1 Arbitrary s.p.d. metric

1.1 Assumptions

- Ind(M) = 0
- $g = \begin{bmatrix} g_{11} & g_{12} \\ g_{12} & g_{22} \end{bmatrix} = g_{11} (dx^1)^2 + 2g_{12} dx^1 dx^2 + g_{22} (dx^2)^2 (\mathbf{s.p.d.})$

1.2 General proberties

 $\alpha \in \Omega^p(M), \, \beta \in \Omega^q(M), \, \gamma \in \Omega^r(M), \, \vec{v} \in \mathcal{V}(M)$

1.2.1 Wedge product \wedge

- $\alpha \wedge \beta = (-1)^{pq}\beta \wedge \alpha$ (anti-/commutativ)
- associativ $(\alpha \land \beta \land \gamma)$
- $(c_1\alpha + c_2\beta) \wedge \gamma = c_1\alpha \wedge \gamma + c_2\beta \wedge \gamma$ (bilinear)

1.2.2 Exterior derivative $d: \Omega^p(M) \to \Omega^{p+1}(M)$

 $\alpha \in \Omega^p(M)$

- $\mathbf{d} \circ \mathbf{d} = 0$ (complex proberty)
- $\mathbf{d}(\alpha \wedge \beta) = \mathbf{d}\alpha \wedge \beta + (-1)^p \alpha \wedge \mathbf{d}\beta$ (product rule, \wedge -antiderivation)

1.2.3 Hodge star $*: \Omega^p(M) \to \Omega^{2-p}(M)$

- $\alpha \wedge *\beta = \beta \wedge *\alpha = \langle \alpha, \beta \rangle \mu$
- $*1 = \mu$ (* $\mu = 1$)
- ** $\alpha = (-1)^p \alpha$
- $\langle \alpha, \beta \rangle = \langle *\alpha, *\beta \rangle$

1.2.4 Contraction $\mathbf{i}: (\mathcal{V} \times \Omega^p)(M) \to \Omega^{p-1}(M)$ (inner product)

- $\mathbf{i}_{\vec{v}}\alpha\left(\vec{t}_{1},\ldots\vec{t}_{p-1}\right) = \alpha\left(\vec{v},\vec{t}_{1},\ldots\vec{t}_{p-1}\right)$
- $f \mathbf{i}_{\vec{v}} \alpha = \mathbf{i}_{f \vec{v}} \alpha = \mathbf{i}_{\vec{v}} f \alpha$ (bilinear)
- $\mathbf{i}_{\vec{v}}(\alpha \wedge \beta) = (\mathbf{i}_{\vec{v}}\alpha) \wedge \beta + (-1)^p \alpha \wedge (\mathbf{i}_{\vec{v}}\beta) \ (\wedge$ -antiderivation)

1.2.5 Lie-derivative $\mathcal{L}: (\mathcal{V} \times \Omega^p)(M) \to \Omega^p(M)$

- $\mathcal{L}_{\vec{v}}\alpha = \mathbf{i}_{\vec{v}}\mathbf{d}\alpha + \mathbf{di}_{\vec{v}}\alpha$ (Cartans magic formular)
- $\mathcal{L}_{f\vec{v}}\alpha = f\mathcal{L}_{\vec{v}}\alpha + \mathbf{d}f \wedge \mathbf{i}_{\vec{v}}\alpha$
- $\mathcal{L}_{\vec{v}}(\alpha \wedge \beta) = \mathcal{L}_{\vec{v}}\alpha \wedge \beta + \alpha \wedge \mathcal{L}_{\vec{v}}\beta$
- $\mathcal{L}_{\vec{v}}\mathbf{d}\alpha = \mathbf{d}\mathcal{L}_{\vec{v}}\alpha$
- $\mathcal{L}_{\vec{v}}\mathbf{i}_{\vec{v}}\alpha = \mathbf{i}_{\vec{v}}\mathcal{L}_{\vec{v}}\alpha$ $\Rightarrow \alpha \in \Omega^{1}(M) : \mathcal{L}_{\vec{v}}\langle \vec{v}^{\flat}, \alpha \rangle = \langle \vec{v}^{\flat}, \mathcal{L}_{\vec{v}}\alpha \rangle$
- $\mathcal{L}_{\vec{v}}\vec{w} = [\vec{v}, \vec{w}] = \nabla_{\vec{v}}\vec{w} \nabla_{\vec{w}}\vec{v}$ ((Levi-Civita-)Conection ∇ is Torsion-free)

1.3 Wedge product ∧

 $f \in \Omega^0(M), \ \tilde{f} \in \Omega^0(M), \ \alpha := a_1 dx^1 + a_2 dx^2 \in \Omega^1(M), \ \beta := b_1 dx^1 + b_2 dx^2 \in \Omega^1(M), \ \omega := w_{12} dx^1 \wedge dx^2 \in \Omega^2(M)$

- $f\tilde{f} = f \wedge \tilde{f} = \tilde{f} \wedge f \in \Omega^0(M)$
- $f\alpha := f \wedge \alpha = \alpha \wedge f = fa_1 dx^1 + fa_2 dx^2 \in \Omega^1(M)$
- $\alpha \wedge \beta = -\beta \wedge \alpha = (a_1b_2 a_2b_1) dx^1 \wedge dx^2 \in \Omega^2(M)$
- $f\omega := f \wedge \omega = \omega \wedge f = fw_{12}dx^1 \wedge dx^2 \in \Omega^2(M)$

1.4 Exterior derivative d

 $f \in \Omega^{0}(M), \ \alpha := a_{1}dx^{1} + a_{2}dx^{2} \in \Omega^{1}(M)$

- $\mathbf{d}f = \partial_1 f dx^1 + \partial_2 f dx^2$
- $(\mathbf{d}f)_{\mu} = \partial_{\mu}f$ (Ricci)
- $\mathbf{d}\alpha = (\partial_1 a_2 \partial_2 a_1) dx^1 \wedge dx^2$
- $(\mathbf{d}\alpha)_{12} = (-1)^{\mu-1} \partial_{\mu} a_{\bar{\mu}} \ (\mathbf{Ricci})$

1.5 Hodge star *

 $f \in \Omega^0(M), \ \alpha := a_1 dx^1 + a_2 dx^2 \in \Omega^1(M), \ \omega := w_{12} dx^1 \wedge dx^2 \in \Omega^2(M)$

- $\bullet \ *f = f\mu = \sqrt{|g|}fdx^1 \wedge dx^2$
- $*\alpha = \sqrt{|g|} \left(-\left(a_1g^{12} + a_2g^{22}\right) dx^1 + \left(a_1g^{11} + a_2g^{12}\right) dx^2 \right)$
- $(*a)_{\mu} = (-1)^{\mu} \sqrt{|g|} g^{\nu\bar{\mu}} a_{\nu} = (-1)^{\mu} \sqrt{|g|} a^{\bar{\mu}}$ (Ricci)
- $*\omega = \frac{w_{12}}{\sqrt{|q|}}$

1.6 Rising and lowering indices # / b

 $\alpha := a_1 dx^1 + a_2 dx^2 \in \Omega^1(M), \ \vec{v} := v^1 \partial_1 + v^2 \partial_2 \in \mathcal{V}(M)$

•
$$\alpha^{\sharp} = (g^{11}a_1 + g^{12}a_2) \partial_1 + (g^{12}a_1 + g^{22}a_2) \partial_2$$

•
$$a^{\mu} = g^{\mu\nu}a_{\nu}$$
 (Ricci)

•
$$\vec{v}^{\flat} = (g_{11}v^1 + g_{12}v^2) dx^1 + (g_{12}v^1 + g_{22}v^2) dx^2$$

•
$$v_{\mu} = g_{\mu\nu}v^{\nu}$$
 (Ricci)

1.7 Contraction i

 $\alpha := a_1 dx^1 + a_2 dx^2 \in \Omega^1(M), \ \omega := w_{12} dx^1 \wedge dx^2 \in \Omega^2(M) \ \vec{v} := v^1 \partial_1 + v^2 \partial_2 \in \mathcal{V}(M)$

•
$$\mathbf{i}_{\vec{v}}\alpha = \alpha(\vec{v}) = a_1v^1 + a_2v^2$$

•
$$\mathbf{i}_{\vec{v}}\omega = w_{12} \left(-v^2 dx^1 + v^1 dx^2 \right)$$

1.8 Lie-derivative \mathcal{L}

 $f \in \Omega^{0}(M), \alpha := a_{1}dx^{1} + a_{2}dx^{2} \in \Omega^{1}(M), \omega := w_{12}dx^{1} \wedge dx^{2} \in \Omega^{2}(M), \vec{v} := v^{1}\partial_{1} + v^{2}\partial_{2} \in \mathcal{V}(M)$

•
$$\mathcal{L}_{\vec{v}}f = v^1 \partial_1 f + v^2 \partial_2 f$$

•
$$\mathcal{L}_{\vec{v}}\alpha = \sum_{i,k=1,2} \left(v^k \partial_k a_i dx^i + a_i \partial_k v^i dx^k \right)$$

•
$$\mathcal{L}_{\vec{v}}\omega = (\partial_1 (w_{12}v^1) + \partial_2 (w_{12}v^2)) dx^1 \wedge dx^2$$

•
$$\mathcal{L}_{\vec{v}}\omega = (w_{12}\partial_{\mu}v^{\mu} + v^{\mu}\partial_{\mu}w_{12}) dx^1 \wedge dx^2$$
 (Ricci)

1.9 Levi-Civita-Connection (co-/contravariant derivatives)

•
$$\Gamma^k_{ij} = g^{kl}\Gamma_{ijl} = \frac{1}{2}g^{kl}\left(\partial_i g_{jl} + \partial_j g_{il} - \partial_l g_{ij}\right)$$
 (Christoffel symbols)

$$\bullet \ \nabla_j v^i = v^i_{;j} = v^i_{|j} = \partial_j v^i + v^k \Gamma^i_{jk}$$

•
$$\nabla \vec{v} := \left[\nabla_j v^i\right]^i_{\ \ i}$$

•
$$\left[\nabla \vec{v}^{\dagger}\right]_{ij} = \left[g\left(\nabla \vec{v}\right)\right]_{ij} = \nabla_{j}v_{i} = v_{i|j} = v_{i|j} = \partial_{j}v_{i} - v_{k}\Gamma_{ij}^{k} = g_{il}\nabla_{j}v^{l}$$

•
$$\left[\nabla^{\sharp}\vec{v}^{\flat}\right]_{i}^{j} = \left[g\left(\nabla\vec{v}\right)g^{-1}\right]_{i}^{j} = \nabla^{j}v_{i} = v_{i}^{j} = v_{i}^{j} = g^{jk}g_{il}\nabla_{k}v^{l}$$

•
$$\nabla_i f = [\nabla f]_i = \partial_i f$$

•
$$\nabla_{\vec{v}} f = \mathcal{L}_{\vec{v}} f = \langle \vec{v}, \nabla_{\Gamma} f \rangle = (\mathbf{d} f)(\vec{v}) = v^i \nabla_i f = v^i \partial_i f$$

1.10 Shape-Operator S, etc

• Second fundamental form:

$$[II]_{ij} = [S^{\flat}]_{ij} = h_{ij} = -\partial_i \vec{N} \cdot \partial_j \vec{X} = -\left[\nabla \vec{N}\right]_{ij} = \vec{n} \cdot \partial_i \partial_j \vec{X}$$

• Shape operator (Weingarten map):

$$[S]_{j}^{i} = g^{ik}h_{kj} = -\left[\nabla_{\Gamma}\vec{N}\right]^{i} \cdot \partial_{j}\vec{X} = -\left[\nabla_{\Gamma}\vec{N}\right]_{j}^{i}$$

• Inverse of second fundamental form: $b^{ij} = \left[H^{-1} \right]^{ij} = \frac{1}{|a|K} \left[H^{\mathrm{Adj}} \right]^{ij}$

$$b^{ij} = \left[II^{-1} \right]^{ij} = \frac{1}{|a|K} \left[II^{\text{Adj}} \right]^{ij}$$

•
$$[S(\vec{v})]_i = -\left[\nabla_{\vec{v}}\vec{N}\right]_i = v^j h_{ij}$$

•
$$S^T \alpha = \alpha S = S(\alpha^{\sharp})$$

1.11 Conclusions

$$\vec{v} := v^1 \partial_1 + v^2 \partial_2 \in \mathcal{V}(M)$$

• Grad
$$f = \nabla_{\Gamma} f = \nabla^{\sharp} f = (\mathbf{d}f)^{\sharp}$$

[Grad f] $^{i} = \nabla^{i} f = g^{ij} \nabla_{i} f = g^{ij} \partial_{i} f$

• Div
$$\vec{v} = -\delta \vec{v}^{\flat} = *\mathbf{d} * \vec{v}^{\flat} = \nabla_i v^i = \partial_i v^i + v^k \Gamma^i_{ik} = \partial_i v^i + v^k \partial_k \log \sqrt{|g|}$$

$$= \sum_{i=1,2} \frac{1}{\sqrt{|g|}} \partial_i \sqrt{|g|} v^i = \sum_{i=1,2} \frac{v^i}{\sqrt{|g|}} \partial_i \sqrt{|g|} + \partial_i v^i$$

•
$$\delta(f\alpha) = f\delta\alpha - \langle \mathbf{d}f, \alpha \rangle$$

•
$$\operatorname{Div}(f\vec{v}) = f\operatorname{Div}\vec{v} + \nabla_{\vec{v}}f = f\nabla_i v^i + v^i\nabla_i f$$

• Laplace-Beltrami operator:

$$\Delta_B f = -\delta \mathbf{d} f = *\mathbf{d} * \mathbf{d} f = \text{DivGrad} f = \nabla_i \nabla^i f = \frac{1}{\sqrt{|g|}} \partial_j \left(g^{ij} \sqrt{|g|} \partial_i f \right)$$

• Laplace-de Rham operator:

$$\Delta_{dR}\alpha = (\delta \mathbf{d} + \mathbf{d}\delta) \alpha =: -(\Delta_B + \Delta_{CB}) \alpha$$

$$\Delta_{dR}\vec{v} = (\Delta_{dR}\vec{v}^{\flat})^{\sharp}$$

• Giaquinta-Hildebrandt operator:

$$\Delta_{GH}f = \Box f = \operatorname{Div}\left(KII^{-1}\mathbf{d}f\right) = -\delta\left(KS^{-T}\mathbf{d}f\right) = \frac{1}{\sqrt{|g|}}\partial_{j}\left(\sqrt{|g|}Kb^{ij}\partial_{i}f\right)$$

•
$$-\delta (S^T \alpha) = -H \text{Div}\alpha^{\sharp} - \text{Div} (KII^{-1}\alpha) - \nabla_{\alpha^{\sharp}}H = H\delta\alpha + \delta (KS^{-T}\alpha) - \langle \alpha, \mathbf{d}H \rangle - \delta (S^T \mathbf{d}f) = -H\Delta_B f - \Delta_{GH} f - \langle \mathbf{d}H, \mathbf{d}f \rangle$$

1.12 Moving Surfaces M(t)

 $\vec{V} := \vec{v} + v_n \vec{N} = \partial_t \vec{X}$ (surface velocity), $\vec{X} : M \to E^3$ (parametrization)

•
$$\partial_i \vec{V} \cdot \partial_j \vec{X} = g_{jk} \nabla_i v^k - v_n h_{ij} = \left[(\nabla \vec{v} - v_n S)^{\flat} \right]_{ij}$$

• (rate-of-deformation tensor
$$\boldsymbol{d}$$
)

$$rac{d}{dt}g = \left(
abla ec{v}^{\,\flat}
ight) + \left(
abla ec{v}^{\,\flat}
ight)^T - 2v_n II = \mathcal{L}_{ec{V}}g = 2\mathbf{d}$$
 $rac{d}{dt}g_{ij} = g_{ik}
abla_j v^k + g_{jk}
abla_i v^k - 2v_n h_{ij} = 2d_{ij}$

•
$$\frac{d}{dt}\alpha^{\sharp} = \left[\dot{\alpha} + \left(2v_n S^T - (\nabla \vec{v})^T - \left(\nabla^{\sharp} \vec{v}^{\flat}\right)\right)\alpha\right]^{\sharp}$$

•
$$\frac{d}{dt} * \omega = * [\dot{\omega} - (\text{Div}\vec{v} + v_n H) \omega]$$

•
$$\frac{d}{dt} * \vec{p}^{\flat} = * \left[\dot{\vec{p}} + (\text{Div}\vec{v} + v_n H) \vec{p} \right]^{\flat}$$

•
$$\frac{d}{dt} * \alpha = * \left[\dot{\alpha} + \left(2v_n S^T - (\nabla \vec{v})^T - \left(\nabla^{\sharp} \vec{v}^{\flat} \right) \right) \alpha + (\text{Div} \vec{v} + v_n H) \alpha \right]$$

•
$$\frac{1}{2} \frac{d}{dt} \|\alpha\|^2 = \langle \dot{\alpha} + v_n S^T \alpha - (\nabla \vec{v})^T \alpha, \alpha \rangle = \dot{\alpha} \alpha^{\sharp} + \alpha (v_n S - \nabla \vec{v}) \alpha^{\sharp}$$
$$= \dot{\alpha}_i \alpha^i + v_n \alpha_i h_j^i \alpha^j - \alpha_i (\nabla_j v^i) \alpha^j$$

•
$$\frac{1}{2}\frac{d}{dt}\|\omega\|^2 = \frac{1}{2}\frac{d}{dt}(*\omega)^2 = \langle \dot{\omega}, \omega \rangle - (\text{Div}\vec{v} + v_n H)\|\omega\|^2$$

•
$$\frac{1}{2}\frac{d}{dt}\|\delta\alpha\|^2 = \left\langle \delta\left[\dot{\alpha} + \left(2v_nS^T - (\nabla\vec{v})^T - \left(\nabla^{\sharp}\vec{v}^{\flat}\right)\right)\alpha + (\text{Div}\vec{v} + v_nH)\alpha\right], \delta\alpha\right\rangle - (\text{Div}\vec{v} + v_nH)\|\delta\alpha\|^2$$

•
$$\frac{1}{2} \frac{d}{dt} \left\| \delta \vec{p}^{\flat} \right\|^2 = \left\langle \delta \left[\dot{\vec{p}} + (\text{Div}\vec{v} + v_n H) \vec{p} \right]^{\flat}, \delta \vec{p}^{\flat} \right\rangle - (\text{Div}\vec{v} + v_n H) \left\| \delta \vec{p}^{\flat} \right\|^2$$

•
$$\frac{d}{dt} \int_{M(t)} f\mu = \int_{M(t)} \dot{f} + f(\operatorname{Div} \vec{v} + v_n H) \mu$$

•
$$\frac{d}{dt} \int_{M(t)} \frac{1}{2} \|\alpha\|^2 \mu = \int_{M(t)} \langle \dot{\alpha}, \alpha \rangle + v_n \left\langle S^T \alpha + \frac{1}{2} H \alpha, \alpha \right\rangle + \left\langle \frac{1}{2} \left(\text{Div} \vec{v} \right) \alpha - (\nabla \vec{v})^T \alpha, \alpha \right\rangle \mu$$

•
$$\frac{d}{dt} \int_{M(t)} \frac{1}{2} \|\omega\|^2 \mu = \int_{M(t)} \langle \dot{\omega}, \omega \rangle - \frac{1}{2} \left(\text{Div} \vec{v} + v_n H \right) \|\omega\|^2 \mu$$

$$\bullet \quad \frac{d}{dt} \int_{M(t)} \frac{1}{2} \left\| \mathbf{d}\vec{p}^{\flat} \right\|^{2} \mu = \int_{M(t)} \left\langle \frac{d}{dt} \vec{p}^{\flat}, \delta \mathbf{d}\vec{p}^{\flat} \right\rangle - \frac{1}{2} \left(\mathrm{Div}\vec{v} + v_{n} H \right) \left\| \mathbf{d}\vec{p}^{\flat} \right\|^{2} \mu$$

$$= \int_{M(t)} \dot{\vec{p}} \delta \mathbf{d}\vec{p}^{\flat} + \vec{p} \left((\nabla \vec{v})^{T} + \left(\nabla^{\sharp} \vec{v}^{\flat} \right) - 2v_{n} S^{T} \right) \delta \mathbf{d}\vec{p}^{\flat}$$

$$- \frac{1}{2} \left(\mathrm{Div}\vec{v} + v_{n} H \right) \left\| \mathbf{d}\vec{p}^{\flat} \right\|^{2} \mu$$

$$\bullet \frac{d}{dt} \int_{M(t)} \frac{1}{2} \left\| \delta \vec{p}^{\flat} \right\|^{2} \mu = \int_{M(t)} \left\langle \frac{d}{dt} \vec{p}^{\flat}, \mathbf{d} \delta \vec{p}^{\flat} \right\rangle + \left\langle \left(2v_{n} S^{T} - (\nabla \vec{v})^{T} - \left(\nabla^{\sharp} \vec{v}^{\flat} \right) \right) \vec{p}^{\flat}, \mathbf{d} \delta \vec{p}^{\flat} \right\rangle + \left\langle \left(\mathrm{Div} \vec{v} + v_{n} H \right) \vec{p}^{\flat}, \mathbf{d} \delta \vec{p}^{\flat} \right\rangle - \frac{1}{2} \left(\mathrm{Div} \vec{v} + v_{n} H \right) \left\| \delta \vec{p}^{\flat} \right\|^{2} \mu$$

$$= \int_{M(t)} \dot{\vec{p}} \mathbf{d} \delta \vec{p}^{\flat} + \left(\mathrm{Div} \vec{v} + v_{n} H \right) \vec{p} \mathbf{d} \delta \vec{p}^{\flat} - \frac{1}{2} \left(\mathrm{Div} \vec{v} + v_{n} H \right) \left\| \delta \vec{p}^{\flat} \right\|^{2} \mu$$

•
$$\frac{d}{dt} \int_{M(t)} \frac{1}{2} \left(\left\| \mathbf{d} \vec{p}^{\flat} \right\|^{2} + \left\| \delta \vec{p}^{\flat} \right\|^{2} \right) \mu = \frac{d}{dt} \int_{M(t)} \frac{1}{2} \left(\left\| \operatorname{Rot} \vec{p} \right\|^{2} + \left\| \operatorname{Div} \vec{p} \right\|^{2} \right) \mu$$

$$= \int_{M(t)} \left\langle \frac{d}{dt} \vec{p}^{\flat}, \Delta_{dR} \vec{p}^{\flat} \right\rangle - \frac{\operatorname{Div} \vec{v} + v_{n} H}{2} \left(\left\| \mathbf{d} \vec{p}^{\flat} \right\|^{2} + \left\| \delta \vec{p}^{\flat} \right\|^{2} \right)$$

$$+ \left\langle \left(\operatorname{Div} \vec{v} + v_{n} H \right) \vec{p}^{\flat}, \mathbf{d} \delta \vec{p}^{\flat} \right\rangle$$

$$- \left\langle \left(\left(\nabla \vec{v} \right)^{T} + \left(\nabla^{\sharp} \vec{v}^{\flat} \right) - 2 v_{n} S^{T} \right) \vec{p}^{\flat}, \mathbf{d} \delta \vec{p}^{\flat} \right\rangle \mu$$

$$= \int_{M(t)} \left\langle \dot{\vec{p}}, \Delta_{dR} \vec{p} \right\rangle - \frac{\operatorname{Div} \vec{v} + v_{n} H}{2} \left(\left\| \operatorname{Rot} \vec{p} \right\|^{2} + \left\| \operatorname{Div} \vec{p} \right\|^{2} \right)$$

$$+ \left(\operatorname{Div} \vec{v} + v_{n} H \right) \vec{p} \mathbf{d} \delta \vec{p}^{\flat}$$

$$+ \vec{p} \left(\left(\nabla \vec{v} \right)^{T} + \left(\nabla^{\sharp} \vec{v}^{\flat} \right) - 2 v_{n} S^{T} \right) \delta \mathbf{d} \vec{p}^{\flat} \mu$$

•
$$\int_{M(t)} \left\langle (\operatorname{Div}\vec{v} + v_n H) \vec{p}^{\flat}, \mathbf{d}\delta \vec{p}^{\flat} \right\rangle - \frac{1}{2} \left(\operatorname{Div}\vec{v} + v_n H \right) \left\| \delta \vec{p}^{\flat} \right\|^2 \mu$$

$$= \int_{M(t)} \mathcal{L}_{\vec{p}} \left\langle \vec{p}^{\flat}, \mathbf{d}\delta \vec{v}^{\flat} + \mathbf{d} \left(v_v H \right) \right\rangle + \frac{1}{2} \left(\operatorname{Div}\vec{v} + v_n H \right) \left\| \delta \vec{p}^{\flat} \right\|^2 \mu$$

2 Tensors

2.1 Flat / Sharp

- $t := t^i{}_j \partial_i \otimes dx^j$
- ${}^{\flat}t = gt = g_{ik}t^k{}_j dx^i \otimes dx^j = t_{ij}dx^i \otimes dx^j$
- $t^{\sharp} = tg^{-1} = t^i{}_k g^{kj} \partial_i \otimes \partial_j = t^{ij} \partial_i \otimes \partial_j$
- ${}^{\flat}t^{\sharp} = gtg^{-1} = g_{ik}t^{k}{}_{l}g^{lj}dx^{i} \otimes \partial_{j} = t_{i}{}^{j}dx^{i} \otimes \partial_{j}$

2.1.1 Conclusions

 $\alpha = \vec{v}^{\flat} = {}^{\flat}\vec{v}, \ \vec{w} = \beta^{\sharp} = {}^{\sharp}\beta, \ s = \vec{v} \otimes \beta$:

- t symmetric $(t_{12} = t_{21} \text{ resp. } t^{12} = t^{21})$: ${}^{\flat}t^{\sharp} = t^T$
- $\alpha t \vec{w} = \vec{v}^{\dagger} t \vec{w} = \alpha t^{\sharp} \beta = \vec{v}^{\dagger} t^{\sharp} \beta$ (Associativity referring to arguments)
- $\Rightarrow t(\alpha, \vec{w}) = {}^{\flat}t(\vec{v}, \vec{w}) = t^{\sharp}(\alpha, \beta) = {}^{\flat}t^{\sharp}(\vec{v}, \beta)$
- $s = \vec{v} \otimes \beta$: ${}^{\flat}s = \alpha \otimes \beta$, $s^{\sharp} = \vec{v} \otimes \vec{w}$, ${}^{\flat}s^{\sharp} = \alpha \otimes \vec{w}$ (Associativity referring to factors, tensor product is metric compatible)
- $t^T := (({}^{\flat}t)^T)^{\sharp} = {}^{\flat}((t^{\sharp})^T) = t_i{}^i dx^j \otimes \partial_i$

2.2 Covariant Derivative $\nabla_{\bullet} = g_{\bullet i} \nabla^{\bullet}$

- $\nabla_k f = \partial_k f$
- $\bullet \ \nabla_k v^i = \partial_k v^i + \Gamma_{kl}{}^i v^l$
- $\bullet \ \nabla_k v_i = \partial_k v_i \Gamma_{ki}{}^l v_l$
- $\bullet \ \nabla_k t^i{}_j = \partial_k t^i{}_j + \Gamma_{kl}{}^i t^l{}_j \Gamma_{kj}{}^l t^i{}_l$
- $\nabla_k t_i{}^j = \partial_k t_i{}^j \Gamma_{ki}{}^l t_l{}^j + \Gamma_{kl}{}^j t_i{}^l$
- $\nabla_k t^{ij} = \partial_k t^{ij} + \Gamma_{kl}{}^i t^{lj} + \Gamma_{kl}{}^j t^{il}$
- $\nabla_k t_{ij} = \partial_k t_{ij} \Gamma_{ki}{}^l t_{lj} \Gamma_{kj}{}^l t_{il}$
- $\operatorname{Div}(v) = \nabla_i v^i = \nabla^i v_i = \operatorname{Tr}(\nabla \vec{v}) = \operatorname{Tr}({}^{\flat}\nabla^{\sharp}\alpha)$
- $\operatorname{Rot}(v) = (\sqrt{|g|})^{-1} \epsilon^{ki} \nabla_k v_i = (\sqrt{|g|})^{-1} \operatorname{Tr}((\nabla \alpha) \epsilon^{\sharp})$
- $\operatorname{Div}(t) = \nabla^j t^i{}_j \partial_i = \nabla_j t_i{}^j dx^i = \nabla_j t^{ij} \partial_i = \nabla^j t_{ij} dx^i$

2.3 Rotation $R = R^{-T}: T_pM \rightarrow (T_pM)'$

•
$$R = R_{\varphi} = \begin{bmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{bmatrix} = R^{i}{}_{j}\partial_{i} \otimes dx^{j}$$

2.3.1 Pull-back $R^* = R_*^T$

Hint: Use rotated metric $g' = R_*g = RgR^T$ in rotated coords. system!

•
$$R^*v' = R^{-1}v' = R^Tv' = v \in T_pM \longrightarrow [R^*v']^i = [R^T]^i_{\ j}v'^j$$

•
$$R^*\alpha' = \alpha'(R\bullet) = \alpha'R = \alpha \in T_p^*M \quad \leadsto [R^*\alpha']_i = R^j{}_iv_i'$$

•
$$R^{* \bullet} t'^{\bullet} = R^{T \bullet} t'^{\bullet} R = {}^{\bullet} t^{\bullet}$$
 (Rotation is metric compatible)

•
$$R^*(\bullet \otimes \bullet) = (R^* \bullet) \otimes (R^* \bullet)$$

2.3.2 Push-forward $R_* = R^{*T}$

•
$$R_*v = Rv = v'$$

•
$$R_*\alpha = \alpha R^T = \alpha'$$

•
$$R^* \cdot t^{\bullet} = R \cdot t^{\bullet} R^T = t'^{\bullet}$$

•
$$R_*(\bullet \otimes \bullet) = (R_*\bullet) \otimes (R_*\bullet)$$