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/*
* main.c
*
*  Created on: 25-Aug-2017
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*/

#define F_CPU 8000000UL
#define LCD_PRT PORTA
#define LCD_DDR DDRA
#define LCD_PIN PINA
#define LCD_RS 3
#define LCD_EN 2
#define LCD_RW 1
#include <avr/io.h>
#include <util/delay.h>
#include <stdlib.h>
#include <avr/interrupt.h>

volatile unsigned int counter=0;                    //Counter for Timer/Counter1
int day=0;                                          //Number of days passed
unsigned int month[6];                              //Array of monthly usage data
char month_no=0;
int count=0;                                        //PIR Count of people

void delay_us(int d)
{
        _delay_us(d)
}

void delay_ms(int d)
{
        _delay_ms(d)
}


// Functions of  Timer/Counter1
ISR(TIM1_OVF)                                       //Timer/Counter1 Overflow ISR
{
        counter++;                                  //+2 sec
        TCNT1H=0xC2;                                // Adding offset
        TCNT1L=0xF5;
}

void initT1()                                       //Initialization of Timer/Counter1
{
        TCNT1H=0xC2;                                // Adding offset
        TCNT1L=0xF5;
        TCCR1A=0x00;                                //Normal Mode
        TCCR1B=0x05;                                //prescaler of 1024
```

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	TIMSK1 |= 1<<TOIE1;                    //enable Timer/Counter1 overflow interrupt
}

//Function of Pir Sensor
ISR(INT0)
{
	count++;
	GIMSK = 0x00;                          //Disable External Interrupt Request
	delay_ms(120000);                      //Delay of 2 min
	GIMSK =(1<<INT0)|(0<<PCIE1)|(0<<PCIE0);  //External Interrupt Request 0
                                           //Enable and Pin Change Interrupt
                                           //Disable for 1 and 0
}

void initI0()                              //Initialization Of External Interrupt 0
{
	GIMSK =(1<<INT0)|(0<<PCIE1)|(0<<PCIE0);  //External Interrupt Request 0
                                           //Enable and Pin Change Interrupt
                                           //Disable for 1 and 0
	MCUCR = (1<<ISC01)|(1<<ISC00);         //The rising edge of INT0 generates
                                           //an interrupt request
}

//LCD
void lcdCommand( unsigned char cmnd )
{
	LCD_PRT = (LCD_PRT & 0x0F) | (cmnd & 0xF0);
	LCD_PRT &= ~ (1<<LCD_RS);              //RS = 0 for command
	LCD_PRT &= ~ (1<<LCD_RW);              //RW = 0 for write
	LCD_PRT |= (1<<LCD_EN);                //EN = 1 for H-to-L pulse
	delay_us(1);                           //make EN pulse wider
	LCD_PRT &= ~ (1<<LCD_EN);              //EN = 0 for H-to-L pulse

	delay_us(20);                          //wait

	LCD_PRT = (LCD_PRT & 0x0F)|(cmnd<<4);  //Send low nibble to D4-D7
	LCD_PRT |= (1<<LCD_EN);                //EN = 1 for H-to-L pulse
	delay_us(1);                           //make EN pulse wider
	LCD_PRT &= ~ (1<<LCD_EN);              //EN = 0 for H-to-L pulse
}

void lcdData( unsigned char data )
{
	LCD_PRT = (LCD_PRT & 0x0F) | (data & 0xF0);  //Send high nibble to D4-D7
	LCD_PRT |= (1<<LCD_RS);                //RS = 1 for data
	LCD_PRT &= ~ (1<<LCD_RW);              //RW = 0 for write
	LCD_PRT |= (1<<LCD_EN);                //EN = 1 for H-to-L pulse
	delay_us(1);                           //make EN pulse wider
	LCD_PRT &= ~ (1<<LCD_EN);              //EN = 0 for H-to-L pulse
	LCD_PRT = (LCD_PRT & 0x0F) | (data <<4);  //Send low nibble to D4-D7
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	LCD_PRT |= (1<<LCD_EN);			//EN = 1 for H-to-L pulse
	delay_us(1);				//make EN pulse wider
	LCD_PRT &= ~ (1<<LCD_EN);		//EN = 0 for H-to-L pulse
}

void lcd_init()
{
	LCD_DDR = 0x7F;

	LCD_PRT &=~(1<<LCD_EN);			//LCD_EN = 0
	delay_us(2000);
	lcdCommand(0x33);			//send $33 for init.
	delay_us(100);
	lcdCommand(0x32);			//send $32 for init
	delay_us(100);
	lcdCommand(0x28);			//init. LCD 2 line,5*7 matrix
	delay_us(100);
	lcdCommand(0x0e);			//display on, cursor on
	delay_us(100);
	lcdCommand(0x01);			//clear LCD
	delay_us(2000);
	lcdCommand(0x06);			//Shift cursor right
	delay_us(100);
}

void lcd_gotoxy(unsigned char x, unsigned char y)	//function to goto x,y on LCD
{
	unsigned char firstCharAdr[]={0x80,0xC0,0x94,0xD4} ;
	lcdCommand(firstCharAdr[y-1] + x - 1);
	delay_us(100);
}

void lcd_print(char * str )				//function to print given str. on LCD
{
	unsigned char i = 0 ;
	while(str[i]!=0)
	{
		lcdData(str[i]);
		i++ ;
	}
}


//Main Code
int main(void)
{
	DDRA=0b00111111;			//LCD Interfacing
	PORTB2=1;				//pull up activated
	initI0();				//External Interrupt 0
	initT1();				//Timer/Counter1 to count time
```

```
        sei();                                          //enable global interrupt
        while(1)
        {
                if(counter>=43200)                      //No of days passed (30*60*24 = 43200 )
                {
                        day++;                          //+day
                        counter=counter-43200;          //counter remainder
                }
                if (day==30)
                {
                        month[month_no]=((count/2)/30);     //Assigning monthly average data
                        month_no++;                         //+month_no
                        day=0;
                }
        }

        if ( PINA & 0b00000001)
        {
                //LCD code
                lcd_init();
                lcd_gotoxy(1,1);
                lcd_print("%4d  %4d  %4d",month[0], month[1], month[2]);
                lcd_gotoxy(1,2);
                lcd_print("%4d  %4d  %4d",month[3], month[4], month[5]);

        }

}
```