

# Efficiently Identify the failure-inducing schemas

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**Abstract**—It is common that the software under test(SUT) fails during testing under some specific test configurations(we called failing configurations) and passes under the others. For these failing configurations,in the most general case,not all the options in this configuration is related to the failures. It is desirable to identify the specific options responsible for the failures,i.e., failure-inducing schemas,as by doing this it can reduce the debugging effort.

Combinatorial testing(CT) can effectively detect the errors in SUT which are triggered by interactions of options.However, it provide weak support for identifying them.In this paper, we propose an efficient approach which can aids the CT to locate them.Through using the notions of CMINFS(represent for candidate minimal faulty schemas) and CMAXHS(represent for candidate maximal healthy schemas), our approach can get an efficient performance when identifying the failure-inducing schemas compared to our prior work.Also we make an improvement on the approach to better handle the case where additional failure-inducing schemas may be introduced by newly generated test configurations.

Moreover, we conduct empirical studies on both widely-used real highly-configurable software systems and simulated toy softwares.The results shows that the failure-inducing schemas do exist in software and our approach can identify them more effectively and efficiently than other works.

**Index Terms**—failure-inducing schemas, fault location, debugging aids, combinatorial testing

## 1 INTRODUCTION

MANY modern softwares are highly configurable and customizable, while this can increase the reusability of common code base and basic components, make the software easier to be extended, enable the software to run across different environments, however, it also make the testing task to be more challenging. This is because we need to test the software under every possible configurations(we called configuration space) to ensure the correctness of it, which is not feasible in practice. Combinatorial testing technique can handle this problem well. It design a relatively small test suite from the configuration spaces to test the SUT and can ensure to cover all the interactions of option values which not exceed  $t$ . When we find some configurations fail in this test suite, which means this suite detect some interaction fault, what we want to know next is to identify which specific interaction options and its values are the cause of these failures. To our best know, combinatorial testing provide weak support to identify them.

As an example,consider the database MYSQL and some of its configuration options list in Table 1. Assume we generate a test suite consists of available configurations using combinatorial testing technique, and find some test configurations failed, say, (). Then which specific is the cause, is it *extra-charsets=NULL*

TABLE 1  
MySQL configuration options example

Compile Time Options	
Binary Options(Enabled/NULL)	
assembler, local-infile, thread-safe-client, archive-storage-engine, big-tables, blackhole-storage-engine,client-dflags, csv-storage-engine, example-storage-engine, fast-mutexex, federated-storage-engine, libedit, mysqld-ldflags, ndbcluster, pic, readline, config-ssl, zlib-dir	
Non-binary Options	values
extra-charsets	-with-extra-charsets=all, -with-extra-charsets=complex, NULL
innodb	-with-innodb, -without-innodb, NULL
Runtime options	values
transaction-isolation	READ-UNCOMMITTED, READ-COMMITTED, REPEATABLE-READ, SERIALIZABLE, NULL
innodb-flush-log	0, 1, 2, NULL
sql-mode	ANSI, TRADITIONAL, STRICT_ALL_TABLES

and *assembler = Enabled* , or *extra-charsets = NULL* and *assembler=Enabled* and *innodb-flush-log = 2* or other possible interactions . Generally, for a failed test configurations consists of  $n$  options have  $2^n - 1$  possibilities. To identify them is important, for they can help reduce the scope of source code need to be inspected.

We call the faulty interactions of option values the failure-inducing schemas, in effect, this notion is not limited in configurable software testing. The input testing may want to find the failure causing input

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interaction. The GUT testing may want to find the events interaction which makes the software down. The regression testing may want to find which change trigger the new failure. The html testing may want to isolate the minimal faulty related html source code. The Compatibility testing may want to test which some software run simultaneously will crash the system.

How to identify them is not easy, in effect, there are two problems need to be solved: First, we just need to know the properties of the faulty schemas and healthy schemas, i.e., the differences between them. Figuring out that can help us to design approaches to identify a schema to be healthy or faulty. Second, we should find some strategy to check every possible schemas in a test configuration while using as small resources as possible. As the possible schemas in a test configurations can get to  $2^n$  ( $n$  is the number of options in a configuration), then we want the resources needed is logarithmic related to the number of schemas, which will result in the complexity of algorithm with  $O(n)$  ( $n$  is the number of options in a configuration).

In this paper, we first give the properties of faulty schemas and healthy schemas. Furthermore, we propose the notion CMINFS (represent for candidate minimal faulty schemas) and CMAXHS (represent for candidate maximal healthy schemas). Through using them we can easily check whether some schemas are healthy or faulty according existed checked schemas. For these schemas can not be checked by existed checked schemas, we generate an newly configuration to test, (do we need to describe it ?????) and the state pass or fail indicate that whether the schema is healthy or faulty. Note that if newly faulty schemas introduced from the extra test configurations, then the identify result is influenced. We take it into account and solve it by introduce the feedback machinery into our approach.

We studied existed works which also target this problem. To propose a clear view of the characteristics of existed works and our work, we summary a list of metrics include constraints, limitations, complexities and so on. Through an comprehensive analysis, we have list the results in our paper. Besides these theoretical metrics, we also conduct empirical studies of these approaches. These experiment objects consists of a group of simulated toy softwares, the Small-Scale and Medium-scale Siemens Software Sets and two large highly-configurable softwares: Apache and MySQL. Our results shows that the failure-inducing schemas do existed in software, and our approach can get the best performance when identify them compared with existed works.

**contributions of this paper:** 1) we study the failure-inducing schema to analysis its properties. 2) we propose a new approach which can identify the failure-inducing schemas effectively. 3) we classified existed works, and give an comprehensive comparison both

on theoretical and empirical metrics. 4) give an general identify framework when facing real failure-inducing problems, and give advices on when an which circumstances to choose which algorithm.

The remainder of this paper is organized as follows: Section 2 introduce some preliminary definitions and propositions. Section 3 describe our approaches for identify failure-inducing schemas. Section 4 give the comparisons in theoretical metrics. Section 5 describe the experiments design. Section 6 list the result of the experiments. Section 7 summarize the related works. Section 8 conclude this paper and discuss the future works.

## 2 PRELIMINARY

Before we talk about our approach, we will give some formal definitions and proposals first, which is helpful to understand the background of our description of our approach.

### 2.1 definitions

Assume that the SUT (software under test) is influenced by  $n$  parameters, and each parameter  $c_i$  has  $a_i$  discrete values from the finite set  $V_i$ , i.e.,  $a_i = |V_i|$  ( $i = 1, 2, \dots, n$ ). Some of the definitions and propositions below are originally defined in and .

**Definition 1** (test configuration). *A test configuration of the SUT is an array of  $n$  values, one for each parameter of the SUT, which is denoted as a  $n$ -tuple  $(v_1, v_2, \dots, v_n)$ , where  $v_1 \in V_1, v_2 \in V_2, \dots, v_n \in V_n$ .*

**Definition 2** (test oracle). *the test oracle is that whether it is a test configuration pass or fail. For a clear discuss, we didn't take the multiple output state into account, but we believe our method can easily extend to the multiple oracles.*

*However, our discuss is based on the SUT is a deterministic software, i.e., will not pass this time and fail that time. We can run our approach multiple times to eliminate this problem, which, however is beyond the scope of this paper.*

**Definition 3** (schema). *For the SUT, the  $n$ -tuple  $(v_{n_1}, \dots, v_{n_k}, \dots)$  is called a  $k$ -value schema ( $k \geq 0$ ) when some  $k$  parameters have fixed values and the others can take on their respective allowable values, represented as "-". In effect a test configuration its self is a  $k$ -value schema, which  $k$  is equal to  $n$ . Furthermore, if a test configuration contain a schema, i.e., every fixed value in this schema is also in this test configuration, we say this configuration hit this schema.*

**Definition 4** (subsume relationship). *let  $s_l$  be a  $l$ -value schema,  $s_m$  be an  $m$ -value schema for the SUT and  $l \leq m$ . If all the fixed parameter values in  $s_l$  are also in  $s_m$ , then  $s_m$  subsumes  $s_l$ . In this case we can also say that  $s_l$  is a subschema of  $s_m$  and  $s_m$  is a parent-schema of  $s_l$ . Additionally, if  $m = l + 1$ , then the relationship between  $s_l$  and  $s_m$  is direct.*

**Definition 5** (healthy,faulty and pending). A  $k$ -value schema is called a faulty schema if all the valid test configuration hit the schema trigger a failure. And a  $k$ -value schema is called a healthy schema when we find at least one passed valid test configuration that hits this schema. In addition, if we don't have enough information of a schema,i.e., we don't sure whether it is a healthy schema or faulty schema, we call it the pending schema.

Note that, in real software context, there existed the case that a test configuration hit a faulty schema but passed. We call this case the coincidental correctness, which may be caused by other factors which influence the execution result. We will not discuss this case in this paper.

**Definition 6** (minimal faulty schema). If a schema is a faulty schema and all its subschemas are healthy schemas, we then call the schema a minimal faulty schema(MINFS for short).

Note that this is the target to identify,for that this will give us the most precise while enough information to help the developers to inspect the scope of the source code.

**Definition 7** (maximum healthy schema). If a schema is a healthy schema and all its parent-schemas are faulty schemas, we then call the schema a maximum healthy schema(MAXHS for short).

**Definition 8** (candidate minimal faulty schema). If a schema is a faulty schema and satisfy the followed condition: 1.none of its subschemas are faulty schemas, 2. at least one subschema is pending schema.(is need discuss!!!! one or none is okay?)We then call the schema a candidate minimal faulty schema(CMINFS for short).

**Definition 9** (candidate maximum healthy schema). If a schema is a healthy schema and and satisfy the followed condition: 1.none of its parent-schemas are healthy schemas, 2. at least one subschema is pending schema. We then call the schema a candidate maximum healthy schema(CMAXHS for short).

## 2.2 propositions

**Propositions 1.** All the schemas in a passed test configuration are healthy schemas. All the subschemas of a healthy schemas are healthy schemas.

**Propositions 2.** If schema  $s_a$  subsumes schema  $s_b$ , schema  $s_b$  subsumes schema  $s_c$ , then  $s_a$  subsumes  $s_c$ .

**Propositions 3.** All the parent-schemas of a faulty schema are faulty schemas.

**Propositions 4.** All the subschemas of a healthy schema are healthy schemas.

## 3 THE APPROACH TO IDENTIFY THE MINIMAL FAILURE-INDUCING SCHEMAS

Based on these definitions and proportions, we will describe our approach to identify the failure-inducing schemas in the SUT. To give a better description, we

will start give an approach with an assumption , and later we will weak the assumption.

### 3.1 additional failure-inducing not be introduced

**Assumption 1.** Any newly generated test configuration will not introduce additional failure-inducing schemas.

There are similar assumptions defined in[[1]], however, it is a strong assumption, which we will change later. And still for this assumption, we can get the followed lemma which can help us to identify whether a pending schema is a healthy schema or a faulty schema.

**Lemma 1.** For a pending schema, we generate an extra test configuration that contains this schema. If the extra test configuration passes, then this schema is a healthy schema. If the extra test configuration fails, then the schema is a faulty schema.

*Proof:* According to definition of healthy schema, it is obvious that this schema is a healthy schema when the extra test configuration passes.

When the extra configuration fails, this is a faulty schema (or there exists no faulty schema and this test configuration would not fail because the assumption says that this newly generated configuration will not introduce additional faulty schemas).  $\square$

### 3.2 framework to identify the minimal faulty schema

As we can identify a pending schema to be healthy schema or faulty schema by generating newly test configurations, then the approach to identify the minimal faulty schema is clear. Fig.1 shows an overview of our approach. We next discuss each part of the approach in more detail.

#### 3.2.1 Choosing a pending schema

Before we think getting a pending schema, we should assume an general scenario. That is, we have already make sure some schemas to be healthy schemas and some schemas to be faulty schemas, then assume that we still don't meet the stopping criteria, we will choose a pending to check next. But first, we should make sure what schema is pending schema?

In effect, the schemas we can't make sure whether are faulty schemas nor healthy schemas are our wanted. Step further, we sperate this condition into two parts: 1. can't make sure it is faulty schema. As we already know some faulty schemas, then we just make the schema that first not be any one of these faulty schemas and not be the parent-schema of any one of these faulty schemas(As if not, it must be a faulty schema according to the proposition 3). 2 can't make sure it is healthy schema. Similar to the first condition,we already know some healthy schemas, then we just make the schema that first not be any one



Fig. 1. overview of approach of identifying MFS

of these healthy schemas and not be the subschema of any one of these healthy schemas. It is obvious a pending schema must meet both the two conditions.

However, this is not the end of story of checking a pending schema. With the process of identifying, more and more faulty schemas and healthy schemas will be identified. It is not a small number, as it can reach to  $O(2^n)$ . So both for space and time restriction, we should not record all the faulty schemas and healthy schemas. Then we should find another way to check the pending schema.

To eliminate this problem, we propose an method which can check a pending schema with a small cost. It need to record the CMINFS and CMAXHS all through the process. Instead record all the faulty schemas and healthy schemas, CMINFS and CMAXHS are rare in amount, which can help to largely reduce the space need to record. Then according to the followed two propositions, we can easily check a pending schema.

**Propositions 5.** *If a schema is neither one of nor the parent-schema of any one of the CMINFS, then we can't make sure whether it is a faulty schema.*

*Proof:* Take a schema  $s_a$ , a CMINFS set  $S_{cminfs}$  and a faulty schema  $S_{fs}$  set which determined now. It is note that any element  $fs_i \in S_{fs}$  must meet that either  $fs_i \in S_{cminfs}$  or  $fs_i$  be the parent-schema of one of the  $S_{cminfs}$ . Assume that  $s_a$  is neither the one of nor the parent-schema of any one of the  $S_{cminfs}$ . To proof the proposition, we just need to proof that  $s_a$  is neither the one of nor the parent-schema of any one of the  $S_{fs}$ .

As  $s_a$  is neither the one of nor the parent-schema of any one of the  $S_{cminfs}$ , so it is not one of  $S_{fs}$ . Then we assume  $s_a$  is the parent-schema of one of  $S_{fs}$ , say,

$fs_j$ . As  $fs_j$  must meet either  $fs_j \in S_{cminfs}$  or  $fs_j$  be the parent-schema of one of the  $S_{cminfs}$ . So  $s_a$  is the parent-schema of one of  $S_{cminfs}$  according to the proposition 2, which is contradict. So the proposition is correct.  $\square$

**Propositions 6.** *If a schema is neither one nor the the subschema of any one of the CMAXHS, then we can't make sure whether it is a healthy schema.*

We ignore this proof as it is very similar to the previous one.

Up to now, we can judge whether a schema is a pending schema, but in effect, there are many pending schemas in a test configurations, especially at the beginning of our process. To choose which one has an impact on our approach. To better illustrate this problem, we consider the followed example:

Assume the failing test configuration: (1 2 1 1 1 2 1 2), that the CMINFS set: (1 2 1 1 - 2 - -) (- 2 - - 1 2 - 2), the CMAXHS set: (- 2 - - - - -) (- - - 1 - - -). We list some pending schemas followed (not all, as the number of all the pending schemas is too much that is not suitable to list here):

(1 2 1 - - 2 1 2) (- 2 1 1 - 2 - 2) (1 2 1 1 - - - -) (- 2 1 1 - 2 - -) (1 2 1 - - - - -) (- 2 - 1 - - 2 -) (1 2 - - - - -) (- 1 1 - - - -) (1 - - - - - -) (- - 1 - - - -).

Choose what is really different. If we choose (1 2 1 - - - -), assume we check it as a healthy schema. Then all its subschemas, such as (1 2 - - - - -) (1 - - - - - -) (- - 1 - - - -), are healthy schemas. It means that we did not need generate newly test configurations for them. But if we check it as a faulty schema, we can make sure all its parent-schemas are faulty schemas, in this case, they are (1 2 1 1 - - - -) and (1 2 1 - - 2 1 2) need no newly test configurations to test.

Let's look at this problem from another angle. Take the schema as a integer number, these parent-schemas of a schema is like the integer numbers bigger then this number, and these subschemas of a schemas is like the numbers smaller than this number. Take a float number as the metric, then, we can describe the faulty schema as the number bigger than this metric, and healthy schema as number smaller than this metric. So the minimal faulty schema is just the number most approximate the metric and bigger than the metric.

It seems like a search problem scenario. Then can we directly apply the efficiently algorithm binary-search? the answer is no, because there are schemas that neither parent-schema or subschema relationship, such as (1 2 1 - - 2 1 2) (- 2 1 1 - 2 - 2). So to utilize the binary search technique, we should make some change. First, should give the followed definitions:

**Definition 10** (chain). *A chain is an ordered sequences of schemas in which every schemas is the direct parent-schema of the schema that follows. Moreover, if all the schemas in a chain are pending schemas, we call the chain a pending*

chain.

This definition is similar to the path in []

As all the schemas in a chain are have relationships, then we can apply binary search technique. As we all know, the longer the pending chain, the better performance binary search technique will get. So we should choose a pending chain as longer as possible each iteration.

To get a longest chain, we need to ensure that the head schema of this chain do not have any parent-schema which is a pending schema(called up pending schema), and the tail schema do not't have any subschema which is a pending schema (called down pending schema). The algorithm that get the up pending schemas and down pending schemas are list in algorithm 1 and algorithm 2.

As showed in algorithm 1, we start from the failing test configuration  $\mathcal{T}$ , assign it to the *rootSchema*(line 1)and then add it to a *lists*(line 3). We then do some operation (line 4 -line 12)to this lists and at last get these pending schemas in lists as up pending schemas.(line 13) This operation consists of two iteration:

1. successively get one *CMINFS* in  $\mathcal{S}_{CMINFS}$ . (line 4). Define a temple value *nextLists* which initialize an empty set(line 5).We then execute the second iteration. After that, we will eliminate these same schemas list in *nextLists* (line 10)and then assign to *lists* (line 11).

2. Successively get one schema in *lists*(line 6). And then mutant it according to the *CMINFS* to a set of schemas(line 7). Add them to the *nextLists* (line 8).

The mutant procedure for a schema is just remove one value in it which this value is also in *CMINFS*. This procedure will result in *k* mutant schemas if the *CMINFS* is a *k*-value schema. By doing this, any mutant schema will not be the parent-schema of the corresponding *CMINFS*.

After this two iteration, the schemas in the *lists* will not be the parent-schema of any *CMINFS* in the  $\mathcal{S}_{CMINFS}$ .

Fig.2 gives an example to the algorithm 1.

Algorithm 2 is a bit different from algorithm 1. As our target is to get the minimal value pending schema, we get started from a 0-value schema(line 1). Then to make schemas not to be the subschema of any *CMAHXS* in  $\mathcal{S}_{CMAHXS}$ , we should let the schemas must contain at least one value that is not in the corresponding *CMAHXS*. So the strategy is to get a reverse schema of the *CMAHXS* which this schema consists of all these values in the failed configuration except these are in *CMAHXS*(line 5). And mutant the schema by adding one value in the reversed schema to make the schma not to be the subschema of the corresponding *CMAHXS*(line 8). After two iteration similar to Algorithm 1, we will get all the schemas that meet that not to be subschema of any *CMAHXS* in  $\mathcal{S}_{CMAHXS}$  from which we choose these pending

### Algorithm 1 getting up pending schema

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**Input:**  $\mathcal{T}$  ▷ failing test configuration  
 $\mathcal{S}_{CMINFS}$  ▷ set of CMINFS  
 $\mathcal{S}_{CMAHXS}$  ▷ set of CMAHXS  
**Output:**  $\mathcal{S}_{UPS}$  ▷ the set of up pending schemas  
▷ %comment: initialize%

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```

1: rootSchema  $\leftarrow \mathcal{T}$ 
2: lists  $\leftarrow \emptyset$ 
3: lists  $\cup \{\textit{rootSchema}\}$ 
4: for each CMINFS in  $\mathcal{S}_{CMINFS}$  do
5:   nextLists  $\leftarrow \emptyset$ 
6:   for each schema in lists do
7:     Scandidate  $\leftarrow \textit{mutant}_r(\textit{schema}, \textit{CMINFS})$ 
8:     nextLists  $\leftarrow \textit{nextLists} \cup \textit{S}_{candidate}$ 
9:   end for
10:  compress(nextLists)
11:  lists  $\leftarrow \textit{nextLists}$ 
12: end for
13:  $\mathcal{S}_{UPS} \leftarrow \{s | s \in \textit{lists} \wedge s \text{ is pending}\}$ 

```

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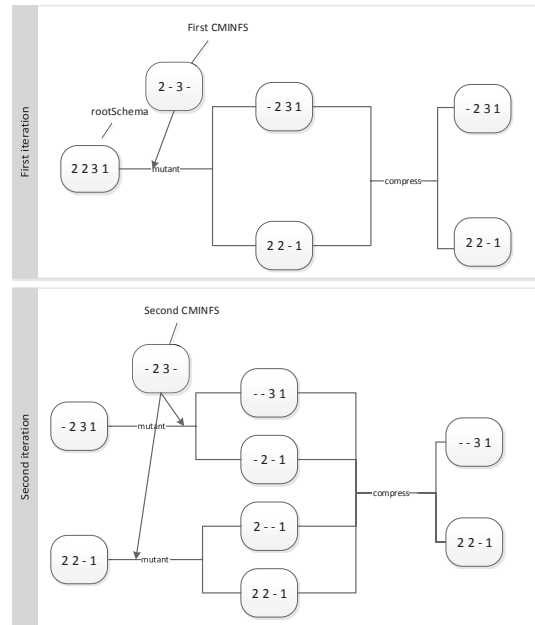


Fig. 2. example of getting up pending schemas

schemas as down pending schemas(line 14).

Fig.3 gives an example to the algorithm 2. we can see.

After we can get the up pending schemas and down pending schemas, then the algorithm of getting the longest chain can be very simple, which is list in Algorithm 3. In this algorithm we can see that we just search through the up pending schemas and down pending schemas(line 7 - 8) to find the two schemas which has the maximum distance(line 9 - 13). The distance of a *k*-value schema and a *l*-value schema (*k*! *l*) is defined as:

**Algorithm 2** getting down pending schema

**Input:**  $\mathcal{T}$   $\triangleright$  failing test configuration  
 $\mathcal{S}_{CMINFS}$   $\triangleright$  set of CMINFS  
 $\mathcal{S}_{CMAXHS}$   $\triangleright$  set of CMAXHS  
**Output:**  $\mathcal{S}_{DOWNS}$   $\triangleright$  the set of down pending schemas

$\triangleright$  %comment: initialize%

```

1:  $initSchema \leftarrow ()$ 
2:  $lists \leftarrow \emptyset$ 
3:  $lists \cup \{initSchema\}$ 
4: for each  $CMAXHS$  in  $\mathcal{S}_{CMAXHS}$  do
5:    $reverse \leftarrow reverse(CMAXHS)$ 
6:    $nextLists \leftarrow \emptyset$ 
7:   for each  $schema$  in  $lists$  do
8:      $S_{candidate} \leftarrow mutant_a(schema, reverse)$ 
9:      $nextLists \leftarrow nextLists \cup S_{candidate}$ 
10:  end for
11:   $compress(nextLists)$ 
12:   $lists \leftarrow nextLists$ 
13: end for
14:  $\mathcal{S}_{DOWNS} \leftarrow \{s | s \in lists \wedge s \text{ is pending}\}$ 

```

**Algorithm 3** Finding the longest pending schema

**Input:**  $\mathcal{T}$   $\triangleright$  failing test configuration  
 $\mathcal{S}_{CMINFS}$   $\triangleright$  set of CMINFS  
 $\mathcal{S}_{CMAXHS}$   $\triangleright$  set of CMAXHS  
**Output:**  $\mathcal{CHAIN}$   $\triangleright$  the chain

```

1:  $S_{UPS} \leftarrow getUPS(\mathcal{T}, \mathcal{S}_{CMINFS}, \mathcal{S}_{CMAXHS})$ 
2:  $\mathcal{S}_{DOWNS} \leftarrow getDOWNS(\mathcal{T}, \mathcal{S}_{CMINFS}, \mathcal{S}_{CMAXHS})$ 
3:  $max \leftarrow 0$ 
4:  $head \leftarrow NULL$ 
5:  $tail \leftarrow NULL$ 
6:  $chain \leftarrow NULL$ 
7: for each  $up$  in  $S_{UPS}$  do
8:   for each  $down$  in  $\mathcal{S}_{DOWNS}$  do
9:     if  $distance(up, down) \geq max$  then
10:       $max \leftarrow distance(up, down)$ 
11:       $head \leftarrow up$ 
12:       $tail \leftarrow down$ 
13:   end if
14: end for
15: end for
16:  $\mathcal{CHAIN} \leftarrow makechain(head, tail)$ 

```



Fig. 3. example of getting down pending schemas

the approach, we discuss it in the overall identifying algorithm which is list in the Algorithm 4. As we have talked previously, we first judge the end criteria, if meet we will report the minimal faulty result. Otherwise we will do the loops. In the loop, we first judge if it is the beginning or headIndex greater than tailIdx, then we will update the CMINFS and CMAXHS, followed generated the longest chain and initial the headIndex, tailIndex and middleIdx. If not we will get the middleIndex indicate the half. Then will select the schema with index of middleindex in the longest chain. And then generate a test configuration and execute the SUT under it. If the result passed, we let tail = middle - 1 else head = middle + 1. By doing this and the previous set the middleIndex we can apply the binary search to the indenting. It is noted that we intially let middle = 0. which we want know if this chain has faulty schema as soon as possible.

**3.2.2 generate a new test configuration**

To generate a new test configuration to test the schema. The generated test configuration must meet the followed rules:

1. must contain the selected schema.
2. must not
3. constraint(system-wide constraint and test case specific constraint, i.e., masking effect)

The first one is easy to meet. We just keep the same value which are in the schema are also in the test configuration. We must meet the second condition for that if we contain another one, combine this then this test configuration will contain an parent-schema of this selected schema in the original test configuration,

$$distance(S_k, S_l) = \begin{cases} -1, & S_k \text{ is not parent-schema of } S_l \\ k - l, & \text{otherwise} \end{cases}$$

Then we just use *makechain* procedure to generate the longest chain. The *makechain* procedure is very simple, it just repeat adding one schema by keeping all the value in down pending schema and removing one factor of the previous schema.

The last step of getting the schema is just choose the schema from the longest chain. To clearly describe



**Algorithm 4** identify process

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**Input:**  $\mathcal{T}$  ▷ failing test configuration  
 $\mathcal{S}_{CMINFS}$  ▷ set of CMINFS  
 $\mathcal{S}_{CMAXHS}$  ▷ set of CMAXHS

- 1: **while** *hasn't meet the end criteria* **do**
- 2:   **if** *the beginning or headIndex > tailIndex* **then**
- 3:      $update(\mathcal{S}_{CMINFS}, \mathcal{S}_{CMAXHS})$
- 4:      $longest \leftarrow getLongest(\mathcal{T}, \mathcal{S}_{CMINFS}, \mathcal{S}_{CMAXHS})$
- 5:      $headIndex \leftarrow 0$
- 6:      $tailIndex \leftarrow length(longest) - 1$
- 7:      $middleIndex \leftarrow 0$
- 8:   **else**
- 9:      $middleIndex \leftarrow \frac{1}{2} \times (tailIndex + headIndex)$
- 10:   **end if**
- 11:    $SCHEMA \leftarrow longest[middleIndex]$
- 12:   *generate a extra test configuration  $\mathcal{T}'$  contain SCHEMA*
- 13:   *execute SUT under  $\mathcal{T}'$*
- 14:   **if** *the test configuration passed* **then**
- 15:      $tailIndex \leftarrow middleIndex - 1$
- 16:   **else**
- 17:      $headIndex \leftarrow middleIndex + 1$
- 18:   **end if**
- 19: **end while**
- 20: *report the minimal faulty schemas*

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and it will confuse us whether it is indicate this schema or its parent-schemas dedicate this result. To fulfil this condition, we need to choose other available values in the SUT which are different from the original test configuration. the third one is that we should consider the constraints

**3.2.3** *execute SUT under the test configuration*

In real software testing scenario, when we test a SUT under a test configuration, there may be many possible testing state: such as pass the testing assertion, don't pass the testing the assertion but with different failure type, can't complete the testing. To get a clear discussion, in this paper we just use *pass* represent the state that pass the testing assertion and *fail* represent all the remained state.

**3.2.4** *update information*

The update information is followed when the current chain is checked over. Then before we generate another longest chain, we should update the CMINFS and CMAXHS set. In fact, we just need the CMINFS and CMAXHS in the longest chain.

**3.2.5** *stop criteria*

The stop criteria is clear, our algorithm stops when there are no pending schemas left, for that when we once can checked all the schemas of a test configuration, we can get the minimal faulty schemas, which is the target of our algorithm. And whether there are

pending schemas can be easily checked by that if we can't generate a longest chain (the length must greater than 1), there must be no pending schemas.

**3.2.6** *report the result*

In fact, the last in the CMINFS lists is must be the minimal faulty schemas. For that if these schema in the CMINFS is not minimal faulty schema, then there must be some pending schemas. However, the algorithm stop when there are no pending schemas remained. So at last these in the CMINFS must be the minimal faulty schemas.

**3.2.7** *new ideas*

you should first identify a failure-inducing schema, and then find others. initial the find tuples, and then using the same algorithms as others. when identify is confirm , then choosing new longest path.

**3.3** *example*

We will give an complete example listed in Table 2. Assume that a SUT is . constraints.

**3.4** *Without Safe Values Assumption*

Up to now our algorithm is based on the assumption that additional generated test configuration does not introduce newly faulty schema. We will give an augment algorithm this section to eliminate this assumption. Our augment algorithm is inspired by the feedback machinery in the controlling system, which in high level we will validate the identify result at the end of the aforementioned algorithm, and if the schema is validated as a minimal faulty schema, we will end the algorithm, otherwise we will repeat the algorithm again to adjust the result. The detail of our augment algorithm is list in Algorithm 5. We can find the first part of augment algorithm is an unlimited loop, in the loop we first use previous identify algorithm to identify the MFS, and then we will check the result, the check process is just to additional generate another test configurations and execute. When we find the MFS is not right, which means our process introduce newly MFS, then we first label this MFS as an healthy schema, and then update the CMAXHS. After check, if we find at least one MFS is not right, we then empty the CMINFS, and then readd these right identified MFS to this set, and then reprocess this process untill all the MFS is validated as right. The second part of our algorithm is just we look through the generated test cases one by one, if it failed, and did not contain the MFS we identified in the first part, which means it introduce newly faulty schema, and we will rerun this process to find these introduced MFS.

Table 3 illustrate this augment algorithm with an example.

TABLE 2  
An example of identifying

$S_{CMINFS}$	$S_{CMAXHS}$	Longest Chain	Choosing Schema	Generating Test Configuration	Execution result
1	1	1	1	1	false
1	1	1	1	1	pass
1	1	1	1	1	false

TABLE 3  
An example of augment identifying

$S_{CMINFS}$	$S_{CMAXHS}$	Longest Chain	Choosing Schema	Generating Test Configuration	Execution result
1	1	1	1	1	false
1	1	1	1	1	pass
1	1	1	1	1	false

---

**Algorithm 5** augment identify process

---

**Input:**  $\mathcal{T}$   $\triangleright$  failing test configuration  
 $S_{CMINFS}$   $\triangleright$  set of CMINFS  
 $S_{CMAXHS}$   $\triangleright$  set of CMAXHS

```

1: while true do
2:    $S_{MFS} = Identify\_process(\mathcal{T})$ 
3:   for each  $MFS$  in  $S_{MFS}$  do
4:     if  $validate(MFS) = fail$  then
5:        $updateHealthySchemas(S_{CMAXHS}, MFS)$ 
6:     end if
7:   end for
8:   if at least one  $MFS$  is not correct then
9:      $empty(S_{CMINFS})$ 
10:    add all the validated  $MFS$  in the  $S_{CMINFS}$ 
11:   else
12:     break
13:   end if
14: end while
15: for each  $testCase$  in  $EXTRATESTCASES$  do
16:   if  $testCase$  introduce newly  $MFS$  then
17:      $augment\_identify\_process(testCase)$ 
18:   end if
19: end for
20: report the minimal faulty schemas

```

---

## 4 EVALUATION USING SIMULATED MODEL

In this section, we give an a series of studies of our two identify algorithms on simulated model. The goal of our experiments is to evaluate the efficiency and effectiveness of our two identify algorithms compared with other existed algorithms. The reason why we use simulated model is that we can control. We will validate in real softwares in the next section.

### 4.1 comparison algorithms

There are some algorithms aim to identify the MFS, they can be classified as non-adaptive methods and adaptive methods. The first set of methods do not need additional test configurations and can identify

the when given an executed test configurations while the second one do need. Our algorithm is belong to the second part. To make a clear comparison, we just compare the algorithms which all belong to this part. The more detail and discuss of all the algorithms is listed in the section 6. The compared algorithms is as follows:

#### 4.1.1 OFOT

This method is proposed by Nie[]. It first separates the faulty-possible tuples and healthy-possible tuples into two sets. Subsequently, by changing a parameter value at a time of the original test configuration, this approach generates extra test configurations. After executing the configurations, the approach converges by reducing the number of tuples in the faulty-possible sets.

#### 4.1.2 IterAIFL

This method proposed by Wang[] is a mutant based on the Nie's[]. It define the "change strength" that not like the previous one just change one factor one time, it may change many factors one time.

#### 4.1.3 FIC

Zhang [] propose this method which is combined the OFOT method and binary search. Different from the OFOT, it change half factor one time to quickly located in one factor firstly and then keep the factor and loop the process.

#### 4.1.4 RI

Lee propose this algorithm[]. Similar to the FIC, it is also inspired by the delta debugging. The difference is the order that it change factors.

#### 4.1.5 Spectrum based method

Different from the aforementioned methods, Ghandehari.etc [10] defines the suspiciousness of tuple and suspiciousness of the environment of a tuple. Based



on this, they rank the possible tuples and generate the test cases. Although their approach imposes minimal assumption, it does not ensure that the tuples ranked in the top are the faulty tuples.

the parameter setting is as follows: the predefined number is 5, and the number of turns of finding the minimum pe is the parameter multiplied.

#### 4.1.6 Martin safe value

#### 4.1.7 classified tree

must add "-M 1" "-U" confidence factor 0.25

#### 4.1.8 TRT

This algorithm is proposed in[. Different from this work. It should record all the schemas of a failed test configuration. It is very resource assume and this is reason we propose this work. A second difference is that the TRT algorithm when meet the situation the extra test configuration may introduce newly faulty schemas is using more test configuration to confirm a schema each time when find a schema is labeled as a faulty schema while this work just validate one time at the end of algorithm.

### 4.2 subject programs

This section will give an general illusion of the algorithms. We will give an test bench to measure the properties of all the algorithms. All the programs are toys and have the property that we can easily control its input parameters and faulty schemas, which makes clearly get the view of what we want to know from the algorithms. In addition, we will corroborate the results by observing each algorithm of identifying failure-inducing schemas in real software in section 6.

### 4.3 evaluation metrics

The metrics are additional generated test configurations, the recall and precise. The recall and precise is defined as:

$$recall = \frac{Identified\ MFS}{all\ the\ MFS\ in\ SUT}$$

$$precise = \frac{correctly\ Identified\ MFS}{all\ the\ identified\ MFS}$$

### 4.4 experiment setups

We will do the three experiment: (1)single faulty schema. (2)multiple faulty schema in a failed test configuration. (3)multiple faulty schema, which give a fail test configuration contain one faulty schema, we do so that give an chance that the extra test configuration can introduce another faulty schema.

In detail, for every experiment in the toy experiment section, we first vary the number of input

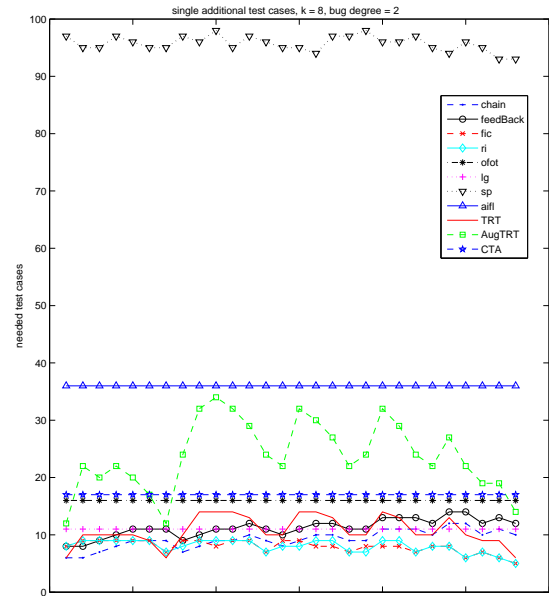


Fig. 4.  $k = 8$ ,  $t = 2$ , additional test suites

parameters of SUT, i.e.,  $n = 10, 40, 80, 120, 160, 200, 240, 280, 320, 360$  to observe the behaviour of the algorithms executed among different size of SUT. Then to get an relative generally evaluation, we inject each possible  $t$ -value schema (reach to  $\binom{n}{t}$ ), one time for the single faulty schema experiment and each possible combination of two  $t$ -value schema one time for the multiple faulty schema experiment. ( $t = 2, 3, 4, 5, 6$ ). For the third, we first fix one  $t$ -value faulty schema, and give an failed test configuration contain this schema, then for each algorithm aims to identify this faulty schema, the first extra test configuration each algorithm generate, we random select an  $t$ -value schema (do not contained in the original failing test configuration) as the introduced faulty schema.

For all the three experiment, we record the number of extra test configurations, correctly identified schemas and incorrectly identified schemas. At last we compute the recall and precise along with the number of extra test configurations.

### 4.5 results and discuss

#### 4.6 threats to validate

how seeded bugs are representative auto oracle, if we don't have a correct version, or we can't determine a test case is faulty and wrong, then what can i do? timing result One worrying aspect of this research is that it seems to consider only the number of tests and number of faults uncovered. In the practice of testing, it is as important or more important to know testing times.

## 5 EMPIRICAL CASE STUDY

While we got know that our approach have a better performance than others in several scenarios such as

a failing test case contains multiple MFSs, the generated extra test case introduces newly MFS and so on from previous simulated experiments, it does not give us strong confidence in that our approach will also perform well in real software systems. One important reason of this is that we don't know whether these competitive scenarios for our approach existed in real software systems. So to eliminate the doubt we conduct a series empirical studies in this section. These empirical studies aimed to answer the following questions: Q1:Is there any test case that contain multiple MFSs, and if so, do they overlapped each other? Do any of these MFSs have high degree and how likely does it introduce newly MFS when generate extra test cases. Q2:How well of these approaches mentioned in previous sections performed when identifying the MFS in the real softwares? Q3:If we combine the result of one approach with another one, does it give us a better result than both of them?

The subject systems for these studies are HSQldb-B(2.0rc8). HSQldb is a database management system written in pure java.

## 5.1 experimental setup

Before we use these programs for study, we will take the following steps for each program to obtain the basic information of them, 1)Build the input configuration model of the subject program 2)execute the test case under each possible configuration and record their executed result. 3)list all the types of fault during testing and judge their priority.

We will depict these processes and results for each subject program in detail.

### 5.1.1 HSQldb

Through searching the developers' community of HSQldb in sourceforge, we found a buggy version with its faulty description in [], and a test script is attached which can reproduce the bug. The original test script only considered one option which have two values, remaining the other options set default configuration. To make the testing scenario the configuration testing, we added some other options of the database management software to make it , combined with the option in test script we derive the input configuration model in listed table 4.

Before we describe our case studies we should first describe the subject programs in our case study. Database systems is customizable and complicated. so we choose a database as our system. Through viewing its developer's community . we find a bug description which have been repaired[]. We take this version and its test script. To be more adaptive for our testing approach, we add some configuration options to the test script. To be more specific, we can see the followed model the test model is as follows,

TABLE 4  
input model of HSQldb

SQL properties(TRUE/FALSE)	
sql.enforce_strict_size,	sql.enforce_names,sql.enforce_refs,
sql.enforce_size,	sql.enforce_types,
sql.enforce_tdc_update,	sql.enforce_tdc_delete,
table properties	values
hsqldb.default_table_type	CACHED, MEMORY
hsqldb.tx	LOCKS, MVLOCKS, MVCC
hsqldb.tx_level	read_committed, SERIALIZABLE
hsqldb.tx_level	read_committed, SERIALIZABLE
Database properties	values
existed form	MEM, FILE
Server Type	SERVER, WEBSERVER, INPROCESS
Result Set properties	values
resultSetTypes	TYPE_FORWARD_ONLY,TYPE_SCROLL_INSENSITIVE,TYPE_SCROLL_SENSITIVE
resultSetConcurrencys	CONCUR_READ_ONLY,CONCUR_UPDATABLE
resultSetHoldabilitys	HOLD_CURSORS_OVER_COMMIT,CLOSE_CURSORS_AT_COMMIT
StatementType	
STATEMENT, PREPAREDSTATEMENT	

TABLE 5  
input model of HSQldb

faulty	priority
1	2
2	1
3	1 2
4	1 2

from which the configuration file which controlled the behavior of data base is the input model which listed as follows: we can simplify as this  $2^1 3 * 3^3 = 221184$

the source code of HSQldb is just a jar library, the test file is a common script file that drive one running case of the sqldb.

Our testing paradigm is writing the configure file and executing the test script.

### 5.1.2 preprocessing

To evaluate the performance of different algorithms , we should know the real MFS in this software, the original webpage is a hint, but is not enough, as it is just adapt two options. And now we add more options , which make the problem more complicated. So we take the followed steps: 1.execute the test script under each possible configuration. we running Particularly, we should run  $2^1 3 * 3^3 = 221184$  test cases. and This process is time consuming. 2.collect the failure information and their priority. this is done by We also by static review of the test script code. 3.Use definition to exhaustive get the real faulty schema information.

### 5.1.3 result

The result is as follows: four types of fault. their priority is as: we get the followed faulty schema for each failure.

## 5.2 Study 1: what the schemas like in test configurations of HSQldb

In this study, we want to answer the first question. Do they have multiple faulty schemas, and do they have higher degrees. And can they import bugs.

### 5.2.1 Study setup

The first two one : multiple and high degree and overlapped is counted very easy, we just use their definitions. But the way we evaluate the introduce rate is not so. First, our introduce rate is based on the followed theory: In a test case, if we change one factor of it to generate a new test case. And assume that we introduce a new failure-inducing schema, but meanwhile we didn't break the original failure-inducing schema in the previous test case. At this situation it will not influence our identifying result for that if we do not introduce the schema, our result is the same—trigger a failure.

## 5.3 Study 1: input testing

This section we will apply the identifying techniques into the input testing. Input testing is the correct testing for any input that is supplied by the system under testing. The input could vary from user operation, network event signal, program input parameters and so on. In this section, we just limit the input to the input parameter values. And the SUT is just a simple program that need input parameter to run. We believe the study of other form of input testing is similar.

### 5.3.1 Subject programs

Siemens, which is a small set of programs, has been used as a benchmark to evaluate the effectiveness of many testing techniques[]. It contains six C programs, which range in size from 138 to 516 lines of non-blank, non-comment code, and perform a variety of functions. Each program has one correct version and several faulty versions which come from by mutating the source code of the original correct version.

The Siemens is original thought to study the fault-detecting effectiveness of coverage criteria[], as a result, the large test pool assembled by researchers is not suitable for our testing purpose. We find laleh[] has modeled all the programs according to the combinatorial testing purpose. It is very fit with our work, so we adopt their modeling method. The detail information is listed in table 6.

TABLE 6  
The description of Siemens

program	LOC	bug versions	input model
print_tokens	726	7	7 submodel list in table 7
print_tokens2	570	10	7 submodel list in table 7
replace	564	32	$2^4 \times 4^{16}$
schedule	412	9	$2^1 \times 3^8 \times 8^2$
schedule2	374	10	$2^1 \times 3^8 \times 8^2$
tcas	173	41	$2^7 \times 3^2 \times 4^1 \times 10^2$
totinfo	565	23	$3^3 \times 5^1 \times 6^1$

TABLE 7  
The description of print\_tokens and print\_tokens2

sub program	input model
keyword	$2^1 \times 3^1 \times 5^1$
identifier	$2^6 \times 3^1$
number	$2^3 \times 3^1$
comment	$2^9 \times 3^1$
special	$2^1 \times 3^1 \times 8^1$
character	
string	

### 5.3.2 preprocessing

The information of the TCAS is as followed, and to be clearly, we also list the information of other program in Siemens set. but they are average information.

As we all see the multiple and overlapped is existed and the introduce ratio also shows that our algorithm is necessary when face the real bug.

o we should need the tool to make sure the faulty schemas in these system, Symbolic executing, and then we find a failing test configuration contain these test configuration of each faulty version and feed it to each algorithm to see the result. The record information is the same as the toy experiment.

2) The second set is the small and middle scale real softwares: the Siemens software. It has six programs, to make them feasible to test we model them as follows which are the same as the paper[]. Each descriptions are listed in table 6.

### 5.3.3 get statistic info in the software

first using the completely searching method to get all the failure-inducing combinations. It is very time-consuming which is not practical in large parameter SUT. and then using all the algorithms to get it.

### 5.3.4 experiment setup

### 5.3.5 experiment results and analysis

## 5.4 Study 2: configuration testing

### 5.4.1 Subject programs

## 5.5 Large scale experiment

This last experiment is similar to the second one, except it doesn't have faulty version. It is a real published

TABLE 8  
The description of Large-scale software

program	version No	LOC	input model
MySQL	2013121	1	$2^2 \times 3^2$
	2013121	1	$2^2 \times 3^2$
	2013121	1	$2^2 \times 3^2$
	2013121	1	$2^2 \times 3^2$
FireFox	2013121	1	$2^2 \times 3^2$
	2013121	1	$2^2 \times 3^2$
	2013121	1	$2^2 \times 3^2$

version, however it has faulty for sure. Each newer version will help to fix some of them. And to make the evaluation feasible, we also need to know the real MFS. However, it is not possible for we can't using the symbolic execution because it is too large. So we change the style we validate, for each MFS the algorithm identified, we additional generate test configurations to test whether it is right. If all its are right, then we compare which of them are the minimal and identify the most number of MFS. 3)The last set of programs is the large open-source scale software: MySQL and FireFox. We model them as table 8:

## 5.6 Study 2: regression testing

### 5.6.1 Subject programs

## 6 RELATED WORKS AND DISCUSS

Nie approach in [3] and [6] first separates the faulty-possible tuples and healthy-possible tuples into two sets. Subsequently, by changing a parameter value at a time of the original test configuration, this approach generates extra test configurations. After executing the configurations, the approach converges by reducing the number of tuples in the faulty-possible sets. Delta debugging [5] proposed by Zeller is an adaptive dividend-conquer approach to locating interaction fault. It is very efficient and has been applied to real software environment. Zhang et al. [4] also proposed a similar approach that can identify the failure-inducing combinations that has no overlapped part efficiently, Colbourn and McClary [7] proposed a non-adaptive method. Their approach extends the covering array to the locating array to detect and locate interaction faults. C. Martez [8-9] proposed two adaptive algorithms. The first one needs safe value as their assumption and the second one remove the assumption when the number of values of each parameter is equal to 2. Their algorithms focus on identifying the faulty tuples that have no more than 2 parameters. Ghandehari.etc [10] defines the suspiciousness of tuple and suspiciousness of the environment of a tuple. Based on this, they rank the possible tuples and generate the test cases. Although their approach imposes minimal assumption, it does not ensure that the tuples ranked in the top are the

faulty tuples. Yilmaz [11] proposed a machine learning method to identify inducing combinations from a combinatorial testing set. They construct a classified tree to analyze the covering arrays and detect potential faulty combinations. Beside this, Fouché [12] and Shakya [13] made some improvements in identifying failure-inducing combinations based on Yilmaz work.

We list a comprehensive detail and comparison table 9as followed.

But even we get the failure-inducing schemas, it is still having a gap to fetch the failure causing root from the code. Such as int the TCAS, we get the failure-inducing schemas, and this is caused by a code mutation in the code such as followed:. So in the future, we will analysis the relationship between the failure-inducing schemas and the real code causing.

## 7 CONCLUSION

The conclusion goes here.

## APPENDIX A

### PROOF OF THE FIRST ZONKLAR EQUATION

Appendix one text goes here.

## APPENDIX B

Appendix two text goes here.

The procedure :

$$mutant_a$$
$$mutant_r$$

*ispending*schema

makechain

## ACKNOWLEDGMENTS

[illegible]

## REFERENCES

- [1] H. Kopka and P.W. Daly, *A Guide to L<sup>A</sup>T<sub>E</sub>X*, third ed. Harlow, U.K.: Addison-Wesley, 1999.

TABLE 9

algorithms	time complexity	space complexity	multiple schemas	strength of schema	safe value	result style
CMinFS	$O(\log(n))$	$O(n)$	yes, no limit, can overlapped	1 n	can handle	precise
FIC	$O(\log(n))$	$O(n)$	yes, no limit, can't overlapped	1 n	can't handle	precise
TRT	$O(\log(n))$	$O(2^n)$	yes, no limit, can overlapped	1 n	can handle	precise
Spetrum	$O(n*t)$	$O(n * t)$	yes, no limit, can overlapped	1 n	can handle	a rank of possible

PLACE  
PHOTO  
HERE

[illegible][illegible]