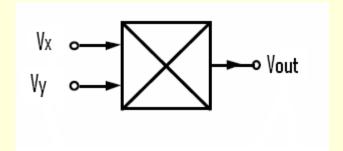


Microelectronics

Chapter 2:

(Lecture 2 and 3)

BJT and MOS Analog Multiplier



Analog Multiplier

Objectives:

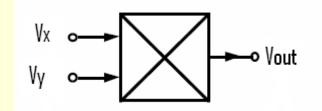
- Introduction
- 2. Revision of Simple Emitter Coupled Circuit.
- 3. Gilbert Cell As a 4-quadrant Multiplier
- 4. Complete Gilbert Multiplier without any restriction on the I/P Signals.
- 5. The application of the Gilbert Cell to realize a Phase Detector (PD)
- 6. Gilbert Cell as a DSB-SC Modulator
- MOS Gilbert Cell



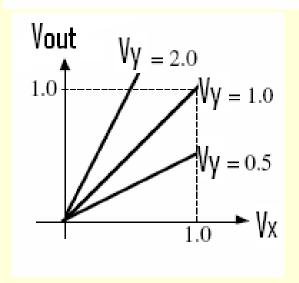
Introduction

- One of the fundamental building blocks in analog circuit design is the analog multiplier.
- Multipliers are particularly important in communication and signal processing circuits.
- Applications of Multipliers
 - Nonlinear analog signal processing
 - Mixing
 - Phase difference detection
 - Modulation and demodulation
 - Frequency translation

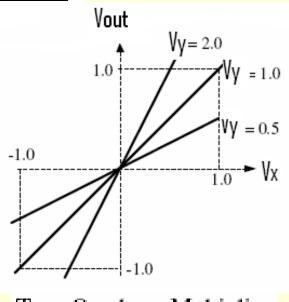
Introduction



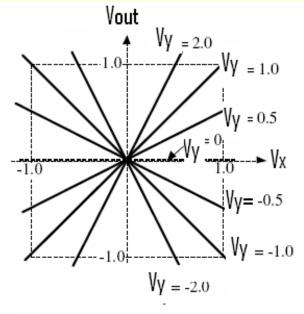
Types of Multiplication



One-Quadrant Multiplier



Two-Quadrant Multiplier



Four-Quadrant Multiplier

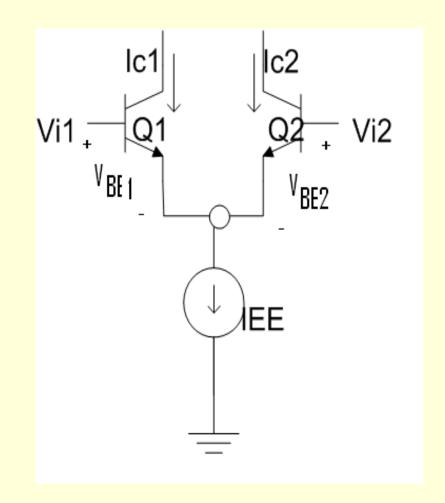
The Basic equation of the ECC is:

$$V_{i1} - V_{BE1} = V_{i2} - V_{BE2}$$

But in the active region, the collector current of the npn transistor is given by:

$$I_C = I_o e^{\frac{V_{BE}}{V_T}}$$

$$\Rightarrow V_{BE} = V_T \ln(\frac{I_C}{I_o})$$



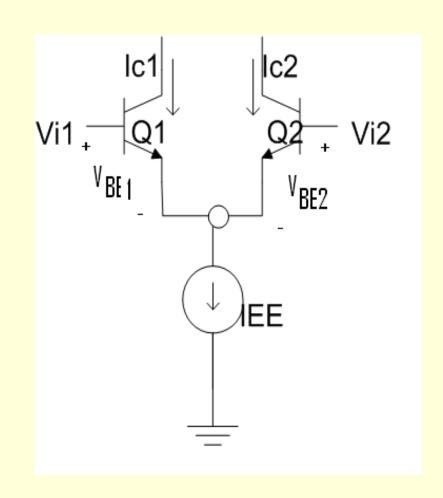
Therefore

$$V_{i1} - V_{i2} = V_{id} = V_T \ln(\frac{I_{C1}}{I_{o1}}) - V_T \ln(\frac{I_{C2}}{I_{o2}})$$

For a matched transistors

$$I_{o1} = I_{o2}$$

$$V_{id} = V_T \ln(\frac{I_{C1}}{I_{C2}})$$

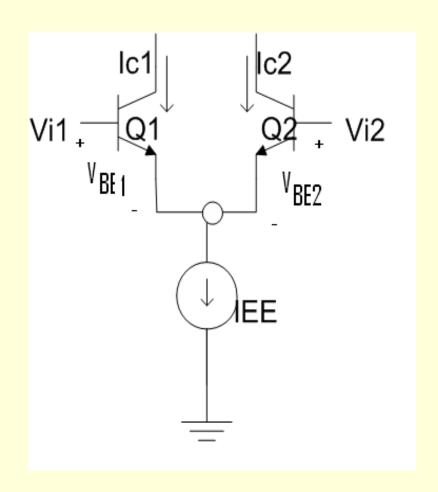


Therefore:

$$\frac{I_{C1}}{I_{C2}} = e^{\frac{V_{id}}{V_T}} \tag{1}$$

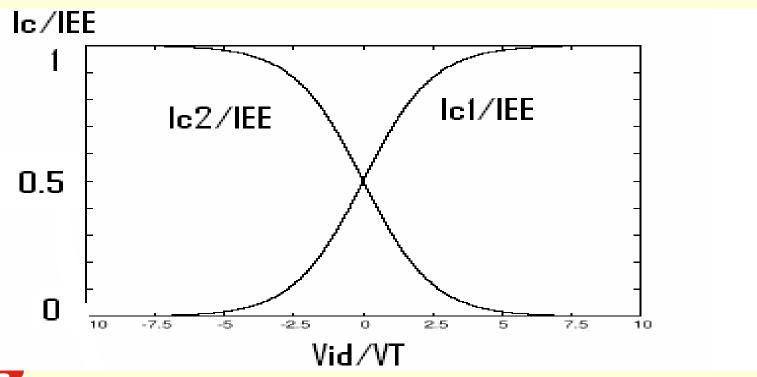
And assuming high β

$$I_{C1} + I_{C2} = IEE \tag{2}$$



From (1) and (2):

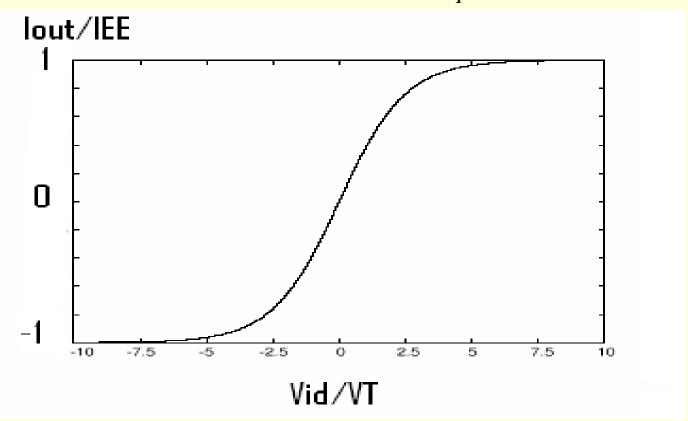
$$I_{C1} = \frac{IEE}{\frac{V_{id}}{1 + e^{V_T}}}$$
 & $I_{C2} = \frac{IEE}{\frac{V_{id}}{V_T}}$





And also:

$$I_{out} = IEE \tanh(\frac{V_{id}}{2V_T})$$





Note That:

For
$$\left|V_{id}\right| << V_T$$

The output current of the ECC is given by:

$$I_{out} \cong K(V_{id}) * (IEE)$$

Therefore, the circuit can operates as a multiplier with two inputs V_{id} and $I\!E\!E$

Where K is the constant of the proportionality and is given by:

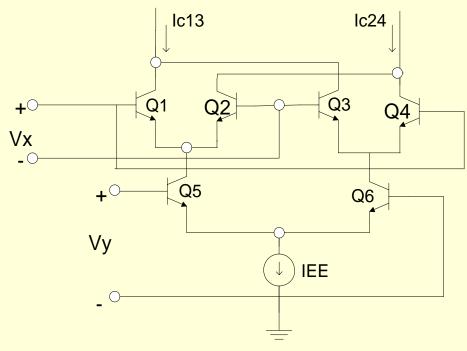
$$K = \frac{1}{2V_T} \quad [V^{-1}]$$

The disadvantages of the ECC as an multiplier:

- The circuits operates as 2- quadrant multiplier
 (Vid may be positive or negative but IEE must be positive)
- 2. The two inputs of the multiplier are not the same type (one of the inputs is voltage Vid and the another is current)
- 3. The circuits operates as 2- quadrant multiplier under the restriction: $|V_{id}| << V_T$

Gilbert Cell As a 4-quadrant Multiplier

The Gilbert Cell is a circuit used to overcome the disadvantages of the ECC.



The output differential current of the Gilbert Cell is defined as:

$$I_{out} = (I_{C13} - I_{C24}) = (I_{C1} + I_{C3}) - (I_{C2} + I_{C4})$$



Gilbert Cell As a 4-quadrant Multiplier

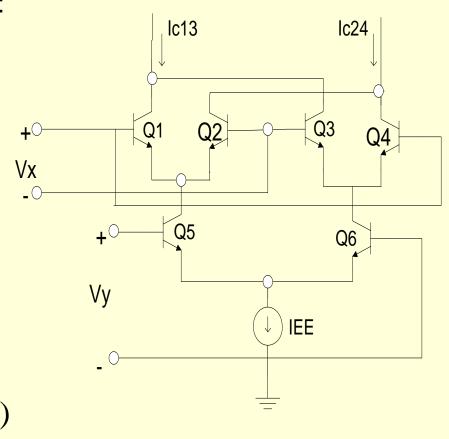
The output current can be written as:

$$I_{out} = (I_{C1} - I_{C2}) + (I_{C3} - I_{C4})$$

$$Iout = I_{C5} \tanh \frac{V_X}{2V_T} + I_{C6} \tanh(\frac{-V_X}{2V_T})$$

$$Iout = (I_{C5} - I_{C6}) \tanh(\frac{V_X}{2V_T})$$

$$Iout = IEE \tanh(\frac{V_Y}{2V_T}) \tanh(\frac{V_X}{2V_T})$$





Gilbert Cell As a 4-quadrant Multiplier

Note that:

From the expression of the output current of the Gilbert Cell:

$$Iout = IEE \tanh(\frac{V_Y}{2V_T}) \tanh(\frac{V_X}{2V_T})$$

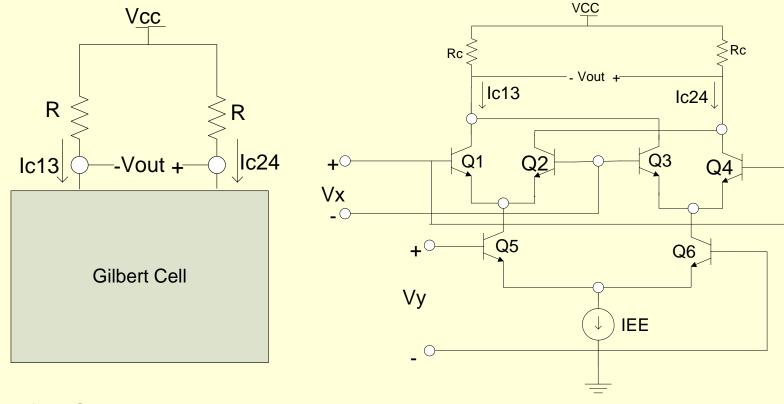
For

$$|V_X| \& |V_Y| << V_T \implies I_{out} \cong K(V_X * V_Y)$$

Therefore Gilbert Cell operates as 4-quadrant multiplier because Vx & Vy can take positive and negative values, Where $K = \frac{IEE}{(2V_T)^2}[mA/V^2]$

Gilbert Cell As a 4-quadrant Multiplier with Output Voltage

Note that: The output of the Gilbert Multiplier is a current, and if it is required to have an output voltage, a differential current to a voltage converter is needed. This can be realized by using the two resistors connected to Vcc as shown.





Gilbert Cell As a 4-quadrant Multiplier with Output Voltage

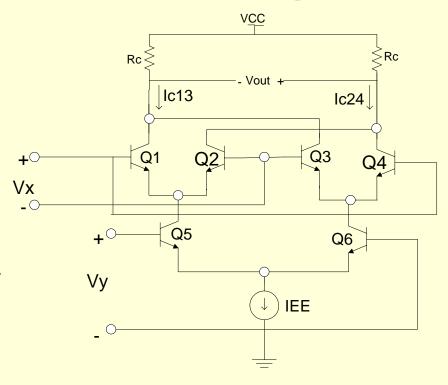
$$V_{out} = (V_{CC} - I_{C24}R_C) - (V_{CC} - I_{C13}R_C)$$

$$V_{out} = (I_{C13} - I_{C24})R_C$$

$$V_{out} = I_{EE}R_C \tanh(\frac{V_X}{2V_T}) \tanh(\frac{V_Y}{2V_T})$$

$$V_{out} \cong K(V_X * V_Y)$$
 For $|V_X| \& |V_Y| << V_T$

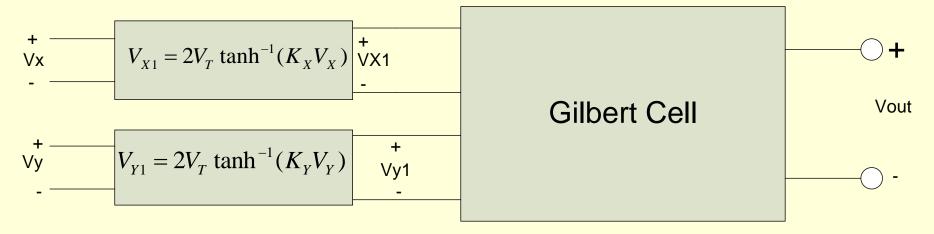
Where
$$K = I_{EE}R_C/(2V_T)^2[V^{-1}]$$



Note that: For large signals, the Gilbert cell is not operate correctly as a multiplier, therefore we try to make the I/P signals pass through certain circuits that eliminate the nonlinearity of the tanh function.

Complete Gilbert Multiplier without any restriction on the I/P Signals

Basic Idea



$$V_{out} = I_{EE}R_C \tanh(\frac{V_{X1} = 2V_T \tanh^{-1}(K_X V_X)}{2V_T}) \tanh(\frac{V_{Y1} = 2V_T \tanh^{-1}(K_Y V_Y)}{2V_T})$$

$$V_{out} = K(V_X * V_Y)$$
 where $K = I_{EE}R_CK_XK_Y[V^{-1}]$



tanh⁻¹ circuit

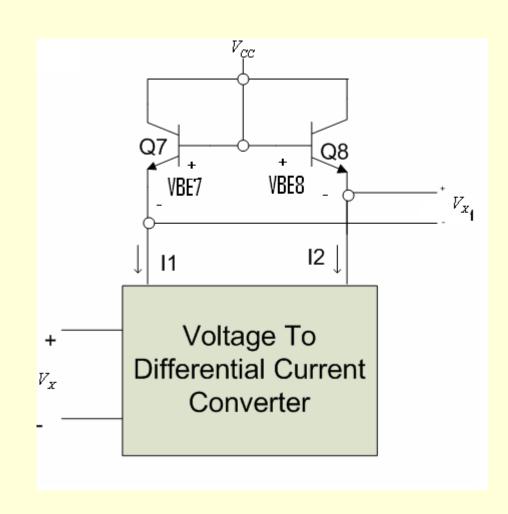
From the shown circuit:

$$V_{X1} = V_{BE7} - V_{BE8}$$

$$V_{X1} = V_T \ln(\frac{I_1}{I_{o7}}) - V_T \ln(\frac{I_2}{I_{o8}})$$

Assuming Q7 and Q8 are matched

$$V_{X1} = V_T \ln(\frac{I_1}{I_2})$$



tanh⁻¹ circuit

Assuming the voltage to differential current converter produces two Output currents given by:

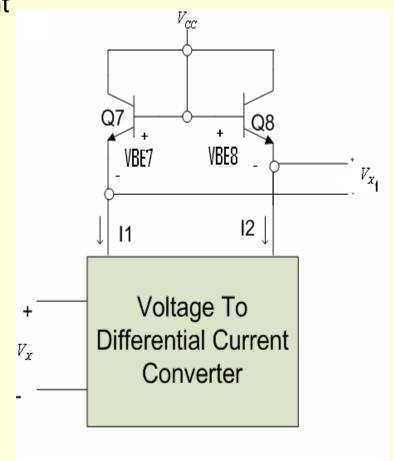
$$I_1 = I_{dc}(1 + K_X V_X)$$
 &

$$I_2 = I_{dc}(1 - K_X V_X)$$

Therefore, the output voltage of the tanh-1 circuit is given by:

$$V_{X1} = V_T \ln(\frac{1 + K_X V_X}{1 - K_X V_X})$$

$$\implies V_{X1} = 2V_T \tanh^{-1}(K_X V_X)$$

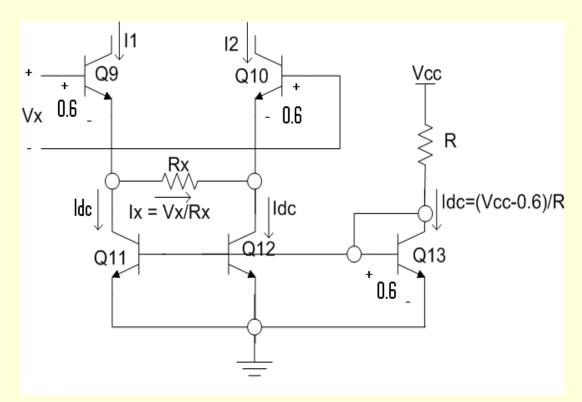




Voltage to Differential Current Converter

From the shown circuit, we have:

$$\begin{split} I_1 &= I_{dc} + \frac{V_X}{R_X} \\ I_1 &= I_{dc} (1 + \frac{V_X}{I_{dc} R_X}) \\ \Rightarrow I_1 &= I_{dc} (1 + K_X V_X) \\ \text{and} \qquad K_X &= \frac{1}{I_{dc} R_X} \end{split}$$



Similarly
$$I_2 = I_{dc}(1 - K_X V_X)$$



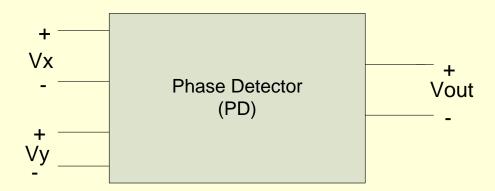
The application of the Gilbert Cell to realize a Phase Detector (PD)

Phase Detector is a circuit provide output voltage proportional to the phase difference between two input signals.

Types of PD:

Linearized phase detector: The output is linearly proportional to the phase difference between the two input signal.

Sinusoidal phase detector: The output is proportional to the Sin or Cosine the phase difference between the two input signal.





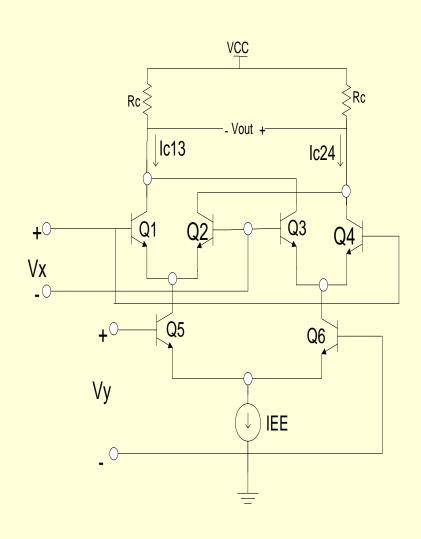
Linearized PD

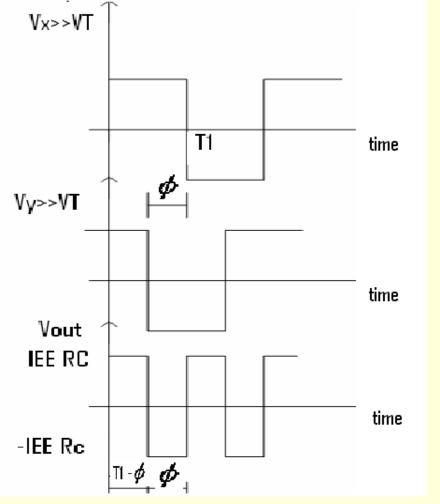
Condition on the inputs for proper operations:

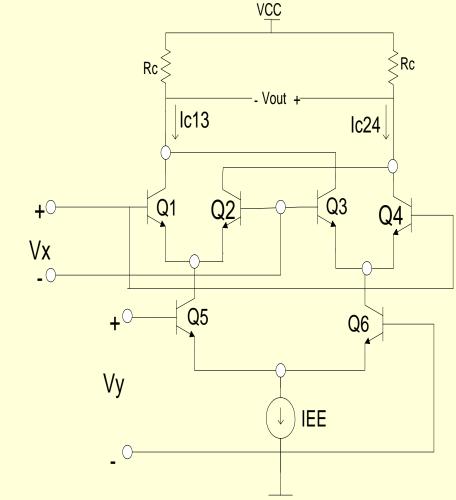
The amplitudes of $\left|V_{X}\right| \& \left|V_{y}\right| >> V_{T}$

Therefore, the transistors operate as a switch (ON/OFF)

Example: Draw the output waveform and calculate its average value for the input signal waveforms shown below:







$$\bar{V}_{out} = \int_{0}^{T_{1}} v_{out}(t)dt = -\frac{1}{T_{1}} [I_{EE}R_{C}\phi - I_{EE}R_{C}(T_{1} - \phi)]$$

$$\bar{V}_{out} = -I_{EE}R_{C}[2\phi/T_{1} - 1]$$

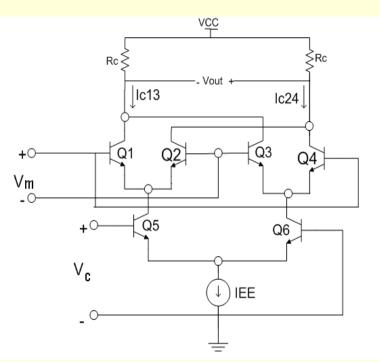


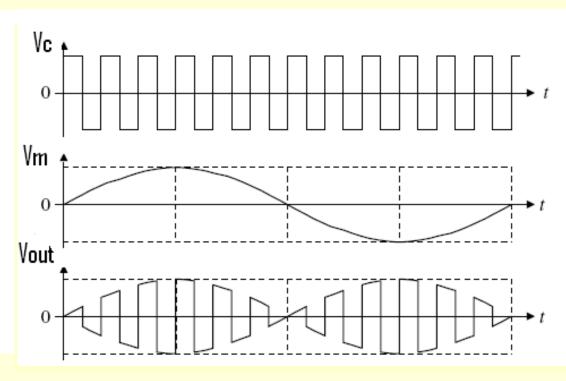
Prof. Dr. Soliman Mahmoud & Dr. Ahmed Madian Electronics and Electrical Engineering Department

Gilbert Cell as a DSB-SC Modulator

Condition on the inputs for proper operations:

The Gilbert Cell can be used as a switching modulator under the condition, One of the input signal (Carrier) is >> VT and the another input (modulating Signal) is << VT







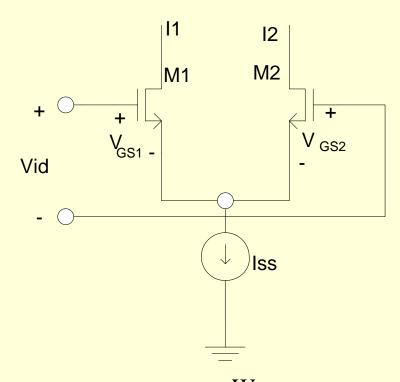
The output current of the NMOS Differential pair is given:

$$I_{out} = I_1 - I_2$$

Where the currents of M1 and M2 in the saturation region are given by:

$$I_1 = \frac{K_1}{2} (V_{GS1} - V_T)^2 = \frac{K_1}{2} A^2$$

$$I_2 = \frac{K_2}{2} (V_{GS2} - V_T)^2 = \frac{K_2}{2} B^2$$



And assuming M1 and M2 are matched ($K_1 = K_2 = \mu_n C_{ox} \frac{W}{L}$)

Therefore:

$$I_{out} = \frac{K}{2}(A^2 - B^2) = \frac{K}{2}(A - B)(A + B) + \bigcirc$$

$$\text{And } I_1 + I_2 = \frac{K}{2}(A^2 + B^2) = I_{SS}$$

Where
$$A-B=V_{GS\,1}-V_{GS\,2}=V_{id}$$

Note:
$$(A+B)^2 + (A-B)^2 = 2(A^2 + B^2)$$

$$(A+B)^{2} = 4\frac{I_{SS}}{K} - V^{2}_{id} \longrightarrow (A+B) = \sqrt{4\frac{I_{SS}}{K}} (\sqrt{1 - \frac{V^{2}_{id}}{4I_{SS}/K}})$$

$$I_{out} = \sqrt{I_{SS}KV_{id}}(\sqrt{1 - \frac{V_{id}^2}{4I_{SS}/K}})$$



Note:

$$I_{out} = I_1 - I_2 = \sqrt{I_{SS}KV_{id}}(\sqrt{1 - \frac{V_{id}^2}{4I_{SS}/K}})$$

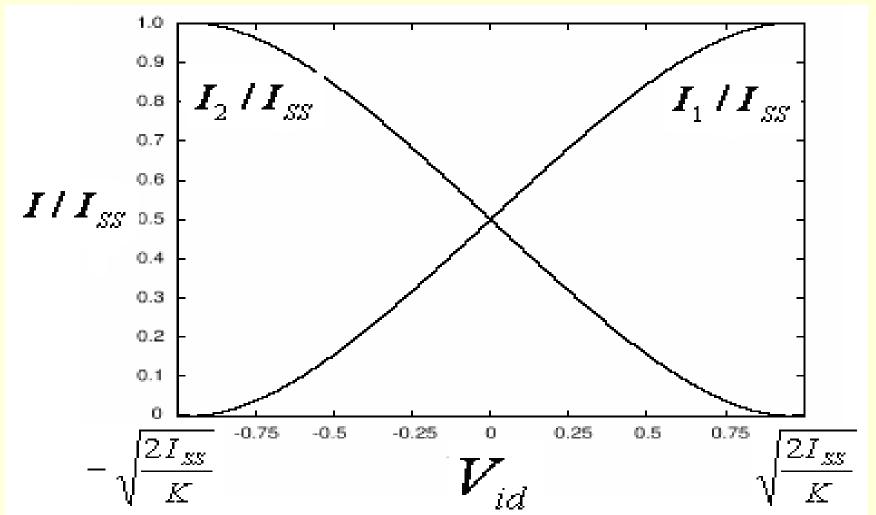
and

$$I_1 + I_2 = I_{SS}$$

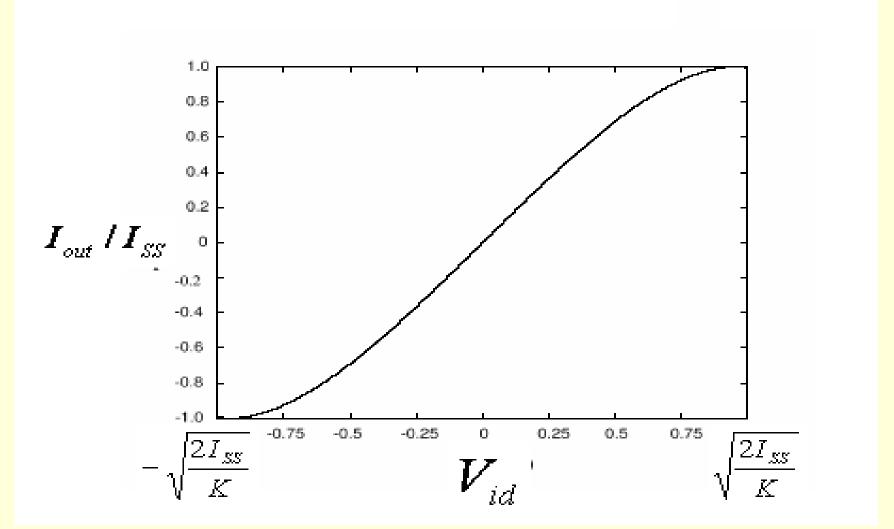
Therefore:

$$I_{1} = \frac{I_{SS}}{2} + \frac{1}{2} \sqrt{I_{SS} K} V_{id} \left(\sqrt{1 - \frac{V_{id}^{2}}{4I_{SS} / K}} \right)$$

$$I_{2} = \frac{I_{SS}}{2} - \frac{1}{2} \sqrt{I_{SS} K} V_{id} \left(\sqrt{1 - \frac{V_{id}^{2}}{4I_{SS} / K}} \right)$$









Note: if
$$V_{id} < \sqrt{\frac{2I_{SS}}{K}}$$

The nonlinear term of output current can be neglected and the output current is given by:

$$I_{out} \cong \sqrt{I_{SS}KV_{id}}$$

and

$$I_1 \cong \frac{I_{SS}}{2} + \frac{1}{2} \sqrt{I_{SS} K} V_{id}$$

$$I_2 \cong \frac{I_{SS}}{2} - \frac{1}{2} \sqrt{I_{SS} K} V_{id}$$

MOS Gilbert Cell

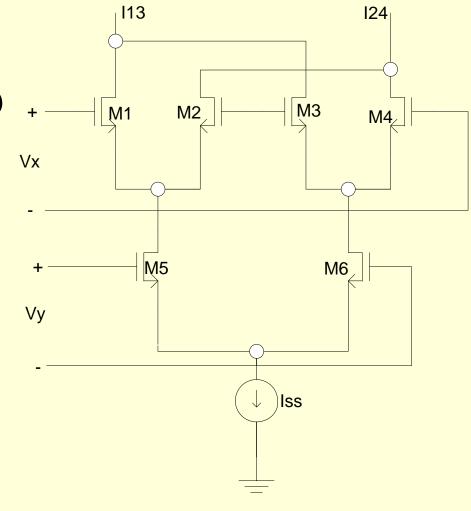
The output current can be written as:

$$I_{out} = I_{13} - I_{24} = (I_1 - I_3) + (I_2 - I_4)$$

$$I_{out} \cong \sqrt{I_5 K} V_X - \sqrt{I_6 K} V_X$$

$$I_{out} \cong \sqrt{K} (\sqrt{I_5} - \sqrt{I_6}) V_X$$

and
$$(\sqrt{I_5} - \sqrt{I_6}) = \sqrt{\frac{K}{2}}V_y$$





BJT and MOS Analog Multiplier

END of Chapter 2