## BLUE YONDER'S NEXT-GEN OPTIMIZED DELIVERY ECOSYSTEM



## **Output Format:**

`Scenario3` contains 4 output files `CostReport1A.csv`,
`CostReport1B.csv`, `DronePath1A.csv` and `DronePath1B.csv`
containing cost reports and drone paths respectively. Since
Complexity 3 is being handled, CostReport1A and DronePath1A
will be the original plan whereas CostReport1B and
DronePath1B will be the replan after cancellation.

Our solution takes care of the base solution and all three complexity levels (1+2+3).

In all the 3 scenarios, we are able to deliver all the demands.

## **Assumptions:**

Here are some of the assumptions we took based on our observations of the test data. This assumption holds on the data provided.

Assumption 1: Round trips to the demand location should be possible to each of the demand locations without using any Recharge Stations.

Assumption 2: There is no demand location such that it is directly above or below any of the No-Fly Zones in the future datasets.

Assumption 3: There are no No-Fly Zones on the ground.

Assumption 4: We can dynamically decide which drone should belong to which warehouse at the end of the day. In the case of multiple days, if a particular drone belongs to Warehouse 1 on day 1, it can belong to Warehouse 2 on the next day.