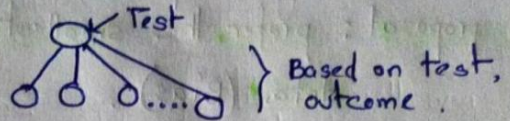
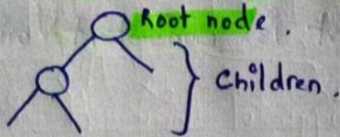


1 DECISION TREE (INTRODUCTION) (Pages 1-8)

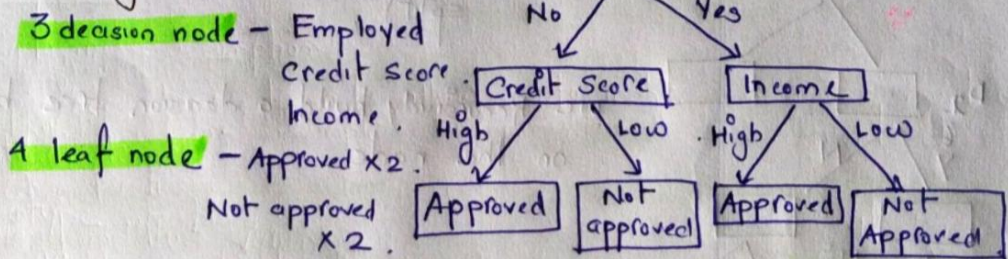
Page 1

- Non linear function.
- A tree has nodes and branches.



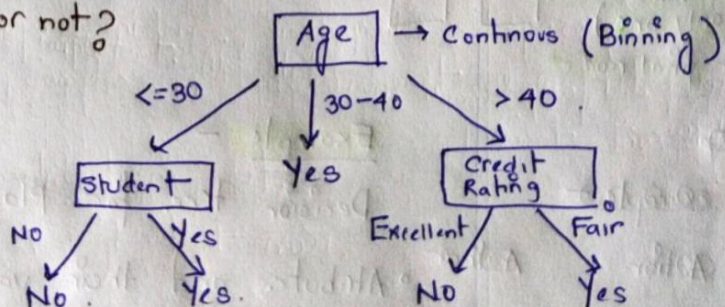
- 2 type of nodes - i) Decision Node . ii) Leaf node .
- In decision node we specify a choice or test based on this we can decide which direction we can go.
- The test is usually done on the value of a feature or attribute of the instance.
- Leaf node indicate the classification of an example or value of the example.
- Decision tree can be used for classification and regression.
- Test will be done until we reach the value of the example / predicted value for classification, regression (target variable) or it can be probability.

Example - To give loan or not?

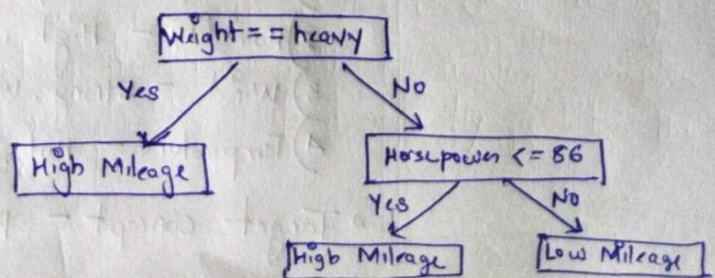


Will buy a computer or not?

Yes → Will buy
No → Not buy



Car Mileage prediction?



- By seeing a training sets, it should build a decision tree.

Issues

- Given some training examples, what decision tree should be generated?
- One proposal: prefer the smallest tree that is consistent with the data (Bias).

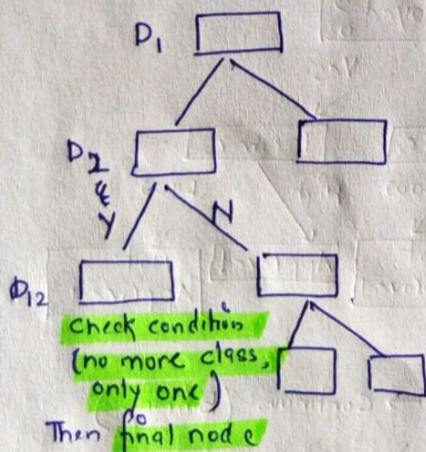
Possible Method:

- Search the space of decision trees for the smallest decision tree that fits the data.

Choose a tree which have less error.

- So choose bias.
- Once we choose decision tree as hypothesis space, so put some bias. Preferably, we should have smaller trees (bias).
Smaller tree means small number of nodes / small depth.

- Recursively built a decision tree - At every step, we check the condition (if yes we want to increase a tree, on which feature we want to split).



we Recursively build a decision tree based on the node.

Example

~~training examples~~

Action

Action

Example -

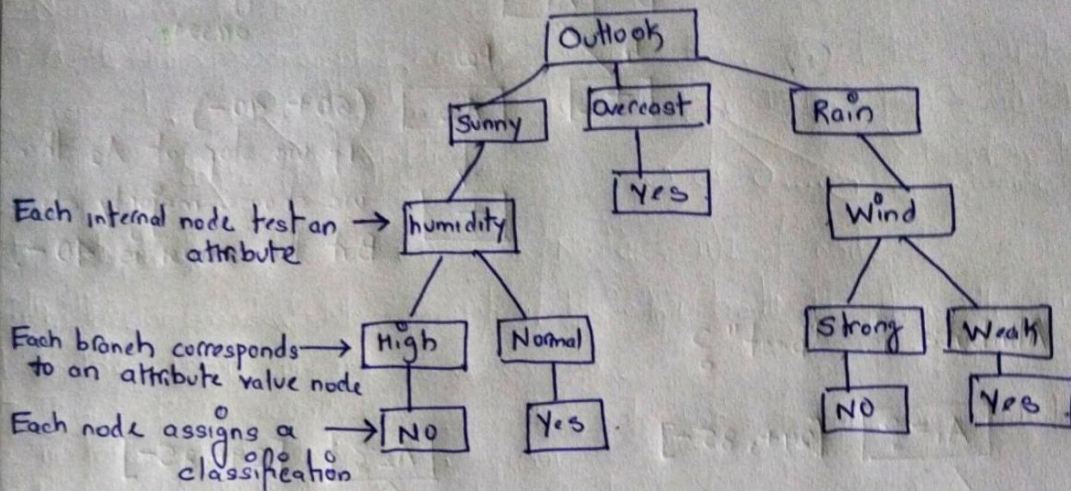
Decision tree for Play Tennis

Attributes and their values:

- 1) outlook - Sunny, Overcast, Rain
- 2) Humidity - High, Normal
- 3) Wind - Strong, Weak
- 4) Temperature - Hot, Mild, cold.

Target concept - Play tennis - Yes/No.

③ Sample decision tree for Play Tennis -



Question → Outlook Sunny Temperature Hot Humidity High Wind Weak Play Tennis ?
(No)

Searching for a good tree ?

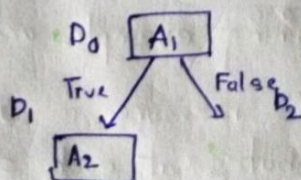
- The space of decision trees is too big for symmetric search.
- Stop and
 - return the a value of for the target feature or.
 - a distribution over target features values.
- Choose a test (eg input feature) to split on.
 - For each value of test, build a subtree for those examples with this value for the test.

Two Main Questions - i) When to stop the decision tree ?
ii) Which attribute to choose for split ?

Learning Decision tree -

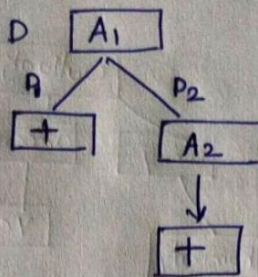
Attribute $A = A_1, A_2, A_3, \dots, A_n$.

Decision → D .



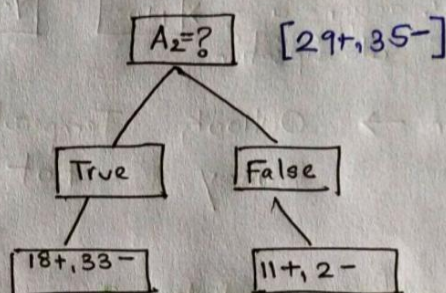
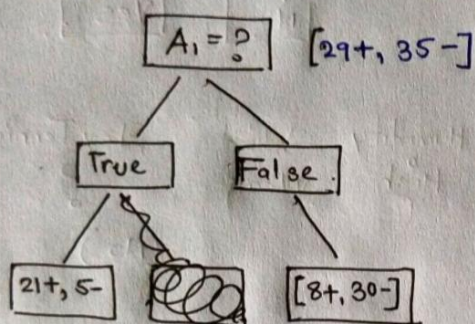
1) When to stop?

2) Which attribute to split on? → Split should give the smallest error.



(60+, 40-)
If we stop at A2 then we choose majority class. But the error is 40-.

→ Which Attribute is "best"?



Entropy - It is a measure of disorder in a system.

If in particular node, all value is of one class (either + or -) then it is homogenous class and entropy is 0, entropy is low.

- If it contain half-half class, then entropy is high.
- Leaf node have lowest entropy.

Principled criterion - selection of an attribute to test at each node - choosing the most useful attribute for classifying examples.

Information gain - Measure how well a given attribute separates the training example according to their target classification.

- This measure is used to select among the candidate attributes at each step while growing the tree.
- Gain is measure of how much we can reduce uncertainty (Values lies between 0,1).

⑤

- So if all examples have same target classification, information is high and information gain is high. (No certainty)
- In case of 50-50, information gain is low. (High certainty)

So first choose entropy and then basis of that choose information gain.

Entropy \rightarrow High purity \rightarrow Entropy = 0.

$$\text{Entropy} = -\log_2 P$$

probability

- A measure for i) uncertainty ii) purity iii) information gain.

- Information theory: Optimal length code assigns $(-\log_2 P)$ bits to message having probability P .

- S is the sample of training examples

- P_+ is the proportion of positive example in S .

- P_- is the proportion of negative example in S .

- Entropy(S) - Average optimal numbers of bits to encode information about certainty / uncertainty about S .

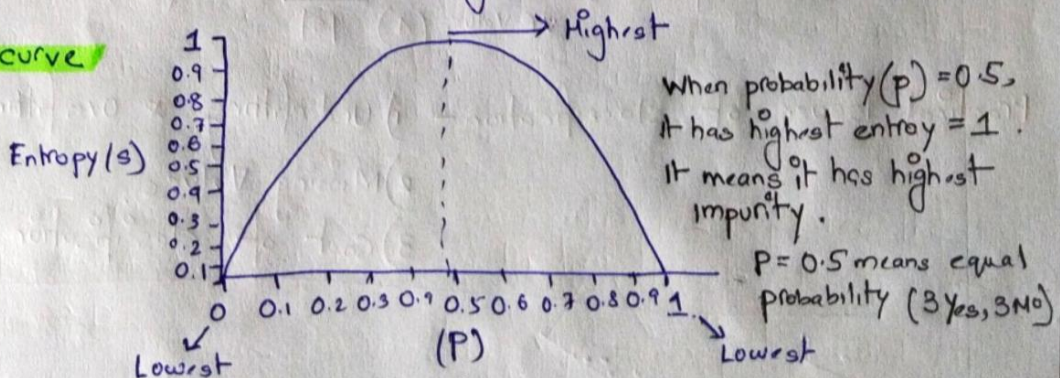
$$\text{Entropy}(S) = P_+ (-\log_2 P_+) + P_- (-\log_2 P_-)$$

$$\text{Entropy}(S) = -P_+ \log_2 P_+ - P_- \log_2 P_-$$

$P_+ = 1, P_- = 0$ / $P_+ = 0, P_- = 1$, Entropy will be lowest, if class contain only one class.

$P_+ = 1/2, P_- = 1/2$, Entropy will be highest, if it contain equally both class.

Entropy curve



- The entropy is 0 if the outcome is "certain".

- The entropy is maximum if we no knowledge of system (or any outcome is equally possible)

Information Gain -

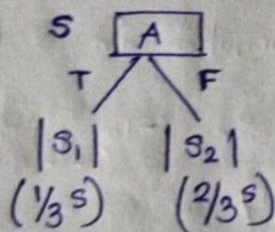
Gain (S, A) - Expected reduction in entropy due to partitioning S on attribute A. For every value of A, if we split the how many A.

$$\text{Gain}(S, A) = \text{Entropy}(S) - \sum_{v \in \text{values}(A)} \frac{|S_v|}{|S|} \text{Entropy}(S_v)$$

$$\text{Entropy}([29+, 35-]) = -29/64 \log_2 29/64 - 35/64 \log_2 35/64$$

$$= 0.99$$

Suppose,



$$\Rightarrow \text{Entropy} = \frac{1}{3} |S_1| + \frac{2}{3} |S_2|$$

$$\text{Information gain} = \text{Entropy}(S) - \sum \frac{|S_v|}{|S|} \text{Entropy}(S_v)$$

(original Entropy) (Resulting entropy)

- Information gain is high, on that split should be done. In other word, reduce the entropy reduction in entropy because we want low entropy and smaller decision tree.

Other popular rule for splitting - Gini Index.

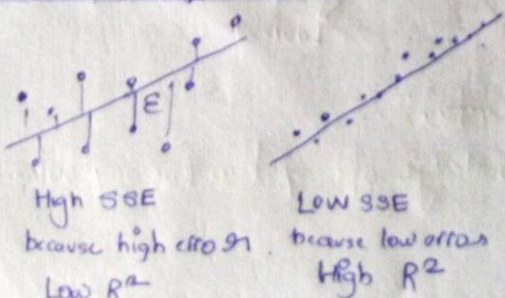
- Measure of node impurity

$$\text{GINI}_{\text{node}}(\text{Node}) = 1 - \sum_{c \in \text{classes}} [p(c)]^2$$

$$\text{GINI}_{\text{split}}(A) = \sum_{v \in \text{Values}(A)} \frac{|S_v|}{|S|} \text{GINI}(N_v)$$

Practical Issues of classification -

- 1) Underfitting & overfitting
- 2) Missing Values
- 3) Cost of classification.



High SSE

Low SSE

because high errors

because low errors

Low R^2

High R^2