HAR_LSTM-MODEL

June 29, 2019

```
In [1]: # Importing Libraries
        import pandas as pd
        import numpy as np
        import os
        import pickle
        # Import Model related packages
        import tensorflow as tf
        from keras import backend as K
        from keras.models import Sequential
        from keras.layers import LSTM
        from keras.layers.core import Dense, Dropout
        from keras.callbacks import EarlyStopping, ModelCheckpoint
        # Model evaluation related packages
        from sklearn.metrics import confusion_matrix
        from sklearn.metrics import precision_recall_fscore_support
        # for one hot encoding of labels
        from sklearn.preprocessing import OneHotEncoder
        # Plot related packages
        import matplotlib.pyplot as plt
        import seaborn as sns
        sns.set()
        # Presenting the results
        from prettytable import PrettyTable
```

Using TensorFlow backend.

1 HumanActivityRecognition

This project is to build a model that predicts the human activities such as Walking, Walking_Upstairs, Walking_Downstairs, Sitting, Standing or Laying.

This dataset is collected from 30 persons(referred as subjects in this dataset), performing different activities with a smartphone to their waists. The data is recorded with the help of sensors

(accelerometer and Gyroscope) in that smartphone. This experiment was video recorded to label the data manually.

1.1 How data was recorded

By using the sensors (Gyroscope and accelerometer) in a smartphone, they have captured '3-axial linear acceleration' (tAcc-XYZ) from accelerometer and '3-axial angular velocity' (tGyro-XYZ) from Gyroscope with several variations.

prefix 't' in those metrics denotes time.

suffix 'XYZ' represents 3-axial signals in X, Y, and Z directions.

1.1.1 Feature names

- 1. These sensor signals are preprocessed by applying noise filters and then sampled in fixed-width windows(sliding windows) of 2.56 seconds each with 50% overlap. ie., each window has 128 readings.
- From Each window, a feature vector was obtianed by calculating variables from the time and frequency domain. > In our dataset, each datapoint represents a window with different readings
- 3. The acceleration signal was saperated into Body and Gravity acceleration signals(*tBodyAcc-XYZ* and *tGravityAcc-XYZ*) using some low pass filter with corner frequecy of 0.3Hz.
- 4. After that, the body linear acceleration and angular velocity were derived in time to obtian *jerk signals* (*tBodyAccJerk-XYZ* and *tBodyGyroJerk-XYZ*).
- 5. The magnitude of these 3-dimensional signals were calculated using the Euclidian norm. This magnitudes are represented as features with names like *tBodyAccMag*, *tGravityAccMag*, *tBodyAccJerkMag*, *tBodyGyroMag* and *tBodyGyroJerkMag*.
- 6. Finally, We've got frequency domain signals from some of the available signals by applying a FFT (Fast Fourier Transform). These signals obtained were labeled with *prefix 'f'* just like original signals with *prefix 't'*. These signals are labeled as *fBodyAcc-XYZ*, *fBodyGyroMag* etc.,.
- 7. These are the signals that we got so far.
 - tBodyAcc-XYZ
 - tGravityAcc-XYZ
 - tBodyAccJerk-XYZ
 - tBodyGyro-XYZ
 - tBodyGyroJerk-XYZ
 - tBodyAccMag
 - tGravityAccMag
 - tBodyAccJerkMag
 - tBodyGyroMag
 - tBodyGyroJerkMag
 - fBodyAcc-XYZ

- fBodyAccJerk-XYZ
- fBodyGyro-XYZ
- fBodyAccMag
- fBodyAccJerkMag
- fBodyGyroMag
- fBodyGyroJerkMag
- 8. We can esitmate some set of variables from the above signals. ie., We will estimate the following properties on each and every signal that we recoreded so far.
 - mean(): Mean value
 - std(): Standard deviation
 - *mad()*: Median absolute deviation
 - *max()*: Largest value in array
 - *min()*: Smallest value in array
 - *sma()*: Signal magnitude area
 - *energy()*: Energy measure. Sum of the squares divided by the number of values.
 - *iqr*(): Interquartile range
 - *entropy()*: Signal entropy
 - arCoeff(): Autorregresion coefficients with Burg order equal to 4
 - *correlation()*: correlation coefficient between two signals
 - *maxInds*(): index of the frequency component with largest magnitude
 - *meanFreq()*: Weighted average of the frequency components to obtain a mean frequency
 - *skewness()*: skewness of the frequency domain signal
 - *kurtosis()*: kurtosis of the frequency domain signal
 - *bandsEnergy()*: Energy of a frequency interval within the 64 bins of the FFT of each window.
 - *angle()*: Angle between to vectors.
- 9. We can obtain some other vectors by taking the average of signals in a single window sample. These are used on the angle() variable'
 - gravityMean
 - tBodyAccMean
 - tBodyAccJerkMean
 - tBodyGyroMean
 - tBodyGyroJerkMean

1.1.2 Y Labels(Encoded)

- In the dataset, Y_labels are represented as numbers from 1 to 6 as their identifiers.
 - WALKING as 1
 - WALKING UPSTAIRS as 2
 - WALKING_DOWNSTAIRS as 3
 - SITTING as 4
 - STANDING as 5
 - LAYING as 6

1.2 Train and test data were saperated

• The readings from 70% of the volunteers were taken as *trianing data* and remaining 30% subjects recordings were taken for *test data*

1.3 Data

- All the data is present in 'UCI_HAR_dataset/' folder in present working directory.
 - Feature names are present in 'UCI_HAR_dataset/features.txt'
 - Train Data
 - * 'UCI_HAR_dataset/train/X_train.txt'
 - * 'UCI_HAR_dataset/train/subject_train.txt'
 - * 'UCI_HAR_dataset/train/y_train.txt'
 - Test Data
 - * 'UCI_HAR_dataset/test/X_test.txt'
 - * 'UCI_HAR_dataset/test/subject_test.txt'
 - * 'UCI_HAR_dataset/test/y_test.txt'

1.4 Data Size:

27 MB

2 Quick overview of the dataset:

- Accelerometer and Gyroscope readings are taken from 30 volunteers(referred as subjects) while performing the following 6 Activities.
 - 1. Walking
 - 2. WalkingUpstairs
 - 3. WalkingDownstairs
 - 4. Standing
 - 5. Sitting
 - 6. Lying.
- Readings are divided into a window of 2.56 seconds with 50% overlapping.
- Accelerometer readings are divided into gravity acceleration and body acceleration readings, which has x,y and z components each.
- Gyroscope readings are the measure of angular velocities which has x,y and z components.
- Jerk signals are calculated for BodyAcceleration readings.
- Fourier Transforms are made on the above time readings to obtain frequency readings.
- Now, on all the base signal readings., mean, max, mad, sma, arcoefficient, engery-bands, entropy etc., are calculated for each window.

- We get a feature vector of 561 features and these features are given in the dataset.
- Each window of readings is a datapoint of 561 features.

2.1 Problem Framework

- 30 subjects(volunteers) data is randomly split to 70%(21) test and 30%(7) train data.
- Each datapoint corresponds one of the 6 Activities.

3 Configs

4 UTIL functions

```
In [3]: def get_confusion_matrix(actual_list, predicted_list, title_suffix=str(), plot_fig=True)
            This function plots the confusion matrix given ground truth and predicted
            11 11 11
            conf_matrix = confusion_matrix(actual_list, predicted_list,
                                            labels=list(range(0, num_clasess)))
            conf_df = pd.DataFrame(conf_matrix, columns=class_names_list)
            conf_df.index = class_names_list
            # plot confusion matrix
            if plot_fig:
                plt.figure(figsize=(9,6))
                sns.heatmap(conf_df, annot=True, annot_kws={'size': 8}, fmt='g', cmap='YlGnBu',
                                cbar_kws={'label': 'prediction_count', 'format':'%d'})
                plt.yticks(rotation=0)
                plt.xticks(rotation=90)
                plt.xlabel('Predicted')
                plt.ylabel('Actual')
                plt.title('Confusion Matrix -' + title_suffix)
                plt.show()
```

```
return conf_df
In [4]: def get_precision_recall_matrix(conf_matrix, title_suffix=str(), plot_fig=True):
            # compute precision matrix
            precision_matrix = conf_matrix.div(conf_matrix.sum(axis=0), axis=1) * 100.0
            # compute recall matrix
            recall_matrix = conf_matrix.div(conf_matrix.sum(axis=1), axis=0) * 100.0
            # plot both the matrices
            if plot_fig:
                # plot precision matrix
                plt.figure(figsize=(9,6))
                sns.heatmap(precision_matrix, annot=True, annot_kws={'size': 8},
                            fmt='.4f', cmap='YlGnBu',
                            cbar_kws={'label': 'percentage', 'format':'%.2f'})
                plt.yticks(rotation=0)
                plt.xticks(rotation=90)
                plt.xlabel('Predicted')
                plt.ylabel('Actual')
                plt.title('Precision Matrix -' + title_suffix)
                plt.show()
                # plot recall matrix
                plt.figure(figsize=(9,6))
                sns.heatmap(recall_matrix, annot=True, annot_kws={'size': 8},
                            fmt='.4f', cmap='YlGnBu',
                            cbar_kws={'label': 'percentage', 'format':'%.2f'})
                plt.yticks(rotation=0)
                plt.xticks(rotation=90)
                plt.xlabel('Predicted')
                plt.ylabel('Actual')
                plt.title('Recall Matrix -' + title_suffix)
                plt.show()
            # return as a tuple
            return (precision_matrix, recall_matrix,)
In [5]: def get_classification_report(actual, predicted, title_suffix=str(), plot_fig=True):
            # compute performance df
            eval_matrix = precision_recall_fscore_support(actual, predicted,
                                            labels=list(range(0, num_clasess)))
            eval_df = pd.DataFrame(list(eval_matrix), columns=list(range(0, num_clasess)))
            eval_df.index = ['Precision', 'Recall', 'Fscore', 'Support']
```

```
eval_df.columns = class_names_list
            # normalize the performace df
            eval_df_normed = eval_df * 100.0
            eval_df_normed.loc['Support', class_names_list] /= eval_df_normed.loc['Support',
                                                                class_names_list].sum()
            eval_df_normed.iloc[3:4, :] *= 100.0
            # plot the classification report
            if plot_fig:
                plt.figure(figsize=(9,6))
                sns.heatmap(eval_df_normed, annot=True, annot_kws={'size': 8},
                            fmt='.4f', cmap='YlGnBu',
                            cbar_kws={'label': 'Percentage', 'format':'%.2f'})
                plt.yticks(rotation=0)
                plt.xticks(rotation=90)
                plt.xlabel('Classes')
                plt.ylabel('Metrics')
                plt.title('Classification Report on ' + title_suffix + ' Data')
                plt.show()
            return eval_df_normed
In [6]: def plot_loss_curve(hist_obj):
            This function plots the loss curve
            # get train , validation loss information from object
            train_loss_list = list(hist_obj['loss'])
            validation_loss_list = list(hist_obj['val_loss'])
            # get x-label list
            epcoh_list = range(1, len(train_loss_list) + 1 )
            # plot the performace
            # plot both train, validation curve
            plt.plot(epcoh_list, train_loss_list,
                     label='Train Loss', color='r')
            plt.plot(epcoh_list, validation_loss_list,
                     label='Validation Loss', color='b')
            plt.xlabel('Training Epoch')
            plt.ylabel('Multiclass Log Loss')
            plt.title('Training Loss Vs Validation Loss')
            plt.legend()
            plt.show()
```

```
In [7]: def plot_accuracy_curve(hist_obj):
            This is a helper function for plotting accuracy
            # extract train, validation accuracy metrics
            train_acc_list = list(hist_obj['acc'])
            val_acc_list = list(hist_obj['val_acc'])
            # get x-label list
            epcoh_list = range(1, len(train_acc_list) + 1 )
            # plot both train, validation curve
            plt.plot(epcoh_list, train_acc_list, label='Train Accuracy', color='r')
            plt.plot(epcoh_list, val_acc_list, label='Validation Accuracy', color='b')
            plt.xlabel('Training Epoch')
            plt.ylabel('Accuracy')
            plt.title('Training Accuracy Vs Validation Accuracy')
            plt.legend()
            plt.show()
5
  Data
In [8]: # declare one hot encoder for label
        one_hot_encoder = OneHotEncoder(sparse=False, categories='auto')
        one_hot_encoder.fit(np.array(class_labels_list).reshape(num_clasess, 1))
Out[8]: OneHotEncoder(categorical_features=None, categories='auto',
               dtype=<class 'numpy.float64'>, handle_unknown='error',
               n_values=None, sparse=False)
In [9]: # Utility function to load the features
        def load_features(data_base_dir, dataset_type):
            # declare all the signals in a list
            SIGNALS = [
            'body_acc_x',
            'body_acc_y',
            'body_acc_z',
            'body_gyro_x',
            'body_gyro_y',
            'body_gyro_z',
            'total_acc_x',
            'total_acc_y',
            'total_acc_z' ]
            # declare a list for holding the entire data frame
```

```
signals_data = list()
            # do for all signals in the list
            for signal in SIGNALS:
                # set the file path
                file_path = os.path.join(data_base_dir,
                                         f'{dataset_type}/Inertial Signals/{signal}_{dataset_type}
                # read the file
                tdf = pd.read_csv(file_path, delim_whitespace=True, header=None)
                # update the list
                signals_data.append(tdf.values)
            # Transpose is used to change the dimensionality of the output,
            # aggregating the signals by combination of sample/timestep.
            # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
            signals_data = np.transpose(signals_data, (1, 2, 0))
            return signals_data
In [10]: def load_labels(data_base_dir, dataset_type):
             # set the file path
             file_path = os.path.join(data_base_dir, f'{dataset_type}/y_{dataset_type}.txt')
             # read the file
             tdf = pd.read_csv(file_path, delim_whitespace=True, header=None, squeeze=True)
             print('Distribution of labels :\n', tdf.value_counts())
             # get labels in one-hot encoded representation
             labels = one_hot_encoder.transform(tdf.values.reshape(len(tdf), 1)).astype(int)
             return labels
5.1 Raw data signals Information
```

Signals are from Accelerometer and Gyroscope The signals are in x,y,z directions Triaxial acceleration from the accelerometer is total acceleration. Sensor signals are filtered to have only body acceleration excluding the acceleration due to gravity

```
In [11]: # Load the features
         X_train = load_features(data_base_dir, 'train')
         X_test = load_features(data_base_dir, 'test')
         # Load the labels
         y_train = load_labels(data_base_dir, 'train')
```

```
y_test = load_labels(data_base_dir, 'test')
         if dataset_size > 0:
             X_train = X_train[0:dataset_size]
             X_test = X_test[0:dataset_size]
             y_train = y_train[0:dataset_size]
             v_test = v_test[0:dataset_size]
Distribution of labels :
6
     1407
     1374
5
     1286
4
1
     1226
     1073
3
     986
Name: 0, dtype: int64
Distribution of labels :
6
     537
5
     532
1
     496
4
     491
2
     471
     420
Name: 0, dtype: int64
In [12]: print('Train features shape : ', X_train.shape)
         print('Train labels shape : ', y_train.shape)
         print('Test features shape : ', X_test.shape)
         print('Test labels shape : ', y_test.shape)
Train features shape: (7352, 128, 9)
Train labels shape: (7352, 6)
Test features shape: (2947, 128, 9)
Test labels shape: (2947, 6)
   MODEL
In [13]: def build_model_a(timesteps, input_dim, h_params):
             # Initiliazing the sequential model
             model = Sequential()
             # extract the hyper params
             n_hidden = h_params[0]
             dr_rate = h_params[1]
```

```
# Configuring the parameters
             model.add(LSTM(n_hidden, input_shape=(timesteps, input_dim)))
             # Adding a dropout layer
             model.add(Dropout(dr_rate))
             # Adding a dense output layer with sigmoid activation
             model.add(Dense(num_clasess, activation='sigmoid'))
             print(model.summary())
             return model
In [14]: def build_model_b(timesteps, input_dim, h_params):
             # Initiliazing the sequential model
             model = Sequential()
             # Extract Hyperparameters
             # 1 - extract the number of neuorons
             n_hidden_1 = h_params[0]
             n_hidden_2 = h_params[1]
             # 2 - extract dropout rates
             dr_rate_1 = h_params[2]
             dr_rate_2 = h_params[3]
             # Configuring the parameters
             model.add(LSTM(n_hidden_1, input_shape=(timesteps, input_dim),
                            return_sequences=True))
             model.add(Dropout(dr_rate_1))
             model.add(LSTM(n_hidden_2, return_sequences=False))
             # Adding a dropout layer
             model.add(Dropout(dr_rate_2))
             # Adding a dense output layer with sigmoid activation
             model.add(Dense(num_clasess, activation='sigmoid'))
             print(model.summary())
             return model
In [15]: def train_model(model, model_name, X_train, y_train, num_epochs):
             # Compiling the model
             model.compile(loss='categorical_crossentropy',
```

```
optimizer='adam',
                       metrics=['accuracy'])
             # monitor the performace of model on every epoch
             checkpoint = ModelCheckpoint('./model/' + model_name, monitor='val_loss',
                                          verbose=0, save_best_only=True, mode='auto')
              # add early stopping
             early_stop = EarlyStopping(monitor='val_loss', min_delta=0,
                               patience=5, verbose=0, mode='auto')
             callbacks_list = [checkpoint, early_stop]
             # Train the model
             hist_obj = model.fit(X_train, y_train, epochs=num_epochs, batch_size=batch_size,
                                  validation_data=(X_test, y_test),
                                  callbacks=callbacks_list, verbose=0)
             hist_obj = hist_obj.history
             # write train history to a file
             hist_path = './results/' + model_name[0:-3] + '_train_history.pkl'
             pickle_out = open(hist_path, 'wb')
             pickle.dump(hist_obj, pickle_out)
             pickle_out.close()
             return hist_obj
In [16]: def evaluate_model(model, model_name, X, y, title_suffix=str(), plot_fig=True):
             # load weights from the saved model
             model_path = './model/' + model_name
             model.load_weights(model_path)
             # Compile model (required to make predictions)
             model.compile(loss='categorical_crossentropy', optimizer='adam',
                           metrics=['accuracy'])
             print('Restored best model weights from saved file', model_path)
             # evaluate model
             score = model.evaluate(X, y)
             # predict using model & get the labels
             predicted_labels = model.predict(X)
             predicted_labels_list = predicted_labels.argmax(axis=1)
             # format the actual list
```

7 Run Models

```
In [17]: # Initializing parameters
         num_epochs = 30
         batch_size = 16
         timesteps = len(X_train[0])
         input_dim = len(X_train[0][0])
         print('Number of clasess :', num_clasess)
         print('Number of timesteps :', timesteps)
         print('Input data dimenion :', input_dim)
Number of clasess : 6
Number of timesteps: 128
Input data dimenion: 9
In [18]: # Importing tensorflow
        np.random.seed(42)
         tf.set_random_seed(42)
In [19]: # Configuring a session
         session_conf = tf.ConfigProto(
             intra_op_parallelism_threads=1,
             inter_op_parallelism_threads=1
         )
```

7.1 a) Single-Layered Architecture

7.1.1 Architecture 1

```
In [21]: # Build the Model
    h_params_a1 = (32, 0.32,)
    model_a1 = build_model_a(timesteps, input_dim, h_params_a1)
```

WARNING:tensorflow:From /home/nisheel-s/anaconda3/lib/python3.6/site-packages/keras/backend/tensInstructions for updating:

keep_dims is deprecated, use keepdims instead

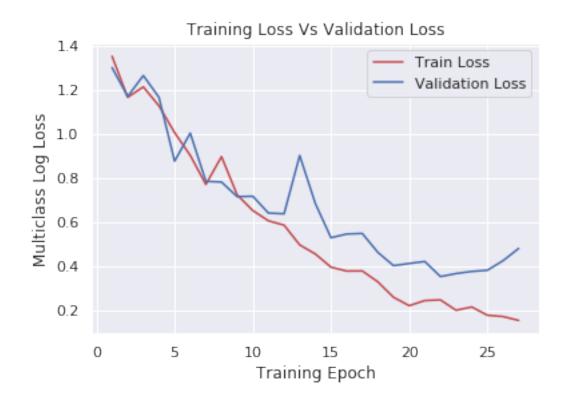
Layer (type)	Output Shape	Param #
lstm_1 (LSTM)	(None, 32)	5376
dropout_1 (Dropout)	(None, 32)	0
dense_1 (Dense)	(None, 6)	198

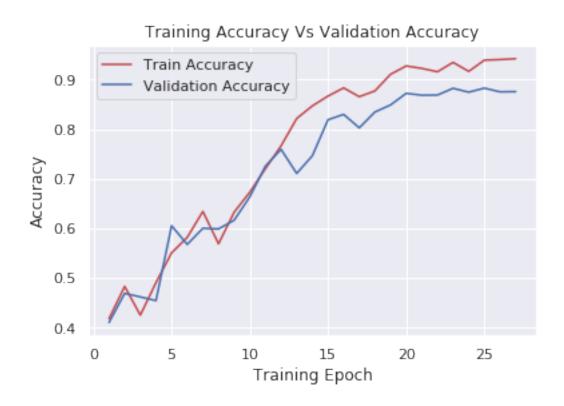
Total params: 5,574 Trainable params: 5,574 Non-trainable params: 0

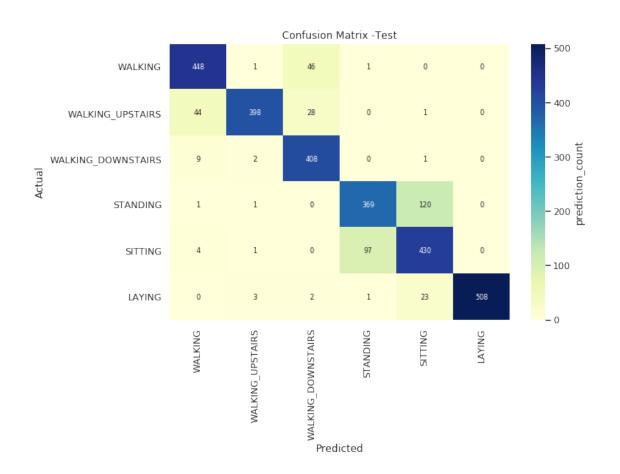
None

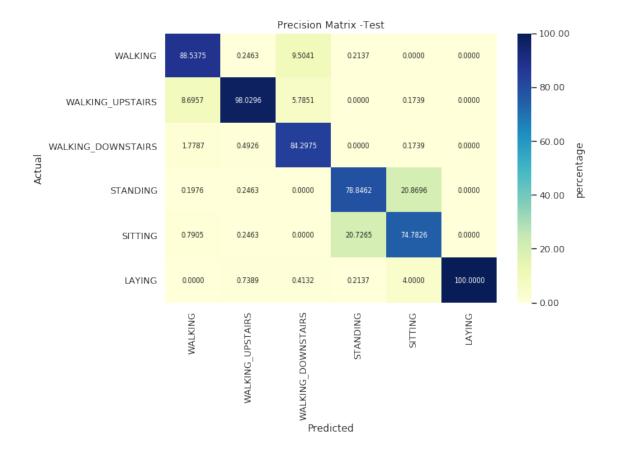
WARNING:tensorflow:From /home/nisheel-s/anaconda3/lib/python3.6/site-packages/keras/backend/tensInstructions for updating:

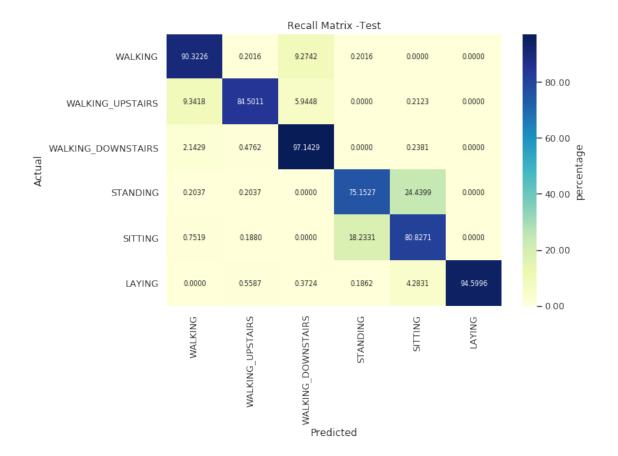
keep_dims is deprecated, use keepdims instead

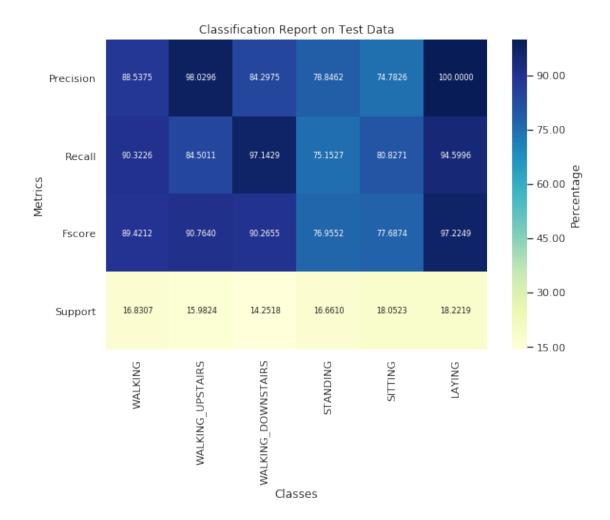












7.1.2 Architecture 2

Layer (type)	Output Shape	Param #
lstm_2 (LSTM)	(None, 48)	11136
dropout_2 (Dropout)	(None, 48)	0
dense_2 (Dense)	(None, 6)	 294

Total params: 11,430 Trainable params: 11,430 Non-trainable params: 0

None

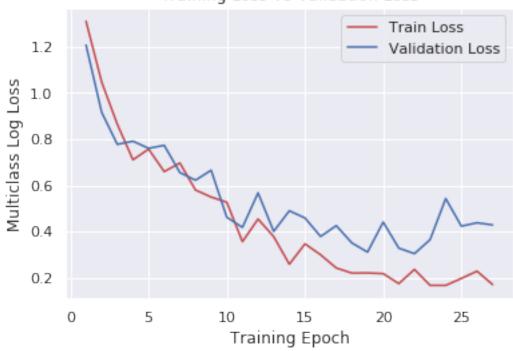
In [28]: # Train the Model

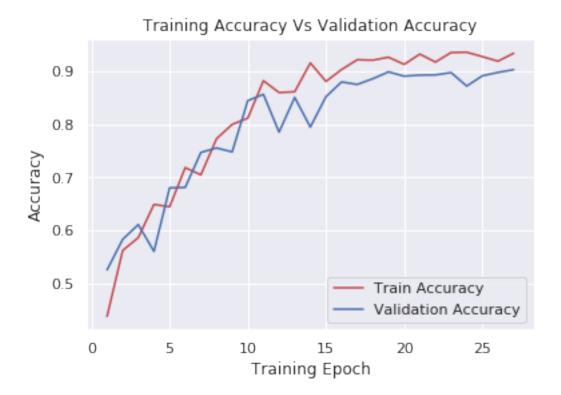
model_a2_name = 'Single_Layered_LSTM_2.h5'
hist_model_a2 = train_model(model_a2, model_a2_name, X_train, y_train, num_epochs)

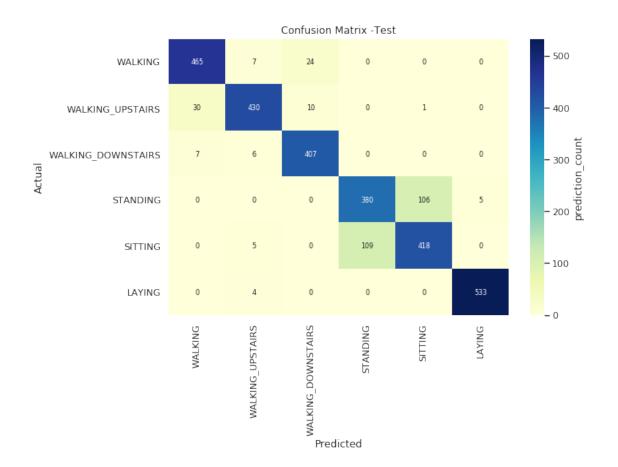
In [29]: # plot loss, accuracy curves

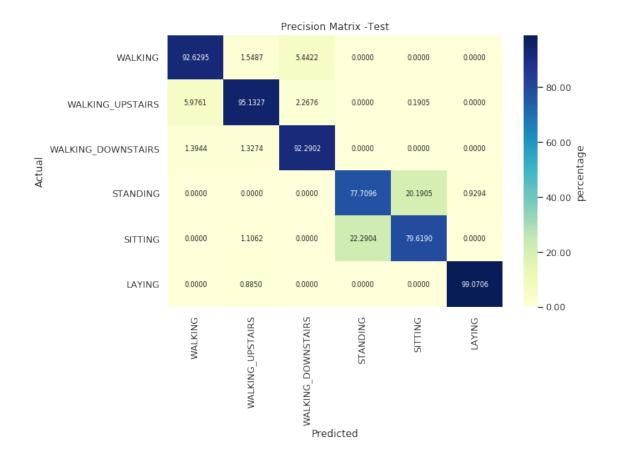
plot_loss_curve(hist_model_a2)
plot_accuracy_curve(hist_model_a2)

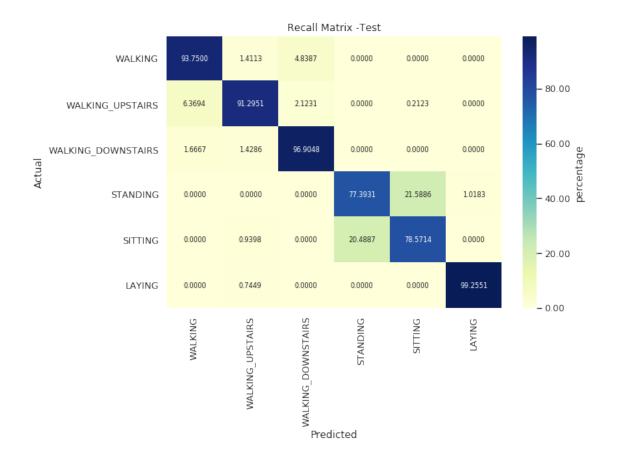


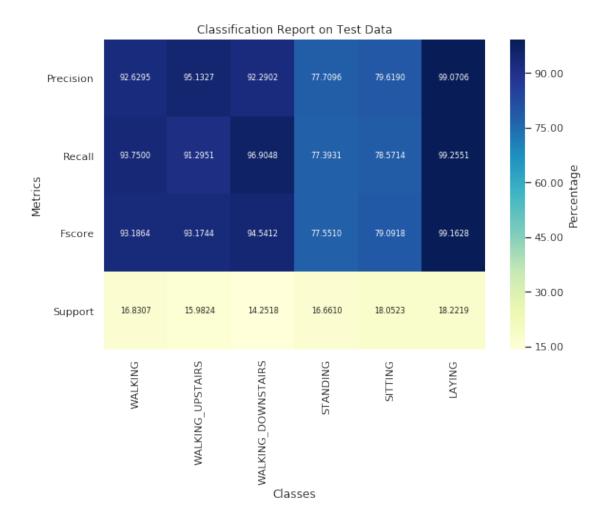












7.2 b) 2-Layered Architecture

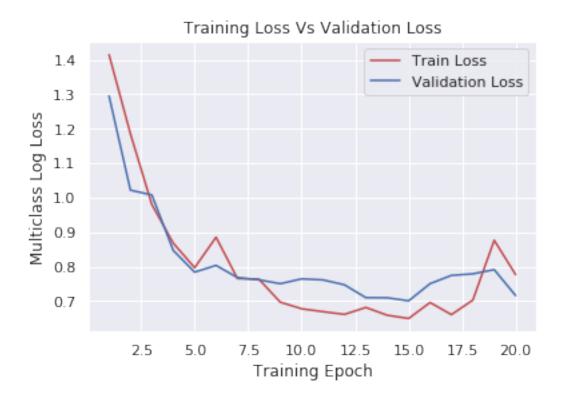
7.2.1 Architecture 1

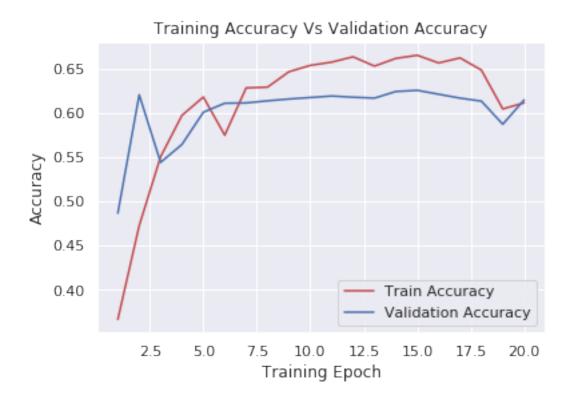
Layer (type)	Output Shape	Param #		
lstm_3 (LSTM)	(None, 128, 32)	5376		
dropout_3 (Dropout)	(None, 128, 32)	0		
lstm_4 (LSTM)	(None, 18)	3672		

dropout_4 (Dropout)	(None, 18)	0
dense_3 (Dense)	(None, 6)	114

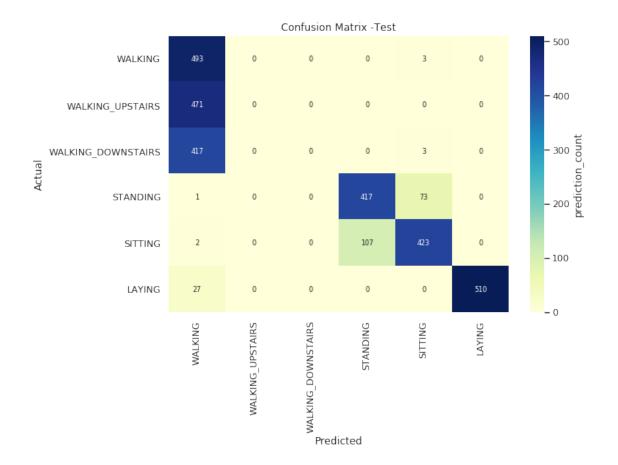
Total params: 9,162 Trainable params: 9,162 Non-trainable params: 0

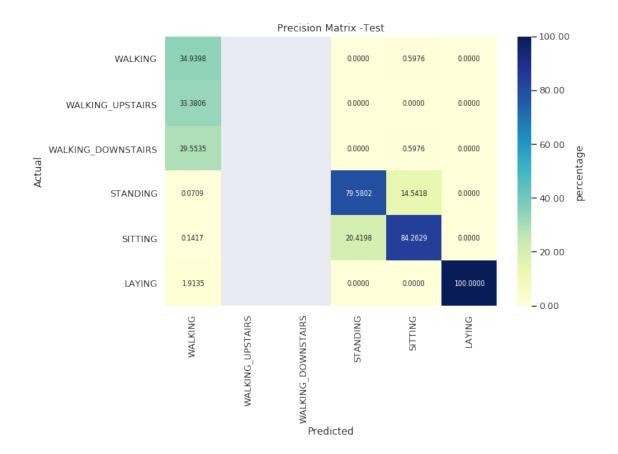
None

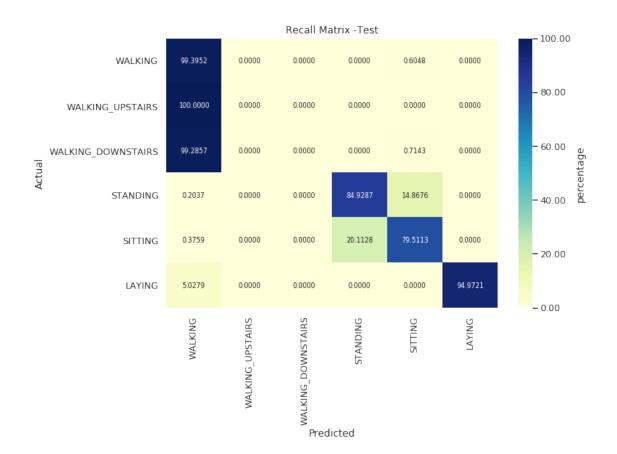




/home/nisheel-s/anaconda3/lib/python3.6/site-packages/sklearn/metrics/classification.py:1143: Un 'precision', 'predicted', average, warn_for)







/home/nisheel-s/anaconda3/lib/python3.6/site-packages/sklearn/metrics/classification.py:1143: Un 'precision', 'predicted', average, warn_for)



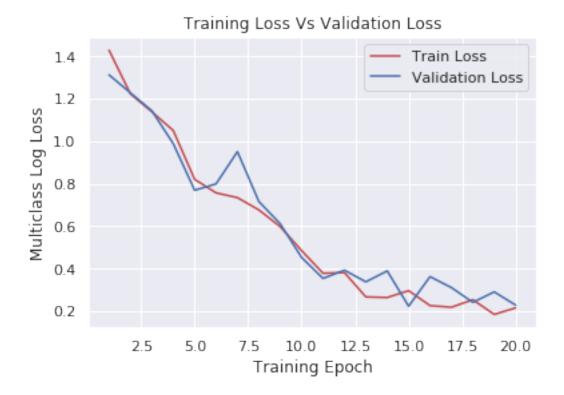
7.2.2 Architecture 2

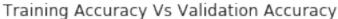
Layer (type)	Output Shape	Param #	
lstm_5 (LSTM)	(None, 128, 44)	9504	
dropout_5 (Dropout)	(None, 128, 44)	0	
lstm_6 (LSTM)	(None, 23)	6256	
dropout_6 (Dropout)	(None, 23)	0	

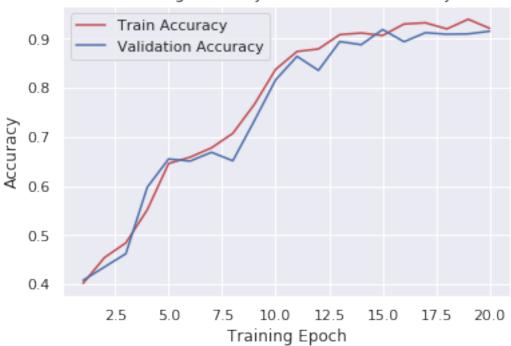
dense_4 (Dense) (None, 6) 144

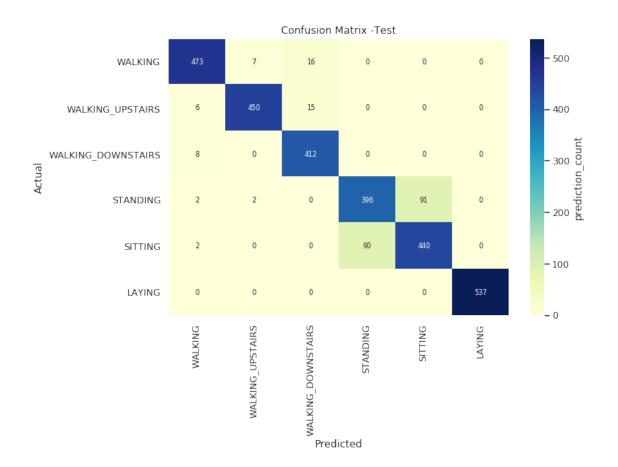
Total params: 15,904 Trainable params: 15,904 Non-trainable params: 0

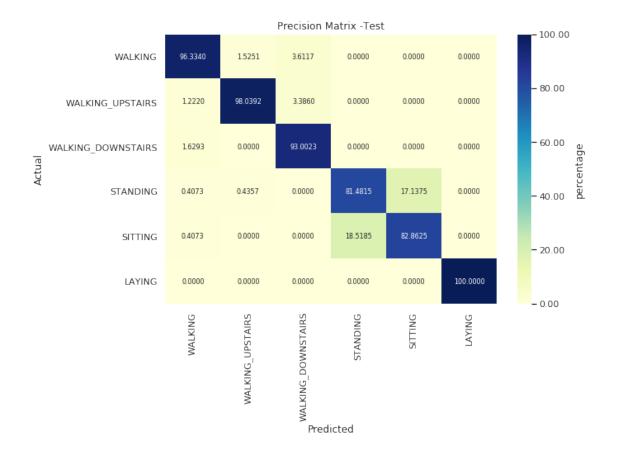
None

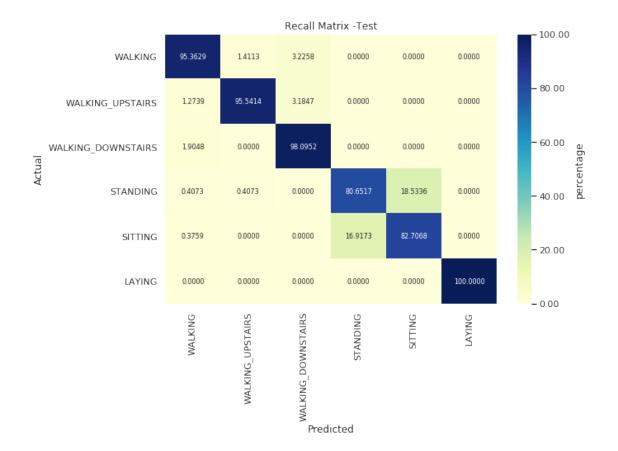


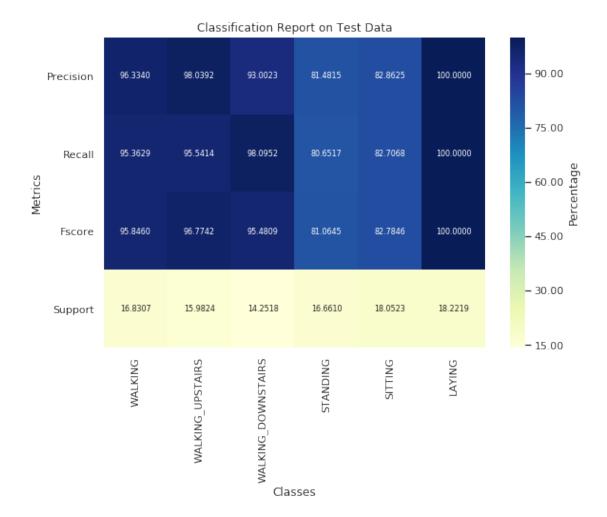












8 Results

+.			+_		+	+.		+	
1	Model	Hyperparam (#units,dropout)		Train Loss	Train Acc (%)		Test Loss	T	es.
	1 Layered LSTM(1)			0.1624	93.7432	Ì	0.3532	_	8
	1 Layered LSTM(2)	(48, 0.4)		0.1592	94.056		0.3041		8
	2 Layered LSTM(1)	(32, 18, 0.3, 0.45)		0.6048	67.519		0.7012		6
	2-Layered LSTM(2)	(44, 23, 0.32, 0.48)		0.1456	94.9674		0.2236		S
+.		-	+_		+	+.		+	

9 Procedure Summary

The dataset is re-formated to feed into LSTM model

The datset is pattioned based on the number of users , 21 users in train side, 9 in test side (70:30) split

Two versions of single layered LSTM is architecure is desinged

Two versions of two layered LSTM is architecure is desinged

Train vs validation loss plot is made to ealuate performance

10 Conclusion

2-Layered LSTM architecture 2 performed well with 91.89 % accuracy

2-Layered LSTM architecure performace is not good as the accuracy is 62% very less compared to other models

Single layered architectue 1 showed 7% deviation between train, test. It shows tendancy to overfit

Hyperparam of 2-layered architecture 2 can be tuned to improve the results further All models get confused more in classiying between sitting & standing