Amrita School of Engineering, Bengluru-35 23MAT117-Linear Algebra Lab Practice Sheet-2

(Left Inverse, Right Inverse, Pseudo inverse, Solution to Linear System)

Left Inverse of a matrix: If all columns of matrix A of size $m \times n$ are independent (or rank(A) = n), then the matrix has a left inverse such that

$$A_{LI} \times A = I_{n \times n}$$

 $A_{LI} \equiv Left \text{ inverse of A}$
 $A_{LI} = (A^T A)^{-1} A^T$

If all columns are independent, you may notice that 'm' should be greater than or equal to 'n'. If m = n, then it is a square matrix and left inverse is same as original inverse.

Perform the following experiments:

- a) Create a random 4 by 3 matrices
- b) Check whether rank(A) = n = 3
- c) Find Left inverse of A. Ans: $A_{LI} = inv(A' * A) * A'$
- d) Check whether $A_{LI} * A$ produces an identity matrix.

Right Inverse of a matrix: If all rows of matrix A of size $m \times n$ are independent (or rank(A) = m), then the matrix has a right inverse such that

$$A \times A_{RI} = I_{m \times m}$$

$$A_{RI} \equiv Right \text{ inverse of A}$$

$$A_{RI} = A^{T} (AA^{T})^{-1}$$

Create such matrices and verify the result.

If all rows are independent, you may notice that 'm' should be less than or equal to 'n'. If m = n, then it is a square matrix and right inverse is same as original inverse.

Perform the following experiments:

- a) Create a random 5 by 7 matrices
- b) Check whether rank(A) = m = 5
- c) Find right inverse of A. Ans: $A_{RI} = A' * inv(A * A')$
- d) Check whether $A * A_{LI}$ produces an identity matrix.

Pseudoinverse of an $m \times n$ matrix, A

Every matrix $A_{m \times n}$ has a pseudoinverse A^+ or pinv(A)

- If m = n = rank(A), then A is invertible and $A^+ = A^{-1}$
- If rank(A) = n, (all columns of A are independent), then $A^+ = (A^T A)^{-1} A^T = Left Inverse of <math>A$, and $A^+ A = I_n$.
- If rank(A) = m, (all rows of A are independent), then $A^+ = A^T (A^T A)^{-1} = Right Inverse of A$, and $A^+ A = I_m$.
- Pseudoinverse A^+ of any matrix A can be obtained in MATLAB using the command 'pinv(A)'.
- a) Generate a 9×9 random integer matrix and verify that inv(A) = pinv(A).
- b) Generate a 5×4 random integer matrix and verify that pinv(A) is same as the left inverse of A.
- c) Generate a 3×7 random integer matrix and verify that pinv(A) is same as the right inverse of A.

Solutions to Linear System AX = B:

• $A = [1 \ 2 \ 3; 4 \ 5 \ 6; 9 \ 1 \ 3]; b = [6;15;13]; X = A \ b$

• $A = [1 \ 2 \ 3; 4 \ 5 \ 6; 9 \ 1 \ 3]; b = [6;15;13]; X = inv(A)*b$

Solves the system AX=b if A is invertible. Here if inv is replaced with pinv we will get the same solution.

• $A = [1 \ 2 \ 3; 4 \ 5 \ 6; 5 \ 7 \ 9]; b = [6;15;21]; pinv(A)*b$

With 'pinv' we can obtain a solution of the infinitely many solutions of a system (When A is not invertible)

Practice questions

- 1. Consider the matrices given below: A, B, C, D and E.
 - a) Which of the matrices have inverse? Find if it exists.
 - b) Which of the matrices will have a left inverse? Find if it exists.
 - c) Which of the matrices will have a right inverse? Find if it exists.
 - d) Find pseudo inverse of all these matrices using the command 'pinv'. Compare the answers with the answers obtained in (a), (b), (c) and (d).

$$A = \begin{bmatrix} 1 & 4 & 5 & 6 & 9 \\ 3 & -2 & 1 & 4 & -1 \\ -1 & 0 & -1 & -2 & -1 \\ 2 & 3 & 5 & 7 & 8 \end{bmatrix}, \quad B = \begin{bmatrix} 3 & 4 \\ 1 & 8 \end{bmatrix}, \quad C = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 4 & 2 \end{bmatrix},$$

$$D = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 2 & 4 & 0 & 2 \end{bmatrix}, \qquad E = \begin{bmatrix} 0 & 1 & 4 & 1 \\ 0 & 0 & 8 & 1 \\ 0 & 1 & 4 & 0 \\ 1 & 0 & 8 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$

2. Solve the given linear system using MATLAB.

$$x + y = 6$$
; $2x - y = 9$.

3. Solve the system using pinv command

$$x + y + z = 6$$
; $2x - y + z = 3$; $3x + 2y + z = 10$.

4. Solve the given system using pinv command.

$$x + y + z = 6$$
; $2x + y + z = 7$; $3x + 2y + 2z = 13$.

- 5. Solve the following systems of linear equations (rref command can be used in MATLAB to get the row reduced echelon form). Mention what the solution geometrically represents (a point or a line or a plane or a hyperplane).
 - a) 3x+3y-z=4; 3x-8y+6z=7; x+y+10z=22
 - b) 4x-3y+2z+5w=10; 9x-2y-3z+6w=7; 2x+11y+3z-6w=13; 8x-3y+5z-w=14
 - c) x-3y+2z+5w=3; 2x-2y+3z+6w=11; 2x+11y-3z-6w=40; 5x+6y+2z+5w=54
 - d) 4x-3y+2z+5w=10; 9x-2y-3z+6w=7; 5x+1y-5z+w=13; 8x-6y+4z+10w=20
 - e) x+y-z=7; 2x-2y+3z=9; 3x+2y-5z=10
 - f) x-3y+2z+5w=0; 2x-2y+3z+6w=0; 2x+11y-3z-6w=0; 5x+6y+2z+5w=0
 - g) 4x-3y+2z+5w=0; 9x-2y-3z+6w=0; 5x+1y-5z+w=0; 8x-6y+4z+10w=0
 - h) x+y-2z=0; 2x-3y+z=0; 3x-2y-z=0
 - i) x+y-5z+3w=0; 2x-3y-10z+4w=0; x-9y-5z+w=0; 4x-11y-20z+8w=0