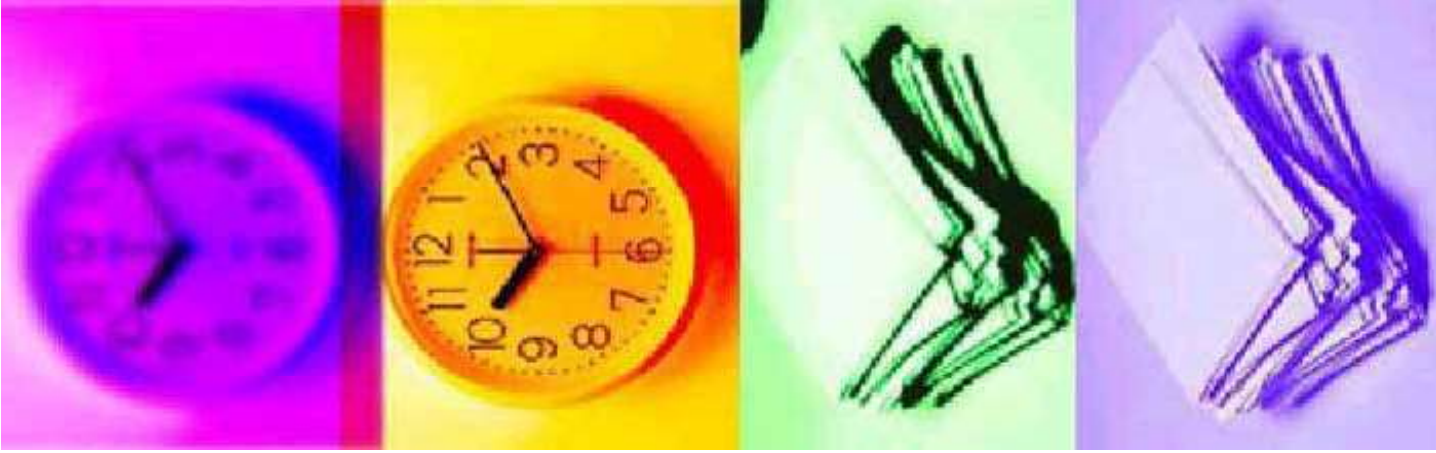


# Network Management

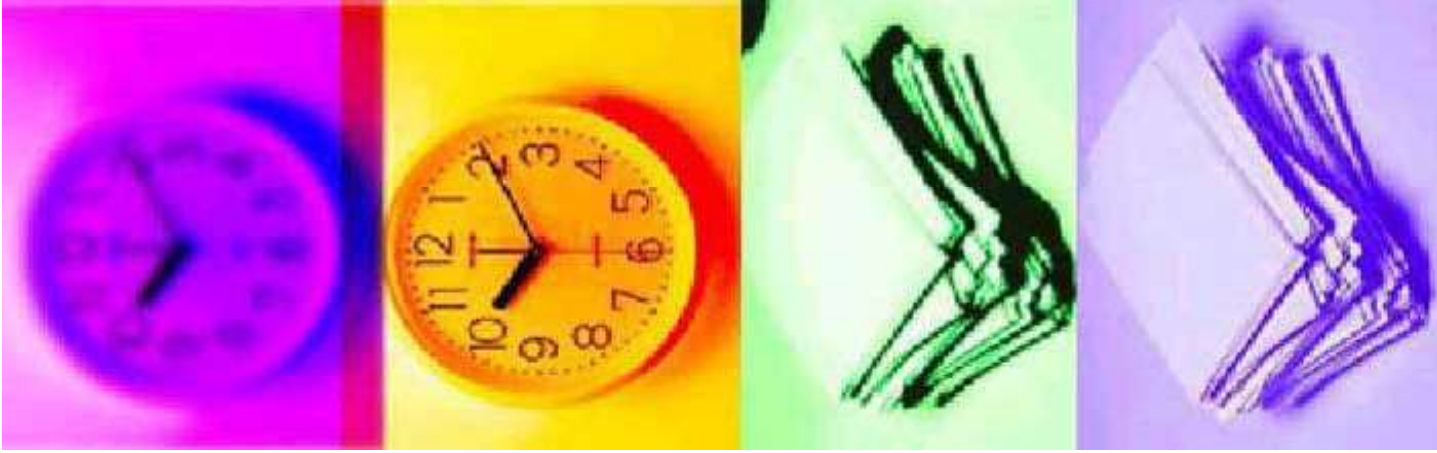
## Overview

- Managing several control units linked together via their network nodes
- Managing different ECU those exchange information via the same CAN bus



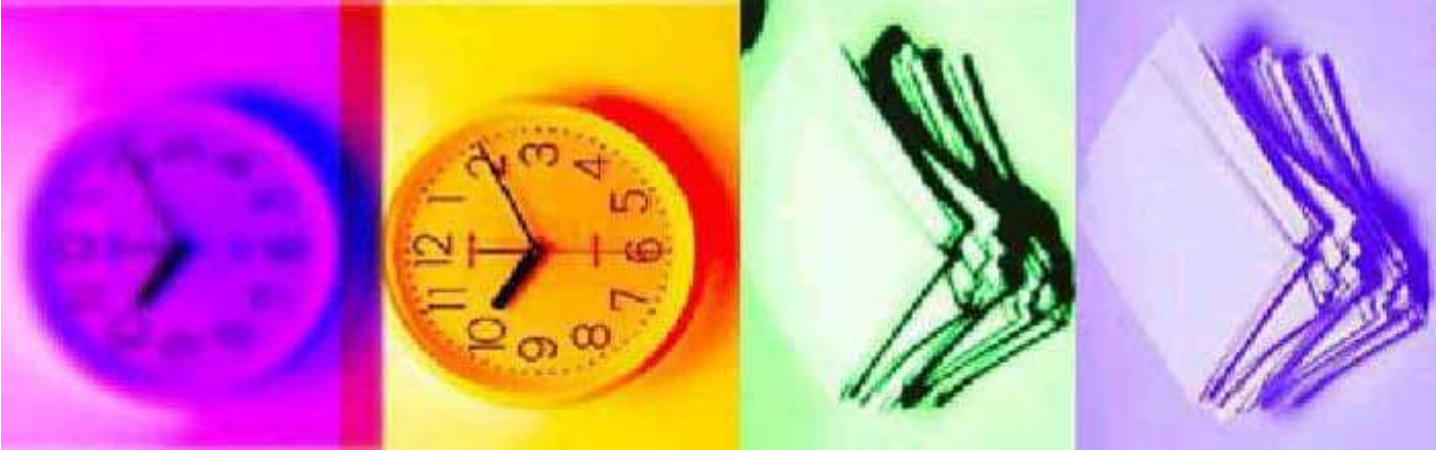
# Network Management (NM) Task

- Startup and shut down of network communication
- Handling communication failure
- Appointment for Network Configuration
- Inspection of network configuration
- Power management
- Node management



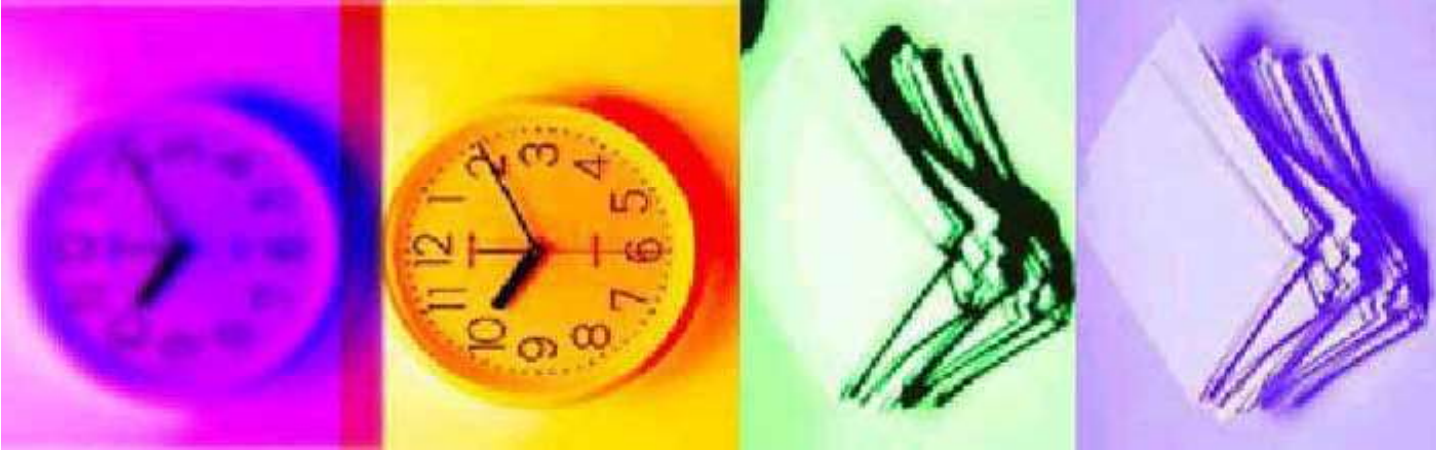
# OSEK NM

- It is a token based strategy for the communication.
- Besides normal application message a special message is defined for each node
- it passes the network information and control the transmission and reception of application message



# OSEK NM Function

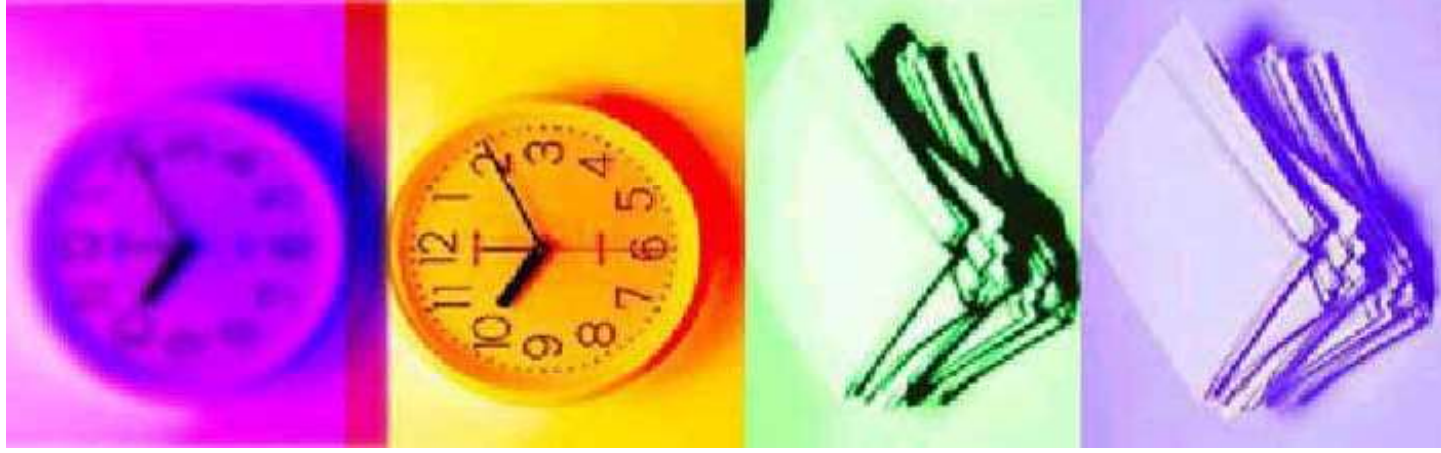
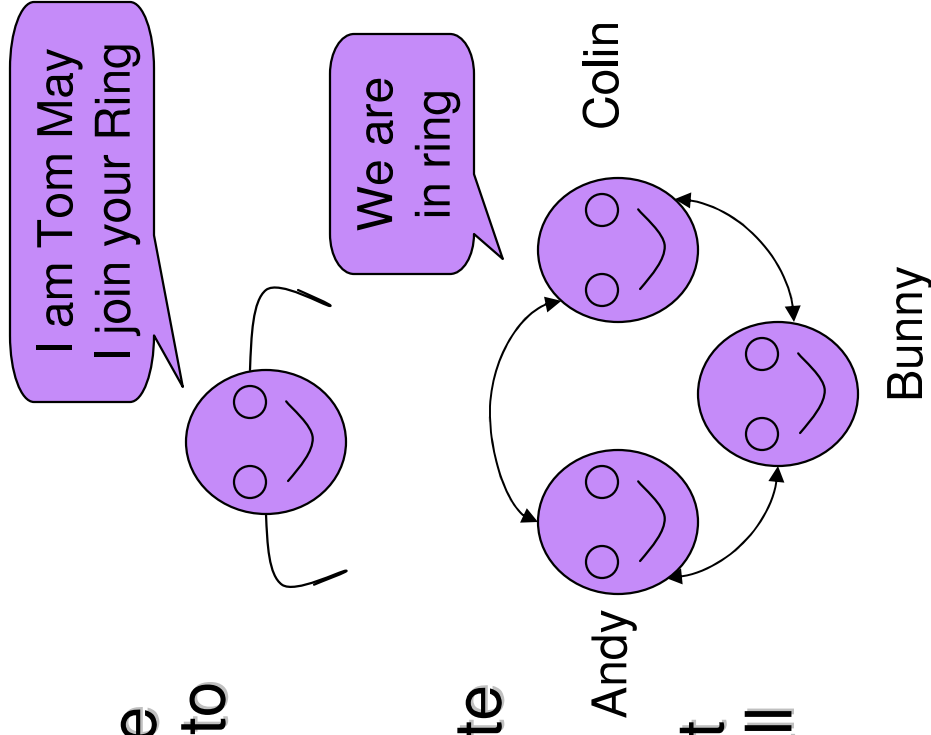
- Alive
- Ring
- Sleep
- Wakeup
- Sleep indication
- Limp home
- Sleep acknowledge



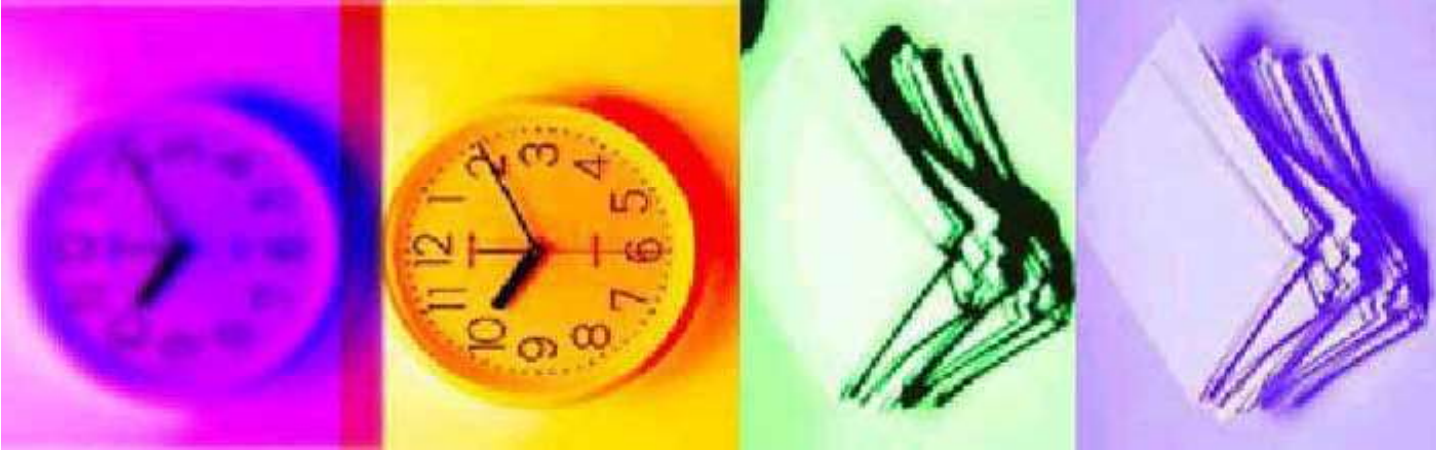
# Alive

- If a node needs the network and want to join the communication it sends an “Alive” message to indicate the other nodes of existing

- When a node want to join a ring it shall send its can message with “Alive” bit set

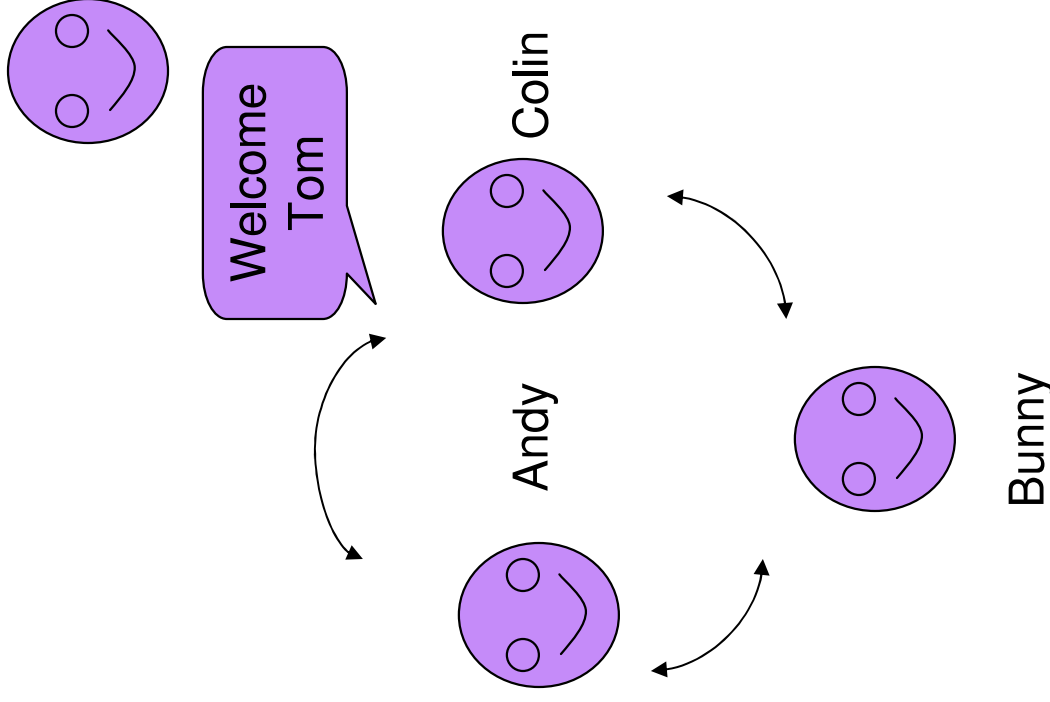


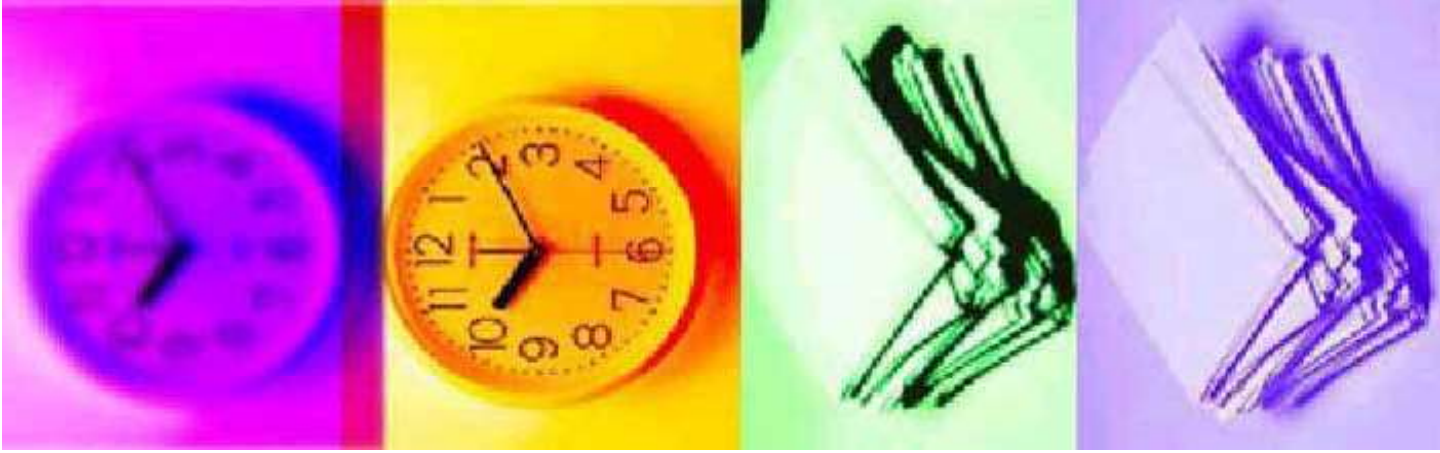




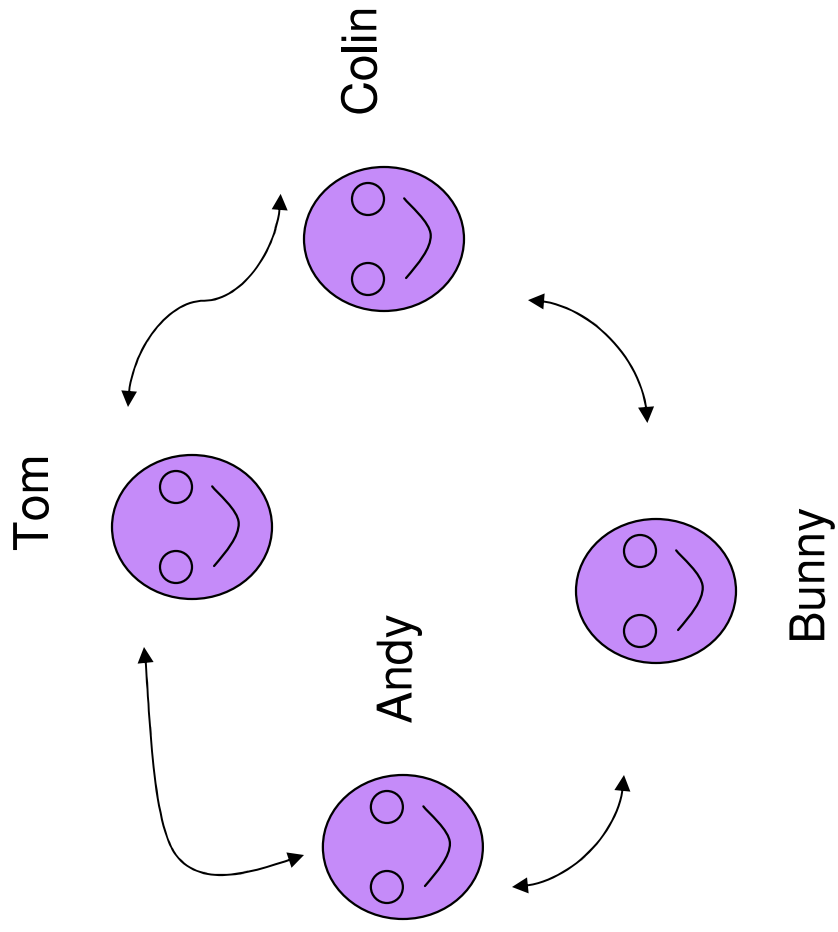
# Ring

- All nodes will build up a logical ring to achieve a network-wide synchronization of all ECUs that take part in communication



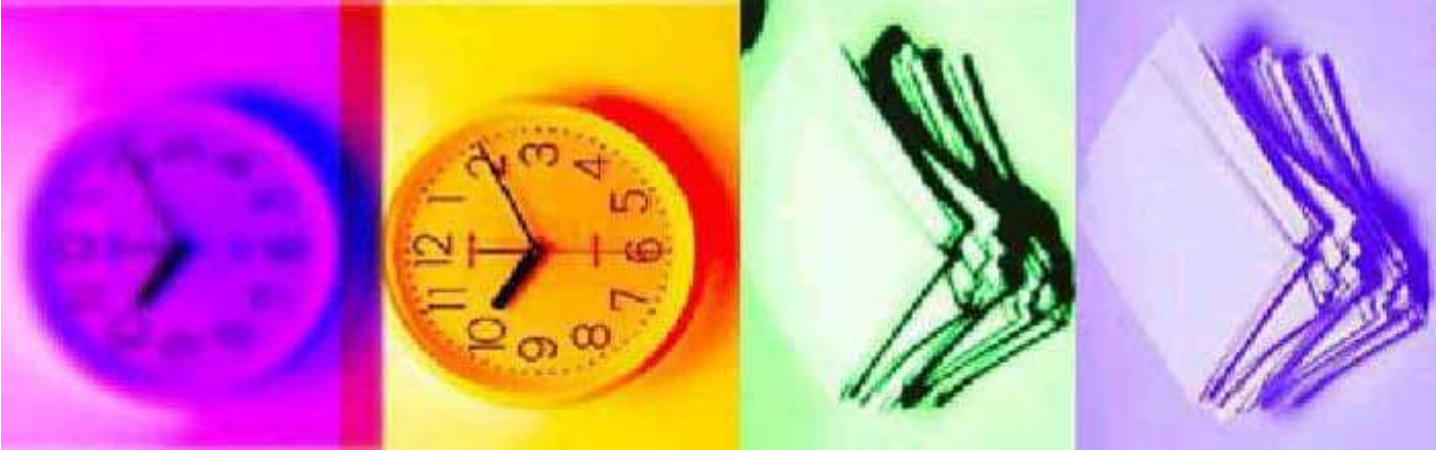


# After Ring Formation

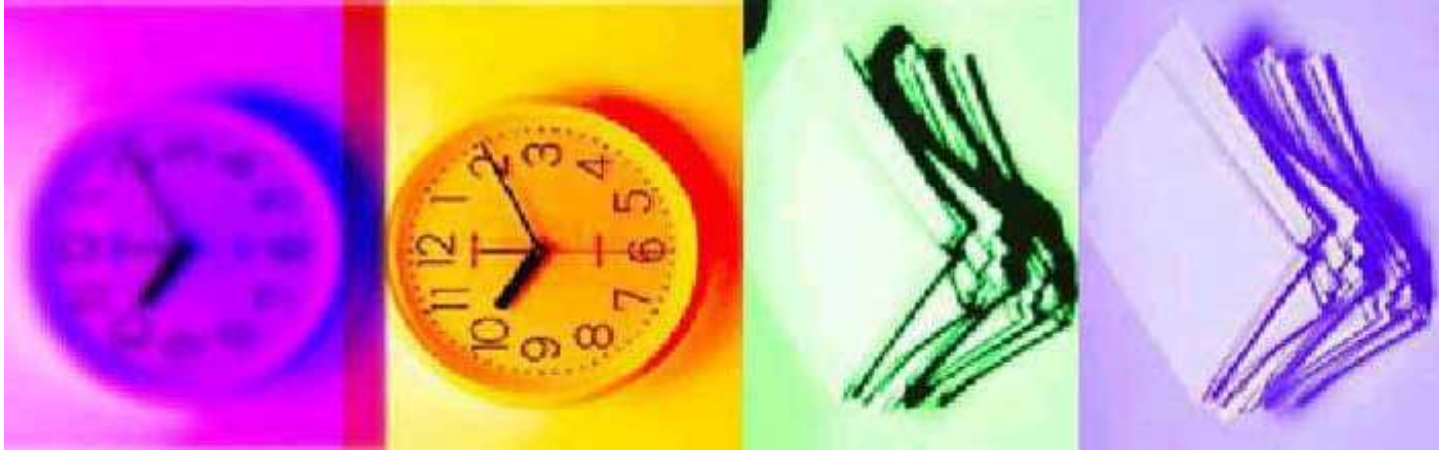


# Sleep Indication

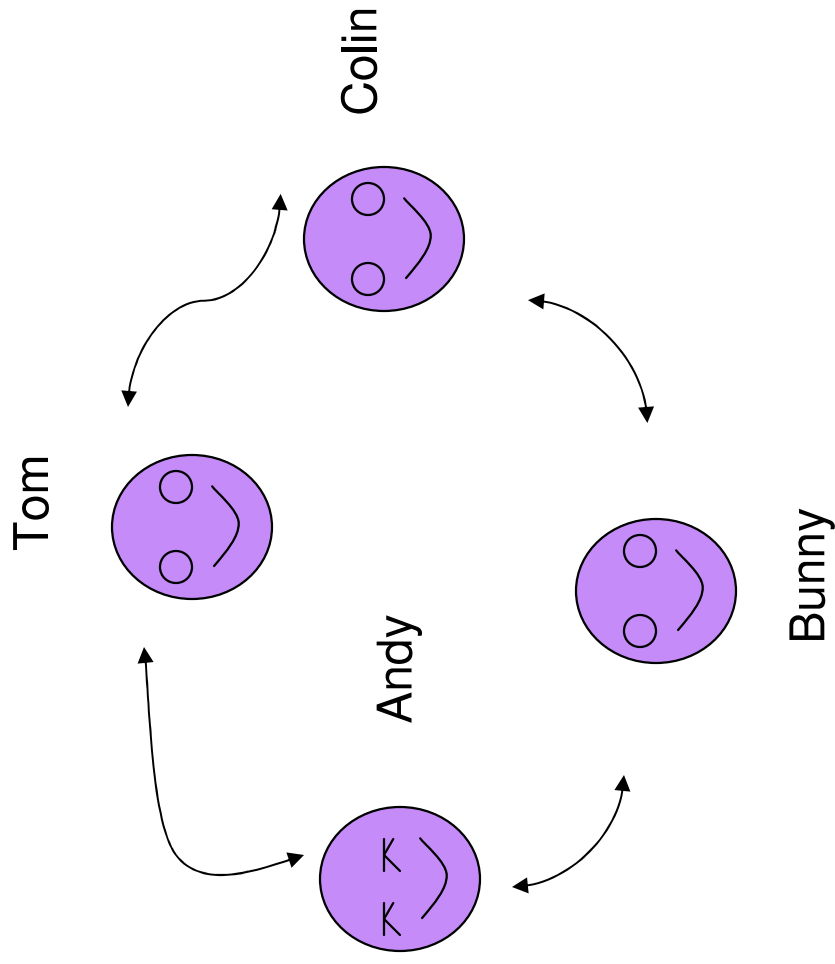
- When ECU does not need the network it sends out “Sleep Indication” to inform the other ones that it want to off the line





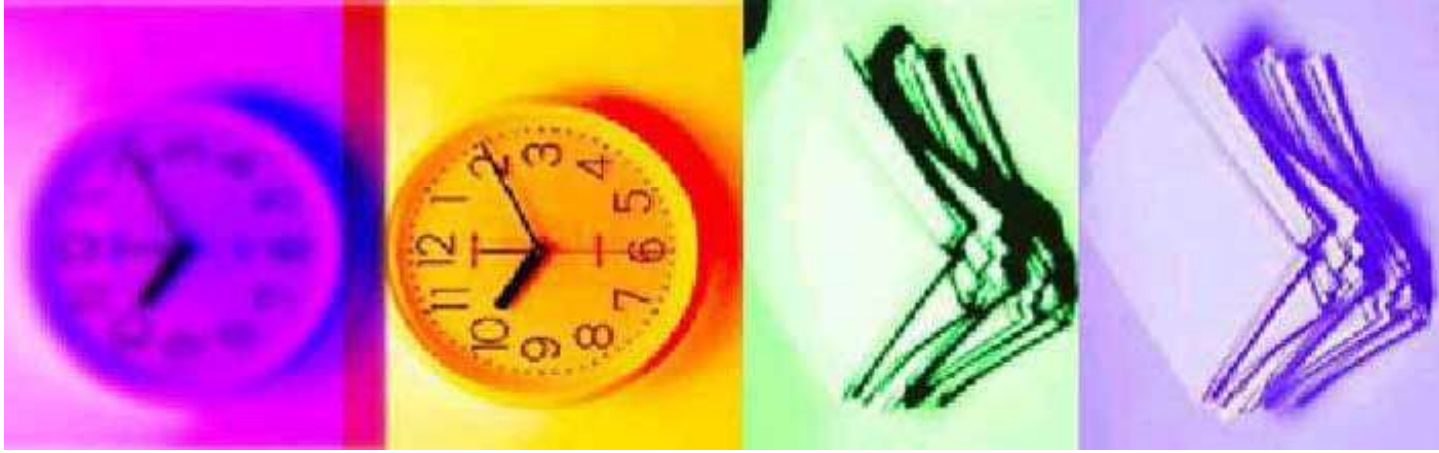


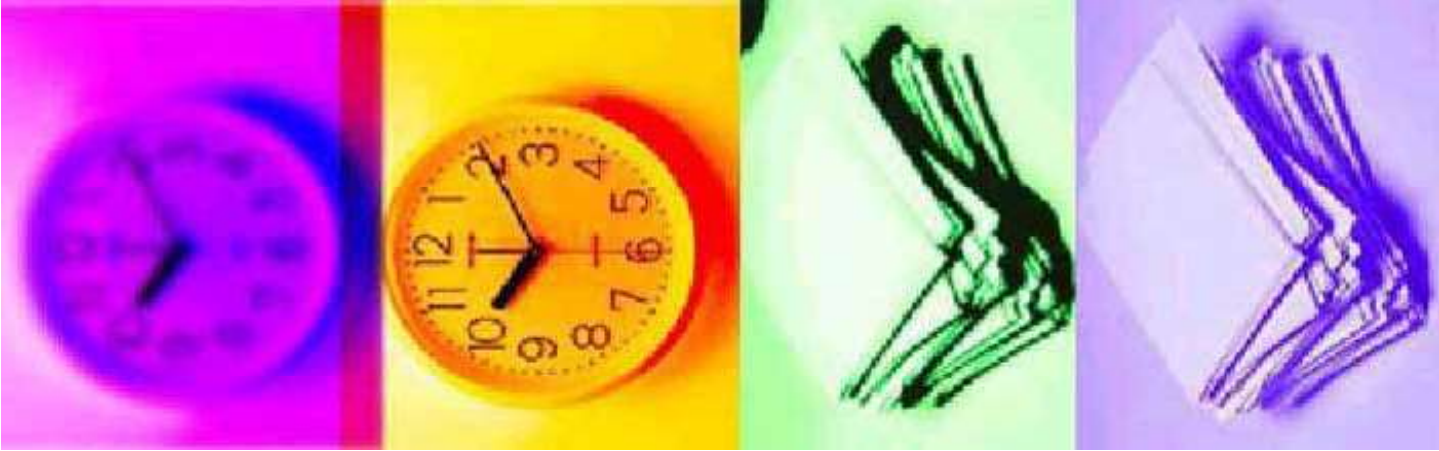
Let us assume Andy wants to sleep



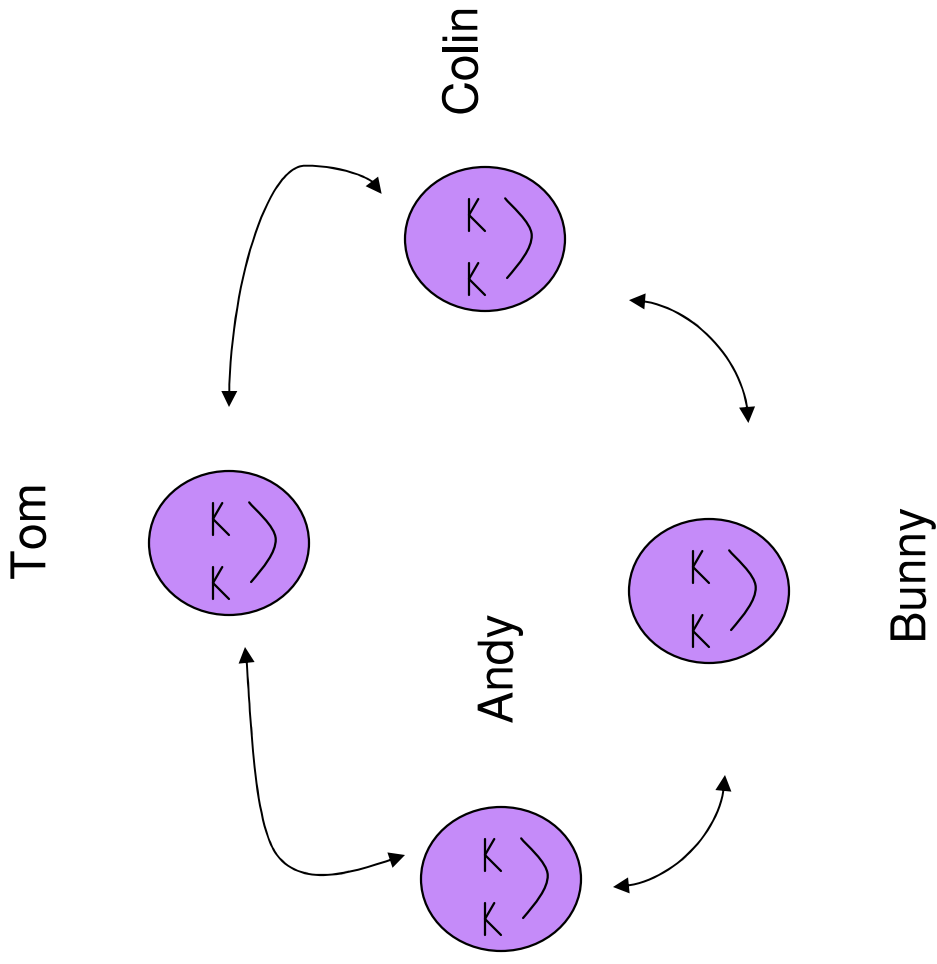
# Sleep Acknowledge

- When All ECU sets sleep indication a sleep acknowledge bit will be set



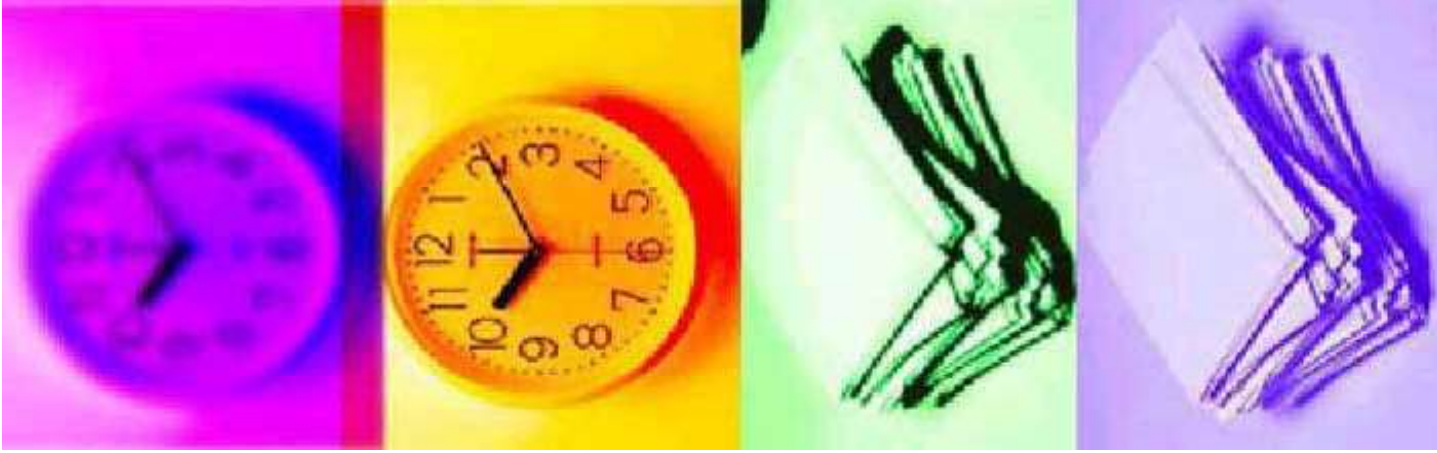


# Sleep Acknowledge state



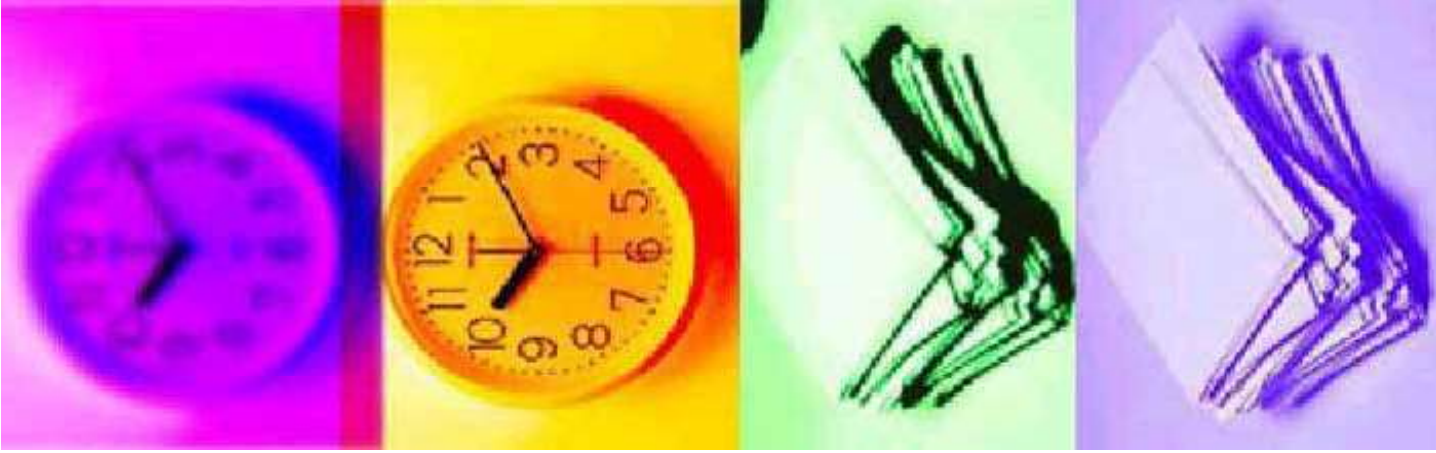
# How to implement NM layer in CANoe

- Network management consists of the following two files
  - OSEKNM01.DLL
  - OSEKNM.INI
- They may be stored with the CANoe configuration, e.g. in a directory called .exec32



# CAN db Attributes

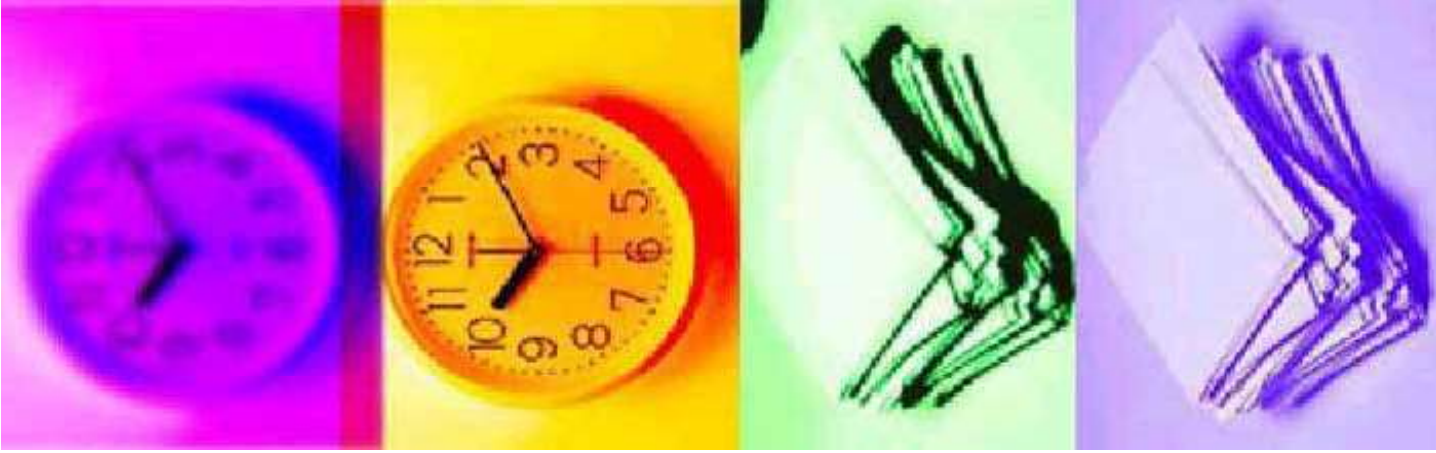
- The DLL obtains its information from the appended database.
- This information is contained in suitable attributes. The following attributes must be included in the database for Osek network management.
- The attribute name must be entered in the same way as formulated below





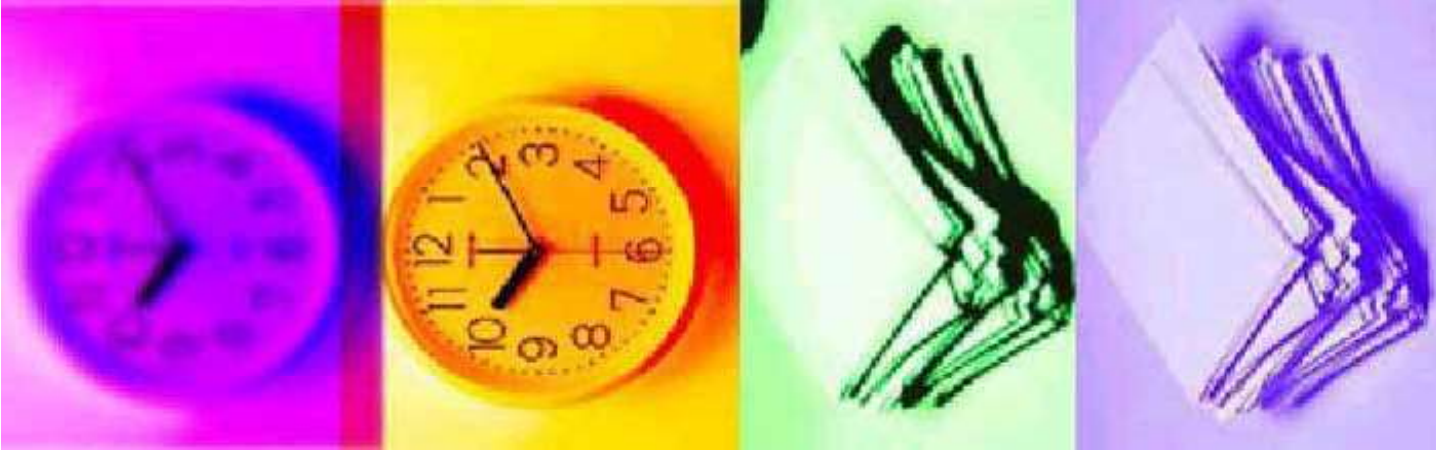
# CAN db Attributes

- The maximum number  $N$  of nodes participating in Network Management can be determined via the attribute **NmMessageCount**.
- When doing this, see to it that the number is always set as  $2^M$ , with  $M$  as a natural number (hence  $N = 16, 32$  or  $64$ ).
- In turn, the base address of this CAN Identifier area must be divisible by the number of nodes with no remainder.
- The base address is also determined in the database and described with the network attribute **NmBaseAddress**.



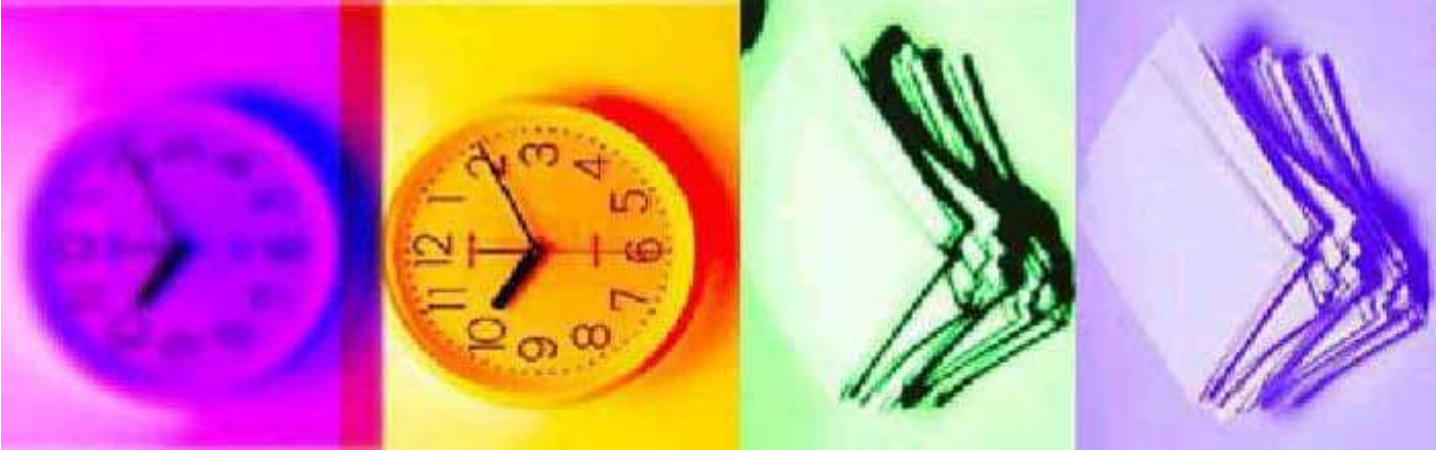
# CAN db Attributes

- **NMIdType** (enumeration)
- This attribute defines if standard or extended IDs are used. Valid values are:
  - 0: standard (11 bit, default)
  - 1: extended (29 bit)



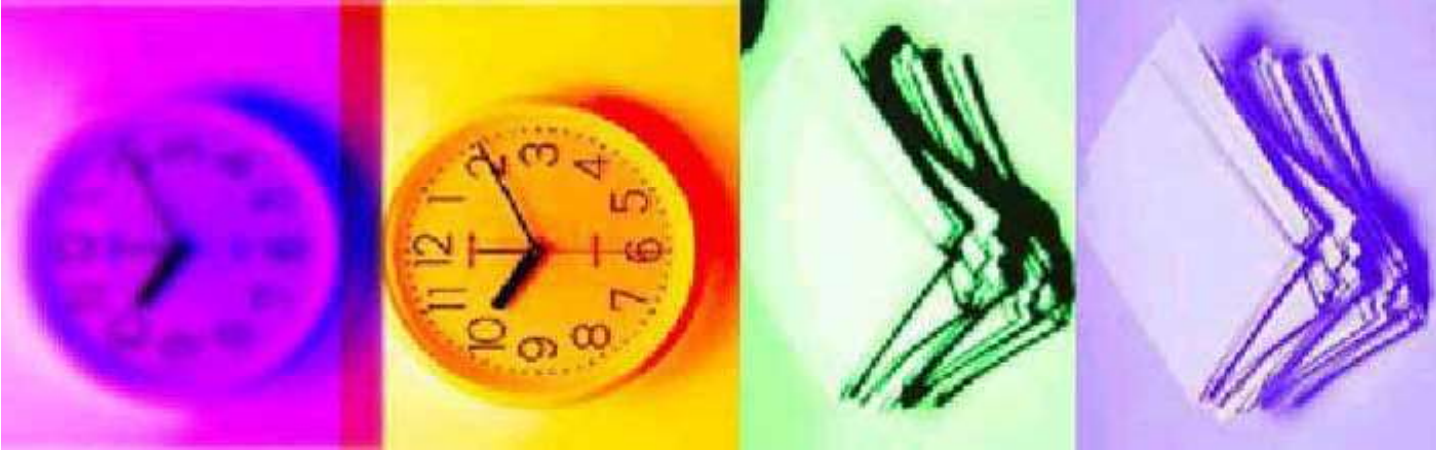
# CAN db Attributes

- **NmCAN** - See network attribute NmCAN. This node attribute allows to set the CAN channel on node level



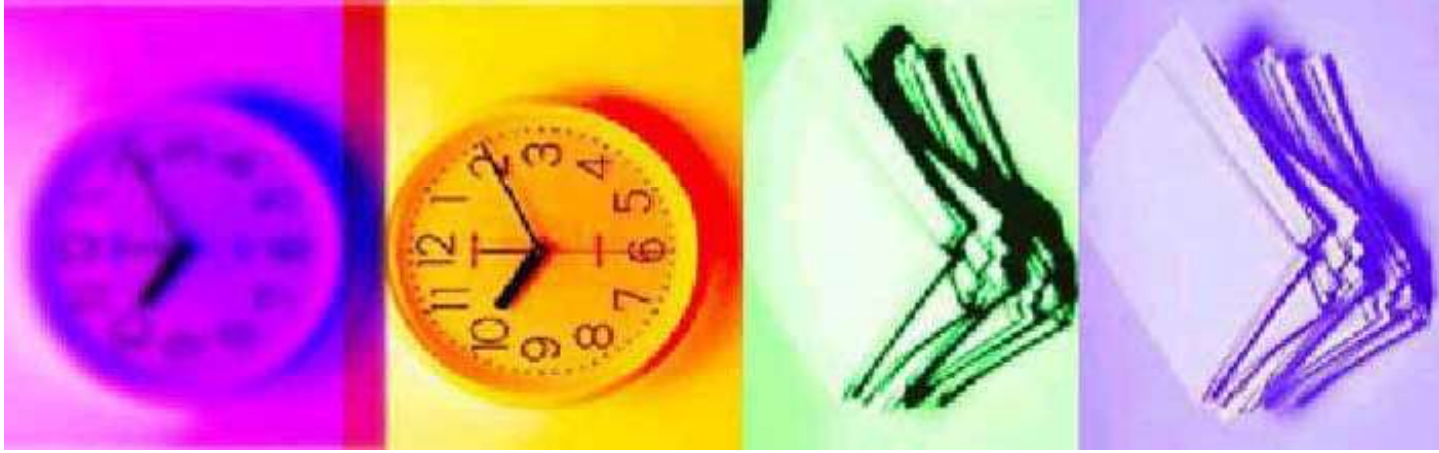
# CAN db Attributes

- **NodeLayerModules** (string)  
*mandatory*
- The attribute  
NodeLayerModules must be  
defined as a string field and  
contains the name of the  
NodeLayer DLL, i.e.  
**OSEKNM01.DLL.**



# Osek Network Management DLL Interface Functions

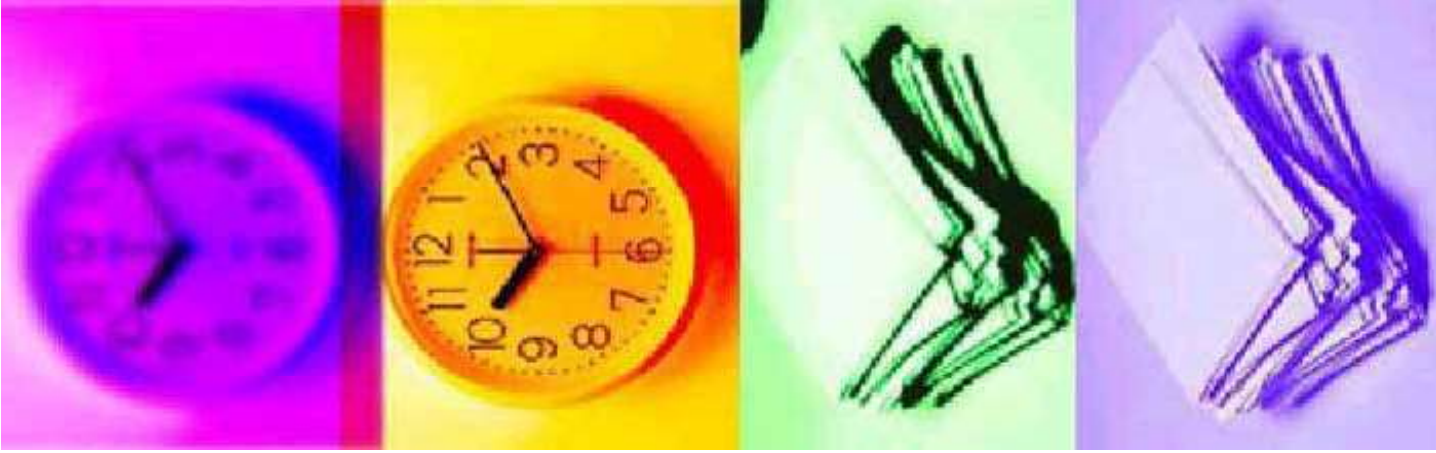
- API functions which the DLL provides and can be called from CAPL
- The CALLBACK functions which must be defined in CAPL and are called by the DLL.





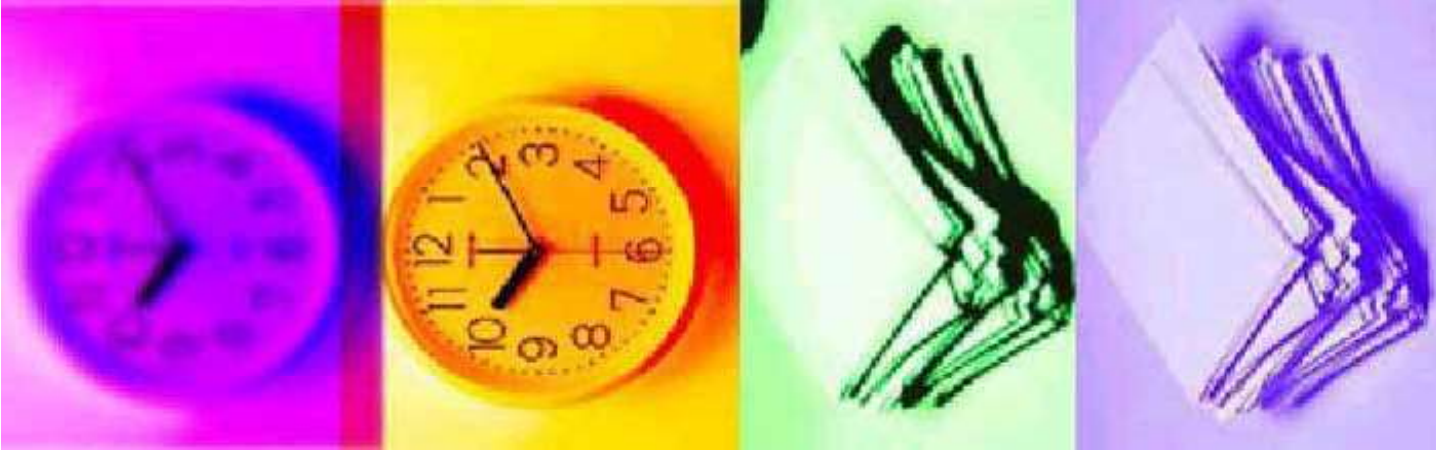
# API Functions Of The DLL

- The Network Management DLL provides 16 different API functions.
- The OSEK names agree with both the OSEK specification and with the name used in the ECUs



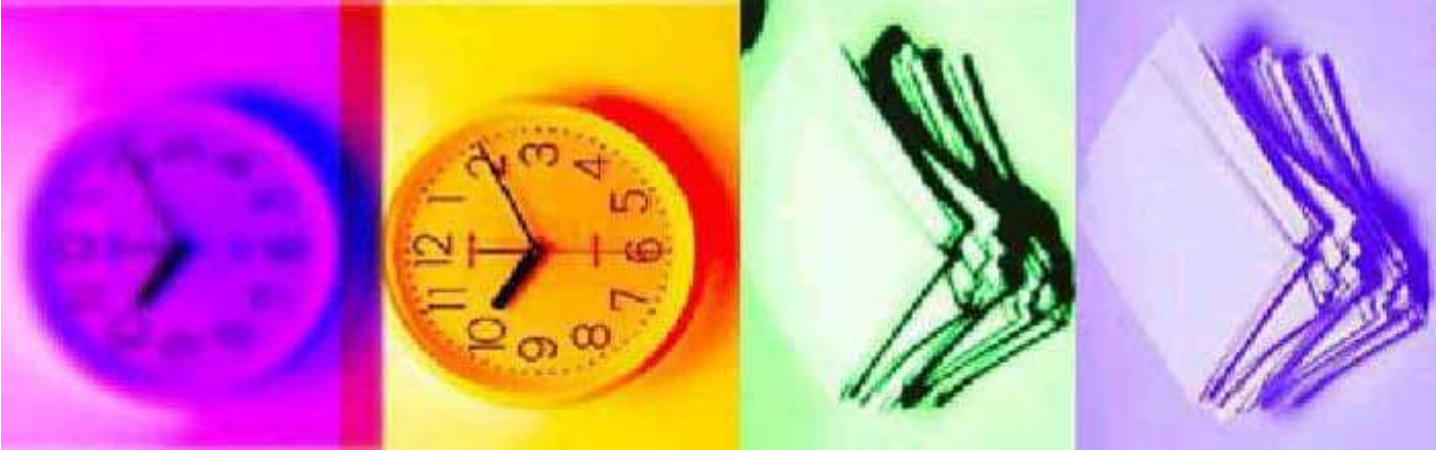
# TalkNM

- void **TalkNM**(void); [old-style name: OsekNMTalk]
- Network Management is switched to active, so that it can participate in the ring.



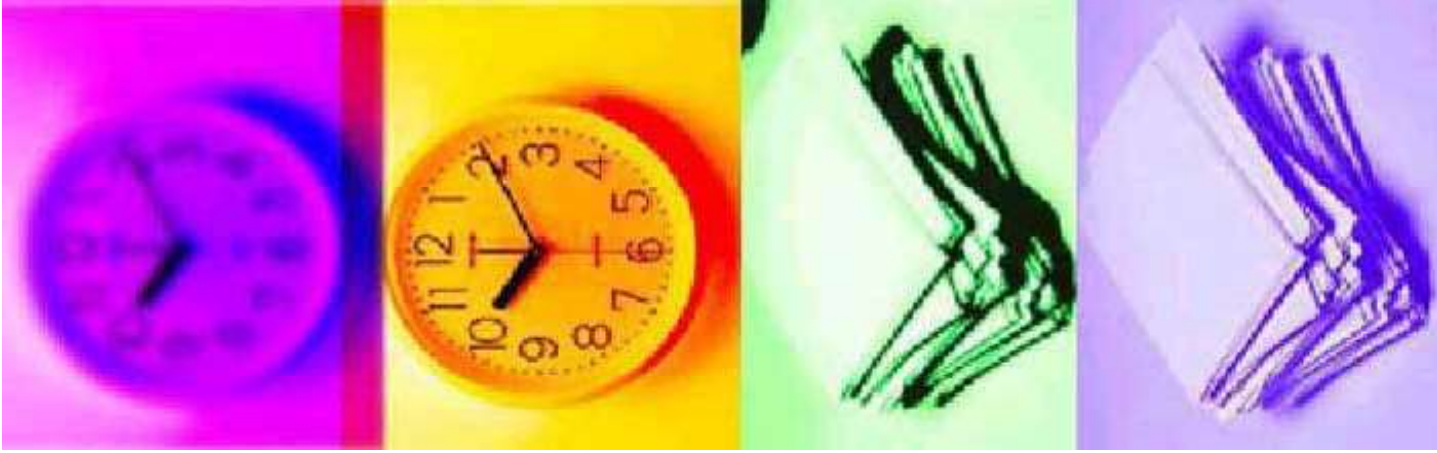
# SilentNM

- void **SilentNM**(void);  
[OsekNMSilent]
- After this call Network Management does not participate in the ring any more
- It does not observe incoming messages



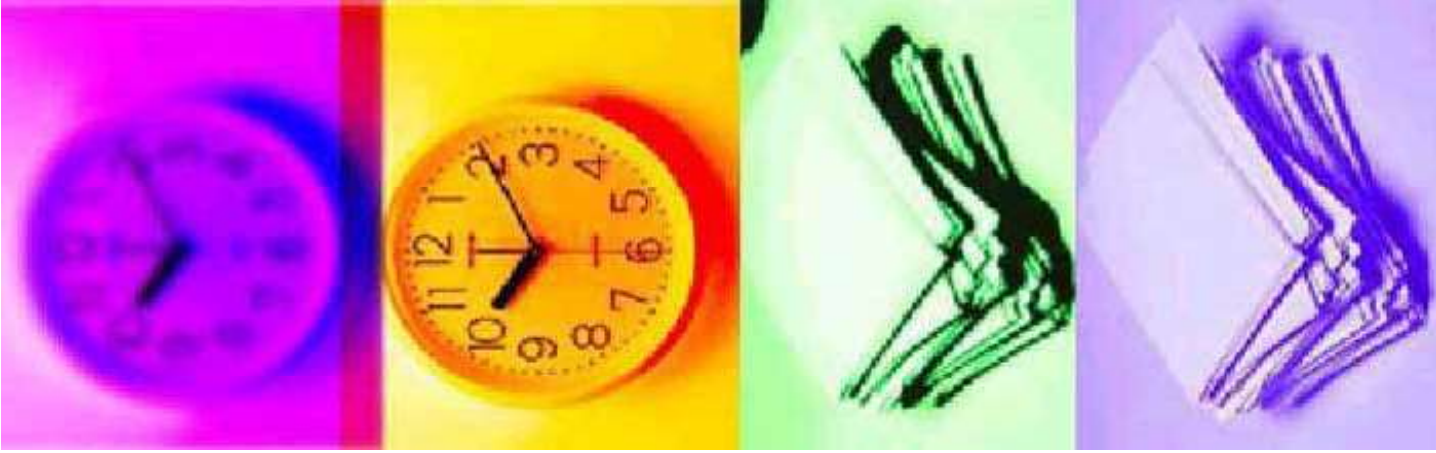
# GotoMode\_BusSleep

- `void GotoMode_BusSleep(void);`  
`[OsekNMBusSleepInd]`
- This function communicates to Network Management that the application is ready to sleep

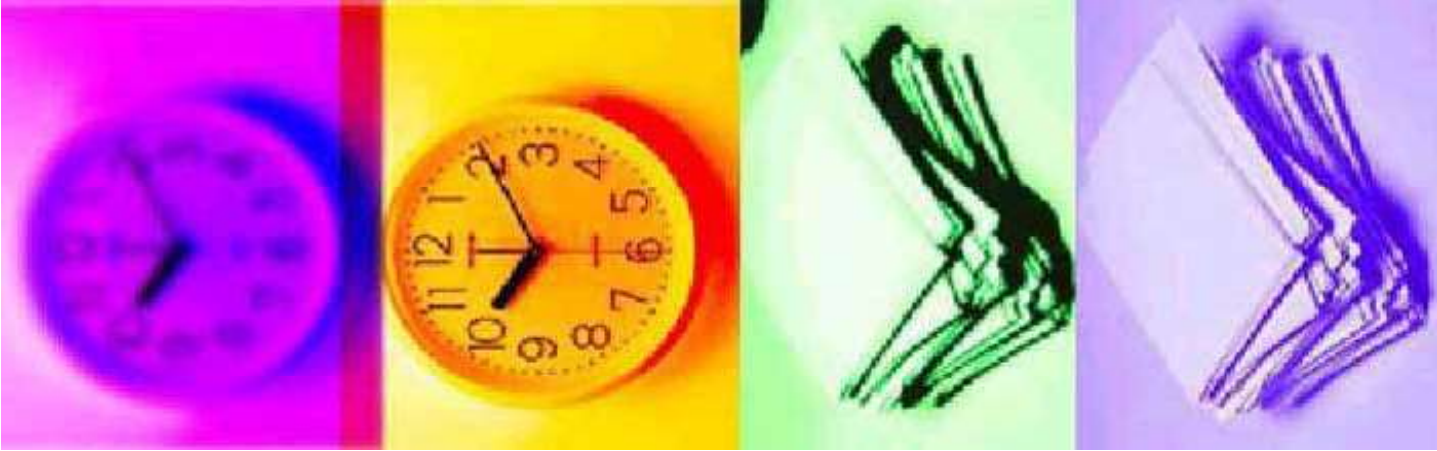


# GotoMode\_Awake

- void **GotoMode\_Awake**(void);  
[OsekNMAwake]
- The application can cancel its readiness to sleep with this function while Network Management is running.
- If the sleep state has already been entered, this function must be called to initialize Network Management.
- This function is then generally called by the function ApplCanWakeUp() (cf. CALLBACK Function 4)







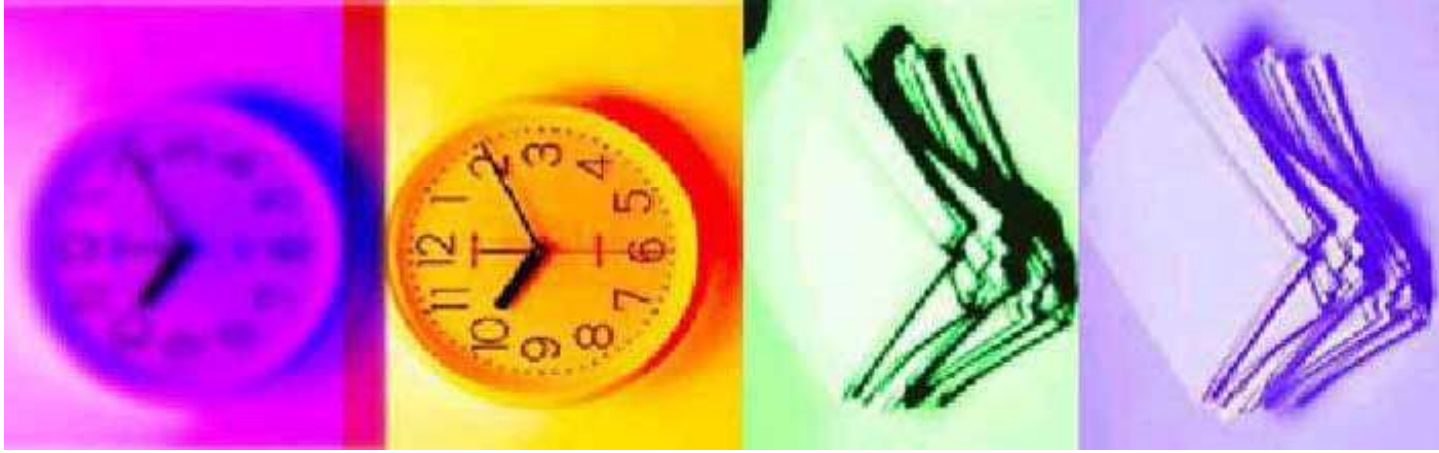
# NMGetStatus

- unsigned long **NMGetStatus**(void);  
[OsekNMGetStatus]
- The internal status of Network Management is retrieved with this function

Bit	Bit2	Bit3	Bit4	Bit5	Bit6	Bit7	Bit8
Config Stable	CAN-Diag Active			NM in BusSleep	NM in LimboHme	NM On	Sleep Ready On

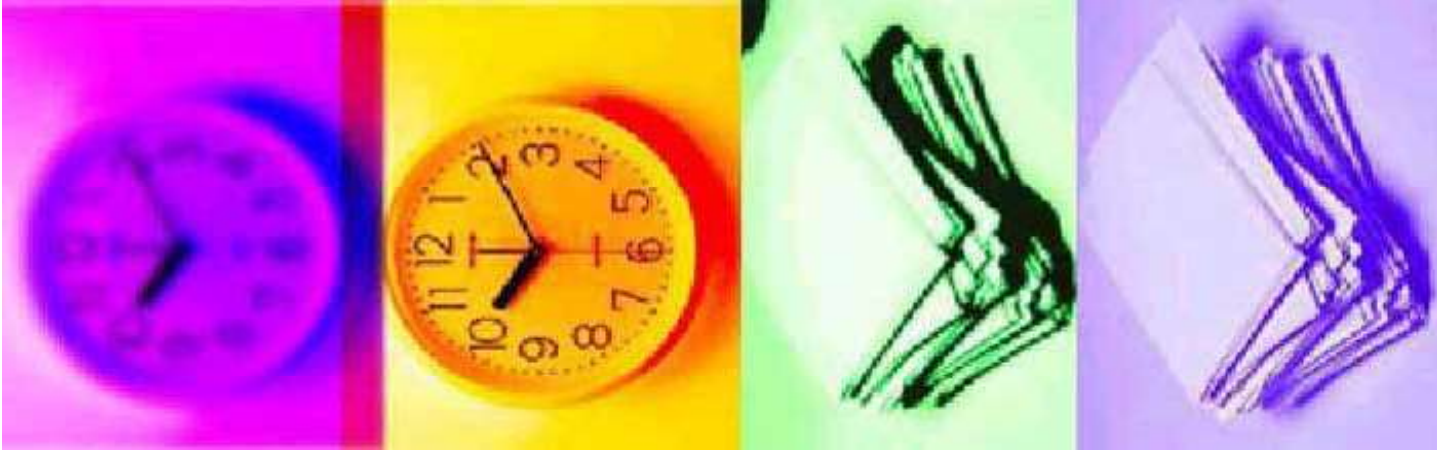
# Canonline()

- This function make the node to available and transmit the messages in CAN bus



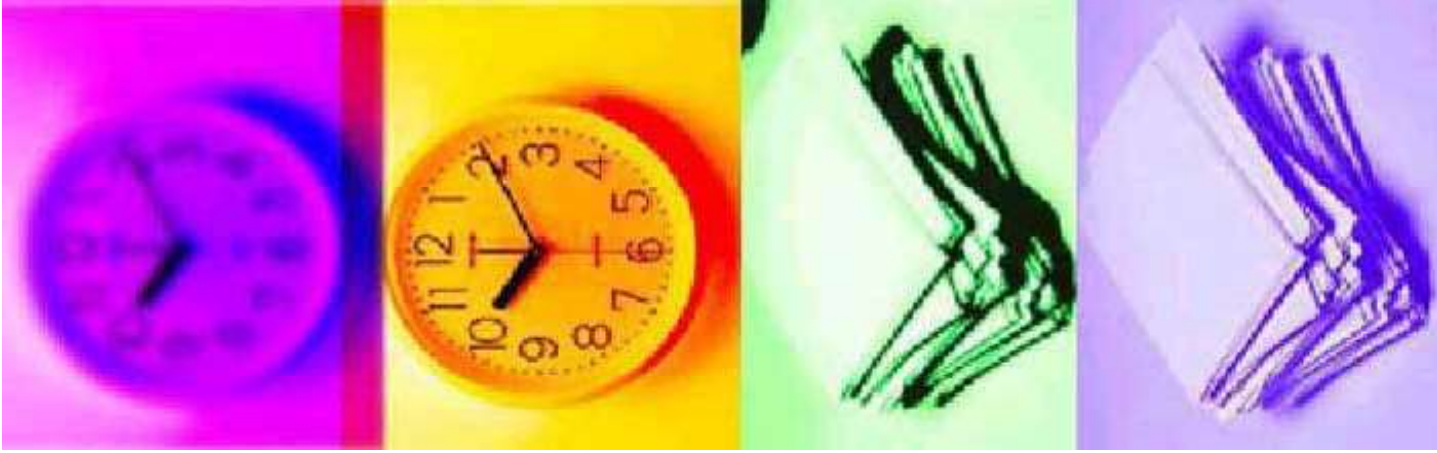
# Canoffline

- This function make the node to unavailable and stop transmitting the messages in CAN bus



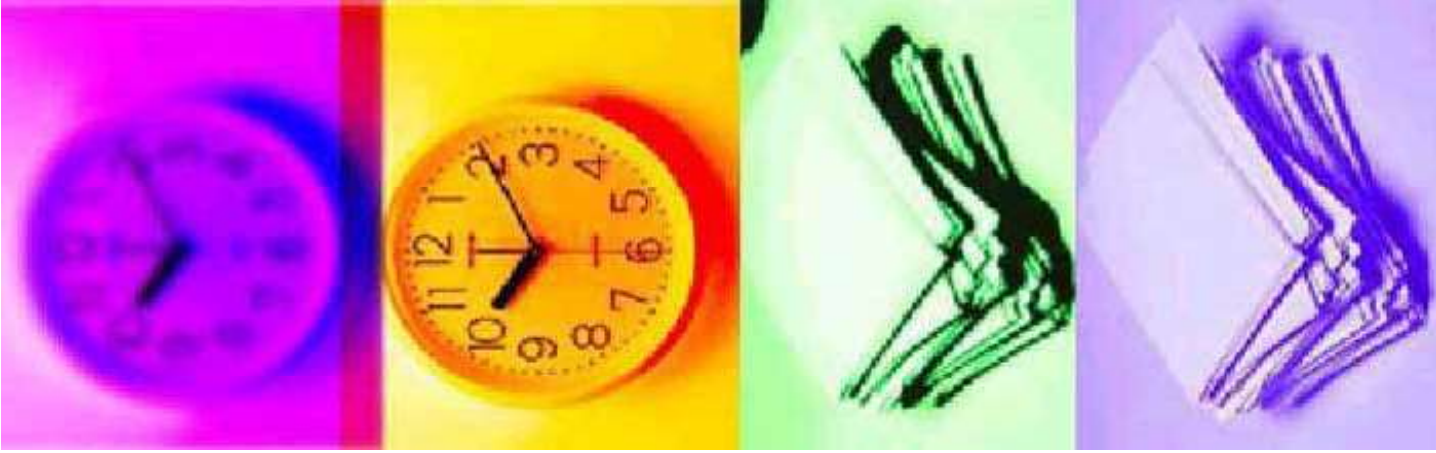
# Functions Provided by CAPL

- **void apBusSleep(void)**
- **void apCanSleep(void)**
- **void apCanNormal(void)**
- **void apCanWakeUp(void)**
- **void apCanOff(void)**
- **void apCanOn(void)**
- **void apInclRingData(void)**
- **void apInclLastAwake(void)**



## `void apBusSleep(void)` (CALLBACK function 1)

- The signal SleepAck was received/sent, and time T\_BUSSLEEP has elapsed. From standby mode the CAN transceiver can be placed in sleepmode here.
- In the transition to sleep mode this function is called directly after the function call `apCanSleep()`.





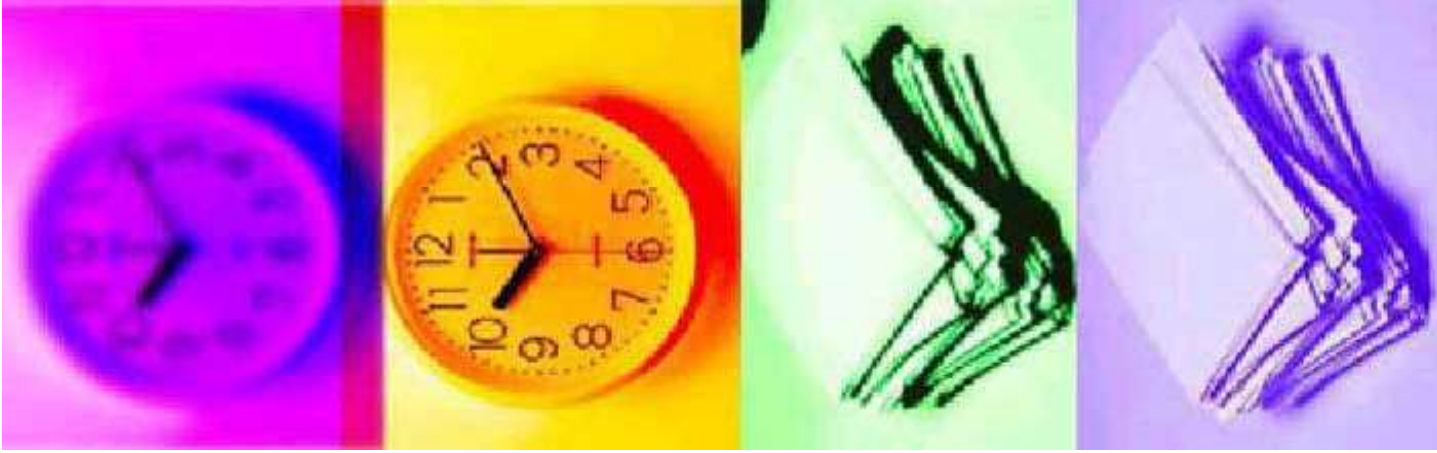
**void apCanSleep(void)**  
**(CALLBACK function 2)**

- The signal SleepAck was received/sent, and time T\_BUSSLEEP has elapsed. From active mode the CAN transceiver can be placed in standbymode here.
- In the transition to sleep mode this function is called directly before the the function call apCanBusSleep().



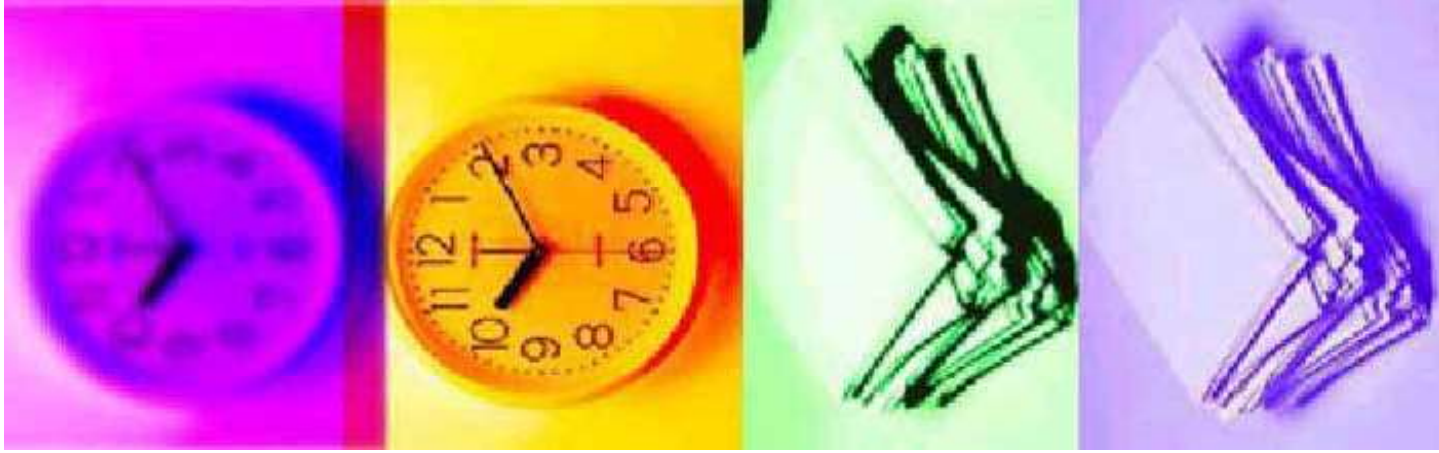
**void apCanNormal(void)**  
(CALLBACK function 3)

- This is called to place the CAN transceiver in the active state. This function is called if the function OsekNMAwake() was called and there was a bus quiet state.



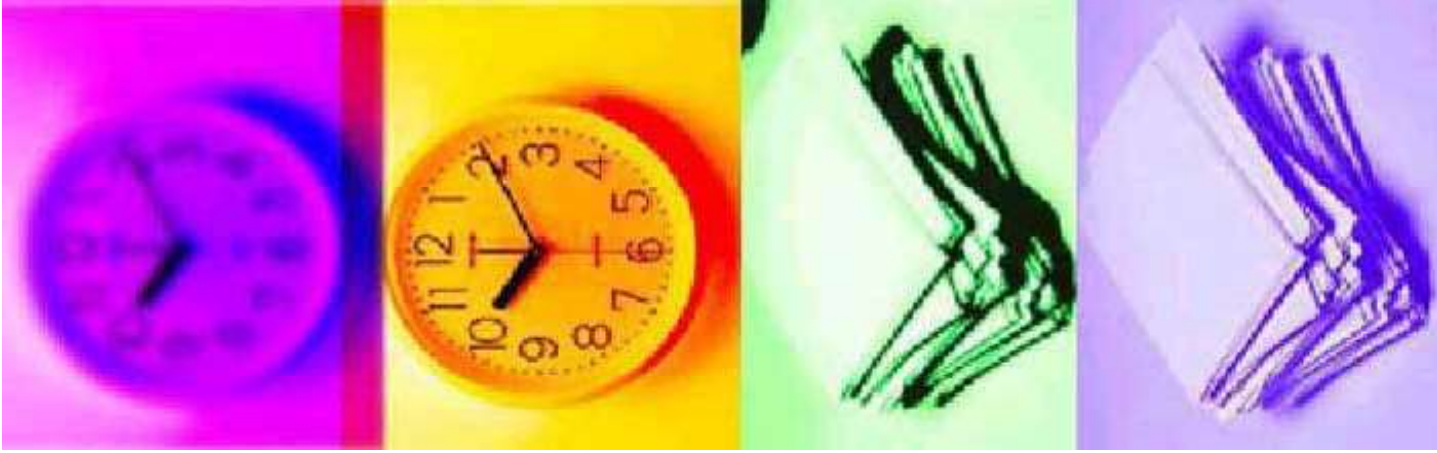
## void apCanWakeUp(void) (CALLBACK function 4)

- This function is called if the network management DLL has received a message while in the sleep state.
- In this case the function *OsekNMAwake()* must be called to activate network management! If the network management is to remain sleep-ready, the function *OsekNMBusSleepInd()* must be called **after** the Awake call



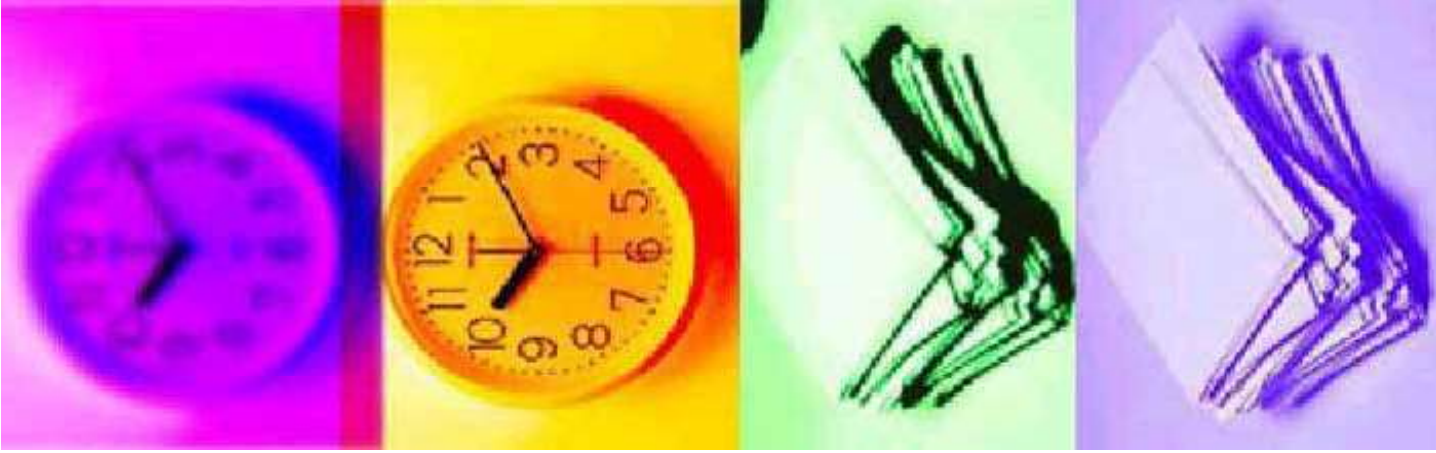
## `void apCanOff(void)` (CALLBACK Function 5)

- This function is called during the transition to sleep mode and instructs the CAPL node not to send any more messages.



**void apCanOn(void)**

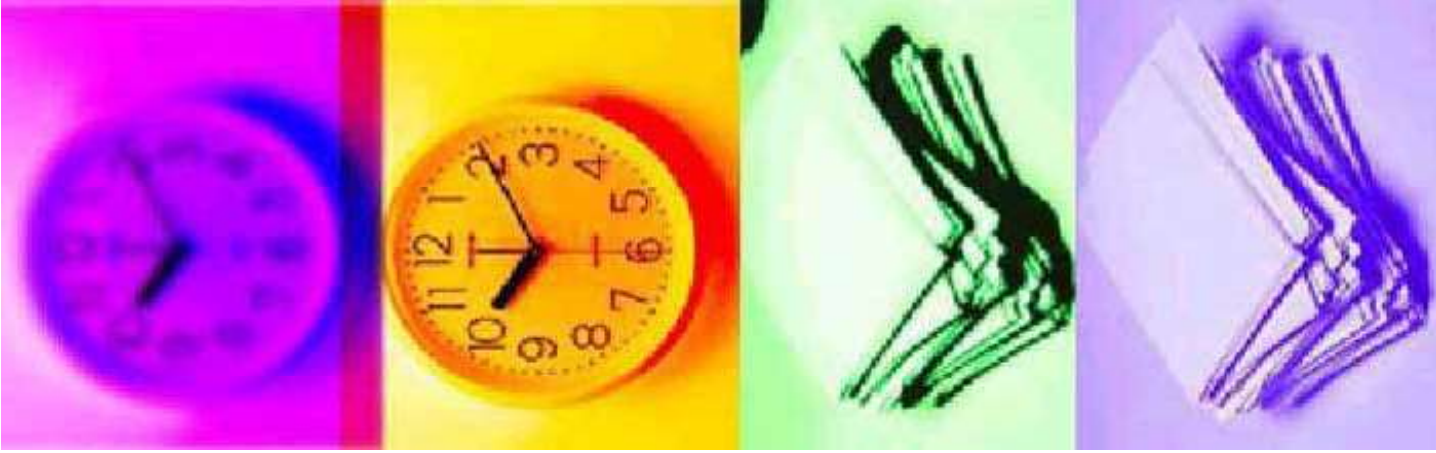
- Network management is reactivated. CAN output is enabled again.





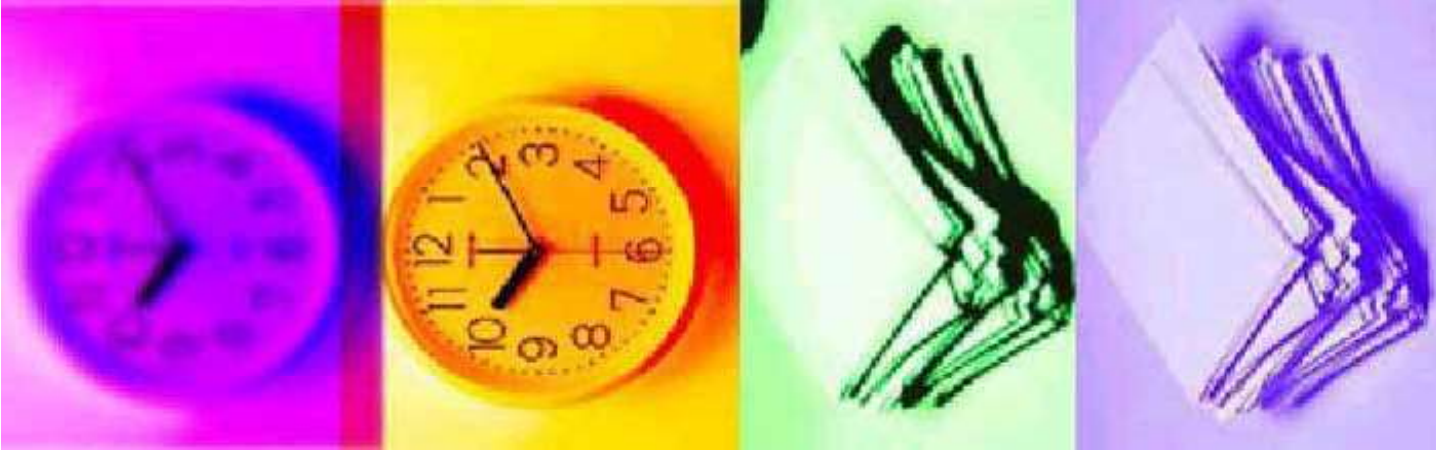
## `void apInRingData(void)` (CALLBACK-Function 7)

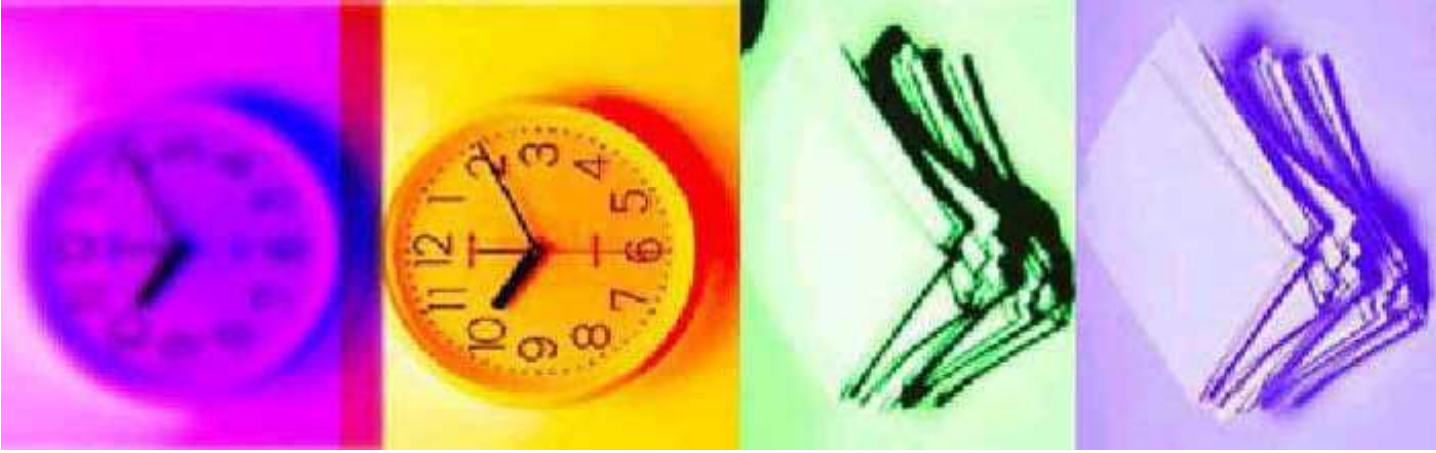
- This function will be called if the node receives the token and the ring is stable.
- The application can get the latest data received by this NM-message.



## `void apInLastAwake(void)`

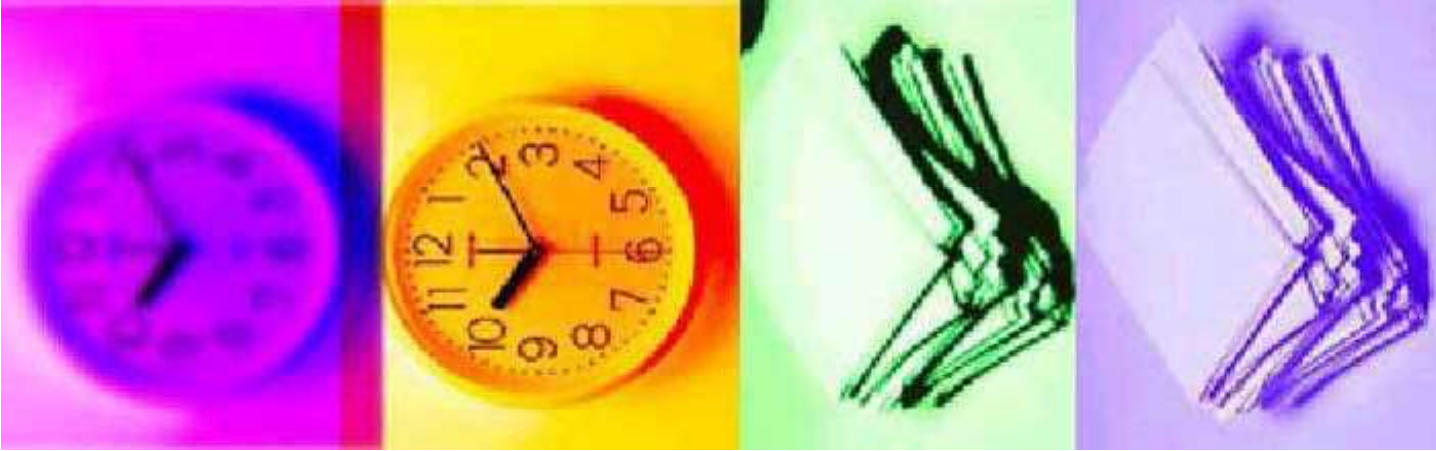
- This function is called when the node is the last active node on the bus that does not signal sleep readiness. Therefore the bus would go into sleep mode
- if this node also signaled sleep readiness. The condition is checked on the reception of every NM message where the sleep readiness bit is set, therefore this function can be called repeatedly.





# OSEKNM.INI

- [LINEMODE]
- Chips = 0; ; 0 - both, 1 - chip 1 only, 2 - chip 2 only
- [WAKEUP]
- WakeUpOnAllMsg = 1
- [Debug]
- ;AcknowledgeRcv = 0
- ;DebugId = 0x222;
- [MESSAGE]
- DlcLen=8 ; Min. 2 max. 8
- RingDataStartIndex=2 ; Min. is 2
- RingDataLength=6 ; max. is 6

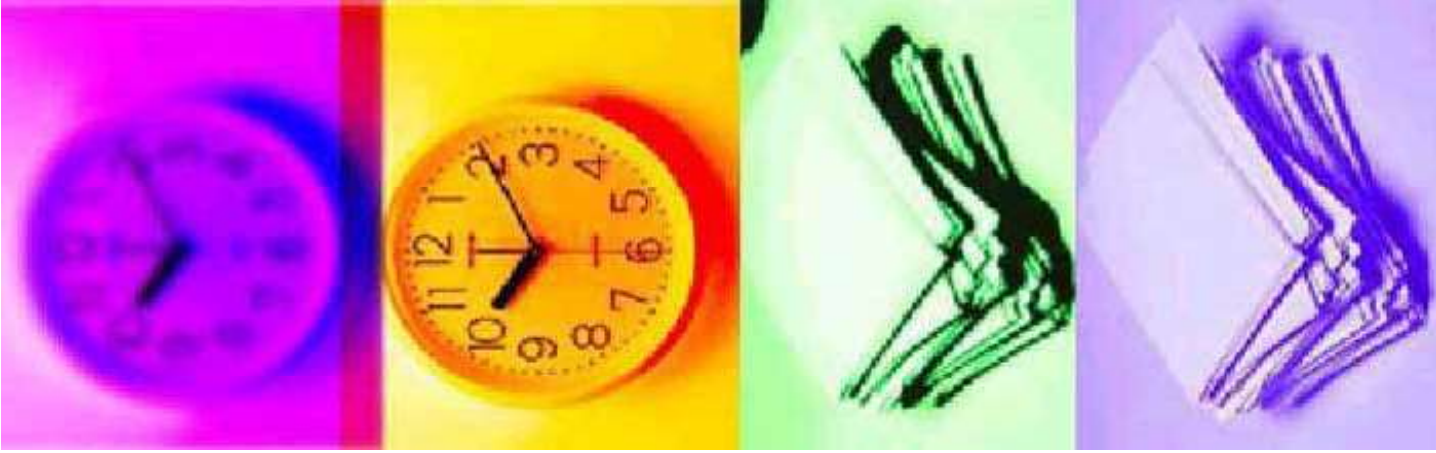


# OSEKNM.INI

- RingDataFill=0
- ; Specify the value to initialize the ring data with
- ;RingDataInit=0
- [WRITE]
- VERBOSE = 1 ; verbose level: 0 - no messages, 1 - some messages, 2 - more messages,
- 3 - even more messages
- [NAMES]
- CALLBACKFunc1 = apBusSleep
- CALLBACKFunc2 = apCanSleep
- CALLBACKFunc3 = apCanNormal
- CALLBACKFunc4 = apCanWakeUp
- CALLBACKFunc5 = apCanOff
- CALLBACKFunc6 = apCanOn
- CALLBACKFunc7 = apIndRingData
- [TIMER]
- T\_RING\_TYP = 100 ; Typical time interval between two ring messages
- T\_RING\_MAX = 250 ; max. time interval between two ring
- T\_NOTLAUF = 1000 ; time interval between two ring messages with NMLimpHome
- ; identification
- T\_BUSSLEEP = 1500 ; Time the NM waits before transmission into the state
- ; NMBusSleep

# Structure of Network Management Messages

- Data byte 1: Receiver address For the messages ALIVE and LIMPHOME the node's own station address is found here. This station's address is also entered here for the first RING message, provided that no other NM message could have been received between the ALIVE message and this RING message. Otherwise the address of the logical successor within the ring will be located here.





# Structure of Network Management Messages

- Data byte 2: Identifies the type of NM message and contains sleep information
  - Bit 1: ALIVE message
  - Bit 2: RING message
  - Bit 3: LIMPHOME message
  - Bit 4: Reserved
  - Bit 5: Sleep readiness (SleepIndicator)
  - Bit 6: Sleep acknowledgment (SleepAcknowledge)
  - Bit 7: Reserved
  - Bit 8: Reserved

