

THE MOST COMPLETE STARTER KIT TUTORIAL FOR UNO

Preface

Our Company

Established in 2011, Elego Inc. is a professional manufacturer and exporter that is concerned with the design, development production and marketing of arduino, 3d printers, raspberry pi and STM32. We are located in Shenzhen which is known as Chinese Silicon Valley. All of our products comply with international quality standards and are greatly appreciated in a variety of different markets throughout the world.

Our official website is: [Http://www.elego.cc](http://www.elego.cc)

Our USA amazon shop is: [Http://www.amazon.com/shops/A2WWHQ25ENKVJ1](http://www.amazon.com/shops/A2WWHQ25ENKVJ1)

Our Tutorial

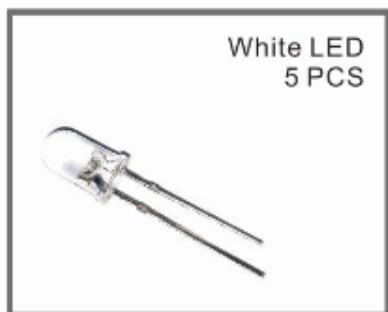
The tutorial is for beginners. In the tutorial, you can learn how to use arduino controller board, sensors and components. You can also learn the basic knowledge of all the parts. But if you want to study arduino systematically, we recommend you to buy the book "Arduino Cookbook" which is written by Michael Margolis.

Our after-sales

If you have any question or suggestion about our company, product or tutorial. Please send us a email. Our email address is service@elego.cc.

We will very appreciate and improve ourselves so that we can offer you a better service.

Packing List



White LED
5 PCS



Yellow LED
5 PCS



Blue LED
5 PCS



Green LED
5 PCS



Red LED
5 PCS



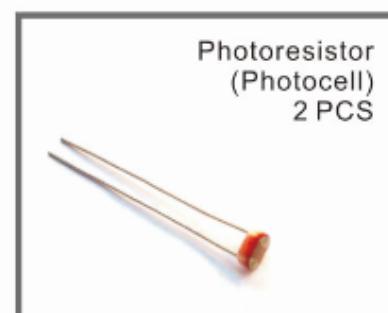
RGB LED
1 PCS



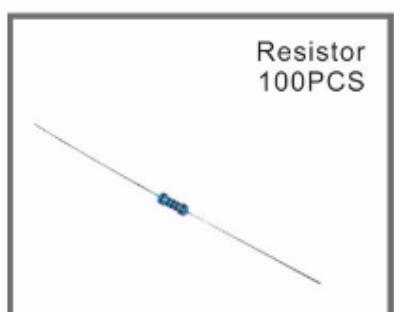
22pf ceramic
capacitor
5 PCS



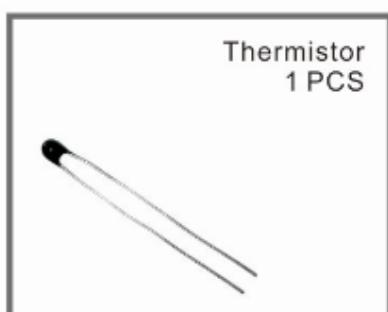
104 ceramic
capacitor
5 PCS



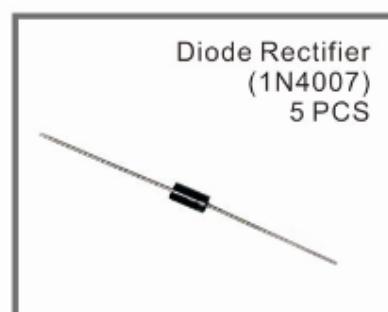
Photoresistor
(Photocell)
2 PCS



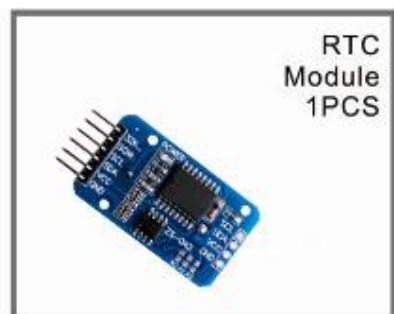
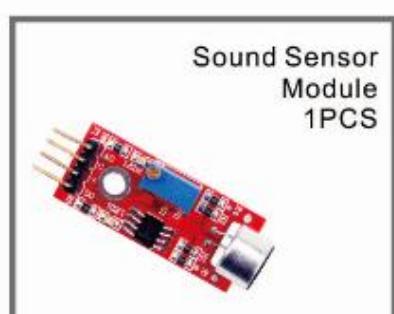
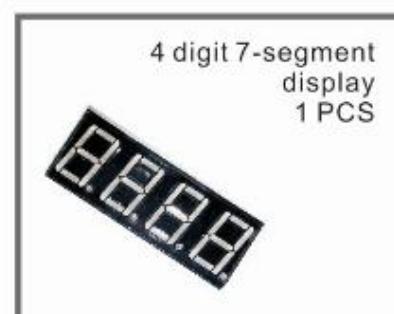
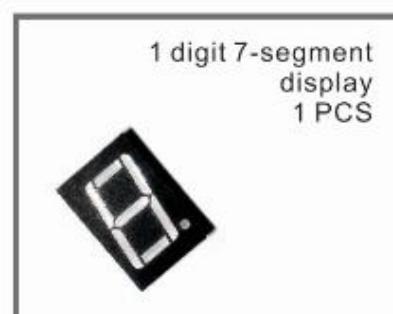
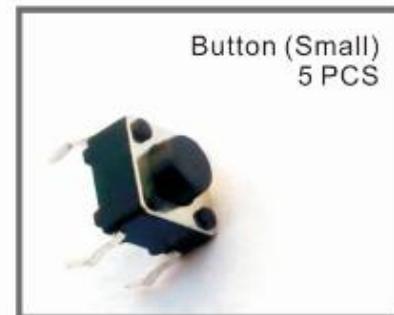
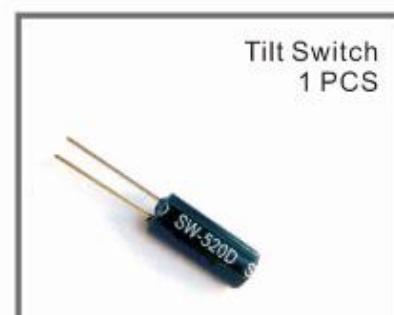
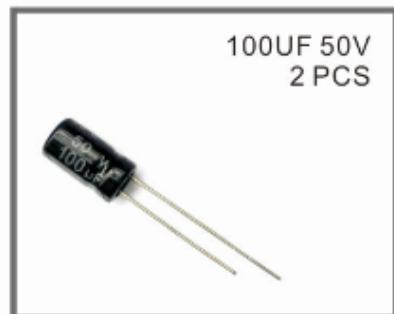
Resistor
100PCS

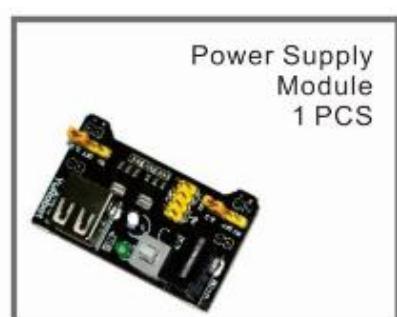
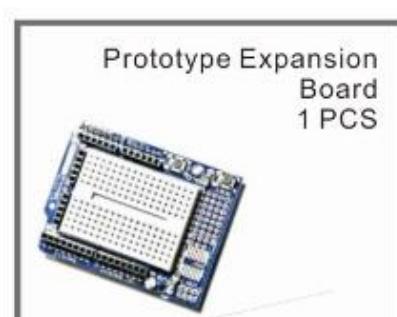
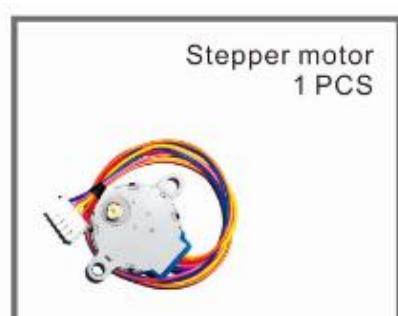
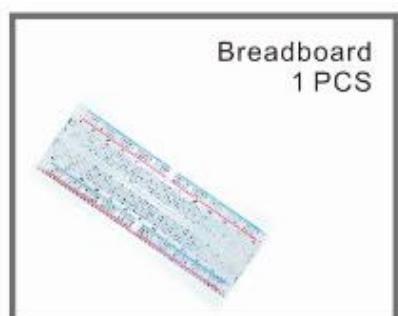
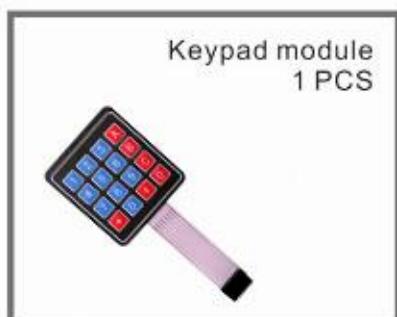
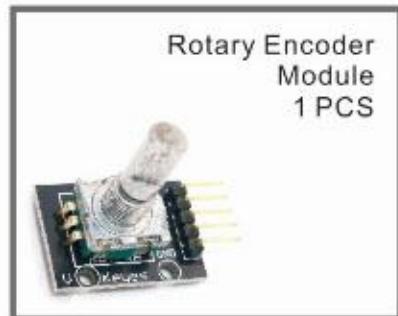


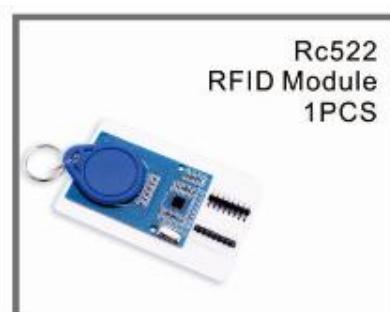
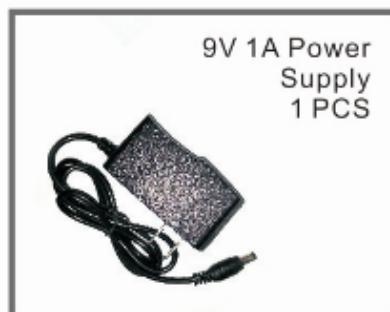
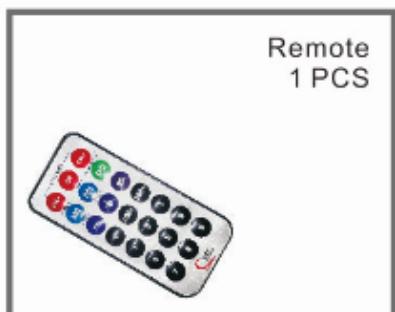
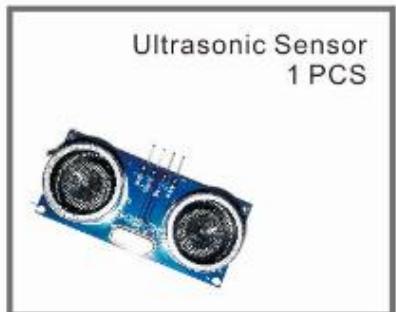
Thermistor
1 PCS



Diode Rectifier
(1N4007)
5 PCS







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Lesson 0 Installing IDE

Introduction

In this lesson, you will learn how to setup your computer to use Arduino and how to set about the lessons that follow.

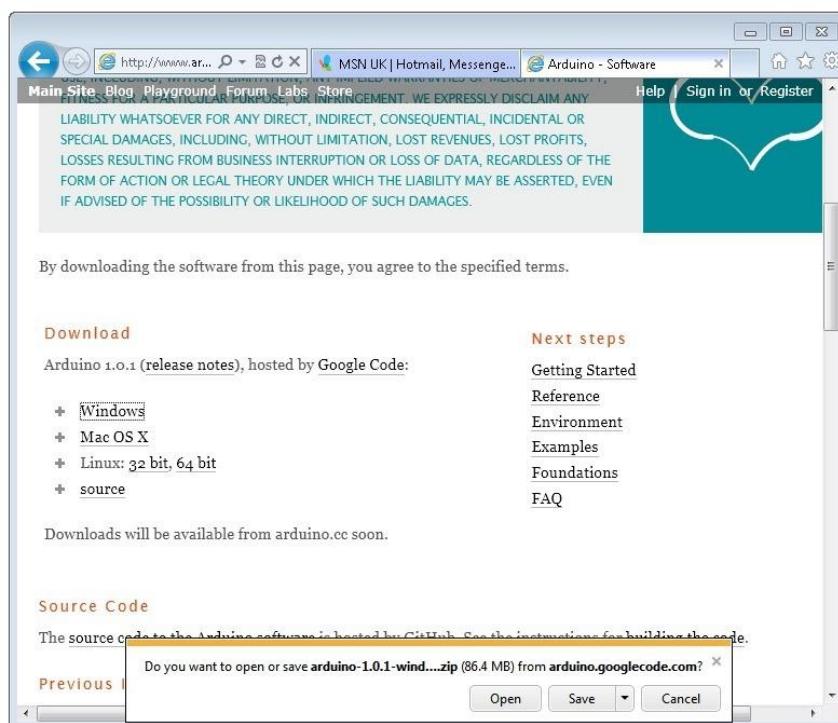
Installing Arduino (Windows)

The Arduino software that you will use to program your Arduino is available for Windows, Mac and Linux. The installation process is different for all three platforms and unfortunately there is a certain amount of manual work to install the software. There is no installer program, but rather you have to unzip a folder which gives you an Arduino folder that contains the Arduino program and a few other items.

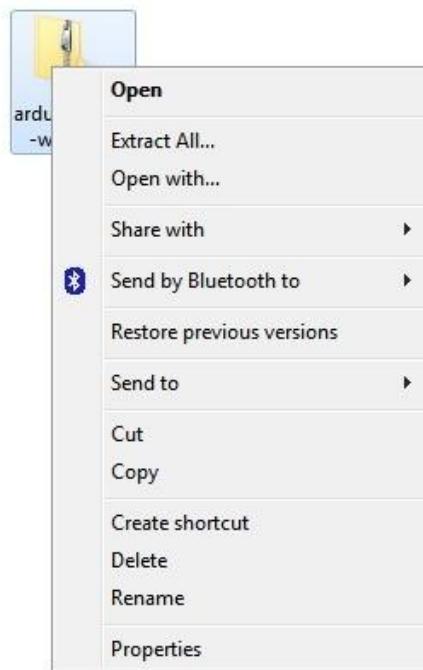
In a separate step, you must then install USB drivers, which is the only bit that is a bit fiddly.

Get started by visiting the Arduino.cc website. As of April 2014 we suggest v1.05 as 1.5 is still in beta. If 1.5 is no longer in beta when you read this you can try it out!

Start by downloading the zip file for Windows. There is only one version of the software, whether you are using Windows XP through to Windows 7.



When the zip file has downloaded, extract the contents onto the Desktop, by right-clicking on the file and selecting 'Extract All...' from the pop-up menu.



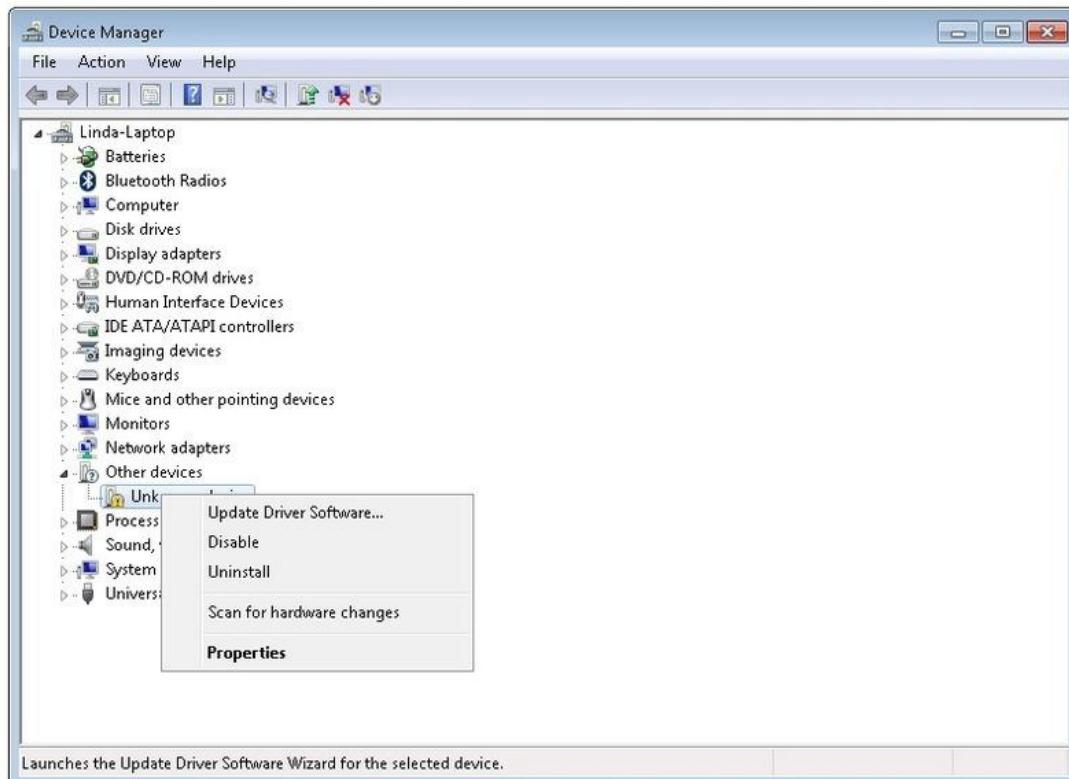
Next select your Desktop and click 'Extract'. You can move it somewhere else onto your computer later, just by moving the folder, but for now, just keep it on the Desktop.

The Arduino folder contains both the Arduino program itself and also the drivers that allow the Arduino to be connected to your computer by a USB cable. Before we launch the Arduino software, you are going to install the USB drivers.

Plug one end of your USB cable into the Arduino and the other into a USB socket on your computer. The power light on the LED will light up and you may get a 'Found New Hardware' message from Windows. Ignore this message and cancel any attempts that Windows makes to try and install drivers automatically for you.

The most reliable method of installing the USB drivers is to use the Device Manager. This is accessed in different ways depending on your version of Windows. In Windows 7, you first have to open the Control Panel, then select the option to view Icons, and you should find the Device Manager in the list.

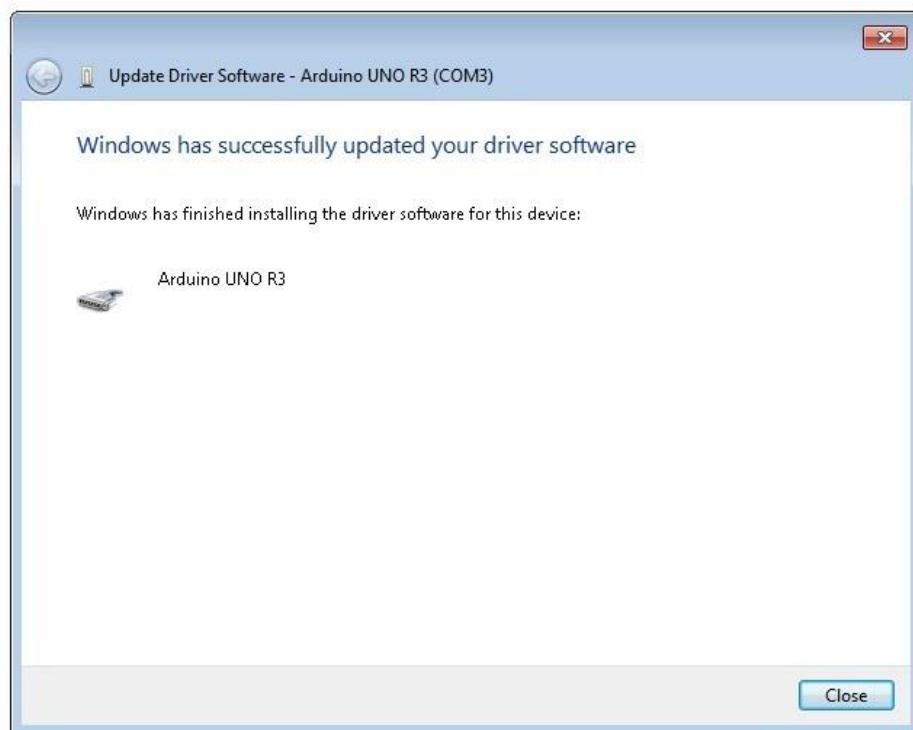
Under the section 'Other Devices' you should see an icon for 'unknown device' with a little yellow warning triangle next to it. This is your Arduino.



Right-click on the device and select the top menu option (Update Driver Software...). You will then be prompted to either 'Search Automatically for updated driver software' or 'Browse my computer for driver software'. Select the option to browse and navigate to the arduino-1.0.2-windows\arduino1.0.2\drivers.



Click 'Next' and you may get a security warning, if so, allow the software to be installed. Once the software has been installed, you will get a confirmation message.



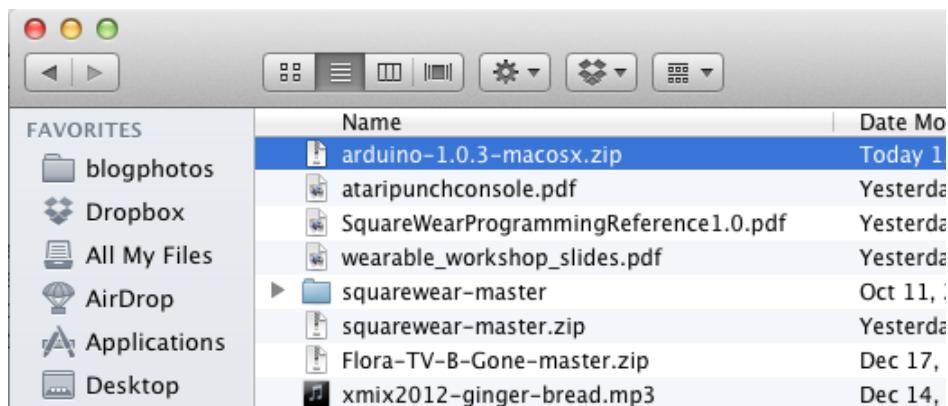
That's it, you are now ready for action, so Skip the next section on installation on Mac and Linux and move straight on to 'Boards and Ports'.

Installing Arduino (Mac and Linux)

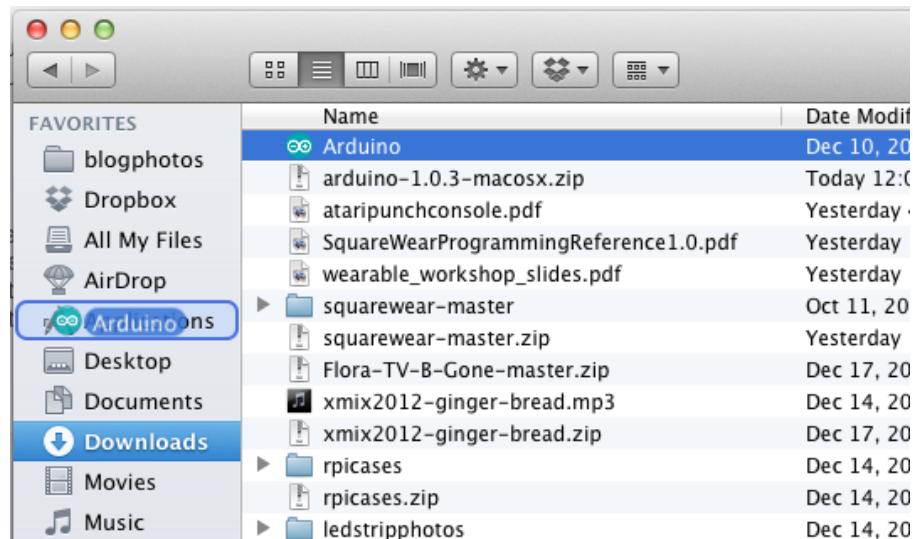
Get started by visiting the Arduino.cc website and downloading the matching IDE for your operating system. As of April 2014 we suggest v1.05 as 1.5 is still in beta. If 1.5 is no longer in beta when you read this you can try it out!

A screenshot of the Arduino website. On the left, there is a large teal Arduino logo with a minus sign and a plus sign inside a circle. Below it, the word "ARDUINO" is written in a bold, sans-serif font. At the top, there is a navigation bar with links: Buy, Download, Getting Started, Learning, Reference, and Products. The "Download" link is highlighted. Below the navigation bar, there is a section titled "Download the Arduino Software" with a sub-section about the open-source environment. To the right of this, a "Firefox" download dialog box is overlaid. The dialog box title is "Opening arduino-1.0.3-macosx.zip". It says "You have chosen to open arduino-1.0.3-macosx.zip which is a: ZIP archive (77.2 MB) from: http://arduino.googlecode.com". It asks "What should Firefox do with this file?". There are two radio buttons: "Open with Archive Utility (default)" and "Save File". The "Save File" option is selected. There is also a checkbox "Do this automatically for files like this from now on." which is unchecked. At the bottom right of the dialog box are "Cancel" and "OK" buttons.

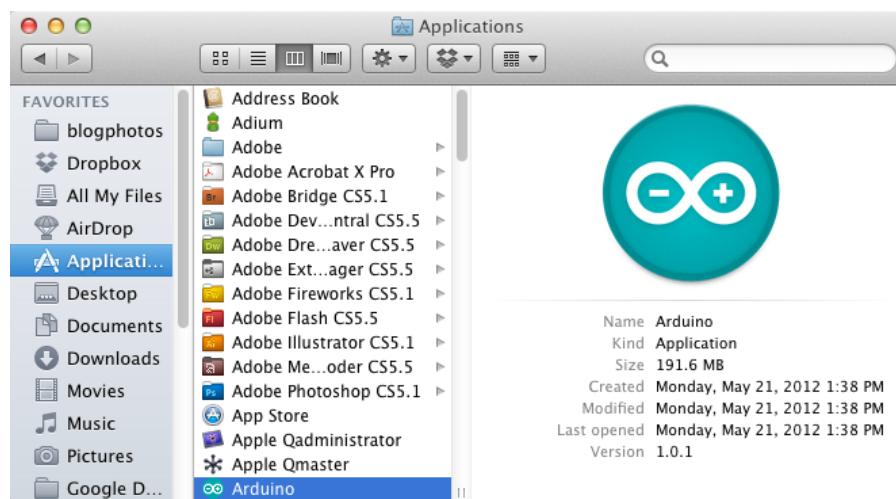
Save the install software to your desktop or wherever

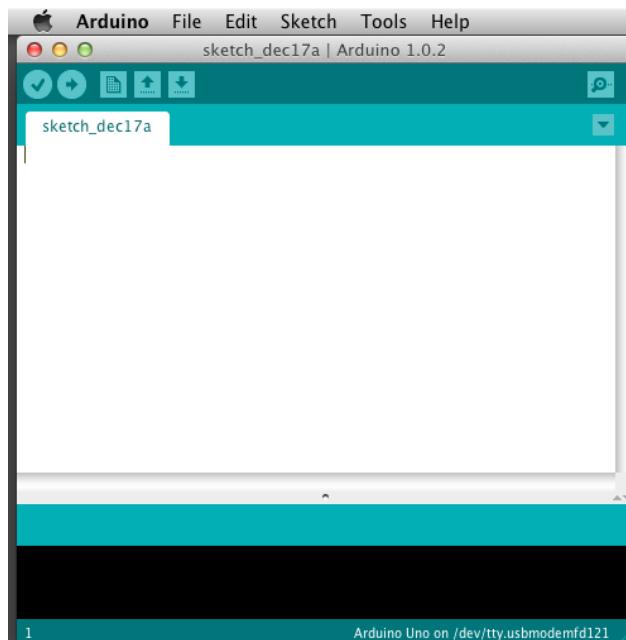


The process for installing the Arduino software on the Mac is a lot easier than on the PC. As before, the first step is to download the file. In the case of the Mac, it is a zip file.



Once downloaded, double-click on the zip file, which will extract a single file called 'Arduino.app'. This is the whole Arduino application, just drag it into your Applications Folder.



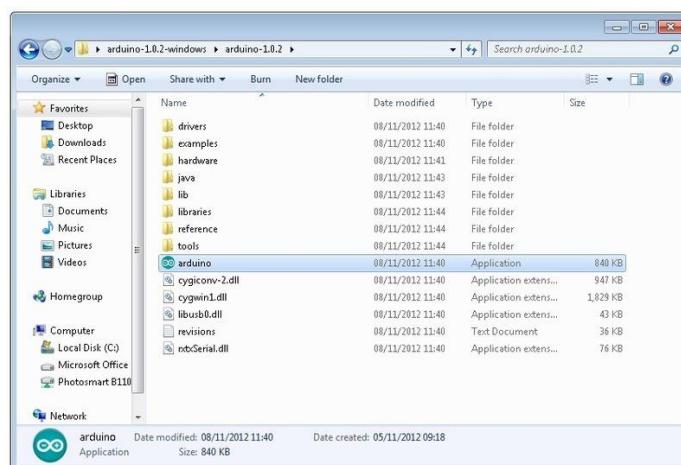


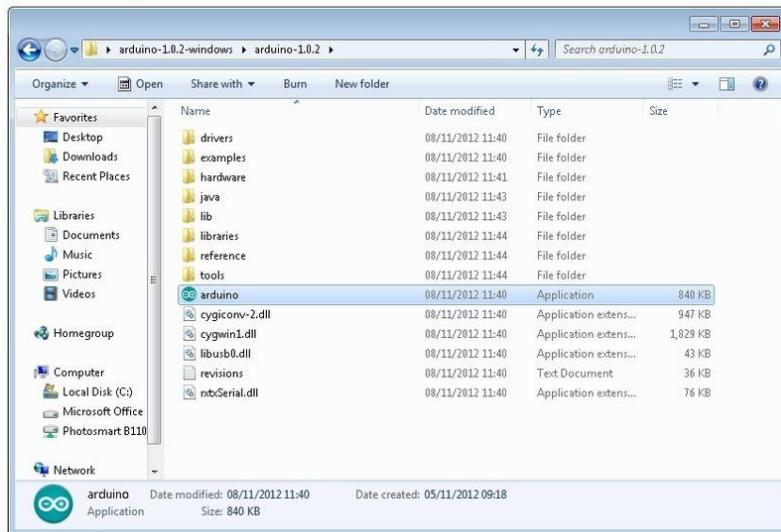
You can now find and launch the Arduino software in your Applications folder. As you are going to use it frequently, you may wish to right-click its icon in the dock and set it to Keep In Dock.

There are many different LINUX distributions and the instructions for each distribution are a little different. The Arduino community has done a great job of putting together sets of instructions for each distribution. So follow the link below and select one of the ten or more distributions on offer.

Boards and Ports

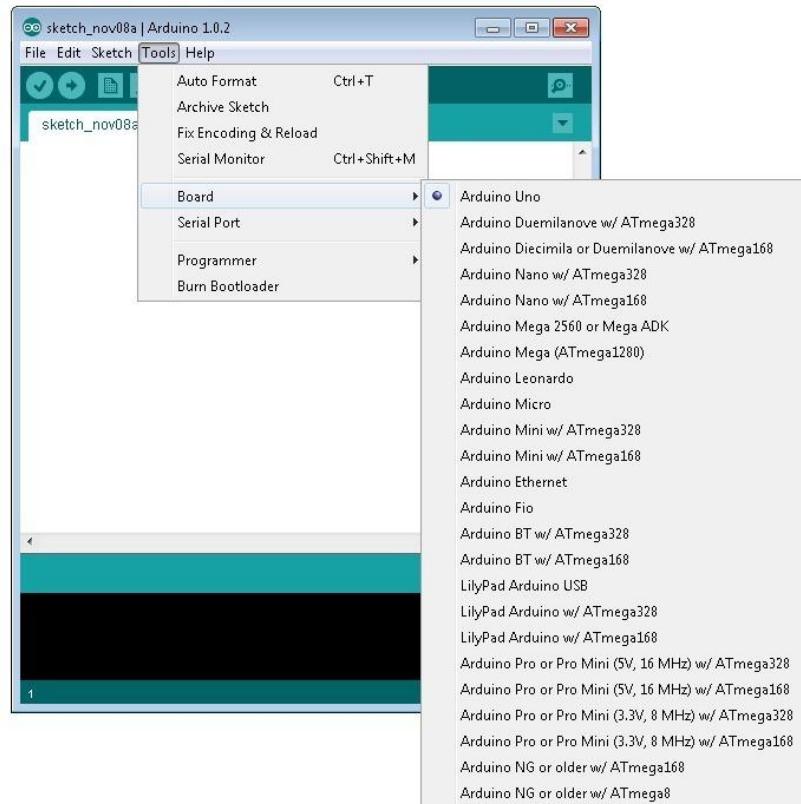
You are now ready to start the Arduino Software, so whatever platform you are using, open the Arduino folder and open the Arduino application contained within it.



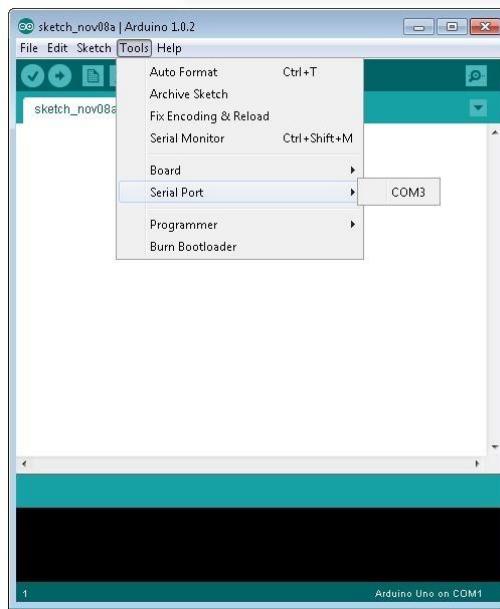


This will start the Arduino IDE, but before you can get programming, you have to tell the Arduino software which type of Arduino board you are using and also select the port it is connecting to.

To tell the Arduino IDE which type of board you are using. From the 'Tools' menu, select Board and then 'Arduino Uno' or 'Leonardo' as appropriate.

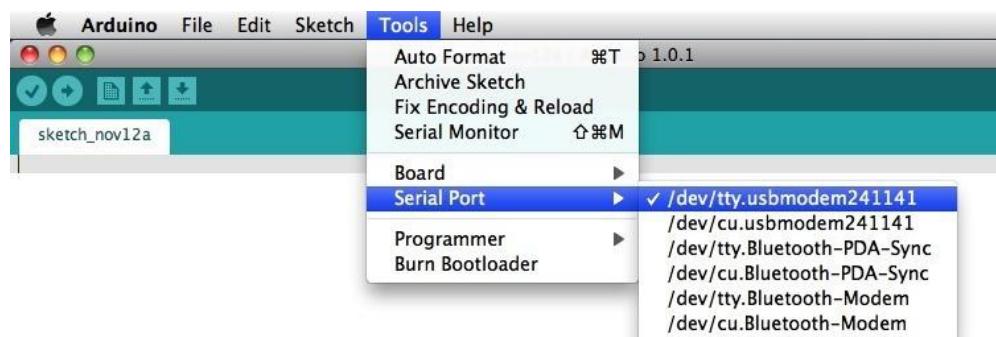


Also on the 'Tools' menu, you will find the 'Serial Port' option. Select this option.



If you are using Windows, there will probably only be one option here and it will either say COM3 or COM4. Even though there is only one option, you will still need to select it.

If you are using a Mac or Linux, there will be more options there, but it will usually be the top option in the list, as this will be the device most recently plugged in. This is useful, as the name of the port may not look like it has anything to do with Arduino. It will probably be called something like /dev/tty.usbmodemXXXX or /dev/ttYSBn



Lesson 1 Add Libraries

Once you are comfortable with the Arduino software and using the built-in functions, you may want to extend the ability of your Arduino with additional libraries.

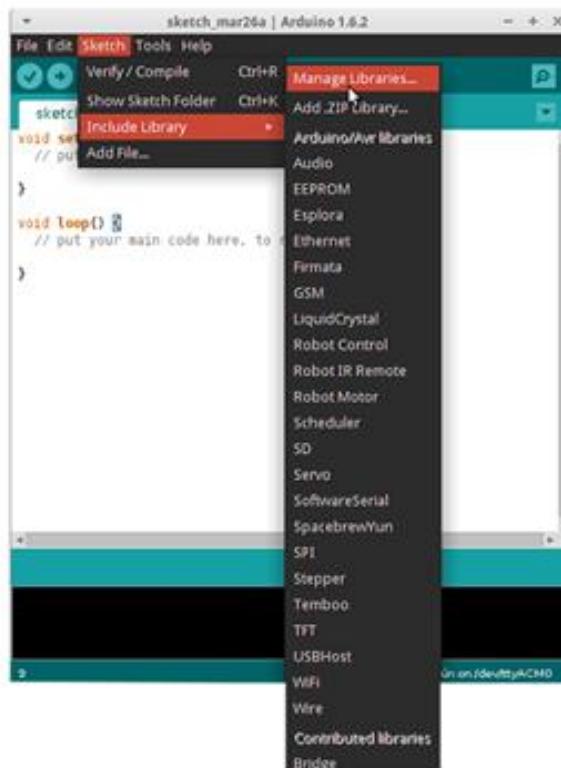
What are Libraries?

Libraries are a collection of code that makes it easy for you to connect to a sensor, display, module, etc. For example, the built-in LiquidCrystal library makes it easy to talk to character LCD displays. There are hundreds of additional libraries available on the Internet for download. The built-in libraries and some of these additional libraries are listed in the reference. To use the additional libraries, you will need to install them.

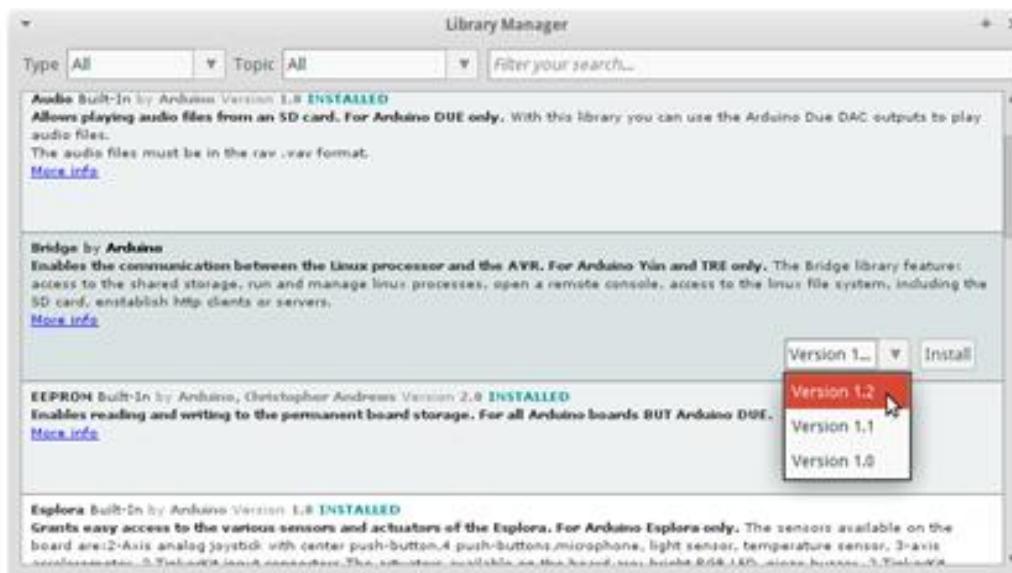
How to Install a Library

Using the Library Manager

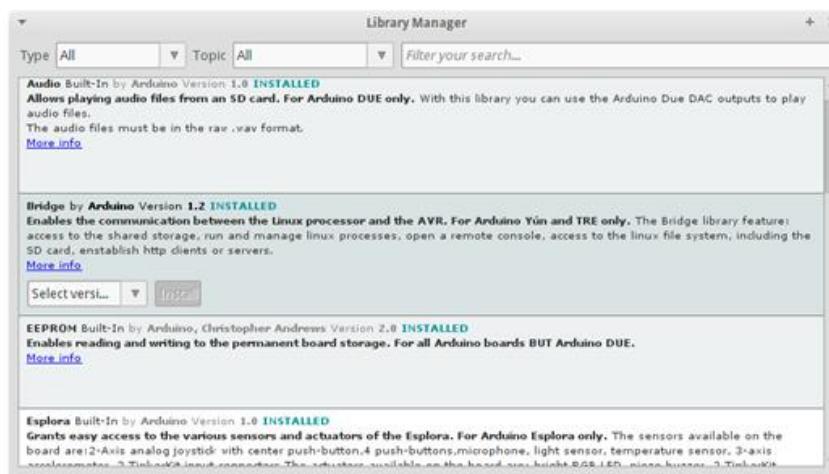
To install a new library into your Arduino IDE you can use the Library Manager (available from IDE version 1.6.2). Open the IDE and click to the "Sketch" menu and then Include Library > Manage Libraries.



Then the library manager will open and you will find a list of libraries that are already installed or ready for installation. In this example we will install the Bridge library. Scroll the list to find it, then select the version of the library you want to install. Sometimes only one version of the library is available. If the version selection menu does not appear, don't worry: it is normal.



Finally click on install and wait for the IDE to install the new library. Downloading may take time depending on your connection speed. Once it has finished, an Installed tag should appear next to the Bridge library. You can close the library manager.

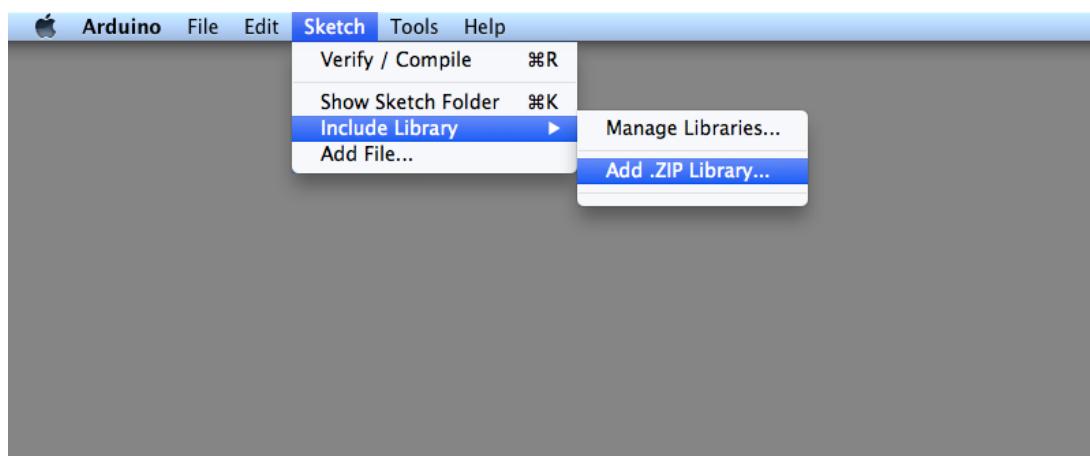


You can now find the new library available in the Include Library menu. If you want to add your own library open a new issue on github.

Importing a .zip Library

Libraries are often distributed as a ZIP file or folder. The name of the folder is the name of the library. Inside the folder will be a .cpp file, a .h file and often a keywords.txt file, examples folder, and other files required by the library. Starting with version 1.0.5, you can install 3rd party libraries in the IDE. Do not unzip the downloaded library, leave it as is.

In the Arduino IDE, navigate to Sketch > Include Library. At the top of the drop down list, select the option to "Add .ZIP Library".



You will be prompted to select the library you would like to add. Navigate to the .zip file's location and open it.

Return to the Sketch > Import Library menu. You should now see the library at the bottom of the drop-down menu. It is ready to be used in your sketch. The zip file will have been expanded in the libraries folder in your Arduino sketches directory.

NB: the Library will be available to use in sketches, but examples for the library will not be exposed in the File > Examples until after the IDE has restarted.

Manual installation

To install the library, first quit the Arduino application. Then uncompress the ZIP file containing the library. For example, if you're installing a library called "ArduinoParty", uncompress ArduinoParty.zip. It should contain a folder called ArduinoParty, with files like ArduinoParty.cpp and ArduinoParty.h inside. (If the .cpp and .h files aren't in a folder, you'll need to create one. In this case, you'd make a folder called "ArduinoParty" and move into it all the files that were in the ZIP file, like ArduinoParty.cpp and ArduinoParty.h.)

Drag the ArduinoParty folder into this folder (your libraries folder). Under Windows, it will likely be called "My Documents\Arduino\libraries". For Mac users, it will likely be called "Documents/Arduino/libraries". On Linux, it will be the "libraries" folder in your sketchbook.

Your Arduino library folder should now look like this (on Windows):

My Documents\Arduino\libraries\ArduinoParty\ArduinoParty.cpp

My Documents\Arduino\libraries\ArduinoParty\ArduinoParty.h

My Documents\Arduino\libraries\ArduinoParty\examples

....

or like this (on Mac and Linux):

Documents/Arduino/libraries/ArduinoParty/ArduinoParty.cpp

Documents/Arduino/libraries/ArduinoParty/ArduinoParty.h

Documents/Arduino/libraries/ArduinoParty/examples

....

There may be more files than just the .cpp and .h files, just make sure they're all there. (The library won't work if you put the .cpp and .h files directly into the libraries folder or if they're nested in an extra folder. For example: Documents\Arduino\libraries\ArduinoParty.cpp and Documents\Arduino\libraries\ArduinoParty\ArduinoParty.cpp won't work.)

Restart the Arduino application. Make sure the new library appears in the Sketch->Import Library menu item of the software. That's it! You've installed a library!

Summary

In this lesson, we will install all the libraries which we will use in the tutorial. Open the libraries folder and install the ZIP one by one. So in the following lesson, we don't need to install them anymore. We just connect the component as the schematic and upload the code provided. Then the kit will work.

Lesson 2 Blink

Overview

In this lesson, you will learn how program your Uno R3 controller board to make the Arduino's built-in LED blink.

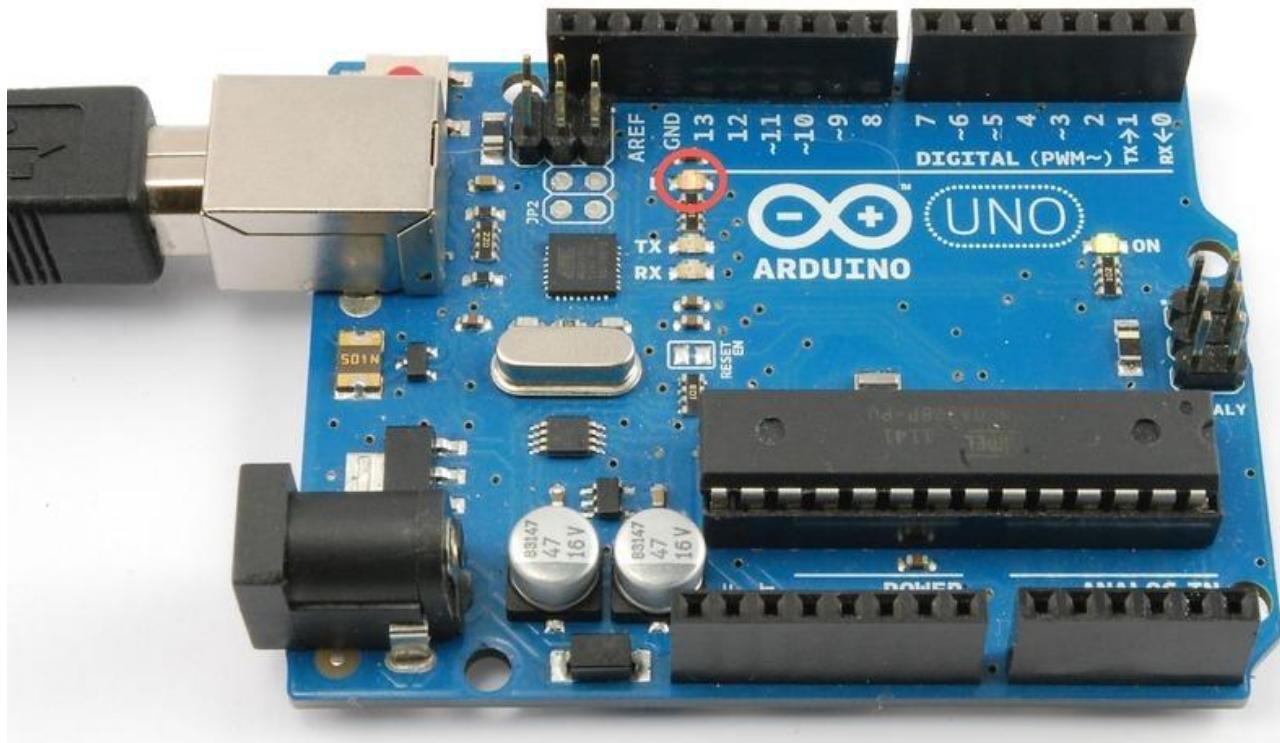
Component Required:

(1) x Elego Uno R3

Principle

The UNO R3 board has rows of connectors along both sides that are used to connect to electronic devices and plug-in 'shields' that allow the UNO R3 board to do more.

However, the UNO R3 board also has a single LED that you can control from your sketches. This LED is built onto the UNO R3 board and is often referred to as the 'L' LED as this is how it is labeled on the board.



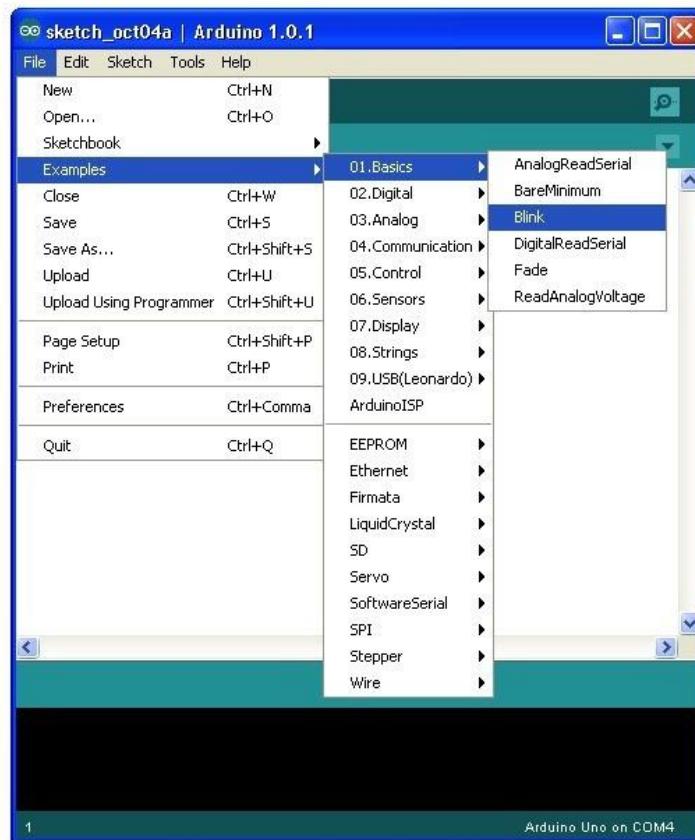
You may find that your UNO R3 board's 'L' LED already blinks when you connect it to a USB plug. This is because UNO R3 boards are generally shipped with the 'Blink' sketch pre-installed.

In this lesson, we will reprogram the UNO R3 board with our own Blink sketch and then change the rate at which it blinks.

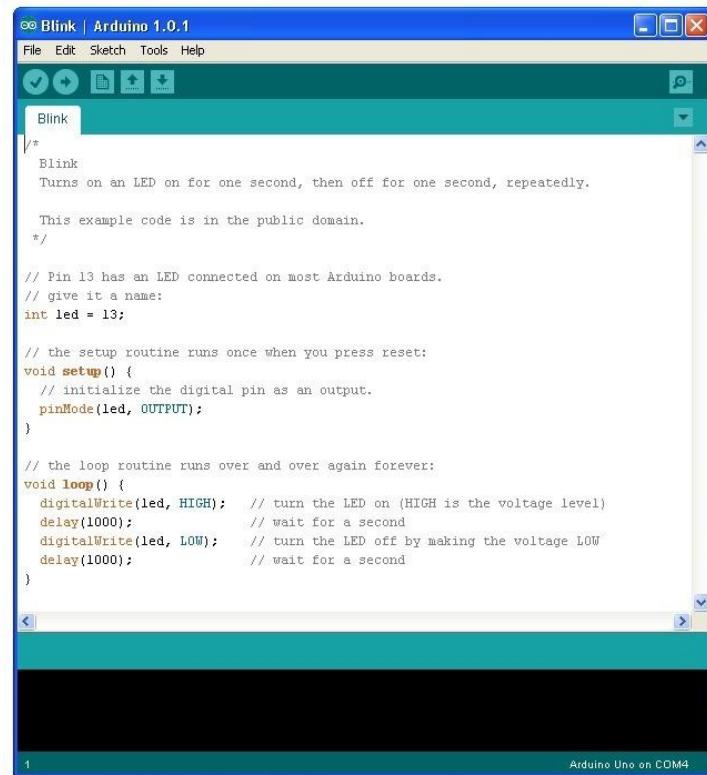
In lesson 0, you setup your Arduino IDE and made sure that you could find the right serial port for it to connect to your UNO R3 board. The time has now come to put that connection to the test and program your UNO R3 board.

The Arduino IDE includes a large collection of example sketches that you can load up and use. This includes an example sketch for making the 'L' LED blink.

Load the 'Blink' sketch that you will find in the IDE's menu system under File → Examples → 01.Basics



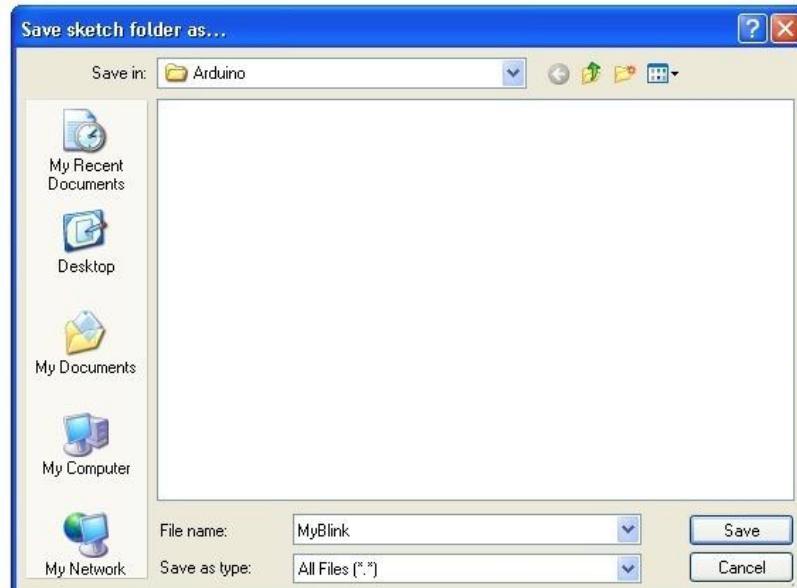
When the sketch window opens, enlarge it so that you can see the whole of the sketch in the window.



The example sketches included with the Arduino IDE are 'read-only'. That is, you can upload them to an UNO R3 board, but if you change them, you cannot save them as the same file.

We are going to change this sketch, so, the first thing you need to do is save your own copy that you can change however you like.

From the File menu on the Arduino IDE select the option 'Save As..' and then save the sketch with the name 'MyBlink'.



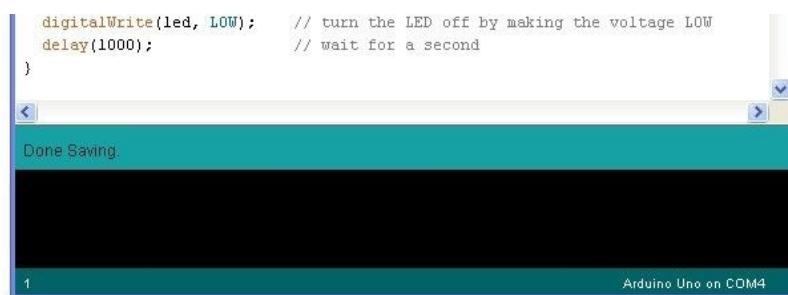
You have saved your copy of 'Blink' in your sketchbook. This means that if you ever want to

find it again, you can just open it using the File → Sketchbook menu option.



Attach your Arduino board to your computer with the USB cable and check that the 'Board Type' and 'Serial Port' are set correctly. You may need to refer back to Lesson 0.

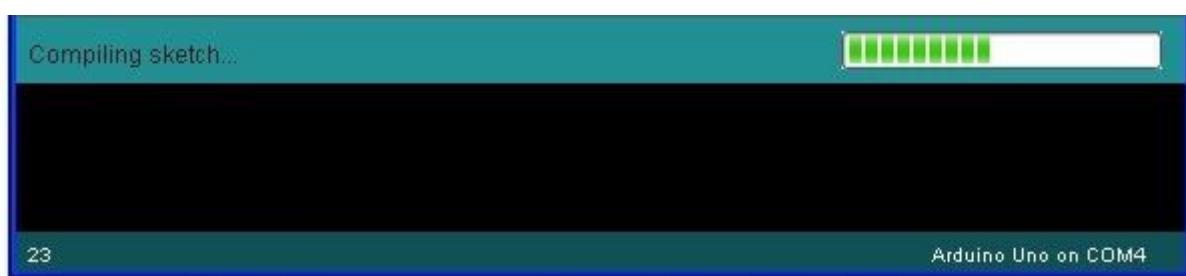
The Arduino IDE will show you the current settings for board at the bottom of the window.



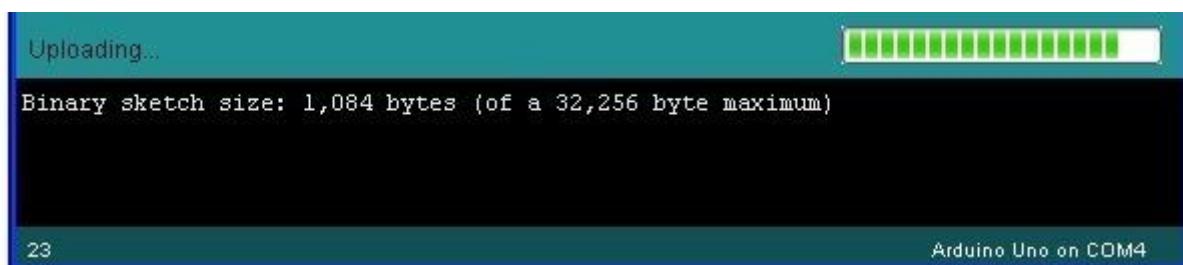
Click on the 'Upload' button. The second button from the left on the toolbar.



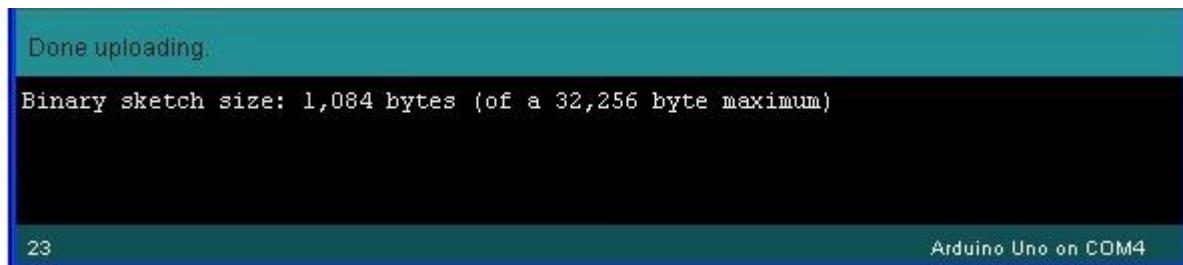
If you watch the status area of the IDE, you will see a progress bar and a series of messages. At first it will say 'Compiling Sketch...'. This converts the sketch into a format suitable for uploading to the board.



Next, the status will change to 'Uploading'. At this point, the LEDs on the Arduino should start to flicker as the sketch is transferred.



Finally, the status will change to 'Done'.



The other message tells us that the sketch is using 1,084 bytes of the 32,256 bytes available. After the 'Compiling Sketch..' stage you could get the following error message:



The clue is at the top here, it probably means that your board is not connected at all, or the drivers have not been installed (if necessary) or that the wrong serial port is selected.

If you get this, go back to Lesson 0 and check your installation.

Once the upload has completed, the board should restart and start blinking.

Open the code

The first thing to note is that quite a lot of this sketch is what is called 'comments'. Comments are not actual program instructions, they are just comments about how the program works. They are there for our benefit, so that there is some explanation to accompany the sketch.

Everything between /* and */ at the top of the sketch is a block comment, that explains what the sketch is for.

There are also single line comments that start with // and everything up until the end of the line counts as being a comment.

The first actual line of code is:

Copy Code

1. int led = 13;

As the comment above explains, this is giving a name to the pin that the LED is attached to. This is 13 on most Arduinos, including the Uno and Leonardo.

Next, we have the 'setup' function. Again, as the comment says, this is run when the reset button is pressed. It is also run whenever the board resets for any reason, such as power first being applied to it, or after a sketch has been uploaded.

Copy Code

```
1. void setup() {  
2.     // initialize the digital pin as an output.  
3.     pinMode(led, OUTPUT);  
4. }
```

Every Arduino sketch must have a 'setup' function, and the part of it where you might want to add instructions of your own is between the { and the }.

In this case, there is just one command there, which, as the comment states tells the Arduino board that we are going to use the LED pin as an output.

It is also mandatory for a sketch to have a 'loop' function. **Unlike the 'setup' function that only runs once, after a reset, the 'loop' function will, after it has finished running its commands, immediately start again.**

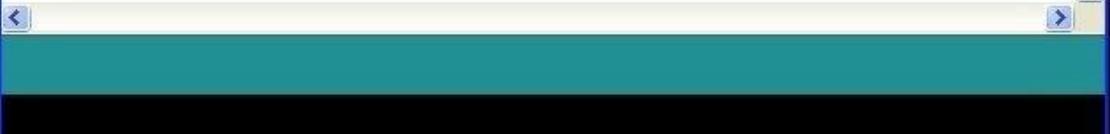
Copy Code

```
1. void loop() {  
2.     digitalWrite(led, HIGH);    // turn the LED on (HIGH is the voltage level)  
3.     delay(1000);            // wait for a second  
4.     digitalWrite(led, LOW);   // turn the LED off by making the voltage LOW  
5.     delay(1000);            // wait for a second  
6. }
```

Inside the loop function, the commands first of all turn the LED pin on (HIGH), then 'delay' for 1000 milliseconds (1 second), then turn the LED pin off and pause for another second.

You are now going to make your LED blink faster. As you might have guessed, the key to this lies in changing the parameter in () for the 'delay' command.

```
// the loop routine runs over and over again forever:  
void loop() {  
    digitalWrite(led, HIGH); // turn the LED on (HIGH is the voltage level)  
    delay(1000); // wait for a second  
    digitalWrite(led, LOW); // turn the LED off by making the voltage LOW  
    delay(1000); // wait for a second  
}
```



This delay period is in milliseconds, and so if you want the LED to blink twice as fast, change the value of 1000 to 500. This would then pause for half a second each delay rather than a whole second.

Upload the sketch again and you should see the LED start to flash more quickly.

Lesson 3 LED

Overview

In this lesson, you will learn how to change the brightness of an LED by using different values of resistor.

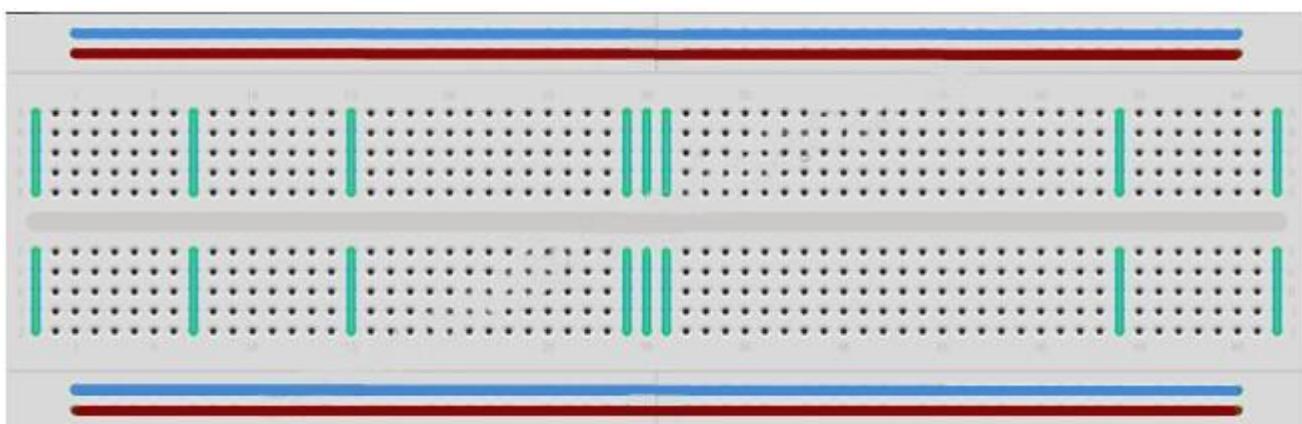
Component Required:

- (1) x Elego Uno R3
- (1) x 5mm red LED
- (1) x 220 ohm resistor
- (1) x 1k ohm resistor
- (1) x 10k ohm resistor
- (2) x M-M wires

Component Introduction

BREADBOARD MB-102:

Breadboard enables you to prototype circuits quickly, without having to solder the connections. Below shows an example of a breadboard.



Breadboards come in various sizes and configurations. The simplest kind is just a grid of holes in a plastic block. Inside are strips of metal that provide electrical connection between holes in the shorter rows. Pushing the legs of two different components into the same row joins

them together electrically. A deep channel running down the middle indicates that there is a break in connections there, meaning you can push a chip in with the legs at either side of the channel without connecting them together. Some breadboards have two strips of holes running along the long edges of the board that are separated from the main grid. These have strips running down the length of the board inside, and provide a way to connect a common voltage. They are usually in pairs for +5 volts and ground. These strips are referred to as rails and they enable you to connect power to many components or points in the board.

While breadboards are great for prototyping, they have some limitations. Because the connections are push-fit and temporary, they are not as reliable as soldered connections. If you are having intermittent problems with a circuit, it could be due to a poor connection on a breadboard.

LED:

LEDs make great indicator lights. They use very little electricity and they pretty much last forever.

In this lesson you will use perhaps the most common of all LEDs a 5mm red LED. 5Mm refers to the diameter of the LED and as well as 5mm, other common sizes are 3mm and the large fun 10mm LEDs.

You cannot directly connect an LED to a battery or voltage source. Firstly, because the LED has a positive and a negative lead and will not light if they are the wrong way around and secondly, an LED must be used with a resistor to limit or 'choke' the amount of current flowing through the LED - otherwise the LED could burn out!



If you do not use a resistor with an LED, then it may well be destroyed almost immediately, as too much current will flow through the LED, heating it and destroying the 'junction' where the light is produced.

There are two ways to tell which is the positive lead of the LED and which the negative.

Firstly, the positive lead is longer.

Secondly, where the negative lead enters the body of the LED, there is a flat edge to the case of the LED.

If you happen to have an LED that has a flat side next to the longer lead, you should assume that the longer lead is positive.

RESISTORS:

As the name suggests, resistors resist the flow of electricity and the higher the value of the resistor, the more it resists and the less electrical current will flow through it. We are going to use this to control how much electricity flows through the LED and therefore how brightly it shines.

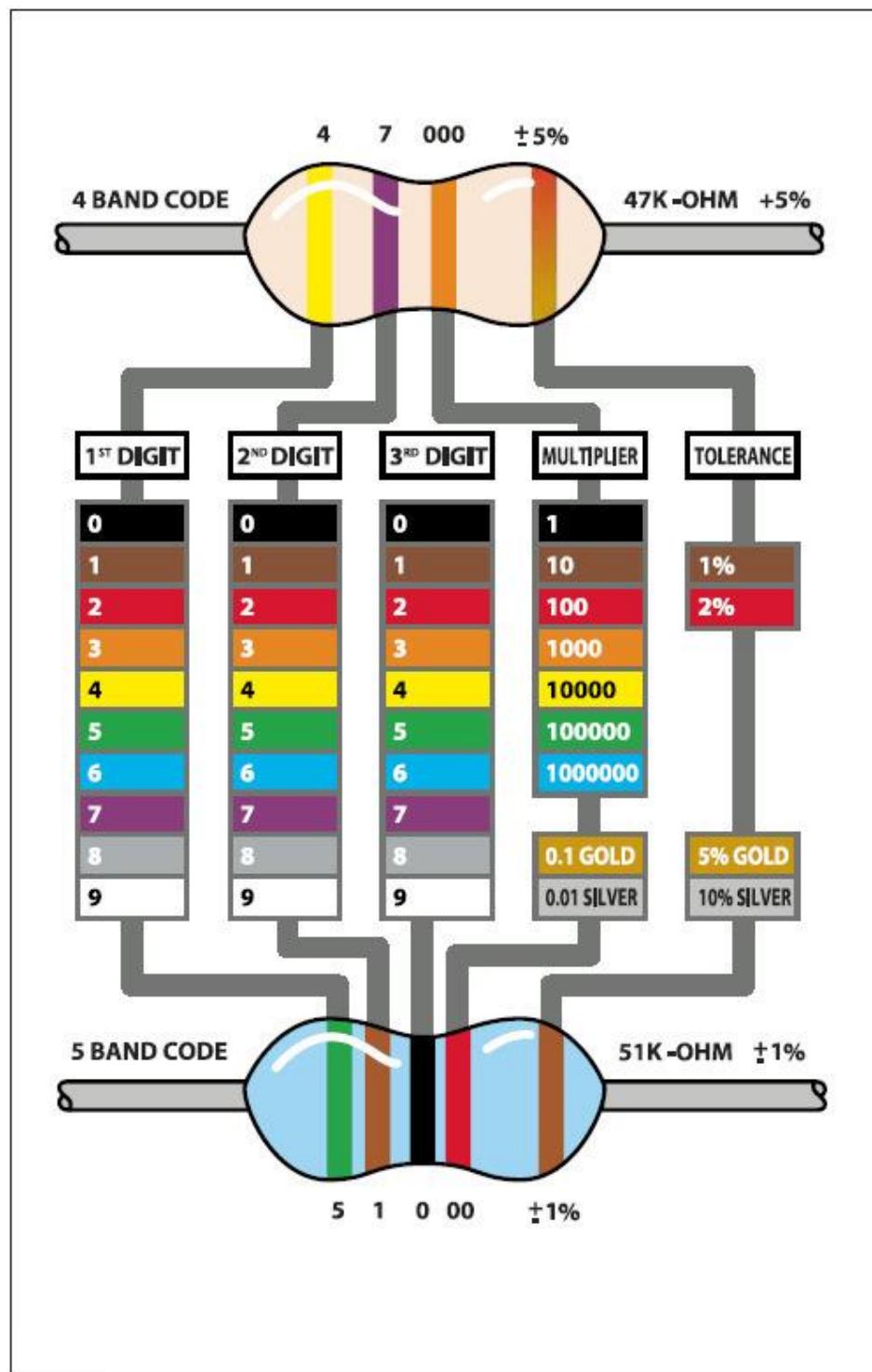


But first, a bit more about resistors.

The unit of resistance is called the Ohm, which is usually shortened to Ω the Greek letter Omega. Because an Ohm is a low value of resistance (it doesn't resist much at all), we also give the values of resistors in $k\Omega$ (1000 Ω) and $M\Omega$ (1000,000 Ω). These are called kilo-ohms and mega-ohms.

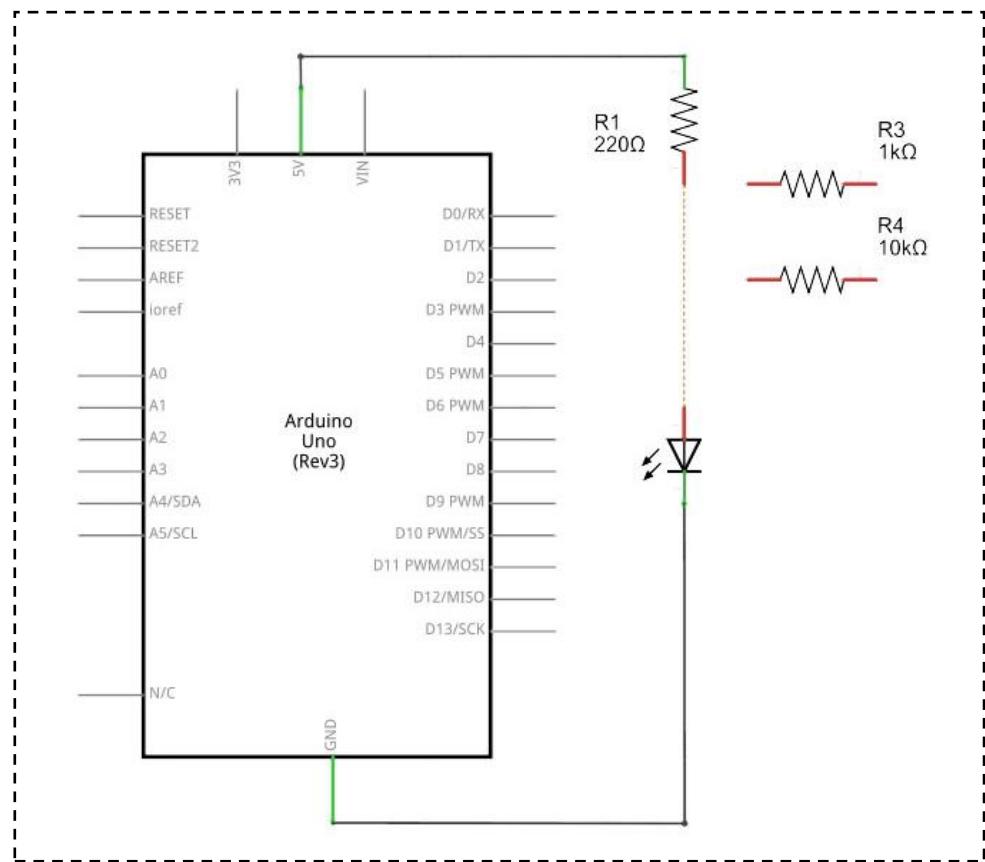
In this lesson, we are going to use four different values of resistor, 220Ω , $1k\Omega$ and $10k\Omega$. These resistors all look the same, except that they have different colored stripes on them. These stripes tell you the value of the resistor.

The resistor color code works like this, for resistors like this with three colored stripes and then a gold stripe at one end.

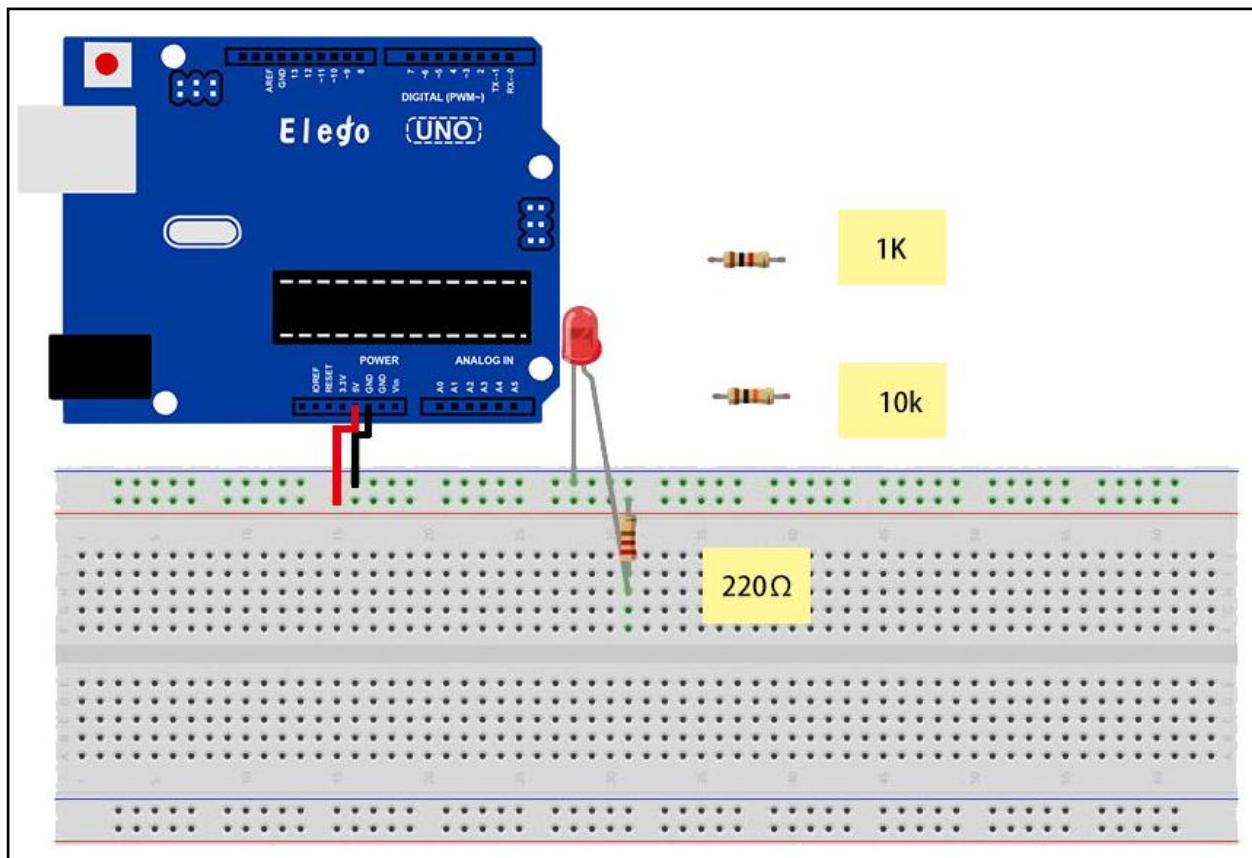


Unlike LEDs, resistors do not have a positive and negative lead. They can be connected either way around.

Connection Schematic



wiring diagram



The UNO is a convenient source of 5 Volts, that we will use to provide power to the LED and

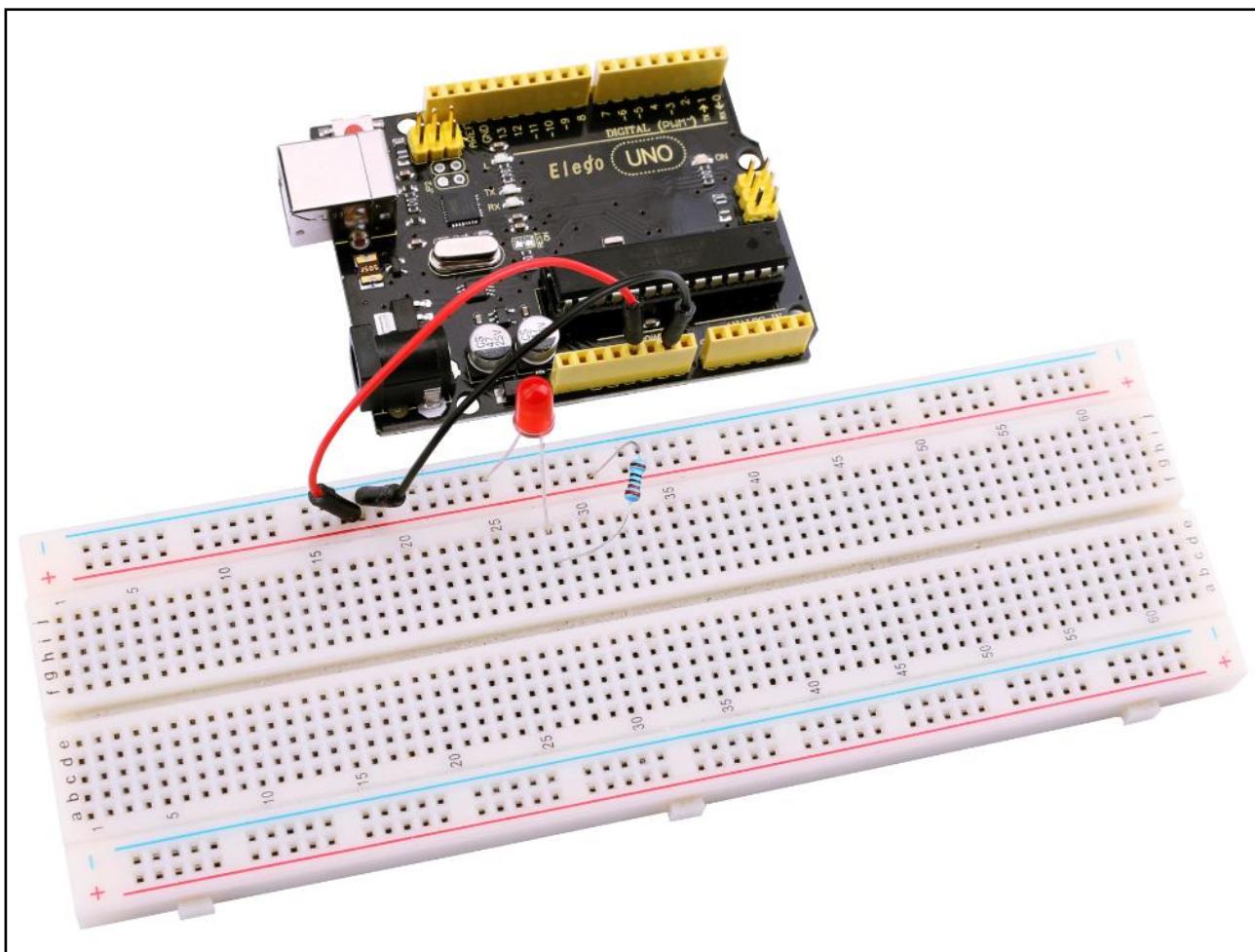
resistor. You do not need to do anything with your UNO, except plug it into a USB cable.

With the $220\ \Omega$ resistor in place, the LED should be quite bright. If you swap out the $220\ \Omega$ resistor for the $1k\Omega$ resistor, then the LED will appear a little dimmer. Finally, with the $10\ k\Omega$ resistor in place, the LED will be just about visible. Pull the red jumper lead out of the breadboard and touch it into the hole and remove it, so that it acts like a switch. You should just be able to notice the difference.

At the moment, you have 5V going to one leg of the resistor, the other leg of the resistor going to the positive side of the LED and the other side of the LED going to GND. However, if we moved the resistor so that it came after the LED, as shown below, the LED will still light.

Note, you will probably want to put the 220Ω resistor back in place.

So, it does not matter which side of the LED we put the resistor, as long as it is there somewhere.



Lesson 4 RGB LED

Overview

RGB LEDs are a fun and easy way to add some color to your projects. Since they are like 3 regular LED in one, the way to use and connect them is not much different.

They come mostly in 2 versions: Common Anode or Common Cathode.

Common Anode uses 5V on the common pin, while Common Cathode connects to Ground.

As with any LED, we need to connect some resistors inline (3 total) so we limit the current being drawn.

In our sketch we will start with the LED in the Red color state, then fade to Green, then fade to Blue and finally back to the Red color. By doing this we will cycle through most of the color that can be achieved.

Component Required:

- (1) x Elego Uno R3
- (1) x Bread board
- (4) x M-M wires
- (1) x RGB LED
- (3) x 220 ohm resistors

Component Introduction

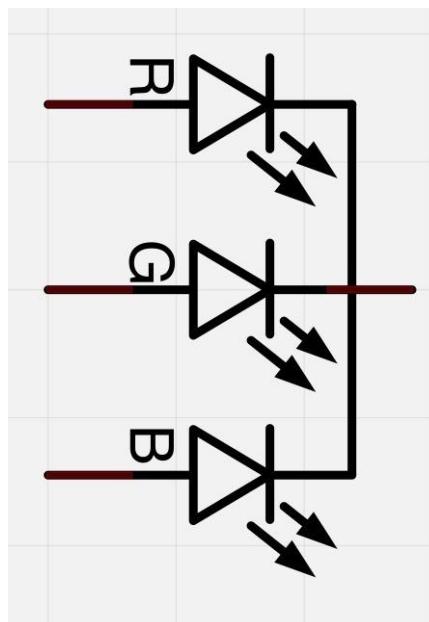
RGB:

At first glance, RGB (Red, Green, Blue) LEDs look just like regular LEDs, however, inside the usual LED package, there are actually three LEDs, one red, one green and yes, one blue. By controlling the brightness of each of the individual LEDs you can mix pretty much any color you want.

We mix colors just like you would mix audio with a 'mixing board' or paint on a palette - by adjusting the brightness of each of the three LEDs. The hard way to do this would be to use

different value resistors (or variable resistors) as we played with in lesson 2. That's a lot of work! Fortunately for us, UNO R3 board has an analogWrite function that you can use with pins marked with a ~ to output a variable amount of power to the appropriate LEDs.

The RGB LED has four leads. There is one lead going to the positive connection of each of the single LEDs within the package and a single lead that is connected to all three negative sides of the LEDs.



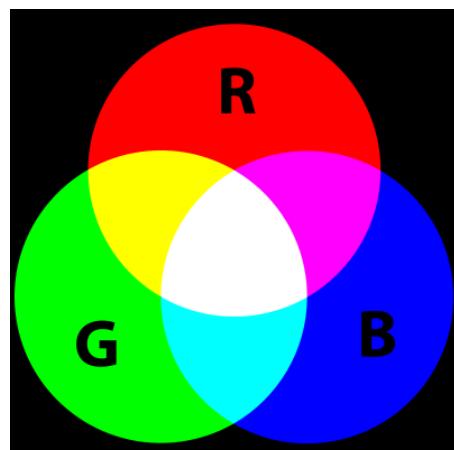
The common negative connection of the LED package is the second pin from the flat side of the LED package. It is also the longest of the four leads. This lead will be connected to ground.

Each LED inside the package requires its own 270Ω resistor to prevent too much current flowing through it. The three positive leads of the LEDs (one red, one green and one blue) are connected to UNO output pins using these resistors.

COLOR:

The reason that you can mix any color you like by varying the quantities of red, green and blue light is that your eye has three types of light receptor in it (red, green and blue). Your eye and brain process the amounts of red, green and blue and convert it into a color of the spectrum.

In a way, by using the three LEDs we are playing a trick on the eye. This same idea is used in TVs, where the LCD has red, green and blue color dots next to each other making up each pixel.



If we set the brightness of all three LEDs to be the same, then the overall color of the light will be white. If we turn off the blue LED, so that just the red and green LEDs are the same brightness, then the light will appear yellow.

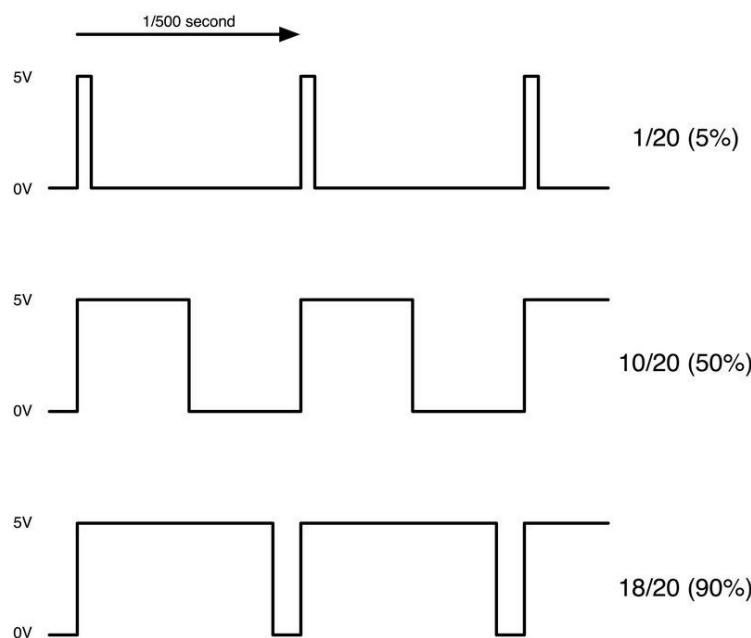
We can control the brightness of each of the red, green and blue parts of the LED separately, making it possible to mix any color we like.

Black is not so much a color as an absence of light. So the closest we can come to black with our LED is to turn off all three colors.

Theory(PWM)

Pulse Width Modulation (or PWM) is a technique for controlling power. We also use it here to control the brightness of each of the LEDs.

The diagram below shows the signal from one of the PWM pins on the UNO.



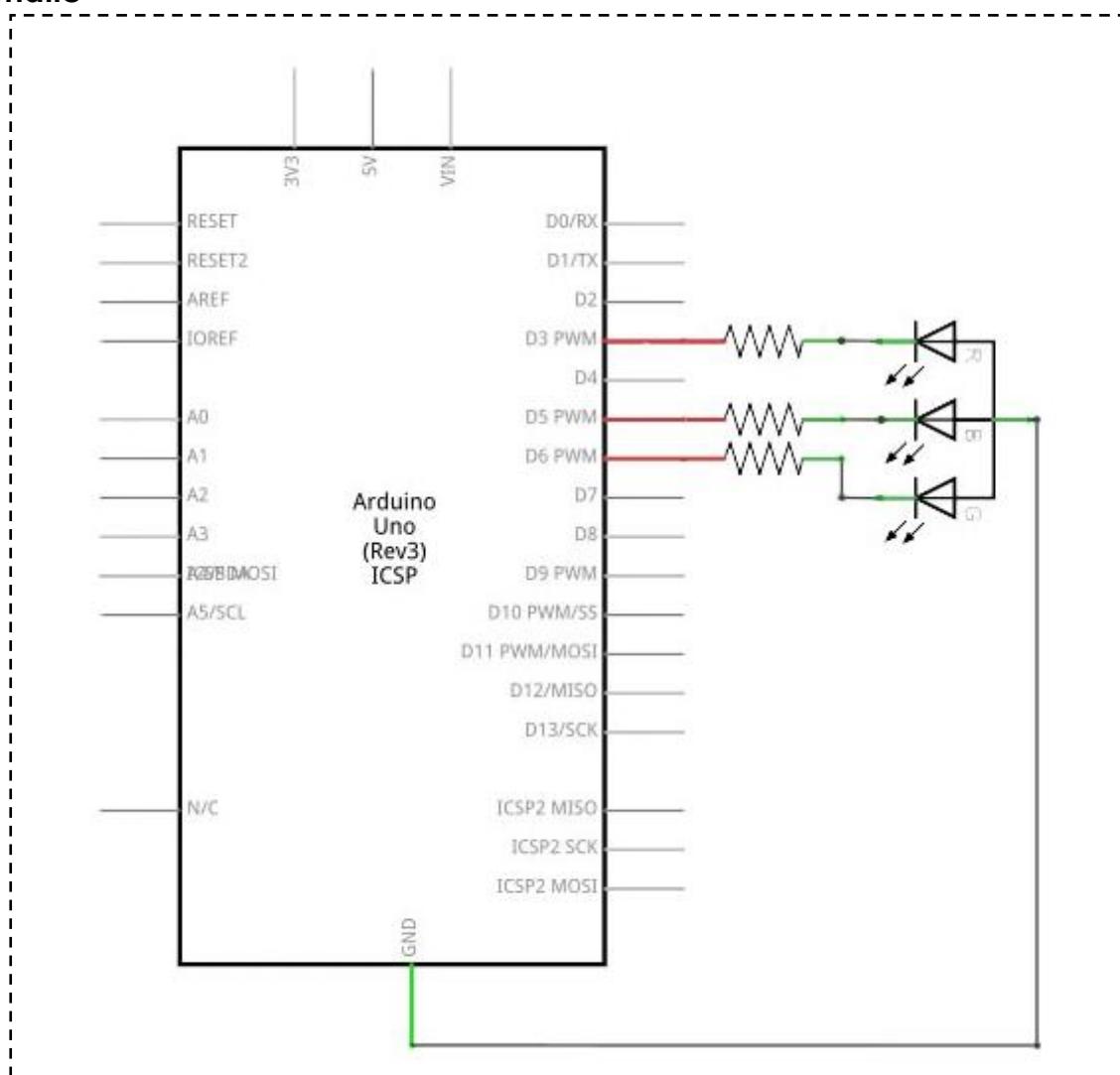
Roughly every 1/500 of a second, the PWM output will produce a pulse. The length of this pulse is controlled by the 'analogWrite' function. So 'analogWrite(0)' will not produce any pulse at all and 'analogWrite(255)' will produce a pulse that lasts all the way until the next pulse is due, so that the output is actually on all the time.

If we specify a value in the analogWrite that is somewhere in between 0 and 255 then we will produce a pulse. If the output pulse is only high for 5% of the time then whatever we are driving will only receive 5% of full power.

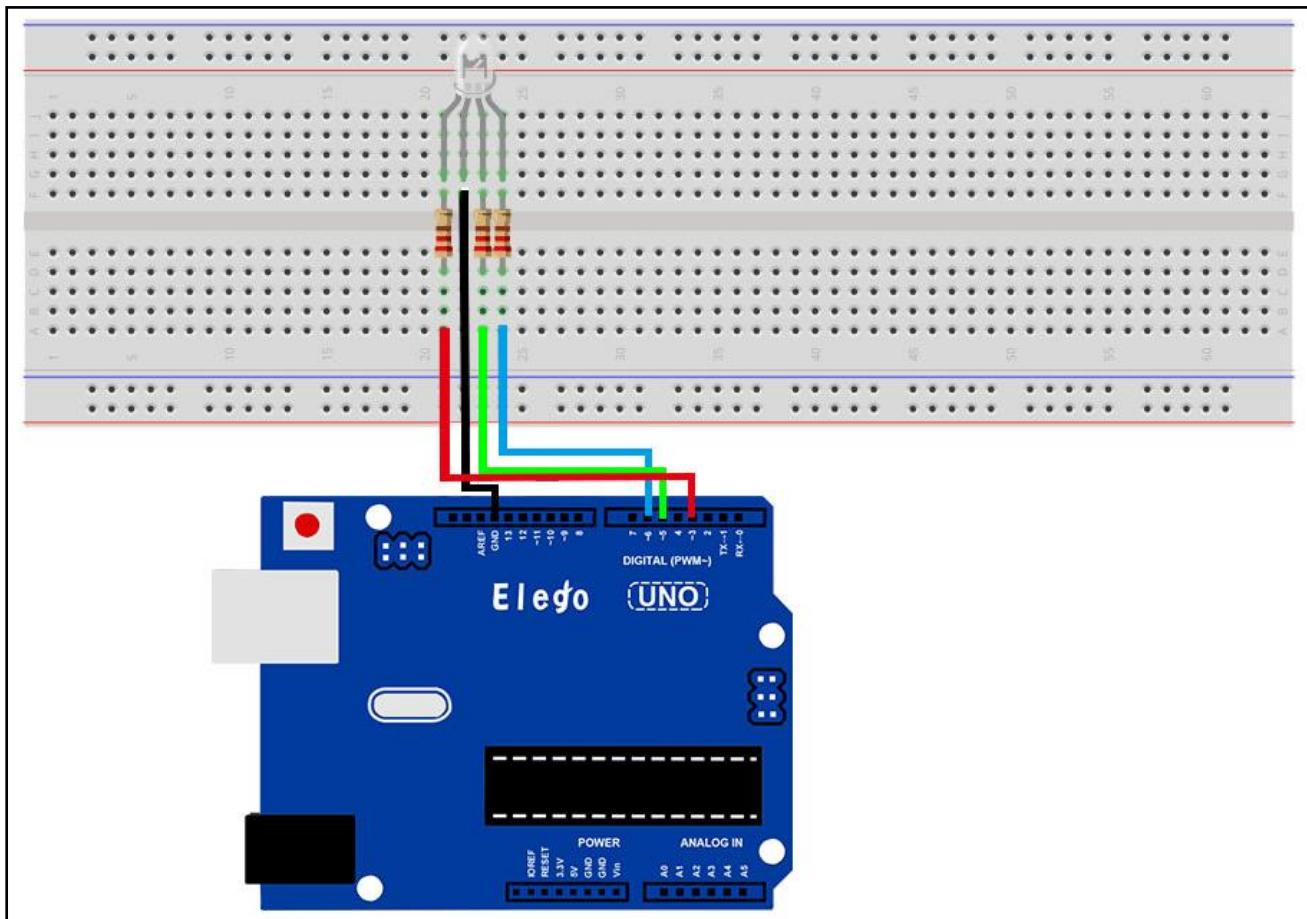
If however the output is at 5V for 90% of the time then the load will get 90% of the power delivered to it. We cannot see the LEDs turning on and off at that speed, so to us, it just looks like the brightness is changing.

Connection

Schematic



wiring diagram



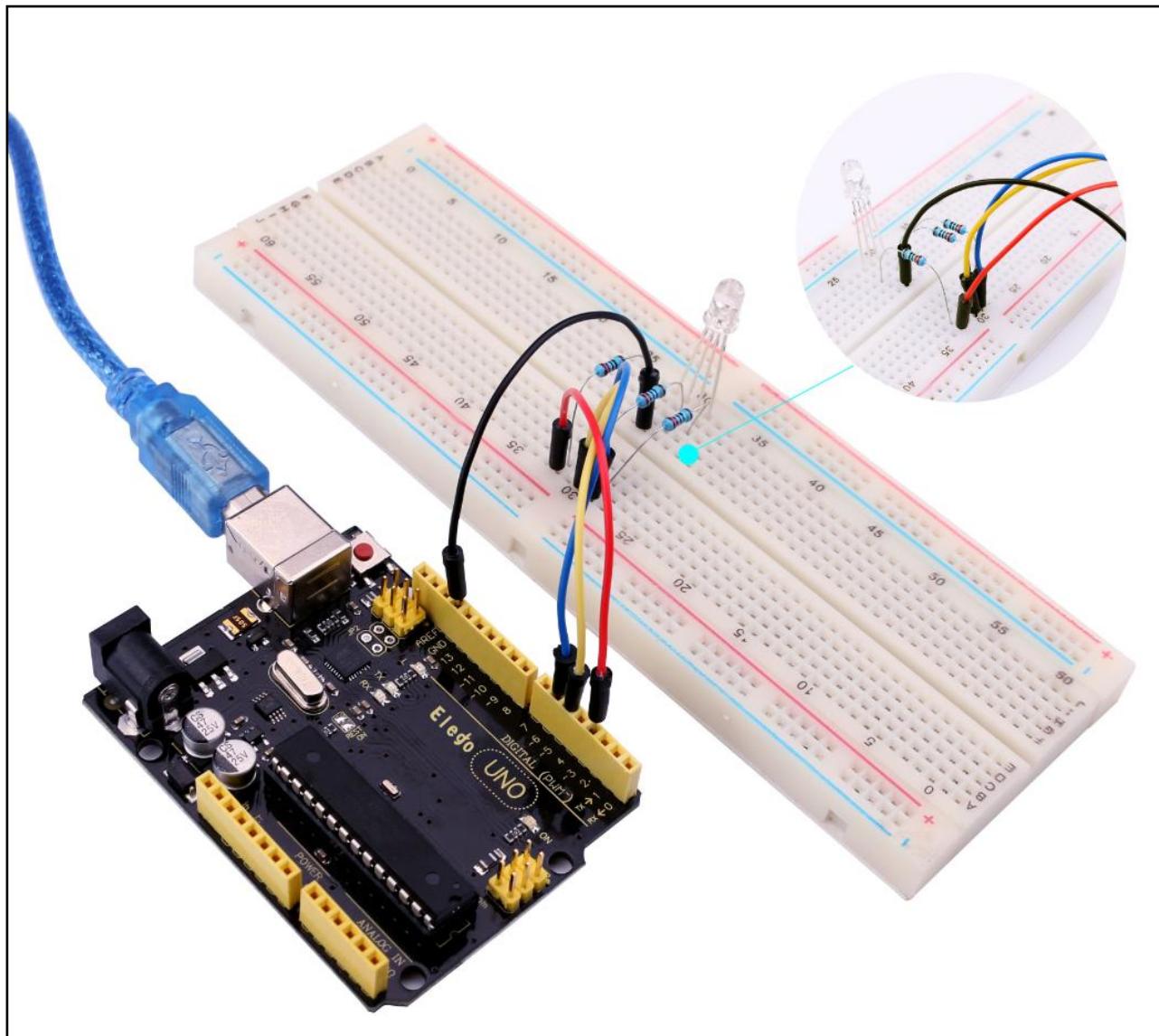
The Code

Our code will use FOR loops to cycle through the colors.

The First FOR loop will go from RED to GREEN

The Second FOR will go from GREEN to BLUE

and finally the last FOR will go from BLUE to RED.



Lesson 5 Digital Inputs

Overview

In this lesson, you will learn to use push buttons with digital inputs to turn an LED on and off.

Pressing the button nearer the top of the breadboard will turn the LED on, pressing the other button will turn the LED off.

Component Required:

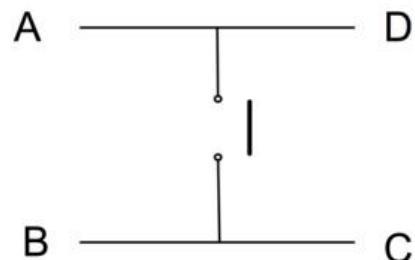
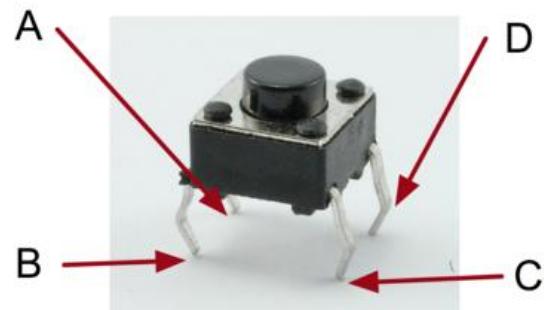
- (1) x Elego Uno R3
- (1) x Breadboard
- (1) x 5mm red LED
- (1) x 220 ohm resistor
- (2) x push switches
- (6) x M-M wires

Component Introduction

PUSH SWITCHES:

Switches are really simple components. When you press a button or flip a lever, they connect two contacts together so that electricity can flow through them.

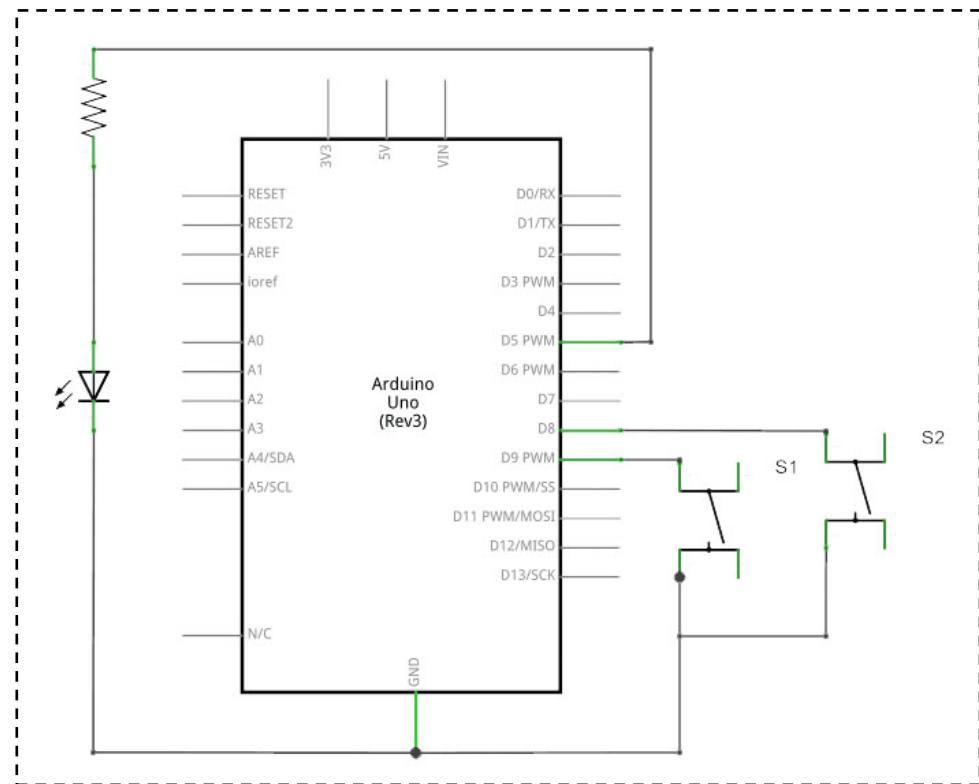
The little tactile switches that are used in this lesson have four connections, which can be a little confusing.



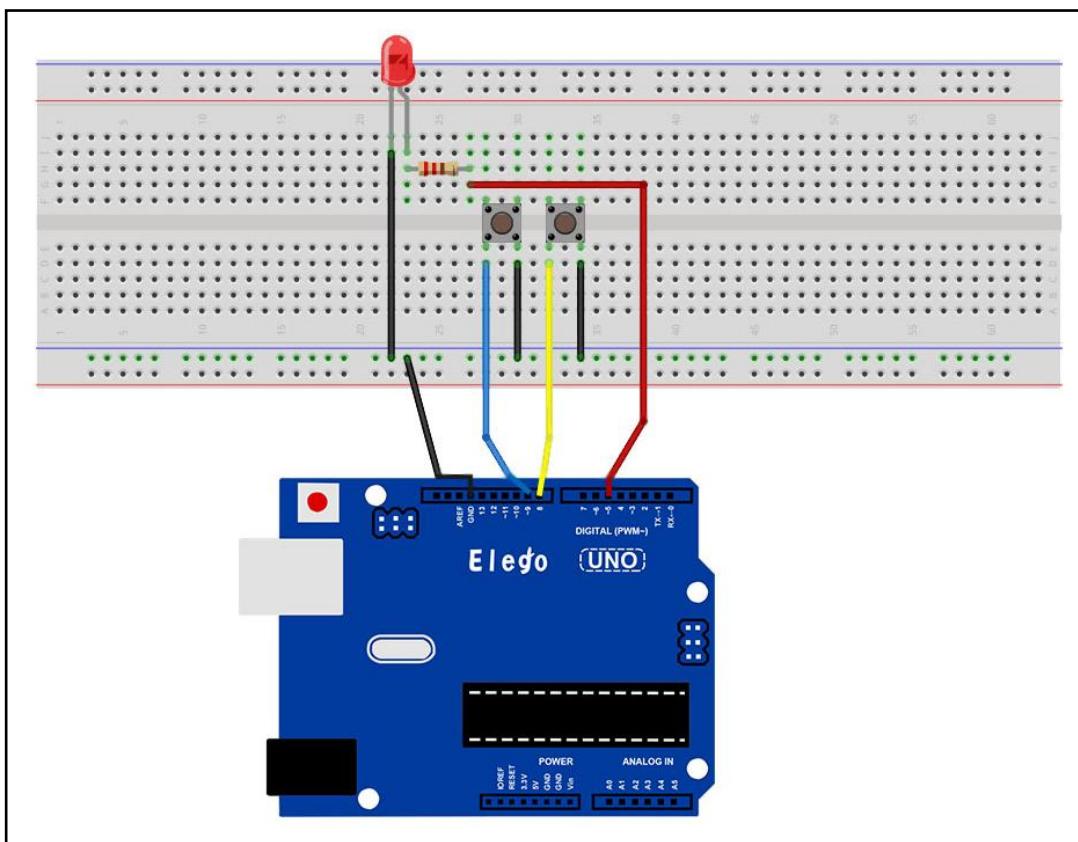
Actually, there are only really two electrical connections, as inside the switch package pins B and C are connected together, as are A and D.

Connection

Schematic



wiring diagram



Although the bodies of the switches are square, the pins protrude from opposite sides of the switch. This means that the pins will only be far enough apart when they are the correct way around on the breadboard.

Remember that the LED has to be the correct way around with the shorter negative lead to the right.

The Code

Load the sketch onto your UNO board. Pressing the top button will turn the LED on, pressing the bottom button will turn it off again.

The first part of the sketch defines three variable for the three pins that are to be used. The 'ledPin' is the output pin and 'buttonApin' will refer to the switch nearer the top of the breadboard and 'buttonBpin' to the other switch.

The 'setup' function defines the ledPin as being an OUTPUT as normal, but now we have the two inputs to deal with. In this case, we use the set the pinMode to be 'INPUT_PULLUP' like this:

```
pinMode(buttonApin, INPUT_PULLUP);  
pinMode(buttonBpin, INPUT_PULLUP);
```

The pin mode of INPUT_PULLUP means that the pin is to be used as an input, but that if nothing else is connected to the input it should be 'pulled up' to HIGH. In other words, the default value for the input is HIGH, unless it is pulled LOW by the action of pressing the button.

This is why the switches are connected to GND. When a switch is pressed, it connects the input pin to GND, so that it is no longer HIGH.

Since the input is normally HIGH and only goes LOW, when the button is pressed, the logic is a little up-side-down. We will handle this in the 'loop' function.

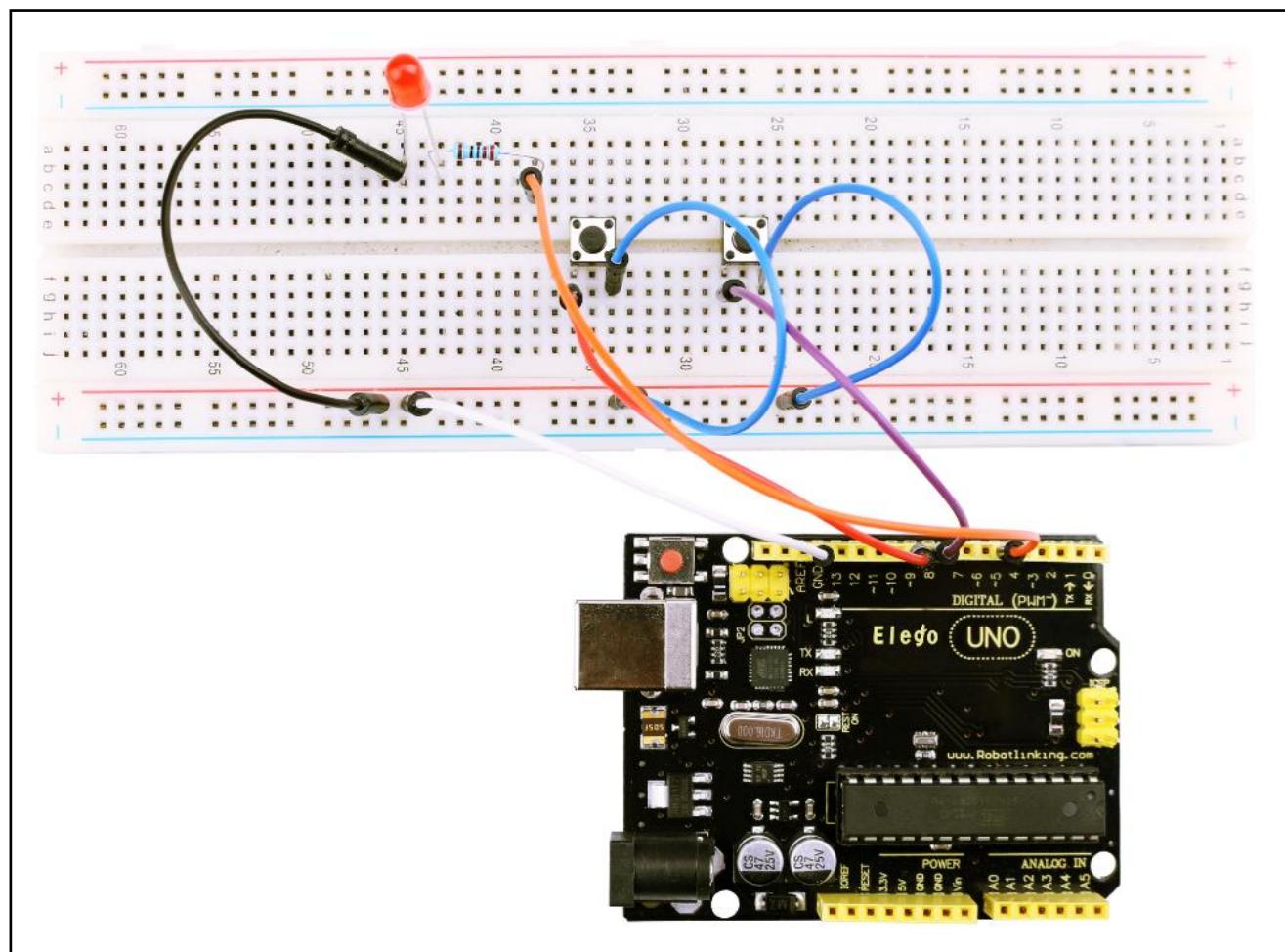
```
void loop()  
{  
    if (digitalRead(buttonApin) == LOW)  
    {  
        digitalWrite(ledPin, HIGH);  
    }  
}
```

```
if (digitalRead(buttonBpin) == LOW)
{
    digitalWrite(ledPin, LOW);
}
}
```

In the 'loop' function there are two 'if' statements. One for each button. Each does an 'digitalRead' on the appropriate input.

Remember that if the button is pressed, the corresponding input will be LOW, if button A is low, then a 'digitalWrite' on the ledPin turns it on.

Similarly, if button B is pressed, a LOW is written to the ledPin.



Lesson 6 Eight LED with 74HC595

Overview

In this lesson, you will learn how to use eight large red LEDs with an UNO without needing to give up 8 output pins!

Although you could wire up eight LEDs each with a resistor to an UNO pin you would rapidly start to run out of pins on your UNO. If you don't have a lot of stuff connected to your UNO. It's OK to do so - but often times we want buttons, sensors, servos, etc and before you know it you've got no pins left. So, instead of doing that, you are going to use a chip called the 74HC595 Serial to Parallel Converter. This chip has eight outputs (perfect) and three inputs that you use to feed data into it a bit at a time.

This chip makes it a little slower to drive the LEDs (you can only change the LEDs about 500,000 times a second instead of 8,000,000 a second) but it's still really fast, way faster than humans can detect, so it's worth it!

Component Required:

(1) x Elego Uno R3

(1) x Breadboard

(8) x led

(8) x 220 ohm resistors

(1) x Breadboard

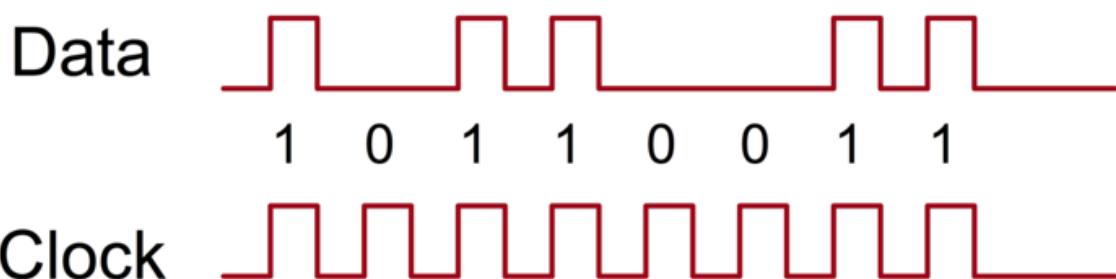
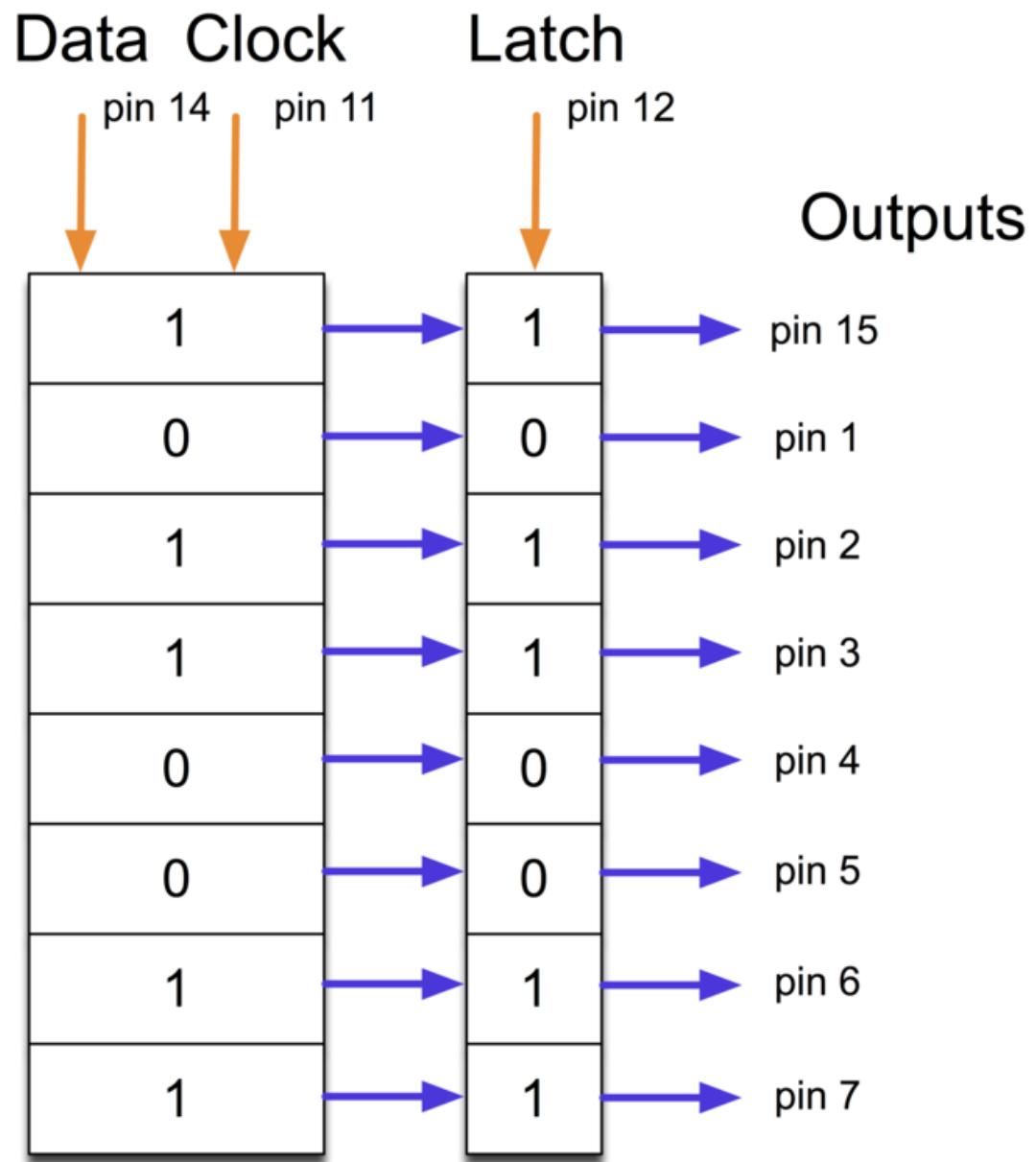
(1) x 74hc595 ic

(14) x M-M wires

Component Introduction

74HC595 Shift Register:

The chip is of a type called a shift register.



The shift register holds what can be thought of as eight memory locations, each of which can be a 1 or a 0.

To set each of these values on or off, we feed in the data using the 'Data' and 'Clock' pins of

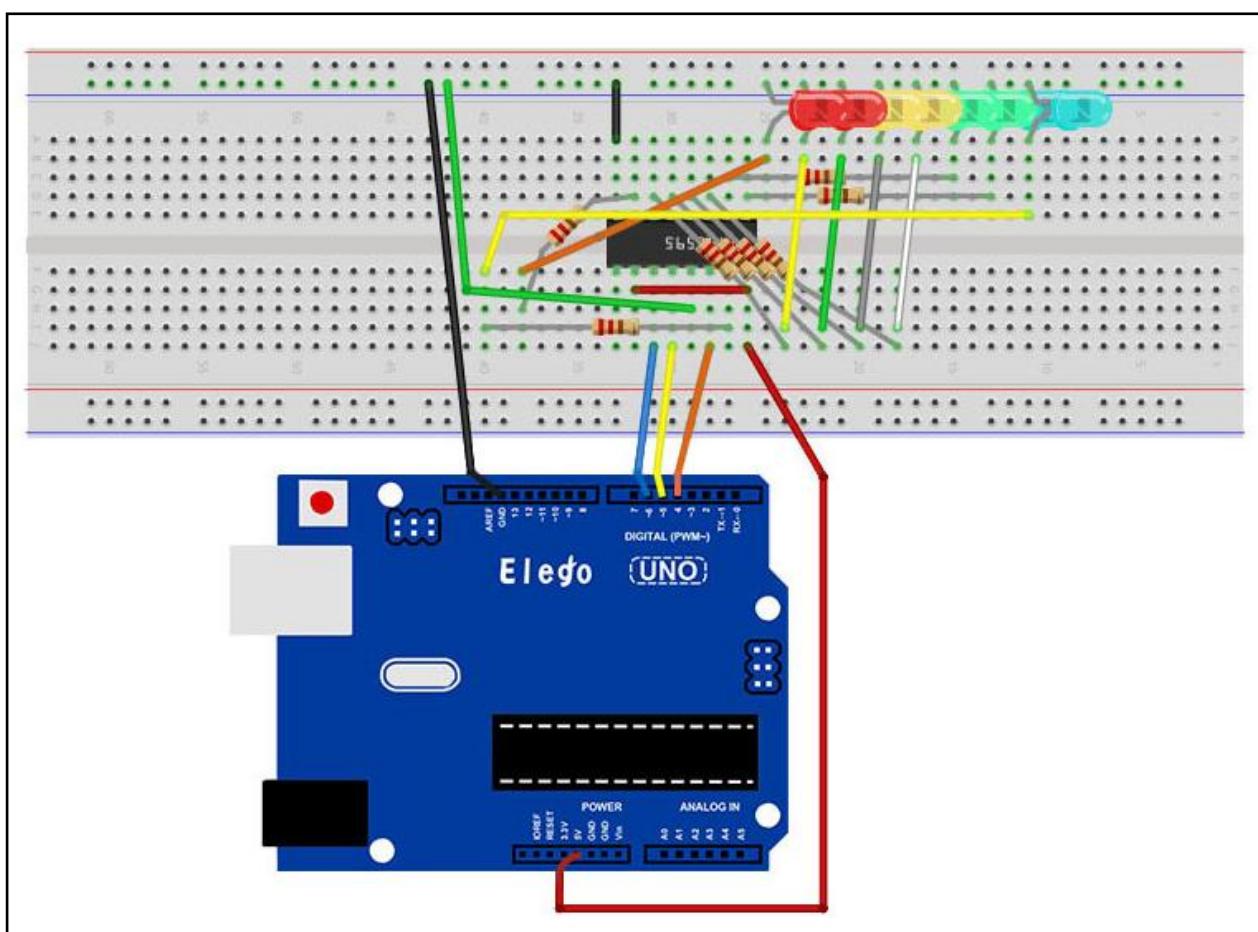
the chip.

The clock pin needs to receive eight pulses, at the time of each pulse, if the data pin is high, then a 1 gets pushed into the shift register, otherwise a 0. When all eight pulses have been received, then enabling the 'Latch' pin copies those eight values to the latch register. This is necessary, otherwise the wrong LEDs would flicker as the data was being loaded into the shift register.

The chip also has an OE (output enable) pin, this is used to enable or disable the outputs all at once. You could attach this to a PWM capable UNO pin and use 'analogWrite' to control the brightness of the LEDs. This pin is active low, so we tie it to GND.

Connection

wiring diagram



As we have eight LEDs and eight resistors to connect up, there are actually quite a few connections to be made.

It is probably easiest to put the 74HC595 chip in first, as pretty much everything else

connects to it. Put it so that the little U-shaped notch is towards the top of the breadboard. Pin 1 of the chip is to the left of this notch.

- Digital 4 from the UNO goes to pin #14 of the shift register
- Digital 5 from the UNO goes to pin #12 of the shift register
- Digital 6 from the UNO goes to pin #11 of the shift register

All but one of the outputs from the '595 are on the left hand side of the chip, hence, for ease of connection, that is where the LEDs are too.

After the chip, put the resistors in place. You need to be careful that none of the leads of the resistors are touching each other. You should check this again, before you connect the power to your UNO. If you find it difficult to arrange the resistors without their leads touching, then it helps to shorten the leads so that they are lying closer to the surface of the breadboard. Next, place the LEDs on the breadboard.

The longer positive LED leads must all be towards the chip, whichever side of the breadboard they are on.

It now just remains to attach the jumper leads as shown above. Do not forget the one that goes from pin 8 of the IC to the GND column of the breadboard.

Load up the sketch listed a bit later and try it out. Each LED should light in turn until all the LEDs are on, and then they all go off and the cycle repeats.

The Code

The first thing we do is define the three pins we are going to use. These are the UNO digital outputs that will be connected to the latch, clock and data pins of the 74HC595.

```
int latchPin = 5;  
int clockPin = 6;  
int dataPin = 4;
```

Next, a variable called 'leds' is defined. This will be used to hold the pattern of which LEDs are currently turned on or off. Data of type 'byte' represents numbers using eight bits. Each bit can be either on or off, so this is perfect for keeping track of which of our eight LEDs are on or off.

```
byte leds = 0;
```

The 'setup' function just sets the three pins we are using to be digital outputs.

```
void setup()
{
    pinMode(latchPin, OUTPUT);
    pinMode(dataPin, OUTPUT);
    pinMode(clockPin, OUTPUT);
}
```

The 'loop' function initially turns all the LEDs off, by giving the variable 'leds' the value 0. It then calls 'updateShiftRegister' that will send the 'leds' pattern to the shift register so that all the LEDs turn off. We will deal with how 'updateShiftRegister' works later.

The loop function pauses for half a second and then begins to count from 0 to 7 using the 'for' loop and the variable 'i'. Each time, it uses the Arduino function 'bitSet' to set the bit that controls that LED in the variable 'leds'. It then also calls 'updateShiftRegister' so that the leds update to reflect what is in the variable 'leds'.

There is then a half second delay before 'i' is incremented and the next LED is lit.

```
void loop()
{
    leds = 0;
    updateShiftRegister();
    delay(500);
    for (int i = 0; i < 8; i++)
    {
        bitSet(leds, i);
        updateShiftRegister();
        delay(500);
    }
}
```

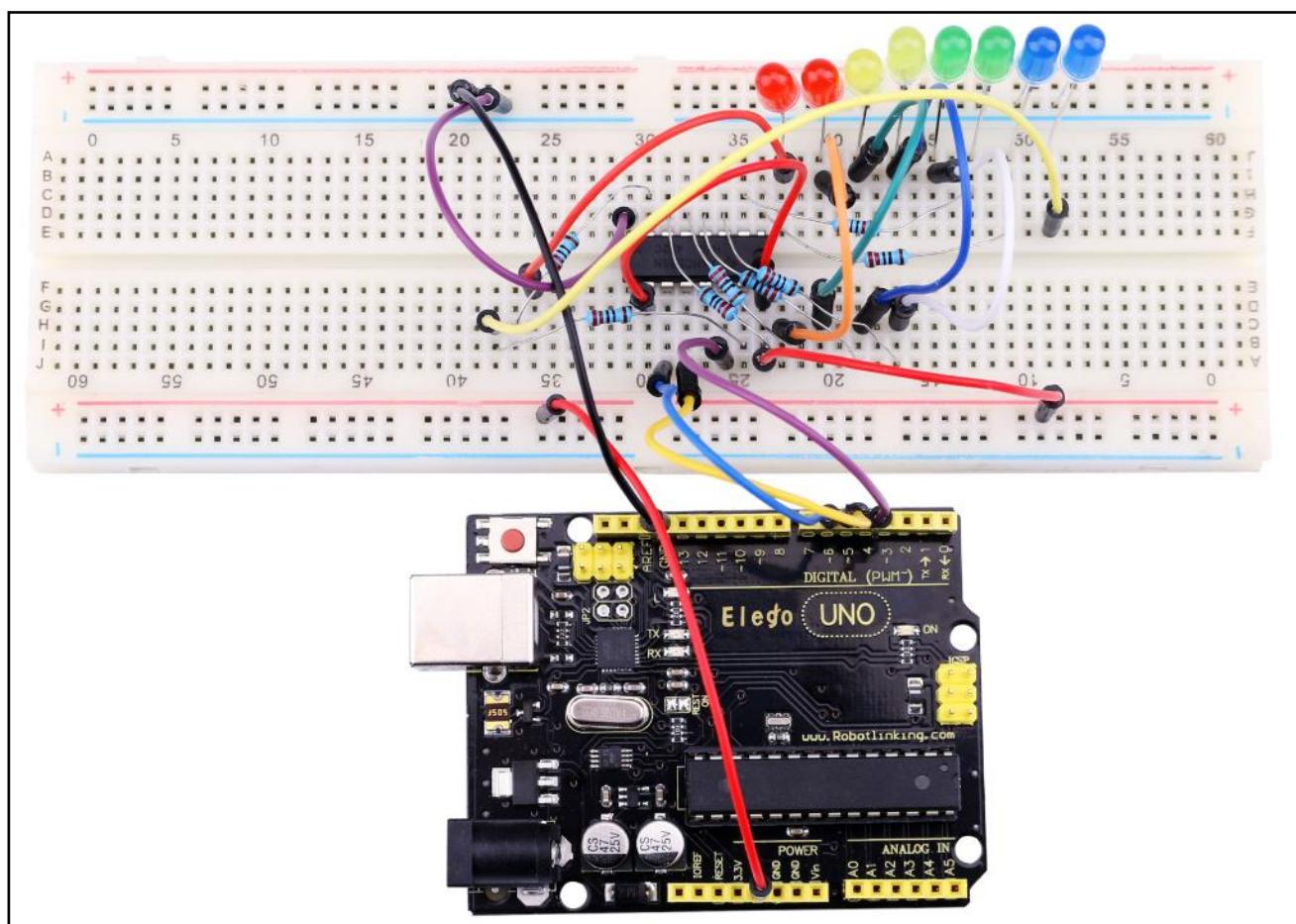
The function 'updateShiftRegister', first of all sets the latchPin to low, then calls the UNO function 'shiftOut' before putting the 'latchPin' high again. This takes four parameters, the first two are the pins to use for Data and Clock respectively.

The third parameter specifies which end of the data you want to start at. We are going to start with the right most bit, which is referred to as the 'Least Significant Bit' (LSB).

The last parameter is the actual data to be shifted into the shift register, which in this case is 'leds'.

```
void updateShiftRegister()
{
    digitalWrite(latchPin, LOW);
    shiftOut(dataPin, clockPin, LSBFIRST, leds);
    digitalWrite(latchPin, HIGH);
}
```

If you wanted to turn one of the LEDs off rather than on, you would call a similar Arduino function (`bitClear`) on the 'leds' variable. This will set that bit of 'leds' to be 0 and you would then just need to follow it with a call to 'updateShiftRegister' to update the actual LEDs.



Lesson 7 The Serial Monitor

Overview

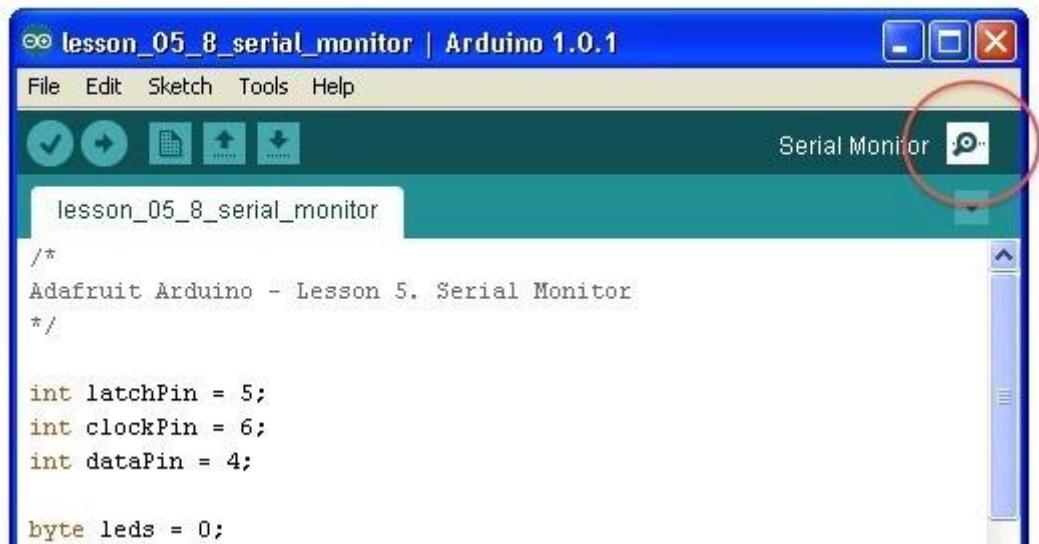
In this lesson, you will build on lesson 6, adding the facility to control the LEDs from your computer using the Arduino Serial Monitor. The serial monitor is the 'tether' between the computer and your UNO - it lets you send and receive text messages, handy for debugging and also controlling the UNO from a keyboard!

For example, you will be able to send commands from your computer to turn on LEDs.

In this lesson, you will use exactly the same parts and a similar breadboard layout as Lesson 6. So, if you have not already done so, follow lesson 6 now.

Steps taken

After you have uploaded this sketch onto your UNO, click on the right-most button on the toolbar in the Arduino IDE. The button is circled below.



The following window will open.

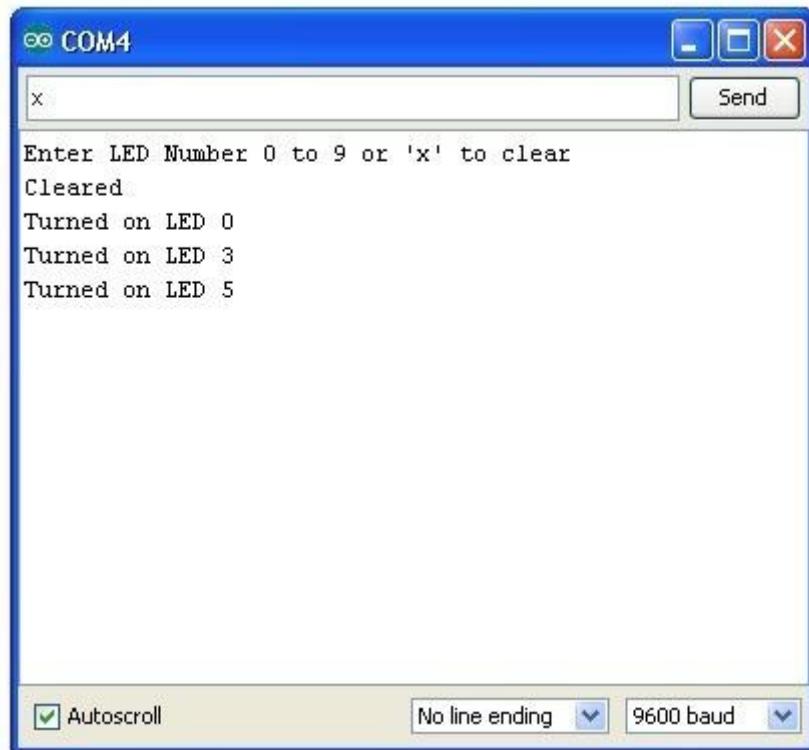


This window is called the Serial Monitor and it is part of the Arduino IDE software. Its job is to allow you to both send messages from your computer to an UNO board (over USB) and also to receive messages from the UNO.

The message "Enter LED Number 0 to 9 or 'x' to clear" has been sent by the Arduino, and it is telling us what commands we can send to the Arduino which is either to send the 'x' (to turn all the LEDs off) or the number of the LED you want to turn on (where 0 is the bottom LED, 1 is the next one up right up to 7 for the top LED).

Try typing the following commands, into the top area of the Serial Monitor that is level with the 'Send' button. Press 'Send', after typing each of these characters: x 0 3 5

Typing x, will have no effect, if the LEDs are already all off, but as you enter each number, the corresponding LED should light and you will get a confirmation message from the UNO board, so that the Serial Monitor will appear as shown below.



You can see that I am about to press send after entering 'x' again. Do this and all the LEDs will turn off.

The Code

As you might expect, the sketch is based on the sketch used in lesson 6. So, we will just cover the new bits here. You will find it useful to refer to the full sketch in your Arduino IDE.

Firstly, in the 'setup' function, there are three new lines on the end:

```
void setup()
{
    pinMode(latchPin, OUTPUT);
    pinMode(dataPin, OUTPUT);
    pinMode(clockPin, OUTPUT);
    updateShiftRegister();
    Serial.begin(9600);
    while (! Serial); // Wait until Serial is ready - Leonardo
    Serial.println("Enter LED Number 0 to 7 or 'x' to clear");
```

```
}
```

Firstly, we have the command 'Serial.begin(9600)'. This starts serial communication, so that the UNO can send out commands through the USB connection. The value 9600 is called the 'baud rate' of the connection. This is how fast the data is to be sent. You can change this to a higher value, but you will also have to change the Arduino Serial monitor to the same value. We will discuss this later, but for now leave it at 9600.

The line beginning with 'while' ensures that there is something at the other end of the USB connection for the Arduino to talk to before it starts sending messages. Otherwise, the message might be sent, but not displayed. This line is actually only necessary if you are using an Arduino Leonardo, because the Arduino Uno automatically resets the Arduino board when you open the Serial Monitor, whereas this does not happen with the Leonardo.

The last of the new lines in 'setup' sends out the message that we see at the top of the serial monitor.

The 'loop' function is where all the action happens:

```
void loop()
{
    if (Serial.available())
    {
        char ch = Serial.read();
        if (ch >= '0' && ch <= '7')
        {
            int led = ch - '0';
            bitSet(leds, led);
            updateShiftRegister();
            Serial.print("Turned on LED ");
            Serial.println(led);
        }
        if (ch == 'x')
        {
            leds = 0;
        }
    }
}
```

```
    updateShiftRegister();
    Serial.println("Cleared");
}
}
```

Everything that happens inside the loop is contained within an 'if' statement. So unless the call to the built-in Arduino function 'Serial.available()' is 'true' then nothing else will happen. Serial.available() will return 'true' if data has been send to the UNO and is there ready to be processed. Incoming messages are held in what is called a buffer and Serial.available() returns true if that buffer is Not empty.

If a message has been received, then its on to the next line of code:

```
char ch = Serial.read();
```

This reads the next character from the buffer, and removes it from the buffer. It also assigns it to the variable 'ch'. The variable 'ch' is of type 'char' which stands for 'character' and as the name suggests, holds a single character.

If you have followed the instructions in the prompt at the top of the Serial Monitor, then this character will either be a single digit number between 0 and 7 or the letter 'x'.

The 'if' statement on the next line checks to see if it is a single digit by seeing if 'ch' is greater than or equal to the character '0' and less than or equal to the character '7'. It looks a little strange comparing characters in this way, but is perfectly acceptable.

Each character is represented by a unique number, called its ASCII value. This means that when we compare characters using `<=` and `>=` it is actually the ASCII values that were being compared.

If the test passes, then we come to the next line:

```
int led = ch - '0';
```

Now we are performing arithmetic on characters! We are subtracting the digit '0' from whatever digit was entered. So, if you typed '0' then '0' – '0' will equal 0. If you typed '7' then '7' – '0' will equal the number 7 because it is actually the ASCII values that are being used in the subtraction.

Since that we know the number of the LED that we want to turn on, we just need to set that bit in the variable 'leds' and update the shift register.

```
bitSet(leds, led);  
updateShiftRegister();
```

The next two lines write back a confirmation message to the Serial Monitor.

```
Serial.print("Turned on LED ");  
Serial.println(led);
```

The first line uses `Serial.print` rather than `Serial.println`. The difference between the two is that `Serial.print` does not start a new line after printing whatever is in its parameter. We use this in the first line, because we are printing the message in two parts. Firstly the general bit: 'Turned on LED ' and then the number of the LED.

The number of the LED is held in an 'int' variable rather than being a text string. `Serial.print` can take either a text string enclosed in double-quotes, or an 'int' or for that matter pretty much any type of variable.

After the 'if' statement that handles the case, when a single digit has been handled, there is a second 'if' statement that checks to see if 'ch' is the letter 'x'.

```
if (ch == 'x')  
{  
    leds = 0;  
    updateShiftRegister();  
    Serial.println("Cleared");  
}
```

If it is, then it clears all the LEDs and sends a confirmation message.

Lesson 8 Photocell

Overview

In this lesson, you will learn how to measure light intensity using an Analog Input. You will build on lesson 8 and use the level of light to control the number of LEDs to be lit.

The photocell is at the bottom of the breadboard, where the pot was above.

Component Required:

(1) x Elego Uno R3

(1) x Breadboard

(8) x led

(8) x 220 ohm resistors

(1) x 1k ohm resistors

(1) x Breadboard

(1) x 74hc595 ic

(1) x Photocell

(14) x M-M wires

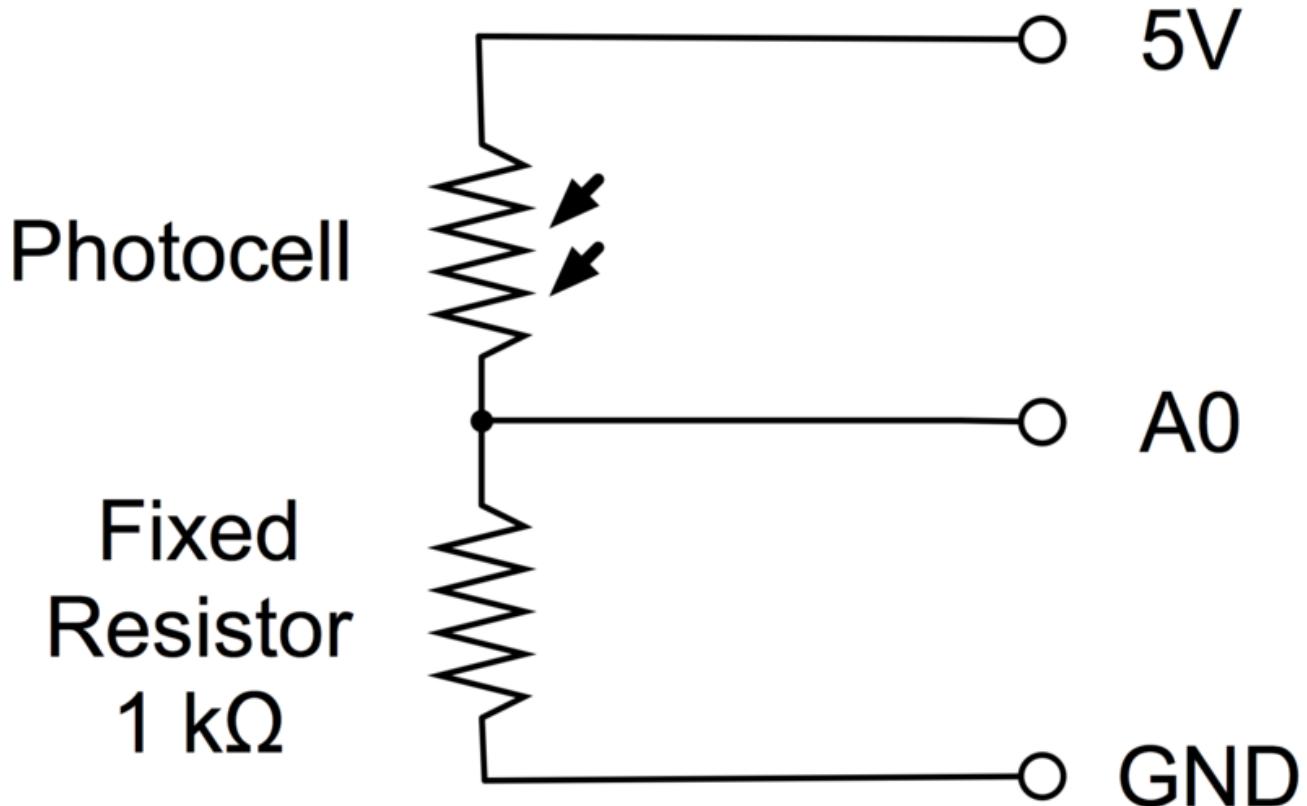
Component Introduction

PHOTOCELL:

The photocell used is of a type called a light dependent resistor, sometimes called an LDR. As the name suggests, these components act just like a resistor, except that the resistance changes in response to how much light is falling on them.

This one has a resistance of about $50\text{ k}\Omega$ in near darkness and $500\ \Omega$ in bright light. To convert this varying value of resistance into something we can measure on an UNO R3 board's analog input, it need to be converted into a voltage.

The simplest way to do that is to combine it with a fixed resistor.



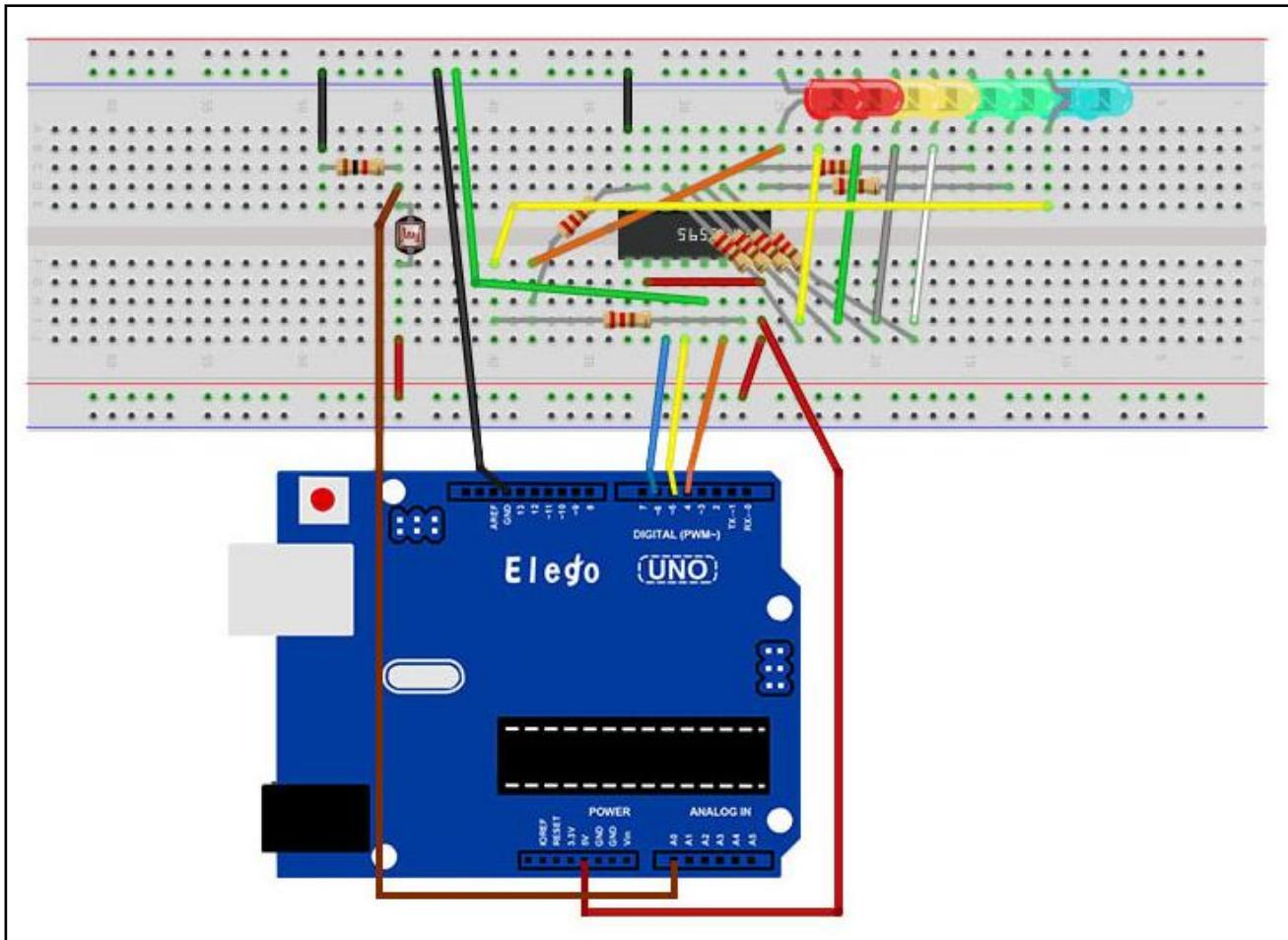
The resistor and photocell together behave rather like a pot. When the light is very bright, then the resistance of the photocell is very low compared with the fixed value resistor, and so it is as if the pot were turned to maximum.

When the photocell is in dull light the resistance becomes greater than the fixed 1kΩ resistor and it is as if the pot were being turned towards GND.

Load up the sketch given in the next section and try covering the photocell with your finger, and holding it near a light source.

Connection

wiring diagram



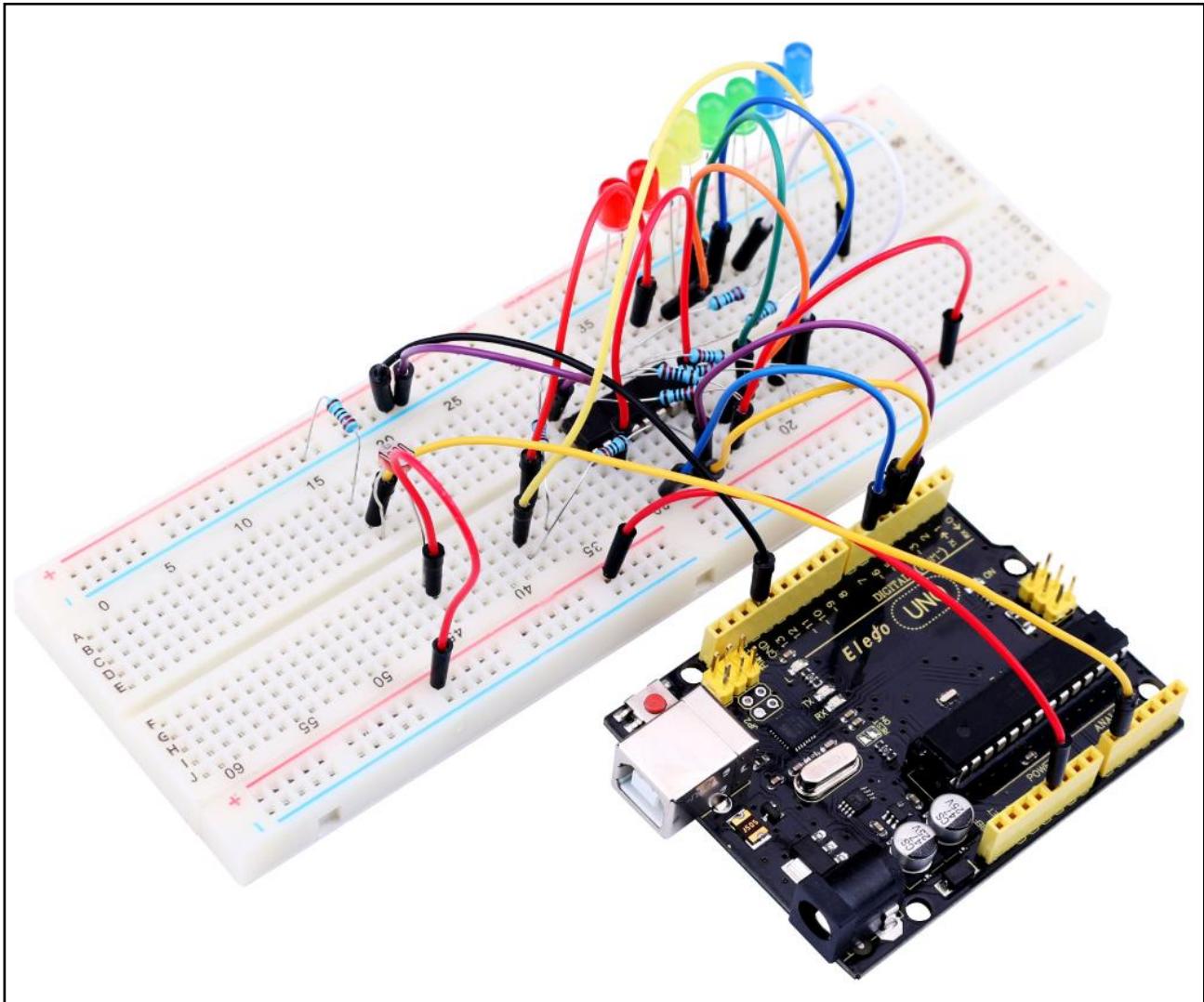
The Code

The first thing to note is that we have changed the name of the analog pin to be 'lightPin' rather than 'potPin' since we no longer have a pot connected.

The only other substantial change to the sketch is the line that calculate how many of the LEDs to light:

```
int numLEDSLit = reading / 57; // all LEDs lit at 1k
```

This time we divide the raw reading by 57 rather than 114 from lesson 8. In other words we divide it by half as much as we did with the pot, to split it into nine zones, from no LEDs lit, to all eight lit. This extra factor is to account for the fixed 1 kΩ resistor. This means that when the photocell has a resistance of 1 kΩ (the same as the fixed resistor) the raw reading will be $1023 / 2 = 511$. This will equate to all the LEDs being lit and then a bit (numLEDSLit will be 9).



Lesson 9 Making Sounds

Overview

In this lesson, you will learn how to make sound with a active buzzer.

Component Required:

- (1) x Elego Uno R3
- (1) x Active buzzer
- (2) x F-M wires

Component Introduction

BUZZER:

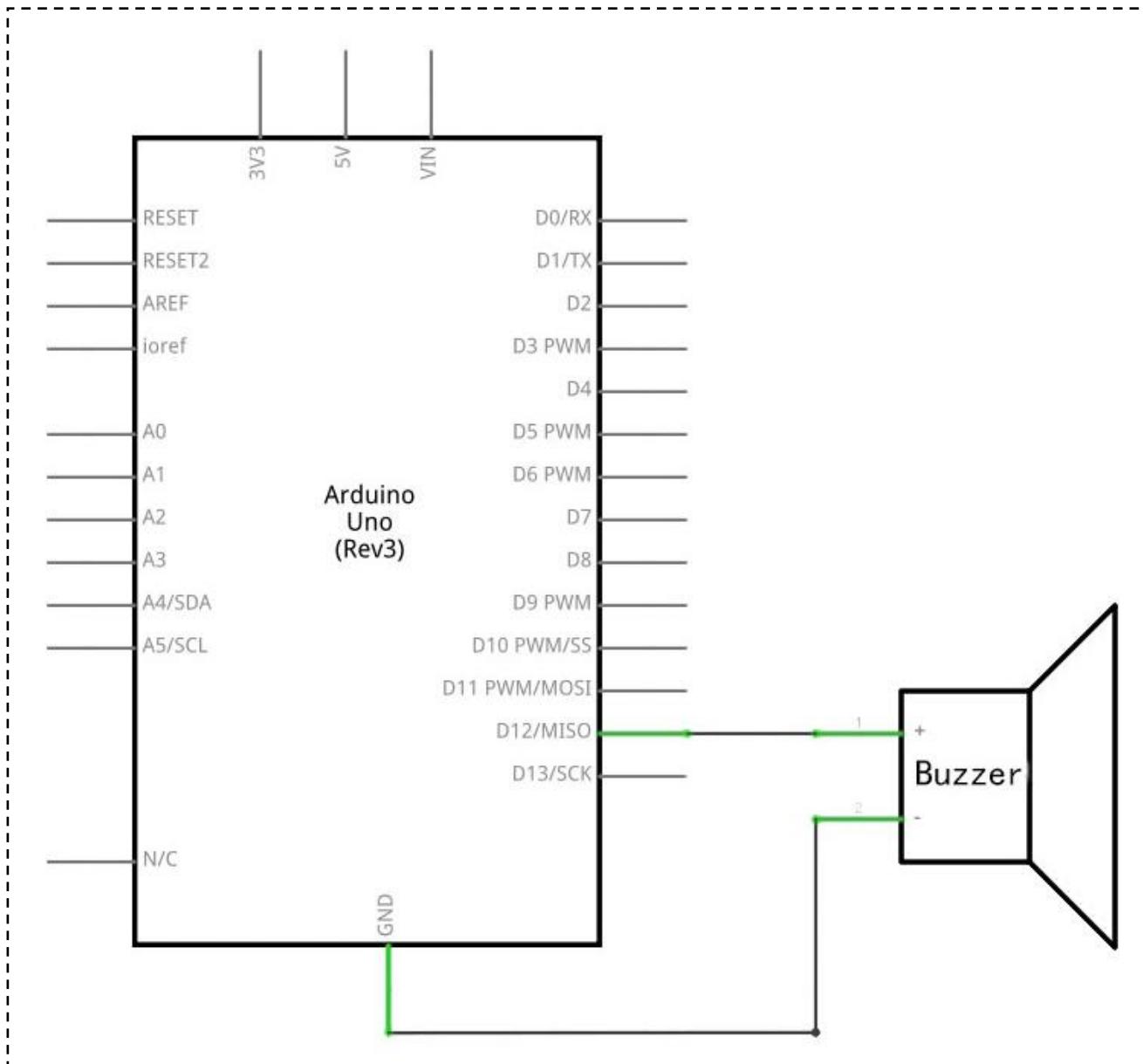
As a type of electronic buzzer with integrated structure, buzzers, which are supplied by DC power, are widely used in computers, printers, photocopiers, alarms, electronic toys, automotive electronic devices, telephones, timers and other electronic products for voice devices. Buzzers can be categorized as active and passive ones (see the following picture). Turn the pins of two buzzers face up, and the one with a green circuit board is a passive buzzer, while the other enclosed with a black tape is an active one.

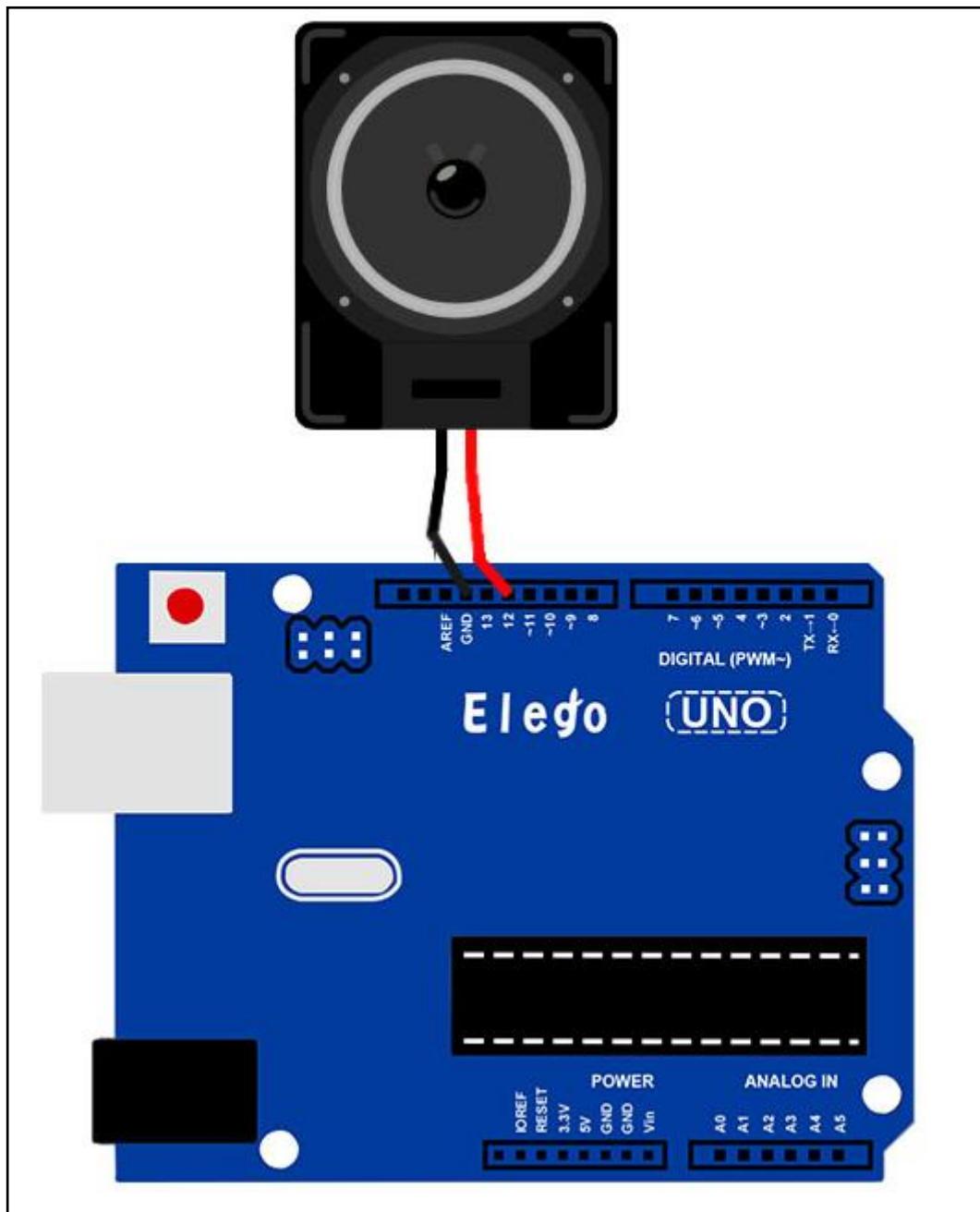
The difference between an active buzzer and a passive buzzer is:

An active buzzer has a built-in oscillating source, so it will make sounds when electrified. But a passive buzzer does not have such source, so it will not tweet if DC signals are used; instead, you need to use square waves whose frequency is between 2K and 5K to drive it. The active buzzer is often more expensive than the passive one because of multiple built-in oscillating circuits.

Connection

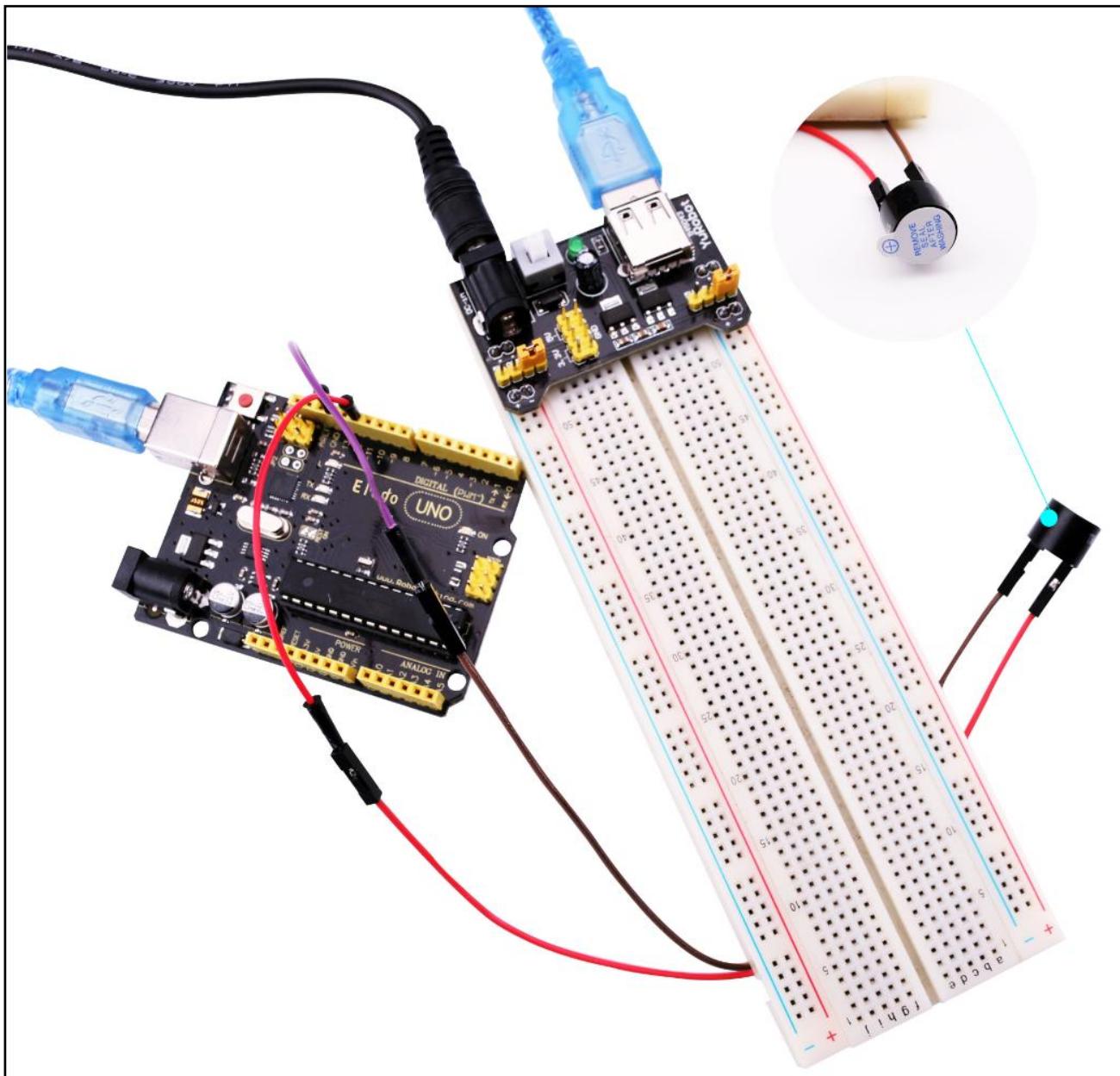
Schematic

**wiring diagram**



The code

See the code file.



Lesson 10 Passive Buzzer

Overview

In this lesson, you will learn how to use a passive buzzer

Purpose of the experiment control buzzer, allowing the buzzer Alto Do (523Hz), Re (587Hz), Mi (659Hz), Fa (698Hz), So (784Hz), La (880Hz), Si (988Hz) to Treble Do (1047Hz). This scale of eight different sounds, each sound scale 0.5 seconds.

Component Required:

- (1) x Elego Uno R3
- (1) x Passive buzzer
- (2) x F-M wires

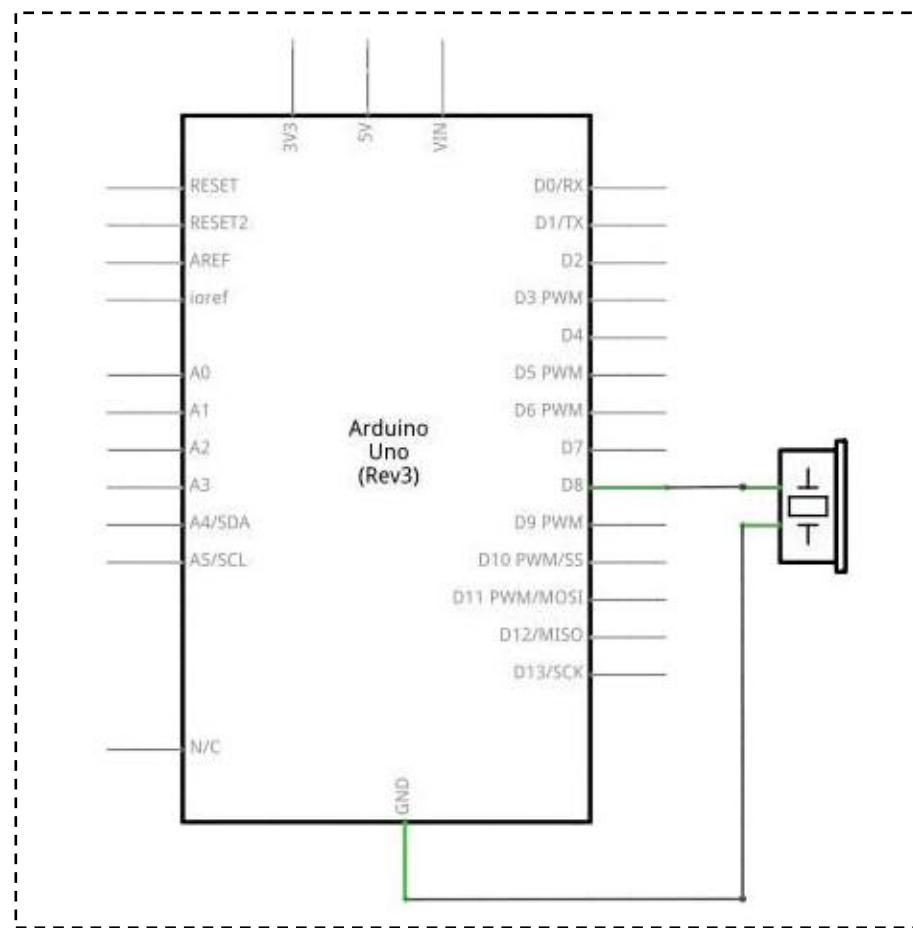
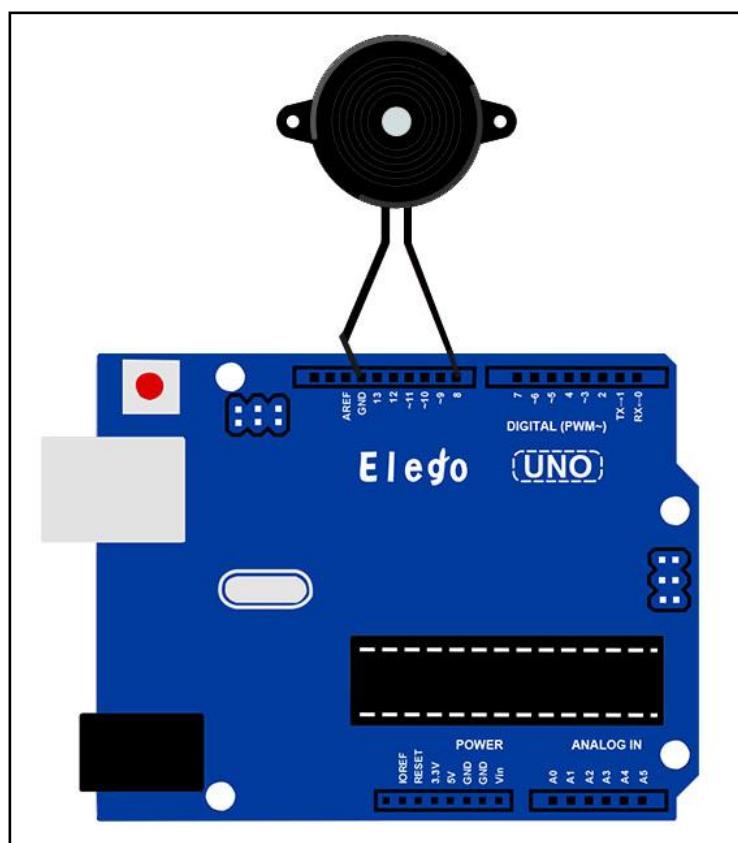
Component Introduction

Passive Buzzer:

Passive buzzer, in fact, just use PWM generating audio, drives the buzzer, allowing the air to vibrate, can sound. Appropriately changed as long as the vibration frequency, it can generate different sound scale. For example, sending a pulse wave can be generated 523Hz Alto Do, pulse 587Hz can produce midrange Re, 659Hz can produce midrange Mi. If you then with a different beat, you can play a song. Here be careful not to use the UNO R3 board analog Write () function to generate a pulse wave, because the frequency analog Write () is fixed (500Hz), no way to scale the output of different sounds.

Connection

Schematic

**wiring diagram**

Wiring the buzzer connected to the UNO R3 board, the red (positive) to the pin8, black wire (negative) to the GND

Description:

L04 ~ L05: definition of alto Do, Re, Mi, So, La, Si and treble Do eight octave frequency, the frequency of each scale is already defined in pitches.h file in, so just find the eight Constant scale and stored in the array to melody.

L06: definition of variable duration, representing each scale response time duration, because the scale to make each sound 0.5 seconds, so the duration is set to 500 (in milisecond)

L13 ~ L19: Let the buzzer Alto Do (523Hz), Re (587Hz), Mi (659Hz), Fa (698Hz), So (784Hz), La (880Hz), Si (988Hz) to treble Do (1047Hz) which eight voices of different scales, each scale ring 0.5 seconds

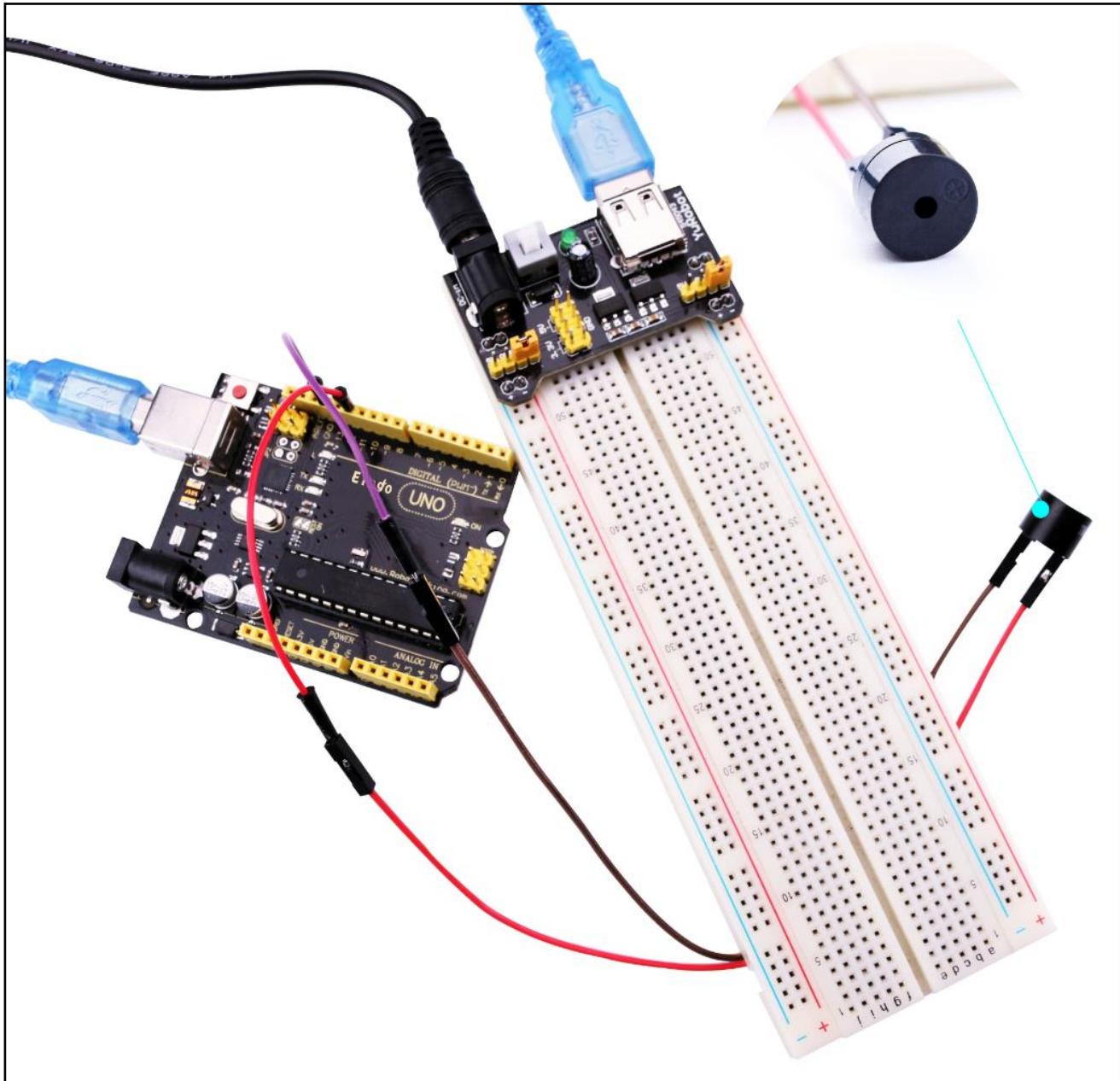
L22: every two seconds, and then replay the content pitches.h stalls:

in this example is based, together with a few LED and modify the program, at the same time to play a sound control LED lights change, so that this paradigm has become a shot in the program. Try to generate an ambulance siren. Tip: Just let the buzzer continuously generate Alto Do (523Hz) and Alto Fa (698Hz), each about 0.8 seconds of sound, you can simulate ambulance siren.

The code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <pitches> library. Or you need to install again. If you do not do this, your code won't work.



Lesson 11 Ball Switch

Overview

In this lesson, you will learn how to use a ball switch.

The ball switch is used to detect small angle of inclination.

Component Required:

- (1) x Elego Uno R3
- (1) x Ball switch
- (2) x F-M wires

Component Introduction

Tilt sensor:

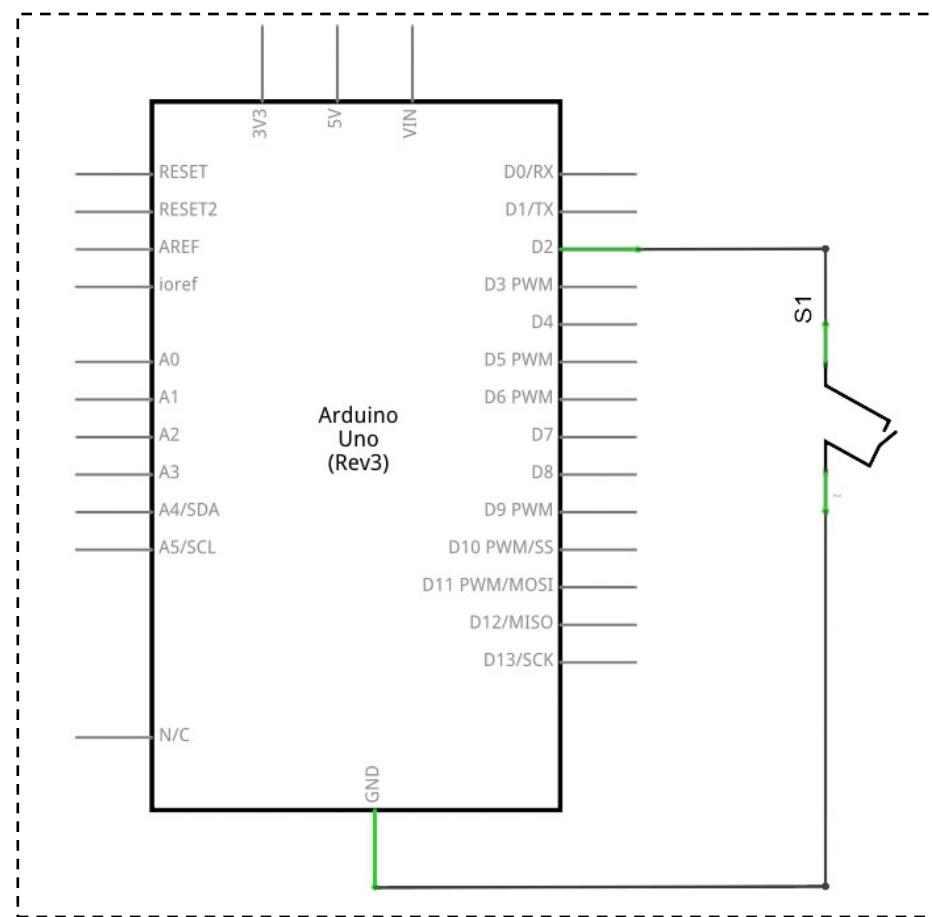
Tilt sensors allow you to detect orientation or inclination. They are small, inexpensive, low-power and easy-to-use. If used properly, they will not wear out. Their simplicity makes them popular for toys, gadgets and appliances. Sometimes they are referred to as "mercury switches", "tilt switches" or "rolling ball sensors" for obvious reasons.

They are usually made by a cavity of some sort (cylindrical is popular, although not always) and a conductive free mass inside, such as a blob of mercury or rolling ball. One end of the cavity has two conductive elements (poles). When the sensor is oriented so that that end is downwards, the mass rolls onto the poles and shorts them, acting as a switch throw.

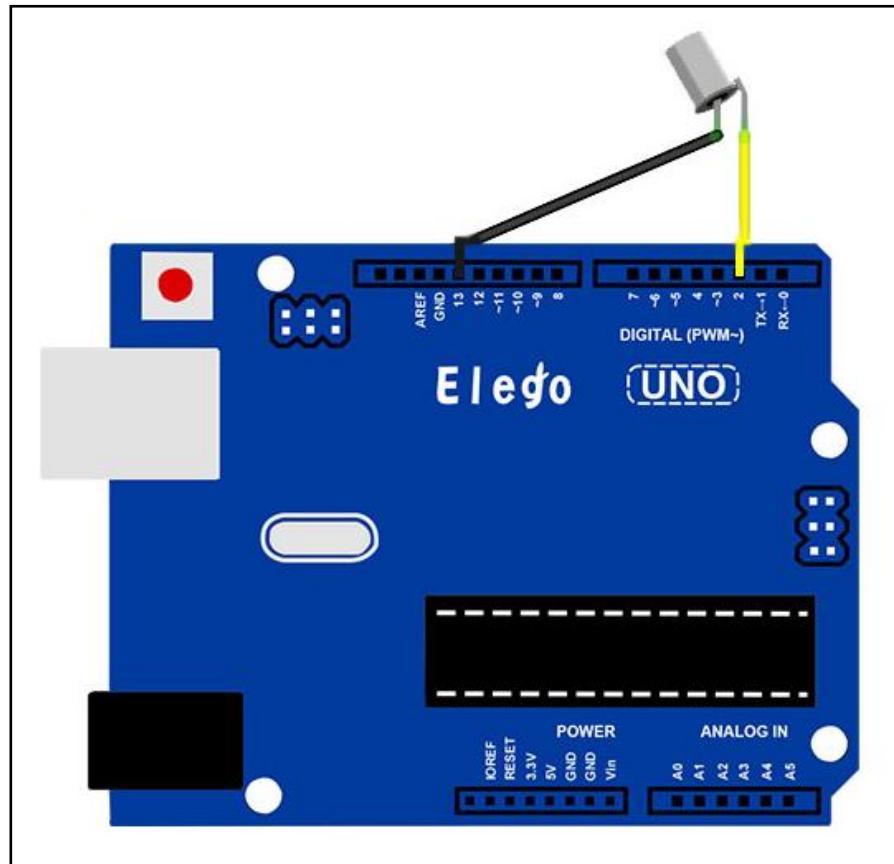
While not as precise or flexible as a full accelerometer, tilt switches can detect motion or orientation simply. Another benefit to them is that the big ones can switch power on their own. Accelerometers, on the other hand, output digital or analog voltage that must then be analyzed with extra circuitry.

Connection

Schematic

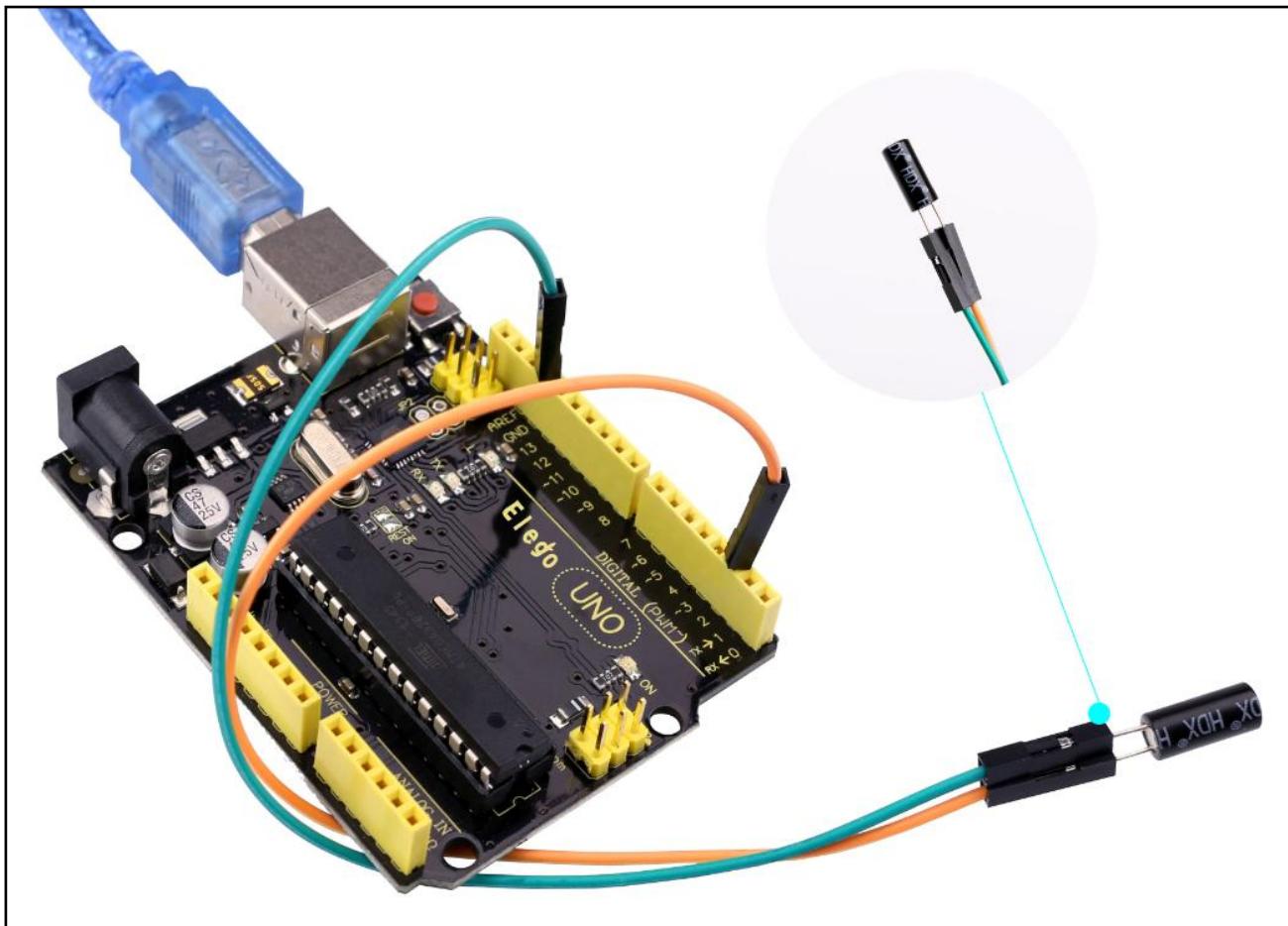


wiring diagram



The code

See the code file.



Lesson 12 Relay

Overview

In this lesson, you will learn how to use a relay.

Component Required:

- (1) x Elego Uno R3
- (1) x Breadboard
- (1) x PN2222
- (1) x 1N4007
- (1) x 220 ohm resistor
- (1) x 6v dc motor
- (1) x Relay
- (1) x Breadboard power supply module
- (1) x 9v power supply adapter
- (8) x M-M wires

Component Introduction

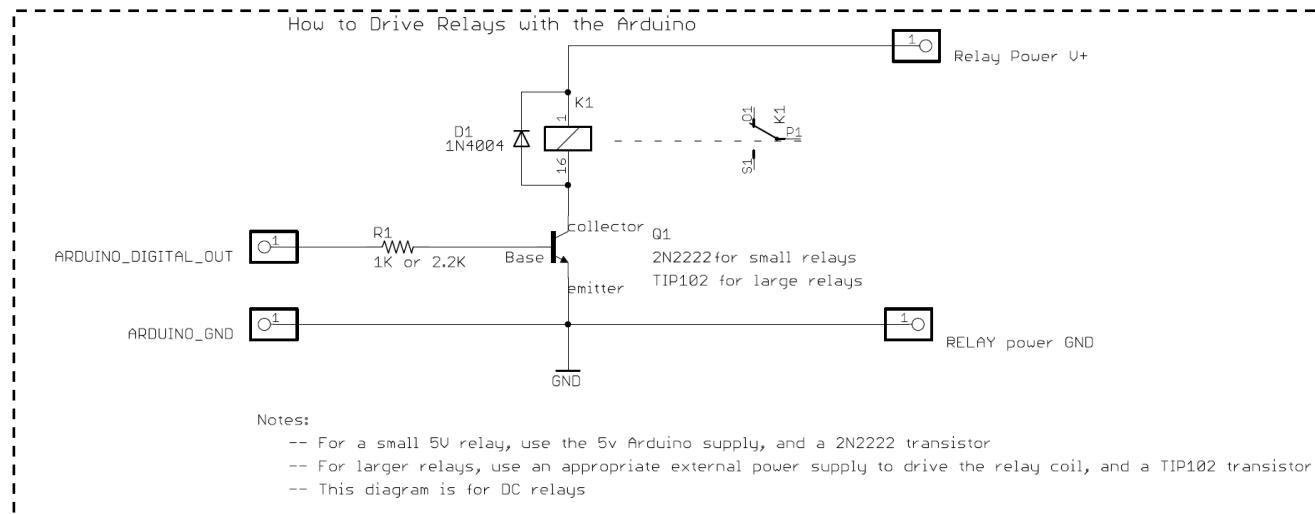
Relay:

A relay is an electrically operated switch. Many relays use an electromagnet to mechanically operate a switch, but other operating principles are also used, such as solid-state relays. Relays are used where it is necessary to control a circuit by a low-power signal (with complete electrical isolation between control and controlled circuits), or where several circuits must be controlled by one signal. The first relays were used in long distance telegraph circuits as amplifiers: they repeated the signal coming in from one circuit and re-transmitted it on another circuit. Relays were used extensively in telephone exchanges and early computers to perform logical operations.

A type of relay that can handle the high power required to directly control an electric motor or other loads is called a contactor. Solid-state relays control power circuits with no moving

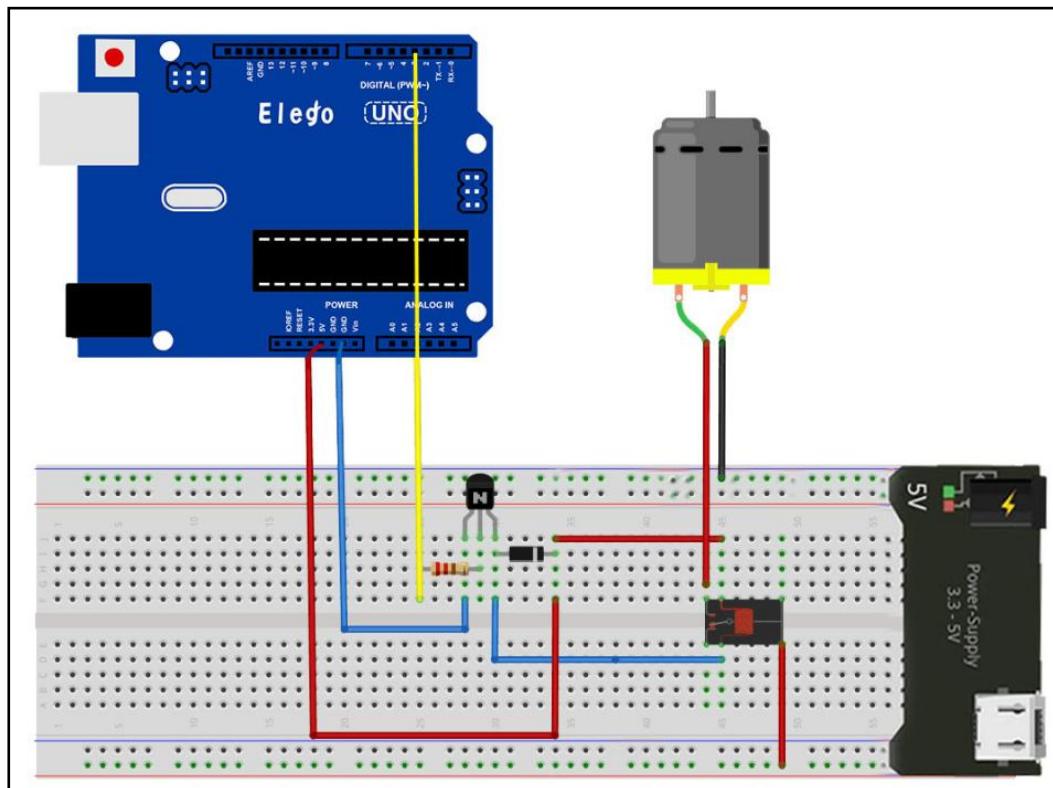
parts, instead using a semiconductor device to perform switching. Relays with calibrated operating characteristics and sometimes multiple operating coils are used to protect electrical circuits from overload or faults; in modern electric power systems these functions are performed by digital instruments still called "protective relays".

Bellow is the schematic of how to drive relay with arduino (down load from the arduino.cc)



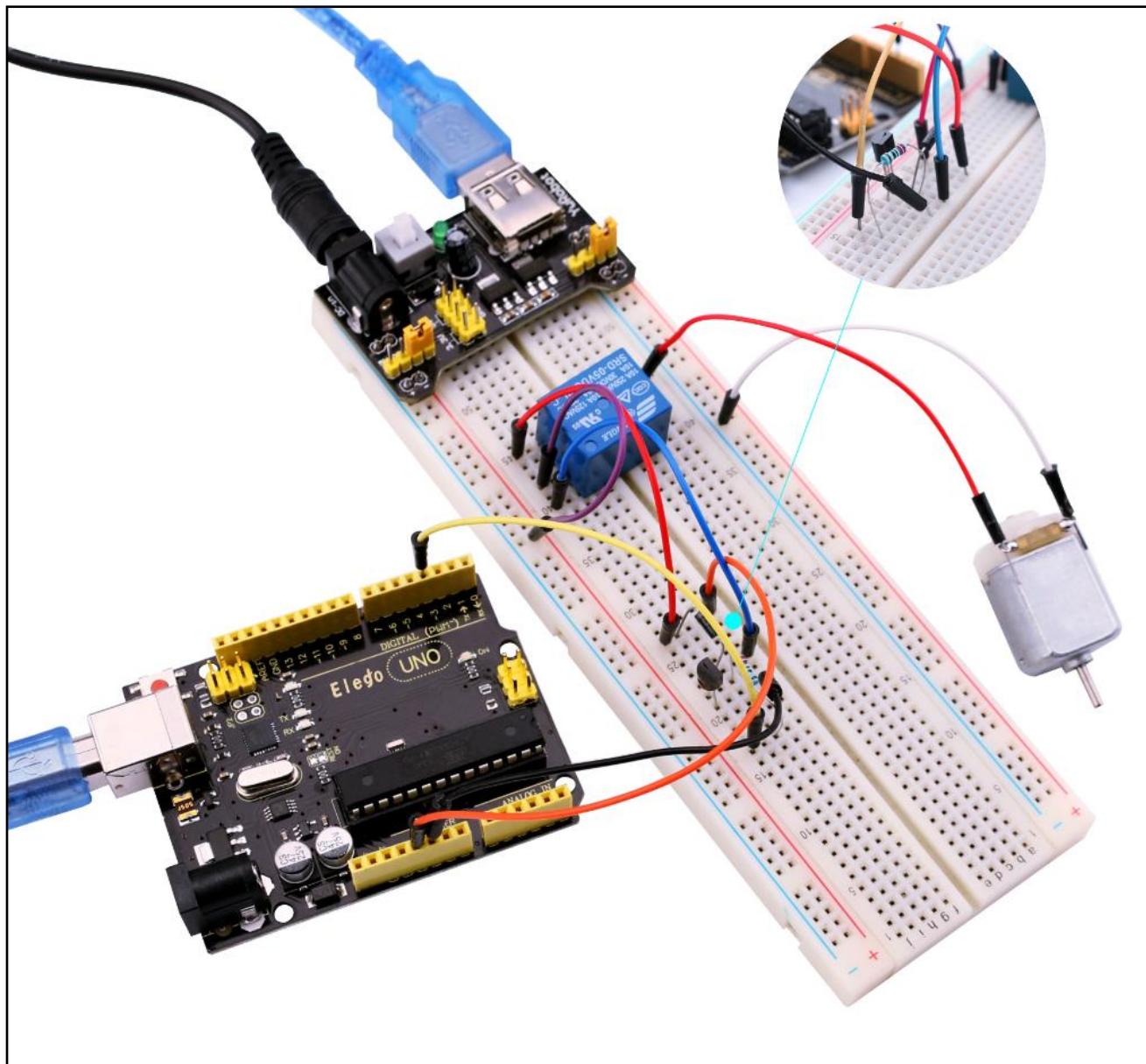
Connection

wiring diagram



The code

See the code file.



Lesson 13 74HC595 And Segment Display

Overview

Rewrite " Lab7 make use of seven-segment display countdown function "to 74HC595 shift register control a seven-segment display sequentially displays the number from 9-0, making the effect of the digital countdown on the seven-segment display.

Note: This test assumes that you have done, " Lab7 make reciprocal use of seven-segment display function "and"Lab11 use 74HC595 and three pins to control 8 LED "principle has been known seven-segment display and a 74HC595 using separate ways.

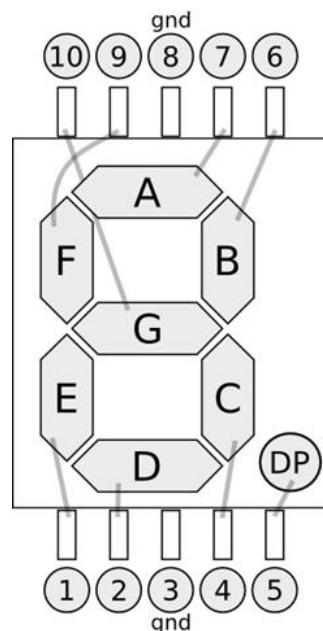
Component Required:

- (1) x Elego Uno R3
- (2) x Breadboard
- (1) x 74HC595
- (1) x Segment Display
- (8) x 220 ohm resistor
- (20) x M-M wires

Component Introduction

Seven segment display

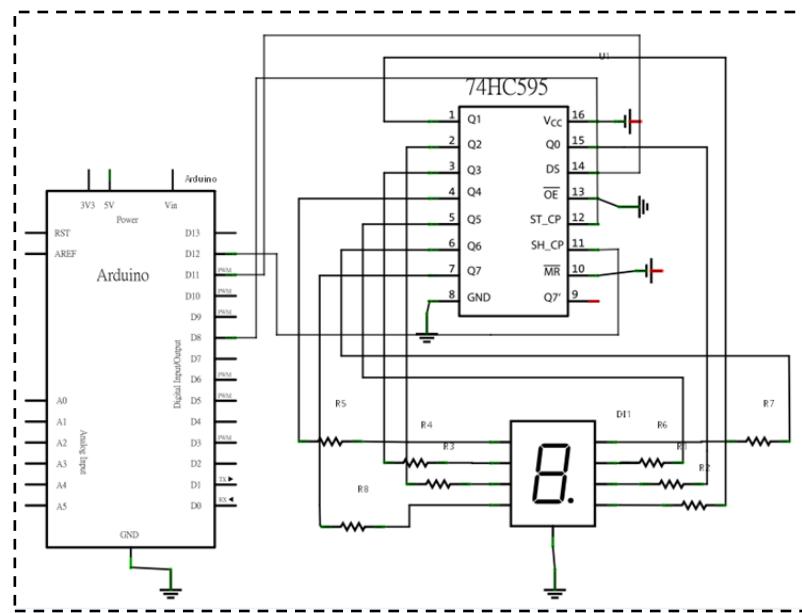
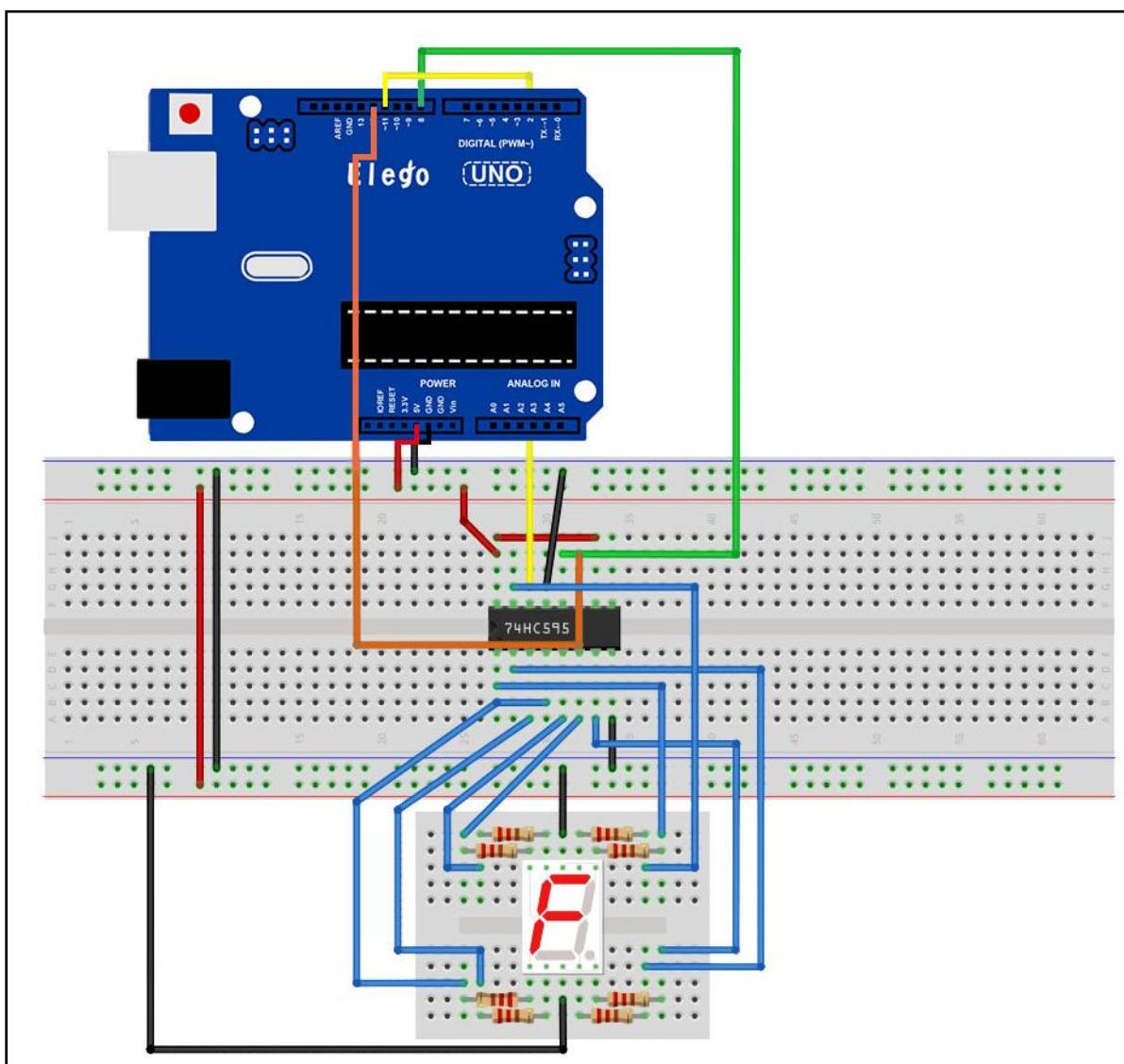
Seven segment display pin diagram below (the picture shows common cathode seven-segment display):



0-9 ten digits correspond with each segment are as follows (the following table applies common cathode seven segment display device, if you are using a common anode, the table should be replaced every 1 0 0 should all replaced by 1):

Display digital	dp	a	b	c	d	e	f	g
0	0	1	1	1	1	1	1	0
1	0	0	1	1	0	0	0	0
2	0	1	1	0	1	1	0	1
3	0	1	1	1	1	0	0	1
4	0	0	1	1	0	0	1	1
5	0	1	0	1	1	0	1	1
6	0	1	0	1	1	1	1	1
7	0	1	1	1	0	0	0	0
8	0	1	1	1	1	1	1	1
9	0	1	1	1	1	0	1	1

Connection

Schematic**wiring diagram**

The following table shows the seven-segment display 74HC595 pin correspondence table:

74HC595 pin	Seven shows remarkable control pin (stroke)
Q0	7 (A)
Q1	6 (B)
Q2	4 (C)
Q3	2 (D)
Q4	1 (E)
Q5	9 (F)
Q6	10 (G)
Q7	5 (DP)

Step one: Connect 74HC595

First, the wiring is connected to power and ground:

- Vcc (pin 16) and MR (pin 10) connected to 5V
- GND (pin 8) and OE (pin 13) to ground

Connection DS, ST_CP and SH_CP pin:

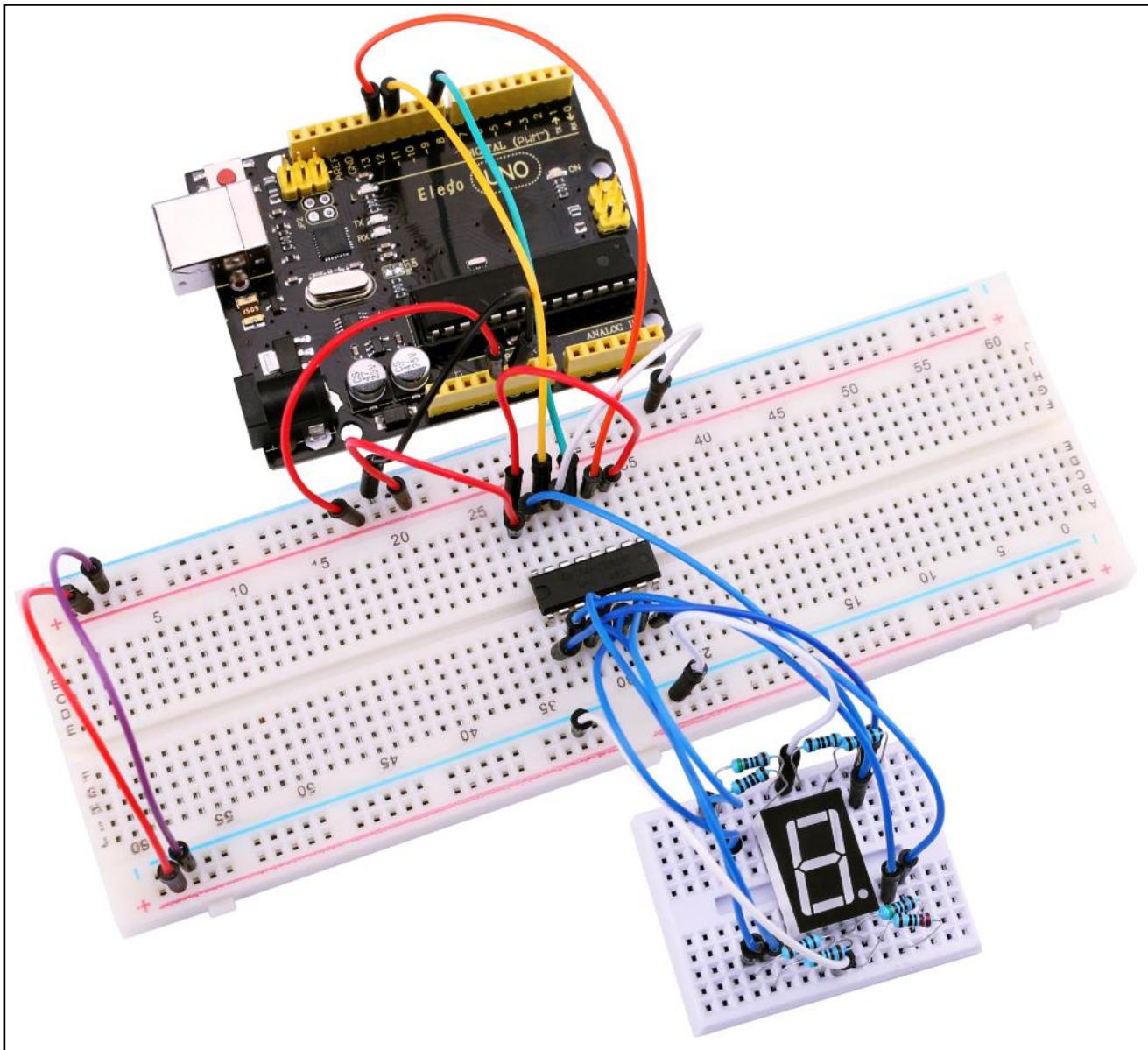
- DS (pin 14) connected to UNO R3 board pin 11 (the figure below the blue line)
- ST_CP (pin 12, latch pin) connected to UNO R3 board pin 8 (FIG green line below)
- SH_CP (pin 11, clock pin) connected to UNO R3 board pin 12 (the figure below the yellow line)

Step two: Connect the seven segment display

- The seven-segment display 3, 8 pin to GND (This example uses the common cathode, anode set if the total of 3, 8 pin to + 5V)
- According to the table of the 74HC595 Q0 ~ Q7 received a seven-segment display corresponding pin (A ~ G and DP), and then each foot in a 220 ohm resistor in series

The code

See the code file.



Lesson 14 Four Digital Tube Segment Display

Overview

In this lesson, we will learn how to use a four digital tube segment.

When using one digit 7-segment display, if it is common anode, we will connect common anode pin to power source; if it is common cathode, we will connect common cathode pin to GND. When using four digit 7-segment display, the common anode or common cathode pin are used to control which digit is displayed. There is only one digit working. However, based on the principle of Persistence of Vision, we can see four 7-segment display is all displaying numbers. This is because electronic scanning speed is fast and we cannot notice it.

Component Required:

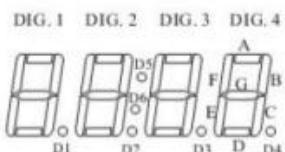
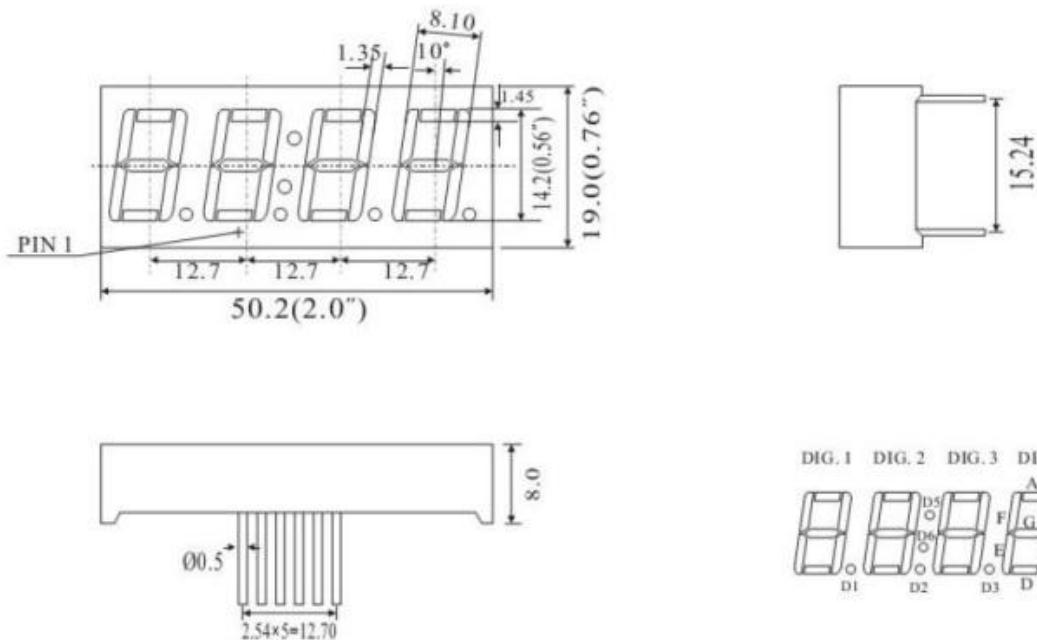
- (1) x Elego Uno R3
- (1) x Breadboard
- (1) x 74HC595
- (1) x Four Digital Tube Segment Display
- (1) x 220 ohm resistor
- (20) x M-M wires

Component Introduction

Four Digital Seven segment display

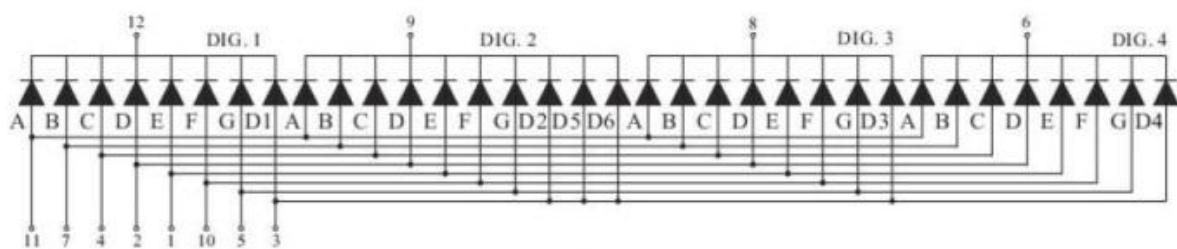
Package Dimensions

CPS05643AB

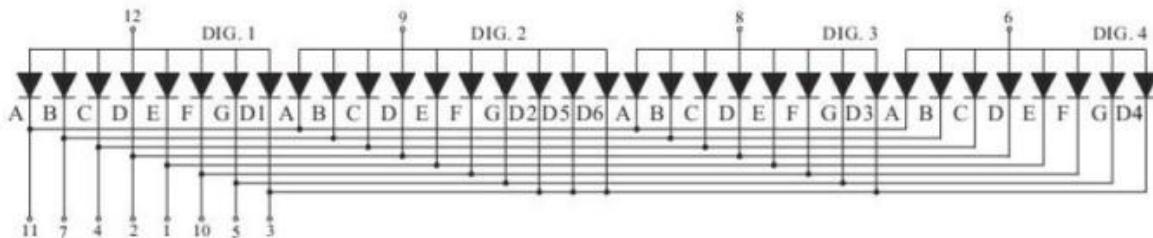


UNIT: MM(INCH) TOLERANCE: $\pm 0.25(0.01")$

Internal Circuit Diagram



5643A

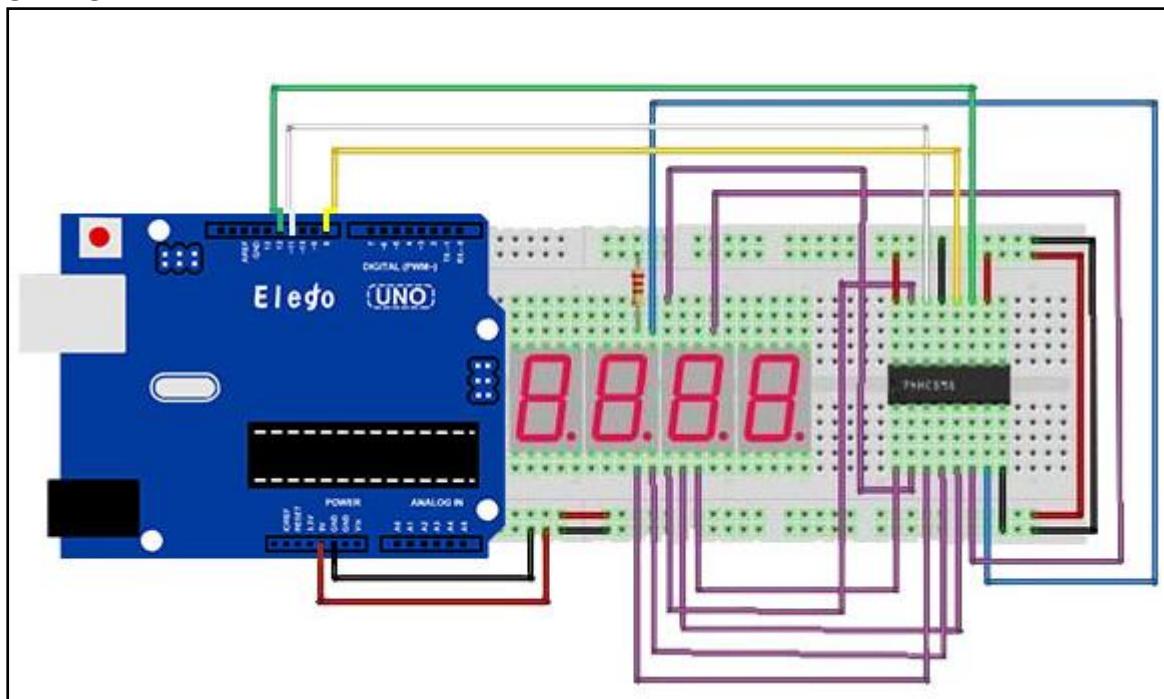


5643B

Four Digits Displays Series

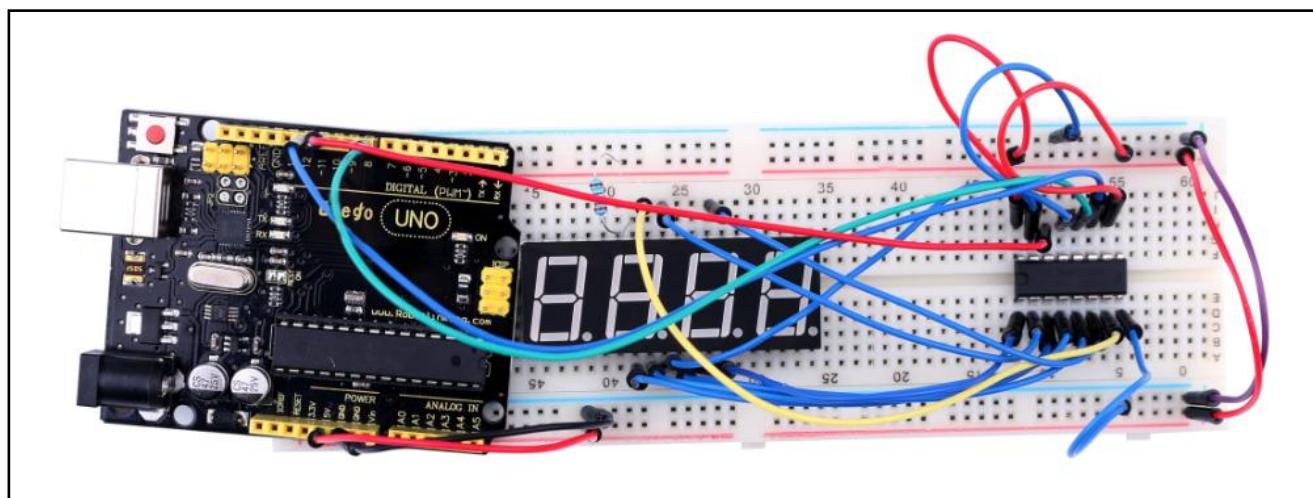
Connection

wiring diagram



The code

See the code file.



Lesson 15 Servo

Overview

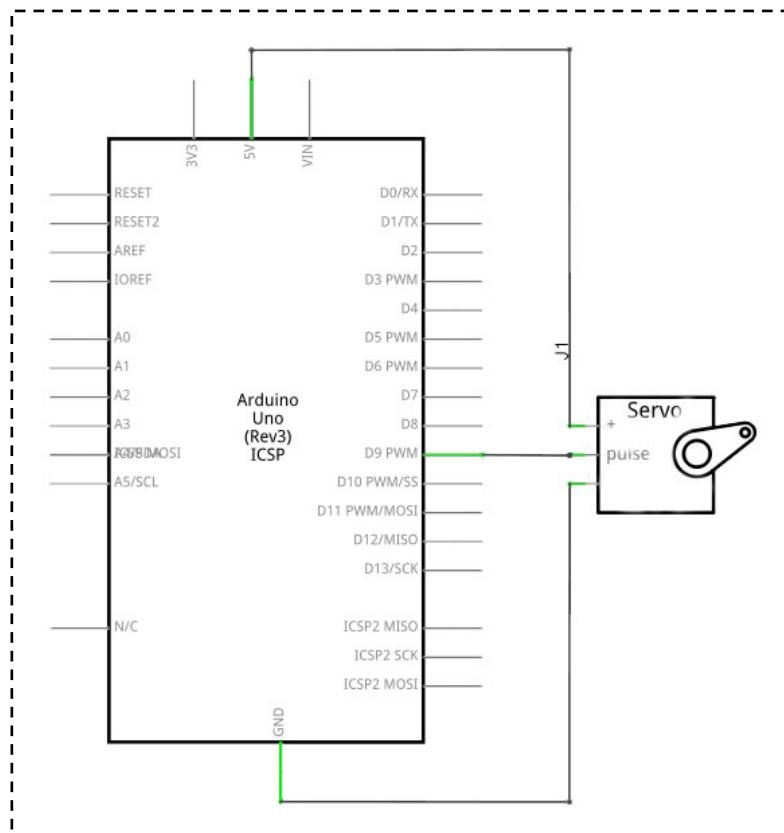
Servo is a type of geared motor that can only rotate 180 degrees. It is controlled by sending electrical pulses from your UNO R3 board. These pulses tell the servo what position it should move to. A servo has three wires, the brown wire is GND, the red one is VCC, and the orange one is signal line.

Component Required:

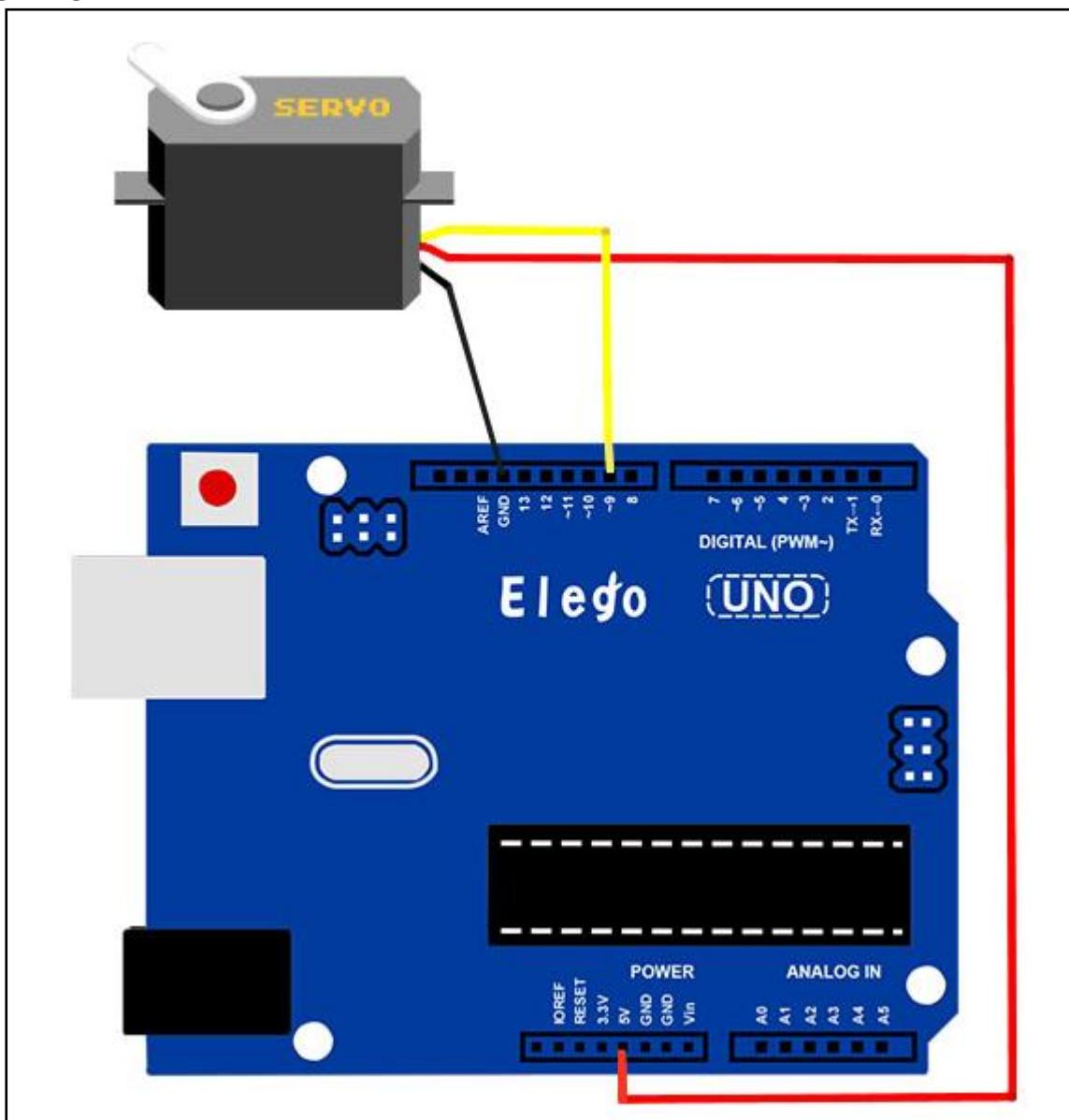
- (1) x Elego Uno R3
- (1) x Servo
- (2) x F-M wires

Connection

Schematic

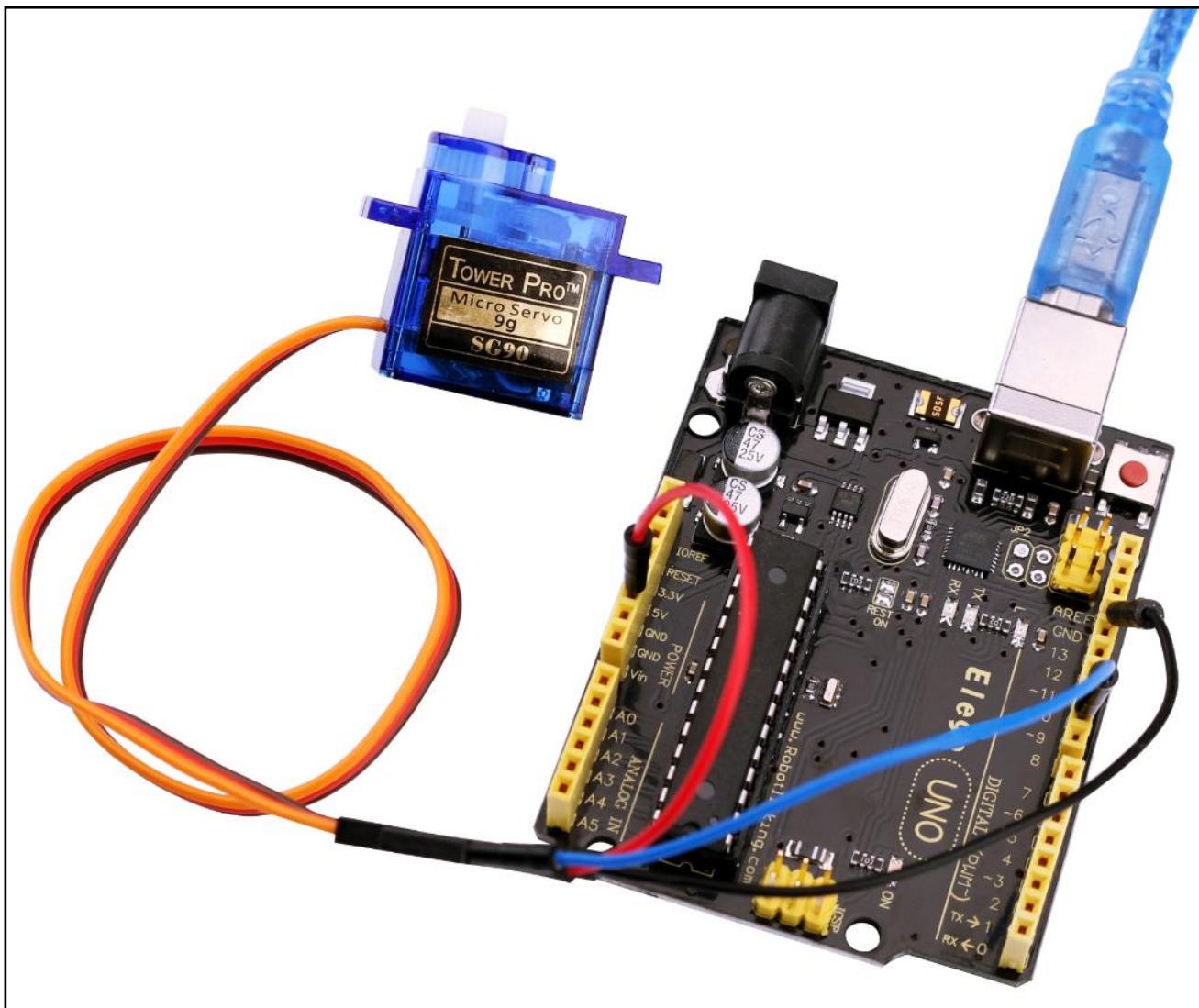


wiring diagram



The code

See the code file.



Lesson 16 LCD Display

Overview

In this lesson, you will learn how to wire up and use an alphanumeric LCD display.

The display has an LED backlight and can display two rows with up to 16 characters on each row. You can see the rectangles for each character on the display and the pixels that make up each character. The display is just white on blue and is intended for showing text.

In this lesson, we will run the Arduino example program for the LCD library, but in the next lesson, we will get our display to show the temperature and light level, using sensors.

Component Required:

(1) x Elego Uno R3

(1) x LCD1602 display

(1) x Potentiometer

(1) x Breadboard

(16) x F-M wires

Component Introduction

LCD1602

introduction to the pins of LCD1602:

V_{SS}: A pin that connects to ground

V_{DD}: A pin that connects to a +5V power supply

VO: A pin that adjust the contrast of LCD1602

RS: A register select pin that controls where in the LCD's memory you are writing data to. You can select either the data register, which holds what goes on the screen, or an instruction register, which is where the LCD's controller looks for instructions on what to do next.

R/W: A Read/Write pin that selects reading mode or writing mode

E: An enabling pin that, when supplied with low-level energy, causes the LDC module to

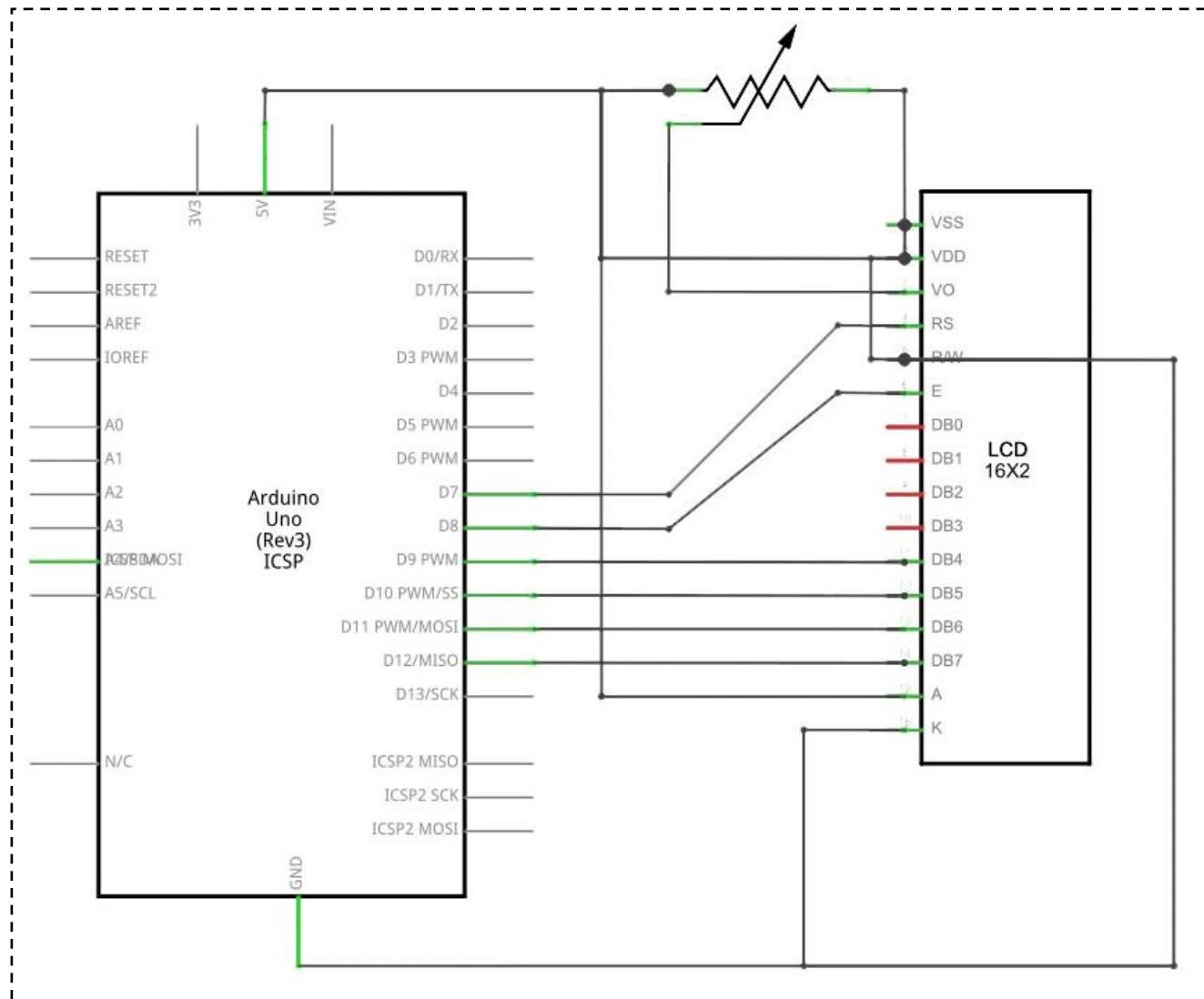
execute relevant instructions.

D0-D7 : Pins that read and write data

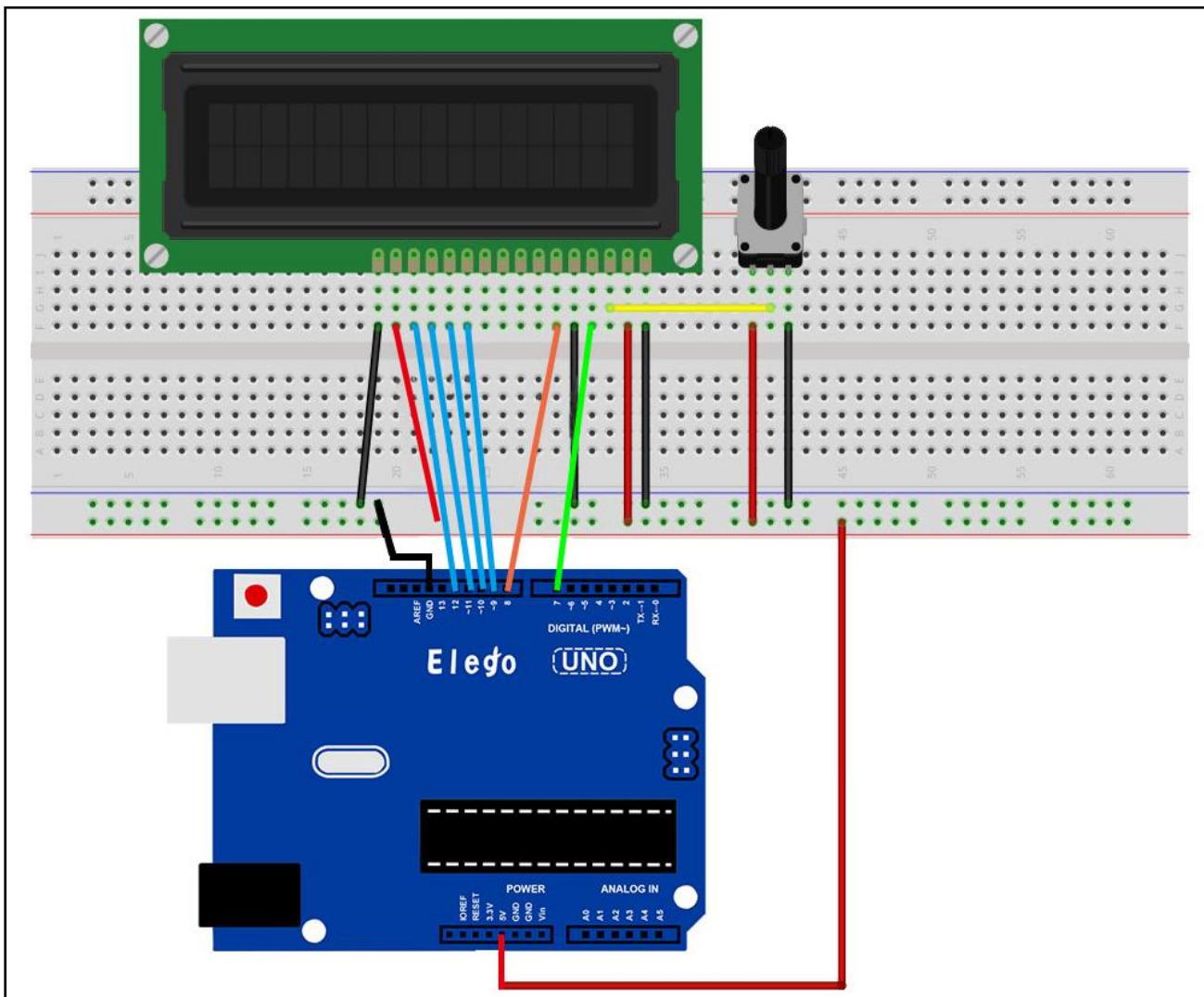
A and K: Pins that control the LED backlight

Connection

Schematic



wiring diagram



The LCD display needs six Arduino pins, all set to be digital outputs. It also needs 5V and GND connections.

There are quite a few connections to be made. Lining up the display with the top of the breadboard helps to identify its pins without too much counting, especially if the breadboard has its rows numbered with row 1 as the top row of the board. Do not forget, the long yellow lead that links the slider of the pot to pin 3 of the display. The 'pot' is used to control the contrast of the display.

You may find that your display is supplied without header pins attached to it. If so, follow the instructions in the next section.

The Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <LiquidCrystal> library. Or you need to install again. If you do not do this, your code won't work.

This example uses different pins to the ones we use, so find the line of code below:

```
LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
```

and change it to be:

```
LiquidCrystal lcd(7, 8, 9, 10, 11, 12);
```

Upload the code to your Arduino board and you should see the message 'hello, world' displayed, followed by a number that counts up from zero.

The first thing of note in the sketch is the line:

```
#include <LiquidCrystal.h>
```

This tells Arduino that we wish to use the Liquid Crystal library.

Next we have the line that we had to modify. This defines which pins of the Arduino are to be connected to which pins of the display.

```
LiquidCrystal lcd(7, 8, 9, 10, 11, 12);
```

The arguments to this are as follows:

Display Pin Name	Display Pin Number	Arduino Pin (in this example)
RS	4	7
E	6	8
D4	11	9
D5	12	
D6	13	
D7	11	
D12	14	

After uploading this code, make sure the backlight is lit up, and adjust the potentiometer all the way around until you see the text message

In the 'setup' function, we have two commands:

```
lcd.begin(16, 2);
```

```
lcd.print("hello, world!");
```

The first tells the Liquid Crystal library how many columns and rows the display has. The second line displays the message that we see on the first line of the screen.

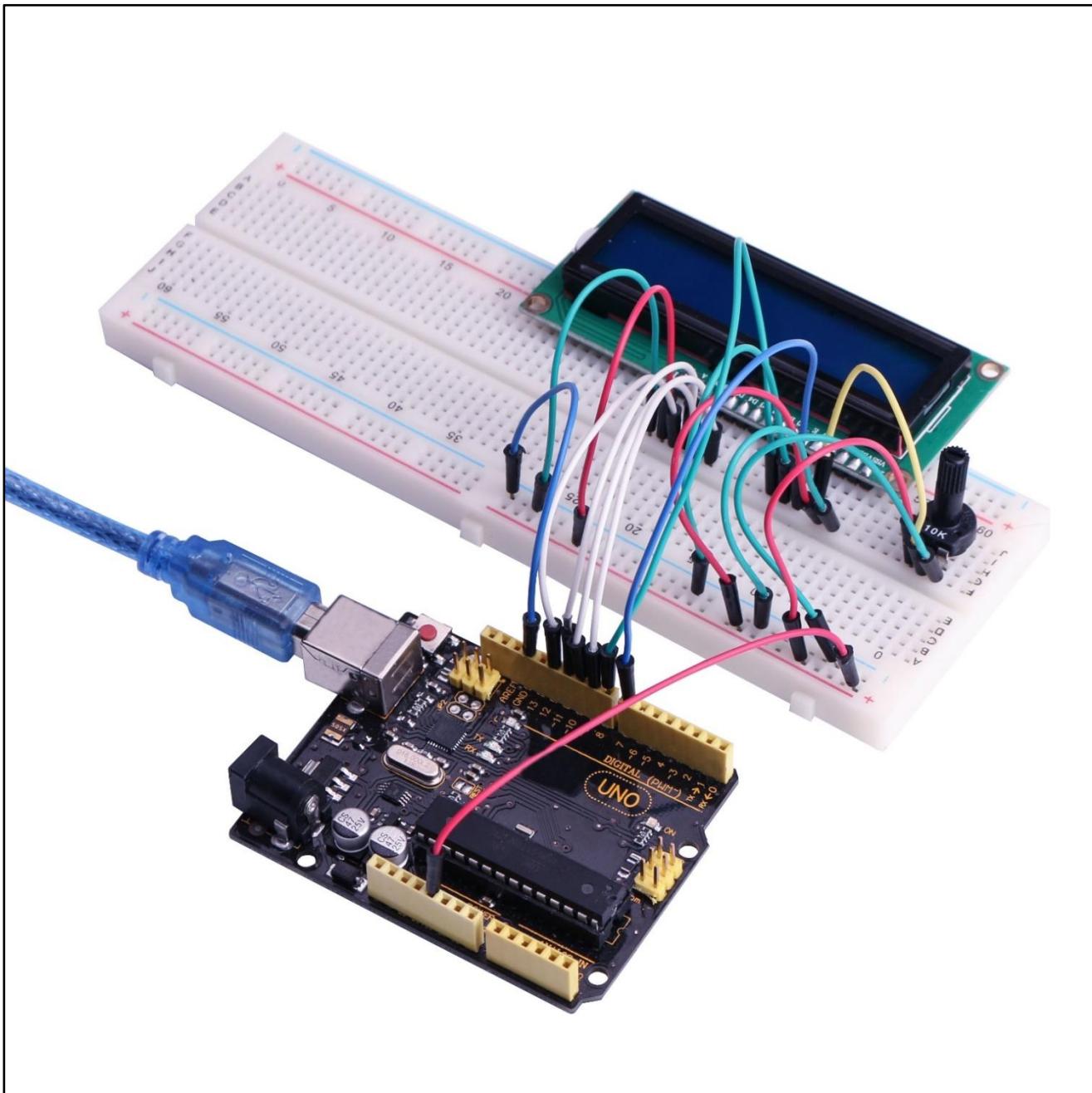
In the 'loop' function, we also have two commands:

```
lcd.setCursor(0, 1);
```

```
lcd.print(millis()/1000);
```

The first sets the cursor position (where the next text will appear) to column 0 & row 1. Both column and row numbers start at 0 rather than 1.

The second line displays the number of milliseconds since the Arduino was reset.



Lesson 17 Thermometer

Overview

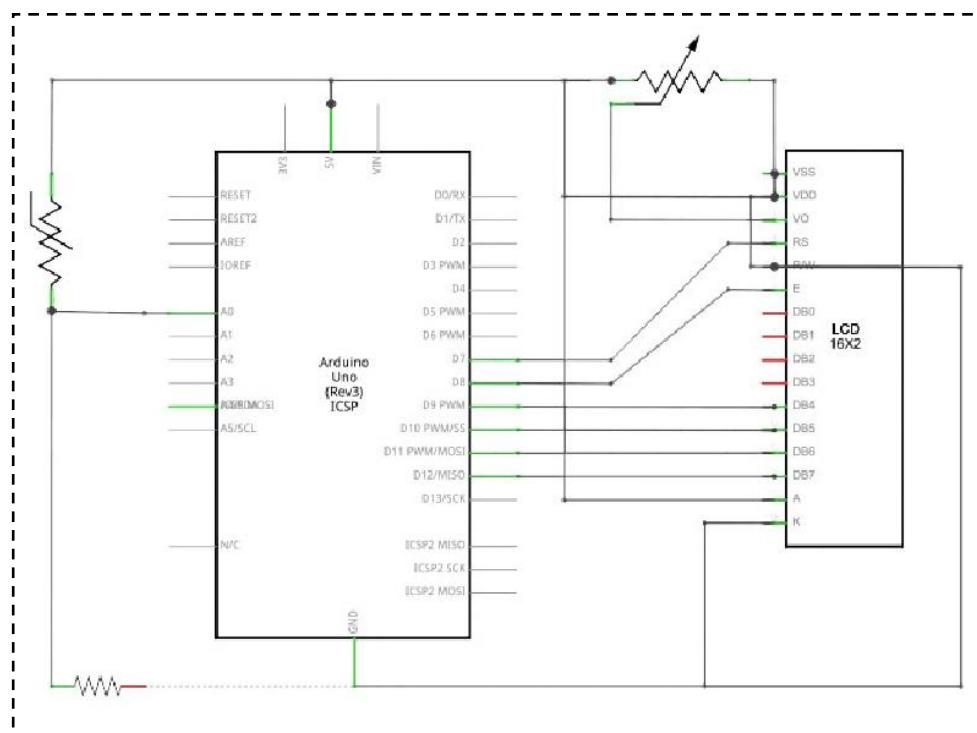
In this lesson, you will use a LCD display to show the temperature.

Component Required:

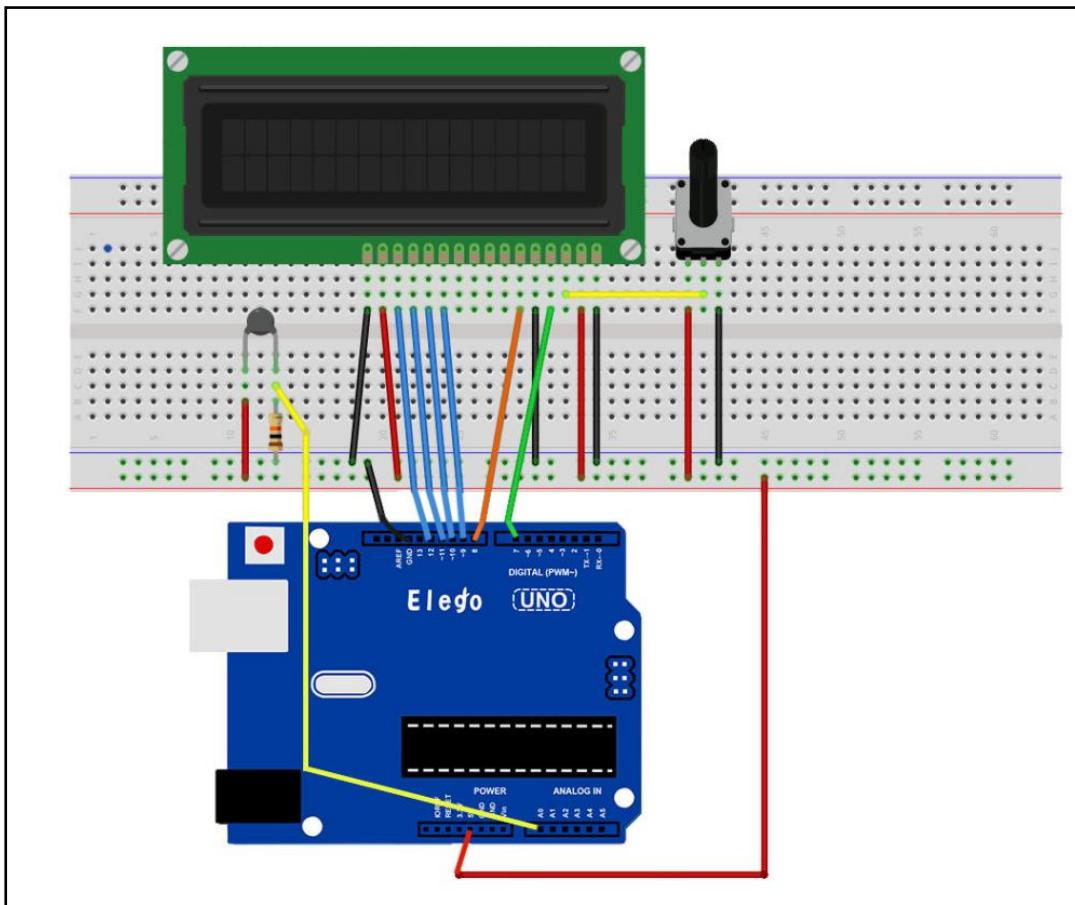
- (1) x Elego Uno R3
- (1) x LCD1602 display
- (1) x 10k ohm resistor
- (1) x Thermistor
- (1) x Potentiometer
- (1) x Breadboard
- (16) x F-M wires

Connection

Schematic



wiring diagram



The breadboard layout is based on the layout from lesson 12, so if you still have this on the breadboard it will simplify things greatly.

There are a few jumper wires that have been moved slightly on this layout. In particular, those near the pot.

The photocell, 1 kΩ resistor and Thermistor are all new additions to the board.

The Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <LiquidCrystal> library. Or you need to install again. If you do not do this, your code won't work.

The sketch for this is based on that of lesson 14. Load it up onto your Arduino and you should find that warming the temperature sensor by putting your finger on it will increase the temperature reading.

I find it useful to put a comment line above the 'lcd' command.

```
//           BS  E  D4 D5  D6 D7
```

```
LiquidCrystal lcd(7, 8, 9, 10, 11, 12);
```

This makes things easier if you decide to change which pins you use.

In the 'loop' function there are now two interesting things going on. Firstly we have to convert the analog from the temperature sensor into an actual temperature, and secondly we have to work out how to display them.

First of all, let's look at calculating the temperature.

```
int tempReading = analogRead(tempPin);
float tempVolts = tempReading * 5.0 / 1024.0;
float tempC = (tempVolts - 0.5) * 100.0;
float tempF = tempC * 9.0 / 5.0 + 32.0;
```

The raw reading from the temperature sensor is first multiplied by 5 and then divided by 1024 to give us the voltage (between 0 and 5) at the 'tempPin' analog input.

To convert the voltage coming from the TMP36 into a temperature in degrees C, you have to subtract 0.5V from the measurement and then multiply by 100.

To convert this into a temperature in Fahrenheit, you then have to multiply it by 9/5 and then add 32.

Displaying changing readings on an LCD display can be tricky. The main problem is that the reading may not always be the same number of digits. So, if the temperature changed from 101.50 to 99.00 then the extra digit from the old reading is in danger of being left on the display.

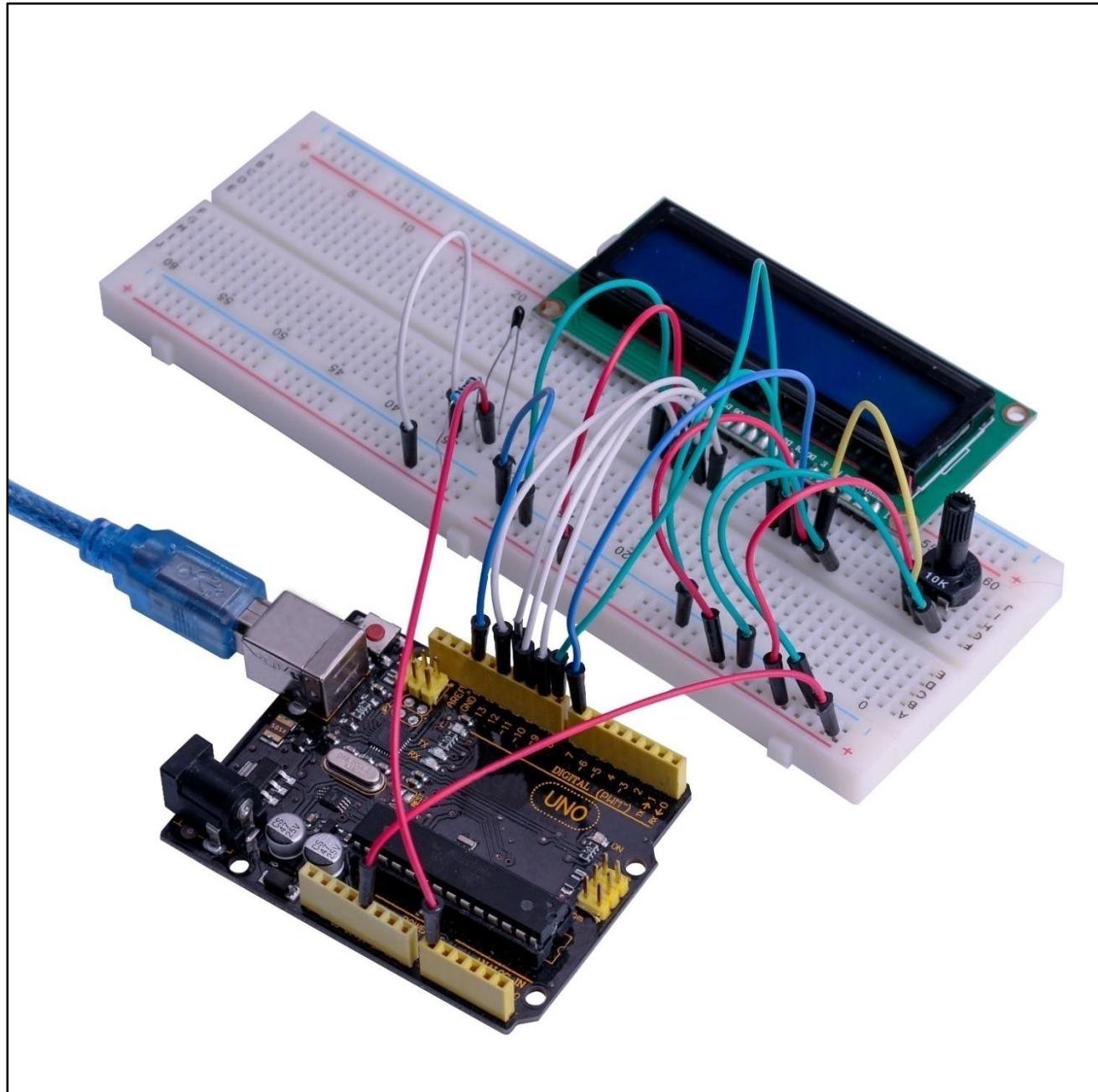
To avoid this, write the whole line of the LCD each time around the loop.

```
// -----
lcd.print("Temp      F  ");
lcd.setCursor(6, 0);
lcd.print(tempF);
```

The rather strange comment serves to remind you of the 16 columns of the display. You can then print a string of that length with spaces where the actual reading will go.

To fill in the blanks, set the cursor position for where the reading should appear and then print it.

Exactly the same approach is used for displaying the light level. There are no units for the light level, we just display the raw reading from the analog read.



Lesson 18 Ultrasonic Sensor Module

Overview

Ultrasonic sensor are great for all kind of projects that need distance measurements, avoiding obstacles as examples.

The HC-SR04 are inexpensive and easy to use since we will be using a Library specifically designed for these sensor.

Component Required:

- (1) x Elego Uno R3
- (1) x Ultrasonic sensor module
- (4) x F-M wires

Component Introduction

Ultrasonic sensor

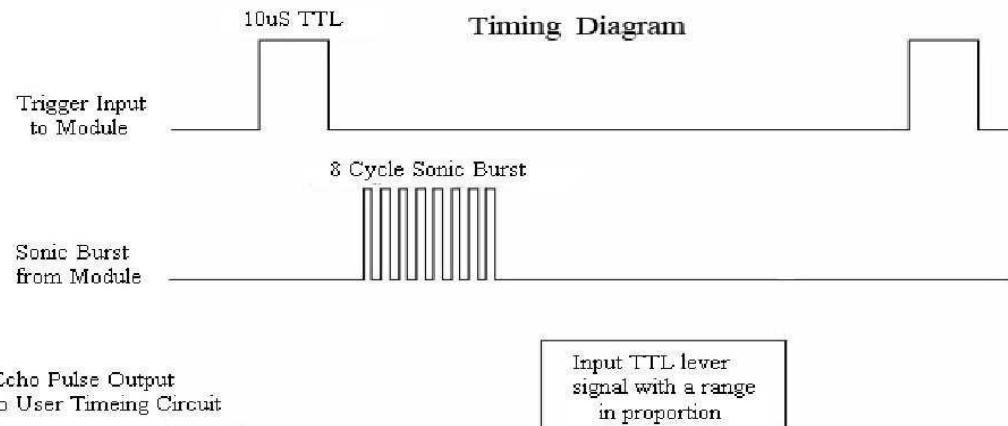
Ultrasonic ranging module HC - SR04 provides 2cm - 400cm non-contact measurement function, the ranging accuracy can reach to 3mm. The module includes ultrasonic transmitters, receiver and control circuit. The basic principle of work:

- (1) Using IO trigger for at least 10us high level signal,
- (2) The Module automatically sends eight 40 kHz and detect whether there is a pulse signal back.
- (3) If the signal back, through high level , time of high output IO duration is the time from sending ultrasonic to receiving.

Test distance = (high level time × velocity of sound (340M/S) /2

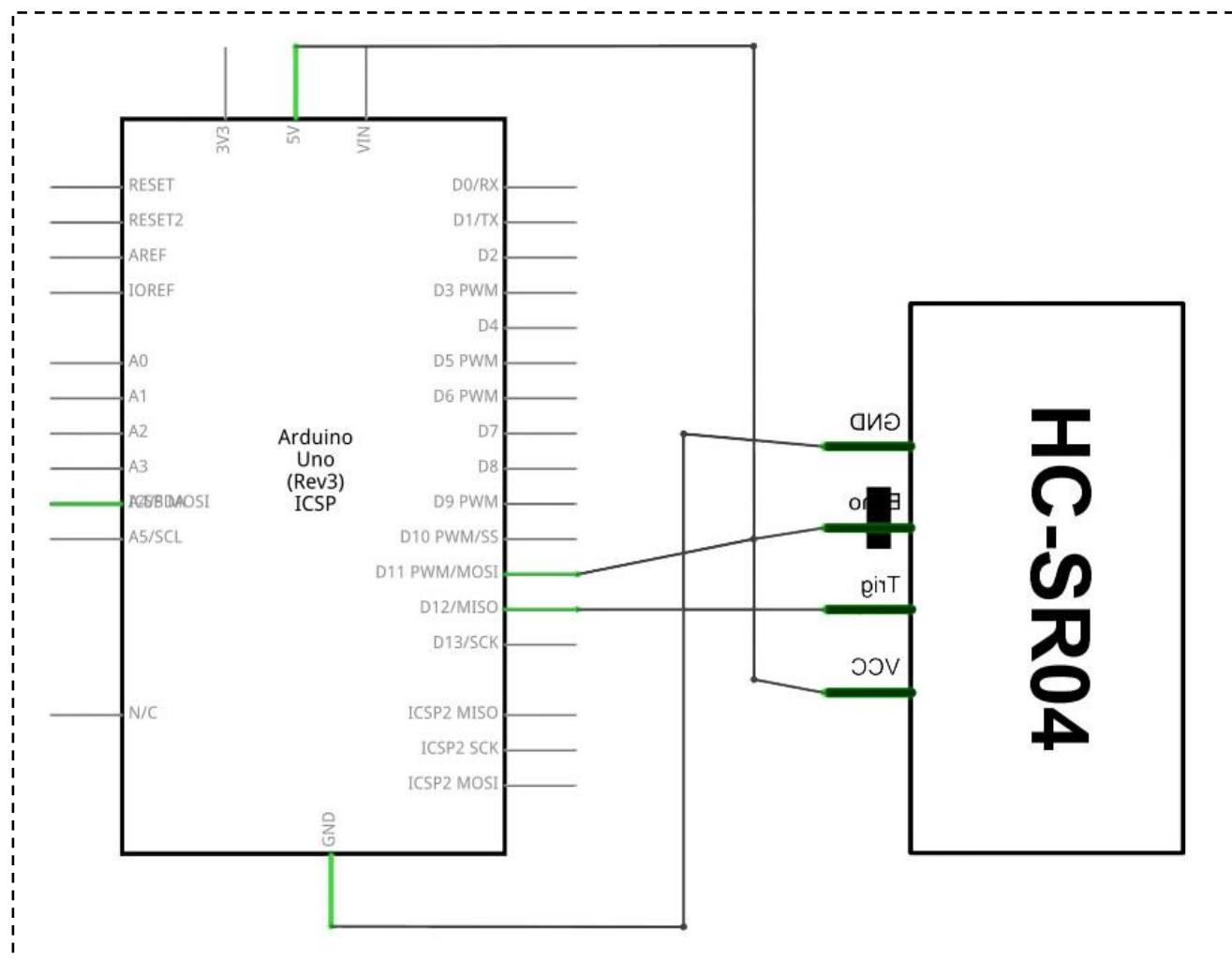
The Timing diagram is shown below. You only need to supply a short 10uSpulse to the trigger input to start the ranging, and then the module will send out an 8 cycle burst of ultrasound at 40 kHz and raise its echo. The Echo is a distance object that is pulse width and the range in proportion .You can calculate the range through the time interval between sending trigger signal and receiving echo signal. Formula: $uS / 58 = \text{centimeters}$ or $uS / 148 = \text{inch}$; or:

the range = high level time * velocity (340M/S) / 2; we suggest to use over 60ms measurement cycle, in order to prevent trigger signal to the echo signal.

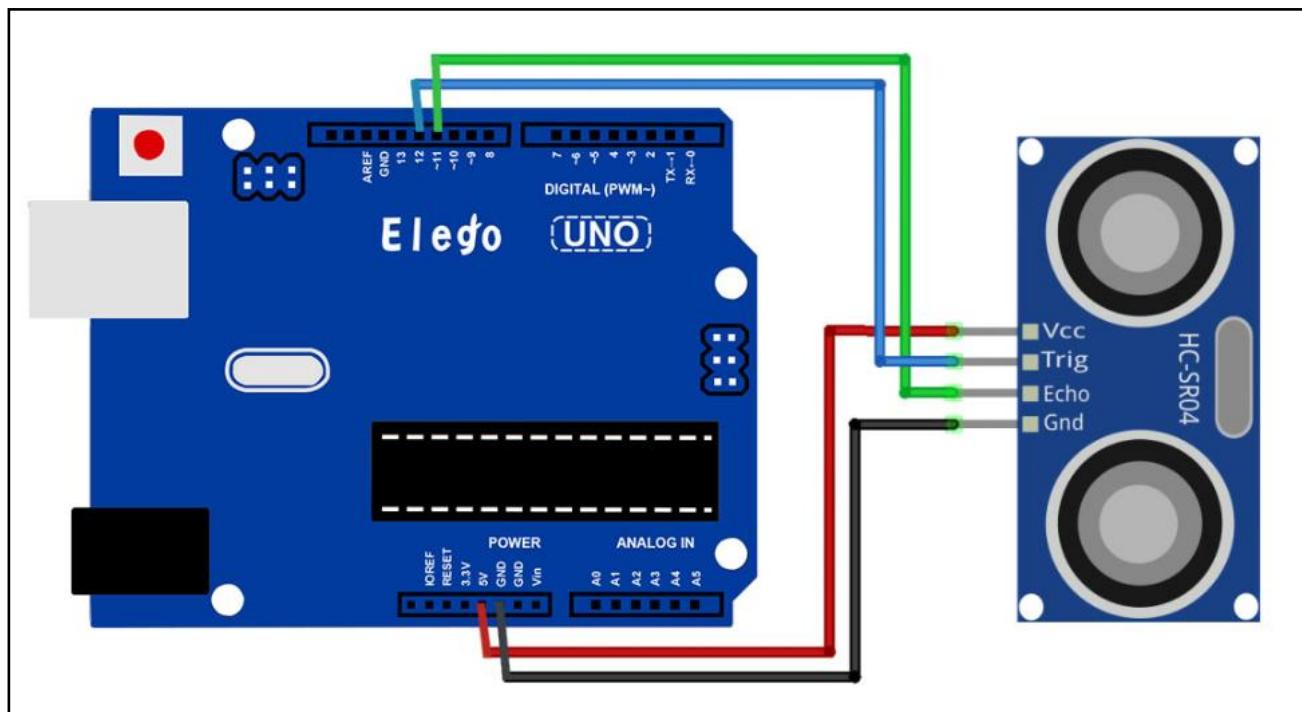


Connection

Schematic



wiring diagram



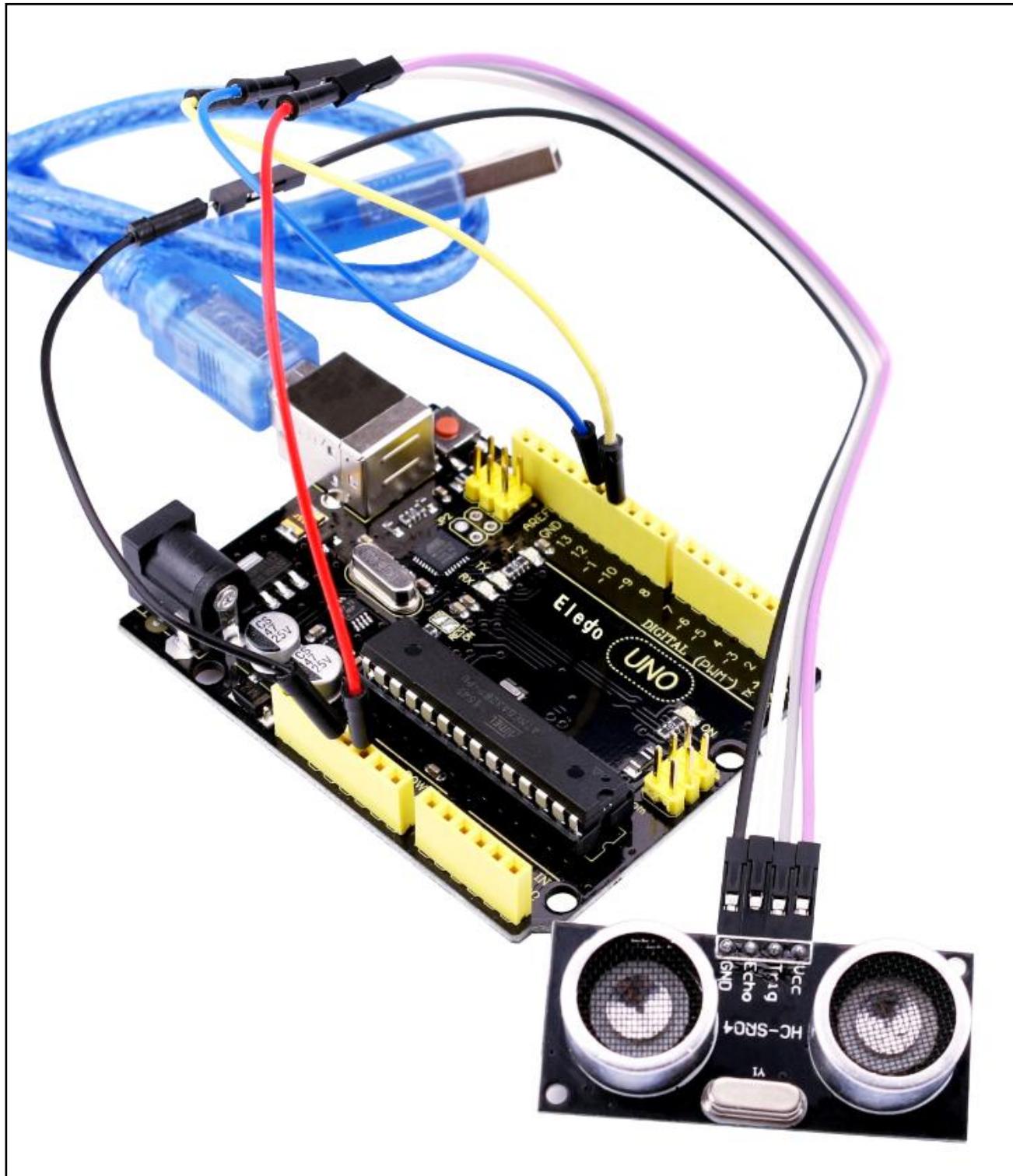
The Code

Using a Library designed for these sensors will make our code short and simple.

We include the library at the beginning of our code, and then by using simple commands we can control the behavior of the sensor.

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the < HC-SR04_Library> library. Or you need to install again. If you do not do this, your code won't work.



Lesson 19 Keypad Module

Overview

In this project, we will go over how to integrate a keyboard with an UNO R3 board so that the UNO R3 can read the keys being pressed by a user.

Keypads are used in all types of devices, including cell phones, fax machines, microwaves, ovens, door locks, etc. They're practically everywhere. Tons of electronic devices use them for user input.

So knowing how to connect a keypad to a microcontroller such as an UNO R3 board is very valuable for building many different types of commercial products.

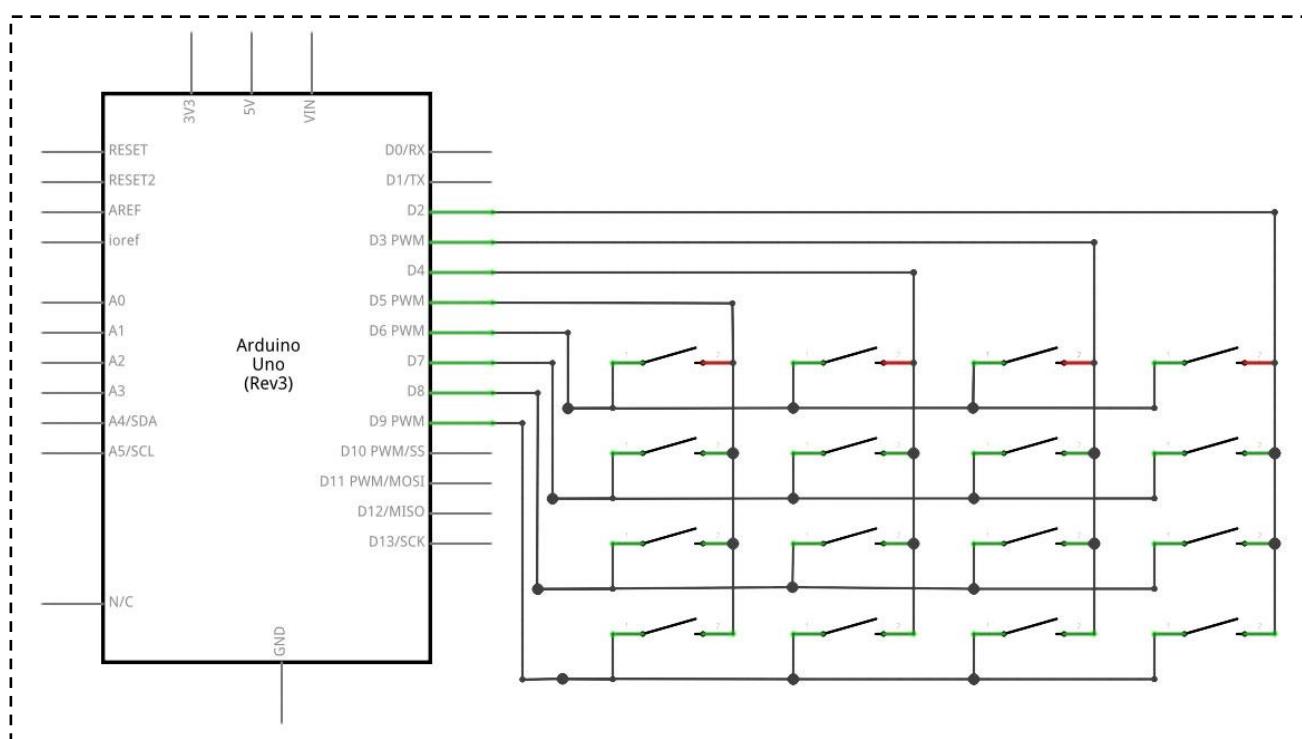
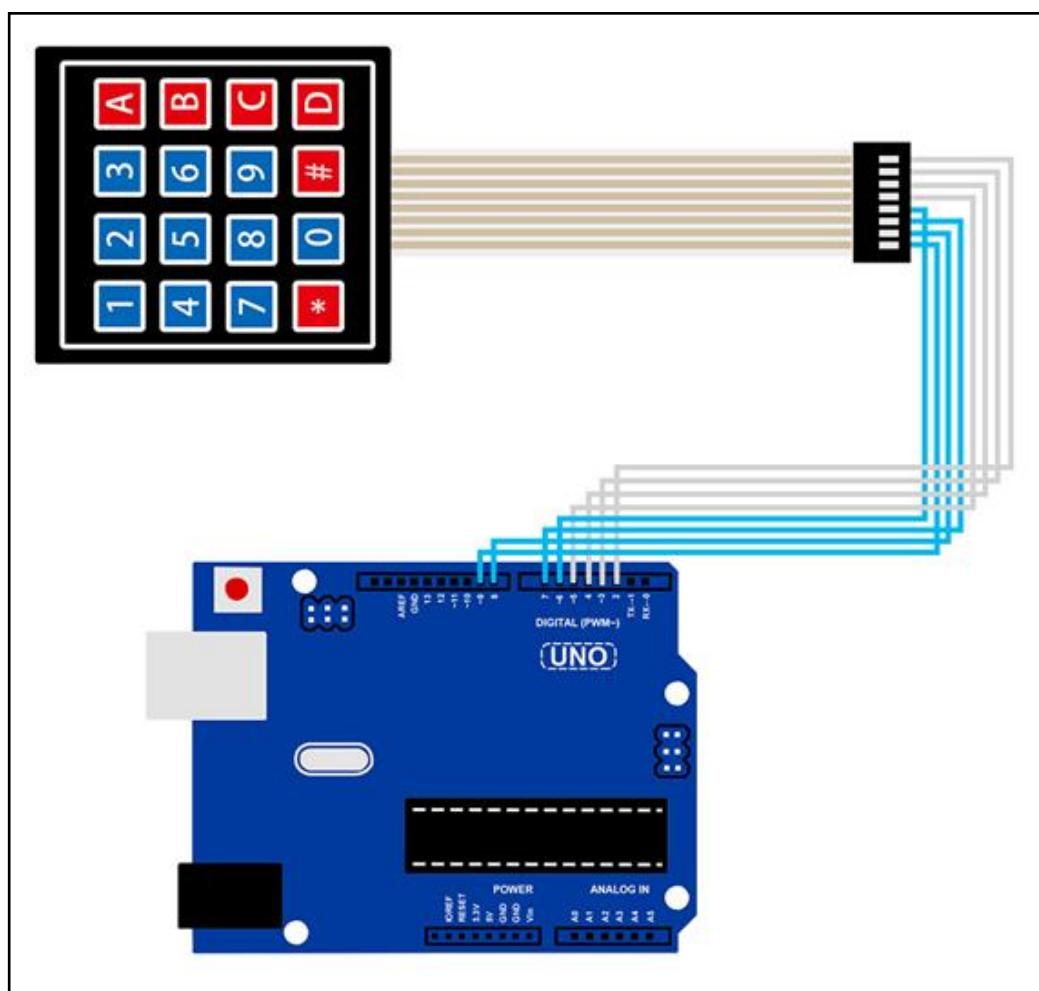
At the end when all is connected properly and programmed, when a key is pressed, it shows up at the Serial Monitor on your computer. Whenever you press a key, it shows up on the Serial Monitor. Later, in another project, we will connect the keypad circuit, so that it will get displayed on an LCD. But for now, for simplicity purposes, we start at simply showing the key pressed on the computer.

For this project, the type of keypad we will use is a matrix keypad. This is a keypad that follows an encoding scheme that allows it to have much less output pins than there are keys. For example, the matrix keypad we are using has 16 keys (0-9, A-D, *, #), yet only 8 output pins. With a linear keypad, there would have to be 17 output pins (one for each key and a ground pin) in order to work. The matrix encoding scheme allows for less output pins and thus much less connections that have to be made for the keypad to work. In this way, they are more efficient than linear keypads, being that they have less wiring.

Component Required:

- (1) x Elego Uno R3
- (1) x Membrane switch module
- (8) x M-M wires

Connection

Schematic**wiring diagram**

When connecting the pins to the UNO R3 board, we connect them to the digital output pins, D9-D2. We connect the first pin of the keypad to D9, the second pin to D8, the third pin to D7, the fourth pin to D6, the fifth pin to D5, the sixth pin to D4, the seventh pin to D3, and the eighth pin to D2.

These are the connections in a table:

Keypad Pin	Connects to Arduino Pin...
1	D9
2	D8
3	D7
4	D6
5	D5
6	D4
7	D3
8	D2

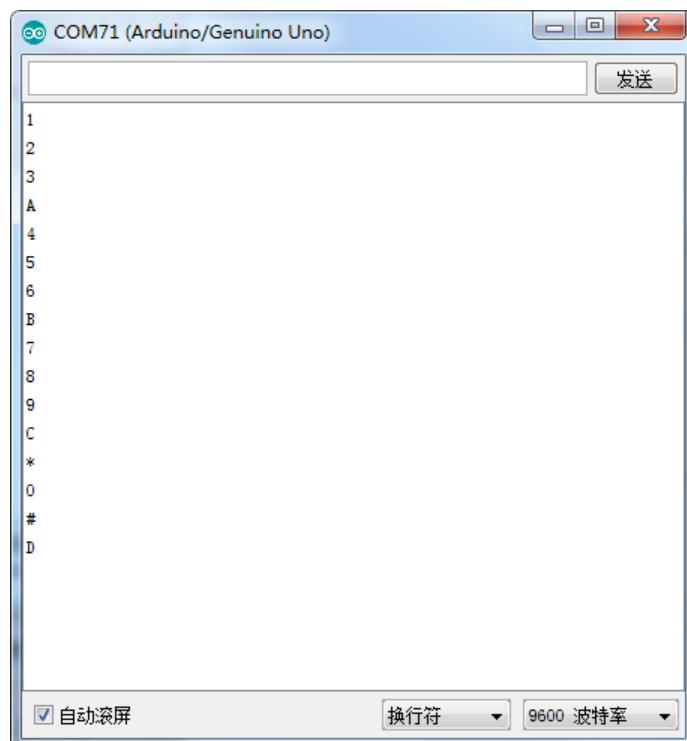
The Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <Keypad> library. Or you need to install again. If you do not do this, your code won't work.



With this code, once we press a key on the keypad, it should show up on the serial monitor of the arduino software once the code is compiled and uploaded to the UNO R3 board.



Lesson 20 DHT11 Temperature and Humidity Sensor

Overview

In this tutorial we will learn how to use a DHT11 Temperature and Humidity Sensor.

It's accurate enough for most projects that need to keep track of humidity and temperature readings.

Again we will be using a Library specifically designed for these sensors that will make our code short and easy to write.

Component Required:

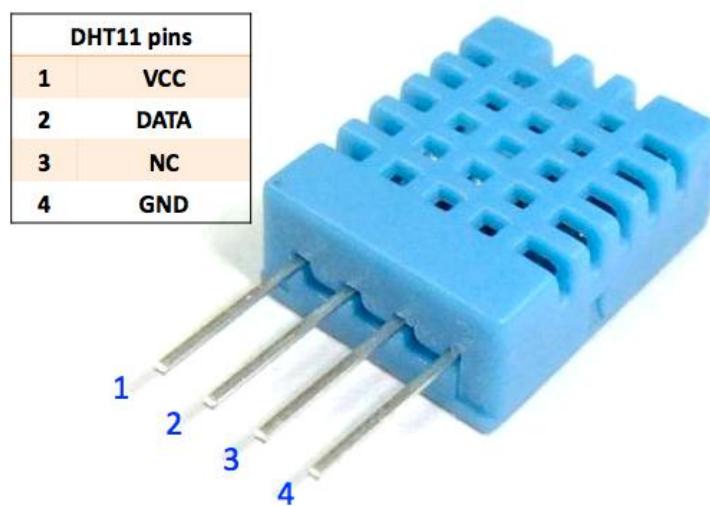
(1) x Elego Uno R3

(1) x DHT11 module

(3) x F-M wires

Component Introduction

Temp and humidity sensor:



DHT11 digital temperature and humidity sensor is a composite Sensor contains a calibrated digital signal output of the temperature and humidity. Application of a dedicated digital modules collection technology and the temperature and humidity sensing technology, to ensure that the product has high reliability and excellent long-term stability. The sensor

includes a resistive sense of wet components and an NTC temperature measurement devices, and connected with a high-performance 8-bit microcontroller.

Applications: HVAC, dehumidifier, testing and inspection equipment, consumer goods, automotive, automatic control, data loggers, weather stations, home appliances, humidity regulator, medical and other humidity measurement and control.

Product parameters

Relative humidity:

Resolution: 16Bit

Repeatability: $\pm 1\%$ RH

Accuracy: At 25°C $\pm 5\%$ RH

Interchangeability: fully interchangeable

Response time: 1 / e (63%) of 25°C 6s

1m / s air 6s

Hysteresis: $<\pm 0.3\%$ RH

Long-term stability: $<\pm 0.5\%$ RH / yr in

Temperature:

Resolution: 16Bit

Repeatability: $\pm 0.2^{\circ}\text{C}$

Range: At 25°C $\pm 2^{\circ}\text{C}$

Response time: 1 / e (63%) 10s

Electrical Characteristics

Power supply: DC $3.5\sim 5.5\text{V}$

Supply Current: measurement 0.3mA standby $60\mu\text{A}$

Sampling period: more than 2 seconds

Pin Description:

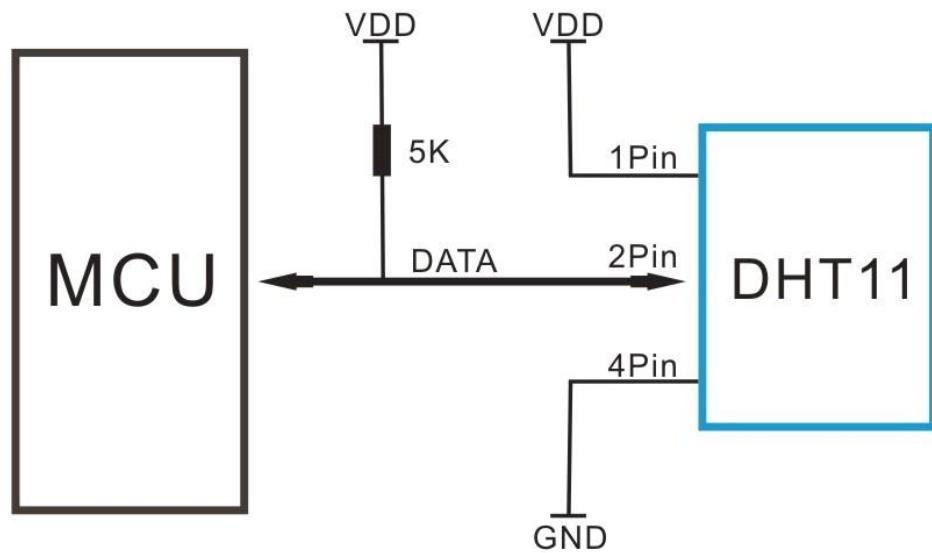
1, the VDD power supply $3.5\sim 5.5\text{V}$ DC

2 DATA serial data, a single bus

3, NC, empty pin

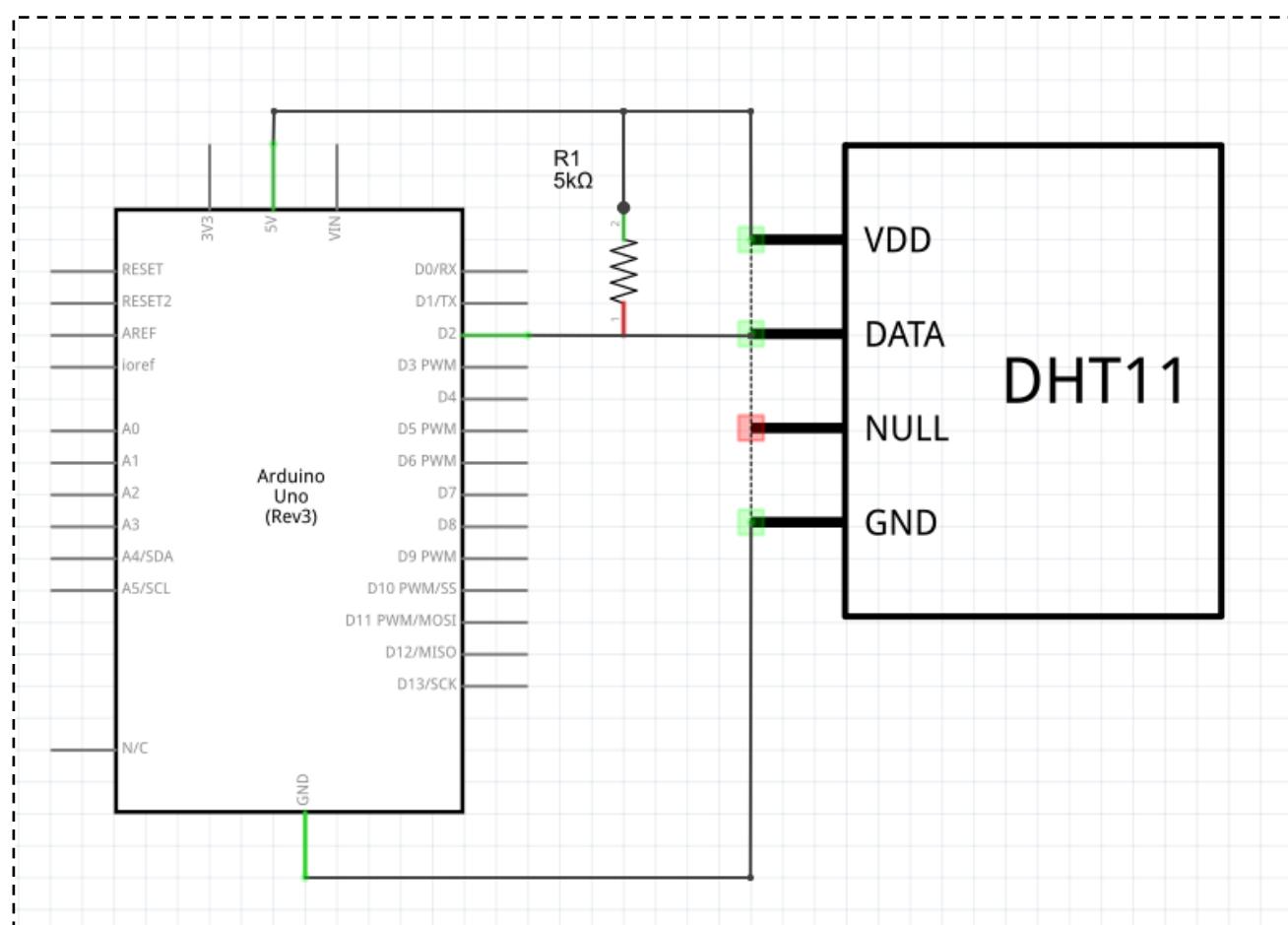
4, GND ground, the negative power

Typical Application

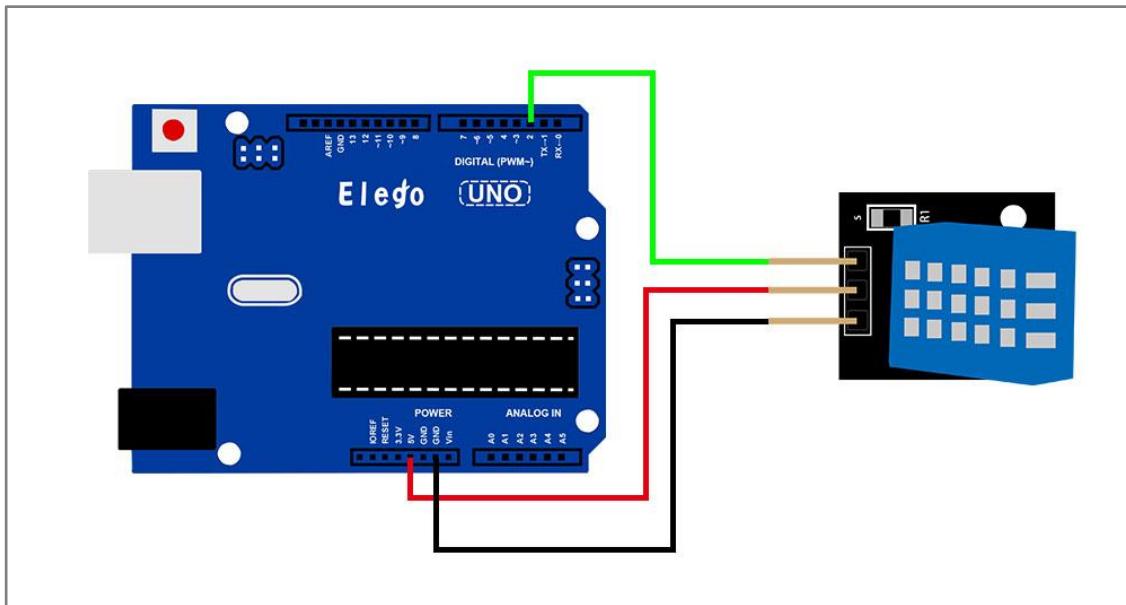


Connection

Schematic



wiring diagram



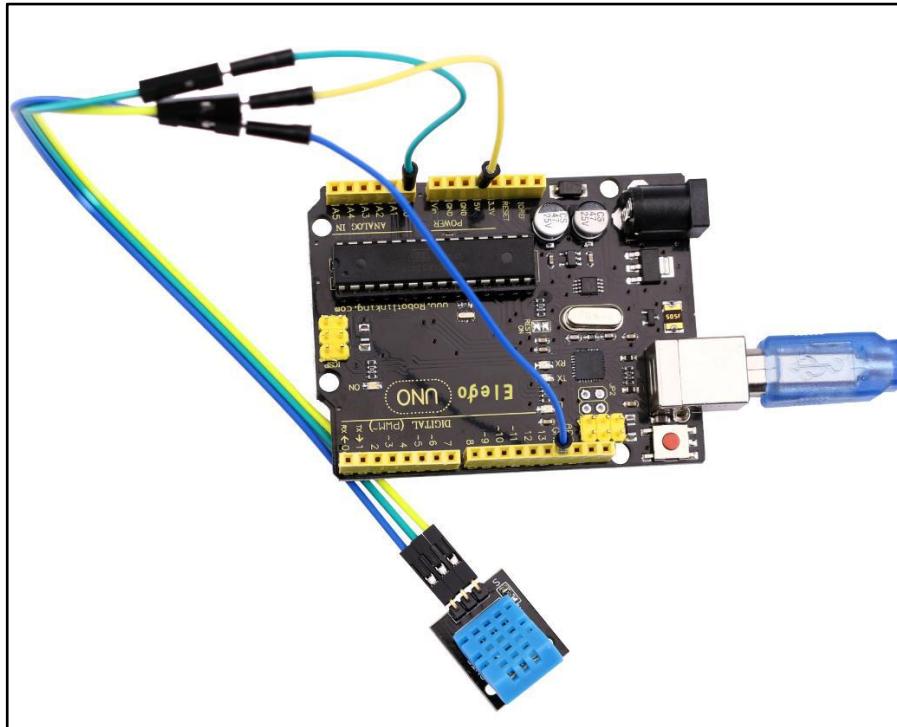
As you can see we only need 3 connections to the sensor, since one of the pin is not used.

The connection are : Voltage, Ground and Signal which can be connected to any Analog Pin on our UNO.

The Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <simpleDHT> library. Or you need to install again. If you do not do this, your code won't work.



Upload the program then open the monitor, we can see the data as below:(It shows the temperature of the environment, we can see it is 21 degree)

```
COM16 (Arduino/Genuino Uno)
发送
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Read DHT11 failed=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %

自动滚屏 没有结束符 9600 波特率
```

Lesson 21 Analog Joystick Module

Overview

Analog joysticks are a great way to add some control in your projects.

In this tutorial we will learn how to use the analog joystick module.

Component Required:

- (1) x Elego Uno R3
- (1) x Joystick module
- (5) x F-M wires

Component Introduction

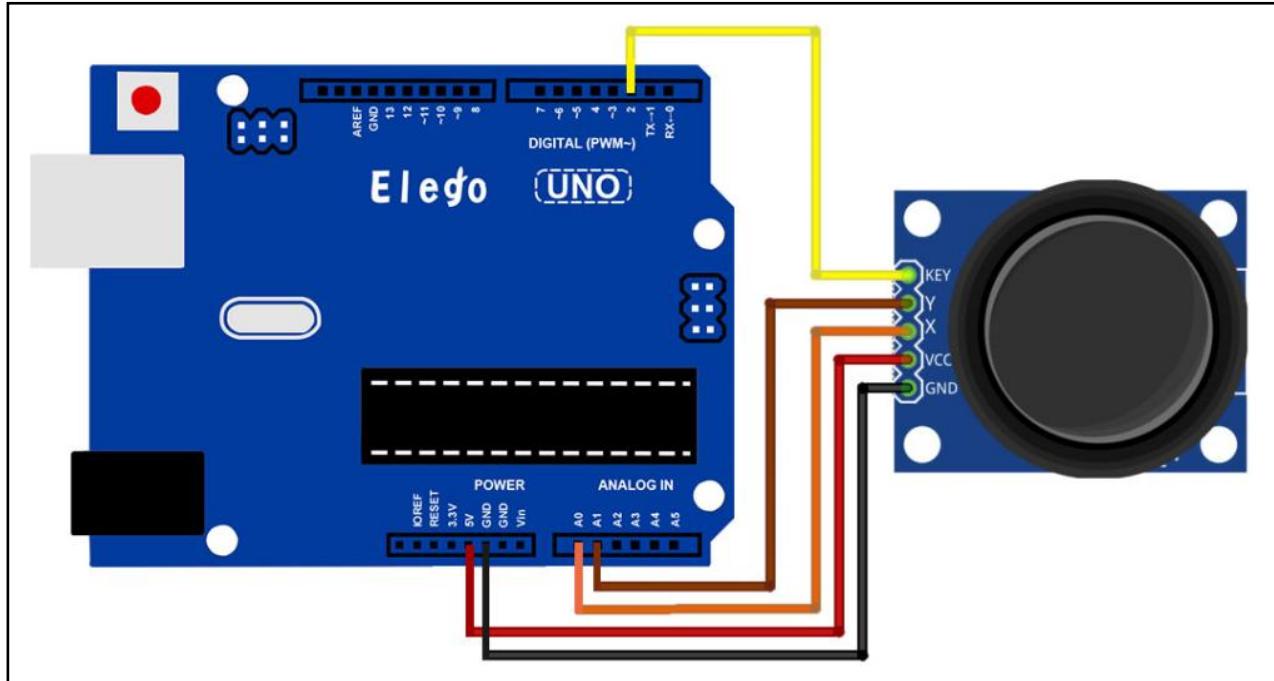
Joystick

The module has 5 pins: Vcc, Ground, X, Y, Key. Note that the labels on yours may be slightly different, depending on where you got the module from. The thumb stick is analog and should provide more accurate readings than simple 'directional' joysticks that use some forms of buttons, or mechanical switches. Additionally, you can press the joystick down (rather hard on mine) to activate a 'press to select' push-button.

We have to use analog Arduino pins to read the data from the X/Y pins, and a digital pin to read the button. The Key pin is connected to ground, when the joystick is pressed down, and is floating otherwise. To get stable readings from the Key /Select pin, it needs to be connected to Vcc via a pull-up resistor. The built in resistors on the Arduino digital pins can be used. For a tutorial on how to activate the pull-up resistors for Arduino pins, configured as inputs

Connection

wiring diagram



We need 5 connections to the joystick.

The connection are : Key, Y, X, Voltage and Ground.

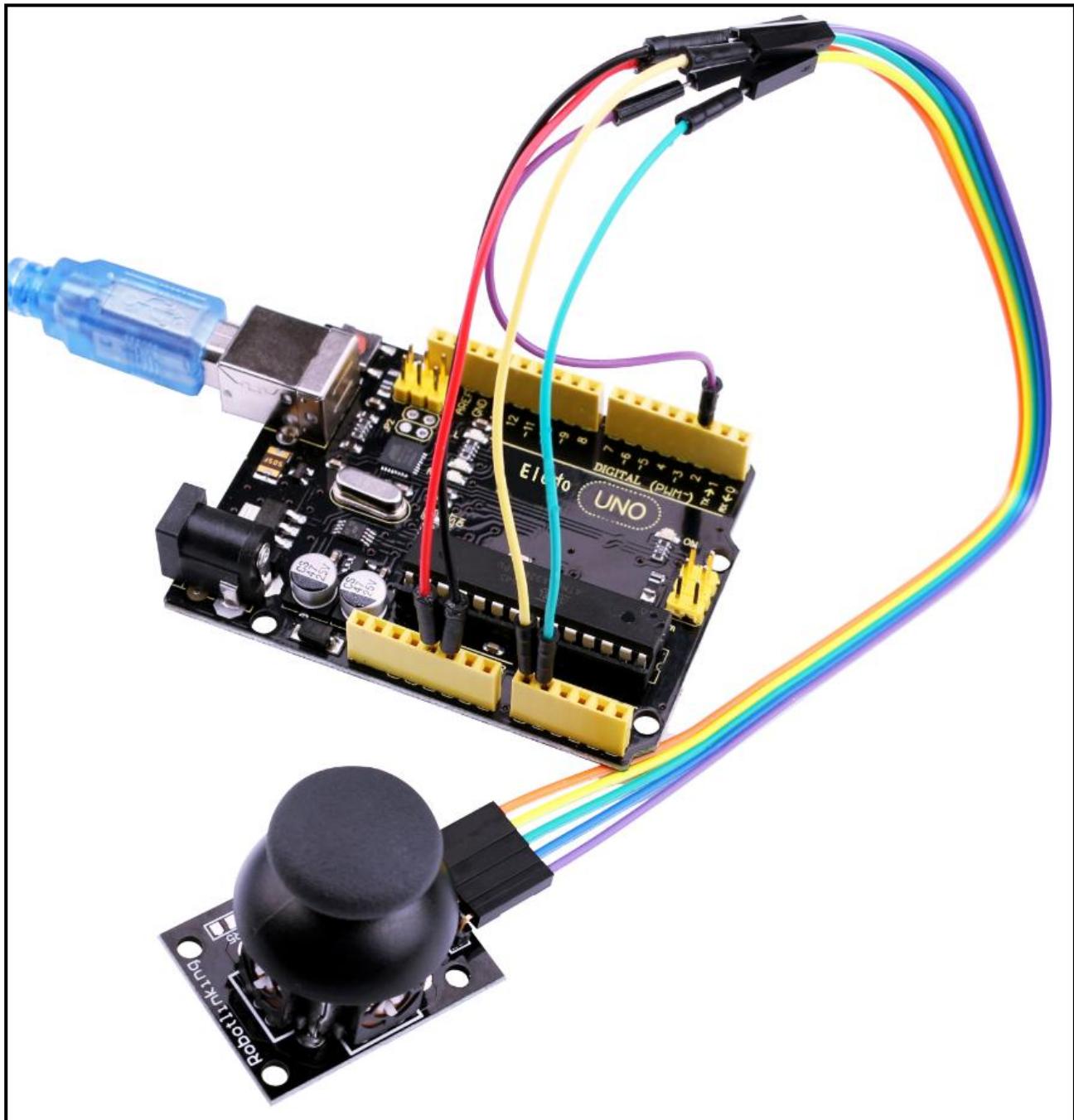
“Y and X” are Analog and “Key” is Digital. If you don't need the switch then you can use only 4 pins.

The Code

Analog joysticks are basically potentiometers so they return analog values.

When the joystick is in the resting position or middle, it should return a value of about 512.

The range of values go from 0 to 1024.



Lesson 22 IR Receiver Module

Overview

Using an IR Remote is a great way to have wireless control of your project.

Infrared remotes are simple and easy to use. In this tutorial we will be connecting the IR receiver to the UNO, and then use a Library that was designed for this particular sensor.

In our sketch we will have all the IR Hexadecimal codes that are available on this remote, we will also detect if the code was recognized and also if we are holding down a key.

Component Required:

(1) x Elego Uno R3

(1) x IR receiver module

(1) x IR remote

(3) x F-M wires

Component Introduction

IR RECEIVER SENSOR:

IR detectors are little microchips with a photocell that are tuned to listen to infrared light. They are almost always used for remote control detection - every TV and DVD player has one of these in the front to listen for the IR signal from the clicker. Inside the remote control is a matching IR LED, which emits IR pulses to tell the TV to turn on, off or change channels. IR light is not visible to the human eye, which means it takes a little more work to test a setup.

There are a few differences between these and say a CdS Photocells:

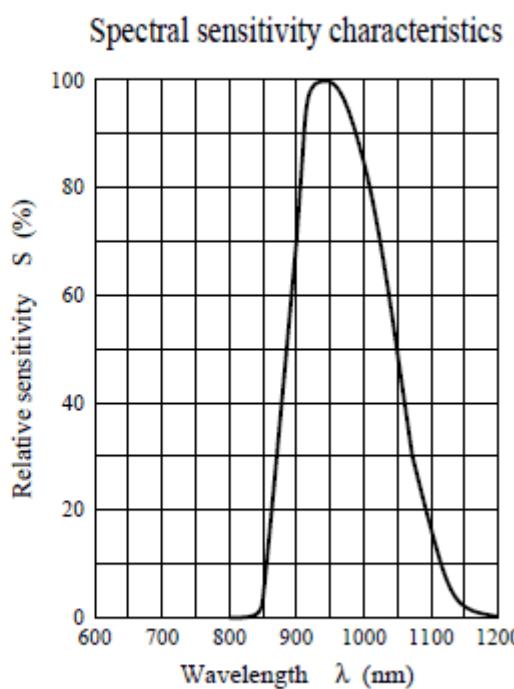
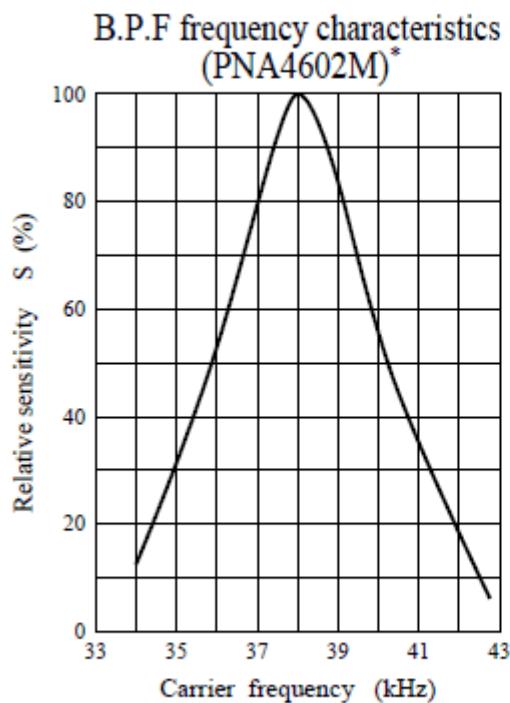
IR detectors are specially filtered for Infrared light, they are not good at detecting visible light. On the other hand, photocells are good at detecting yellow/green visible light, not good at IR light

- IR detectors have a demodulator inside that looks for modulated IR at 38 KHz. Just shining an IR LED won't be detected, it has to be PWM blinking at 38KHz. Photocells do not have any sort of demodulator and can detect any frequency (including DC) within

the response speed of the photocell (which is about 1KHz)

- IR detectors are digital out - either they detect 38KHz IR signal and output low (0V) or they do not detect any and output high (5V). Photocells act like resistors, the resistance changes depending on how much light they are exposed to.

What You Can Measure



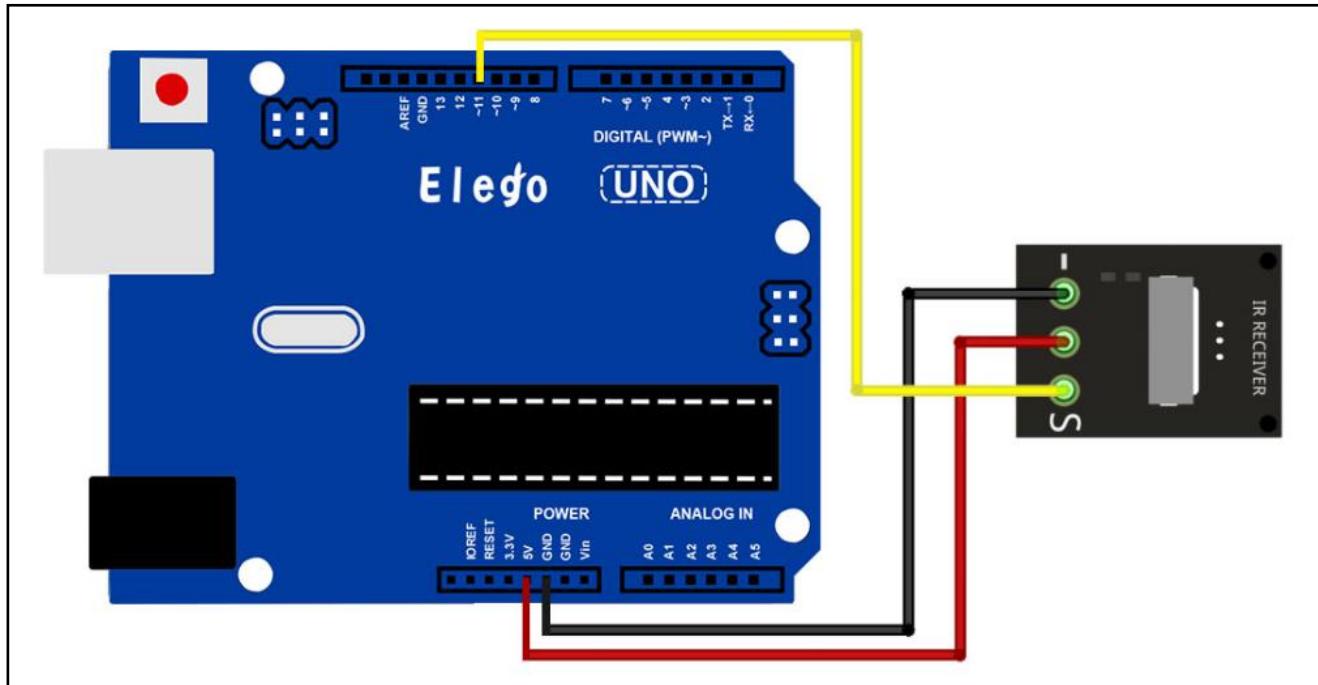
* The peaks for PNA4601M, PNA4608M, and PNA4610M are all f_0 .

As you can see from these datasheet graphs, the peak frequency detection is at 38 KHz and the peak LED color is 940 nm. You can use from about 35 KHz to 41 KHz but the sensitivity will drop off so that it won't detect as well from afar. Likewise, you can use 850 to 1100 nm LEDs but they won't work as well as 900 to 1000nm so make sure to get matching LEDs! Check the datasheet for your IR LED to verify the wavelength.

Try to get a 940nm - remember that 940nm is not visible light (its Infra Red)!

Connection

wiring diagram



There are 3 connections to the IR Receiver.

The connections are : Signal, Voltage and Ground.

The “-” is the Ground, “S” is signal, and middle pin is Voltage 5V.

The Code

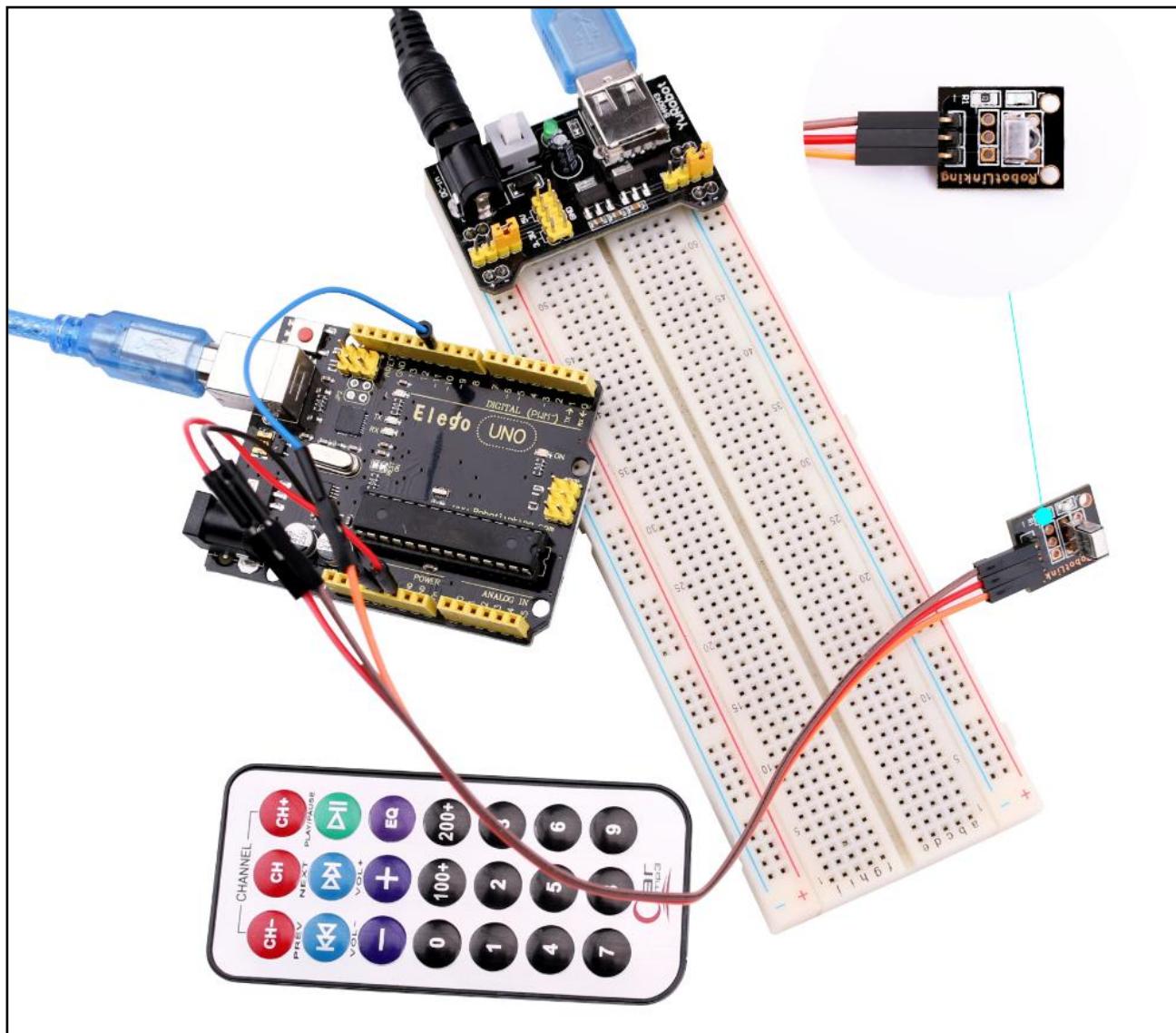
Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <IRremote> library.

Or you need to install again. If you do not do this, your code won't work.

Next we will move the <RobotIRremote> out of the Library folder, we do this because that library conflicts with the one we will be using. You can just drag it back inside the library folder once you are done programming your microcontroller.

Once you have installed the Library, just go ahead and restart your IDE Software.



Lesson 23 MAX7219 LED Dot Matrix Module

Overview

In this tutorial we will connect a MAX7219 and scroll the text across.

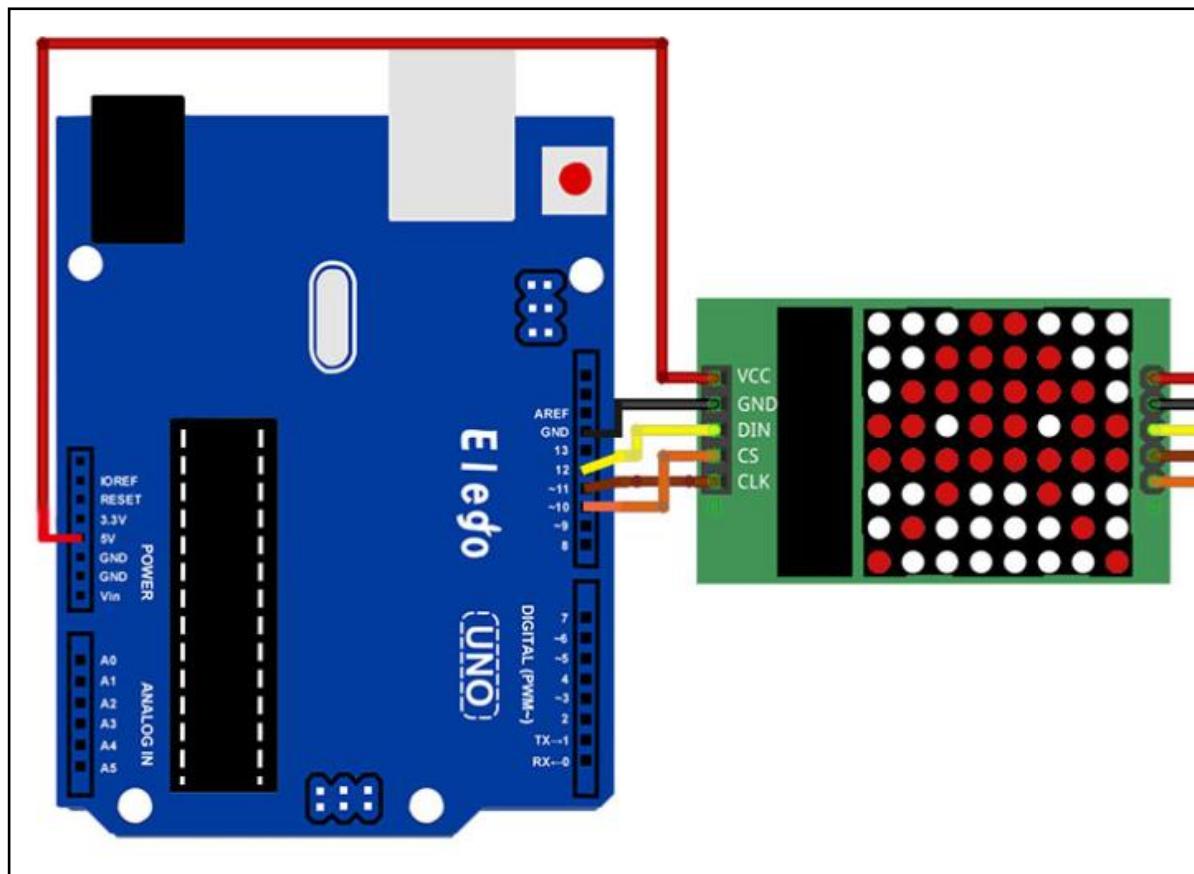
Since these modules use the MAX7219 LED driver chip, we will be able to turn on and off the 64 LEDs of each modules, using only 3 pins on our UNO.

Component Required:

- (1) x Elego Uno R3
- (1) x Max7219 module
- (5) x F-M wires

Connection

wiring diagram



VCC and Ground are connected to the Arduino.

Pin 12 is connected to DIN, Pin 10 is connected to CS and Pin 11 is connected to CLK.

We then daisy-chain the modules together.

The Code

Our Sketch will make use of the “Maxmatrix” Library to communicate with the MAX7219 modules.

Now that we have the physical setup, all we need now is the code.

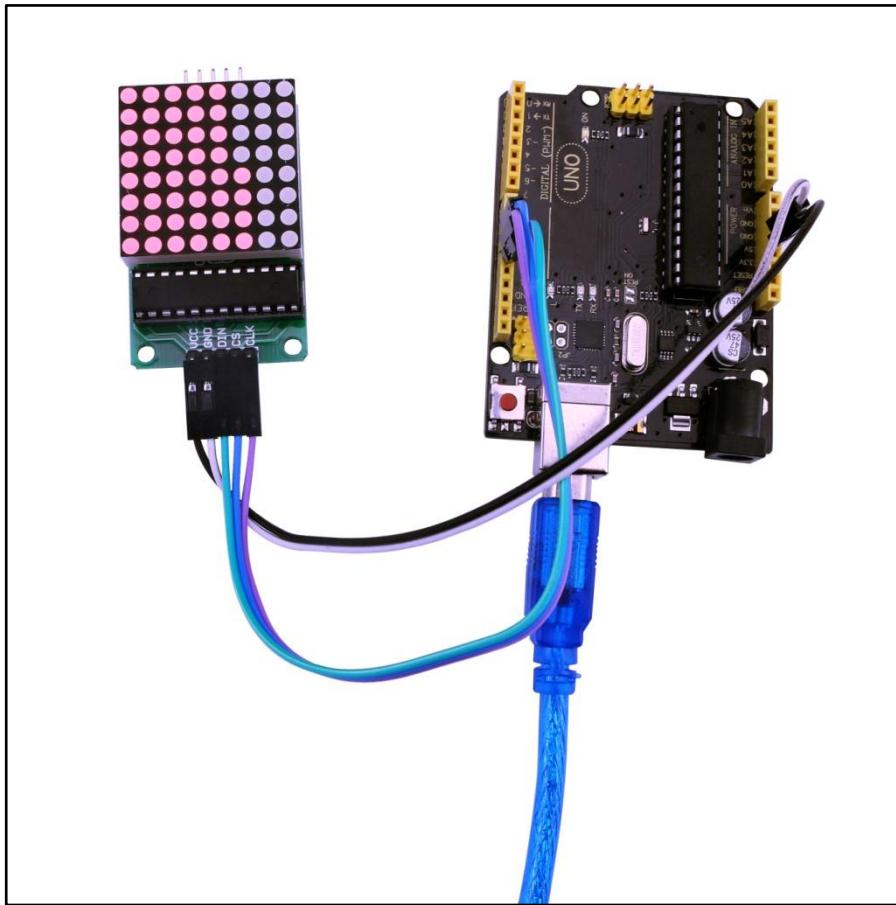
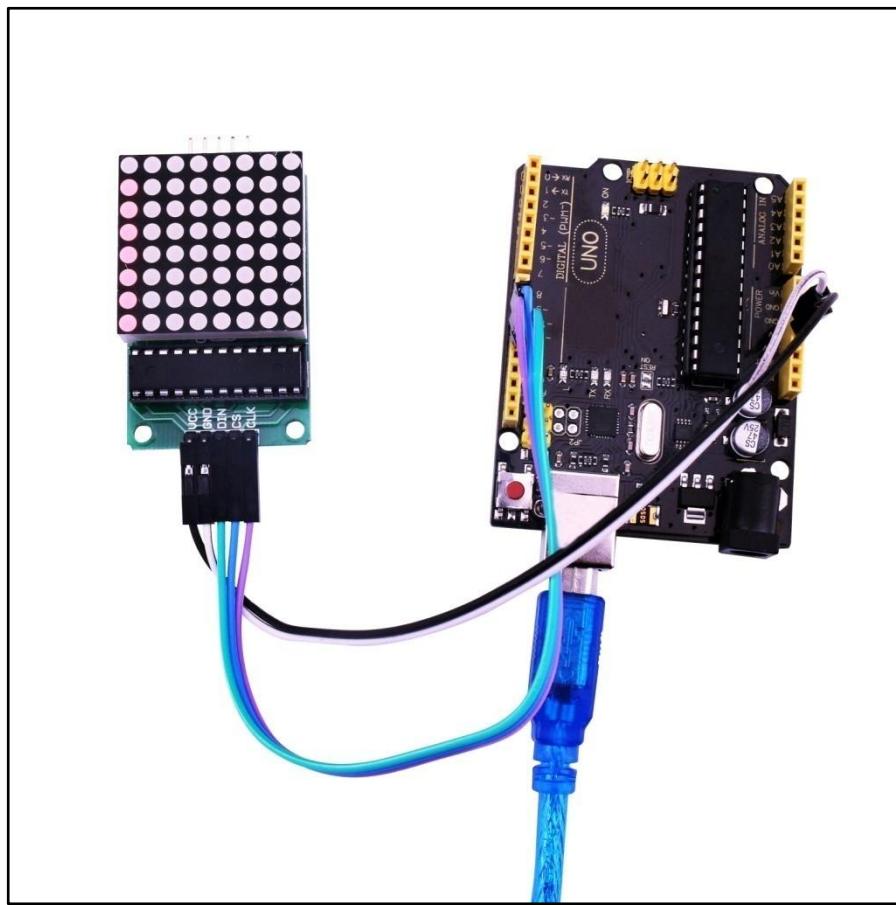
Before you can run this, you have to make sure that you have install the <LedControl> library.

Or you need to install again. If you do not do this, your code won't work.

Since we are defining all the characters possible (0-9 a-z etc..), instead of using the SRAM (2048 bytes), we will put that information in Flash memory on our UNO since that information will not change and also there's more Flash memory available (32k).

We do this by using the “#include <avr/pgmspace.h>” and then “PROGMEM prog uchar CH[] =” to put our array information in Flash memory.

Note: Flash (PROGMEM) memory can only be populated when we upload the code to our UNO. You can't change the values in the flash after the program has started running, unlike SRAM where our sketch is run.



Lesson 24 ADXL335 Module

Overview

The ADXL335 3-Axis module can measures magnetic fields in three directions: X, Y, and Z.

ADXL335 is a kind of acceleration sensor which is high precision, low power consumption and single IC chip. The voltage is between 1.8 V to 3.6 V. And its temperature range is between - 55 ° C to 125 ° C. This product size is only 22 mm x 23 mm so that it is a very convenient project embedded hardware. Here is a special remind: Do not power the module by the UNO R3 board 5v pin. The 3v pin is better.

In this lesson we will learn how to use a ADXL335 module.

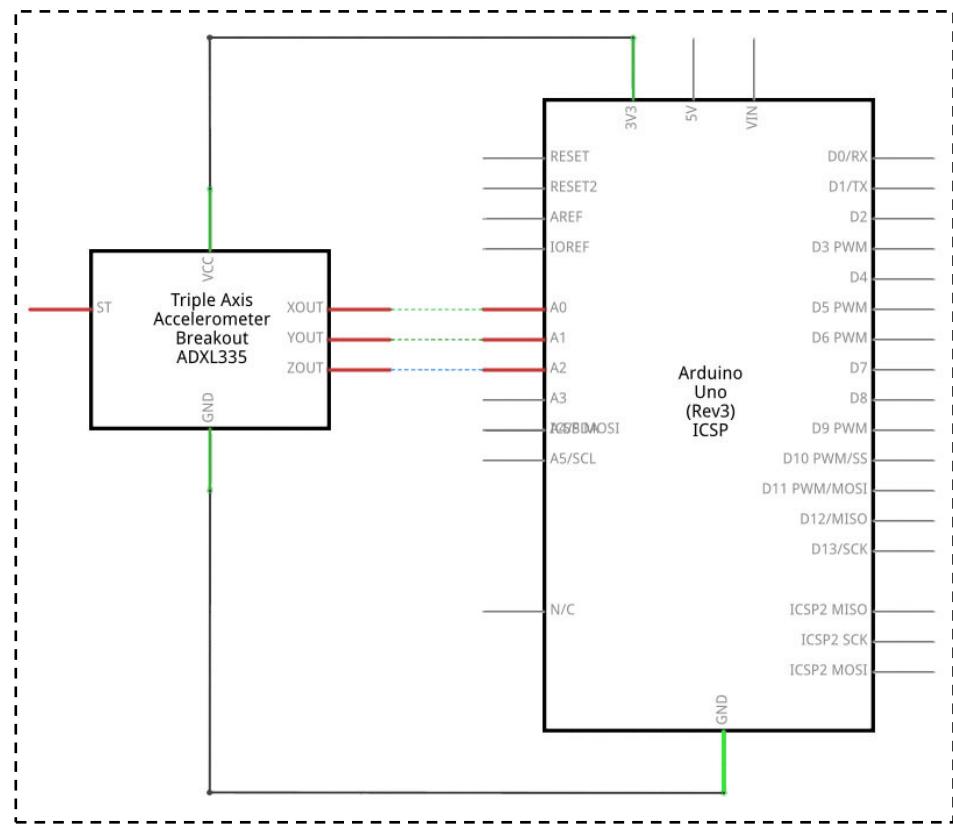
There are libraries available for this sensor that will enable you to tap into more capabilities.

Component Required:

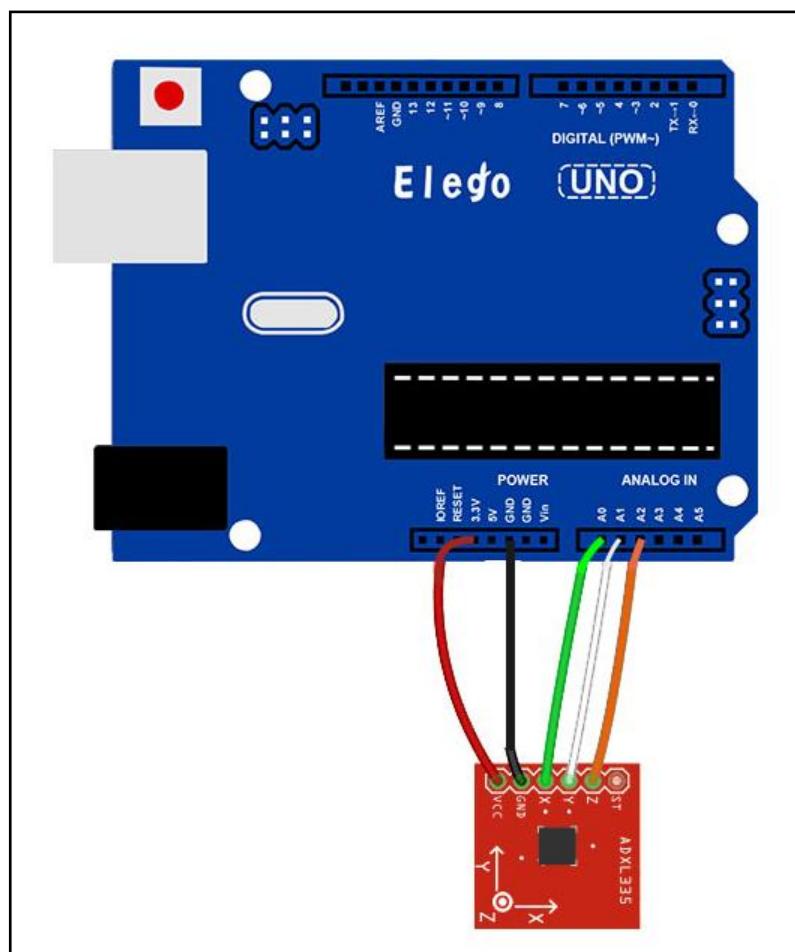
- (1) x Elego Uno R3
- (1) x ADXL335 module
- (5) x F-M wires

Connection

Schematic



wiring diagram

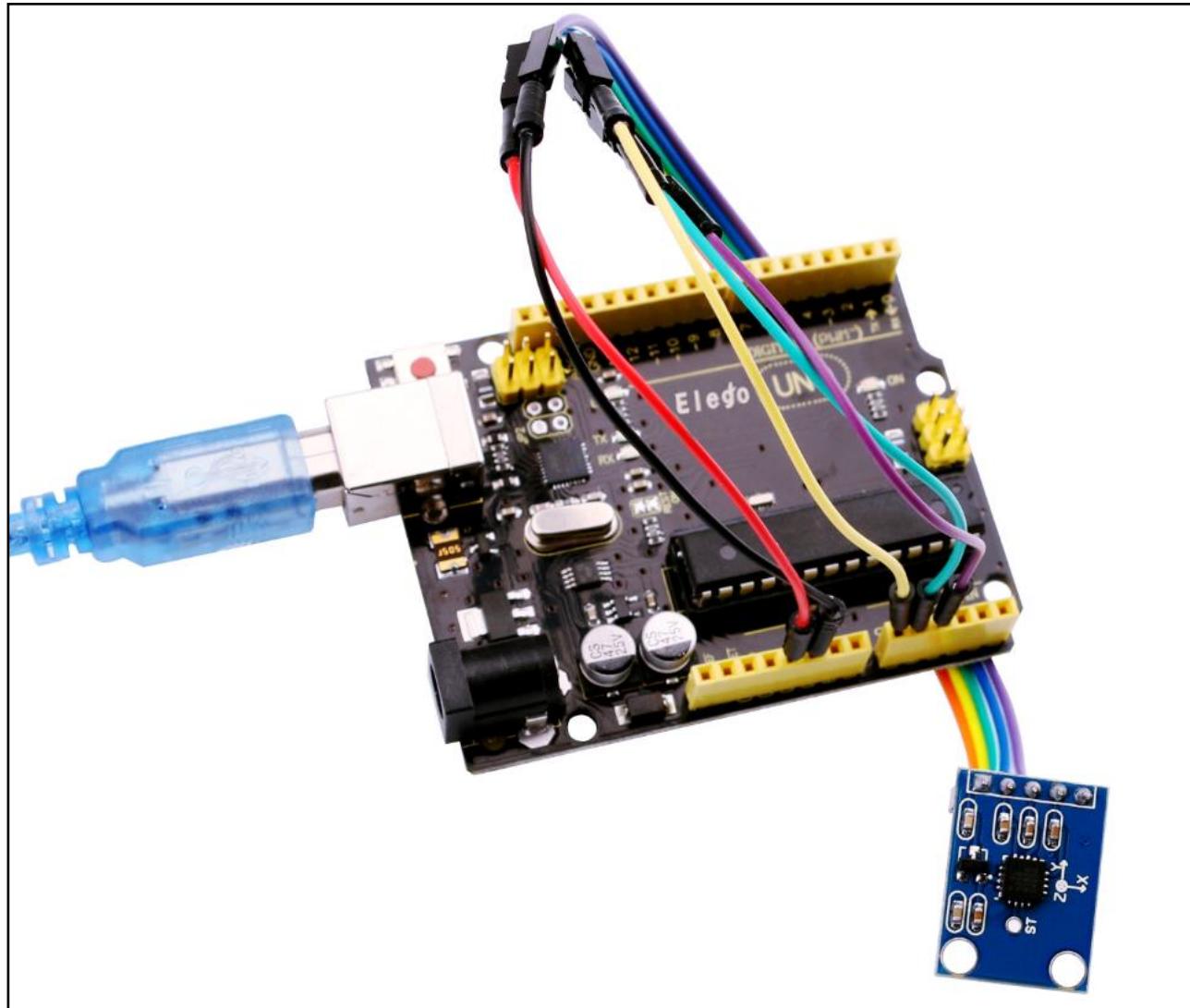


Because the output of ADXL335 is analog voltage value. So when we write programs, our focus is to collect the output voltage. But if you need to do some big project like accurately measuring the specific number, you need to search the technical data for reference.

After uploading program, we open the serial port, you can see we test data shown on the window. When the acceleration changing, the corresponding Numbers will change too.

The code

See the code file.



Lesson 25 HC-SR501 PIR Sensor

Overview

In this lesson you will learn how to use a PIR movement detector with an UNO.

The UNO is the heart of this project. It 'listens' to the PIR sensor and when motion is detect, instructs the LED to light on or shut off.

Component Required:

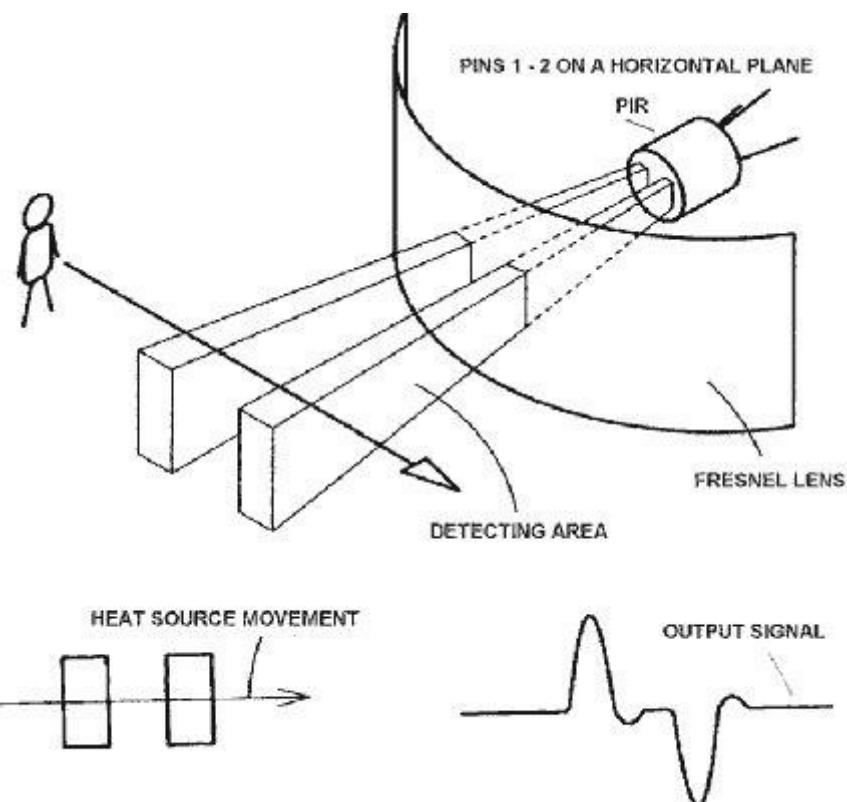
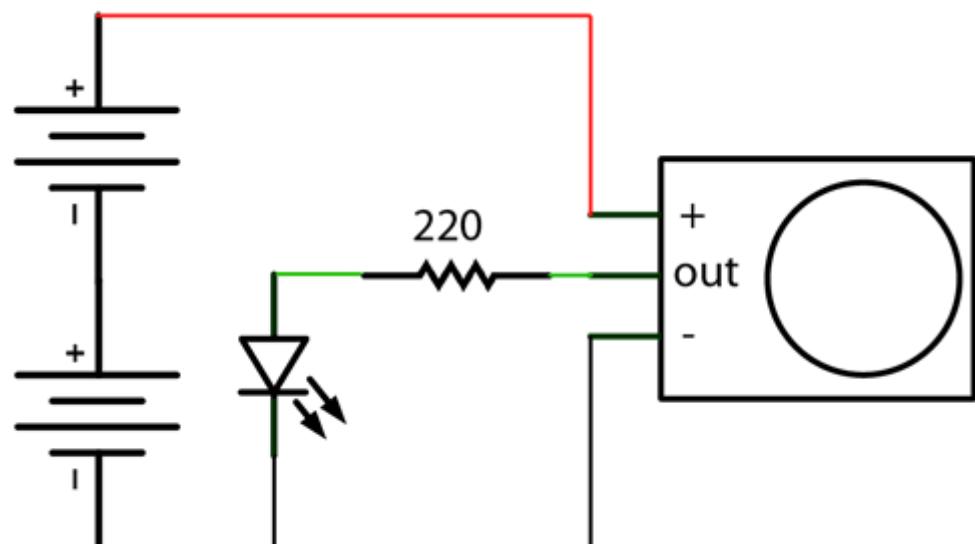
- (1) x Elego Uno R3
- (1) x HC-SR501
- (3) x F-M wires

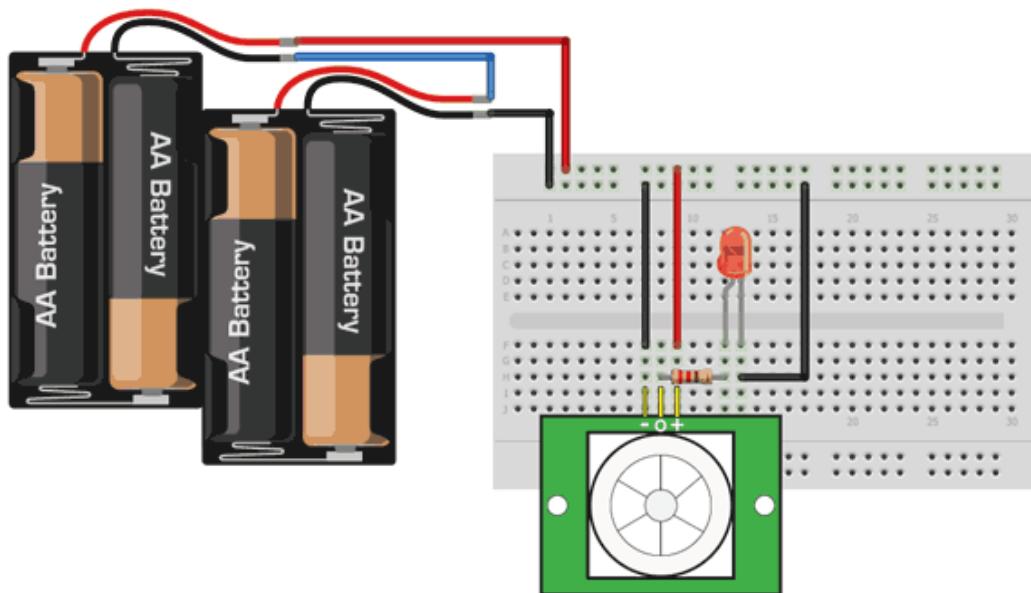
Component Introduction

PIR SENSOR:

PIR sensors are more complicated than many of the other sensors explained in these tutorials (like photocells, FSRs and tilt switches) because there are multiple variables that affect the sensors input and output. To begin explaining how a basic sensor works, we'll use this rather nice diagram (if anyone knows where it originates plz let me know).

The PIR sensor itself has two slots in it, each slot is made of a special material that is sensitive to IR. The lens used here is not really doing much and so we see that the two slots can 'see' out past some distance (basically the sensitivity of the sensor). When the sensor is idle, both slots detect the same amount of IR, the ambient amount radiated from the room or walls or outdoors. When a warm body like a human or animal passes by, it first intercepts one half of the PIR sensor, which causes a positive differential change between the two halves. When the warm body leaves the sensing area, the reverse happens, whereby the sensor generates a negative differential change. These change pulses are what is detected.

**TESTING PIR SENSOR MODULE:**



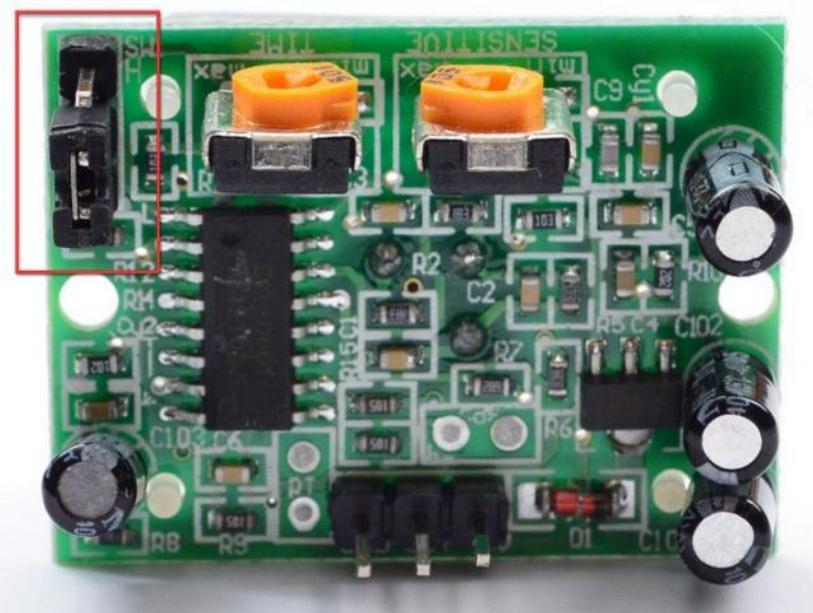
Now when the PIR detects motion, the output pin will go "high" to 3.3V and light up the LED!

Once you have the breadboard wired up, insert batteries and wait 30-60 seconds for the PIR to 'stabilize'. During that time the LED may blink a little. Wait until the LED is off and then move around in front of it, waving a hand, etc, to see the LED light up!

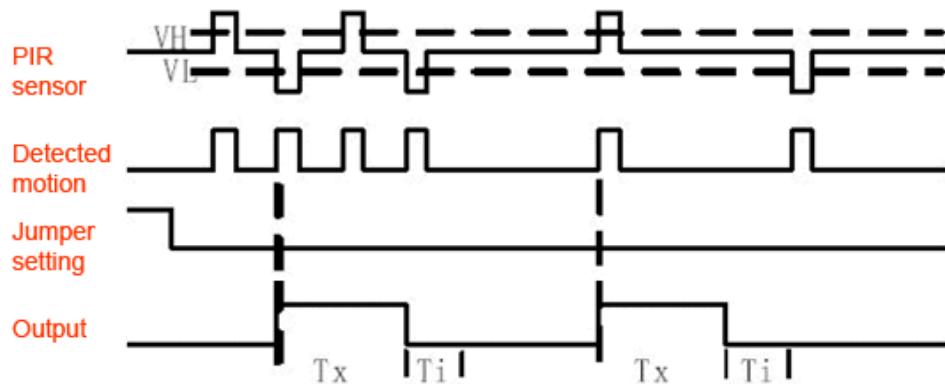
Retriggering

There's a couple options you may have with your PIR. First up we'll explore the 'Retriggering' option.

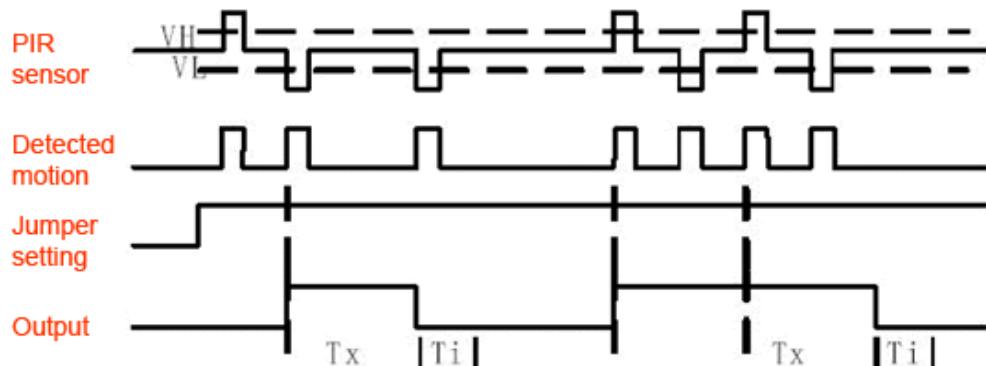
Once you have the LED blinking, look on the back of the PIR sensor and make sure that the jumper is placed in the L position as shown below.



Now set up the testing board again. You may notice that when connecting up the PIR sensor as above, the LED does not stay on when moving in front of it but actually turns on and off every second or so. That is called "non-retriggering".



Now change the jumper so that it is in the H position. If you set up the test, you will notice that now the LED does stay on the entire time that something is moving. That is called "retriggering".



(The graphs above are from the BISS0001 datasheet, they kinda suck)

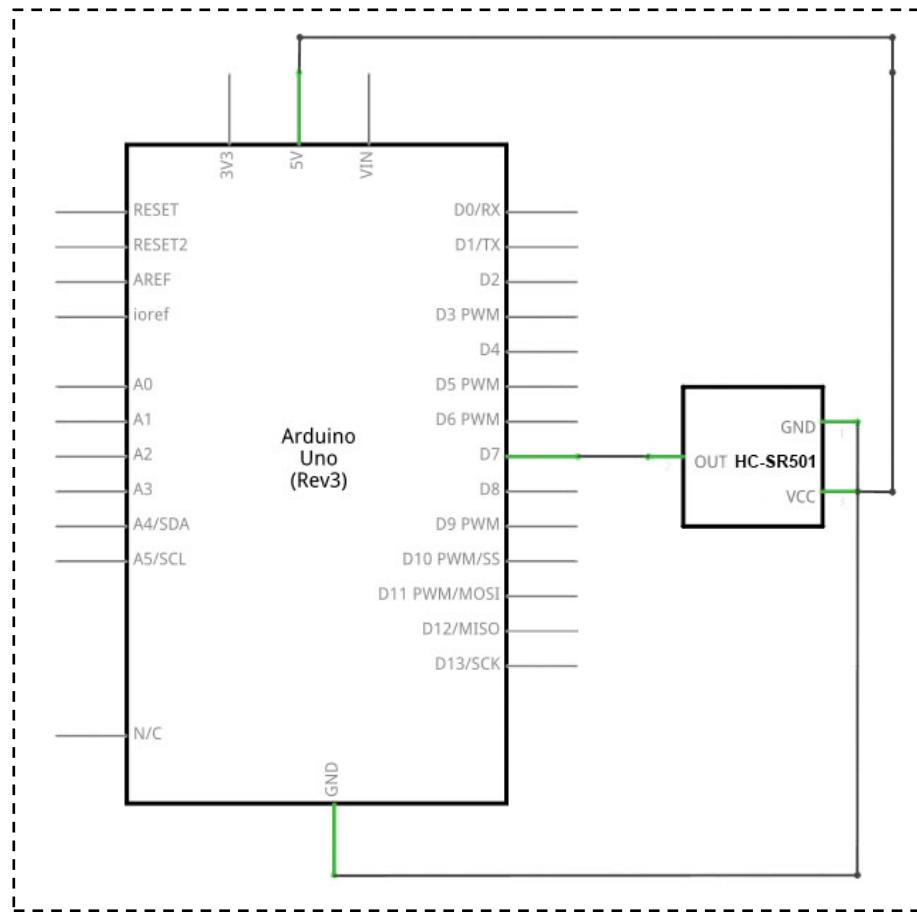
For most applications, "retriggering" (jumper in H position as shown below) mode is a little nicer.



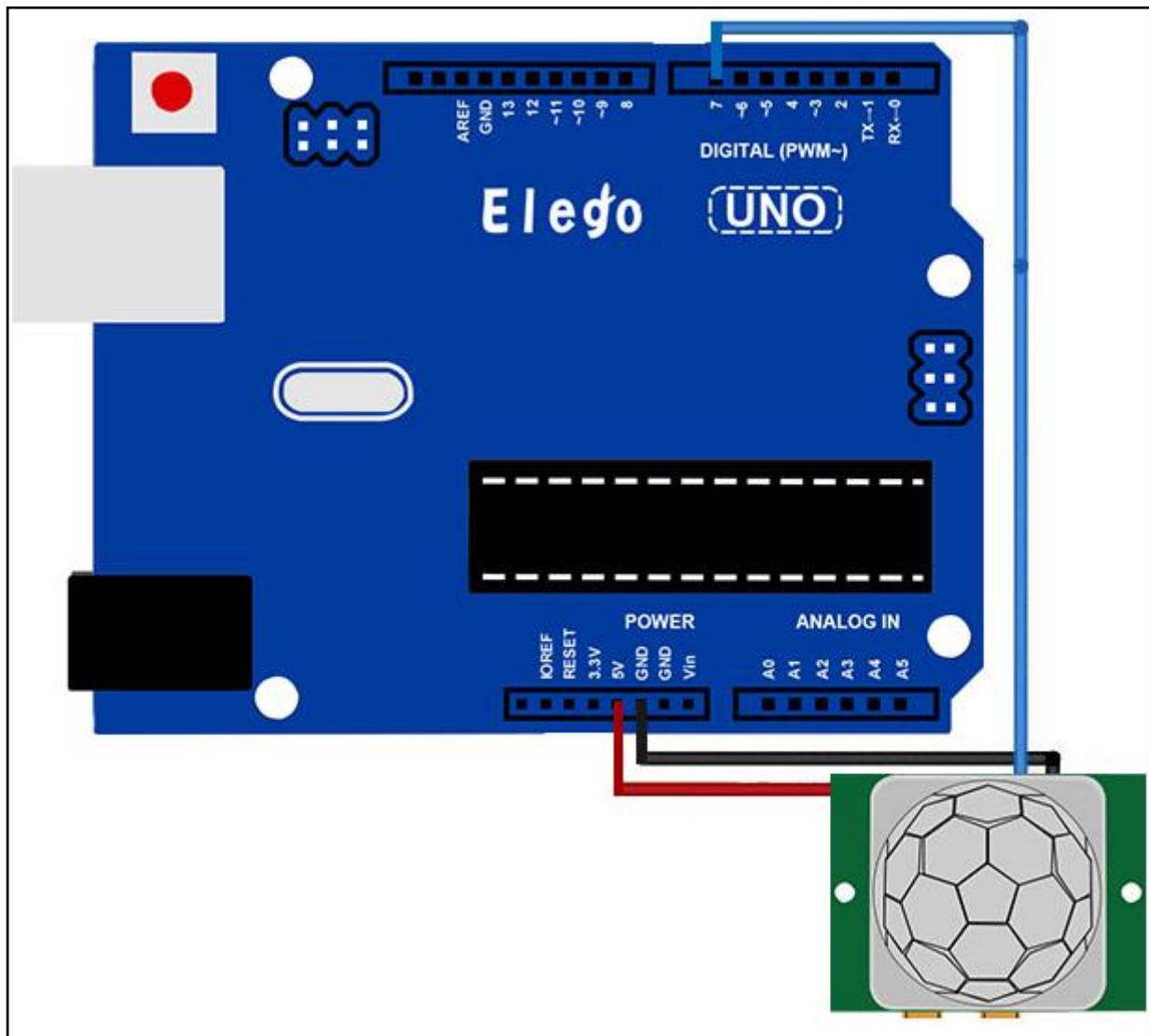
If you need to connect the sensor to something edge-triggered, you'll want to set it to "non-retriggering" (jumper in L position).

Connection

Schematic



wiring diagram



Connecting PIR sensors to a microcontroller is really simple. The PIR acts as a digital output so all you need to do is listen for the pin to flip high (detected) or low (not detected).

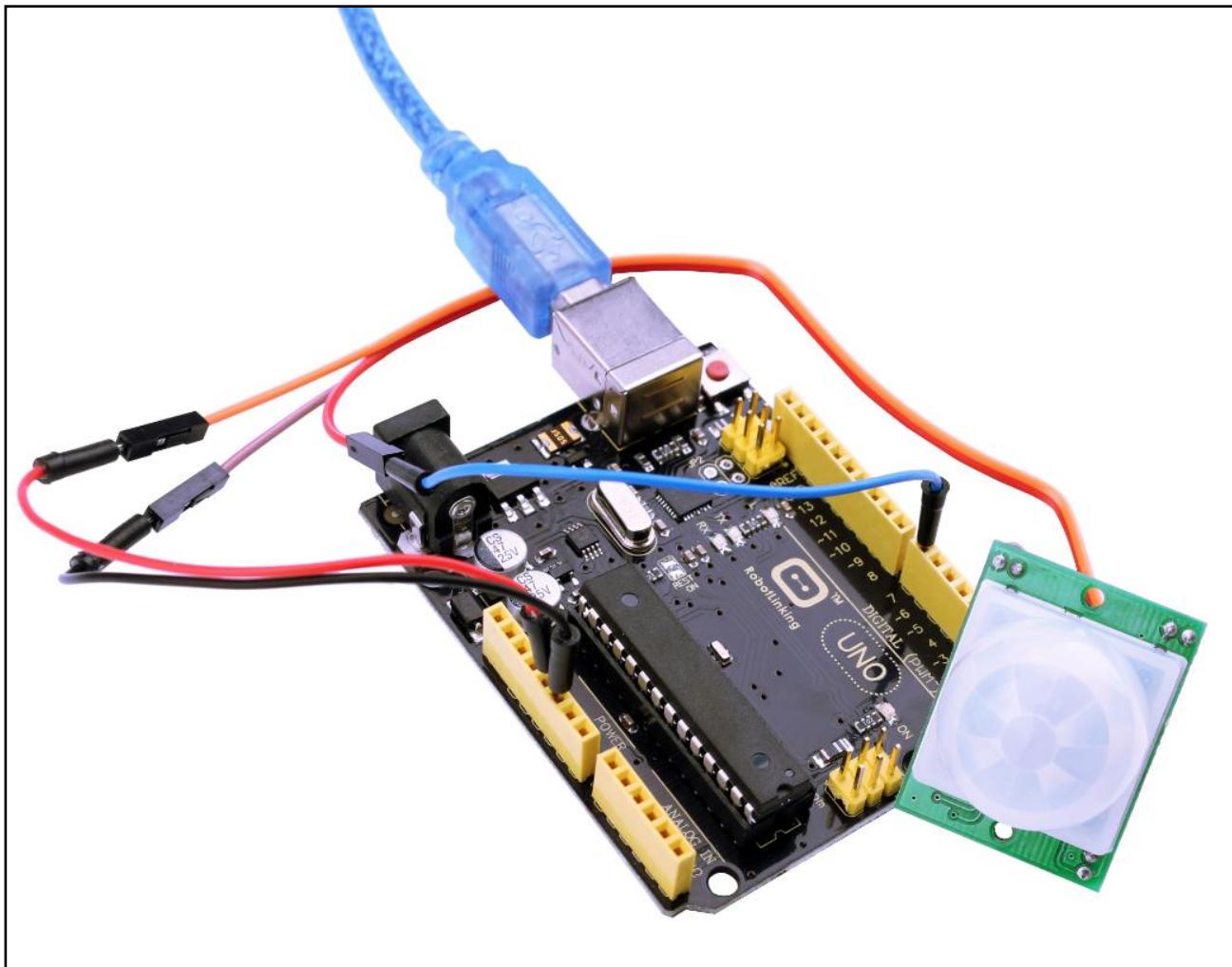
Its likely that you'll want rerigging, so be sure to put the jumper in the H position!

Power the PIR with 5V and connect ground to ground. Then connect the output to a digital pin. In this example we'll use pin 2.

The Code

The code is very simple, and is basically just keeps track of whether the input to pin 2 is high or low. It also tracks the state of the pin, so that it prints out a message when motion has started and stopped.

Don't forget that there are some times when you don't need a microcontroller. A PIR sensor can be connected to a relay (perhaps with a transistor buffer) without a micro!



Lesson 26 Water Level Detection Sensor Module

Overview

In this lesson, we will learn how to use a water level detection sensor module.

Water level detection sensor module is the module that can perceive the depth of water, the core component is amplifying circuit which is made up of a transistor and several pectinate PCB routings, these pectinate routings will present a resistor that can change along with the change of the water's depth when they are put into the water. Then, the signal of water's depth is converted into the electrical signal, and we can know the change of water's depth through the ADC function of our UNO R3.

Component Required:

- (1) x Elego Uno R3
- (1) x Water lever detection sensor module
- (3) x F-M wires

Component Introduction

Water sensor:

Water sensor brick is designed for water detection, which can be widely used in sensing the rainfall, water level, even the liqueate leakage. The brick is mainly comprised of three parts: An Electronic brick connector, a $1\text{ M}\Omega$ resistor, and several lines of bare conducting wires.

This sensor works by having a series of exposed traces connected to ground and interlaced between the grounded traces are the sense traces.

The sensor traces have a weak pull-up resistor of $1\text{ M}\Omega$. The resistor will pull the sensor trace value high until a drop of water shorts the sensor trace to the grounded trace. Believe it or not this circuit will work with the digital I/O pins of your UNO R3 board or you can use it with the analog pins to detect the amount of water induced contact between the grounded and

sensor traces.

This item can judge the water level through with a series of exposed parallel wires stitch to measure the water droplet/water size .

This item can easily change the water size to analog signal, and output analog value can directly be used in the program function, then to achieve the function of water level alarm.

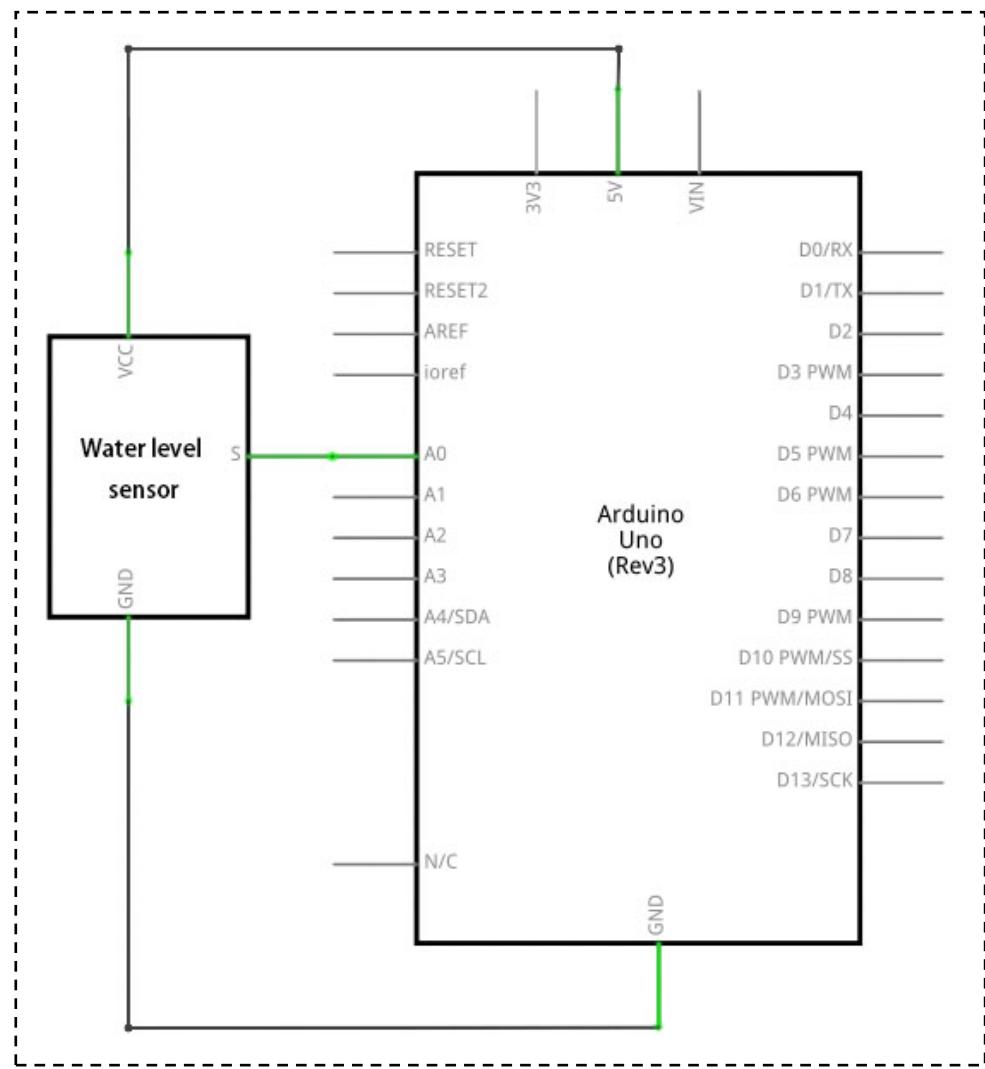
This item have low power consumption, and high sensitivity, which are the biggest characteristics of this module.

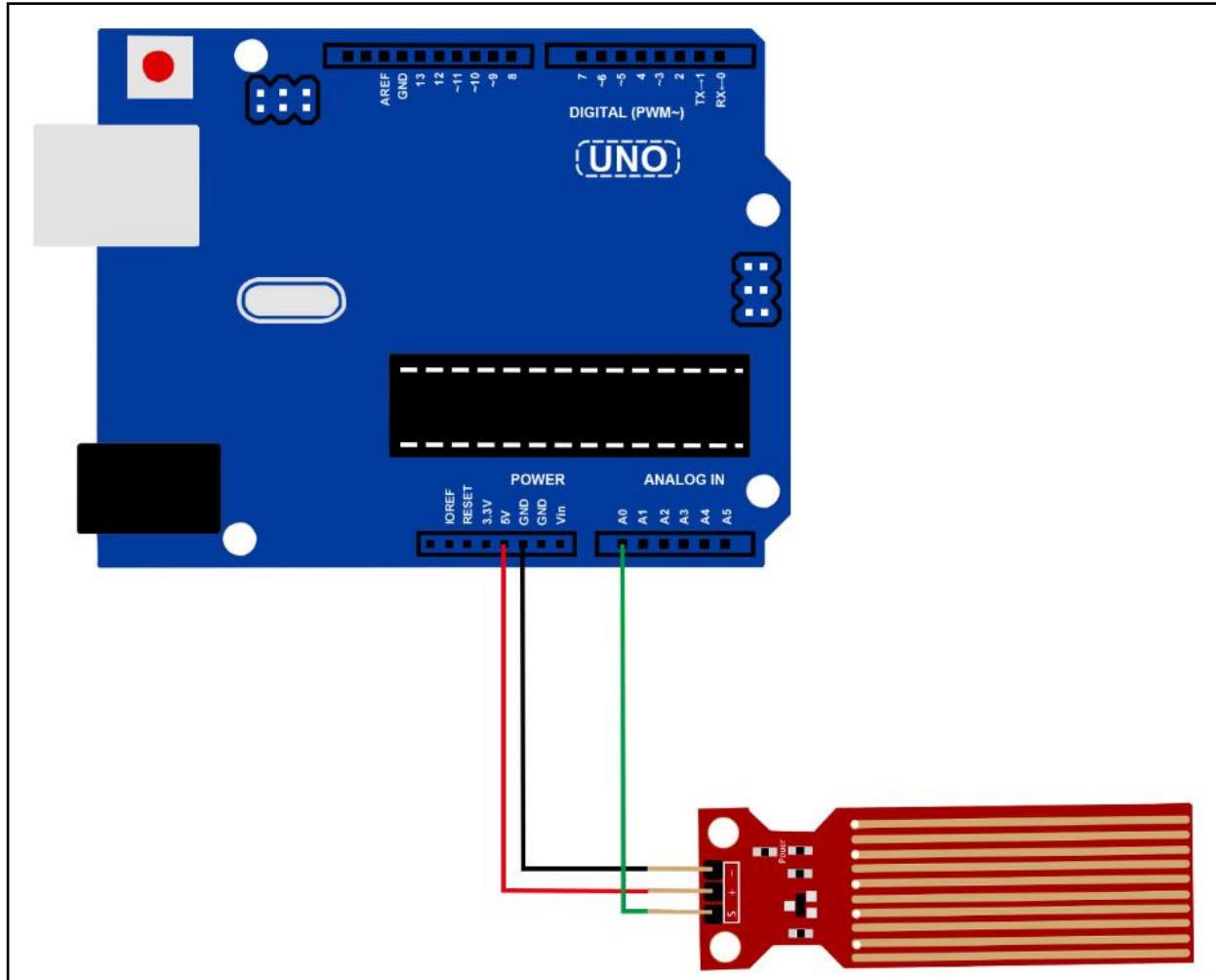
Features: Features: Features: Features:

- 1、Working voltage: 5V
- 2、Working Current: <20ma
- 3、Interface: Analog
- 4、Width of detection: 40mm×16mm
- 5、Working Temperature: 10°C~30°C
- 6、Output voltage signal: 0~4.2V

Connection

Schematic

**wiring diagram**



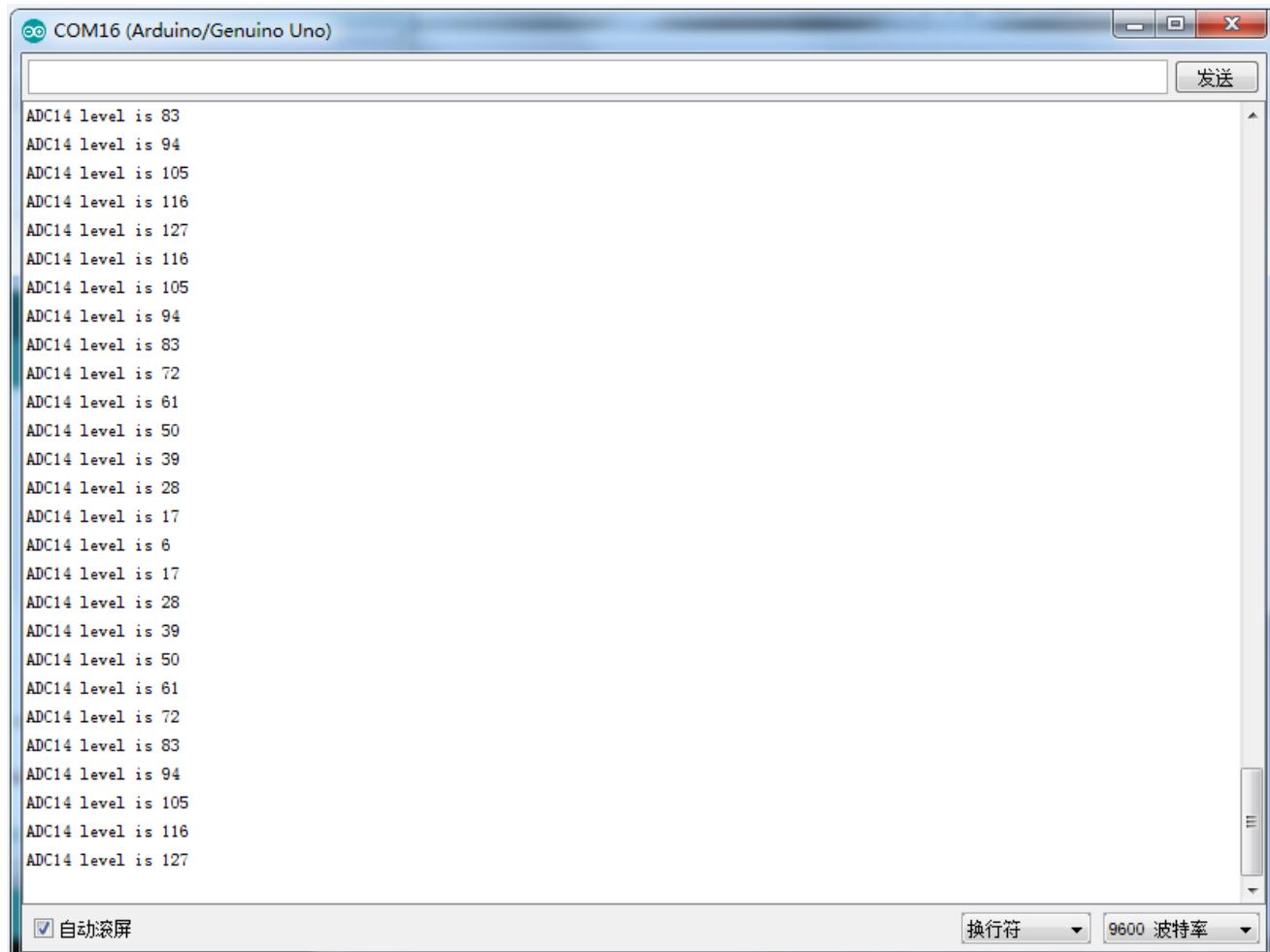
Wiring tips: power supply (+) is connected to 5V of UNO R3 board, ground electrode (-) is connected to GND. Signal output (S) is connected to the ports (A0-A5) which have function of inputting analog signal in UNO R3 board, random one is OK, but it should define the same demo code as the routine

The code

See the code file.



open the monitor you can see the data as below:



Lesson 27 Real Time Clock Module

Overview

In this lesson, we will learn the principle of a clock.

DS3231 is a clock module that is made in maxim, which supports year, month, day, hours, minutes, seconds and week display. Support is backup battery trickle charge, which can be used unless being connected to UNO with only three data cables.

Component Required:

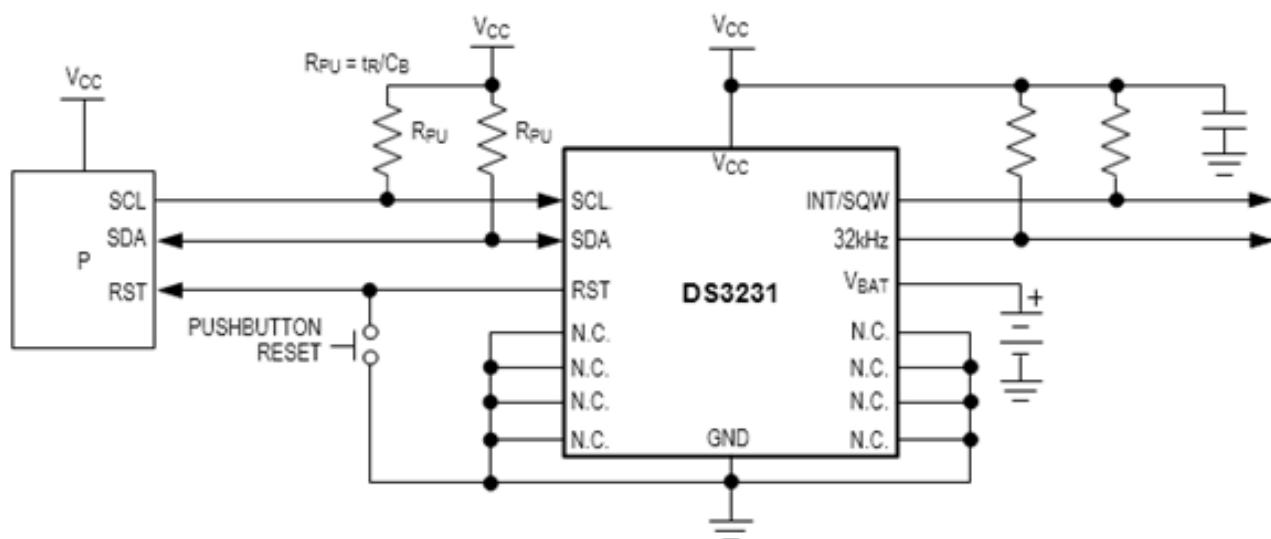
- (1) x Elego Uno R3
- (1) x DS3231 real time clock module
- (4) x F-M wires

Component Introduction

DS1302

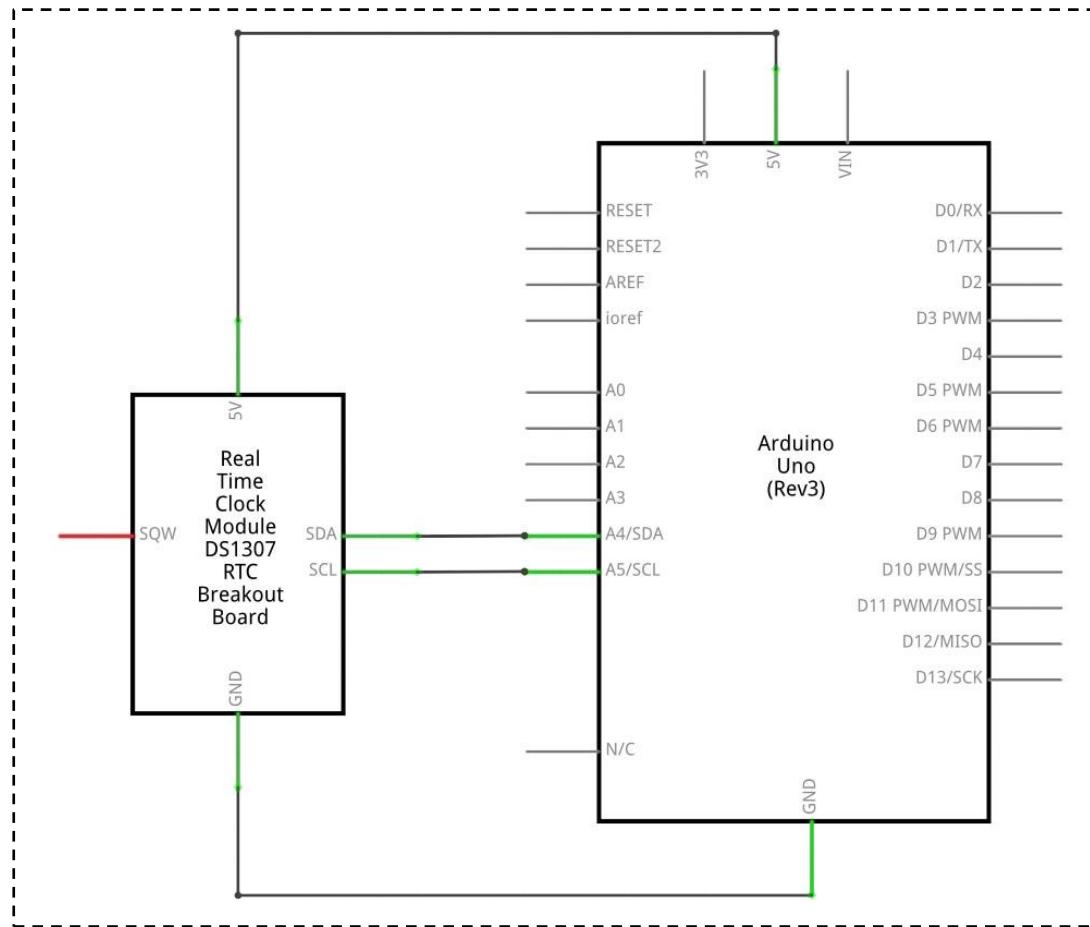
DS3231

The DS3231 is a simple time-keeping chip. The handy thing about it is that there is an integrated battery, so the clock can continue keeping time, even when unplugged.

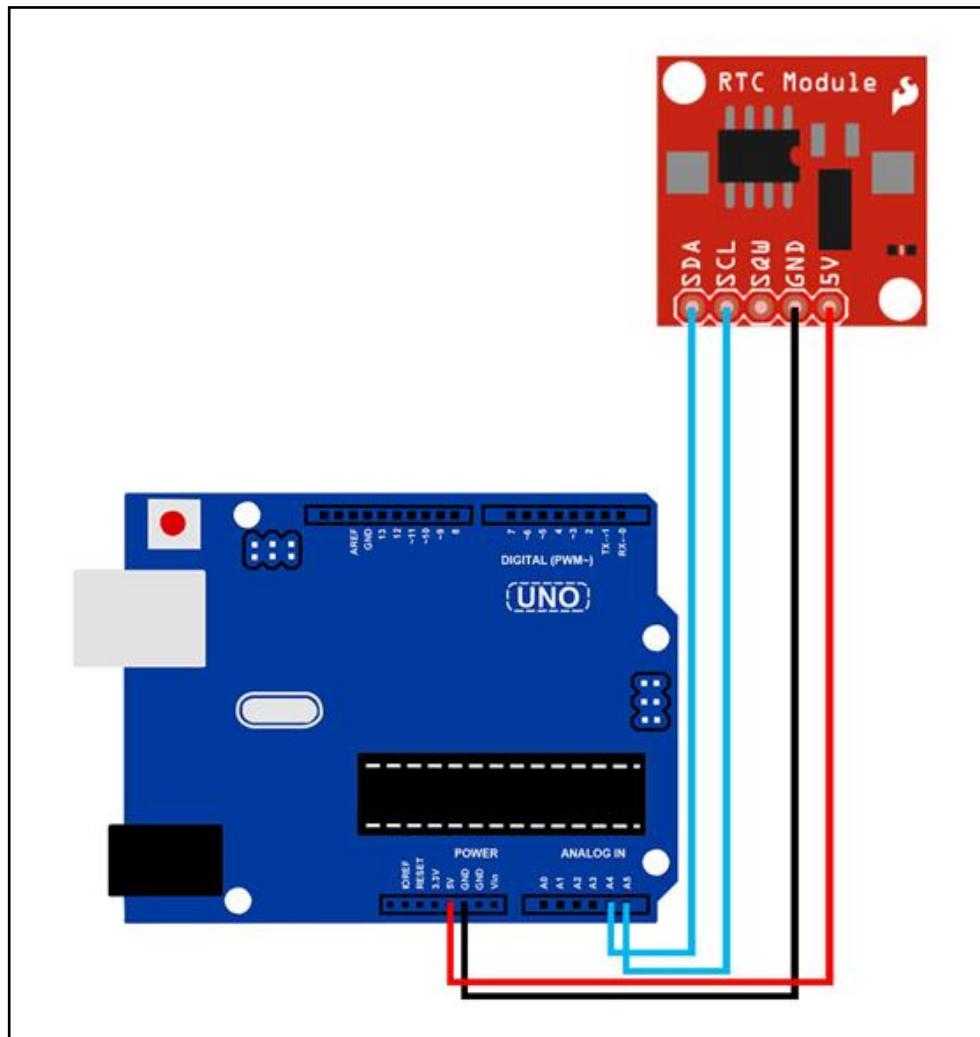


Connection

Schematic



wiring diagram



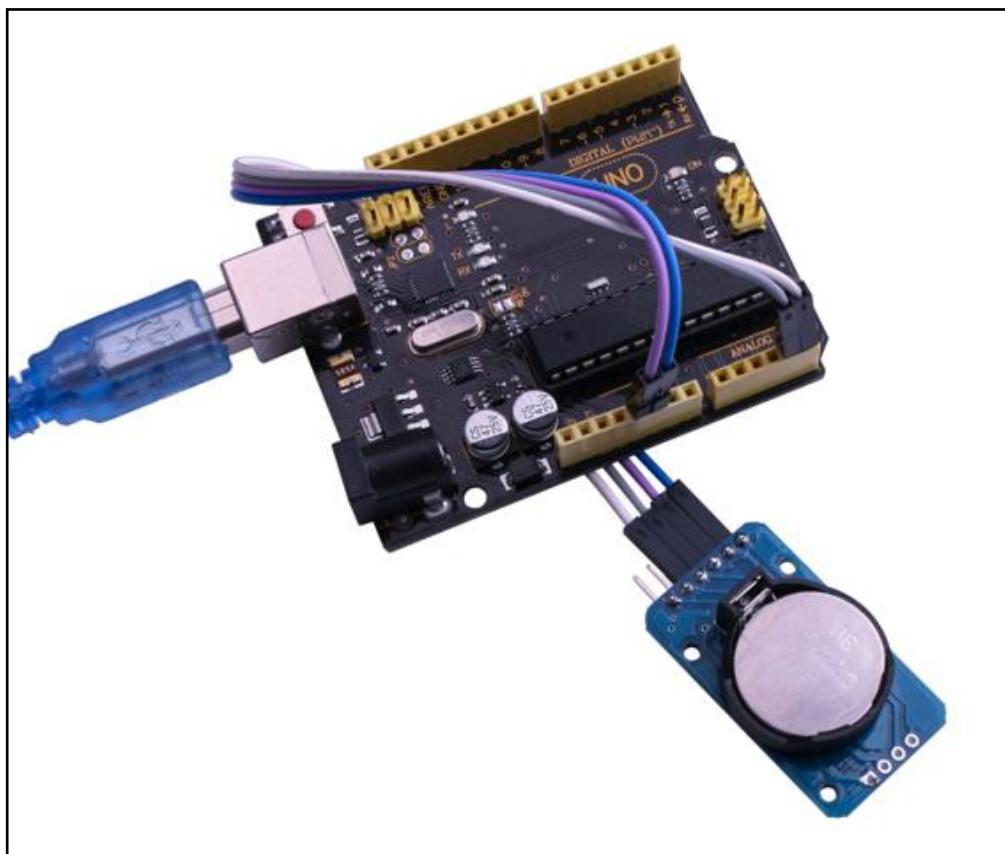
Set up according to the following image.

Ignore the 32K and SQW pins, you will not need them. Plug the SCL pin into your Uno R3 board A5 port, and the SDA pin into the A4 port. The VCC pin plugs into the 5V port, and the GND plugs into the GND port.

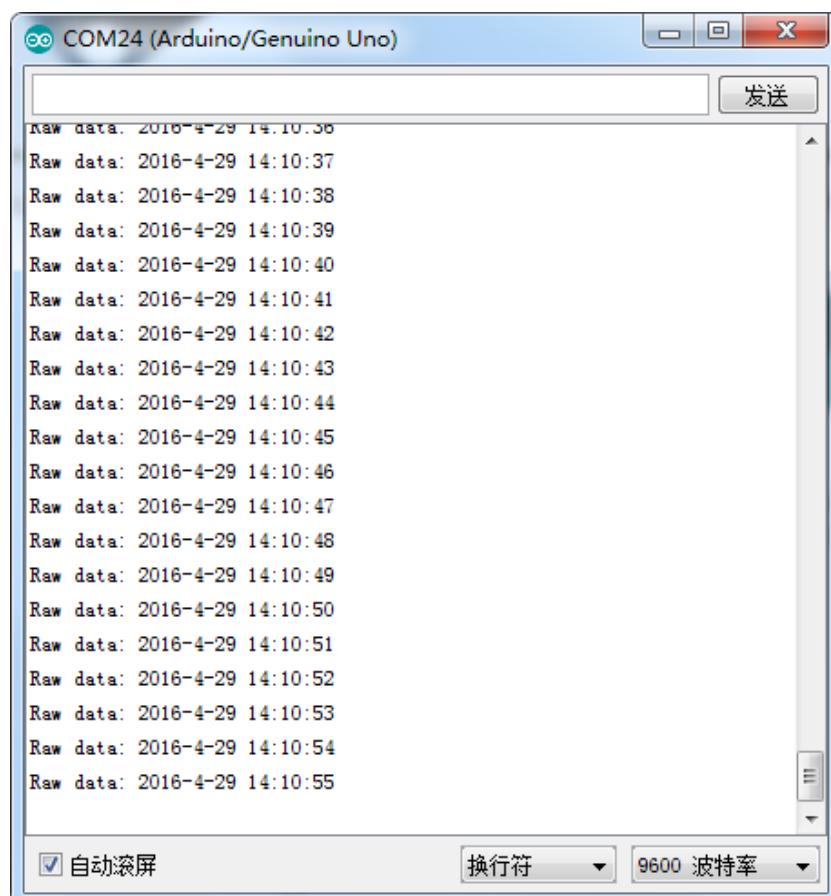
The code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <DS3231> <OneWireKeypad> library. Or you need to install again. If you do not do this, your code won't work.



open the monitor you can see the module can read the time as below:



Lesson 28 Sound Sensor Module

Overview

In this lesson, we will learn how to use a sound sensor module.

Sound sensor module has two output:

AO, analog output, real-time output voltage signal of microphone

DO, when the intensity of the sound to reach a certain threshold, the output high and low level signal, the threshold - sensitivity can be achieved by potentiometer adjustment period



- 1.DO:digital output
- 2.VCC: 3.3V-5V DC
- 3.GND:ground
- 4.AO:analog output

Component Required:

- (1) x Elego Uno R3
- (1) x Sound sensor module
- (3) x F-M wires

Component Introduction

Microphone

Transducers are devices which convert energy from one form to other. A microphone is a transducer which converts sound energy to electrical signals. It works opposite to a speaker (see how speaker works). Microphones are available in different shape and sizes. Depending on the application, a microphone may use different technologies to convert sound to electrical signals. Here we are going to discuss about the Electret Condenser

Microphone which is widely used in mobile phones, laptops, etc.

Electret Condenser Microphone, as the name suggests is a parallel plate capacitor and works on the principle of a variable capacitance. It consists of two plates, one fixed (called the back plate) and the other moveable (called Diaphragm) with a small gap between them. An electric potential charges the plate. When sound strikes the diaphragm it starts moving, thereby changing the capacitance between the plates which in turn results in a variable electric current to flow.

Electret condenser microphone



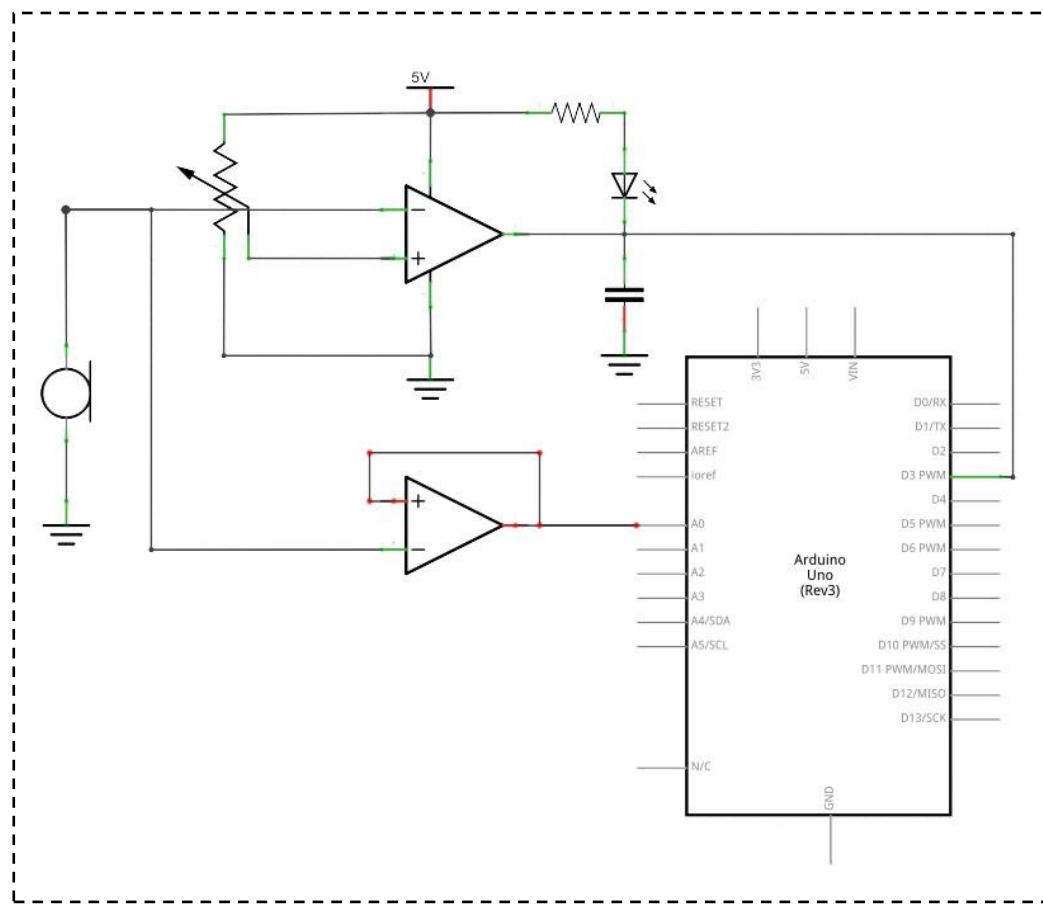
The above image shows an Electret microphone. These microphones are widely used in electronic circuits to detect minor sounds or air vibrations which in turn are converted to electrical signals for further use. The two legs as shown in the image above are used to make electrical connection with the circuit.



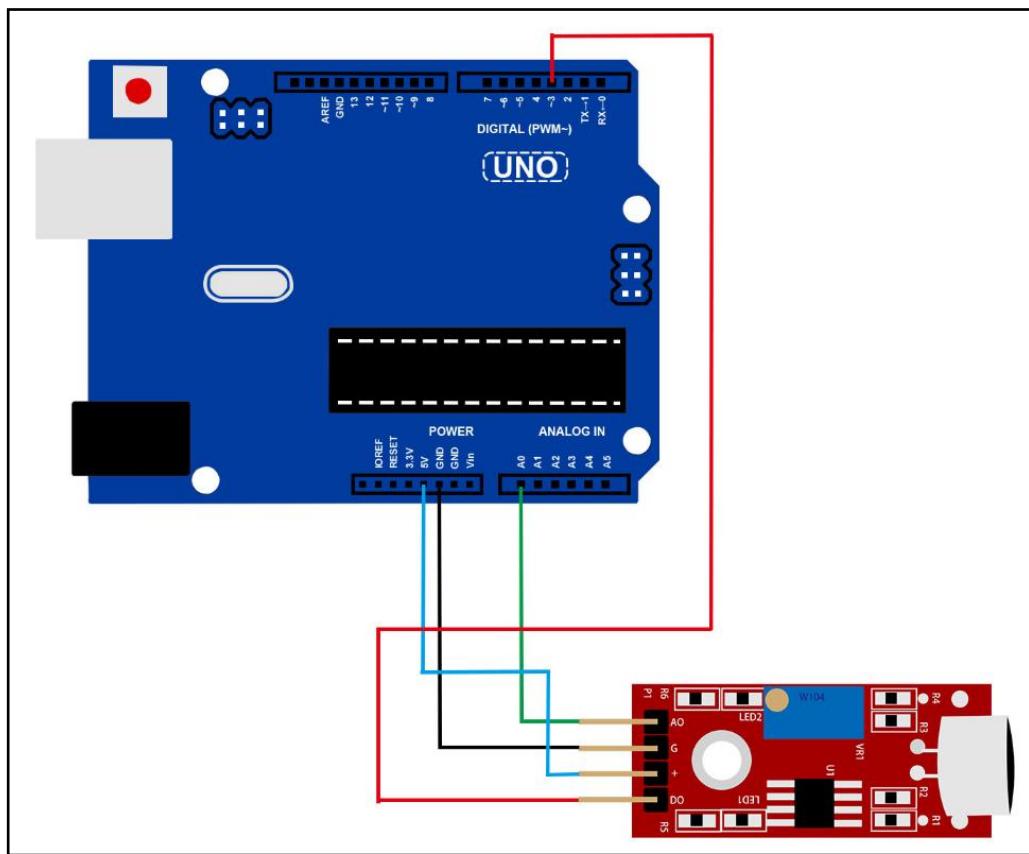
A solid conducting metal body encapsulates the various parts of the microphone. The top face is covered with a porous material with the help of glue. It acts as a filter for the dust particles. The sound signals/air vibrations passes through the porous material and falls on the diaphragm through the hole shown in the image above.

Connection

Schematic

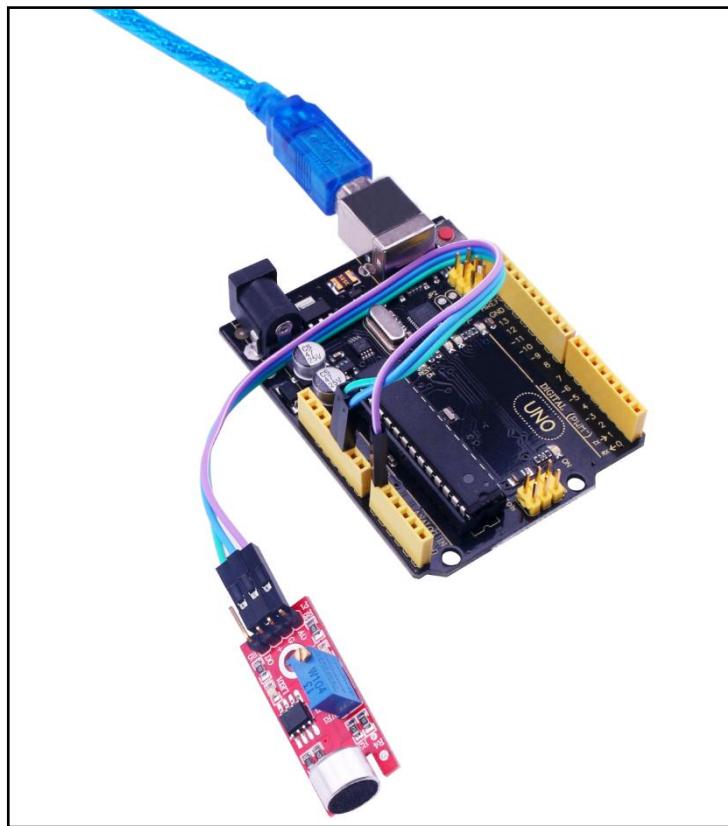


wiring diagram



The code

See the code file.



open the monitor you can see the data as below:

Lesson 29 RC522 RFID Module

Overview

RC522 RFID Reader Module uses the Serial Peripheral Interface (SPI) bus to communicate with controllers such as Arduino, Raspberry Pi, beagle board, etc. This manual is only about how to apply the RC522 RFID Reader Module on UNO R3.

Component Required:

- (1) x Elego Uno R3
- (1) x RC522 module
- (3) x F-M wires

Component Introduction

RC522

The MFRC522 is a highly integrated reader/writer for contactless communication at 13.56 MHz. The MFRC522 reader supports ISO 14443A / MIFARE® mode.

The MFRC522's internal transmitter part is able to drive a reader/writer antenna designed to communicate with ISO/IEC 14443A/MIFARE® cards and transponders without additional active circuitry. The receiver part provides a robust and efficient implementation of a demodulation and decoding circuitry for signals from ISO/IEC 14443A/MIFARE® compatible cards and transponders. The digital part handles the complete ISO/IEC 14443A framing and error detection (Parity & CRC).The MFRC522 supports MIFARE®Classic (e.g. MIFARE® Standard) products. The MFRC522 supports contactless communication using MIFARE® higher transfer speeds up to 848 kbit/s in both directions.

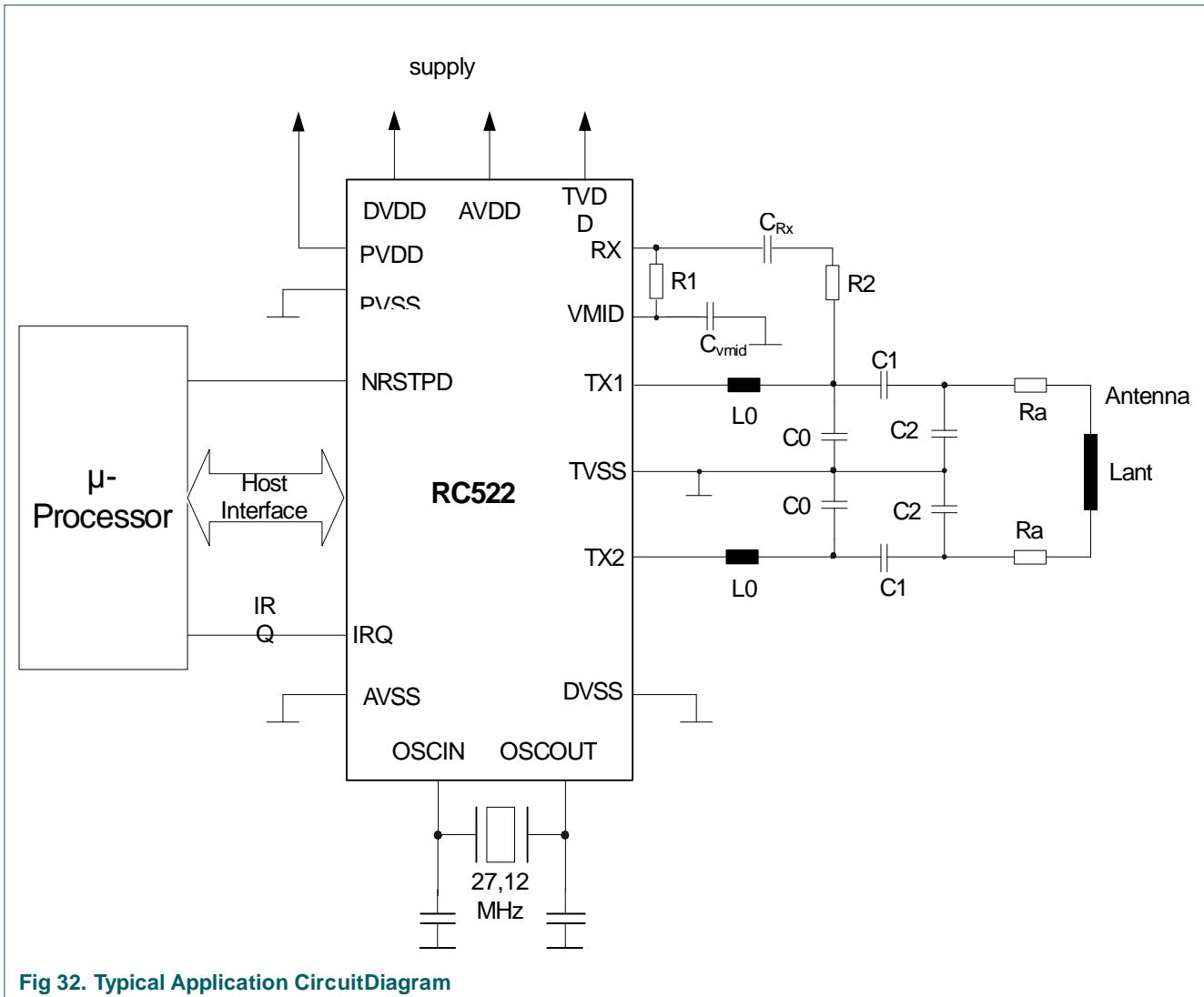
Various host interfaces are implemented:

- SPI interface
- serial UART (similar to RS232 with voltage levels according pad voltage supply)
- I2C interface.

The figure below shows a typical circuit diagram, using a complementary antenna

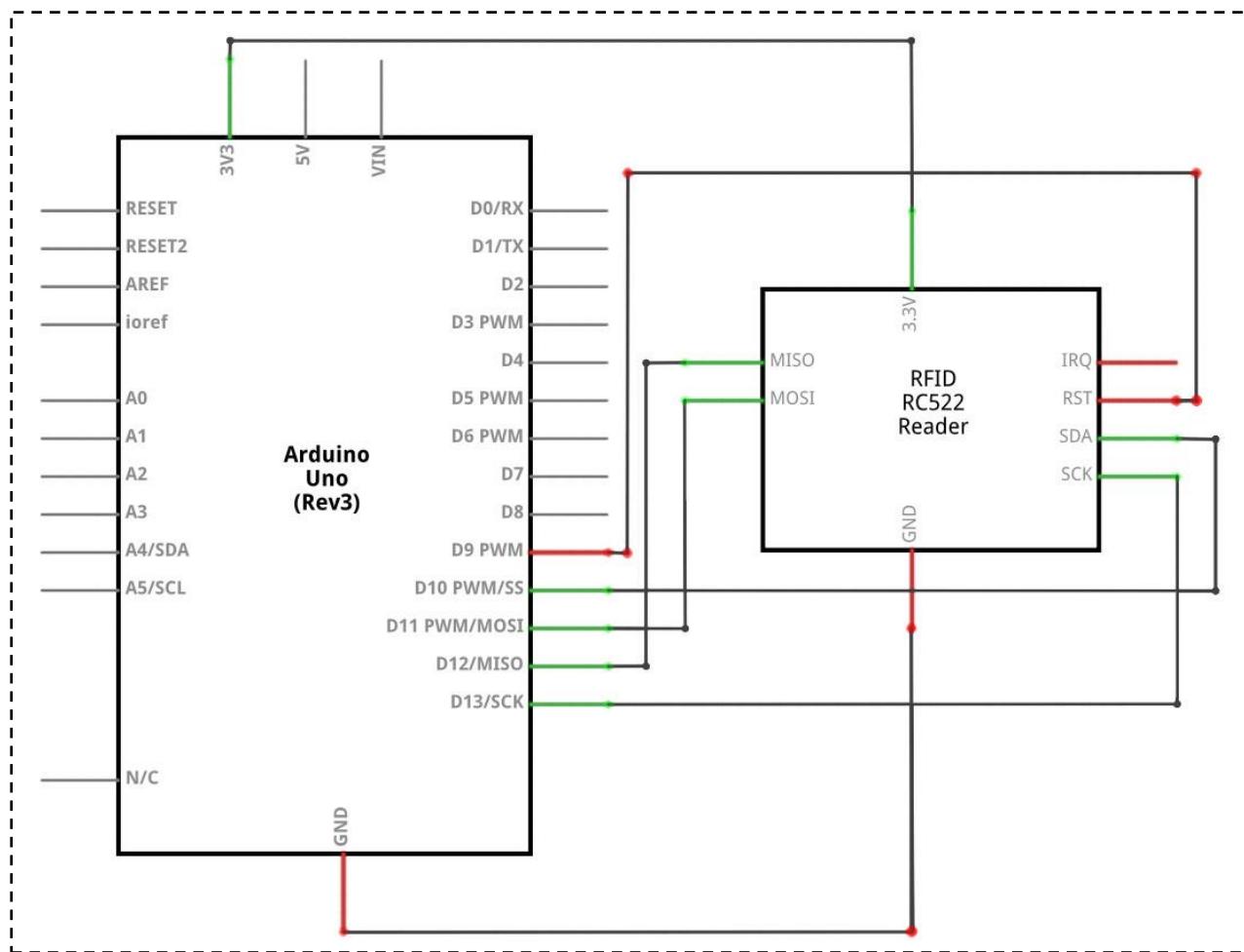
connection to the MFRC522.

The antenna tuning and RF part matching is described in the application note Ref.1 and Ref.2.

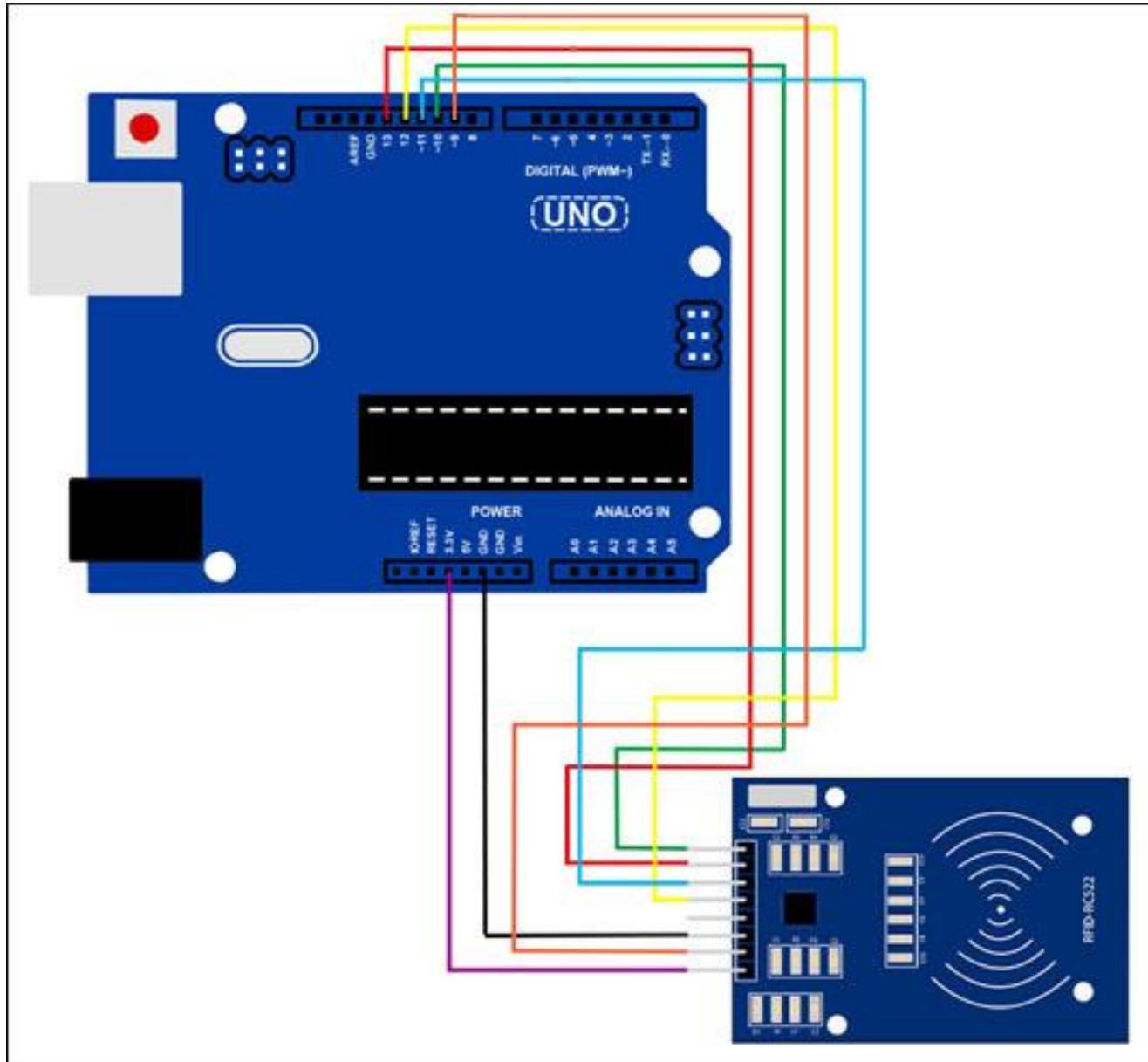


Connection

Schematic



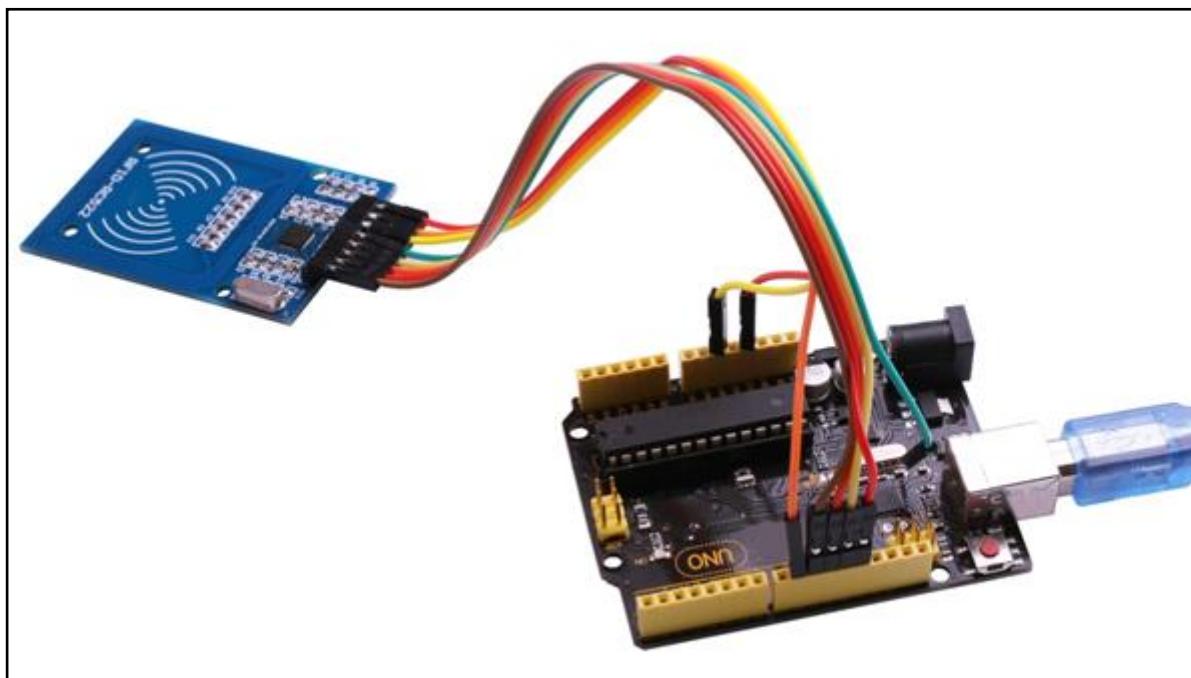
wiring diagram



The code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <rfid> library. Or you need to install again. If you do not do this, your code won't work.



open the monitor you can see the data as blow:

```
COM16 (Arduino/Genuino Uno)
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
```

Lesson 30 DC Motors

Overview

In this lesson, you will learn how to control a small DC motor using an UNO R3 and a transistor.

Component Required:

(1) x Elego Uno R3

(1) x Breadboard

(1) x 6v dc motor

(1) x PN2222

(1) x 1N4007

(1) x 220 ohm resistor

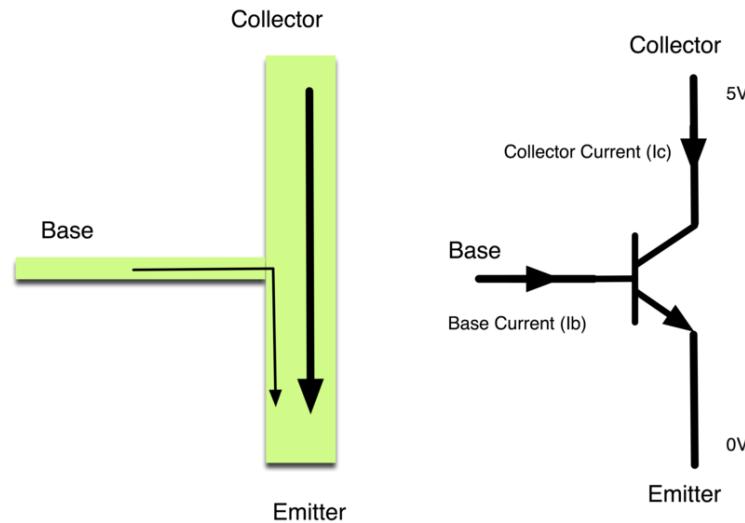
(3) x M-M wires

Component Introduction

TRANSISTORS

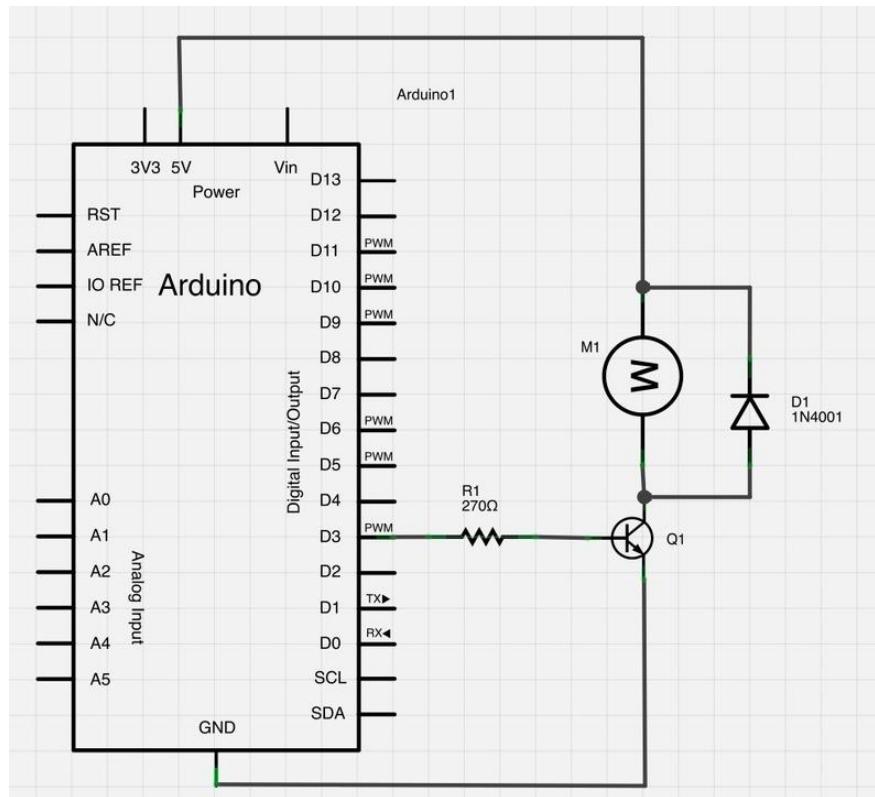
The small DC motor, is likely to use more power than an UNO R3 board digital output can handle directly. If we tried to connect the motor straight to an UNO R3 board pin, there is a good chance that it could damage the UNO R3 board.

A small transistor like the PN2222 can be used as a switch that uses just a little current from the UNO R3 board digital output to control the much bigger current of the motor.



The transistor has three leads. Most of the electricity flows from the Collector to the Emitter, but this will only happen if a small amount is flowing into the Base connection. This small current is supplied by the UNO R3 board digital output.

The diagram below is called a schematic diagram. Like a breadboard layout, it is a way of showing how the parts of an electronic project are connected together.



The pin D3 of the UNO R3 board is connected to the resistor. Just like when using an LED, this limits the current flowing into the transistor through the base.

There is a diode connected across the connections of the motor. Diodes only allow

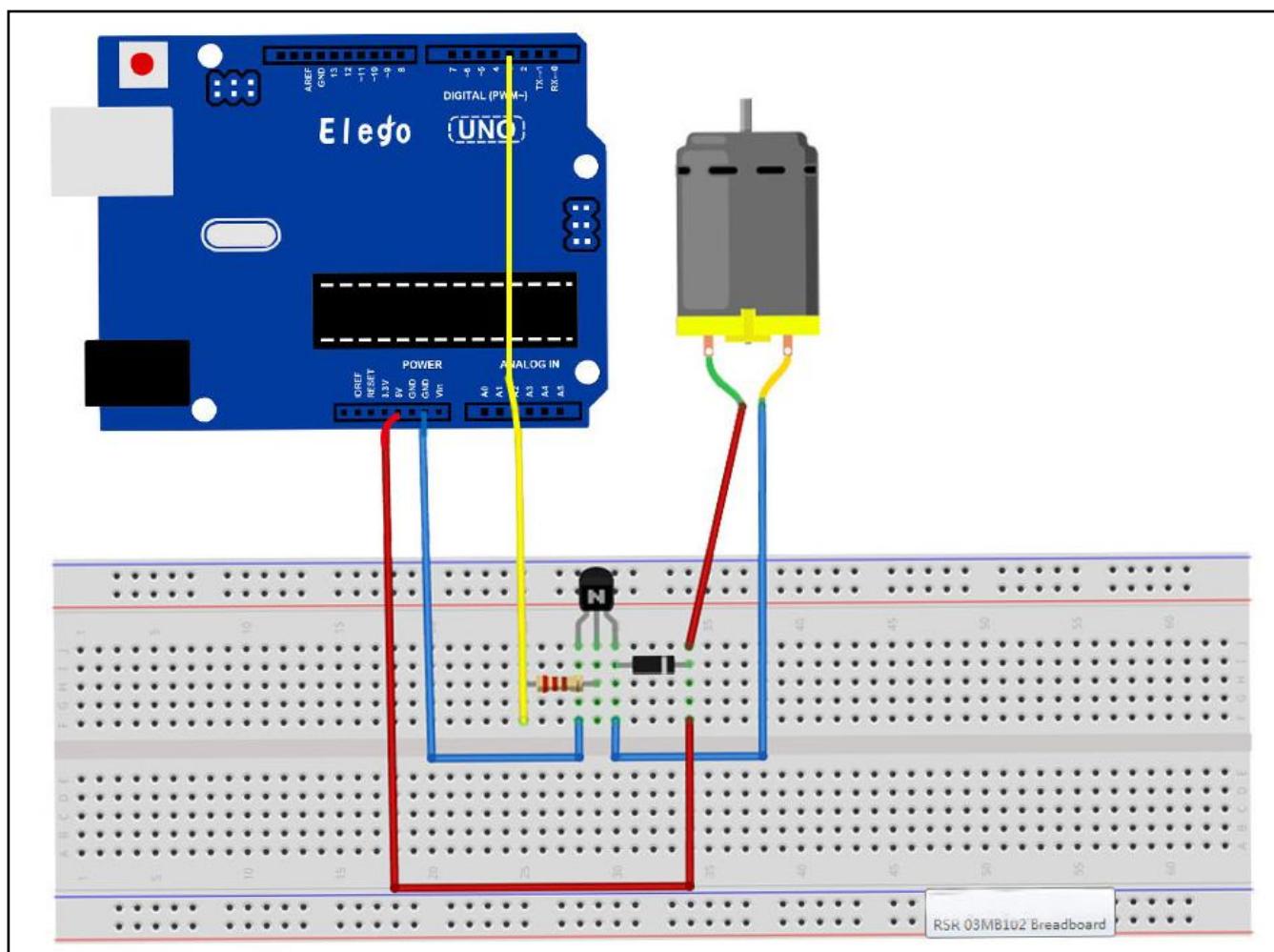
electricity to flow in one direction (the direction of their arrow).

When you turn the power off to a motor, you get a negative spike of voltage, that can damage your UNO R3 board or the transistor. The diode protects against this, by shorting out any such reverse current from the motor.

Through this experiment, you've learned how to drive LCD1602. Now you can create your own messages to display! You can also try letting your LCD1602 display numbers.

Connection

wiring diagram



You will use an UNO R3 board analog output (PWM) to control the speed of the motor by sending a number between 0 and 255 from the Serial Monitor.

When you put together the breadboard, there are two things to look out for.

Firstly, make sure that the transistor is the right way around. The flat side of the transistor should

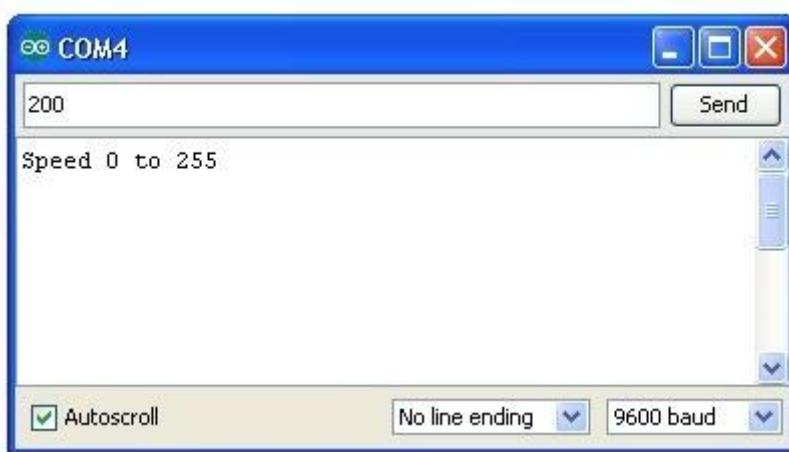
be on the right-hand side of the breadboard.

Secondly the striped end of the diode should be towards the +5V power line - see the image below!

The motor that comes with the kits does not draw more than 250mA but if you have a different motor, it could easily draw 1000mA, more than a USB port can handle! If you aren't sure of a motor's current draw, power the UNO R3 board from a wall adapter, not just USB.

The transistor acts like a switch, controlling the power to the motor, UNO R3 board pin 3 is used to turn the transistor on and off and is given the name 'motorPin' in the sketch.

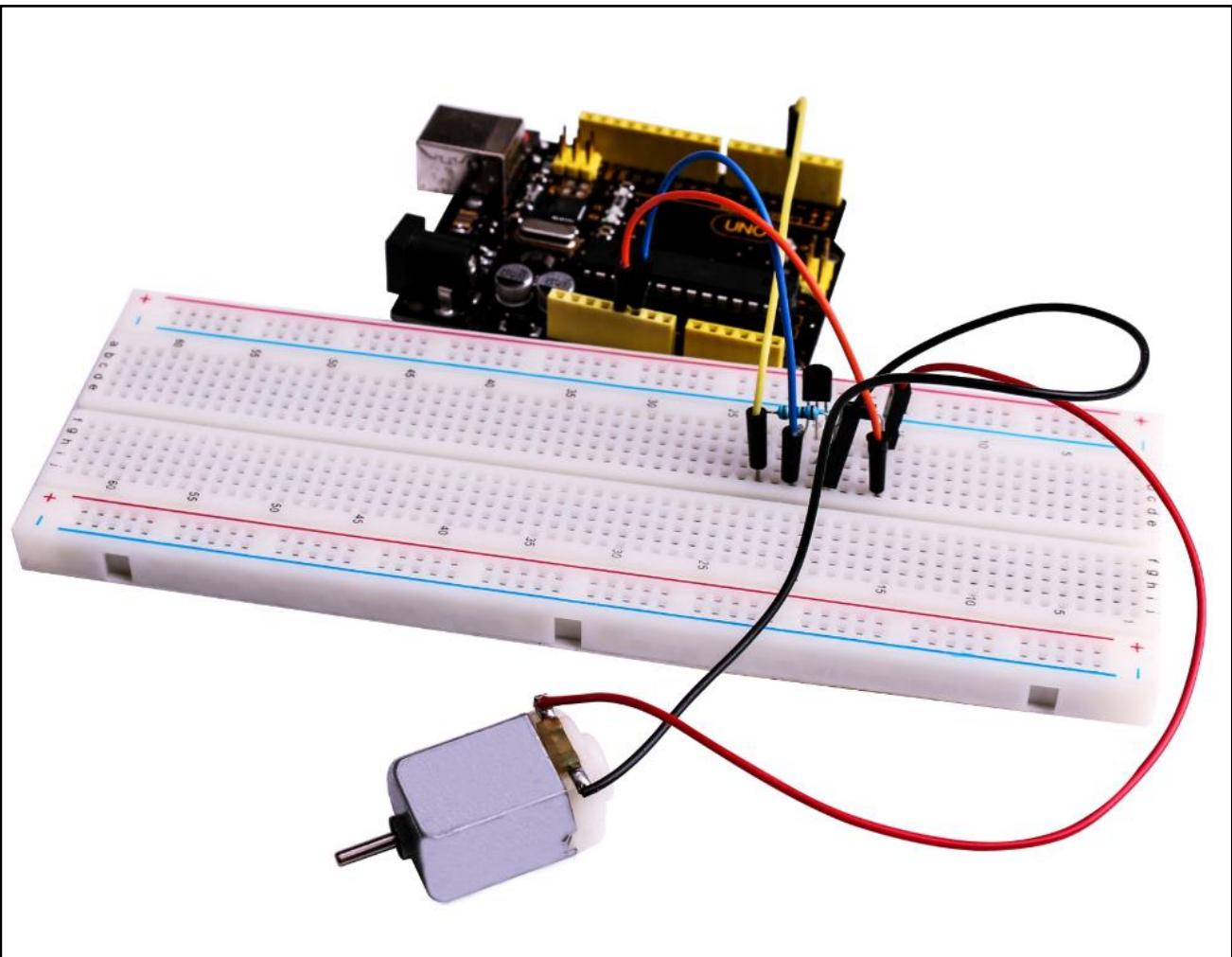
When the sketch starts, it prompts you, to remind you that to control the speed of the motor you need to enter a value between 0 and 255 in the Serial Monitor.



In the 'loop' function, the command 'Serial.parseInt' is used to read the number entered as text in the Serial Monitor and convert it into an 'int'.

You could type any number here, so the 'if' statement on the next line only does an analog write with this number if the number is between 0 and 255.

The Code



Lesson 31 Stepper Motor

Overview

Here's a fun and easy way to drive a Stepper motor.

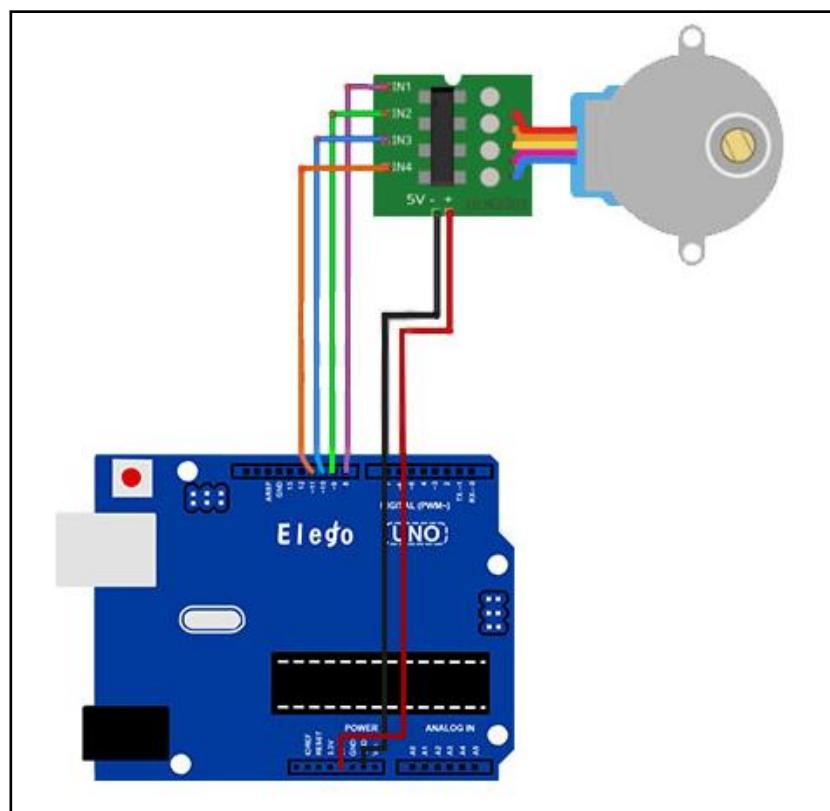
The stepper we are using comes with its own driver board making it easy to connect to our UNO.

Component Required:

- (1) x Elego Uno R3
- (1) x Uln2003 stepper motor driver module
- (1) x Stepper motor
- (9) x F-M wires

Connection

wiring diagram



We are using 4 pins to control the Stepper.

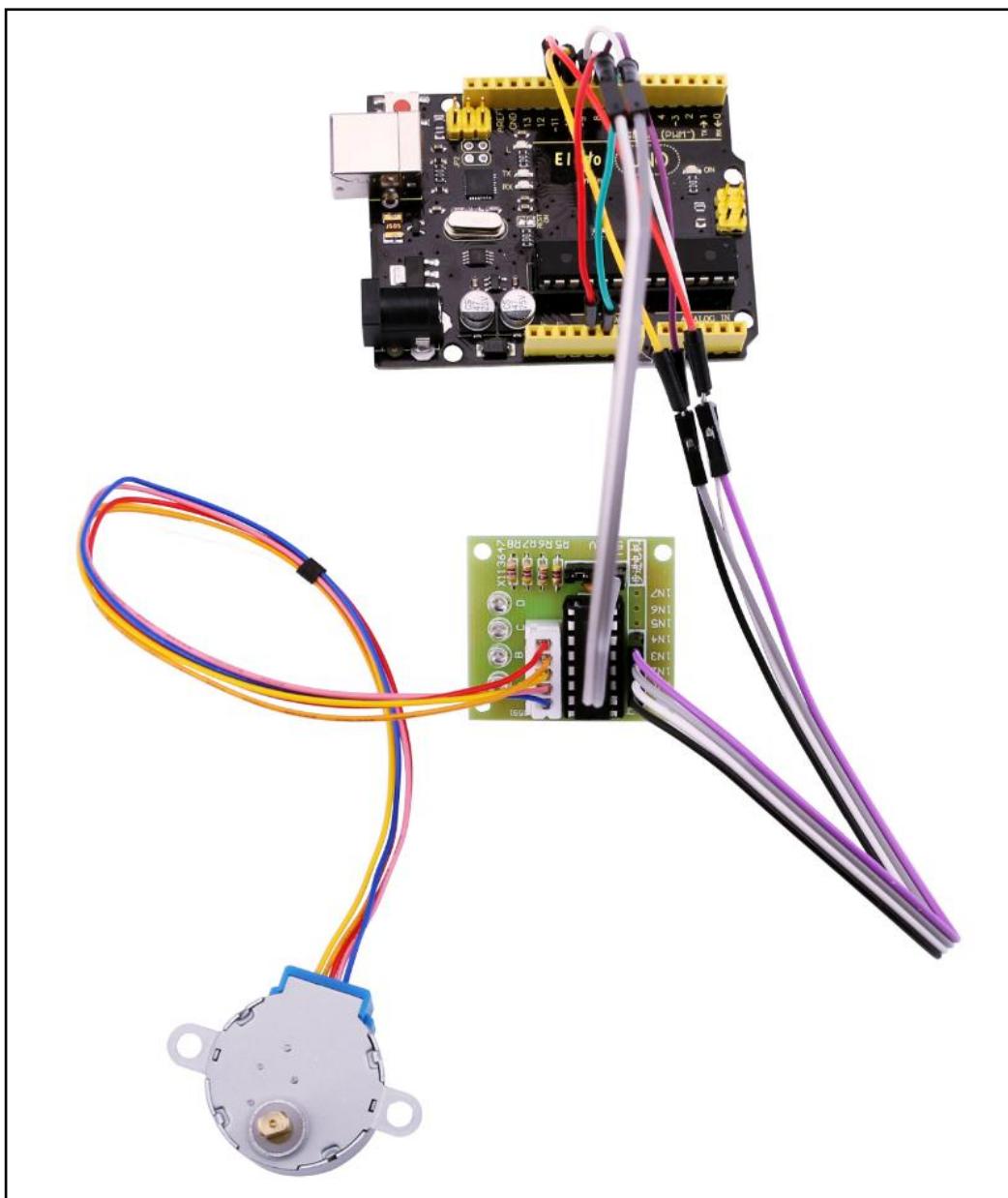
Pin 8-11 are controlling the Stepper motor.

We connect the 5V and Ground from to UNO to the Stepper motor.

The Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <Stepper_Motor_Control> library. Or you need to install again. If you do not do this, your code won't work.



Lesson 32 Controlling Stepper Motor With Remote

Overview

Here's a fun and easy way to control a Stepper motor at a distance using an IR Remote control.

The stepper we are using comes with its own driver board making it easy to connect to our UNO.

Since we don't want to drive the motor directly from the UNO, we will be using an inexpensive little breadboard power supply that plugs right on our breadboard and power it with a 9V 1Amp power supply.

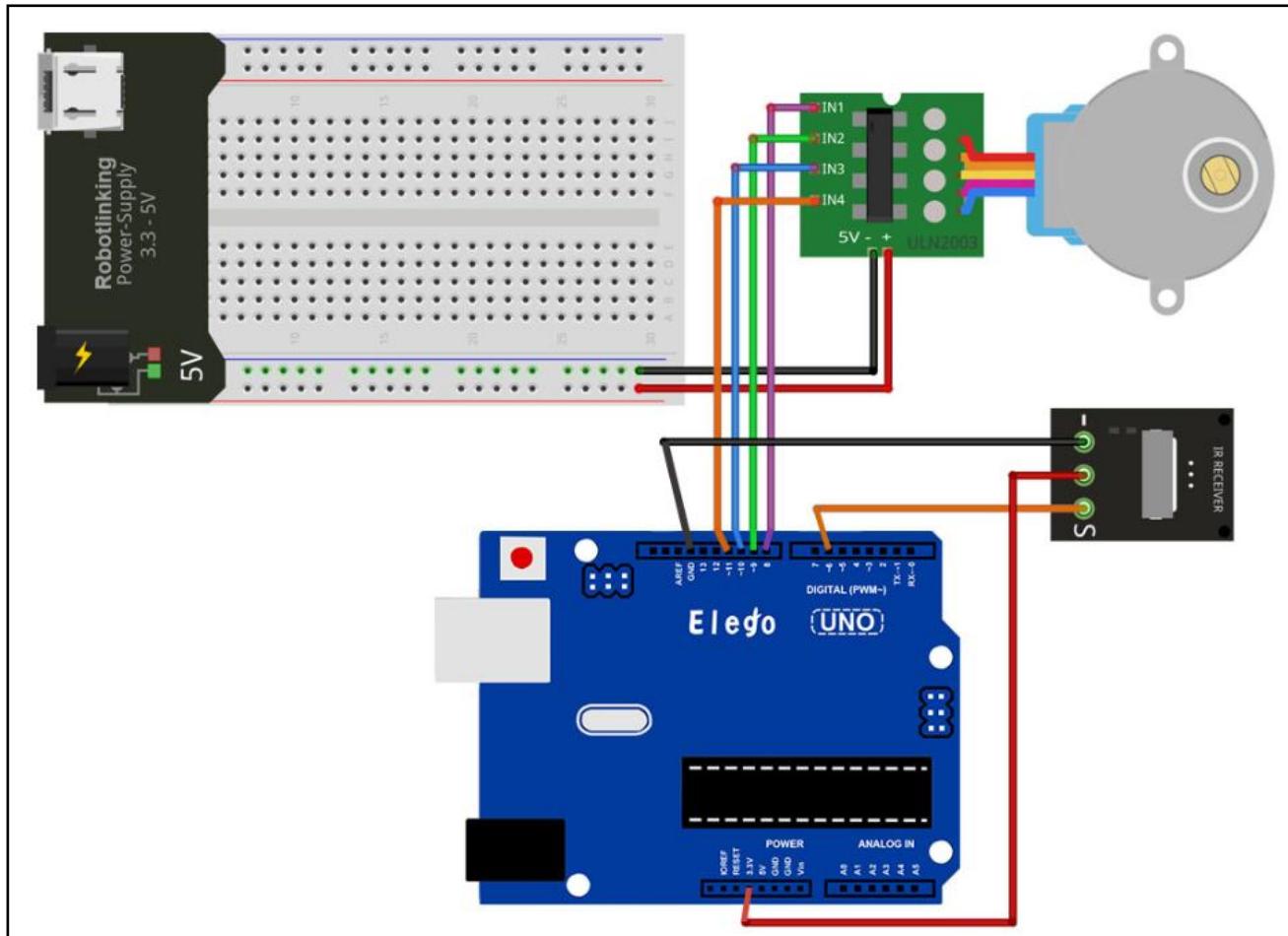
The IR sensor is connected to the UNO directly since it uses almost no power.

Component Required:

- (1) x Elego Uno R3
- (1) x Breadboard
- (1) x IR receiver module
- (1) x IR remote
- (1) x ULN2003 stepper motor driver module
- (1) x Stepper motor
- (1) x Power supply module
- (1) x Adapter
- (9) x F-M wires

Connection

wiring diagram



We are using 4 pins to control the Stepper and 1 pin for the IR sensor.

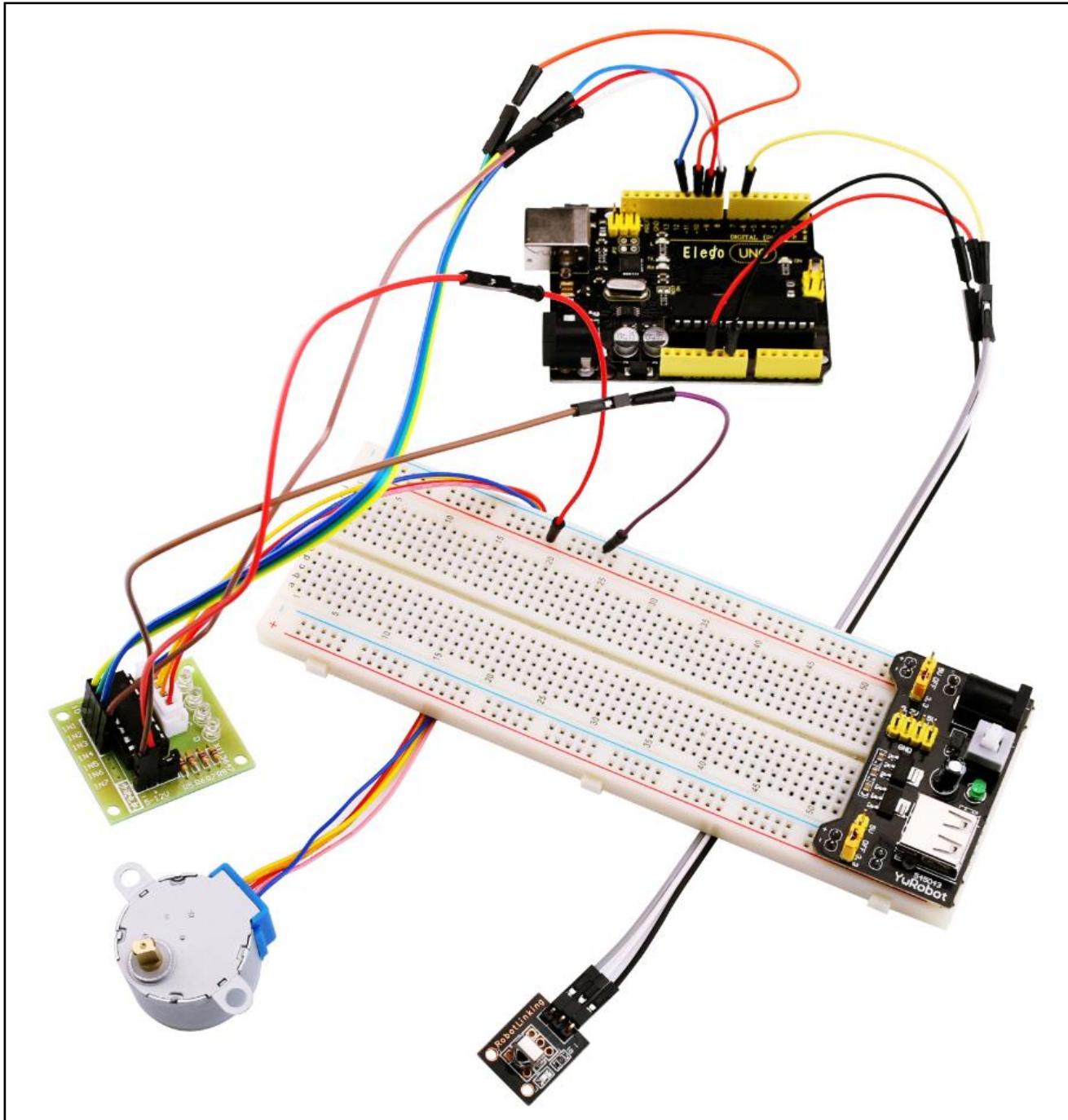
Pin 8-11 are controlling the Stepper motor and pin 6 in Receiving the IR information.

We connect the 5V and Ground from to UNO to the sensor and as a precaution, use a breadboard power supply to power the Stepper motor since it can use more power and we don't want to damage the power supply of the UNO.

The Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <IRremote> <Stepper_Motor_Control> library. Or you need to install again. If you do not do this, your code won't work.



Lesson 33 Controlling Stepper Motor With Encoder

Overview

Welcome to this multi part tutorial on how to control different stepper motors using a rotary encoder.

In this first part we will use the inexpensive and popular stepper motor that comes with it's own control board. The 28BYJ-48 stepper motor with the ULN2003 board.

The 28BYJ-48 motor is not very fast or very strong, but it's great for beginners to start experimenting with controlling a stepper motor with an Arduino.

We will write some code to have the motor move in the direction that we turn the rotary encoder, and will also keep track of how much steps we have taken, so that we can have the motor move back to the starting position by pressing down on the rotary encoder switch.

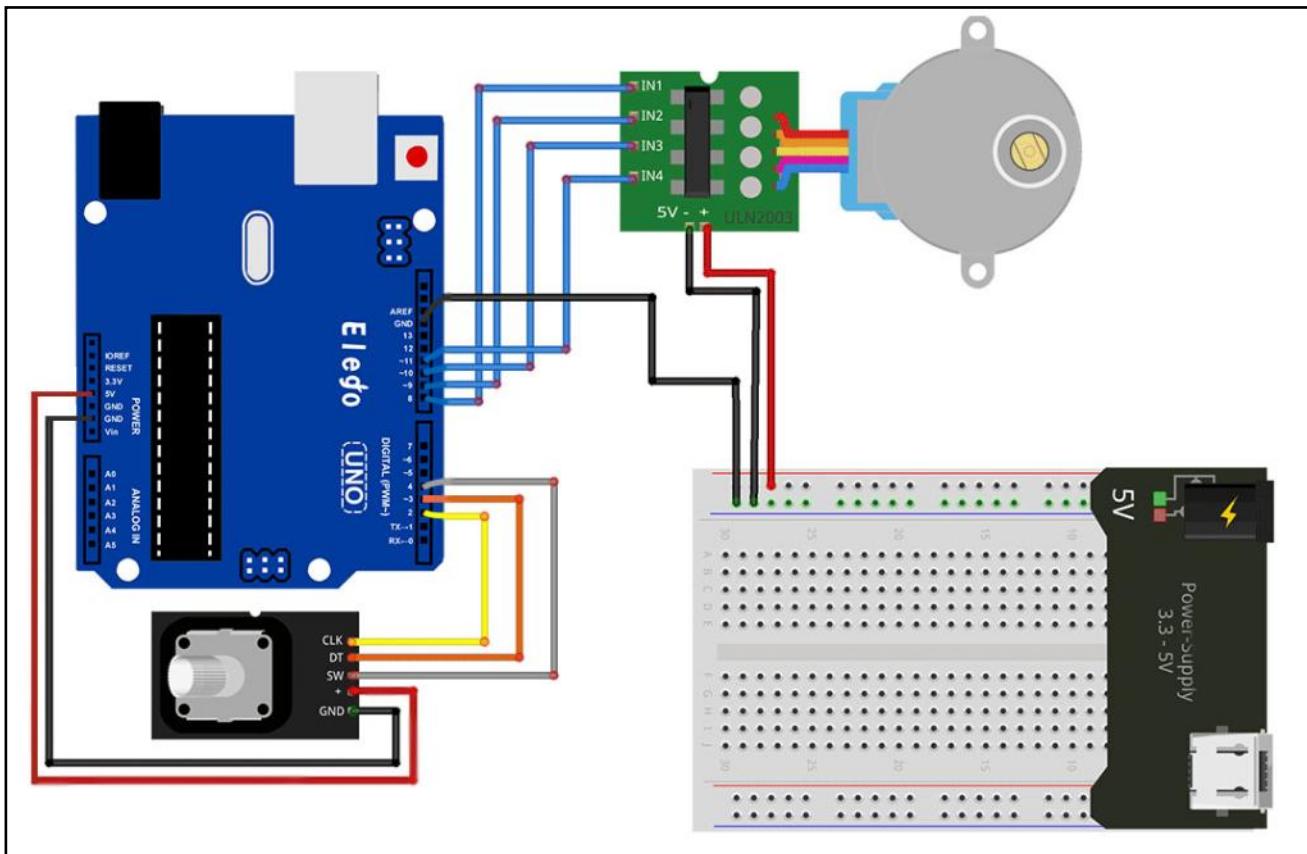
In the next tutorial we will use a Nema 17 stepper motor and the EasyDriver board.

Component Required:

- (1) x Elego Uno R3
- (1) x Breadboard
- (1) x Rotary Encoder
- (1) x ULN2003 stepper motor driver module
- (1) x Stepper motor
- (1) x Power supply module
- (1) x Adapter
- (9) x F-M wires

Connection

wiring diagram



We are using 4 pins to control the Stepper and 3 pins for the rotary encoder module.

Pin 8-11 are controlling the Stepper motor and pin 2-4 are receiving information from the rotary encoder.

We connect the 5V and Ground from to UNO to the rotary encoder and as a precaution, use a breadboard power supply to power the Stepper motor since it can use more power than the UNO can provide.

We also connect the UNO Ground to the breadboard to serve as a reference.

The Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <Stepper_Motor_Control> library. Or you need to install again. If you do not do this, your code won't work.

We are using some variables to store the current position, since we want to keep track of the position of the stepper motor so we can make it move back to the starting position.

We also included some error checking code to make sure that the rotary encoder is not missing steps, since that would make our motor position inaccurate.

