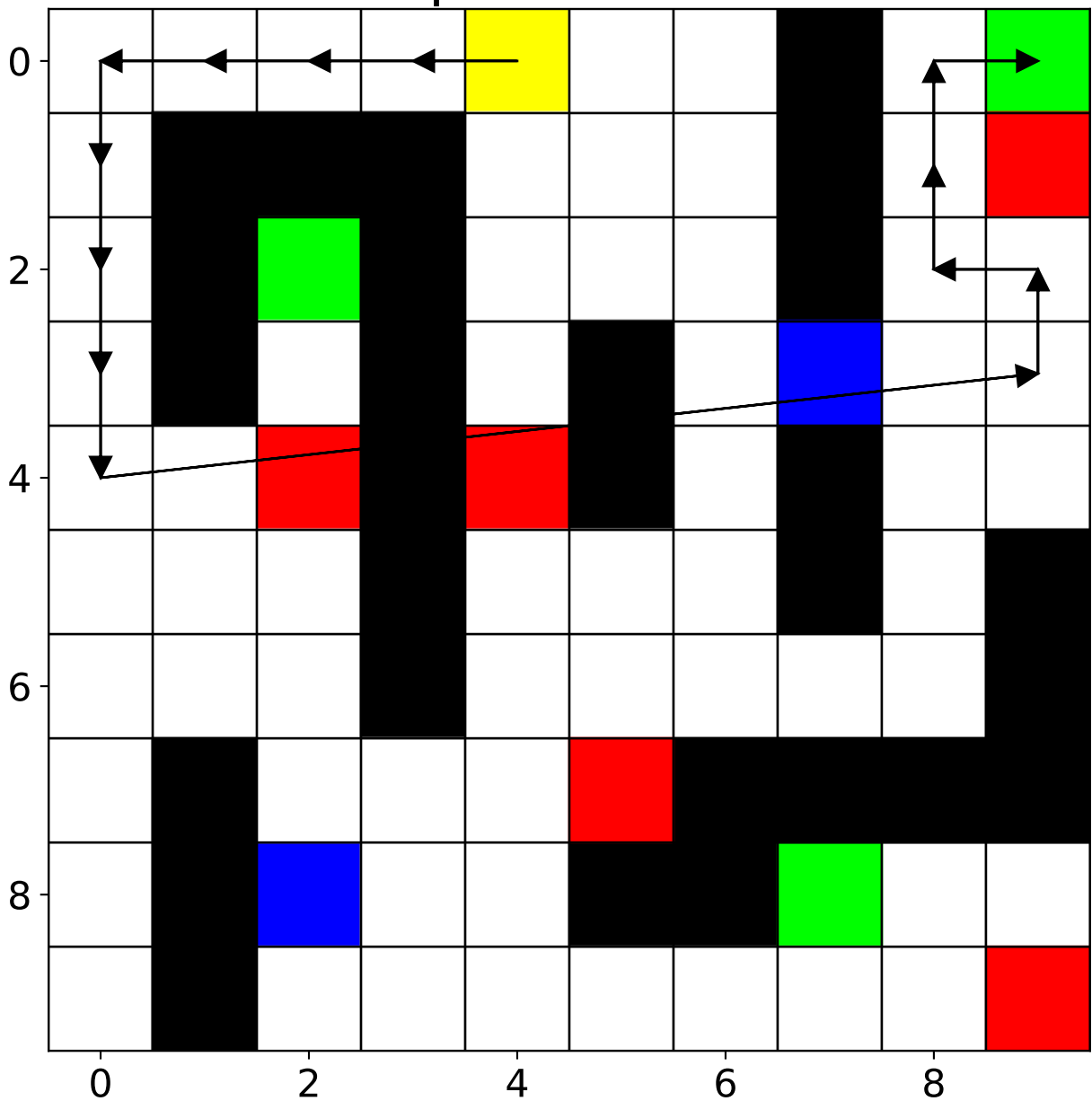


# Optimal Path



- Obstructed
- Restart State
- Start State
- Bad State
- Goal State