3 Elliptic equation

Consider the Dirichlet problem

(3.1)
$$Pu = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y) \text{ in } \Omega = (0, 1) \times (0, 1)$$

with boundary condition

(3.2)
$$u = g(x, y)$$
 on the boundary of $\Omega = \partial \Omega$

Let us denote $u(x_i, y_j) = u_i^j$, $f(x_i, y_j) = f_i^j$ and on boundary $u_i^j = v_i^j = g(x_i, y_j)$. Then the numerical scheme corresponding to (3.1) can be written as

(3.3)
$$P_{\Delta x, \Delta y} v = \frac{v_{i+1}^j - 2v_i^j + v_{i-1}^j}{(\Delta x)^2} + \frac{(v_i^{j+1} - 2v_i^j + v_i^{j-1})}{(\Delta y)^2} = f_i^j$$

which is second order accurate. Because if u is a solution of (3.1) then

$$P_{\Delta x, \Delta y} = O(\Delta x^2) + O(\Delta y^2)$$

Since the ratio of the mesh plays an insignificant role in the theory of elliptic problems. to study the above problem we take $\Delta x = \Delta y = h$ for simplicity. Then (3.3) becomes

$$v_{i+1}^{j} - 2v_{i}^{j} + v_{i-1}^{j} + (v_{i}^{j+1} - 2v_{i}^{j} + v_{i}^{j-1}) = h^{2} f_{i}^{j}$$

i.e.,

$$(3.4) 4v_i^j = v_{i+1}^j + v_{i-1}^j + v_i^{j+1} + v_i^{j-1} - h^2 f_i^j, \quad 1 \le i, j \le M - 1$$

Let
$$x_0 = y_0 = 0$$
 $x_i = i\Delta x = ih, i = 0, ..., M$
 $x_M = y_M = 1$ $y_i = i\Delta y = ih, i = 0, ..., M$

Let us consider the following simple cases to understand the scheme (3.4)

Let M=3

Then by (3.4)

$$4v_1^1 - (v_2^1 + v_0^1 + v_1^2 + v_1^0) = -h^2 f_1^1$$

$$4v_2^1 - (v_3^1 + v_1^1 + v_2^2 + v_2^0) = -h^2 f_2^1$$

$$4v_1^2 - (v_2^2 + v_0^2 + v_1^3 + v_1^1) = -h^2 f_1^2$$

$$4v_2^2 - (v_3^2 + v_1^2 + v_2^3 + v_2^1) = -h^2 f_2^2$$

As on boundary $v_i^j = g_i^j$, this can be written as a linear system

$$Av = b_{g,f}$$

i.e.

$$Av = \begin{bmatrix} 4 & -1 & -1 & 0 \\ -1 & 4 & 0 & -1 \\ -1 & 0 & 4 & -1 \\ 0 & -1 & -1 & 4 \end{bmatrix} \begin{bmatrix} v_1^1 \\ v_2^1 \\ v_1^2 \\ v_2^2 \end{bmatrix} = \begin{bmatrix} g_0^1 & + & g_1^0 - h^2 f_1^1 \\ g_3^1 & + & g_2^0 - h^2 f_2^1 \\ g_0^2 & + & g_1^3 - h^2 f_1^2 \\ g_3^2 & + & g_2^3 - h^2 f_2^2 \end{bmatrix} = bg, f.$$

Now A can be written as

$$A = \begin{bmatrix} B & -I \\ -I & B \end{bmatrix}$$
, where $B = \begin{bmatrix} 4 & -1 \\ -1 & 4 \end{bmatrix}$, $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

A is a strictly diagonally dominant matrix. Hence A is invertible. Therefore above linear system can be solved uniquely.

Now let us consider the case M=4

$$\begin{array}{rclcrcl} 4v_1^1-v_2^1-v_1^2&=&v_1^0+v_0^1-h^2f_1^1\\ 4v_2^1-v_3^1-v_2^1-v_1^1&=&v_2^0-h^2f_2^1\\ &4v_3^1-v_3^2-v_2^2&=&v_3^0+v_4^1-h^2f_3^1\\ 4v_1^2-v_2^2-v_1^3-v_1^1&=&v_0^2-h^2f_1^2\\ 4v_2^2-v_3^2-v_1^2-v_2^3-v_2^1&=&0-h^2f_2^2\\ &4v_3^2-v_2^2-v_3^1-v_3^3&=&v_4^2-h^2f_3^2\\ &4v_1^3-v_2^3-v_1^2&=&v_0^3+v_1^4-h^2f_1^3\\ &4v_2^3-v_3^3-v_2^2-v_1^3&=&v_2^4-h^2f_2^3\\ &4v_3^3-v_2^3-v_3^2&=&v_3^4+v_4^4-h^2f_3^3\\ \end{array}$$

This can be written as a linear system

$$Av = b_{q,f}$$

i,e.,

Now A can be written as

$$A = \begin{bmatrix} B & -I & O \\ -I & B & -I \\ O & -I & B \end{bmatrix} , \text{ where } B = \begin{bmatrix} 4 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 4 \end{bmatrix}$$

A is 9×9 matrix, B, O(zero matrix) and I are 3×3 matrices. In general (3.4) can be written as

$$Av = b_{g,f}$$

where

$$A = \begin{bmatrix} B & -I & & O \\ -I & B & -I & & \\ & -I & B & -I & & \\ & & & \cdot & \cdot & \cdot \\ O & & & -I & B \end{bmatrix}$$

where

$$B = \begin{bmatrix} 4 & -1 & & O \\ -1 & 4 & -1 & \\ & \cdot & \cdot & \cdot \\ O & & -1 & 4 \end{bmatrix}$$

with A is a matrix of order $(M-1)^2$. B, O and I are matrices of order M-1. v is a vector given by

$$v = (v_1^1, v_2^1, \dots, v_{M-1}^1, v_1^2, v_2^2, \dots, v_{M-1}^2, \dots, v_1^{M-1}, \dots, v_{M-1}^{M-1})^T$$

and b_g is a vector depends on the boundary values.

A is symmetric and positive definite. As A is tridioganal block matix there are several methods like direct methods or iterative methods to solve the above system.

Convergence: Let u = u(x, y) be the actual solution of the problem and let $\epsilon_i^j = u_i^j - v_i^j$ where $u_i^j = u(x_i, y_j) = u(ih, jh)$ and v_i^j is obtained from (3.4). Since $\Delta u = f$ we have

$$4u_i^j - (u_{i+1}^j + u_{i-1}^j + u_i^{j+1} + u_i^{j-1} - h^2 f_i^j) + O(h^4) = 0 \quad \text{(is dotained by })$$

Therefore we have, by subtracting 3.4 from above equ.

$$L\epsilon = \epsilon_i^j - \frac{1}{4}(\epsilon_{i+1}^j + \epsilon_{i-1}^j + \epsilon_i^{j+1} + \epsilon_i^{j-1}) = O(h^4) \le Mh^4$$

for some M>0. On the boundary $\epsilon_i^j=u_i^j-v_i^j\equiv 0$. Let $w(x,y)=x^2+y^2$ and $w_i^j=w(ih,jh)$

$$Lw = w_i^j - \frac{1}{4}(w_{i+1}^j + w_{i-1}^j + w_i^{j+1} + w_i^{j-1}) = -h^2$$

Define

$$\tilde{\epsilon}^{j}{}_{i} = \epsilon^{j}_{i} + Mh^{2}w^{j}_{i}$$
. Then

$$L\tilde{\epsilon} = L\epsilon + Mh^2Lw < Mh^4 - Mh^4 = 0$$

 \Rightarrow

$$\tilde{\epsilon}_i^j \le \frac{1}{4} (\tilde{\epsilon}_{i+1}^j + \tilde{\epsilon}_{i-1}^j + \tilde{\epsilon}_i^{j+1} + \epsilon_i^{j-1})$$

 $\Rightarrow \tilde{\epsilon}_i^j$ attains maxima on the boundary

Let r denotes the radius of a circle about the origin enclosing the region $\Omega = (0, 1) \times (0, 1)$.

$$\begin{split} \hat{\epsilon}_i^j &\leq \text{maximum of } \epsilon_i^j \text{ on the boundary } + Mh^2r^2 \\ &= 0 + Mh^2r = Mh^2r^2 (\text{ because } \epsilon_i^j \equiv 0 \text{ on boundary}) \end{split}$$

Now define $\underline{\epsilon}_i^j = \epsilon_i^j - Mh^2w_i^j$. By similar arguments one can show that

$$\underline{\epsilon}_i^j \ge -Mr^2h^2$$

$$-Mr^{2}h^{2} \leq \underline{\epsilon}_{i}^{j} \leq \epsilon_{i}^{j} \leq \tilde{\epsilon}_{i}^{j} \leq Mh^{2}r^{2}$$

$$\Rightarrow |\epsilon_{i}^{j}| \leq Mh^{2}r^{2}$$

Hence as mesh size goes to zero numerical solution goes to actual solution.