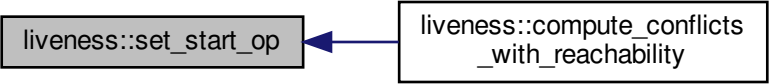


liveness::set_start_op



```
graph LR; A[liveness::compute_conflicts_with_reachability] --> B[liveness::set_start_op];
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'liveness::set_start_op'. The box on the right is white and contains the text 'liveness::compute_conflicts_with_reachability'. A dark blue arrow points from the right side of the white box to the left side of the gray box, indicating a call or relationship between the two functions.

liveness::compute_conflicts
_with_reachability