KNN IMPUTER →

PROBLEM OF DEGREE OF FREEDOM :

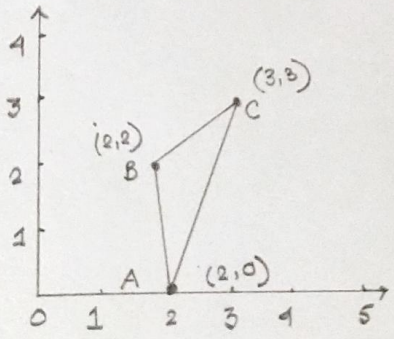
- Generally, if the proportion of missing observations in a dataset is small relative to number of observations, we can simply remove those observations However this is not often most cases.

- Deleting the rows containing missing values may lead to parting away with useful informations or patterns.
- In statistical terms, this leads to reduce degree of freedom as the number of independent pieces of information goes down.

KNN IMPUTATION —

- KNN identifies the neighbouring points through a measure of distance and the missing values can be estimated using value of neighbouring observations.
- Neighbouring points of a dataset are identified by certain distance metric generally euclidean distance.

DISTANCE CALCULATION IN THE PRESENCE OF MISSING VALUES —



Consider 3 observation A(2,0), B(2,2), C(3,3)

$$d_{AB} = \sqrt{(2-2)^2 + (0-2)^2} = \sqrt{0+4} = \sqrt{4}$$

$$d_{BC} = \sqrt{(3-2)^2 + (3-2)^2} = \sqrt{1+1} = \sqrt{2}$$

$$d_{AC} = \sqrt{(2-3)^2 + (0-3)^2} = \sqrt{1+9} = \sqrt{10}$$

The point with the shortest distance based on Euclidean distances are considered to the nearest neighbour.

For example, 1 nearest neighbour to Point A is Point B, For Point B, 1NN is C.

In the presence of missing coordinates, Euclidean distance is calculated by ignoring the missing values and scaling up the weight of non-missing coordinate

$$d_{xy} = \sqrt{\text{weight} * \text{square distance from present coordinates}}$$

where, $$\text{weight} = \frac{\text{Total number of coordinates}}{\text{Number of present coordinates}}$$

For example, two datapoints A(3, NA, 5) and B(1, 0, 0)

$$\text{KNN Imputation of NA} = \sqrt{\frac{3}{2}\{(3-1)^2 + (5-0)^2\}} = 6.595$$

In python,

```
import numpy as np.
from sklearn.metrics.pairwise import nan_euclidean_distances.
X = [[3, np.nan, 5]]
Y = [[1, 0, 0]]
nan_euclidean_distances(X, Y)   # 6.595.
```

Suppose we have matrix / dataset

```
from sklearn.impute import KNNImputer.
import numpy as np.
X = [[3, np.NaN, 5], [1, 0, 0], [3, 3, 3]]
imputer = KNNImputer(n_neighbors = 1).
impute_with_1 = imputer.fit_transform(X)
imputer = KNNImputer(n_neighbors = 2).
impute_with_2 = imputer.fit_transform(X).
```