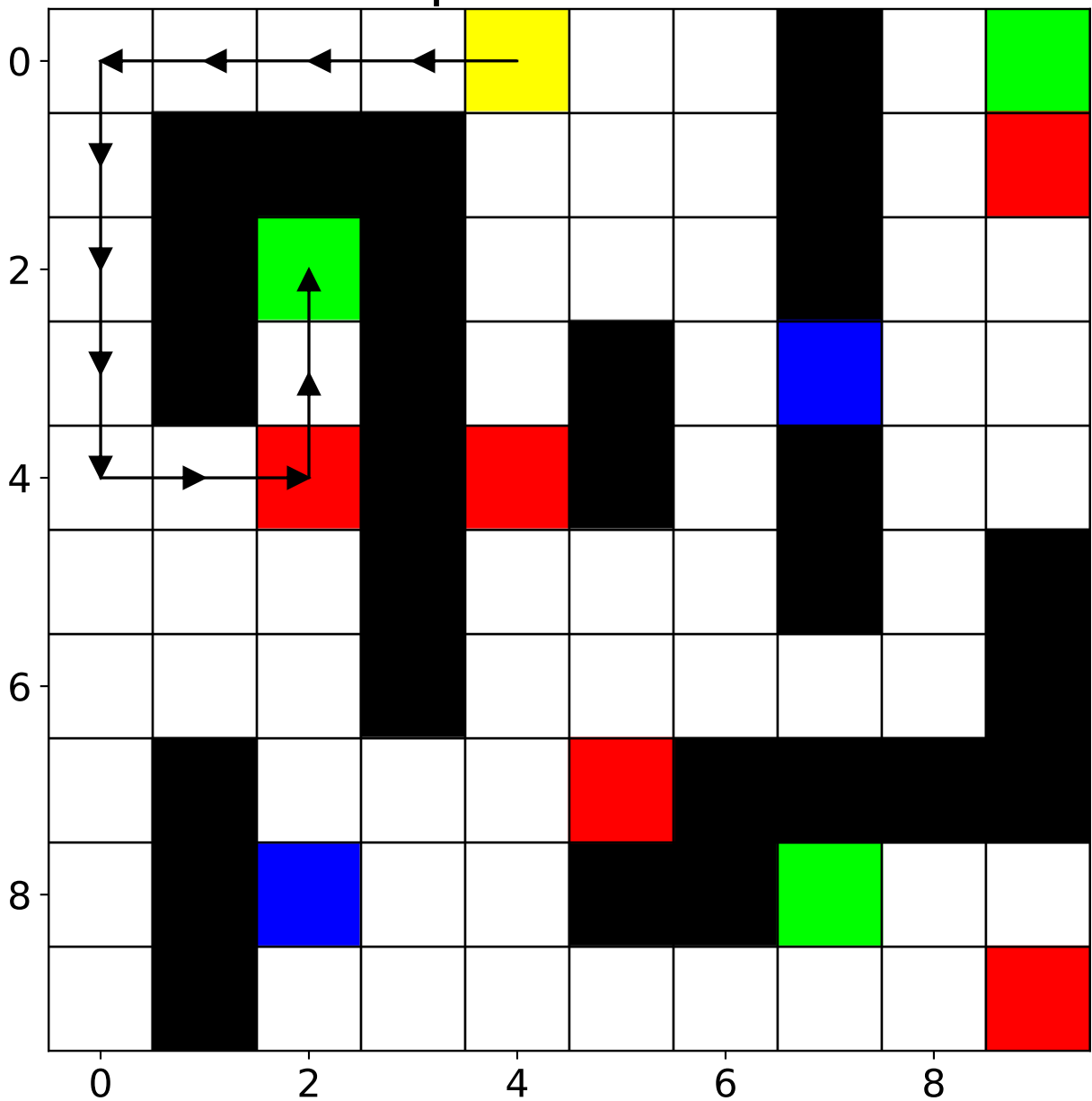


Optimal Path



- | | | | | | |
|--------------|------------|--------------|---------------|---------------|-------------|
| Black square | Obstructed | Blue square | Restart State | Yellow square | Start State |
| Red square | Bad State | Green square | Goal State | | |