

Building Scalable Video Captioning Models

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Presentation Link:

<https://drive.google.com/file/d/16ufs1MBLvK4bzQaLix-bT21RK4whw9xJ/view?usp=sharing>

Introduction

- Large-scale foundational models → video captioning
- Typically use well-performing image to text models (CLIP, ALIGN)
- General theory:
 - Video is a sequence of images
 - Images can be processed separately
 - Then a sequence model is applied
 - Captures characteristics of each frame + temporal aspect
- Our modification: applying transformers as the sequence modeling

Related Work

- CLIP-Hitchhiker (Bain et al., 2022) - takes the mean of image embeddings
- Two-Stream LSTMs (Zhao et al., 2021) - encodes audio and visual data separately, then uses fusion LSTM to combine data into same latent space
- Transformers for Images (Dosovitskiy et al., 2021) - extends self-attention from 2D image space to 3D temporal space

Dataset

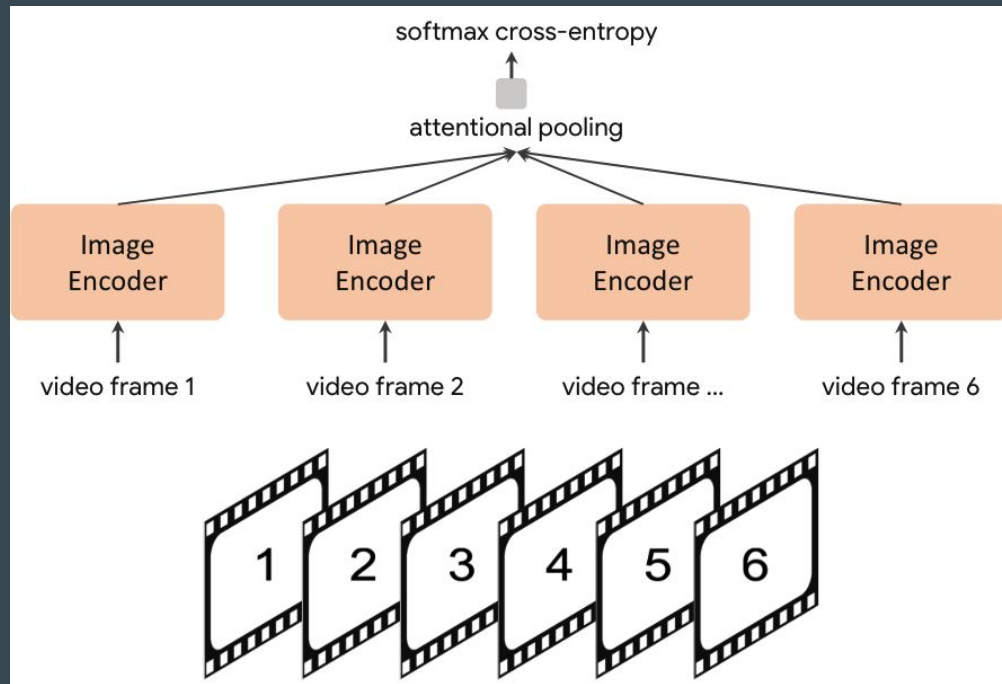
- We used the Microsoft Research Video to Text (MSR-VTT) dataset
- Consists of 10, 000 clips from 20 categories
- Each clip has 20 annotated “captions”
 - Sampled one annotation per clip for ground truth
- Due to storage limits, only used every *40th* frame
- Training-validation-test split of 70-15-15
- Captions preprocessed and tokenized using BERT

Approach 1: Zero-Shot Contrastive Captioning (CoCa)

- CoCa - pre-existing image captioning model
- Uses a cascaded decoder design
 - Bottom half - encodes text content with causally masked self-attention
 - Top half - multimodal decoder using cross-attention to align image with text
- Video captioning - apply pre-trained CoCa on each frame and average results

Approach 2: Fine-tuned CoCa

- Simple CoCa → not guaranteed to capture temporal information
- Add a pooler on top of spatial sequence tokens to attend to temporal sequence patterns



Approach 3: ResNet + Transformer

- ResNet-18 model - used to extract information from independent images
 - Use frozen convolutional blocks
 - Encode each frame of the video
 - Project onto feature space of size 768, matching captions

Approach 3: ResNet + Transformer

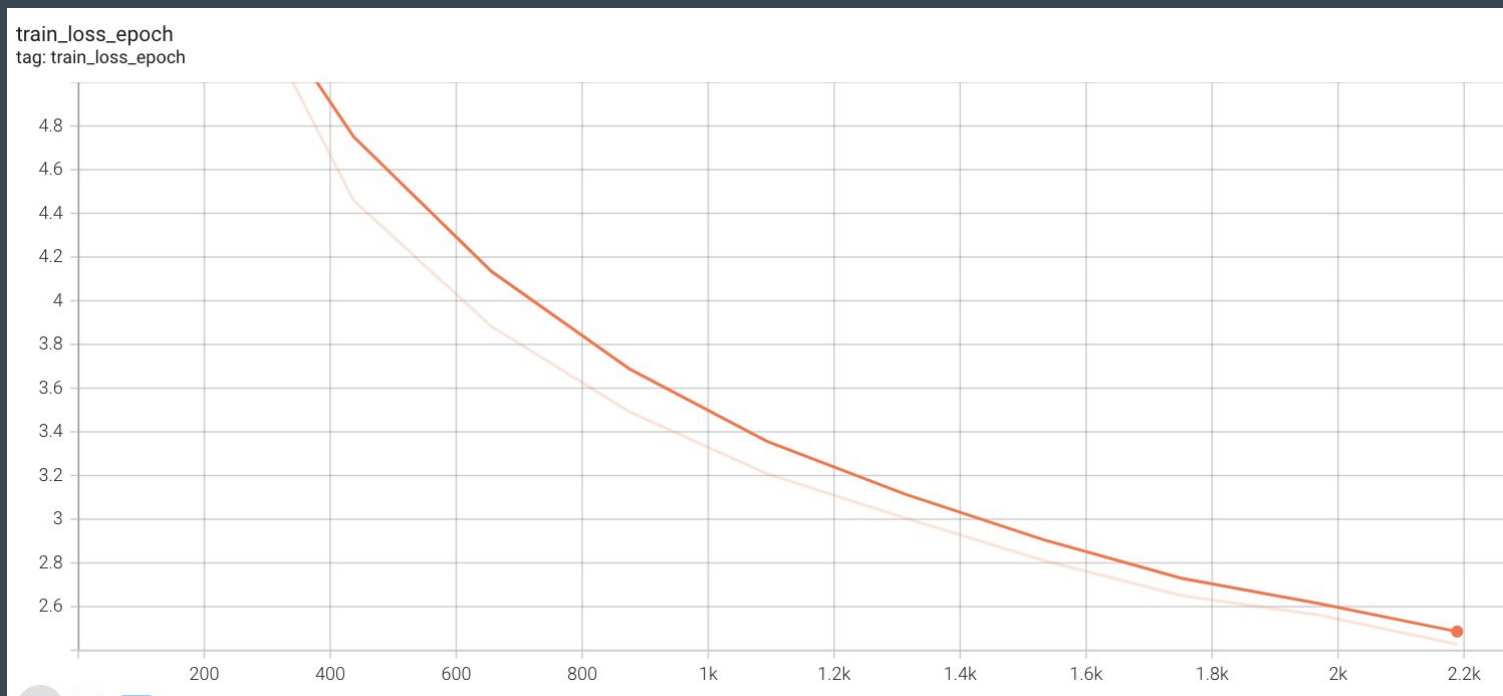
- Transformer - encoder-decoder model used to model sequential (temporal) dependencies
 - Add relative positional bias and absolute positional embeddings
 - Multi-head attention with n layers and h heads
 - No mask applied to encoder - want to capture dependencies
 - Lower triangular square mask for decoder - hides future tokens to allow parallelism
 - Linear layers used to project onto BERT's vocab space

Training

- Primarily focused on approach 3 for our final results
- Used cross-entropy loss with stochastic optimizer Adam
- Learning rate ranged from $1e-3$ to $1e-6$, with scheduler added in some experiments
- Trained model for 15 epochs
- Performed grid search for hyperparameters
 - Optimal combination: LR = $1e-4$ with scheduler, n=6 layers, h=8 heads,
norm_first = True

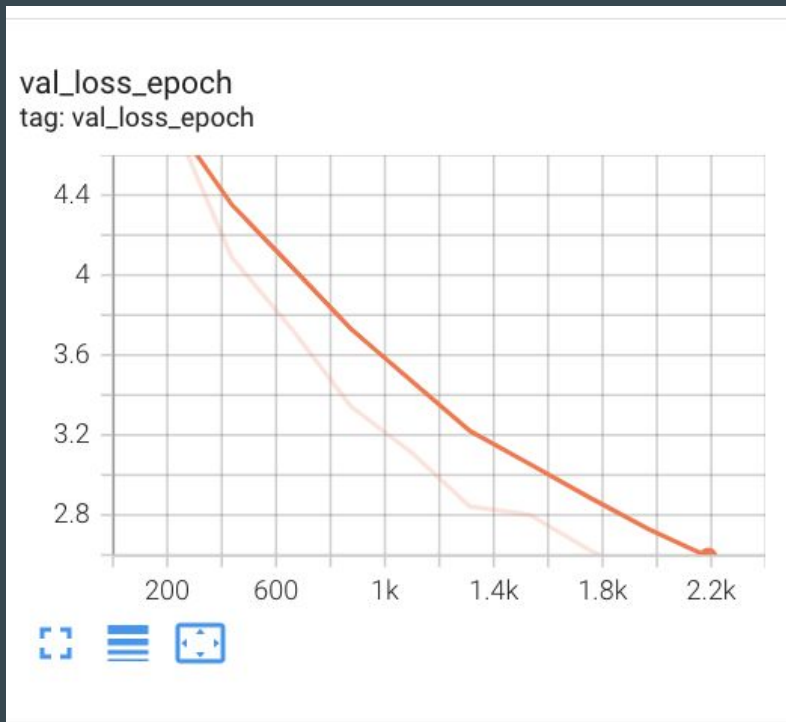
Training Loss

- Training loss steadily decreasing - indicates model hasn't converged yet



Validation Loss

- Validation loss achieved minimum (over 15 epochs) at 1.99



Sample Captions

Predicted Caption	Ground Truth Caption
A man in a purple shirt and red hat is playing guitar while playing on a microphone	A man in a blue shirt and blue shirt is playing guitar and singing into a microphone
A person is trying up through from the	A person is carrying someone away from danger
A group of the sports car are very at at a busy race show	A series of convertible sports cars are lined up at a large car show

Table 1: Comparison of Predicted and Ground Truth Captions

Evaluation Metrics

- Test loss achieved minimum of 2.35

Evaluation Metrics			
	Recall	Precision	F1
ROUGE-1	0.6860699710113917	0.6493109267925568	0.6618847461242713
ROUGE-2	0.45838117034278275	0.2990833003742873	0.35434326640328534
ROUGE-L	0.6722172025069564	0.6365854570425724	0.6487584559993945
BLEU	0.3899576889070564		

Table 2: Combined Evaluation Metrics (ROUGE & BLEU Scores)

Analysis & Future Work

- Results indicate that the general architecture is promising
- With limited dataset and compute power, we achieved moderately good ROUGE and BLEU scores
- More training and high-quality data needed to achieve better results
- Future work: adding audio data from video - currently not included due to memory limits on Colaboratory

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Thank You!