

# Artificial Intelligence Course

## Foundations & Fundamentals

Welcome to an exploration of Artificial Intelligence—the transformative field reshaping how machines think, learn, and interact with the world. This course introduces core concepts that form the foundation of AI research and practice, setting the stage for advanced study and application in modern technology.

# What is Artificial Intelligence?

Artificial Intelligence represents the simulation of intelligent human behavior by computational systems. AI enables machines to perceive their environment, reason about problems, learn from experience, and take actions to achieve specific goals.



## Thinking

Computational reasoning and problem-solving through logical processes and complex algorithms.



## Acting

Taking autonomous, purposeful actions in the physical or digital world based on real-time data.



## Learning

Improving performance over time by analyzing large datasets and adapting to new information.



# Goals of AI

AI research pursues ambitious objectives centered on creating intelligent systems. These foundational goals guide both theoretical inquiry and practical development across the field.



## Automation

Automating complex, repetitive tasks to increase efficiency and reduce human error.



## Decision making

It aims to achieve optimal outcomes by analyzing the environment, predicting results, and selecting the most effective solution.



## Learning and Adaptation

Extracting insights, patterns, and knowledge from vast amounts of data.



## Perception

Interpreting sensory information, such as images, sound, and spatial data.



## Natural Language

Understanding and generating human language for communication and interaction.

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These goals collectively drive the development of systems capable of solving real-world challenges.



# Real-World Applications of AI

AI technologies are actively transforming industries, enhancing human capabilities, and solving complex problems. From diagnosis to discovery, AI's impact spans nearly every sector of society.



## Healthcare

Disease diagnosis, personalized treatment planning, and accelerated drug discovery processes.



## Robotics

Automation in manufacturing, development of autonomous vehicles, and complex exploration tasks.



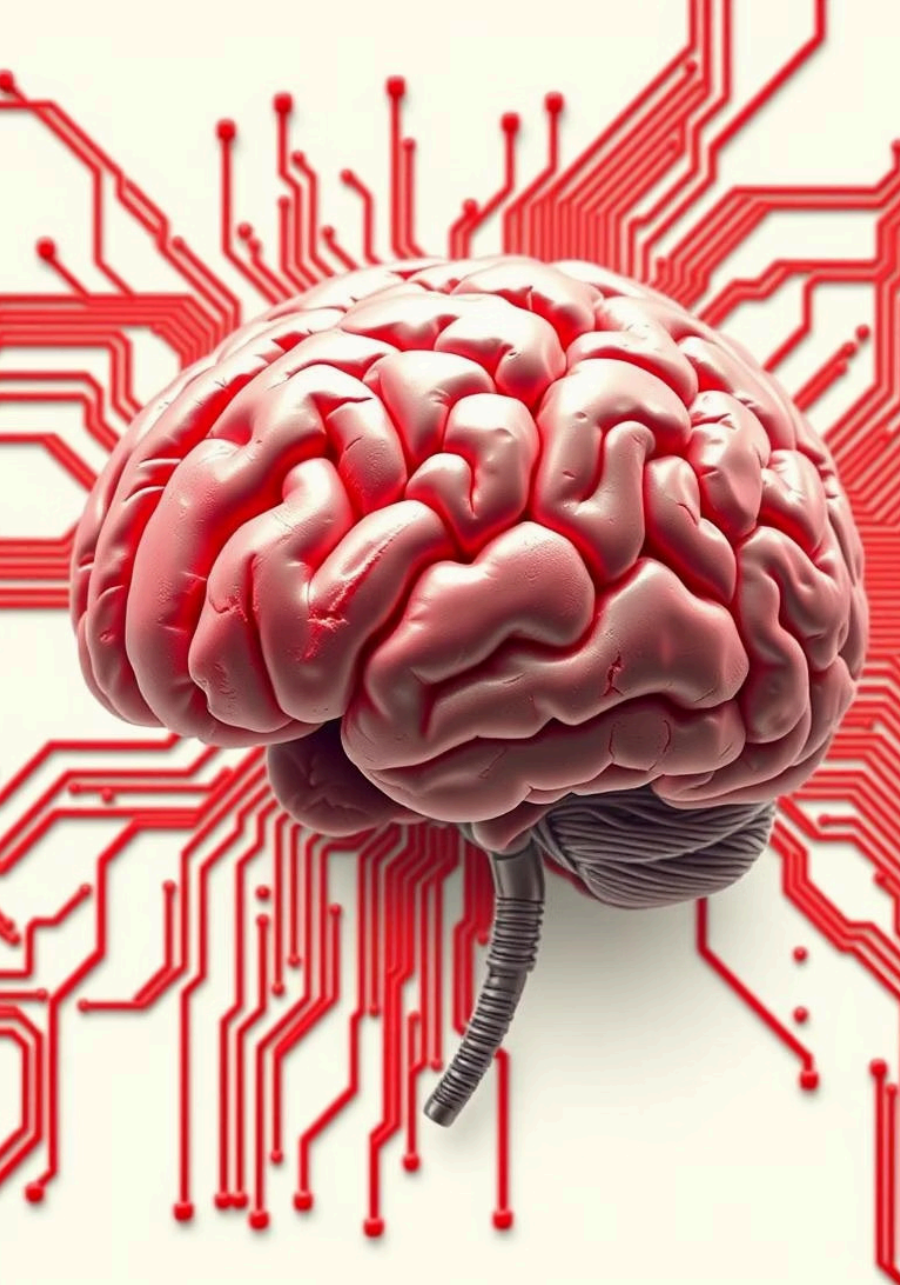
## Education

Personalized tutoring systems, intelligent assessment tools, and adaptive learning platforms.



## Games & Strategy

Developing advanced game-playing agents (e.g., Chess engines) and complex strategic reasoning systems.



# Foundations of Intelligence

Three perspectives frame how we understand and measure artificial intelligence, each offering unique insights into the nature of intelligent behavior.

## Turing Test: The Behavioral Measure

Can a machine exhibit conversational behavior indistinguishable from a human? This behavioral test measures machine intelligence purely through imitation and linguistic output.

## Neuroscience: Biological Inspiration

Understanding biological intelligence in brains inspires computational systems. Cognitive science informs algorithm design and architecture, especially in areas like neural networks.

## Rationality: Optimal Decision Making

Focuses on building systems that make optimal decisions given available information and resources. Logic and decision theory provide rigorous foundations for rational agent behavior.

## cognitive science

how the human mind works—covering thinking, learning, memory, and intelligence.



# Agents in Artificial Intelligence

An agent is an autonomous computational entity that perceives its environment through sensors and acts upon it through actuators. Agents form the conceptual foundation for most AI systems, enabling sophisticated autonomous behavior through perception-action cycles.

## Sensing

Perceiving the environment through various input mechanisms (cameras, microphones, sensors, data feeds).

## Acting

Influencing the environment through strategic actions (moving, displaying information, making decisions, manipulating objects).

- The agent's design determines its intelligence—how well it selects the optimal action based on its perception and knowledge.

# Types of Intelligent Agents

AI agents vary in sophistication and capability, from reactive systems to advanced learning entities. Each type represents different levels of complexity in decision-making and adaptation.

1

## Simple Reflex Agents

Direct stimulus-response mappings without any internal state or explicit planning capability.

2

## Model-Based Agents

Maintain internal models of the world to handle partial observability and track environment changes.

3

## Goal-Based Agents

Plan actions strategically to achieve explicit target goals, considering future states.

4

## Utility-Based Agents

Optimize satisfaction levels, choosing actions that maximize a defined utility function, which accounts for performance quality.

5

## Learning Agents

Improve performance autonomously through experience, knowledge acquisition, and self-correction over time.



# Types of Environments

The performance and design of an AI agent are critically influenced by the characteristics of its operating environment. Understanding these types helps in developing agents that can effectively perceive, plan, and act.



## Observable vs. Partially Observable

An environment is fully observable if the agent's sensors give it access to the complete state of the environment at all times. If not, it's partially observable due to noisy sensors or hidden states.



## Deterministic vs. Stochastic

In a deterministic environment, the next state is completely determined by the current state and the agent's action. A stochastic environment involves randomness, making outcomes uncertain.



## Episodic vs. Sequential

An episodic environment means the agent's experience is divided into independent "episodes," where each action only affects the current episode. In sequential environments, current actions impact all future decisions.



## Static vs. Dynamic

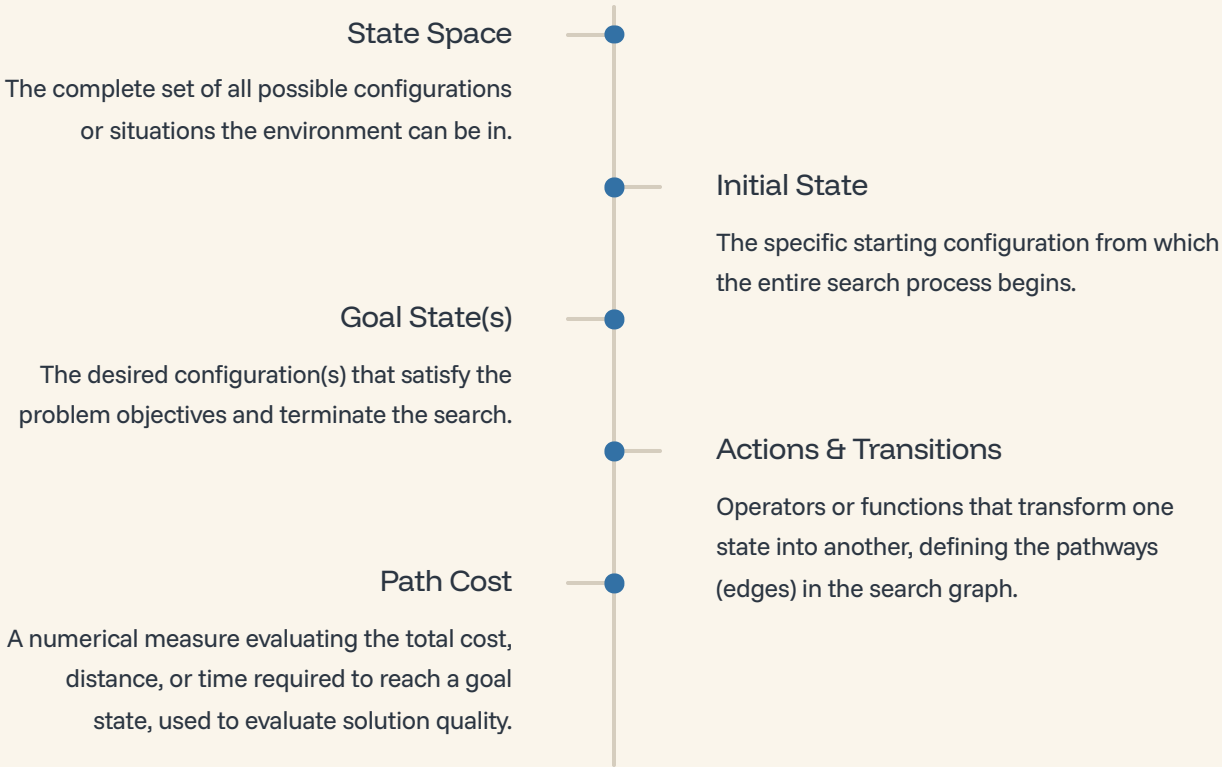
If the environment does not change while the agent is deliberating, it is static. A dynamic environment changes continuously, requiring the agent to constantly adapt and react.



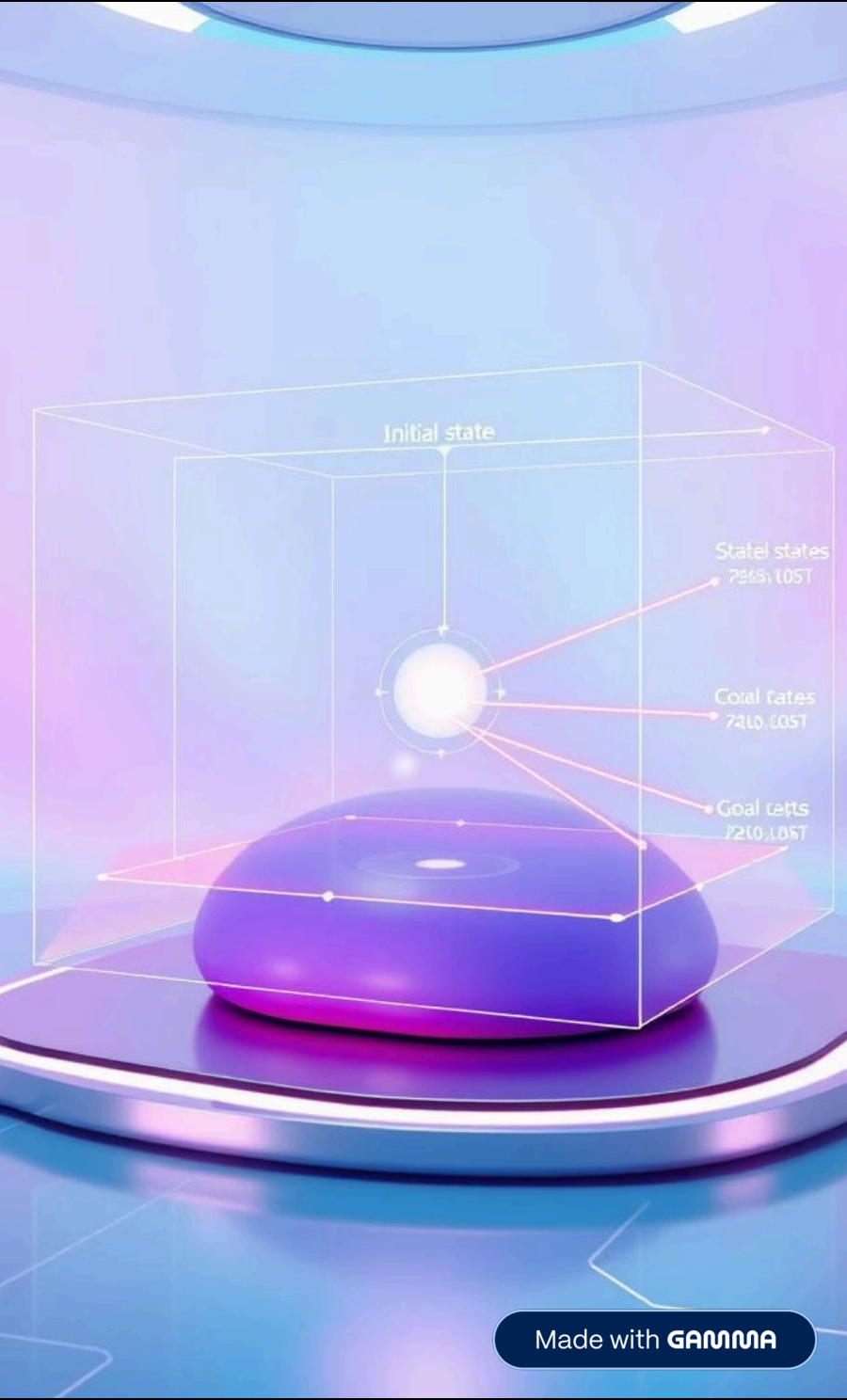


# State Space Search: The Core of Problem-Solving

Search forms the backbone of problem-solving in AI. By systematically exploring possible states and transitions, agents find solutions to complex problems. A well-defined problem specifies how we move through the space of possibilities toward desired goals.



Key Insight: Effective search strategies balance completeness (finding a solution if one exists), optimality (finding the best solution), and computational efficiency.



# A Classic AI Problem: The N-Queen Puzzle

We can use the concept of State Space Search to solve classical AI challenges, such as the N-Queen Problem, which requires sophisticated problem formulation and constraint satisfaction.

## Problem Definition

The task is to place  $N$  queens on an  $N \times N$  chessboard so that no two queens threaten each other. This means no two queens can share the same row, column, or diagonal.

## Why It Matters

This classic problem demonstrates crucial AI techniques like backtracking, depth-first search, and constraint satisfaction—fundamental tools for solving complex combinatorial optimization challenges efficiently.

## Solution Approach

Typically solved using a backtracking search algorithm, where the system incrementally builds a solution, abandoning partial solutions that violate the no-attack constraint.



# Search Algorithms in AI

Search algorithms are fundamental to Artificial Intelligence, enabling agents to explore possible states and actions to find optimal solutions or paths in a problem space. They are crucial for tasks ranging from game playing and pathfinding to resource allocation and theorem proving.

1

## Uninformed Search

These algorithms explore the search space without using any domain-specific knowledge or heuristic information. They systematically check every possible path until the goal is found.

- **Breadth-First Search (BFS):** Explores all nodes at the current depth level before moving to the next level. Guarantees finding the shortest path in terms of number of steps.
- **Depth-First Search (DFS):** Explores as far as possible along each branch before backtracking. May not find the shortest path but is memory efficient.

2

## Informed Search

Informed search algorithms use heuristic functions to estimate the cost from the current state to the goal state, guiding the search more efficiently than uninformed methods.

- **A\* Search:** Combines the cost to reach a node with the estimated cost from that node to the goal. It is optimal and complete if the heuristic is admissible and consistent.
- **Greedy Best-First Search:** Expands the node that appears to be closest to the goal, as estimated by a heuristic function. Fast but not always optimal or complete.

3

## Local Search Algorithms

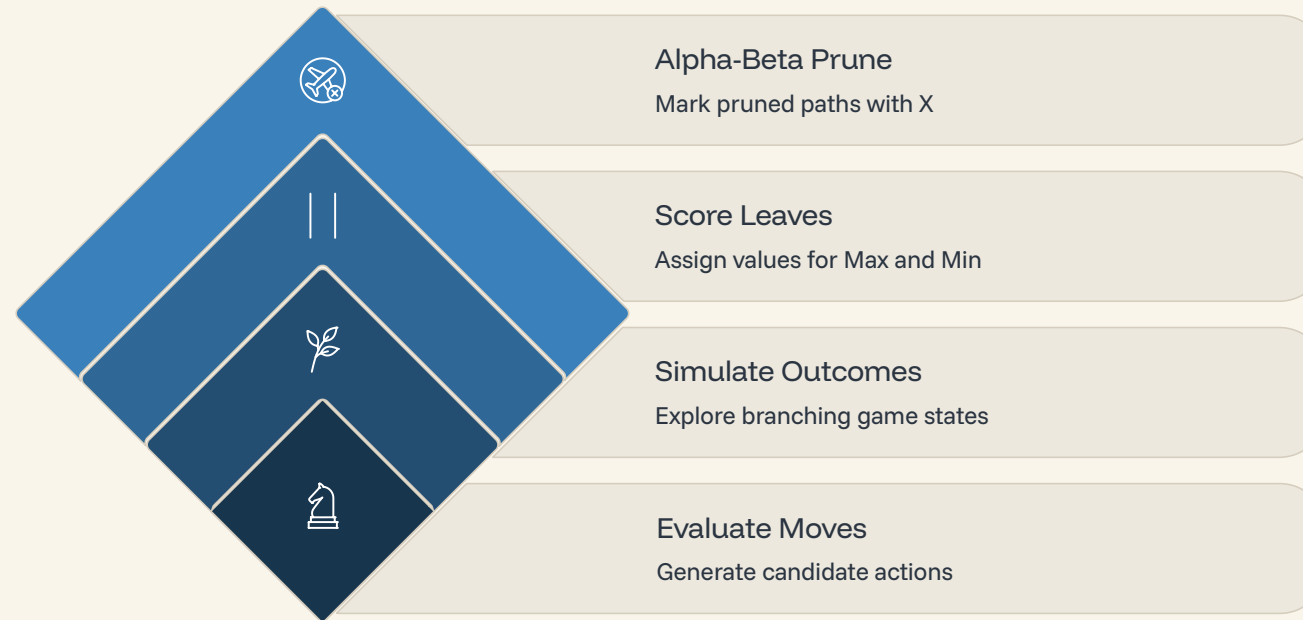
These algorithms operate on a single current state and typically move to a neighboring state, aiming to find an optimal solution within a specific region of the search space. They are often used for optimization problems where the path to the solution is not important, only the solution itself.

- **Hill Climbing:** Iteratively moves towards a state with a better value, continuing until a local optimum is reached. Prone to getting stuck in local maxima.
- **Simulated Annealing:** A metaheuristic inspired by annealing in metallurgy, which accepts worse moves with a certain probability to escape local optima and explore more of the search space.



# AI in Games: Strategic Decision Making

Artificial Intelligence plays a pivotal role in creating intelligent opponents and dynamic game experiences. Gaming algorithms enable AI players to make strategic decisions, anticipate player moves, and provide a challenging yet fair gameplay.



## Minimax Algorithm

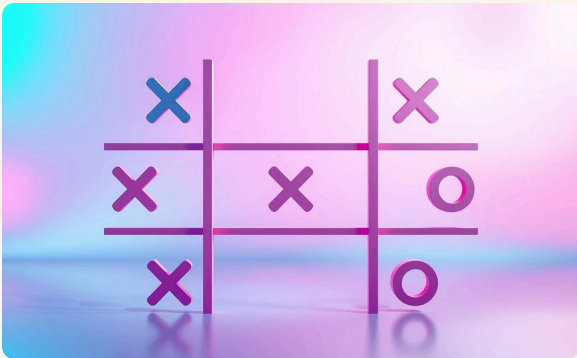
A decision-making rule used in game theory, where the AI player aims to minimize the maximum possible loss from a worst-case scenario (equivalent to maximizing their minimum gain). It explores all possible moves and counter-moves to determine the optimal strategy.

## Alpha-Beta Pruning

An optimization technique for the Minimax algorithm that drastically reduces the number of nodes evaluated in the search tree. It prunes branches that cannot possibly influence the final decision, significantly speeding up the AI's decision-making process without affecting the outcome.

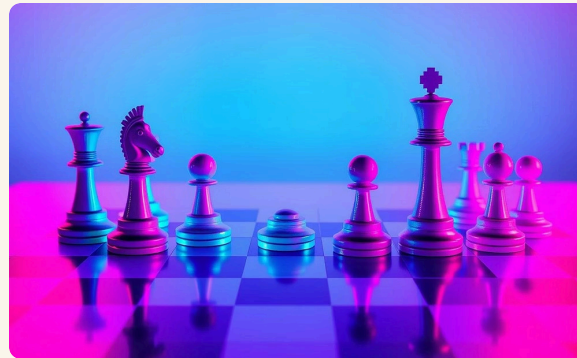
# AI in Games

Games present unique challenges for Artificial Intelligence, requiring agents to navigate situations with often limited information, competitive opponents, and real-time decision-making constraints. Developing AI for games necessitates diverse strategies to predict, plan, and execute optimal moves for victory.



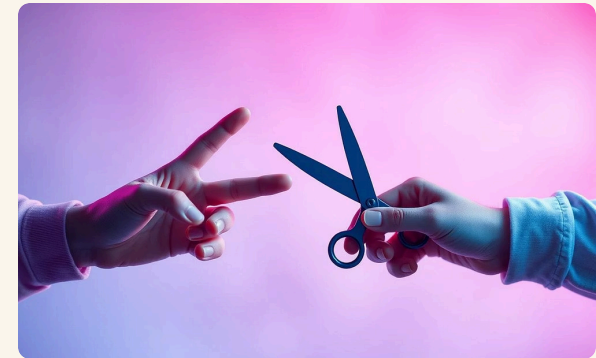
## Tic-Tac-Toe

A simple perfect information game where Min-Max offers a winning strategy, often leading to draws against optimal human play. It's ideal for demonstrating complete game tree evaluation due to its small and manageable search space.



## Chess

This complex game, with an astronomical search space (approx.  $10^{120}$  possible games), combines Min-Max with Alpha-Beta pruning. Modern chess engines evaluate millions of positions per second, showcasing advanced AI techniques in deep search and evaluation.

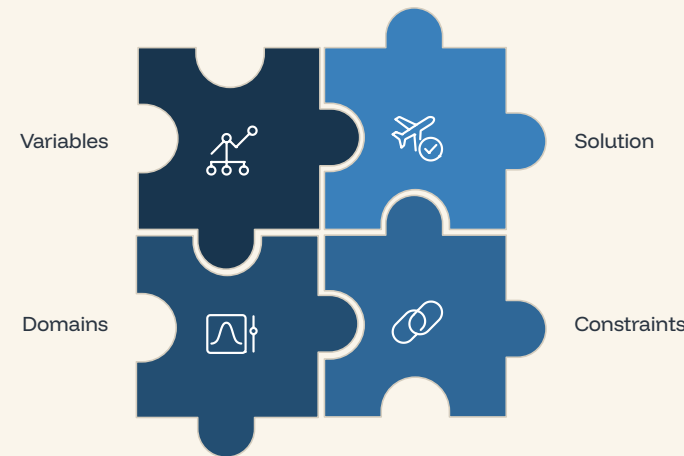


## Rock Paper Scissors

A simple probabilistic game where AI can be enhanced using Monte Carlo methods and pattern recognition. These techniques help predict opponent behavior and maximize win probability by adapting strategies based on observed patterns.

# Constraint Satisfaction Problems (CSPs)

Constraint Satisfaction Problems (CSPs) are a fundamental class of problems in Artificial Intelligence, where the goal is to find a state or an assignment of values to a set of variables that satisfies a given set of conditions or constraints. They provide a powerful framework for modeling and solving diverse real-world challenges.



## Variables

These are the decision-making elements or unknown quantities in the problem. For example, in a scheduling problem, variables might represent the start times of tasks.

## Domains

Each variable has a domain, which is a finite set of possible values it can take. For instance, a task's start time variable might have a domain of specific hours in a day.

## Constraints

These are the rules or conditions that limit the combinations of values that variables can take. Constraints define valid assignments, ensuring that the chosen values are consistent with the problem's requirements.

## Solution

A solution to a CSP is a complete assignment of values to all variables, where each value is taken from its respective domain, such that all the defined constraints are satisfied simultaneously.



# Types of Constraints in CSPs

Constraints are the fundamental rules that define a valid solution in a Constraint Satisfaction Problem. They come in various forms, each specifying how variables must relate to their domains and to each other, guiding the search for a consistent assignment.

1

## Unary Constraints

These constraints restrict the value of a single variable. They are the simplest form and can often be used to preprocess and reduce variable domains before search begins.

- `Color_of_Car = Red`
- `Age > 18`

2

## Binary Constraints

Binary constraints specify a relationship between exactly two variables. They are very common in CSPs, defining how pairs of variables interact and what value combinations are permitted.

- `X != Y` (e.g., adjacent map regions)
- `TaskA_End < TaskB_Start`

3

## Global Constraints

These involve three or more variables, often representing a common structure or property across a larger subset of variables. They can be more expressive and efficient than multiple binary constraints.

- `AllDifferent(V1, V2, V3)` (e.g., Sudoku row)
- `Sum(Items) <= Capacity`

# Cryptarithmic & Bound Propagation

Cryptarithmic puzzles are classic Constraint Satisfaction Problems where letters represent unique digits (0-9) to form valid arithmetic equations. For example, **SEND + MORE = MONEY**.

**Bound Propagation** is a vital technique to solve these. It iteratively updates variable domains by using constraints to eliminate impossible values, significantly reducing the search space and speeding up the solution process.

