

## DFS

→ each time new vertex explored,

Immediately explore neighbours

→ start at 'source vertex' (mark it visited)

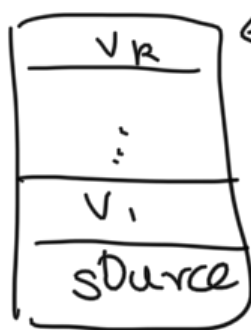
→ Visit first unvisited nbhr of  $i$ , call it  $j$

→ suspend exploration of  $i$  and explore  $j$  instead

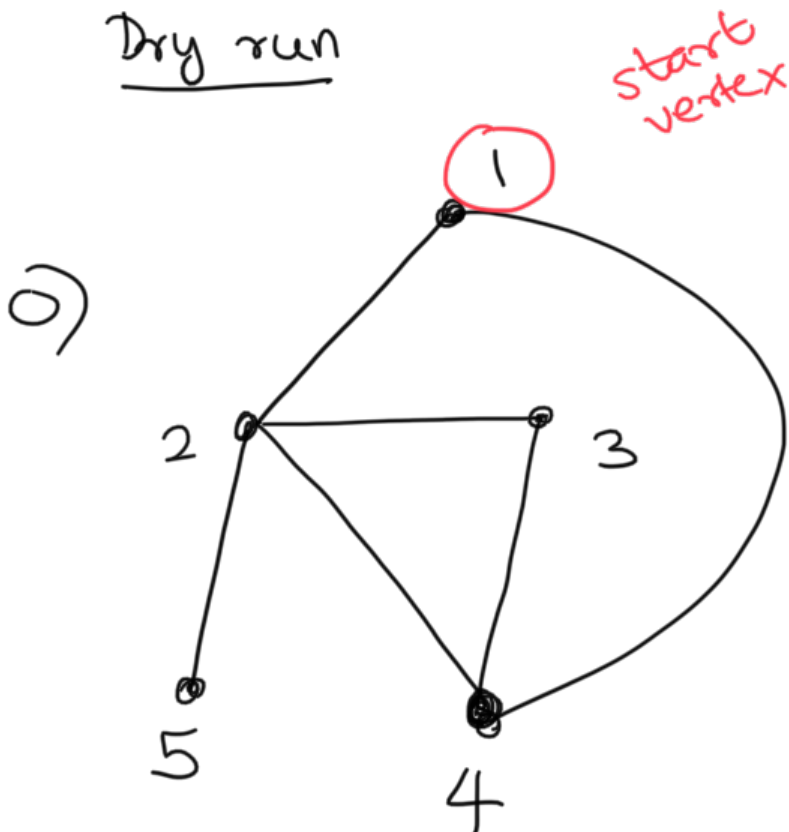
→ continue till you reach vertex with no unvisited neighbours

→ Back track to nearest suspended vertex with  $\geq 1$  unexplored nbhrs → ...

stack of suspended vertices..



Dry run

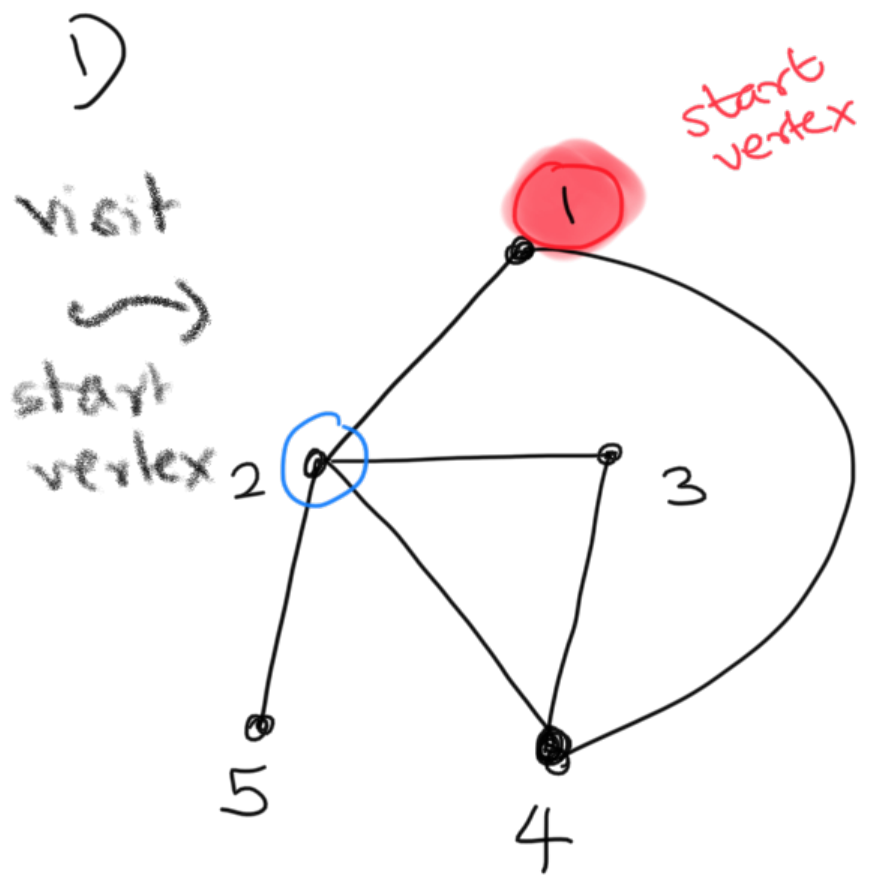


1	2	3	4	5
F	F	F	F	F

visited

$\phi$

stack

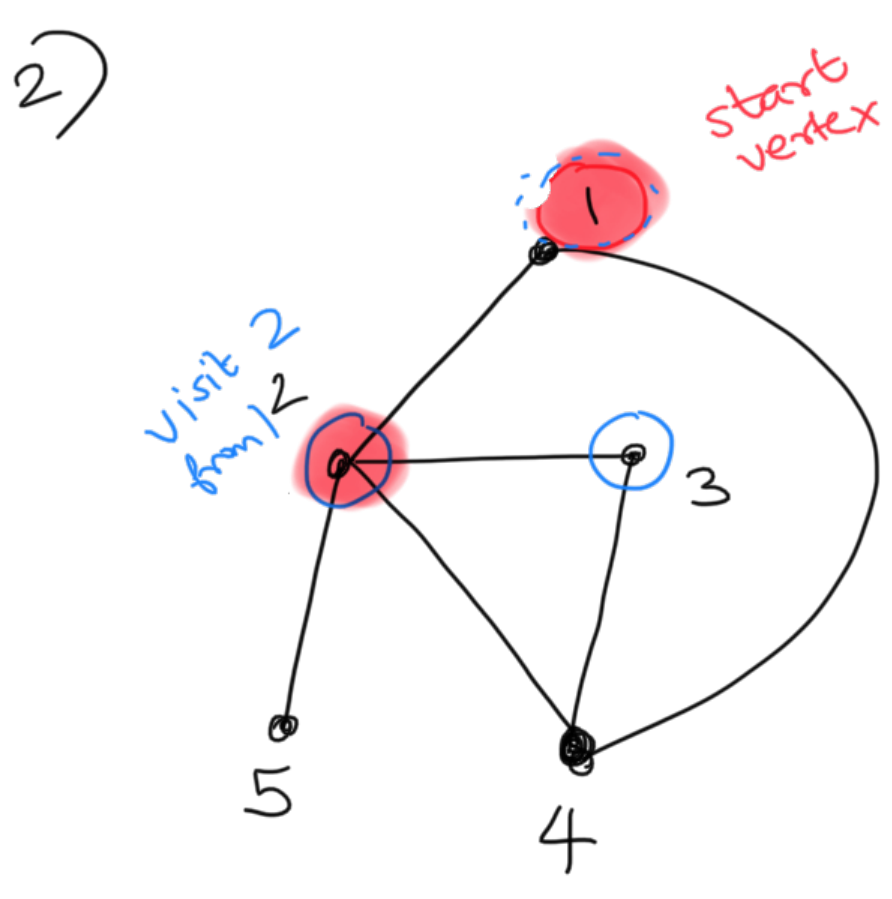


1	2	3	4	5	visited
T	F	F	F	F	

stack

1

↑  
suspend exploration to 1



parent (2) = 1

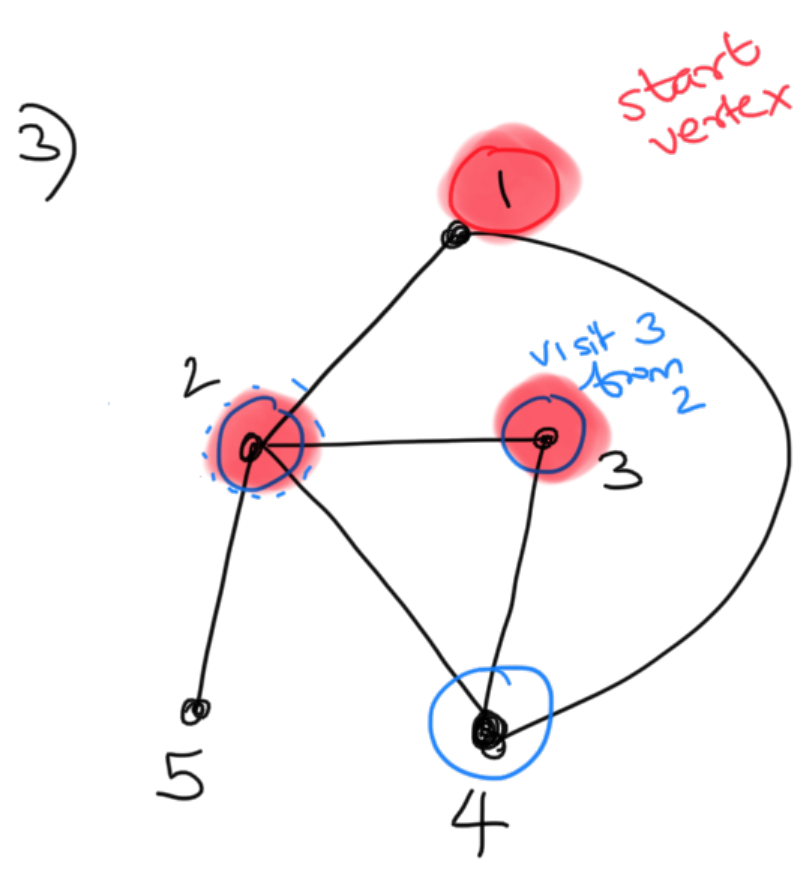
1	2	3	4	5	visited
T	T	F	F	F	

stack

2

1

↑  
suspend exploration to 2



parent (3) = 2

1	2	3	4	5	visited
T	T	T	F	F	

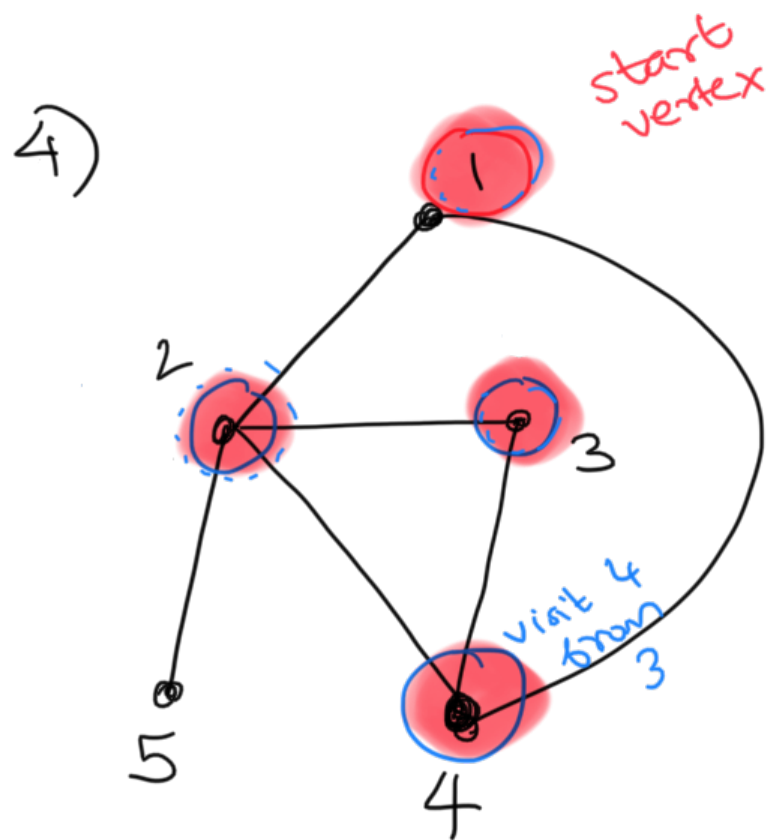
stack

3

2

1

↑  
suspend exploration to 3



parent(4) = 3

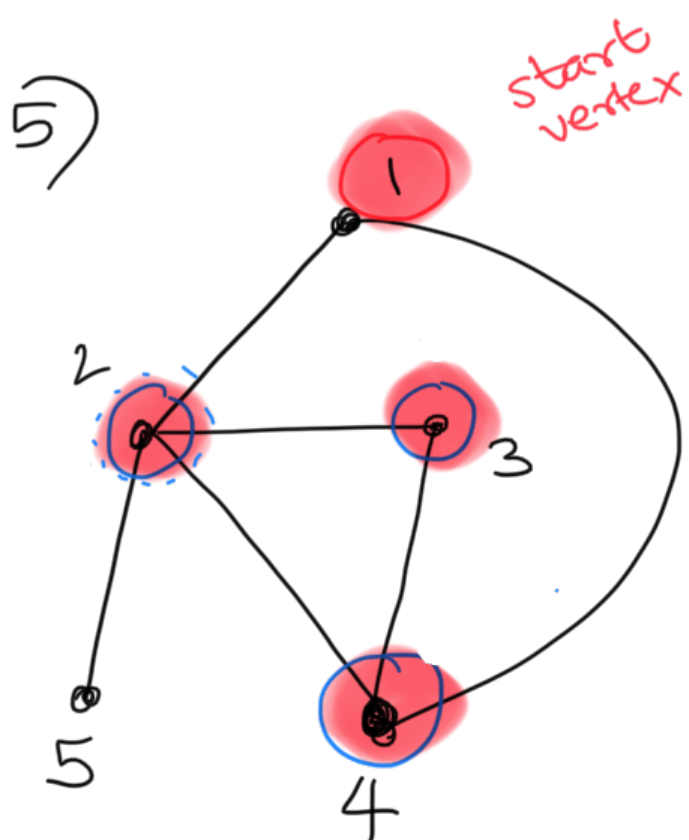
1	2	3	4	5
T	T	T	T	F

visited

3
2
1

stack

4 is a dead end.  
All nbhrs explored



1	2	3	4	5
T	T	T	T	F

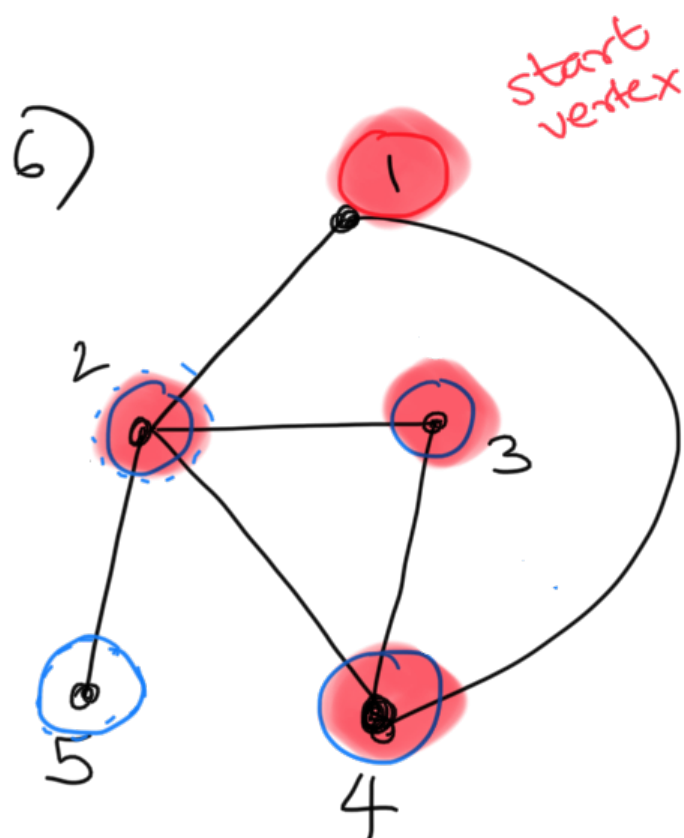
visited

3 ← pop 3 from stack to explore

2
1

stack

3 is a dead end!



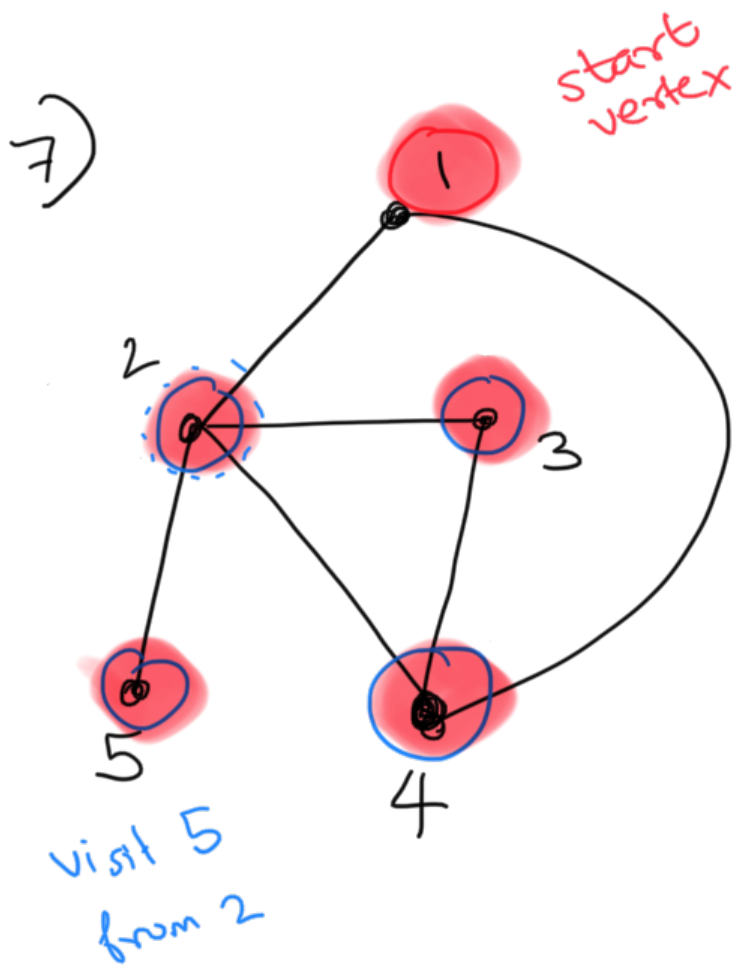
1	2	3	4	5
T	T	T	T	F

visited

2 ←

1
---

pop 2 from stack to explore



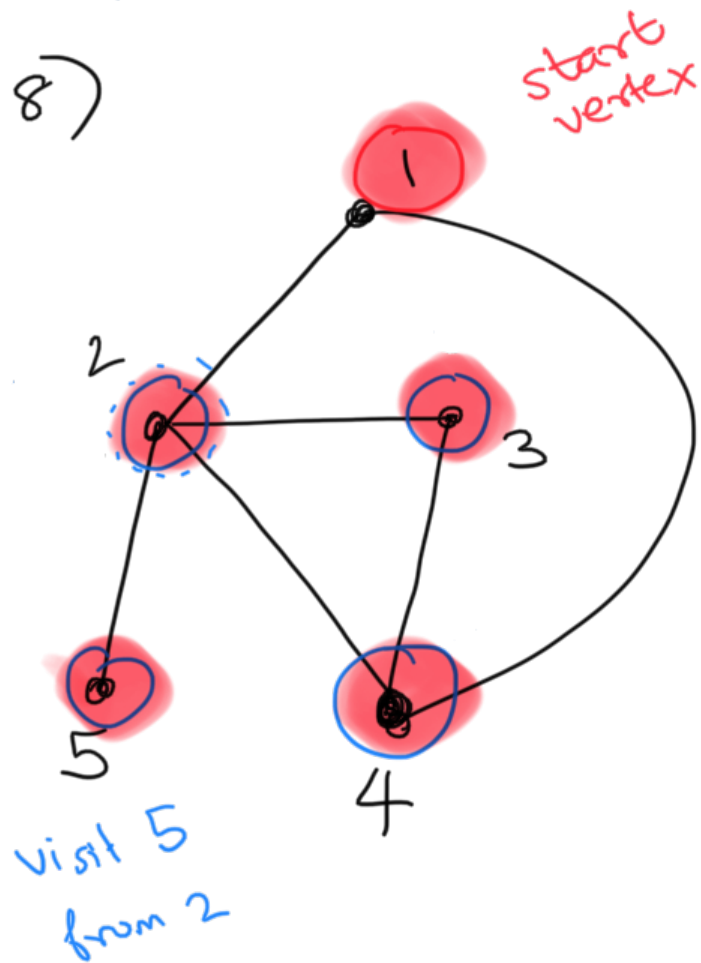
parent(5) = 2

1	2	3	4	5
T	T	T	T	T

visited

1

stack



1	2	3	4	5
T	T	T	T	T

visited

1

pop 1 from stack

↑

∅

1 is a dead end  
All nbhs explored -  
Terminate.

### DFS path recovery

source  $\xrightarrow{?}$  target ?

→ If visited[target] = T,  $\exists$  path bet source, target  
target  $\rightarrow$  parent(target), parent(parent(target))  
... , source

→ if visited[target] = F,  $\nexists$  path bet source and target

Implement using recursion ↙ (implicit stack)

visited : 

F	F	...	F
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parent : 

None	...	None
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def DFS (start vertex) :

visited[start] = T

for w neighbour of start :

if visited[w] = F,  
parent(w) = start  
DFS(w)