

Phys 512 Problem Set 1

Due on github Friday Sep 16 at 11:59 PM. You may discuss problems, but everyone must write their own code.

Problem 1: We saw in class how Taylor series/roundoff errors fight against each other when deciding how big a step size to use when calculating numerical derivatives. If we allow ourselves to evaluate our function f at four points ($x \pm \delta$ and $x \pm 2\delta$),

a) what should our estimate of the first derivative at x be? Rather than doing a complicated fit, I suggest thinking about how to combine the derivative from $x \pm \delta$ with the derivative from $x \pm 2\delta$ to cancel the next term in the Taylor series.

b) Now that you have your operator for the derivative, what should δ be in terms of the machine precision and various properties of the function? Show for $f(x) = \exp(x)$ and $f(x) = \exp(0.01x)$ that your estimate of the optimal δ is at least roughly correct.

Problem 2: Write a numerical differentiator with prototype

```
def ndiff(fun,x,full=False):
```

where `fun` is a function and `x` is a value. If `full` is set to `False`, `ndiff` should return the numerical derivative at `x`. If `full` is `True`, it should return the derivative, `dx`, and an estimate of the error on the derivative. I suggest you use the centered derivative

$$f' \simeq \frac{f(x+dx) - f(x-dx)}{2dx}$$

Your routine should estimate the optimal `dx` then use that in calculating the derivative. If you're feeling ambitious, write your code so that `x` can be an array, not just a single number. If you do that, you may actually wish to save your code as you might use it in the future.

Problem 3: Lakeshore 670 diodes (successors to the venerable Lakeshore 470) are temperature-sensitive diodes used for a range of cryogenic temperature measurements. They are fed with a constant $10 \mu\text{A}$ current, and the voltage is read out. Lakeshore provides a chart that converts voltage to temperature, available at <https://www.lakeshore.com/products/categories/specification/temperature-products/cryogenic-temperature-sensors/dt-670-silicon-diodes>, or you can look at the text file I've helpfully copied and pasted (`lakeshore.txt`). Write a routine that will take an arbitrary voltage and interpolate to return a temperature. You should also make some sort of quantitative (but possibly rough) estimate of the error in your interpolation as well (this is a common situation where you have been presented with data and have to figure out *some* idea of how to get error estimates).

Your prototype should be:

```
def lakeshore(V,data):
```

where data is the output of:

```
dat=np.loadtxt('lakeshore.txt')
```

The columns of lakeshore.txt are 1) the temperature, 2) the voltage across the diode at that temperature (which is what your experiment will actually measure), and 3) dV/dT . You do not need to use the third column, but you may if you wish.

Your code should support V being either a number or array, and it should return the interpolated temperature, and your estimated uncertainty on the temperature.

Problem 4: Take $\cos(x)$ between $-\pi/2$ and $\pi/2$. Compare the accuracy of polynomial, cubic spline, and rational function interpolation given some modest number of points, but for fairness each method should use the same points. Now try using a Lorentzian $1/(1+x^2)$ between -1 and 1.

What should the error be for the Lorentzian from the rational function fit? Does what you got agree with your expectations when the order is higher (say $n=4$, $m=5$)? What happens if you switch from `np.linalg.inv` to `np.linalg.pinv` (which tries to deal with singular matrices)? Can you understand what has happened by looking at p and q ? As a hint, think about why we had to fix the constant term in the denominator, and how that might generalize.