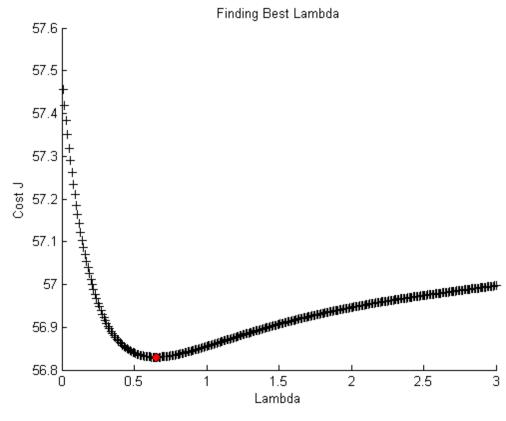
```
%%MADAN MOHAN KURUBA
%%NISHAL PATTAN
%%SRI CHAKRA
%%RAJ KIRAN UPPARI
load('hm2data2.mat')
X = data(:,1:3);
fprintf('\nSize of X');
size(X)
Y = data(:,4);
fprintf('\nSize of Y');
size(Y)
%mean and standard deviation of data X
muX = mean(X);
stdX = std(X);
repstd = repmat(stdX, size(X,1), 1);
repmu = repmat(muX, size(X,1), 1);
%Normalizing X
X norm = (X-repmu)./(repstd);
X_{norm} = [ones(97,1) X_{norm}];
size(X_norm)
%mean(X_norm)
%std(X_norm)
%%%%%L2-regularization%%%%
%size(rand_indices);
X_{train} = X_{norm(1:48,:)};
Y_{train} = Y(1:48,:);
size(X_train)
X_{test} = X_{norm(49:97,:)};
Y test = Y(49:97,:);
size(X_test);
%cost_Reg2(X_train, Y_train, theta, alpha, num_iters,lambda);
%%%%Best Lambda
fprintf('Finding the best lambda ...\n');
%%Using Normal Equation form
%%Find the best lambda
lambda = best_lambda2(X_train, Y_train, X_test, Y_test)
%%%3-Fold validation
% Randomly select half data points to as training_data other as test_data
X_{norm} = X_{norm}(:,1:3);
rand_indices = randperm(size(X_norm))';
%size(rand_indices);
X1 = X_norm(rand_indices(1:32),:);
Y1 = Y(rand_indices(1:32),:);
size(X1);
X2 = X_norm(rand_indices(33:64),:);
Y2 = Y(rand\_indices(33:64),:);
size(X2);
```

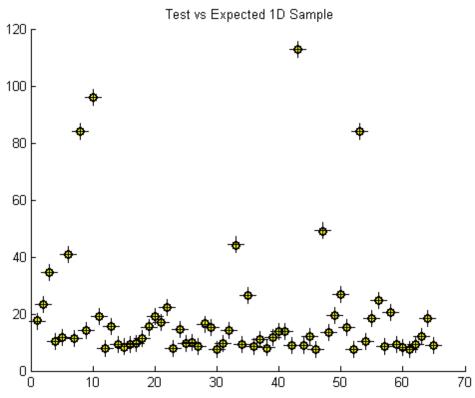
```
X3 = X_norm(rand_indices(65:97),:);
Y3 = Y(rand indices(65:97),:);
size(X3);
%%%%%%% Degree d = 1
error 1d=0;
%Training on X1
theta = zeros(3, 1);
[J, theta] = gdMulti(X1, Y1, theta, 0.5, 600);
%Testing on X2
figure; hold on;
plot([Y2;Y3], 'ko', 'MarkerFaceColor', 'y', 'LineWidth', 2, 'MarkerSize', 7);
plot([X2*theta;X3*theta],'k+','MarkerFaceColor','r','MarkerSize',12);
title(' Test vs Expected 1D Sample')
error_1d= error_1d + computeError(theta, X2, Y2);
%Testing on X3
error_1d= error_1d + computeError(theta,X3,Y3);
%Training on X2
theta = zeros(3, 1);
[J, theta] = gdMulti(X2, Y2, theta, 0.5, 600);
figure; hold on;
plot(1:100,J(1:100));
xlabel('Iterations');ylabel('Cost Value');
title('Gradient Descent');
error 1d =error 1d + computeError(theta, X1, Y1);
error_1d =error_1d + computeError(theta, X3, Y3);
%Training on X3
theta = zeros(3, 1);
[J, theta] = gdMulti(X2, Y2, theta, 0.5, 600);
error_1d =error_1d + computeError(theta,X1,Y1);
error_1d =error_1d + computeError(theta,X3,Y3);
fprintf('Avg Error in 1D : ');
error_1d = error_1d/194;
fprintf('Average Error in 1-D Model : %f\n',error_1d);
%%%% degree d = 2 ;
%%%2nd Dimensions
X1 = [X1(:,1) \ X1(:,2) \ X1(:,3) \ X1(:,2).*X1(:,3) \ X1(:,2).^2 \ X1(:,3).^2];
 \texttt{X2} = [\texttt{X2}(:,1) \ \texttt{X2}(:,2) \ \texttt{X2}(:,3) \ \texttt{X2}(:,2).*\texttt{X2}(:,3) \ \texttt{X2}(:,2).^2 \ \texttt{X2}(:,3).^2]; 
X3 = [X3(:,1) \ X3(:,2) \ X3(:,3) \ X3(:,2).*X3(:,3) \ X3(:,2).^2 \ X3(:,3).^2];
error_2d = 0;
%Training on X1
theta = zeros(6, 1);
[J, theta] = gdMulti(X1, Y1, theta, 0.05, 600);
theta;
%Testing on X2
error1 = Y2-X2*theta;
figure; hold on;
plot([Y2;Y3],'k0','MarkerFaceColor','g','LineWidth',2,'MarkerSize',7);
plot([X2*theta; X3*theta],'k+','MarkerFaceColor','b','MarkerSize',12);
title('Test vs Expected 2D Sample')
error_2d= error_2d + computeError(theta, X2, Y2);
Testing on X3
error_2d = error_2d + computeError(theta,X3,Y3);
```

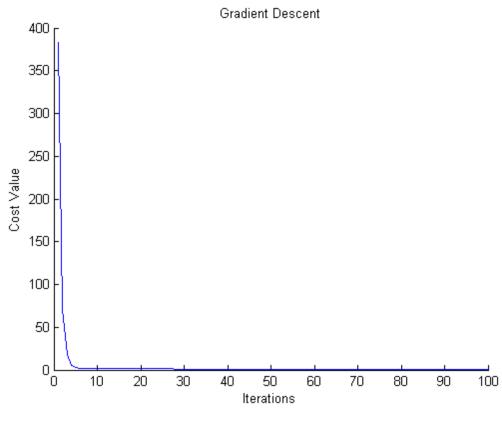
```
%Training on X2
theta = zeros(6, 1);
[J, theta] = gdMulti(X2, Y2, theta, 0.05, 600);
error_2d =error_2d + computeError(theta,X1,Y1);
error_2d =error_2d + computeError(theta, X3, Y3);
%Training on X3
theta = zeros(6, 1);
[J, theta] = gdMulti(X2, Y2, theta, 0.05, 600);
error_2d =error_2d + computeError(theta,X1,Y1);
error_2d =error_2d + computeError(theta,X3,Y3);
fprintf('Avg Error in 2D : ');
error_2d = error_2d/194;
fprintf('Average Error in 2-D Model : %f\n',error_2d);
if error_1d*100 < error_2d*100</pre>
   fprintf('\nAverage Error in 1 Dimentional model is less than 2D\n So we will pr
%%%% Modeling and Generalization Errors %%%%
modelingError=zeros(100,1);
generalizationError=zeros(100,1);
for i=1:100
    rand_indices = randperm(97)';
    %size(rand indices);
    X1 = X \text{ norm(rand indices(1:48),:)};
    Y1 = Y(rand_indices(1:48),:);
    size(X1);
    X2 = X_norm(rand_indices(49:97),:);
    Y2 = Y(rand\_indices(49:97),:);
    size(X2);
    %%%Train the Model
    theta = zeros(3,1);
    [J, theta] = gdMulti(X1, Y1, theta, 0.5, 600);
    modelingError(i) = computeError(theta, X1, Y1)/(length(X1));
    generalizationError(i) = computeError(theta, X2, Y2)/(length(X2));
end
figure; hold on;
plot(1:100, modelingError,1:100, generalizationError, 'LineWidth',2,'MarkerSize',8)
xlabel('Iterations');ylabel('Error Value');
%plot(1:100, generalizationError,'--','LineWidth',2,'MarkerSize',8)
legend('Modeling Error', 'Generalization Error');
fprintf('\n Minimum Modeling Error = %f\n',min(modelingError));
fprintf('\n Maximum Modeling Error = %f\n', max(modelingError));
fprintf('\n Average Modeling Error = %f\n', mean(modelingError));
fprintf('\n\n********************\n\t Generalization Errors\n**************
fprintf('\n Minimum Generalization Error = %f\n',min(generalizationError));
fprintf('\n Maximum Generalization Error = %f\n',max(generalizationError));
fprintf('\n Average Generalization Error = %f\n',mean(generalizationError));
hold off;
%%%Regression Line Plots
figure;
```

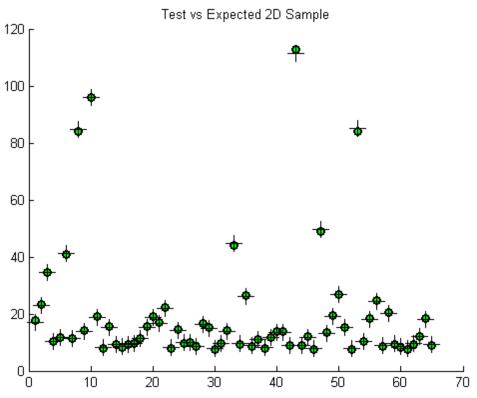
```
subplot(1,2,1);
plot(X2(:,2),Y2,'rx','MarkerSize',10);
hold on;
plot(X2(:,2), X2*theta, 'b-')
xlabel('Attribute W1');
ylabel('Actual and Predicted Values');
subplot(1,2,2);
plot(X2(:,3),Y2,'gx','MarkerSize',10);
hold on;
plot(X2(:,3), X2*theta, 'b--')
xlabel('Attribute W2');
ylabel('Actual and Predicted Values');
legend('Actual Output', 'Linear regression');
% Fill out J_vals
% Grid over which we will calculate J
W1_vals = linspace(-20, 80, 100);
W2_vals = linspace(-20, 50, 100);
[J, theta] = gdMulti(X1, Y1, theta, 0.5, 600);
% initialize J_vals to a matrix of 0's
J_vals = zeros(length(W1_vals), length(W2_vals));
for i = 1:length(W1_vals)
    for j = 1:length(W2_vals)
           t = [theta(1,1); W1_vals(i); W2_vals(j)];
           J_{vals}(i,j) = computeCost(X1(:,1:3), Y1, t,0);
    end
end
J_vals = J_vals';
% Surface plot
figure;
subplot(1,2,1)
surf(W1_vals, W2_vals, J_vals)
xlabel('w 1'); ylabel('w 2');
title('Surface')
% Contour plot
subplot(1,2,2)
contour(W1_vals, W2_vals, J_vals, logspace(-2, 10, 20))
xlabel('W_1'); ylabel('W_2');
hold on;
plot(theta(2), theta(3), 'rx', 'MarkerSize', 10, 'LineWidth', 2);
title('Contour');
Size of X
ans =
    97
            3
Size of Y
ans =
    97
            1
ans =
    97
            4
```

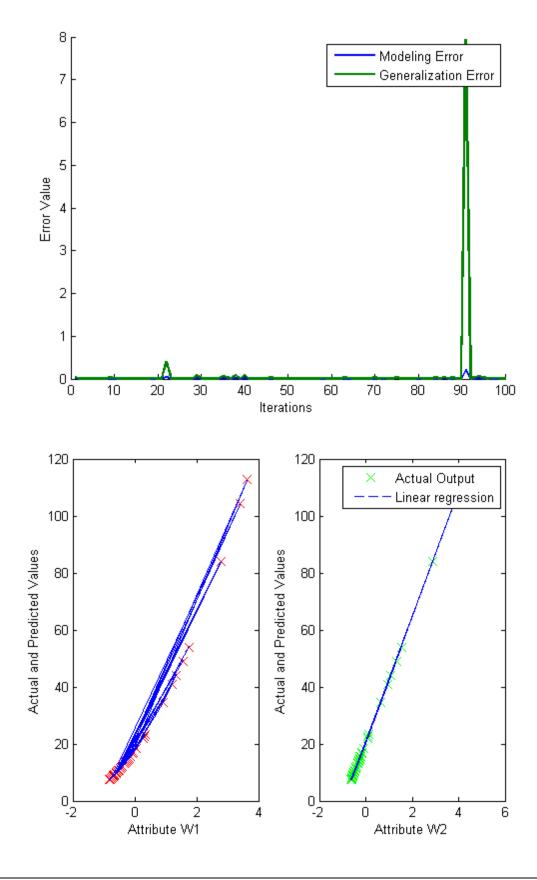
```
ans =
   48
Finding the best lambda ...
Minimum J , theta, lambda
J_min =
  56.8299
theta_at_minJ =
  10.3696
   3.1394
  18.9239
   1.3924
lambda =
   0.6500
lambda =
   0.6500
Warning: Input arguments must be scalar.
Avg Error in 1D : Average Error in 1-D Model : 0.016594
Avg Error in 2D : Average Error in 2-D Model : 0.062250
Average Error in 1 Dimentional model is less than 2D
So we will proceed with is 1D model
        Modeling Errors
*******
Minimum Modeling Error = 0.001957
Maximum Modeling Error = 0.216535
Average Modeling Error = 0.008058
Generalization Errors
Minimum Generalization Error = 0.001029
Maximum Generalization Error = 7.943282
Average Generalization Error = 0.095516
```

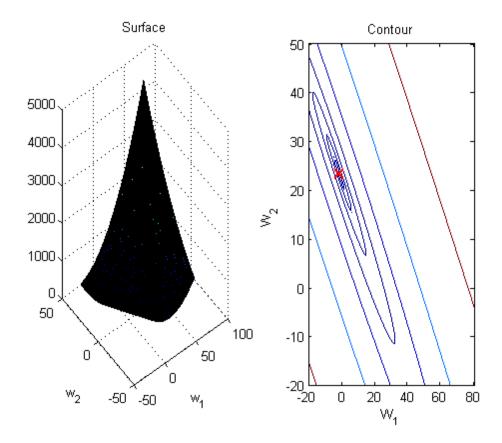












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