

Review for the Final Examination

Ch 3. Integration

Ch 4. MCMC Methods

Ch 5. Bootstrap Methods



1). Arrangement of 2021 Final Examination

- Date and Time**

06 Jan 2022 (Thursday),
08:00am – 10:00am (2 hours)

- Venue**

Room 101, Building 1, Lychee Hills

- Range**

Chapters 1,2,3,4,5 (Except for Sections
3.1, 3.4, 5.2)

- Assessment**

50% weighting

2). The Policy of Closed Book Final Examination

- Please bring **two** pens in case one is not available.
- You can prepare anything on **one** side of an A4 paper and bring it with you to the test venue.
- You are not allowed to bring any other material (including **iPhone/iPad**) to the test venue. **The calculator is not required this time.**

3). The Distribution and Marks of the Questions in the Examination

- Fill-in-the-blanks. [30-marks]
- 1 question on the inversion method in Chapter 1 with 2 sub-questions (one is discrete distribution and the other is continuous distribution). [10-marks]
- 1 question on the mixture representation method for generating a continuous random variable. [10-marks]

- 1 question on the Newton–Raphson, Fisher scoring in Chapter 2. [15-marks]
- 1 question on SR, EM, DA, MM algorithms in Ch 4. [35-marks]

Ch 3. Integration

- §3.2 Riemannian Simulation
- §3.3 The Importance Sampling Method



§3.2 Riemannian Simulation

1. Classical Monte Carlo integration

- The Monte Carlo integration of

$$\mu = E\{h(X)\} = \int_{\mathbb{X}} h(x) \cdot f(x) dx, \quad (3.8)$$

is

$$\bar{\mu}_m = \frac{1}{m} \sum_{i=1}^m h(X^{(i)}). \quad (3.9)$$

where $X^{(1)}, \dots, X^{(m)}$ $\stackrel{\text{iid}}{\sim} f(x)$.

2. The Rieman sum

Let $\mathbb{X} = [a, b]$ and $a = a_1 < \dots < a_{m+1} = b$,
then when $m \rightarrow \infty$, the Rieman sum

$$\sum_{i=1}^m h(a_i) f(a_i)(a_{i+1} - a_i) \rightarrow \int_a^b h(x) \cdot f(x) dx.$$

3. The Riemannian sum estimator

Replacing the fixed points $\{a_i\}_{i=1}^{m+1}$ by stochastic points $\{X_{(i)}\}_{i=1}^{m+1}$, the ordered statistics of i.i.d. samples $X^{(1)}, \dots, X^{(m+1)}$ from $f(x)$, the approach of Riemannian simulation approximates the integral (3.8) by

$$\hat{\mu}^R = \sum_{i=1}^m h(X_{(i)})f(X_{(i)})\{X_{(i+1)} - X_{(i)}\}. \quad (3.14)$$

We call $\hat{\mu}^R$ the Riemannian sum estimator of μ .

§3.3 The Importance Sampling Method

Step 1. Generate i.i.d. samples $\{X^{(i)}\}_{i=1}^m$ from a proposal density $g(\cdot)$ with the same support of $f(\cdot)$;

Step 2. Let $H(x) = h(x)f(x)$. Calculate ratios $\mathbf{w}(X^{(i)}) = H(X^{(i)})/g(X^{(i)})$ for $1 \leq i \leq m$ & approximate $\mu = \int_{\mathbb{X}} H(x) dx = \int_{\mathbb{X}} \mathbf{w}(x)g(x) dx$ by

$$\tilde{\mu}_m = (1/m) \sum_{i=1}^m \mathbf{w}(X^{(i)}), \quad (3.15)$$

Which is called the importance sampling estimator.

Ch 4. MCMC Methods

- §4.1 Bayes Formula and IBF
- §4.2 The Bayesian Methodology
- §4.3 The DA Algorithm
- §4.4 The Gibbs Sampler
- §4.5 The Exact IBF Sampler
- §4.6 The IBF Sampler

§4.1 Three Points to Bayes Formula and IBF

- 1. The core of Bayes Formula:

$$f_{(X|Y)}(x|y)f_Y(y) = f_{(Y|X)}(y|x)f_X(x), \quad (4.1)$$

where $(x, y) \in \mathcal{S}_{(X,Y)}$.

- 2. Given two conditional densities, how to derive three IBF under the assumption of the **product space** (please review (4.3) – (4.6) on pages 154–155, and Ex 4.1 – Ex 4.3).
- 3. Given three **full** conditional densities, how to determine the joint density $f(x_1, x_2, x_3)$ (please review §4.1.3).

§4.2 The Bayesian Methodology

- Posterior \propto Likelihood \times Prior:

$$p(\boldsymbol{\theta}|Y_{\text{com}}) = \frac{f(Y_{\text{com}}|\boldsymbol{\theta})\pi(\boldsymbol{\theta})}{f(Y_{\text{con}})} \propto f(Y_{\text{com}}|\boldsymbol{\theta})\pi(\boldsymbol{\theta}), \quad (4.14)$$

- What is the conjugate prior distribution? (See page 166)
- Please review Exs 4.4, 4.5, and 4.6.

§4.3 The DA Algorithm

- 1. The original DA algorithm:
Please review I-step and P-step in page 179.
- 2. The modern DA algorithm:
 - I-step: Draw $z^{(t)} \sim f(z|Y_{\text{obs}}, \boldsymbol{\theta}^{(t)})$
 - P-step: Draw $\boldsymbol{\theta}^{(t+1)} \sim p(\boldsymbol{\theta}|Y_{\text{obs}}, z^{(t)})$
- 3. The connection with the IBF:
Please review §4.3.4, and Example 4.8.

§4.4 The Gibbs Sampler

- 1. The general sampling procedure:

- Draw $x_1^{(t+1)} \sim f(x_1|x_2^{(t)}, \dots, x_d^{(t)})$;
- Draw $x_2^{(t+1)} \sim f(x_2|x_1^{(t+1)}, x_3^{(t)}, \dots, x_d^{(t)})$;
- \dots \dots \dots
- Draw $x_d^{(t+1)} \sim f(x_d|x_1^{(t+1)}, \dots, x_{d-1}^{(t+1)})$.

- 2. The two-block Gibbs sampling:

- Draw $x_1^{(t+1)} \sim f(x_1|x_2^{(t)})$;
- Draw $x_2^{(t+1)} \sim f(x_2|x_1^{(t+1)})$.

Please review Exs 4.9 and 4.10.

§4.5 The Exact IBF Sampling

- 1. Basic assumptions for the exact IBF sampling:
 $p(\theta|Y_{\text{obs}}, z)$ and $f(z|Y_{\text{obs}}, \theta)$ are given, and Z is a discrete r.v.
- 2. The algorithm:

Step 1. Identify $\mathcal{S}_{(Z|Y_{\text{obs}})} = \{z_1, \dots, z_K\}$ from $f(z|Y_{\text{obs}}, \theta)$ and calculate $\{p_k\}_1^K$ according to (4.32) and (4.31);

§4.5 The Exact IBF Sampling (Cont's)

- Step 2. Generate i.i.d. samples $\{z^{(\ell)}\}_{\ell=1}^L$ of Z from the pmf $f(z|Y_{\text{obs}})$ with probabilities $\{p_k\}_1^K$ on $\{z_k\}_1^K$;
- Step 3. Generate $\boldsymbol{\theta}^{(\ell)} \sim p(\boldsymbol{\theta}|Y_{\text{obs}}, z^{(\ell)})$ for $\ell = 1, \dots, L$, then $\{\boldsymbol{\theta}^{(\ell)}\}_1^L$ are i.i.d. samples from the observed posterior distribution $p(\boldsymbol{\theta}|Y_{\text{obs}})$.

§4.6 The IBF Sampler

- 1. Basic assumptions for the IBF sampler:

The posterior mode $\tilde{\theta}$ can be obtained by an EM algorithm based on $p(\theta|Y_{\text{obs}}, z)$ and $f(z|Y_{\text{obs}}, \theta)$, and set $\theta_0 = \tilde{\theta}$;

- 2. The algorithm:

Step 1. Draw J i.i.d. samples $\{z^{(j)}\}_{j=1}^J$ of Z from $f(z|Y_{\text{obs}}, \theta_0)$;

Step 2. Calculate the reciprocals of the augmented posterior densities to obtain the weights

$$\omega_j = \frac{p^{-1}(\boldsymbol{\theta}_0 | Y_{\text{obs}}, z^{(j)})}{\sum_{\ell=1}^J p^{-1}(\boldsymbol{\theta}_0 | Y_{\text{obs}}, z^{(\ell)})}, \quad (4.35)$$

for $j = 1, \dots, J$;

Step 3. Choose a subset from $\{z^{(j)}\}_1^J$ via resampling **without replacement** from the discrete distribution on $\{z^{(j)}\}$ with probabilities $\{\omega_j\}$ to obtain an i.i.d. sample of size $I (< J)$ approximately from $f(z|Y_{\text{obs}})$, denoted by $\{z^{(k_i)}\}_1^I$;

Step 4. Generate $\boldsymbol{\theta}^{(i)} \sim p(\boldsymbol{\theta}|Y_{\text{obs}}, z^{(k_i)})$ for $i = 1, \dots, I$, then $\{\boldsymbol{\theta}^{(i)}\}_1^I$ are i.i.d. samples from $p(\boldsymbol{\theta}|Y_{\text{obs}})$.

Ch.5 Bootstrap Methods

- §5.1.1 Parametric Bootstrap
- §5.1.2 Non-parametric Bootstrap



§5.1.1 Parametric Bootstrap

- **1. Several important notions:**

Bootstrap sample; Bootstrap replication; Normality-based Bootstrap CI; Non-normality-based Bootstrap CI.

- **2. The Bootstrap Approach for Constructing CIs:** Please review the six steps in pages 205–206 and Table 5.1
- **3. Applications.** (Please review Examples 5.1 and 5.3)

§5.1.2 Non-parametric Bootstrap

- 1. **The empirical distribution function:** Based on the iid observations $x_1, \dots, x_n \stackrel{\text{iid}}{\sim} F$, the empirical cdf is

$$\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n I(x_i \leq x)$$

where $x_1 \leq x_2 \leq \dots \leq x_n$.

- 2. **The Bootstrap Approach for Constructing CIs:** Please review the six steps in pages 214–215 and Table 5.2
- 3. **Applications.** (Please review Examples 5.4 and 5.5)

Please email me or come to my office

During January 3–5, 2022, if you have any questions.

End of the Review

