```
1 import numpy as np
1 a = np.array([2, 6, 5])
2 b = np.array([1, 2, 3])
3 print ("Divide", np.divide(a, b), np.divide(b, a))
   Divide [2.
                      3.
                                 1.66666667] [0.5 0.33333333 0.6
                                                                              1
1 print(a/b)
   [2. 3.
                          1.66666667]
1 print(a//b)
   [2 3 1]
1 print(a*b)
   [ 2 12 15]
1 a=np.array([[1,2],[3,4]])
2 b=np.array([[5,6],[7,8]])
3 print(a,'\n',b)
[ [1 2]
    [3 4]]
    [[5 6]
    [7 8]]
1 print(a+b)
2 print('\n')
3 print(a*b)
4 print('\n')
5 print(a/b)
6 print('\n')
7 print(a//b)
8 print('\n')
9 print(np.multiply(a,b))
   [[ 6 8]
    [10 12]]
   [[ 5 12]
    [21 32]]
   [[0.2
                0.33333333]
    [0.42857143 0.5
                          ]]
```

```
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[[0 0]

[0 0]]

[[ 5 12]

[21 32]]
```

Modulo operation

```
1 a = np.arange(0, 8)
2 print(a)
3 print ('\n')
4 print ("Remainder", np.remainder(a, 3))
5 print ('\n')
6 print ("Remainder", np.remainder(a, np.max(a)))
   [0 1 2 3 4 5 6 7]
   Remainder [0 1 2 0 1 2 0 1]
   Remainder [0 1 2 3 4 5 6 0]
1 print ("Mod", np.mod(a, 3))
   Mod [0 1 2 0 1 2 0 1]
1 print ("% operator", a % 3)
   % operator [0 1 2 0 1 2 0 1]
1 a = np.arange(-4, 4)
2 print(a)
3 print ('\n')
4 print ("Remainder", np.remainder(a, 3))
   [-4 -3 -2 -1 0 1 2 3]
   Remainder [2 0 1 2 0 1 2 0]
1 print ("Fmod", np.fmod(a, 2))
   Fmod [ 0 -1 0 -1 0 1 0 1]
```

→ Changing Shape

```
1 a = np.arange(8)
2 print ('The original array:',a)
3 print ('\n')
4 b = a.reshape(4,2)
5 print ('The modified array:\n',b)
6

The original array: [0 1 2 3 4 5 6 7]

The modified array:
    [[0 1]
    [2 3]
    [4 5]
    [6 7]]

1 print (a.flat)
    <numpy.flatiter object at 0x205f700>
```

flatten(order) order

'C'- row major (default. 'F': column major 'A': flatten in column-major order, if a is Fortran contiguous in memory, row-major order otherwise 'K': flatten a in the order the elements occur in the memory

```
1 import numpy as np
 2 a = np.arange(8).reshape(2,4)
 3 print ('The original array is:\n',a)
 5 print ('\n' )
 6 # default is column-major
 7
8 print ('The flattened array is:' )
9 b=a.flatten()
10 print(b)
12 print ('The flattened array in F-style ordering:')
13
14 b=a.flatten(order = 'F')
15 print(b)
    The original array is:
     [[0 1 2 3]
     [4 5 6 7]]
    The flattened array is:
    [0 1 2 3 4 5 6 7]
    The flattened array in F-style ordering:
    [0 4 1 5 2 6 3 7]
```

```
numpy.ravel(a, order)
```

This function returns a flattened one-dimensional array. A copy is made only if needed. The returned array will have the same type as that of the input array. The function takes one parameter.

```
1 import numpy as np
2 a = np.arange(8).reshape(2,4)
4 print ('The original array is:')
5 print (a )
6 print ('\n')
7
8 print ('After applying ravel function:')
9 print (a.ravel())
10 print ('\n')
11
12 print ('Applying ravel function in F-style ordering:')
13 print (a.ravel(order = 'F'))
    The original array is:
    [[0 1 2 3]
    [4 5 6 7]]
    After applying ravel function:
    [0 1 2 3 4 5 6 7]
    Applying ravel function in F-style ordering:
    [0 4 1 5 2 6 3 7]
```

Transpose operation

```
1 import numpy as np
2 a = np.arange(15).reshape(3,5)
3 print ('The original array is:')
4 print (a )
5 print ('\n')

The original array is:
  [[ 0  1  2  3   4]
  [ 5  6  7  8   9]
  [10 11 12 13 14]]

1 print (np.transpose(a))
  [[ 0  5  10]
  [ 1  6  11]
  [ 2  7  12]
```

```
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                                         Numpy2.ipynb - Colaboratory
        [ 3 8 13]
        [ 4 9 14]]
    1 print (a.T)
       [[ 0 5 10]
        [1 6 11]
        [ 2
            7 12]
        [ 3 8 13]
        [ 4 9 14]]
    1 print (np.rollaxis(a,0) )
       [[0 1 2 3 4]
        [5 6 7 8 9]
        [10 11 12 13 14]]
    1 print (np.rollaxis(a,1) )
       [[ 0 5 10]
        [1 6 11]
        [ 2 7 12]
        [ 3 8 13]
         [ 4 9 14]]
    1 print (np.swapaxes(a,0,0))
       [[0 1 2 3 4]
        [56789]
        [10 11 12 13 14]]
    1 #numpy.swapaxes(arr, axis1, axis2)
    2 #This function interchanges the two axes of an array.
    3 print (np.swapaxes(a,0,0))
       [[0 1 2 3 4]
        [ 5 6
               7 8 9]
        [10 11 12 13 14]]
    1 print (np.swapaxes(a,0,1))
```

Dimension change

7 12] [3 8 13] [4 9 14]]

[[0 5 10] [1 6 11]

[2

Expand

• squeeze

```
1 import numpy as np
2 x = np.array(([1,2],[3,4]))
3 print(x)

    [[1 2]
       [3 4]]
```

numpy.expand_dims(arr, axis)

```
1 y = np.expand_dims(x, axis = 0)
2 print(y)
3 print (x.ndim,y.ndim )
    [[[1 2]
       [3 4]]]
    2 3

1 y = np.expand_dims(x, axis = 1)
2 print(y)
3 print (x.ndim,y.ndim )
    [[[1 2]]
       [[3 4]]]
    2 3
```

numpy.squeeze(arr, axis): removes one-dimensional entry from the shape of the given array.

arr: Input array

axis: int or tuple of int. selects a subset of single dimensional entries in the shape

```
1 y = np.squeeze(x)
2 print(y)
    [[1 2]
       [3 4]]

1 print (x.shape, y.shape)
    (2, 2) (2, 2)

1 y=np.arange(20).reshape(2,2,5)
2 print(y)
3 print(y.shape)
    [[[ 0  1  2  3   4]
       [ 5  6  7  8   9]]
```

```
[[10 11 12 13 14]
     [15 16 17 18 19]]]
     (2, 2, 5)

1 yy=np.squeeze(y)
2 print(yy)
3 print(yy.shape)

[[[ 0  1   2   3   4]
     [ 5   6   7   8   9]]

     [[10 11 12 13 14]
     [15 16 17 18 19]]]
     (2, 2, 5)
```

NumPy - Matrix Library

- NumPy package contains a Matrix library numpy.matlib.
- This module has functions that return matrices instead of ndarray objects.

```
1 import numpy.matlib
2 import numpy as np
3 a=np.matlib.empty((2,2))
4 print (a)
5 print(type(a))
6 b=np.ones(4)
7 print(type(b))

    [[2.5e-323 3.0e-323]
       [3.5e-323 4.0e-323]]
       <class 'numpy.matrix'>
        <class 'numpy.ndarray'>

1 a=np.matlib.ones((2,2))
2 print(a)

    [[1. 1.]
       [1. 1.]]
```

numpy.matlib.eye(n, M,k, dtype) n: The number of rows in the resulting matrix

M: The number of columns, defaults to n

k: Index of diagonal

dtype: Data type of the output

```
1 b= np.matlib.eye(n = 3, M = 4, k = 0, dtype = float)
2 print(b)
  [[1. 0. 0. 0.]
```

```
[0. 1. 0. 0.]
    [0. \ 0. \ 1. \ 0.]]
1 \text{ b= np.matlib.eye}(n = 4, M = 4, k = 0, dtype = int)
2 print(b*5)
   [[5 0 0 0]
    [0 5 0 0]
    [0 0 5 0]
    [0 0 0 5]]
1 \text{ b= np.matlib.eye}(n = 4, M = 4, k = 1, dtype = int)
2 print(b*5)
   [[0 5 0 0]
    [0 0 5 0]
    [0 \ 0 \ 0 \ 5]
    [0 0 0 0]]
1 b= np.matlib.eye(n = 4, M = 4, k = 2, dtype = int)
2 print(b*5)
   [[0 0 5 0]
    [0 0 0 5]
    [0 \ 0 \ 0 \ 0]
    [0 0 0 0]]
1 print (np.matlib.identity(4, dtype = float))
   [[1. 0. 0. 0.]
    [0. 1. 0. 0.]
    [0. 0. 1. 0.]
    [0. 0. 0. 1.]]
1 print (np.matlib.rand(3,3))
   [[0.78655276 0.04105795 0.39871213]
    [0.77818371 0.69576757 0.54566996]
    [0.2831413 0.29581873 0.83618334]]
1 i = np.matrix('1,2;3,4')
2 print (i)
   [[1 \ 2]]
    [3 4]]
1 j = np.asarray(i)
2 print (j )
   [[1 \ 2]]
    [3 4]]
```

```
1 k = np.asmatrix (j)
2 print (k)
    [[1 2]
       [3 4]]
```

Matrix creation from string

```
1 A = np.mat('1 2 3; 4 5 6; 7 8 9')
2 print ("Creation from string", A)
   Creation from string [[1 2 3]
    [4 5 6]
    [7 8 9]]
1 A = np.mat('1 2 3')
2 print ("Creation from string", A)
3 print(A.shape)
   Creation from string [[1 2 3]]
   (1, 3)
1 A = np.mat('1 2 3; 4 5 6; 7 8 9')
2 print ("Creation from string", A)
3 print("transpose of A",A.T)
   Creation from string [[1 2 3]
    [4 5 6]
    [7 8 9]]
   transpose of A [[1 4 7]
    [2 5 8]
    [3 6 9]]
1 a=np.mat('1 2; 3 4')
2 print ("Inverse A", a.I)
   Inverse A [[-2.
    [1.5 - 0.5]
```

- Linear algebra

• The **numpy.linalg** package contains linear algebra functions.

```
1 A = np.mat("0 1 2;1 0 3;4 -3 8")
2 print ("A\n", A)

A
   [[ 0  1   2]
   [ 1  0  3]
   [ 4 -3  8]]
```

```
1 print (np.linalg.det(A))
   -2.0
1 inverse = np.linalg.inv(A)
2 print ("inverse of A\n", inverse)
   inverse of A
    [[-4.5 7. -1.5]
    [-2. 4. -1.]
    [ 1.5 -2. 0.5]]
1 print ("Check\n", A * inverse)
   Check
    [[1. 0. 0.]
    [0. 1. 0.]
    [0. 0. 1.]]
1 print ("Check\n", A.T)
   Check
    [[ 0 1 4]
    [ 1 0 -3]
    [2 3 8]]
```

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