

# 07. Statistical Estimation

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# 1 Maximum Likelihood Estimation

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## Parametric distribution estimation

1. Distribution estimation problem: estimate probability density  $p(y)$  of a random variable from observed values
2. Parametric distribution estimation: choose from a family of densities  $p_x(y)$ , indexed by a parameter  $x$

## Maximum Likelihood Estimation

$$\text{maximize (over } x) \quad \log p_x(y)$$

1.  $y$  is observed value
2.  $l(x) = \log p_x(y)$  is called log-likelihood function
3. can add constraints  $x \in C$  explicitly, or define  $p_x(y) = 0$  for  $x \notin C$
4. a convex optimization problem if  $\log p_x(y)$  is concave in  $x$  for fixed  $y$

# 1 Maximum Likelihood Estimation

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## Linear Measurement Model

$$y_i = a_i^T x + v_i, \quad i = 1, \dots, m$$

$x \in \mathbf{R}^n$  is vector of unknown parameters

$v_i$  is IID measurement noise, with density  $p(z)$

$y_i$  is measurement:  $y$  has density  $p_x(y) = \prod_{i=1}^m p(y_i - a_i^T x)$

maximum likelihood estimate: any solution  $x$  of

$$\text{maximize (over } x) \quad l(x) = \sum_{i=1}^m \log p(y_i - a_i^T x)$$

$y$  is observed value

# 1 Maximum Likelihood Estimation

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1. **Gaussian noise**  $\mathcal{N}(0, \sigma^2) : p(z) = (2\pi\sigma^2)^{-1/2} e^{-z^2/(2\sigma^2)}$ ,

$$l(x) = -\frac{m}{2} \log(2\pi\sigma^2) - \frac{1}{2\sigma^2} (a_i^T x - y_i)^2$$

ML estimate is LS solution

2. **Laplacian noise:**  $p(z) = (1/(2a)) e^{-|z|/a}$ ,

$$l(x) = -m \log(2a) - \frac{1}{a} \sum_{i=1}^m |a_i^T x - y_i|$$

ML estimate is 1-norm solution

3. **uniform noise on  $[-a, a]$ :**

$$l(x) = \begin{cases} -m \log(2a) & |a_i^T x - y_i| \leq a, \quad i = 1, \dots, m \\ -\infty & \text{otherwise} \end{cases}$$

ML estimate is any  $x$  with  $|a_i^T x - y_i| \leq a$

# 1 Maximum Likelihood Estimation

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## Logistic regression

Random variable  $y \in \{0, 1\}$  with distribution

$$p = \mathbf{prob}(y = 1) = \frac{\exp(a^T u + b)}{1 + \exp(a^T u + b)}$$

1.  $a, b$  are parameters;  $u \in \mathbf{R}^n$  are (observable) explanatory variables
  2. Estimation problem: estimate  $a, b$  from  $m$  observations  $(u_i, y_i)$
- log-likelihood function ( for  $y_1 = \dots = y_k = 1, y_{k+1} = \dots = y_m = 0$ ):

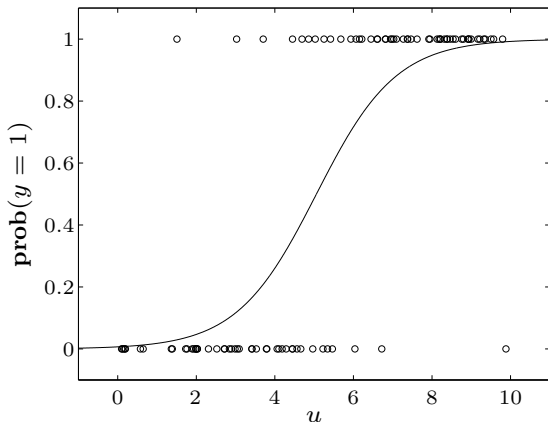
$$\begin{aligned} l(a, b) &= \log \left( \prod_{i=1}^k \frac{\exp(a^T u_i + b)}{1 + \exp(a^T u_i + b)} \prod_{i=k+1}^m \frac{1}{1 + \exp(a^T u_i + b)} \right) \\ &= \sum_{i=1}^k (a^T u_i + b) - \sum_{i=1}^m \log(1 + \exp(a^T u_i + b)) \end{aligned}$$

concave in  $a, b$

# 1 maximum likelihood estimation

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example ( $n = 1$ ,  $m = 50$  measurements)



circles show 50 points  $(u_i, y_i)$

solid curve is ML estimate of  $p = \exp(au + b) / (1 + \exp(au + b))$

## 2 Optimal Detector Design

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### (Binary) hypothesis testing

detection (hypothesis testing) problem

given observation of a random variable  $X \in \{1, \dots, n\}$ , choose between:

1. hypothesis 1:  $X$  was generated by distribution  $p = (p_1, \dots, p_n)$
2. hypothesis 2:  $X$  was generated by distribution  $q = (q_1, \dots, q_n)$

### Randomized detector

a nonnegative matrix  $T \in \mathbf{R}^{2 \times n}$ , with  $\mathbf{1}^T T = \mathbf{1}^T$

if we observe  $X = k$ , we choose hypothesis 1 with probability  $t_{1k}$ ,  
hypothesis 2 with probability  $t_{2k}$

if all elements of  $T$  are 0 or 1, it is called a deterministic detector

## 2 Optimal Detector Design

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**detection probability matrix:**

$$D = [Tp \ Tq] = \begin{bmatrix} 1 - P_{\text{fp}} & P_{\text{fn}} \\ P_{\text{fp}} & 1 - P_{\text{fn}} \end{bmatrix}$$

1.  $P_{\text{fp}}$  is probability of selecting hypothesis 2 if  $X$  is generated by distribution 1 (false positive)
2.  $P_{\text{fn}}$  is probability of selecting hypothesis 1 if  $X$  is generated by distribution 2 (false negative)

**multicriterion formulation of detector design**

$$\begin{array}{ll} \text{minimize (w.r.t. } \mathbf{R}_+^2) & (P_{\text{fp}}, P_{\text{fn}}) = ((Tp)_2, (Tq)_1) \\ \text{subject to} & t_{1k} + t_{2k} = 1, \quad k = 1, \dots, n \\ & t_{ik} \geq 0, \quad i = 1, 2, \quad k = 1, \dots, n \end{array}$$

variable  $T \in \mathbf{R}^{2 \times n}$



## 2 Optimal Detector Design

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scalarization (with weight  $\lambda > 0$ )

$$\begin{array}{ll}\text{minimize} & (Tp)_2 + \lambda(Tq)_1 \\ \text{subject to} & t_{1k} + t_{2k} = 1, \quad t_{ik} \geq 0, \quad i = 1, 2, \quad k = 1, \dots, n\end{array}$$

an LP with a simple analytical solution

$$(t_{1k}, t_{2k}) = \begin{cases} (1, 0) & p_k \geq \lambda q_k \\ (0, 1) & p_k < \lambda q_k \end{cases}$$

A deterministic detector, given by a likelihood ratio test

If  $p_k = \lambda q_k$  for some  $k$ , any value  $0 \leq t_{1k} \leq 1$ ,  $t_{1k} = 1 - t_{2k}$  is optimal (i.e., Pareto-optimal detectors include non-deterministic detectors)

minimax detector

$$\begin{array}{ll}\text{minimize} & \max\{P_{\text{fp}}, P_{\text{fn}}\} = \max\{(Tp)_2, (Tq)_1\} \\ \text{subject to} & t_{1k} + t_{2k} = 1, \quad t_{ik} \geq 0, \quad i = 1, 2, \quad k = 1, \dots, n\end{array}$$

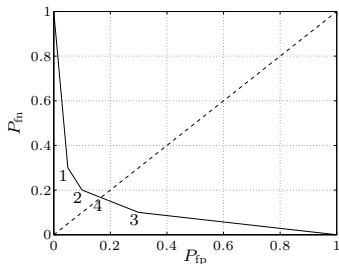
an LP; solution is usually not deterministic

## 2 Optimal Detector Design

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example

$$P = \begin{bmatrix} 0.70 & 0.10 \\ 0.20 & 0.10 \\ 0.05 & 0.70 \\ 0.05 & 0.10 \end{bmatrix}$$



solutions 1, 2, 3 (and endpoints) are deterministic; 4 is minimax detector

### 3 Experiment Design

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$m$  linear measurements  $y_i = a_i^T x + w_i, i = 1, \dots, m$  of unknown  $x \in \mathbf{R}^n$

1. measurement errors  $w_i$  are IID  $\mathcal{N}(0, 1)$
2. ML(least-squares) estimate is

$$\hat{x} = \left( \sum_{i=1}^m a_i a_i^T \right)^{-1} \sum_{i=1}^m y_i a_i$$

error  $e = \hat{x} - x$  has zero mean and covariance

$$E = \mathbf{E} e e^T = \left( \sum_{i=1}^m a_i a_i^T \right)^{-1}$$

confidence ellipsoids are given by  $\{x | (x - \hat{x})^T E^{-1} (x - \hat{x}) \leq \beta\}$

experiment design: choose  $a_i \in \{v_1, \dots, v_p\}$  (a set of possible test vectors) to make  $E$  ‘small’

### 3 Experiment Design

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#### vector optimization formulation

$$\begin{array}{ll}\text{minimize (w.r.t. } \mathbf{S}_+^n) & E = (\sum_{k=1}^p m_k v_k v_k^T)^{-1} \\ \text{subject to} & m_k \geq 0, \quad m_1 + \cdots + m_p = m \\ & m_k \in \mathbf{Z}\end{array}$$

1. variables are  $m_k$  ( $\neq$  vectors  $a_i$  equal to  $v_k$ )
2. difficult in general, due to integer constraint

#### relaxed experiment design

assume  $m \gg p$ , use  $\lambda_k = m_k/m$  as (continuous) real variable

$$\begin{array}{ll}\text{minimize (w.r.t. } \mathbf{S}_+^n) & E = (1/m) (\sum_{k=1}^p \lambda_k v_k v_k^T)^{-1} \\ \text{subject to} & \lambda \succeq 0, \quad \mathbf{1}^T \lambda = 1\end{array}$$

common scalarizations: minimize  $\log \det E$ ,  $\mathbf{tr} E$ ,  $\lambda_{\max}(E)$ ,...

can add other convex constraints, e.g., bound experiment cost  
 $c^T \lambda \leq B$

## 3 Experiment Design

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### D-optimal design

$$\begin{array}{ll}\text{minimize} & \log \det \left( \sum_{k=1}^p \lambda_k v_k v_k^T \right)^{-1} \\ \text{subject to} & \lambda \succeq 0, \mathbf{1}^T \lambda = 1\end{array}$$

interpretation: minimizes volume of confidence ellipsoids

### dual problem

$$\begin{array}{ll}\text{maximize} & \log \det W + n \log n \\ \text{subject to} & v_k^T W v_k \leq 1, \quad k = 1, \dots, p\end{array}$$

interpretation:  $\{x|x^T W x \leq 1\}$  is minimum volume ellipsoid centered at origin, that includes all test vectors  $v_k$

**complementary slackness: for  $\lambda, W$  primal and dual optimal**

$$\lambda_k (1 - v_k^T W v_k) = 0, \quad k = 1, \dots, p$$

optimal experiment uses vectors  $v_k$  on boundary of ellipsoid defined by  $W$