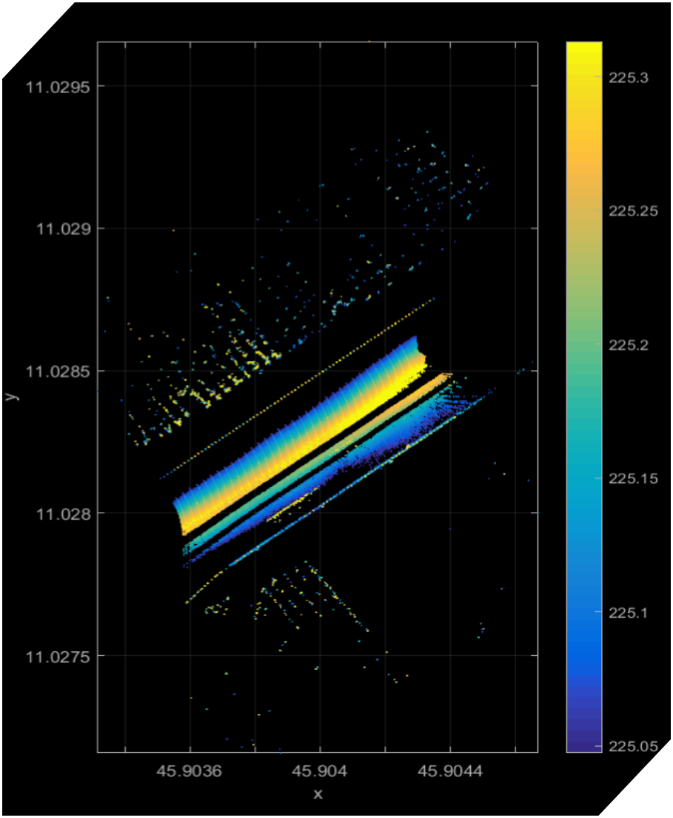
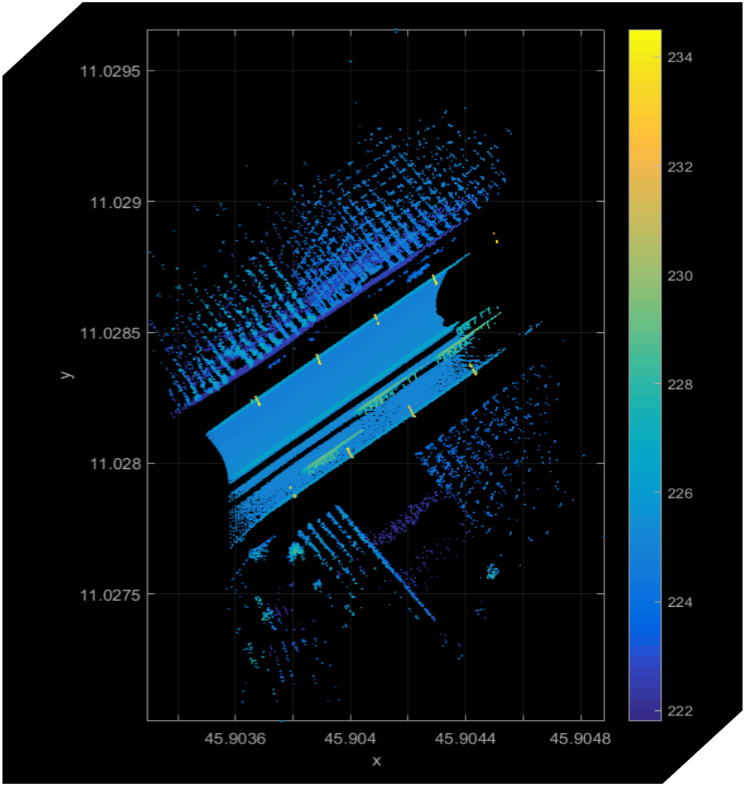
**OUTPUTS**

**APPROACH 1: PYTHON**

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Original point cloud Outliers (objects) Inliers (final output)

**APPROACH 2: MATLAB**

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Original point cloud Inliers (final output)