

Program Verification: Lecture 24

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Case Analysis Rule

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where $x:s \in vars(u)$ and $\{u_1, \dots, u_k\}$ is a pattern set for s .

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VariableName ::= <Special>
ModuleName  ::= <Special>
Term        ::= <Special>
Atom        ::= (Term)=(Term)
              | (Term)≠(Term)
Conjunction ::= true
              | Atom
              | Conjunction /\ Conjunction
Pattern     ::= (Term) "|" Conjunction
PatternFormula ::= Pattern
              | PatternFormula \/ PatternFormula
RFormula    ::= Pattern =>A PatternFormula
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We can now give commands according to the following grammar:

Reachability Logic Tool Commands (III)

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Nat      ::= <Special>
GoalName ::= Nat | Nat GoalName
TermSet  ::= {Term} | TermSet U TermSet
Command  ::= (select ModuleName .)
            | (subsumed Pattern =< Pattern .)
            | (add-goal RFormula .)
            | (def-term-set PatternFormula .)
            | (start-proof .)
            | (step .)
            | (step Nat .)
            | (step* .)
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Recall that in general we need to prove a set \mathcal{C} of reachability formulas, including the *main formula* $A \longrightarrow^* B$ and perhaps some *auxiliary lemmas*. To enter to the tool each formula in \mathcal{C} we give the command: (add-goal RFormula .)

For example, in CHOICE, to enter the formula

$$\{M\} \mid \top \longrightarrow^* \{M'\} \mid M' \subseteq M = tt$$

we give the command:

```
(add-goal ({M:MSet}) | true =>A
           ({M':MSet}) | (M':MSet =C M:MSet) = (tt) .)
```

The tool gives each entered goal a number. It will later generate *subgoals* named by *number sequences* $n_1 \dots n_k$, naming goal $n_1 \bullet \dots \bullet n_k$, such as 2 3 1 as the first child of child 3 of goal 2.

Reachability Logic Tool Commands (VII)

After:

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Reachability Logic Tool Commands (VII)

After: (i) checking containments of the form $\llbracket S_0 \rrbracket \subseteq \llbracket B \rrbracket$ with the `(subsumed Pattern =< Pattern .)` command and (ii) adding all goals in \mathcal{C} to the tool with the `(add-goal RFormula .)` command,

Reachability Logic Tool Commands (VII)

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Reachability Logic Tool Commands (VII)

After: (i) checking containments of the form $\llbracket S_0 \rrbracket \subseteq \llbracket B \rrbracket$ with the `(subsumed Pattern =< Pattern .)` command and (ii) adding all goals in \mathcal{C} to the tool with the `(add-goal RFormula .)` command, we can start the proof process by giving the `(start-proof .)` command.

If we want to see which goals are obtained by one (resp. n) step(s) of applying some rule of inference to each of current goals we give the command:

Reachability Logic Tool Commands (VII)

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If we want to see which goals are obtained by one (resp. n) step(s) of applying some rule of inference to each of current goals we give the command: `(step .)` (resp. `(step n .)`).

Reachability Logic Tool Commands (VII)

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If we want to see which goals are obtained by one (resp. n) step(s) of applying some rule of inference to each of current goals we give the command: `(step .)` (resp. `(step n .)`).

Instead, if we want to go to the end of the proof process in the hope that it will terminate we give the `(step* .)` command.

Reachability Logic Tool Commands (VII)

After: (i) checking containments of the form $\llbracket S_0 \rrbracket \subseteq \llbracket B \rrbracket$ with the (subsumed Pattern =< Pattern .) command and (ii) adding all goals in \mathcal{C} to the tool with the (add-goal RFormula .) command, we can start the proof process by giving the (start-proof .) command.

If we want to see which goals are obtained by one (resp. n) step(s) of applying some rule of inference to each of current goals we give the command: (step .) (resp. (step n .)).

Instead, if we want to go to the end of the proof process in the hope that it will terminate we give the (step* .) command. And at any time we can quit giving the (quit .) command.

Reachability Logic Tool Commands (VIII)

At any time in the proof process we can apply the **Case Analysis** rule to a goal named with a number list l to decompose it into several subgoals by giving the command:

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```

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which was named, say, as goal 1 by the tool, using the pattern set $\{N:Nat, M_1:MSet\ M_2:MSet\}$, we will give the command:

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which was named, say, as goal 1 by the tool, using the pattern set $\{N:Nat, M_1:MSet\ M_2:MSet\}$, we will give the command:

```
(case 1 on M:MSet by {N:Nat} U {M1:MSet M2:MSet} .)
```

Example Proofs (I)

We first recall the CHOICE module from Lecture 23

```
mod CHOICE is
  protecting NAT .
  sorts MSet State Pred .
  subsorts Nat < MSet .
  op _ : MSet MSet -> MSet [ctor assoc comm] .
  op {_} : MSet -> State .
  op tt : -> Pred [ctor] .
  op _=C_ : MSet MSet -> Pred [ctor] .
  vars U V : MSet . var N : Nat .
  eq U =C U = tt .
  eq U =C U V = tt .
  rl [choice] : {U V} => {U} .
endm
```

Example Proofs (II)

Also recall the Hoare Triple from Lecture 23:

$$\{\{M\} \mid \top\} \text{ CHOICE } \{\{N\} \mid N \subseteq M = tt\}$$

In the tool notation, we can write this as the reachability formula:

$$\begin{aligned} &(\{M:\text{MSet}\}) \mid \text{true} \Rightarrow A \\ &(\{N:\text{Nat}\}) \mid (N:\text{Nat} =_{\text{C}} M:\text{MSet}) = (tt) \end{aligned}$$

Sometimes, we *cannot* prove a goal as-is and must analyze cases; this formula is one such example

Example Proofs (III)

$(\{M:MSet\}) \mid \text{true} \Rightarrow A$
 $(\{N:Nat\}) \mid (N:Nat =_C M:MSet) = (tt)$

The case analysis occurs on variable $M:MSet$;

Two cases: $M:MSet \mapsto N:Nat$ (or) $M:MSet \mapsto M1:MSet \ M2:MSet$

Recall any terminating state in this theory has the form $\{N:Nat\}$

Now we are ready to prove this example in the tool

Example Proofs (IV)

The full proof script is given below:

```
load choice.maude
load rltool.maude
(select module CHOICE .)
(def-term-set ({N:Nat}) | true .)
(add-goal ({M:MSet}) | true =>A
          ({N:Nat}) | (N:Nat =C M:MSet) = (tt) .)
(start-proof .)
(case 1 on M:MSet by {K:Nat} U {M1:MSet M2:MSet} .)
(step* .)
```

Note: 3 proof rules sufficient to prove triple for *all multisets*

Example Proofs (V)

Q: Does the system handle general reachability formulas as nicely?

A: Let us illustrate by example...

Recall the CHOICE reachability formula from Lecture 23:

$$\{M\} \mid \top \longrightarrow^* \{M'\} \mid M' \subseteq M = tt$$

Expressible in the tool notation as:

```
({M:MSet}) | true =>A  
  ({M':Nat}) | (M':Nat =C M:MSet) = (tt)
```

We expect the proof will be similar to its Hoare Triple cousin...

Example Proofs (VI)

The proof script confirms our suspicions:

```
load choice.maude
load rltool.maude
(select module CHOICE .)
(def-term-set ({N:Nat}) | true .)
(add-goal ({M:MSet}) | true =>A
  ({M':MSet}) | (M':MSet =C M:MSet) = (tt) .)
(start-proof .)
(case 1 on M:MSet by {K:Nat} U {M1:MSet M2:MSet} .)
(step* .)
```

Except for $N:Nat \mapsto M':MSet$, the two proofs are *identical*

Example Proofs (VII)

We already saw READERS-WRITERS-stop in Lecture 23

```
mod READERS-WRITERS-stop is
  sorts Nat State .
  op 0 : -> Nat [ctor] .
  op s : Nat -> Nat [ctor] .
  sort State .
  op <_,_> : Nat Nat -> State [ctor] .
  op [_,_] : Nat Nat -> State [ctor] .
  vars R W : Nat .
  rl < 0, 0 >      => < 0, s(0) > .
  rl < R, s(W) > => < R, W > .
  rl < R, 0 >      => < s(R), 0 > .
  rl < s(R), W > => < R, W > .
  rl < R, W >      => [R,W] .
endm
```

Recall the *mutual exclusion* proof we were working on earlier...

Example Proofs (VIII)

In READERS-WRITERS, by our corollary, to prove the invariant

$$Mutex = \langle R, W \rangle \mid W = 0 \vee (W = 1 \wedge R = 0)$$

holds from state $\langle 0, 0 \rangle$, we must check:

$$1 \quad \llbracket \langle 0, 0 \rangle \mid \top \rrbracket \subseteq \llbracket Mutex_1 \rrbracket$$

$$2 \quad Mutex_1 \longrightarrow^* [Mutex]$$

$$3 \quad Mutex_2 \longrightarrow^* [Mutex]$$

where:

$$Mutex_1 = \langle R, W \rangle \mid W = 0 \text{ and}$$

$$Mutex_2 = \langle R, W \rangle \mid W = 1 \wedge R = 0.$$

Now we can write our proof script

Example Proofs (IX)

```
load r&w.maude
load rltool.maude
(select module READERS-WRITERS-stop .)
(subsumed (< 0,0 >) | true =<
  (< R:Nat,W:Nat >) | (W:Nat) = (0) .)
(def-term-set ([R:Nat,W:Nat]) | true .)
(add-goal (< R:Nat,W:Nat >) | (W:Nat) = (0)
=>A ([ R':Nat,W':Nat ]) | (W':Nat) = (0) \/  
  ([ R':Nat,W':Nat ]) | (W':Nat) = (s(0)) /\  
    (R':Nat) = (0) .)
(add-goal (< R:Nat,W:Nat >) | (W:Nat) = (s(0)) /\  
  (R:Nat) = (0)
=>A ([ R':Nat,W':Nat ]) | (W':Nat) = (0) \/  
  ([ R':Nat,W':Nat ]) | (W':Nat) = (s(0)) /\  
    (R':Nat) = (0) .)
(start-proof .)
(step* .)
```