



**NATIONAL INSTITUTE OF TECHNOLOGY  
ARUNACHAL PRADESH, JOTE, Pin-791113**

(Established by Ministry of Education, Govt. of India)

**Mid-Semester Examination (Jan-Jun) 2025**

**ME 321B (Automobile Engineering)**

Time: 2 Hours

Max. Marks: 30

**Instructions:**

1. Use question numbers as given in this question paper.
2. Marks are indicated against each question. Answer to all questions.

|   | M | CO |
|---|---|----|
| Q.1 (a) The cooling system of automobile engine most simple when the engine is placed at the_____.                          | 5 | 1  |
| (b) Which of the following is a classification of automobiles based on Load?  |   |    |
| i) Heavy transport vehicle (HTV)  |   |    |
| ii) Sedan Hatchback car   |   |    |
| iii) Four-wheeler vehicle   |   |    |
| iv) Front-wheel drive   |   |    |
| (c) What carries the driving wheels of a vehicle?   |   |    |
| i) crankshaft   |   |    |
| ii) flywheel  |   |    |
| iii) clutch   |   |    |
| iv) axles   |   |    |
| (d) Which of the following is not a part of the chassis?  |   |    |
| i) wheels   |   |    |
| ii) differential  |   |    |
| iii) gear box   |   |    |
| iv) seats   |   |    |
| (e) The space provided beneath the rear hood for the purpose of keeping goods, belongings and spare wheel is known as _____ |   |    |



|    |    |  |      |     |
|----|----|--|------|-----|
|    | c) | Derive the homogenous transformation matrix (T) for the following operation.<br>Rotation of $\alpha$ about OX axis<br>Translation of 'a' along OX axis<br>Translation of 'd' along OZ axis<br>Rotation of $\theta$ about OZ axis                                     | [3]  | 2   |
| 3. |    | Explain the process of determining the Denavit-Hartenberg (DH) parameters for a SCARA robot. Also, discuss how these parameters are used to formulate the forward kinematics of the SCARA robot, and derive the transformation matrix for the end-effector position. | [10] | 2,3 |

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