

# NISHANTH RAJKUMAR

[MAIL](#) | [LINKEDIN](#) | [PORTFOLIO](#) | [TEAM WEBSITE](#)

## OBJECTIVE

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I am a highly passionate and enthusiastic individual with insightful research exposure and hands-on experience that has intrigued me into pursuing M.eng Mechanical Engineering to explore multidisciplinary research options and contribute to community development to the best of my abilities.

## EDUCATION

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Vellore Institute Of Technology - Chennai, India Jul'18 – Apr'22 (expected)

Under graduation – CGPA 8.4/10

Mechanical Engineer- School of Mechanical Engineering (SMEC)

**(Primary focus on Designing and Simulation, Mechatronics and Artificial Intelligence)**

Maharishi International Residential School Jun'04 – March'18

School – Central Board Of Secondary Education

Computer Science, Physics, Maths, Chemistry

## CORE SKILLS

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**SOFTWARE:** Catia, Solidworks, Adams, Fusion 360, Hypermesh, Ansys, Matlab and Simulink

**PROGRAMMING:** Python, C, C++

**HARDWARE:** CNC's – VMC, Lathe; PLC's and SCADA; 3D - Printers

## PROFESSIONAL EXPERIENCE

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**COMBAT VEHICLES R&D ESTABLISHMENT, DRDO, MINISTRY OF DEFENSE** Nov'21 – Apr'22

Project Intern - **Supervised by Dr. Davidson Jebaseelan**, Professor, VIT and **Dr. Babu, Sc "F"**, CVRDE

- Working on project titled "Design and Simulation of a Robotic Arm for Safe Retrieval of Ammunition from a Jammed Machine Gun".
- Designed a mechanical and a mathematical model for a robotic arm that follows a set of sequential operations with Solid works and Matlab and Validated the entire model with MSc Adams.

**UNIVERSITY OF ALBERTA – CANADA** July'21 – Sep'21

Research Intern – **Supervised by Dr. Kim Adams, Director of AT Lab**, UAlberta

- Project Titled – “Brain Controlled Robot for Disabled Children to enhance their neural activity”
- Applied Python programming and understanding of control systems and mathematical models of physical systems to contribute to student trials on children and patients with special abilities specifically related to neurology

**PROFESSIONAL INSPECTION CONSULTANCY, ASME AUTHORIZED, INDIA** Apr'21 – Jun'21

Summer Research Intern – **Supervised by Dr. Davidson Jebaseelan**, Professor, VIT

- Utilized Finite element analysis as per ASME section VIII Div. Part 5 (Numerical analysis) on the pressure vessel for plastic collapse (Plastic Elastic Analysis).
- Performed FE analysis for API 653 above-ground storage tank and analyzed the impact of wind and seismic activity.

**HI-TECH INDUSTRIES CHENNAI, INDIA** Jun'20 – Jul'20

Industrial Intern

- Undergone a technical internship on various machining processes using different milling center's and also gained detailed knowledge of designing and analysis using CATIA and ANSYS.
- Gained a deep knowledge on analyzing different structures being manufactured.

**Industrial Intern**

- Different parts of a stair-climbing robot were designed, engineered, manufactured and assembled with its required electronic sensors.
- Several AI optimizations were done in order to remove unnecessary weights across the whole frame and had obtained the strongest frame among all other interns.

**PROFESSIONAL PROJECTS**

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**Stress Linearization of a Pressure Vessel and CFD Study Due To External Wind Conditions**

- A pressure vessel with different nozzles and flanges were designed according to their NPS (North American set of standard sizes for pipes).
- The pressure vessel was designed with a fixed and a sliding saddle. Different bending moments on the inside and outside of the supports were analyzed that occurs due to the internal pressure and wind pressure with a speed of (45m/s).

**Design and Analysis of Single Clutch Plate**

- Different parts of single clutch plate such as pilot bearing, clutch plate, pressure plate clutch shaft and helical springs were designed and assembled.
- This assembly was analyzed with different stresses a better material was chosen in order to decrease the stresses across the clutch plate.

**Computational Fluid Dynamic Study of Omega VTOL UAV – Atom Robotics**

- An autonomous aerial planetary system designed for logistics and reconnaissance missions in the Mars environment by my team.
- Completely designed and tested from scratch considering the compatibility for flight in a Martian environment.
- A CFD study was done in order to find the critical or stalling angle of attack with the structural study to check the maximum stresses across different regions of the frame.

**Ablution Assist for Elderly and Disabled**

- Designed an advanced manual Rollator for elderly and disabled people, equipped with Arm Rests and Cutouts, which will help them in their morning ablutions.
- The rollator can be pushed on to a lavatory and the water supply can be connected through a hose in the given slot under the seat.
- Nozzles are added according to a nozzle pipe size grades in order to supply a low-pressure water flow to high pressure flow. Other personal and academic projects can be seen in portfolio ([projects](#))

**RESEARCH EXPERIENCE**

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The Research Details are given in my portfolio ([research](#)).

1. **Generative Design Optimization and Analysis of Connecting Rod for Weight Reduction and performance enhancement**, R Nishanth et al 2021 J. Phys.: Conf. Ser. 1969 012022
2. **Numerical Analysis of above ground storage tanks with different settlement conditions**, Elsevier Journal Of Pressure Vessels And Piping, R Nishanth et al 2021 IOP Conf. Ser.: Earth Environ. Sci. 850 012019
3. **Computational Study Of Fire Water Storage Tanks Due To Seismic Loading**, SESBT 2021 International Conference, IOP conference proceedings: journal of physics – Under Review
4. **Fault Diagnosis of an All Terrain Vehicle Gearbox System using Statistical Features and Advanced Classifier Methods**, Elsevier Journal of the International Measurement Confederation – Under Review
5. **A Performance Characteristics Review Of Mahua Bio diesel In Ci Engines**, Prime 2021 International Conference On Progressive Research In Industrial & Mechanical Engineering - Accepted
6. **Fault Diagnosis of Friction Stir Welding Process using Statistical Features and Advanced Classifier Methods** - Ongoing

## ACCOLADES AND RECOGNITION

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1. **Founder and Team-Lead | Atom Robotics | VIT, Chennai** Jan'19 - Present
  - Enthusiastic University chapter on intelligent robotics and satellite exploration focusing on intelligent ground vehicle targeting IGVC, USA, planetary ariel systems, etc. ([Team Website](#))
2. **Mitacs Globalink Graduate Fund (15000 CAD)** for pursuing Master's programs in Canada by virtue of having done an internship at the University of Alberta, Edmonton.
3. **Certified SOLIDWORKS Professional** in Mechanical Design, Dassault Systèmes
4. **Certified SOLIDWORKS Associate and Additive Manufacturing Associate**, Dassault Systèmes
5. An industrial project had been offered by the Indian Oil Corporation through their Tie-Up company titled as Study on the deformation (with and without plumbs) of Vertical Storage Tanks with 50-100 tilt due to sloshing under the Action of Near-Fault Earthquakes.
6. Placed as the **73rd team all over India** in the event Flipkart Grid 2.0 Round-1
7. Placed **1st in the event "Autonomous Line Follower"**, in Currents'20 - NIT Trichy
8. Placed **1st in "Robozest", in Kurukshetra'20** - College of engineering, Anna University
9. Further achievements with certificates can be seen [here](#).

## EXTRA CURRICULAR

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### **President of ATOM Robotics, VIT Chennai**

- An official team of VIT Chennai which conducts workshops, events and symposiums.

### **Member of National Service Scheme**

- A public service program directed by the Government of India.
- As part of NSS, I, as a team had participated in and coordinated several social service activities benefitting various sections of the society and the environment.

### **Member of IEEE Robotics and Automation Society**

- An active group coordinating member of IEEE-RAS.

### **Core Committee of team Vibrance'20**

- Worked as part of a team in-charge of Hospitality Management.

## ACKNOWLEDGEMENT

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I, hereby affirm that the aforementioned statistics is true to my knowledge, as of September 15<sup>th</sup>, 2021. References are available on request.