Nithin Govindarajan

Phone: +31 6 57156899

email: nithin.govindarajan@kuleuven.be

Location: Leuven, Belgium

Areas of expertise

Numerical linear algebra, tensor methods, dynamical systems, systems theory, signal processing.

Education

Oct. 2014 - Dec. 2018 PHD in Mechanical Engineerings, University of California in Santa Barbara

Dissertation title: "Periodic approximations and spectral analysis of the Koopman

operator: theory and applications".

Advisors: I. Mezić, S. Chandrasekaran.

Sep. 2009 - Oct. 2012 MSC in Aerospace Engineering (with honors), Technische Universiteit Delft

Master thesis: "An Optimal Control Approach for Estimating Aircraft Command

Margins".

Advisors: Q.P. Chu, C.C. de Visser.

Jul. 2009 BSc in Aerospace Engineering (with honors), Technische Universiteit Delft

Work experience

Aug. 2019 - present Postdoctoral researcher, KU Leuven, Belgium

Feb. 2019 - July 2019 Lecturer Mathematics, University of Amsterdam (UvA), The Netherlands

Nov. 2012 - May 2013 Junior R&D engineer, National Aerospace Laboratory, Amsterdam, The Netherlands Sep. 2011 - May 2012 Intern, Mission Critical Technologies Inc. (on site at NASA Ames), Moffet Field, CA

Fellowships, honors & awards

Apr. 2016	CCDC fellowship, Center for Control, Dynamics and Computation, Santa Barbara, CA
Apr. 2014	Department Merit Fellowship (UCSB Mech. Eng), Santa Barbara, CA
Mar. 2013	Fulbright scholarship (awarded), Fulbright office, Amsterdam, The Netherlands
May 2011	Huvgens Scholarship Programme, Nuffic, The Hague, The Netherlands

Teaching

Lead instructor & course organizor

Semester 1 2019/2020 Numerical mathematics, Amsterdam University College

Co-instructor

March 2022 Fast algorithms for dense structured matrices, KU Leuven

Semester 2 2021/2022 Numerieke modellering & benadering, KU Leuven Semester 2 2019/2020 Numerieke modellering & benadering, KU Leuven

Teaching assistant

Semester 1 2021/2022 Numerieke wiskunde, KU Leuven Semester 1 2020/2021 Numerieke wiskunde, KU Leuven Semester 1 2019/2020 Numerieke wiskunde, KU Leuven

Spring 2018 Control theory, UCSB

Winter 2017 Electrical circuits Lab, UCSB

Fall 2017 Intro to programming in Matlab, UCSB

Summer 2017 Dynamics, UCSB

Summer 2017 Physics Lab: intro to classical mechanics for non-engineers, UCSB

Spring 2017 Dynamics, UCSB
Spring 2015 Dynamics, UCSB
Winter 2015 Vibrations, UCSB
Fall 2014 Statics, UCSB

2022

2021

2019

2015

Software skills

Matlab, Python, Mathematica, C++, Julia, Latex, Git.

Publications

Journal Publications

Govindarajan, N., Vervliet, N., & De Lathauwer, L. (2022). Regression and classification

with spline-based separable expansions. Frontiers in big Data, 5, 688496.

Govindarajan, N., Epperly, E. N., & Lathauwer, L. D. (2022). $(L_r, L_r, 1)$ -Decompositions, Sparse Component Analysis, and the Blind Separation of Sums of Exponentials. SIAM

Journal on Matrix Analysis and Applications, 43(2), 912-938.

Epperly, E. N., Govindarajan, N., & Chandrasekaran, S. (2021). Minimal rank completions

for overlapping blocks. Linear Algebra and its Applications, 627, 185-198.

Govindarajan, N., Mohr, R., Chandrasekaran, S., & Mezic, I. (2021). On the approximation of Koopman spectra of measure-preserving flows. SIAM Journal on Applied Dynamical

Systems, 20(1), 232-261.

Govindarajan, N., Mohr, R., Chandrasekaran, S., & Mezic, I. (2019). On the approxima-

tion of Koopman spectra for measure preserving transformations. SIAM Journal on Applied

Dynamical Systems, 18(3), 1454-1497.

Govindarajan, N., De Visser, C. C., Van Kampen, E., Krishnakumar, K., Barlow, J., &

Stepanyan, V. (2015). Optimal control framework for estimating autopilot safety margins.

Journal of Guidance, Control, and Dynamics, 38(7), 1197-1207.

Govindarajan, N., de Visser, C. C., & Krishnakumar, K. (2014). A sparse collocation

method for solving time-dependent HJB equations using multivariate B-splines. Automat-

ica, 50(9), 2234-2244.

Conference proceedings

2023

2018

2016

2023

2019

2019

2019

2019

2018

2017

Widdershoven, R., Govindarajan, N., De Lathauwer, L. (2023, September). Overdetermined systems of polynomial equations: tensor-based solution and application. Proceedings of EUSIPCO 2023, Helsinki, Finland.

Chandrasekaran, S., Govindarajan, N., & Rajagopal, A. (2018, July). Fast Algorithms for Displacement and Low-Rank Structured Matrices. In Proceedings of the 2018 ACM International Symposium on Symbolic and Algebraic Computation (pp. 17-22).

Govindarajan, N., Arbabi, H., Van Blargian, L., Matchen, T., & Tegling, E. (2016, December). An operator-theoretic viewpoint to non-smooth dynamical systems: Koopman analysis of a hybrid pendulum. In 2016 IEEE 55th Conference on Decision and Control (CDC) (pp. 6477-6484). IEEE.

Preprints & Tech reports

Govindarajan, N., Widdershoven, R., Chandrasekaran, S. (2023). A fast algorithm for computing Macaulay nullspaces of bivariate polynomial systems. ESAT Tech Report 23-16. Chandrasekaran, S., Epperly, E. N., Govindarajan, N. (2019). Graph-induced rank structures and their representations. arXiv preprint arXiv:1911.05858 [math.NA].

Selected talks

"Periodic approximations and spectral analysis of the Koopman operator - theory and applications" Invited talk KU Leuven

"Fast algorithms for structured matrices with applications to Koopman operator theory and elliptic PDEs" Invited talk RWTH Aachen

"Towards an Algebraic Generalization of SSS to 2D Operators", SIAM CSE 19, Spokane USA "The exact fine structure of the inverse of discrete elliptic operators" SIAM conference on applied linear algebra '18 in Hong Kong

"A toolbox for computing spectral properties of dynamical systems" SIAM conference on applications of Dynamical Systems '17 in Snowbird $\,$

Last updated: August 24, 2023