \sum_{j=1, j \neq i}^{n} w_{ij} y_i + w_{ii} \hat{e}_{(i)}(x_i)$$

$$= \sum_{j=1}^{n} w_{ij} y_i + w_{ii} \hat{e}_{(i)}(x_i) - w_{ii} y_i$$

$$= \hat{e}(x_i) + w_{ii} \hat{e}_{(i)}(x_i) - w_{ii} y_i$$

$$\Rightarrow y_i - \hat{e}_{(i)}(x_i) = y_i - \hat{e}(x_i) - w_{ii} \hat{e}_{(i)}(x_i) + w_{ii} y_i$$

$$= y_i - \hat{e}(x_i) + w_{ii}(y_i - \hat{e}_{(i)}(x_i))$$

$$\therefore y_i - \hat{e}_{(i)}(x_i) = \frac{1}{1 - w_{ii}} (y_i - \hat{e}(x_i)),$$

which gives the desired result.