NICOLAS SOMMER, PhD

Residence permit: Swiss Permis C

Robotics and Machine Learning

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EDUCATION

Nationality: French

PhD

"Multi-contact tactile exploration and interaction with unknown objects"

EPFL

□ December 2012 - May 2017

- Application of machine learning techniques to robotics, taking into account external sensing such as touch or force-torque information
- Robot control applied to haptic exploration using tactile sensors
- Experience with multiple robot platforms (iCub humanoid robot, Barrett WAM Arm, Kuka LWR 4, Kuka IIWA, Wonik AllegroHand)
- Supervision of student's master thesis
- In charge of IT administration in the lab (about 15 persons)

Msc, Microengineering

Robotics and Autonomous Systems

EPFL

2010 - 2012

- Master project: Learning with tactile feedback on a humanoid robot I applied Programming by Demonstration (PbD) methods to learn and reproduce manipulation tasks, taking into account tactile signals from the robot's fingertips
- Double-degree between EPFL (CH) and INSA (FR)

Msc, Mechatronics

INSA

2006 - 2011

♀ Strasbourg, France

• Project: Design of a quadrotor controller Model identification of a quadrotor, optimizing controller parameters for flight, programming of the controller on onboard microcontroller (Microchip dsPIC family)

WORK EXPERIENCE

Teaching assistant for graduate-level courses **EPFL**

2011-2015

Topics: Dimensionality reduction Unsupervised learning

Clustering | Classification Regression

 MICRO-570 Advanced Machine Learning (Spring 2012..2015) PCA | ICA | K-means KNN GMM/GMR

Neural networks **HMM**

MICRO-455 Applied Machine Learning (Fall 2011..2015)

Bagging/boosting | Reinforcement Learning CCA

RESEARCH INTERESTS



Machine Learning

Applied to robotics



Robot control with sensors

Enable robot use in real environments

SKILLS



LANGUAGES

French **English** German **Spanish**



ACHIEVEMENTS



Tasti.ch

Winner of startup weekend Lausanne



Multi-contact haptic exploration

Featured in Science Magazine "In other journals". 23 Sep 2016.



INTERESTS

