Nishi Sharma

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EXPERIENCE

BORGWARNER IPEC | ASSOCIATE SOFTWARE ENGINEER July 2023 – Present | Bengaluru, Karnataka

- Responsible for the development and testing of real-time Application Software for Low Level Drivers, focusing on high reliability, performance, in compliance with AUTOSAR and ISO 26262 functional safety standards.
- Contributed to process improvements and documentation that enabled the project to achieve ASPICE Level 2 compliance, ensuring structured software development and traceability
- Developed automation script for MISRA C/C++ static code analysis, reducing manual effort and development time by 20%.
- Integrated factory test software and MCAL drivers with AUTOSAR RSW
- Collaborated with CoC and CoE teams to support platform-level integration and testing of the Park Lock System.
- Hands on experience in testing with HW boards using tools like JTAG, Trace 32 debuggers and PCAN.
- Participated annually in Tech Day Events with cross-functional teams to foster innovation and collaboration; received Spark Award for paper presentation and contributions to the Variable Gate Drive Strength(VGR) feature.

MCCAIN INDIA | ELECTRICAL INTERN May 2022 - July 2022 | Mehsana, Gujarat

- Worked on reactive and proactive maintenance strategies for reducing and optimizing preventive maintenance time.
- Research work on Industrial Automation, SCADA and PLC

PROJECTS

SMART BATTERY MONITORING SYSTEM | DEVELOPED SIMULINK MODEL FOR BATTERY STATE ESTIMATION

May 2022-May 2023 SVNIT, Surat Link: BMS

- Implemented Simulink Model for Battery SOC and SOH estimation using different algorithms like Coulomb Counting and Kalman Filters.
- Designed and integrated the firmware that runs on Arduino Uno and sensors like wifi module, current and temperature sensor using UART serial communication.
- Worked on User friendly GUI using Thignspeak(IOT) that displays real-time battery data and charts in your mobile application.

UAV CONTROL SYSTEM | DESIGNED SIMULINK MODEL Nov 2022 - Aug 2023 | Drishti SVNIT, Surat | Link: Github

 Designed UAV control system on MATLAB Simulink from scratch using UAV Toolbox. Simulated the mathematical model of UAV and estimated the control system parameters using PID algorithm.

LINE FOLLOWER BOT | EMBEDDED C Nov 2019 Drishti SVNIT, Surat

 Designed an Autonomous line following bot using infrared sensors and ATMEGA 32 microcontroller.

EDUCATION

SVNIT, SURAT

BTECH. ELECTRICAL ENGINEERING, WITH MINORS IN ECE
May 2023 | Surat, Gujarat
Cum. CGPA: 9.21 / 10.0

SKILLS

Languages:

Embedded C \bullet C/C++ \bullet Python \bullet Assembly

Model-Based Design:

MATLAB Simulink

Debugging Tools:

TRACE32 • Lauterbach • MS Visual

Studio • ASTREE

Standards and Compliance

ISO 26262 • AUTOSAR • ASPICE •

MISRA C/C++ • SDLC

Microcontrollers:

Infineon AURIX TC37xx • STM32 •

Arduino (AVR/ARM)

Protocols:

CAN • SPI • I2C • UART

ALM Tools:

JIRA • Polarion

Others:

Git/Bitbucket • RTOS

CI/CD • Automation

Multithreading • Memory Management

COURSEWORK

- Data Structure and Algorithm,LeetCode
- The Ardrino Platform and C Programming, Coursera
- Introduction to the Internet of Things and Embedded Systems, Coursera
- Motor Control and Power Electronics
- Computer Architecture

SOCIETIES

- Drishti, SVNIT
- DSC, NIT SURAT
- EES. NIT SURAT