

AMCS 241 - STAT 250

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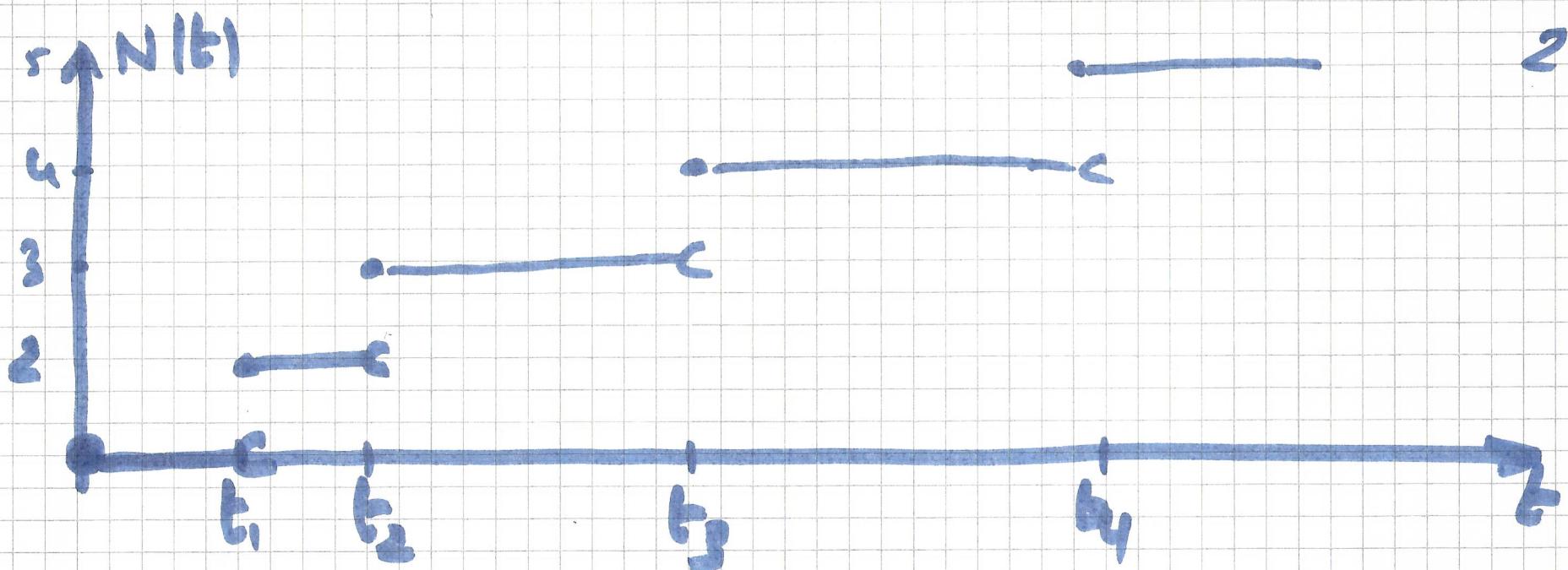
Lecture #10

. Chapter 10 (Some RPs)

10.6 Poisson RP

10.6.a Introduction

A typical illustration of the Poisson RP is :



- The RP whose realizations is a set of times (t_1, t_2, t_3, \dots) is called the Poisson RP
- The RP that counts the number of events in the time interval $[0, t]$ and which is denoted by $N(t)$ is called the Poisson Counting RP

- . $N(t)$ is a discrete valued continuous time RP and is used to model a wide range of physical or man-made phenomena such as
- . Arrival of customers at a cashier
 - . Requests of service in a computer network

....

10.6.b Derivation of the Poisson Counting Process

Our starting Point is 3 Axioms:

Axiom 1

$N(0) = 0$ (since we assume that
the RP starts at $t=0$)

Axiom 2

$N(t)$ has independent and
stationary increments

→ For two increments we assume that the
RVs:

$$I_1: N(t_2) - N(t_1)$$

$$I_2: N(t_4) - N(t_3)$$

* I_1 and I_2 are independent if

$$t_4 \geq t_3 \geq t_2 \geq t_1$$

* I_1 and I_2 have the same PDF

$$\text{if } t_2 - t_1 = t_4 - t_3$$

Axiom 3

$$P[N(t + \Delta t) - N(t) = k] = \begin{cases} 1 - e^{-\lambda \Delta t} & \text{for } k=0 \\ \lambda \Delta t & \text{for } k=1 \end{cases}$$

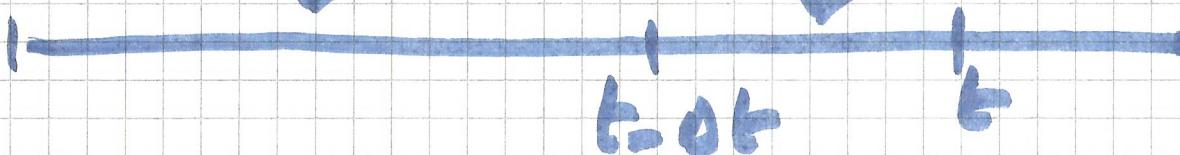
→ We are now ready to derive the
Eulerian Country RE.

6.1

→ Consider first $P[N(t)=0]$

for an arbitrary $t > 0$

0 animals 0 animals



So to have no animals in $[0, t]$,
 there must be no animals in $[0, t - \Delta t]$
 and no animals in $[t - \Delta t, t]$

Thus

$$P[N(t)=0] = P[N(t-\Delta t)=0 \text{ and}]$$

$$N(t-\Delta t)=0)$$

↓ independence
Axiom 2

$$= P[N(t - \Delta t) = 0] \cdot P[N(t) - N(t - \Delta t) = 0]$$

$$= P[N(t - \Delta t) = 0] \cdot (1 - \lambda \Delta t) \quad \downarrow \text{Axiom 3}$$

Now let $P[N(t) = 0] \triangleq P_0(t)$

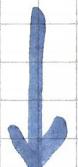
So we can write

$$P_0(t) = P_0(t - \Delta t) \cdot (1 - \lambda \Delta t)$$

$$\frac{P_0(t) - P_0(t - \Delta t)}{\Delta t} = -\lambda P_0(t - \Delta t) \quad \downarrow \Delta t \rightarrow 0$$

$$\frac{d P_0(t)}{dt} = -\lambda P_0(t)$$

8'



$$P_0(t) = K e^{-\lambda t}$$

Using Axiom 1

$$P[N(0) = 0] = P_0(0) = 1$$

$$1 = K e^0 \Rightarrow \boxed{K = 1}$$

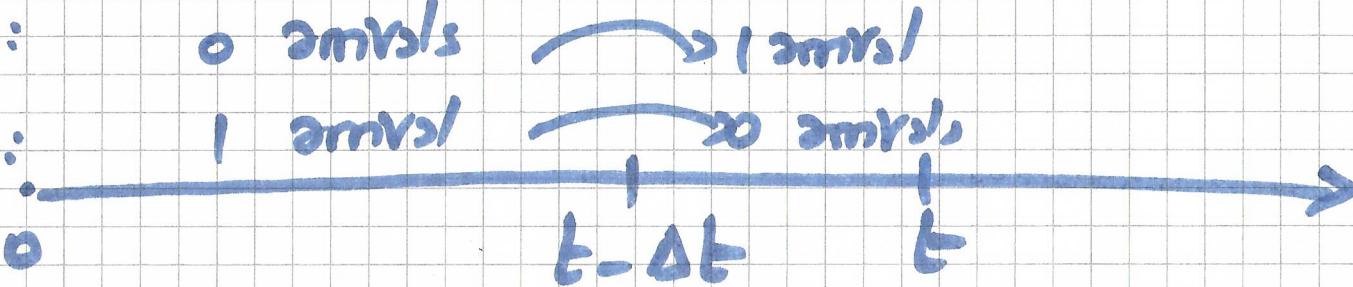
$$\Rightarrow \boxed{P_0(t) = P[N(t) = 0] = e^{-\lambda t}}$$

. Let us focus on

$$\mathbb{P}[N(t) = 1] \stackrel{\Delta}{=} P_1(t)$$

Event 1:

Event 2 :



These two events are mutually exclusive

So we can write

$$P_1(t) = \mathbb{P}[N(t - \Delta t) = 0 \text{ and } N(t) - N(t - \Delta t) = 1]$$

$$+ \mathbb{P}[N(t - \Delta t) = 1 \text{ and } N(t) - N(t - \Delta t) = 0]$$

↓ Axiom 2
independence

$$= P[N(t-\Delta t) = 0] \cdot P[N(t) - N(t-\Delta t) = 1]$$

$$+ P[N(t-\Delta t) = 1] \cdot P[N(t) - N(t-\Delta t) = 0]$$

\downarrow Axiom 2
stationarity

$$= P[N(t-\Delta t) = 0] \cdot P[N(t+\Delta t) - N(t) = 1]$$

$$+ P[N(t-\Delta t) = 1] \cdot P[N(t+\Delta t) - N(t) = 0]$$

\downarrow Axiom 3

$$\Rightarrow P_1(t) = P_0(t-\Delta t) \cdot \lambda \Delta t +$$

$$P_1(t-\Delta t) \cdot (1 - \lambda \Delta t)$$

$$\frac{P_1(t) - P_1(t-\Delta t)}{\Delta t} = -\lambda P_1(t-\Delta t) + \lambda P_0(t-\Delta t)$$

$$\downarrow \Delta t \rightarrow 0$$

$$\boxed{\frac{d P_1(t)}{dt} + \lambda P_1(t) = \lambda P_0(t)}$$

More generally, and using the same steps we can show by induction that

$P_k(t) \stackrel{?}{=} P[N(t) \leq k]$ follows a similar differential equation:

$$\frac{d P_k(t)}{dt} + \lambda P_k(t) = \lambda P_{k-1}(t)$$

for $k=1, 2, 3, \dots$

and with $P_0(t) = e^{-\lambda t}$

→ we can solve this set of differential equations recursively and get:

$$P_k(t) = P[N(t) = k] = \frac{(\lambda t)^k}{k!} e^{-\lambda t}$$

for $k=0, 1, 2, \dots$

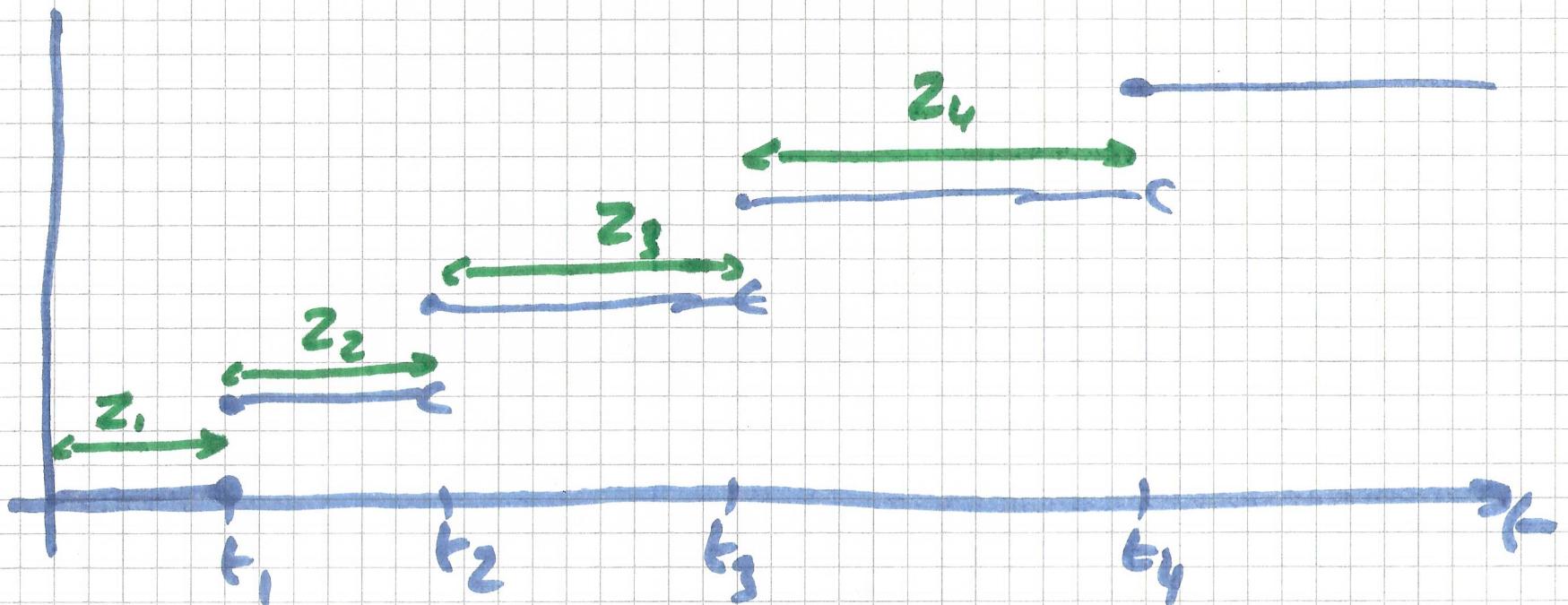
Note that

$E[N(t)] = \lambda t$ function of time \Rightarrow
 $N(t)$ is NOT WSS

$\lambda = \frac{E[N(t)]}{t}$: Average number of
arrivals per second =
rate of the Poisson Rp.

10.6. C Interval Times

Consider a typical realization of $N(t)$



→ the times t_1, t_2, t_3, \dots are called
the arrival times.

→ The time intervals

$$\left. \begin{array}{l} z_1 = t_1 - 0 \\ z_2 = t_2 - t_1 \end{array} \right\} z_3 = t_3 - t_2$$

$$\left. \begin{array}{l} \\ z_4 = t_4 - t_3 \end{array} \right\} \dots$$

5)

.. $Z_n = t_n - t_{n-1}$ are called
the interval times.

Theorem

The interval times Z_1, Z_2, \dots, Z_k
are i. i. d R.V's with each
having an exponential distribution with
parameter λ .

i.e

$$\textcircled{1} \quad f_{Z_k}(z_k) = \begin{cases} \lambda e^{-\lambda z_k} & z_k \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

for $k=1, 2, 3, \dots$

with $E[Z_k] = \frac{1}{\lambda}$

$$\text{Var}[Z_k] = \frac{1}{\lambda^2}$$

2') $f_{Z_1, Z_2, \dots, Z_K}(z_1, z_2, \dots, z_K) = \prod_{k=1}^K f_{Z_k}(z_k) = \lambda^K e^{-\lambda \sum_{k=1}^K z_k}$
 $\lambda \geq 0 \quad z_k \geq 0 \quad \Rightarrow \quad z_k \geq 0$

10.6. d Arrival Times

→ The k^{th} arrival time T_{1k} is defined as the time for $t=0$ until the k^{th} arrival time (i.e. waiting time until the k^{th} arrival)

$$T_k = \sum_{i=1}^k z_i$$

- $z_i \sim \text{Exp}(\lambda)$
- z_i 's are independent

Thus

T_k is the sum of k i.i.d

$\text{Exp}(\lambda)$ RVs



T_k follows a Gamma distribution
given by

$$f_{T_k}(t) = \frac{\lambda^k}{(k-1)!} t^{k-1} e^{-\lambda t} \quad t > 0$$

Proof: Use MGF or C.F approach
for sum of i.i.d RVs.

Remarks:

1. Mean

$$\begin{aligned}
 E[\tau_k] &= E[z_1 + z_2 + \dots + z_k] \\
 &= E[z_1] + E[z_2] + \dots + E[z_k] \\
 &\quad \text{---} \quad \text{---} \quad \text{---} \\
 &= \frac{1}{k} \sum_{i=1}^k E[z_i]
 \end{aligned}$$

$$E[\tau_k] = \frac{1}{k} \sum_{i=1}^k E[z_i]$$

2. Variance

$$\text{Var}(\tau_k) = \text{Var}(z_1 + z_2 + \dots + z_k)$$

The Z_i 's are independent \Rightarrow uncorrelated 20/1

$$\text{Var}(T_k) = \sum_{i=1}^k \text{Var}(Z_i)$$

\Downarrow

$$\boxed{\text{Var}(T_k) = \frac{t^2}{\lambda^2}}$$

3. Arrival Times are NOT independent.

In particular

$$T_1 \leq T_2 \leq T_3 \leq \dots$$