

Week 4: Fourier Approximations

February 11, 2019

The Assignment

We will fit two functions, $\exp(x)$ and $\cos(\cos(x))$ over the interval $[0, 2\pi)$ using the fourier series

$$a_0 + \sum_{n=1}^{\infty} \{a_n \cos(nx) + b_n \sin(nx)\} \quad (1)$$

As you know from earlier courses, the coefficients a_n and b_n are given by

$$\begin{aligned} a_0 &= \frac{1}{2\pi} \int_0^{2\pi} f(x) dx \\ a_n &= \frac{1}{\pi} \int_0^{2\pi} f(x) \cos(nx) dx \\ b_n &= \frac{1}{\pi} \int_0^{2\pi} f(x) \sin(nx) dx \end{aligned}$$

1. Define Python functions for the two functions above, that take a vector (or scalar) input, and return a vector (or scalar) value. Plot the functions over the interval $[-2\pi, 4\pi)$ in Figure 1 and 2 respectively. Determine whether the functions are periodic. What function do you expect to be generated by the fourier series? Compute and plot those functions as well in the respective figures.

Note: Since $\exp(x)$ grows rapidly, use semilogy for that plot.

Note: Add grids and labels to figures.

2. Obtain the first 51 coefficients for the two functions above. **Note:** The built in integrator in Python integrates a scalar function from a to b . So you will have to compute the coefficients in a for loop. Also note that you will have to create two new functions to be integrated, namely $u(x, k) = f(x) \cos(kx)$ and $v(x, k) = f(x) \sin(kx)$. To integrate these, use the option in *quad* to pass extra arguments to the function being integrated:

```
rtnval=quad(u, 0, 2*pi, args=(k))
```

What this does is it accepts a function $u(x, \dots)$; the integration is over x , but the k values is passed to the function by *quad* as the second argument. So you will have to define the two functions as having k as their second (not first) argument.

3. For each of the two functions, make two different plots using “semilogy” and “loglog” and plot the magnitude of the coefficients vs n . The values should be plotted with red circles. Note that the answer should be a vector of the form

$$\begin{pmatrix} a_0 \\ a_1 \\ b_1 \\ \dots \\ a_{25} \\ b_{25} \end{pmatrix}$$

Note: Plot the coefficients for $f_1(x) = \exp(x)$ in Figures 3 and 4, and the coefficients for $f_2(x) = \cos(\cos x)$ in Figures 5 and 6.

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- If you did Q1 correctly, the b_n coefficients in the second case should be nearly zero. **Why does this happen?**
 - In the first case, the coefficients do not decay as quickly as the coefficients for the second case. **Why not?**
 - Why does loglog plot** in Figure 4 look linear, whereas the *semilog* plot in Figure 5 looks linear?

4. We instead do a “Least Squares approach” to the problem. Define a vector x going from 0 to 2π in 400 steps (remember *linspace*). Evaluate the function $f(x)$ at those x values and call it b . Now this function is to be approximated by Eq. (1). So for each x_i we want

$$a_0 + \sum_{n=1}^{25} a_n \cos nx_i + \sum_{n=1}^{25} b_n \sin nx_i \approx f(x_i) \quad (2)$$

Turn this into a matrix problem:

$$\begin{pmatrix} 1 & \cos x_1 & \sin x_1 & \dots & \cos 25x_1 & \sin 25x_1 \\ 1 & \cos x_2 & \sin x_2 & \dots & \cos 25x_2 & \sin 25x_2 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 1 & \cos x_{400} & \sin x_{400} & \dots & \cos 25x_{400} & \sin 25x_{400} \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ b_1 \\ \dots \\ a_{25} \\ b_{25} \end{pmatrix} = \begin{pmatrix} f(x_1) \\ f(x_2) \\ \dots \\ f(x_{400}) \end{pmatrix}$$

Create the matrix on the left side and call it A . We want to solve

$$Ac = b$$

where c are the fourier coefficients.

Note: The matrix can be constructed using `zeros((400,51))` and then filling in the columns in a for loop. Do not use a double for loop. Here is the way to build up x , b and A without using nested loop:

```
x=linspace(0,2*pi,401)
x=x[:-1] # drop last term to have a proper periodic integral
b=f(x)   # f has been written to take a vector
A=zeros((400,51)) # allocate space for A
A[:,0]=1      # col 1 is all ones
for k in range(1,26):
    A[:,2*k-1]=cos(k*x) # cos(kx) column
    A[:,2*k]=sin(k*x)   # sin(kx) column
#endfor
c1=lstsq(A,b)[0] # the '[0]' is to pull out the
# best fit vector. lstsq returns a list.
```

5. Use *lstsq* to solve this problem. You execute

```
c=lstsq(A,b)[0]
```

What this does is to find the “best fit” numbers that will satisfy Eq. (2) at exactly the points we have evaluated $f(x)$. Obtain the coefficients for both the given functions. Plot them with green circles in the corresponding plots.

6. Compare the answers got by least squares and by the direct integration. **Do they agree? Should they?** How much deviation is there (find the absolute difference between the two sets of coefficients and find the largest deviation. **How will you do this using vectors?**)

7. Compute Ac from the estimated values of c . These should be the function values at x_i . Plot them (with green circles) in Figures 1 and 2 respectively for the two functions. Why is there so much deviation in Figure 1 but nearly perfect agreement in Figure 2?
8. Write a report on this assignment in latex and submit the same along with your code.