Part i Machine Learning

Machine Learning

BOLTZMAN MACHINES

Network of symetrically coupled stocastic binary units. Energy of state $\{v, h\}$ is defined as:

$$E(v, h; \theta) = -\frac{1}{2}v^{T}Lv - \frac{1}{2}h^{T}Jh - v^{T}Wh$$
 (1)

where $\theta = \{W, L, J\}$ represents model parameters. diagonal terms of L and J are set to 0.

⁰bias terms have been omitted for clarity

Probability that model assigns a visible vector v is

 $p(v;\theta) = \frac{p^*(v;\theta)}{Z(\theta)}$

 $= \frac{1}{Z(\theta)} \sum_{n} \exp(-E(v, h; \theta))$ $Z(\theta) = \sum_{v} \sum_{h} \exp(-E(v, h; \theta))$

(2)

(3)

(4)

The conditional distribution over hidden and visible units are given by

The conditional distribution over model and visible units are given by
$$\begin{pmatrix}
D & P &
\end{pmatrix}$$

 $p(h_j = 1 | v, h_{-j}) = \sigma \left(\sum_{i=1}^{D} W_{ij} v_i + \sum_{m=1 \setminus j}^{P} J_{jm} h_j \right)$

 $p(v_i = 1|h, v_{-i}) = \sigma \left(\sum_{j=1}^{P} W_{ij} h_j + \sum_{k=1 \setminus i}^{D} L_{ik} v_j \right)$

Parameter updates that are needed to perform gradient ascent in the log-likelihood from Eq. 3:

 $\Delta J = \alpha(\mathbb{E}_{P_{t-1}}[hh^T] - \mathbb{E}_{P_{t-1}}[hh^T])$

$$\Delta W = \alpha(\mathbb{E}_{P_{data}}[vh^T] - \mathbb{E}_{P_{model}}[vh^T])$$
$$\Delta L = \alpha(\mathbb{E}_{P_{data}}[vv^T] - \mathbb{E}_{P_{model}}[vv^T])$$

 $\mathbb{E}_{P_{data}}[\cdot]$ represents expectation w.r.to complete data distribution $P_{data}(h, v; \theta) = p(h|v; \theta)P_{data}(v)$, with $P_{data}(v) = \frac{1}{N}\sum_{n}\delta(v-v_n)$ representing the empirical distribution, and $\mathbb{E}_{P_{model}}$ is an expectation w.r.to. distribution defined by the model.

Reduce the expectation of the model distribution and the data distribution

Graphical Models

A graphical model or probabilistic graphical model (PGM) is a probabilistic model for which a graph expresses the conditional dependence structure between random variables.

Gaussian Bernoulli RBM

$$E(v,h) = ||v - a||^2 - b^T h - v^T W h$$

$$F(v) = -\ln\left(\sum_{h} e^{-E(v,h)}\right)$$



BAYES RULE

$$P(A|B) = P(B|A)\frac{P(A)}{P(B)}$$
(5)

LAW OF TOTAL PROBABILITY

$$P(B) = P(B|A_1)P(A_1) + \dots P(B|A_n)P(A_n)$$
 (6)

where $\{A_i\}_{i=1}^n$ are partitions of sample space

Probability distributions

GAUSSIAN/NORMAL DISTRIBUTION

$$pdf \equiv \frac{1}{\sigma\sqrt{2\pi}}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$cdf \equiv \frac{1}{2}\left[1 + erf\left(\frac{x-\mu}{\sigma\sqrt{2}}\right)\right]$$

$$erf(x) = \frac{1}{\sqrt{\pi}}\int_{-\pi}^{x}e^{-t^2/2}dt$$

Bernoulli Distribution

$$P(X=1) = p$$

$$E[X] = 1 \cdot P(X == 1) + 0 \cdot P(X == 0) = p$$
$$Var[X] = E[X^{2}] - E[X]^{2} = p - p^{2} = p(1 - p) = pq$$

⁰Denoted by Bern(p)

BINOMIAL DISTRIBUTION

Probability distribution of number of successes in n Bernoulli trials Bern(p)

$$P(X = k) = \binom{n}{k} p^k (1 - p)^{n-k}$$

$$E[X] = \sum_i E[X_i] = np$$

$$Var[X] = Var(\Sigma_i X_i) = \Sigma_i Var(X_i) = npq$$

 $X \sim B(n,p)$ and $Y \sim B(m,p)$ are independent binomial variables , $X+Y \sim B(n+m,p)$

Poisson

DIRICHLET

BETA

CENTRAL LIMIT THEOREM

Central Limit Theorem (CLT) states that, given certain conditions, the arithmetic mean of a sufficiently large number of iterates of independent random variables, each with a well-defined expected value and well-defined variance, will be approximately normally distributed, regardless of the underlying distribution.

A simple example of this is that if one flips a coin many times, the probability of getting a given number of heads should follow a normal curve, with mean equal to half the total number of flips.