



Squeezing Operator Performance Potential for the Ascend Architecture

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Outline



- Introduction
- System Design
- Case Study
- Evaluation
- Conclusion

Outline



 Introduction

 System Design

 Case Study

 Evaluation

 Conclusion

AI Domain-Specific Architecture (DSA)

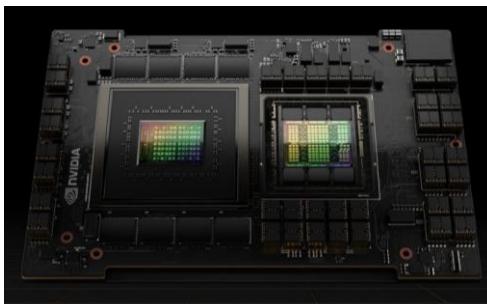


Deep learning models



Better arithmetic support

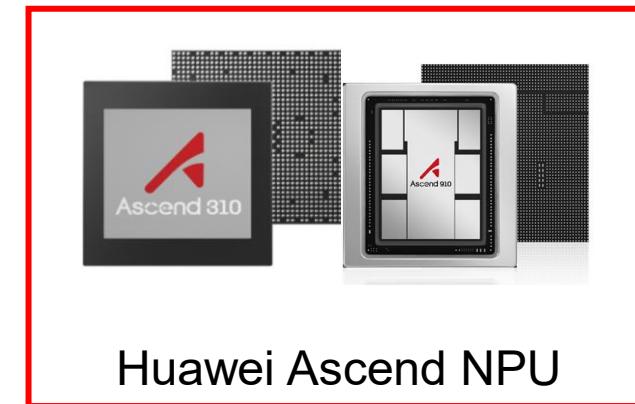
Domain-specific architecture



NVIDIA GPU



Google TPU



Huawei Ascend NPU

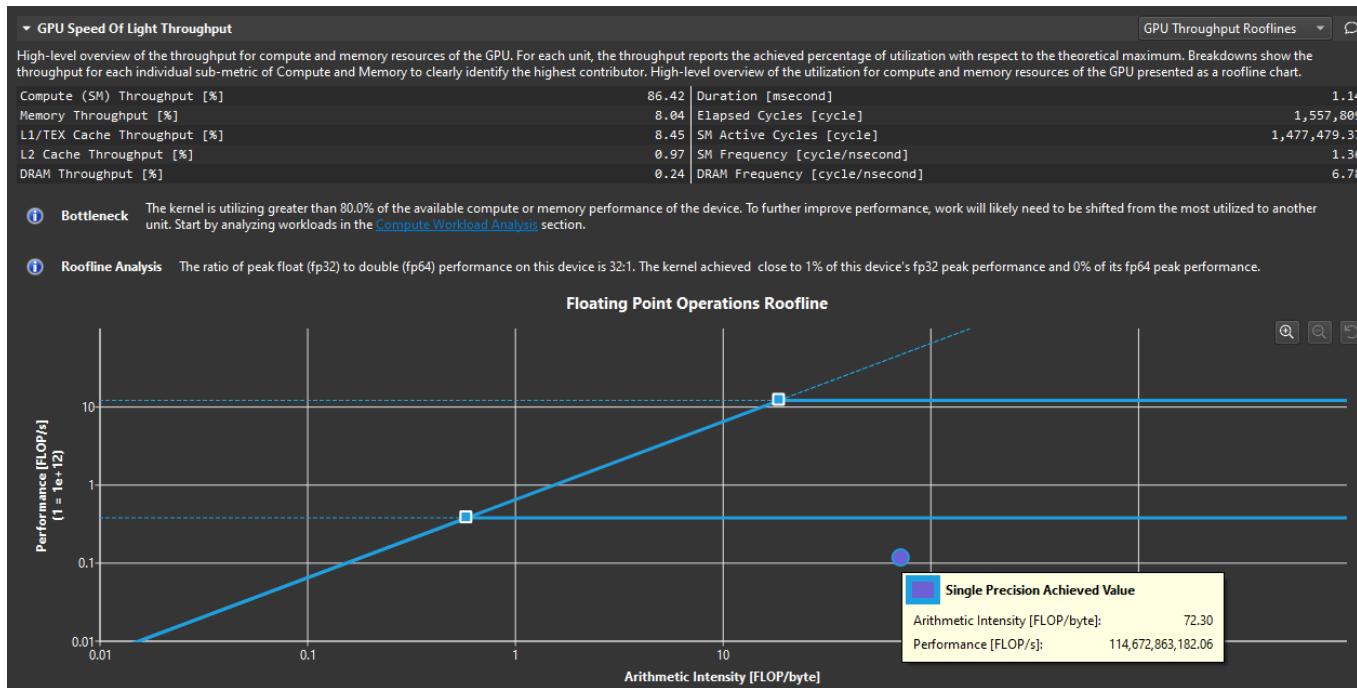


Cambricon MLU

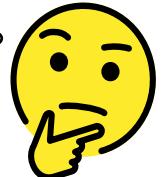




Operator Optimization Needs Profiling

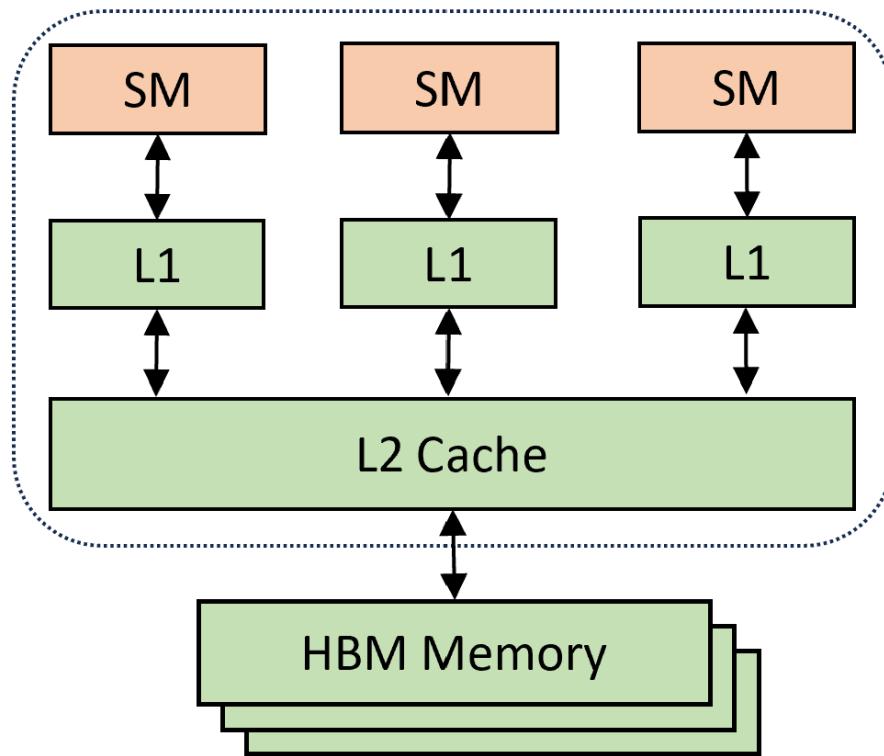


*What about
Ascend?*

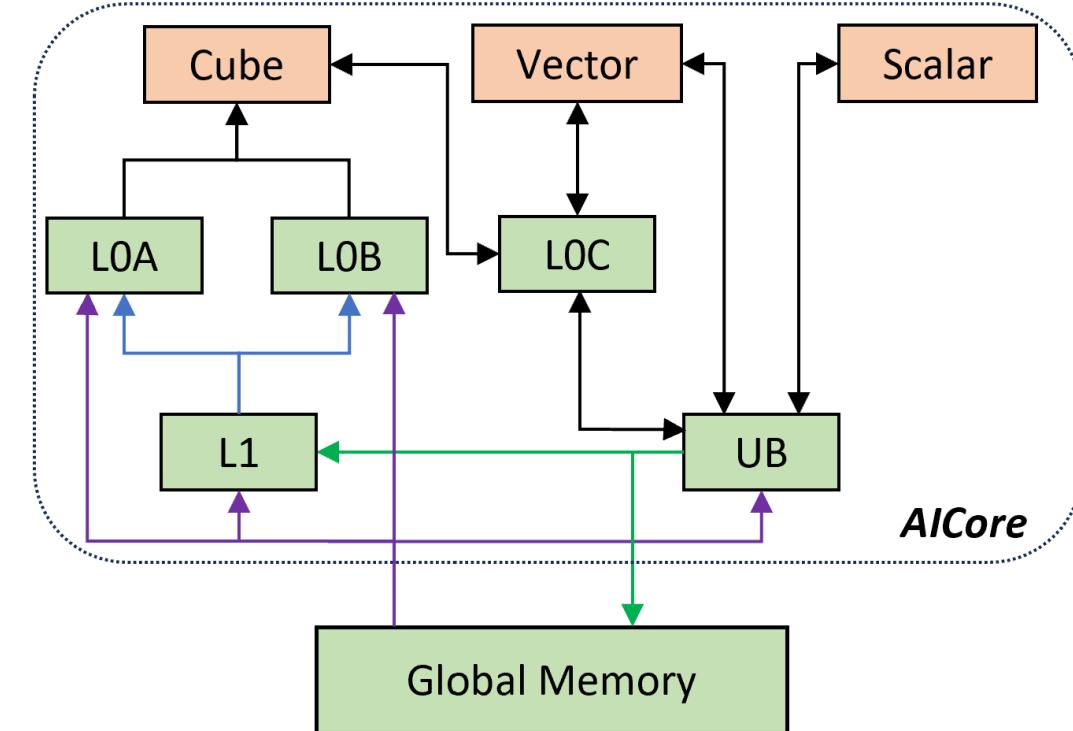




Ascend Architecture



GPU (NVIDIA)



NPU (Ascend)

Compute Unit Memory Unit

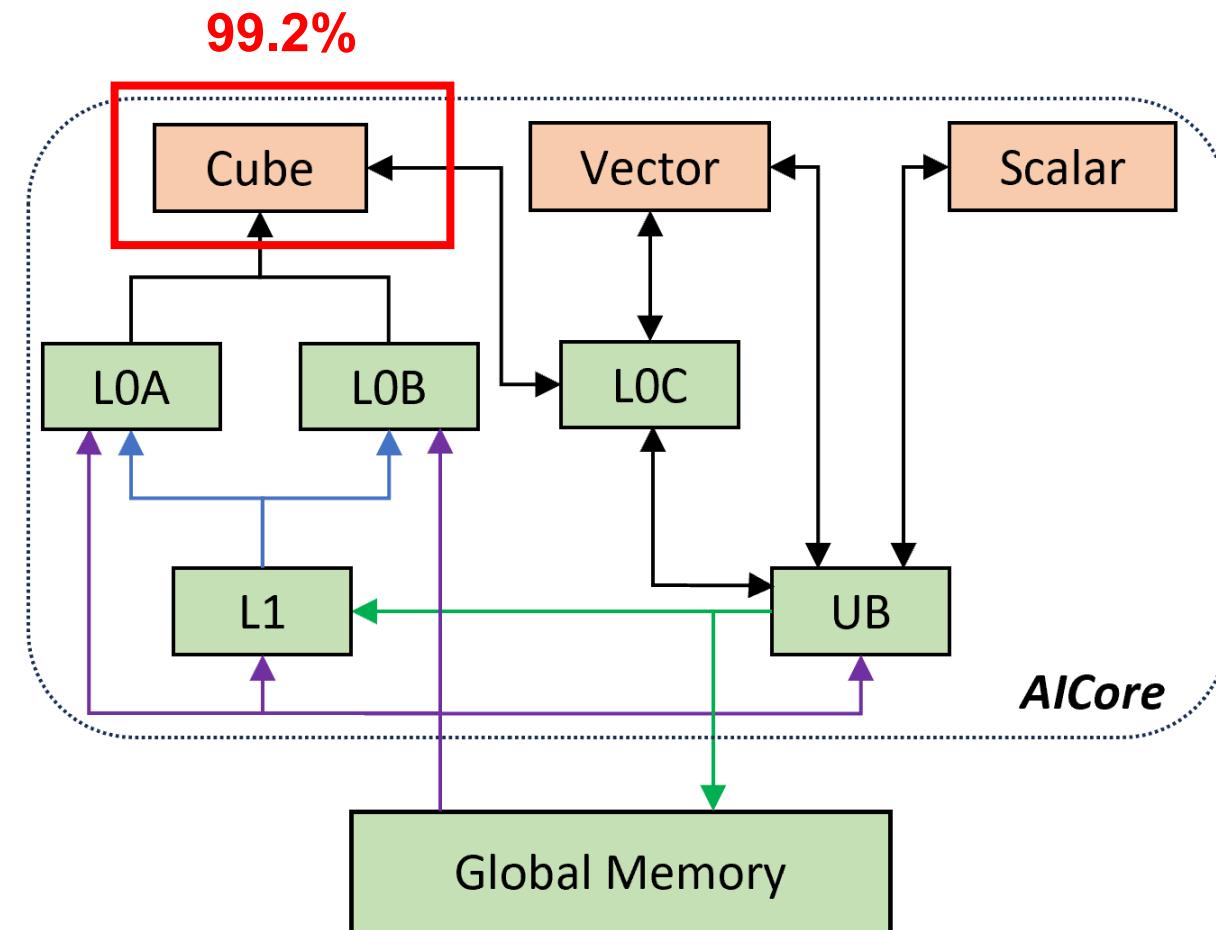


Dedicated Compute Units

Transformer computation

~10%
 (Pooling,
 Relu)

~90%
 (MatMul, Convolution,
 Fully connected)



Computing precision

Cube: INT8/FP16

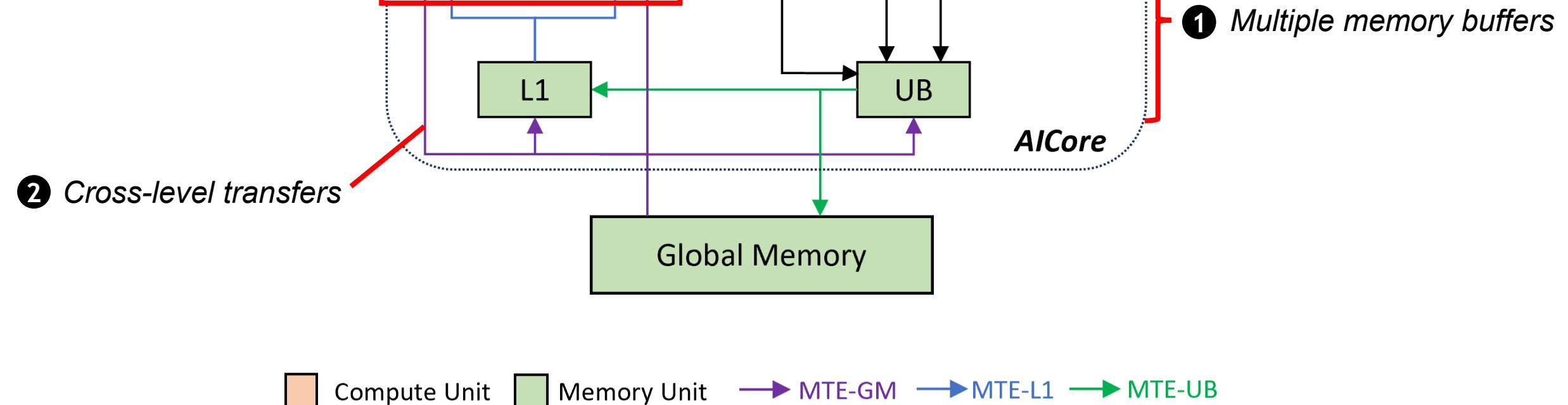
Vector: INT8/FP16/FP32

Scalar: INT32/FP32/...



Customized Memory Architecture

③ Asymmetric bandwidth



Compute Unit



Memory Unit

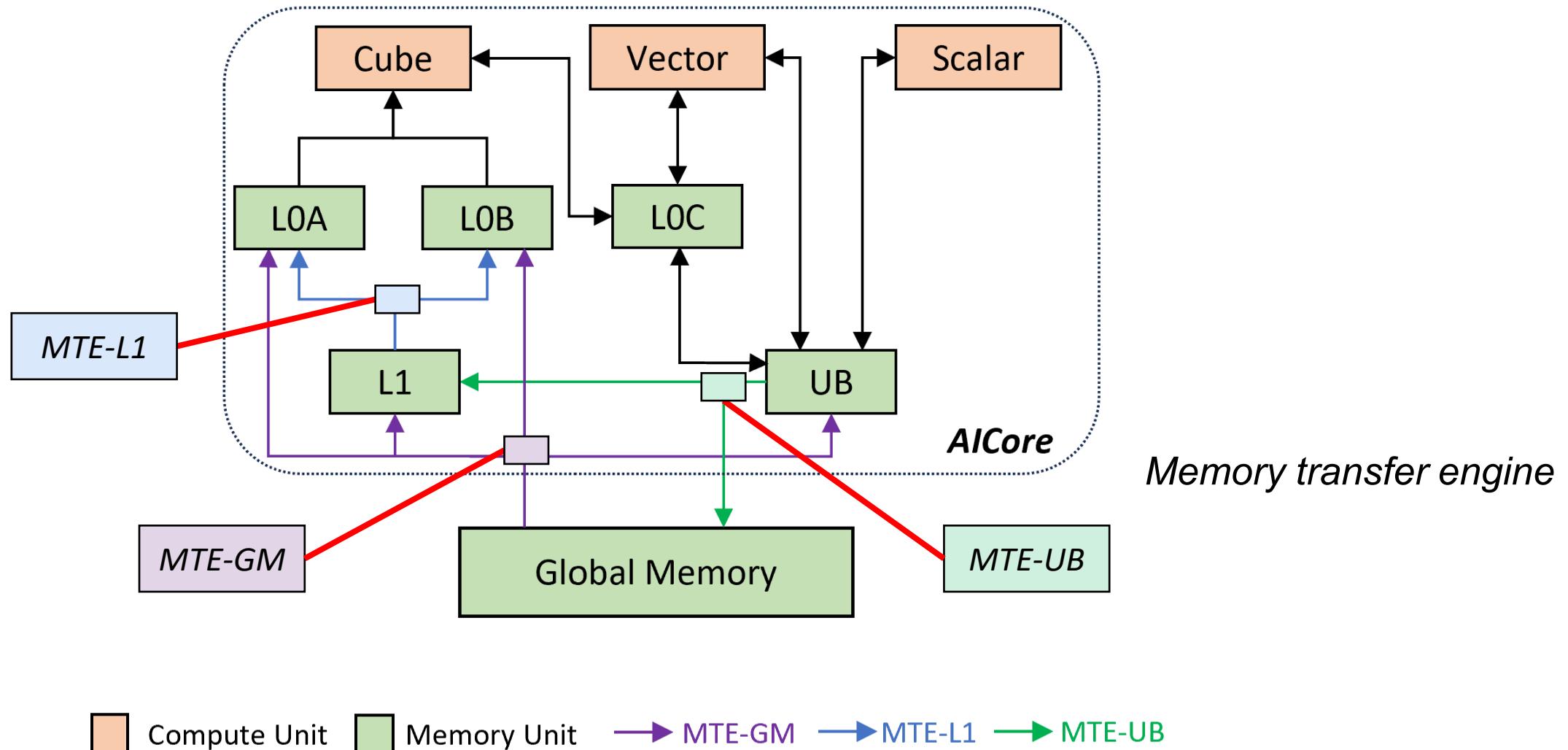
→ MTE-GM

→ MTE-L1

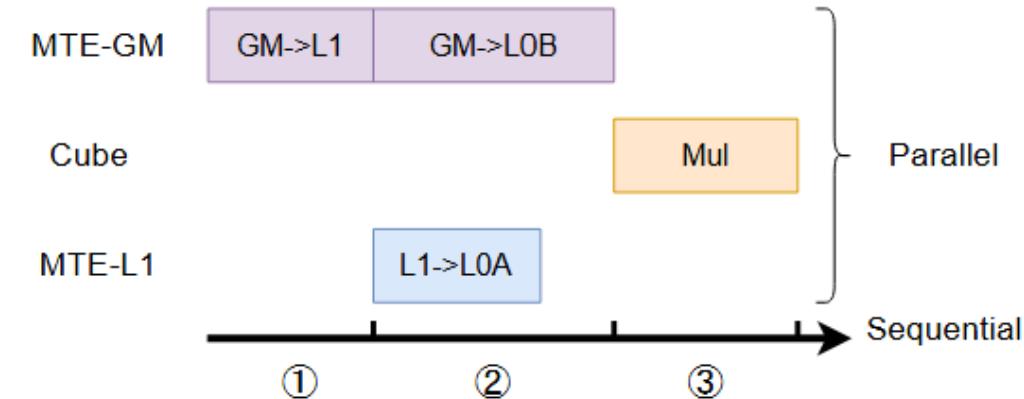
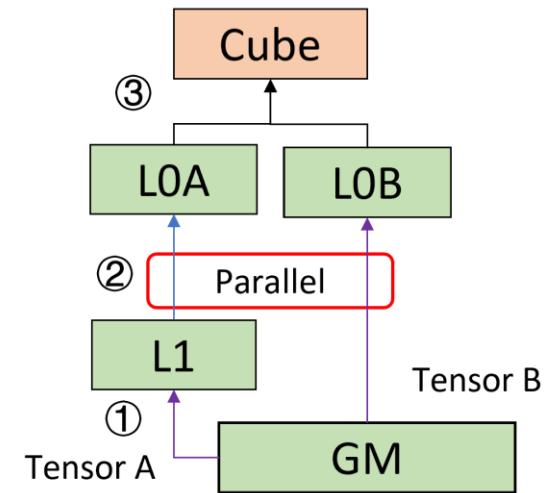
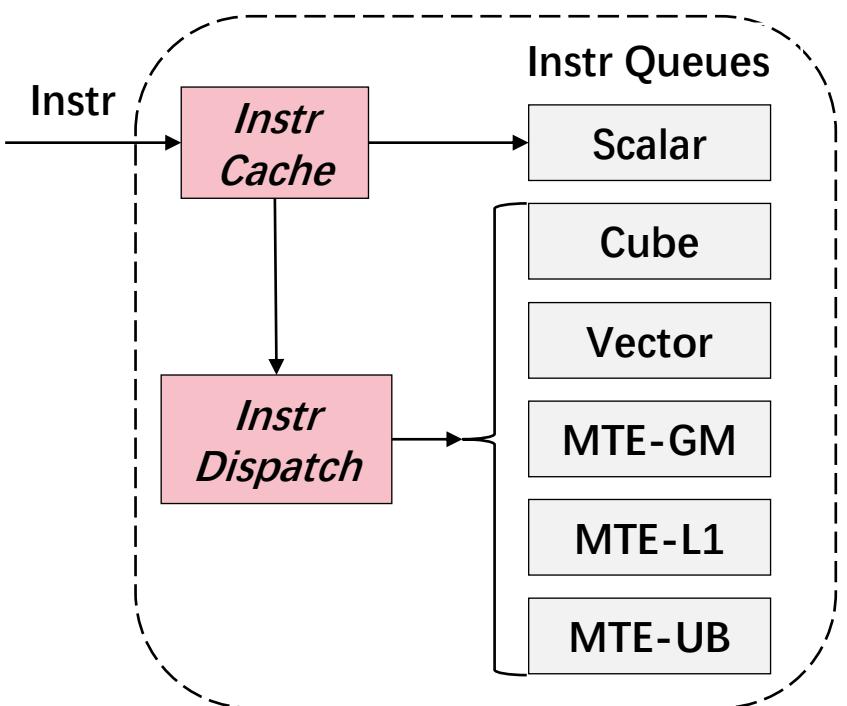
→ MTE-UB



Efficient Transfer Control Units



Instruction Pipeline



Example of matrix multiplication $A \times B$

Inter parallelism, intra serialism.





Summary of Ascend Architecture

Pros

Ascend Architecture

Cons

Dedicated compute units

Accurately identifying operator bottleneck is a challenging, but essential task!

Operational flexibility

Efficient transfer control and instruction pipeline

Inputting

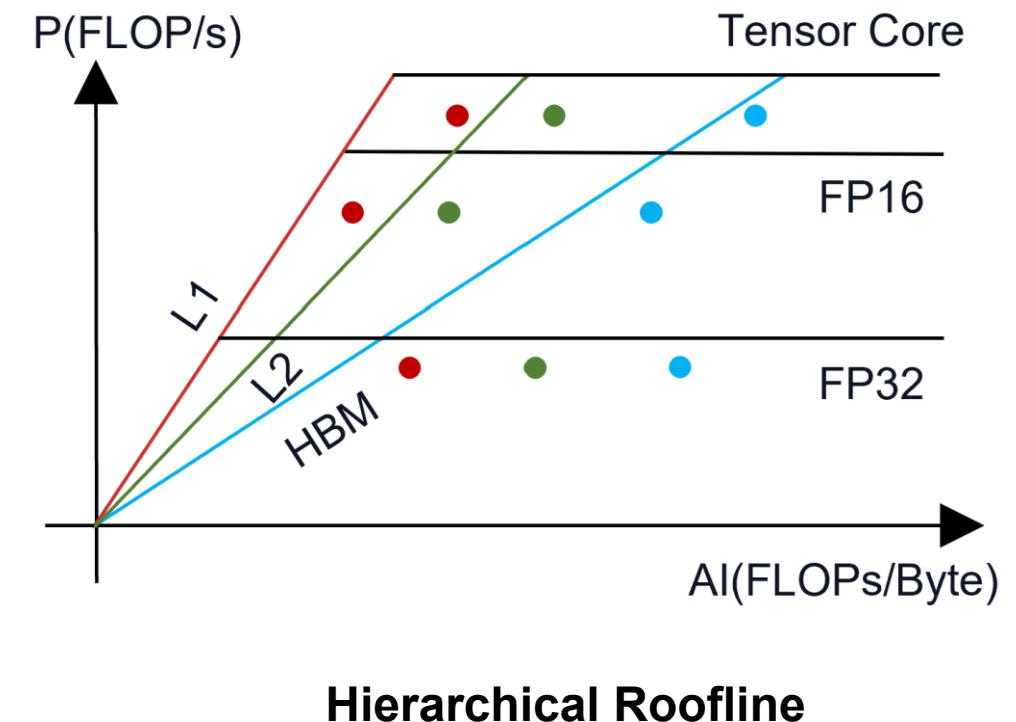
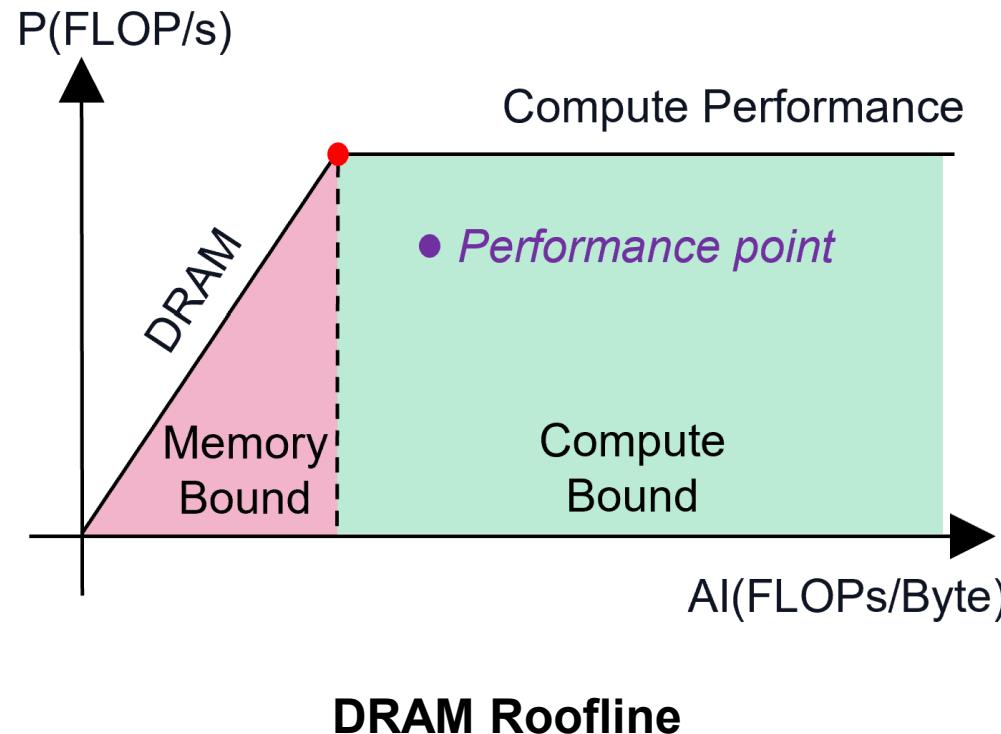
LTE

Pipeline

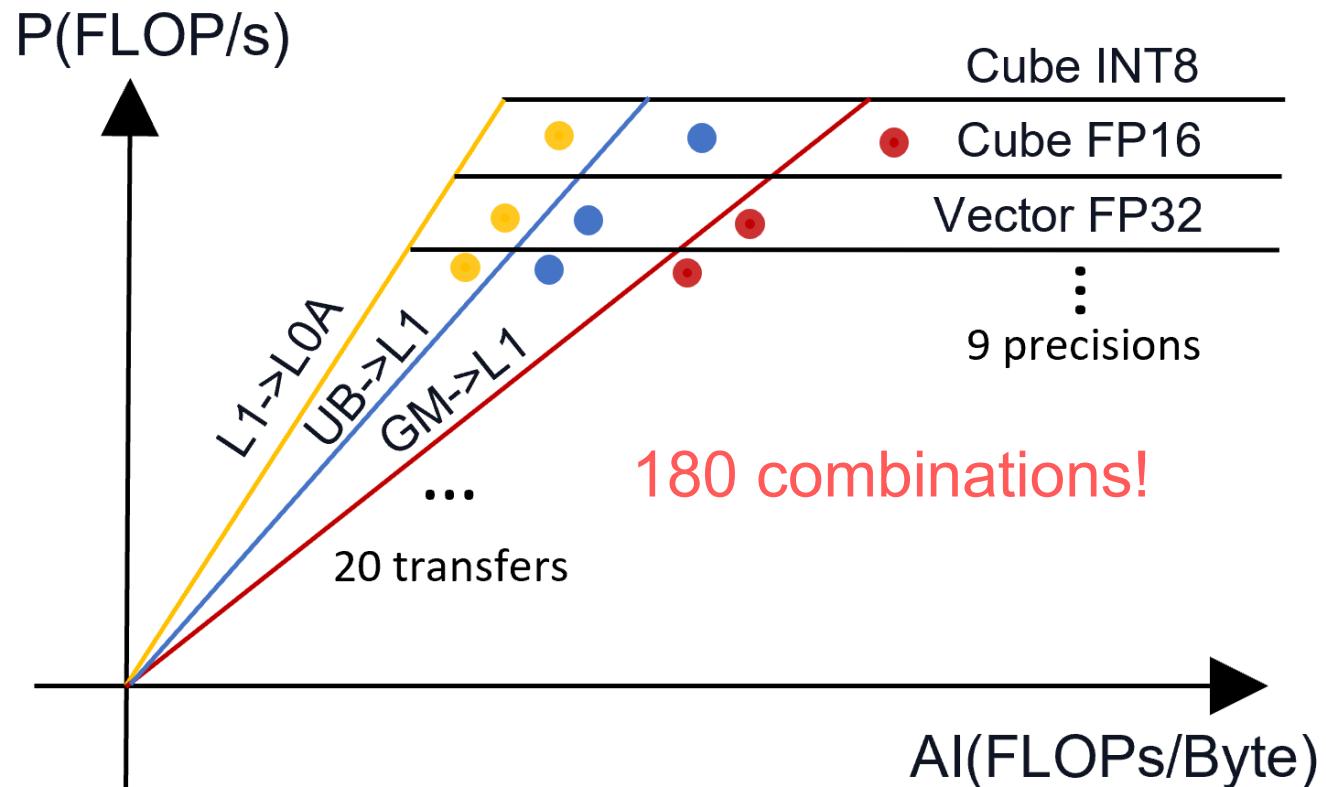
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Existing Operator Performance Analysis



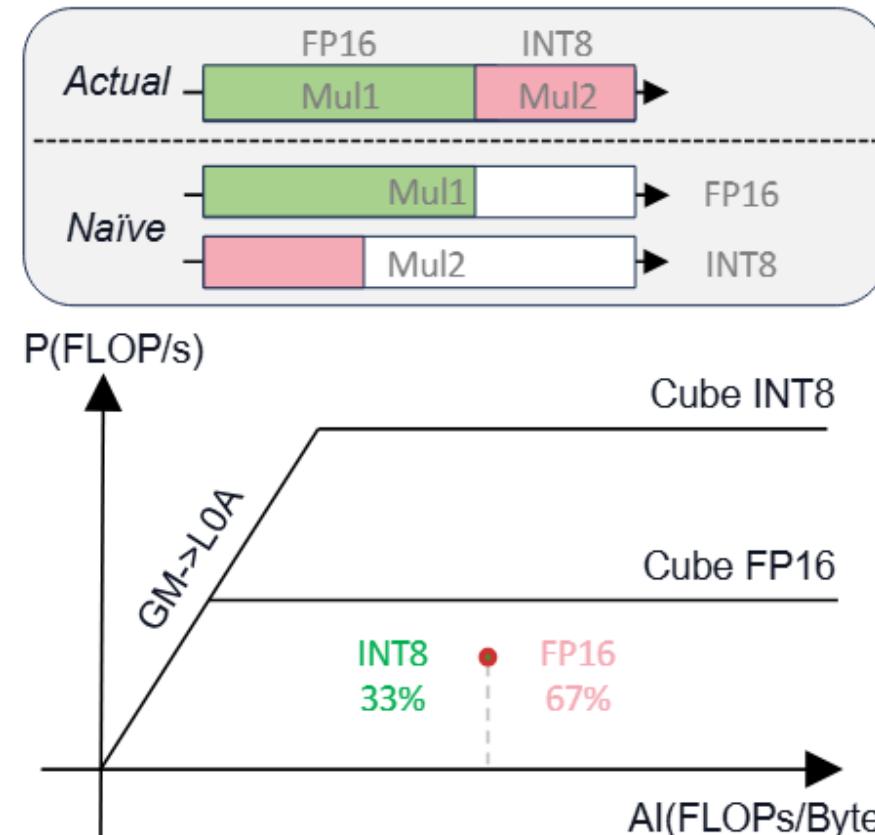
Limitations of Performance Analysis



(i) Massive combinations between precisions and transfers



Limitations of Performance Analysis



Underutilization?

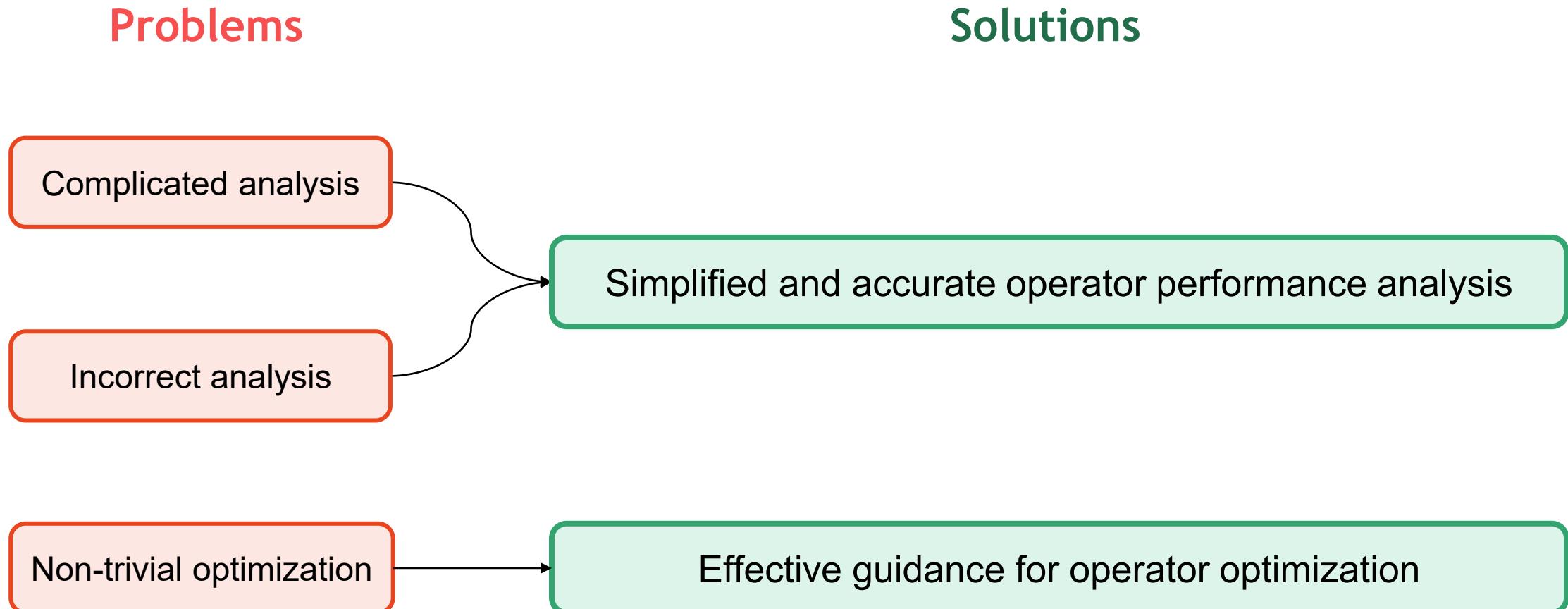


(ii) Incorrect analysis by ignoring the sequential execution





Our Goals

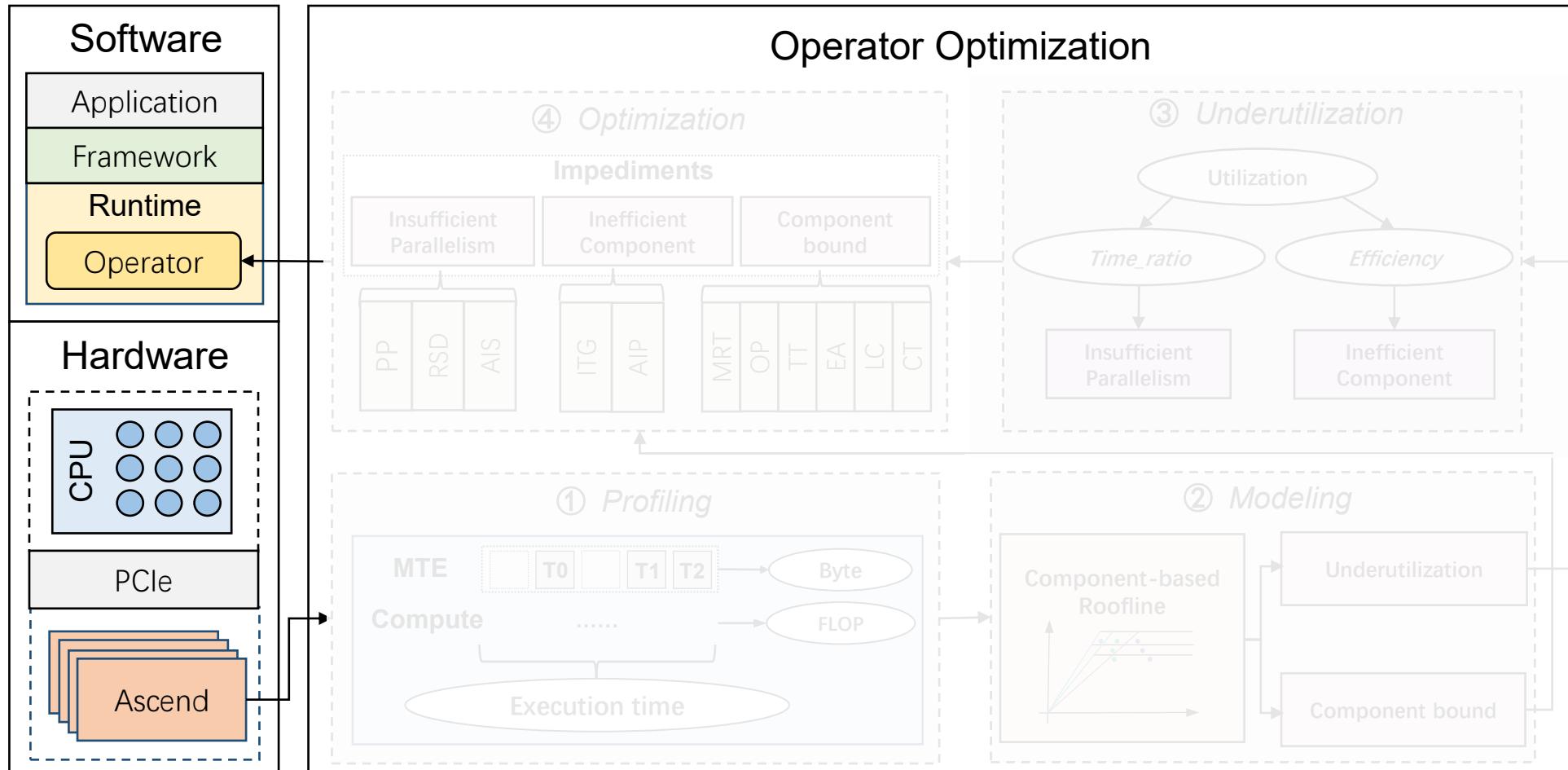


Outline



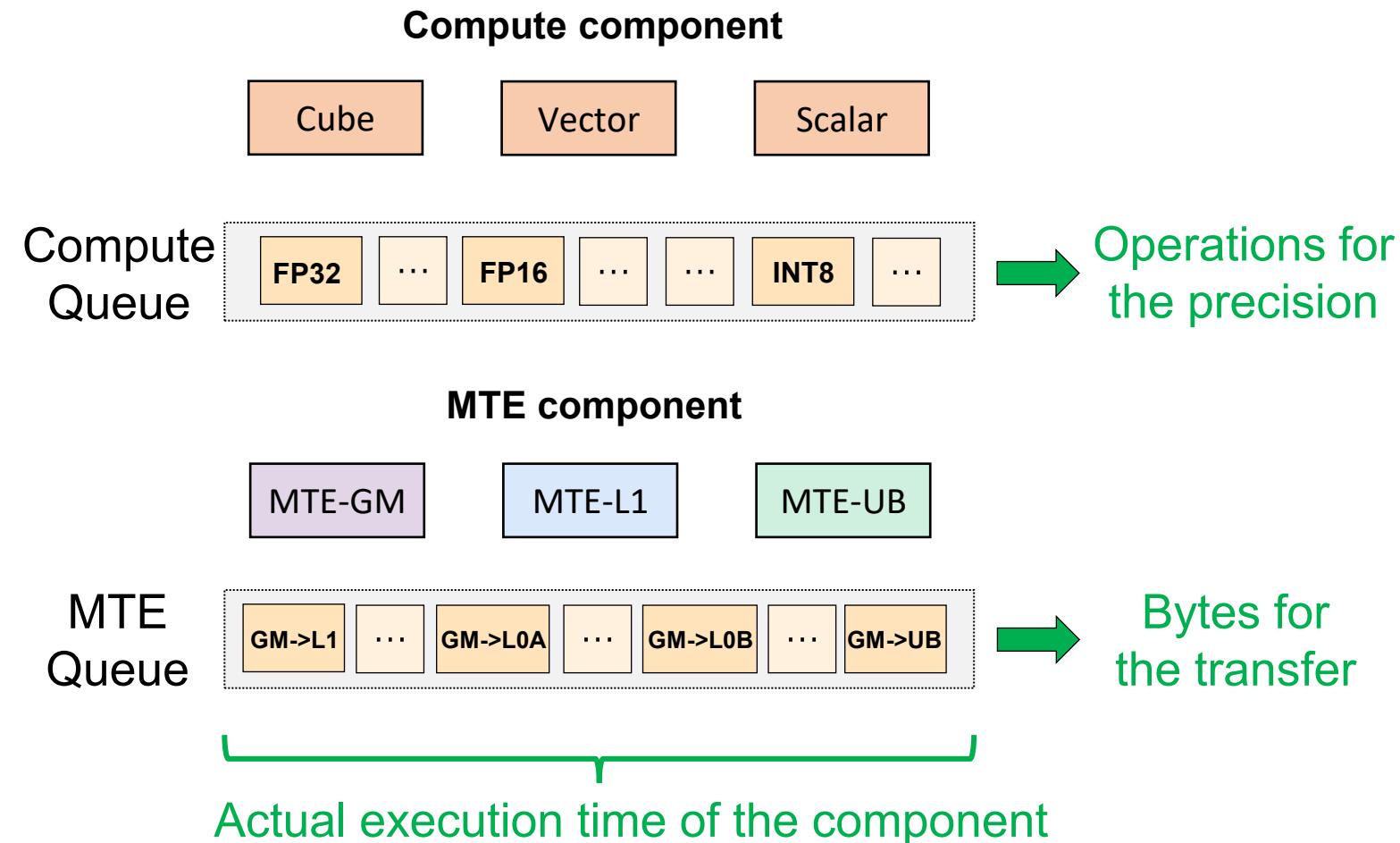
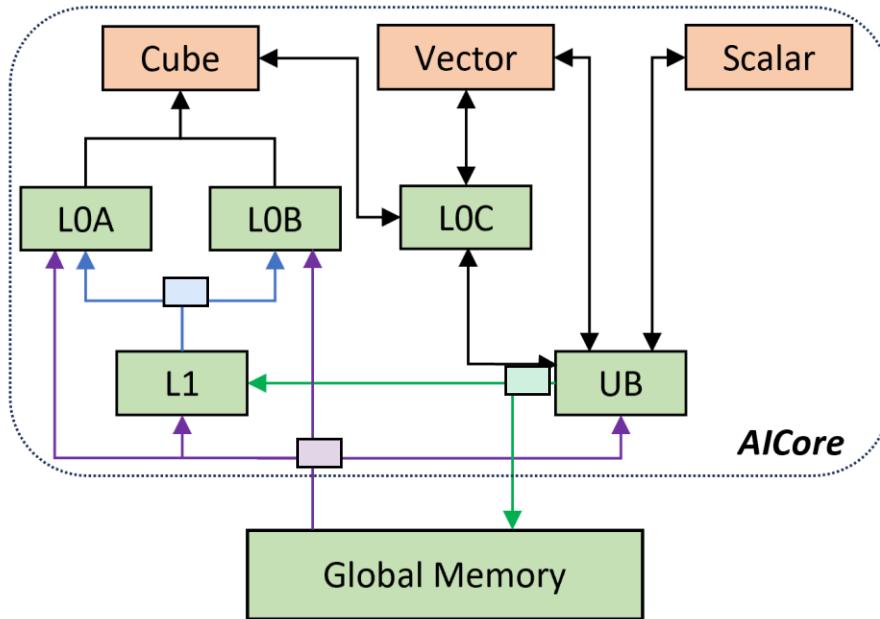
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Overview

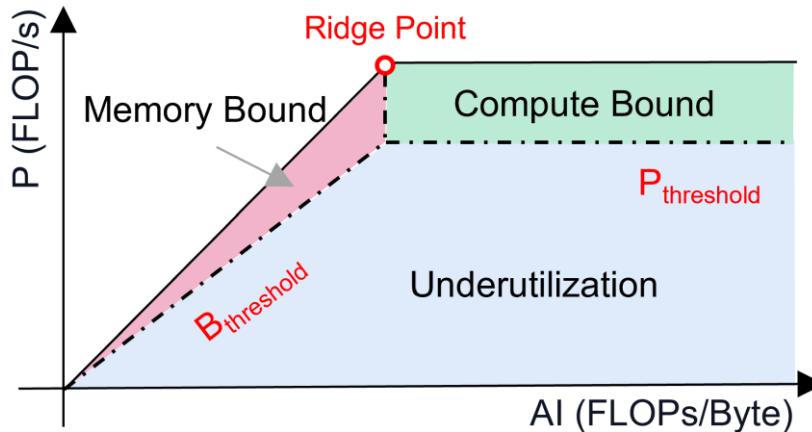




Profiling and Component Abstraction



Component-based Roofline Model



Utilization of component can reflect the operator's bottleneck.

Operator-aware ideal performance

$$U_{cube} = \frac{A_{cube}}{I_{cube}} \quad \begin{cases} A_{cube} = \frac{O_{cube}}{T_{total}} \\ I_{cube} \end{cases} \quad \begin{array}{l} \text{Profiling} \\ \text{Different precisions?} \end{array}$$

$$I_{cube} = \frac{\sum_{\text{prec}} O_{\text{prec}}}{\sum_{\text{prec}} \frac{O_{\text{prec}}}{P_{\text{prec}}}} \quad \begin{array}{l} \text{Harmonic Mean} \\ \text{Arithmetic Power} \end{array}$$

Underutilization Analysis

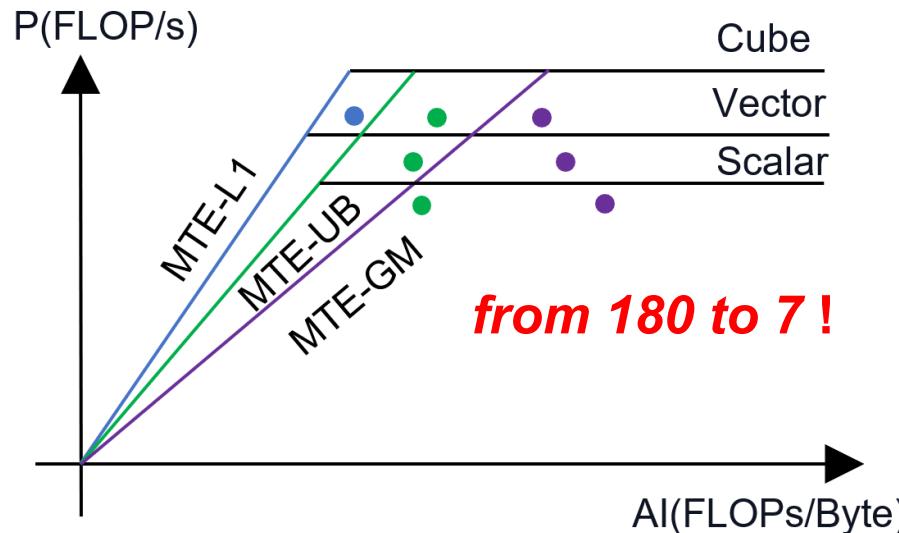
$$\textcircled{1} \quad U_{cube} = \frac{A_{cube}}{I_{cube}} = \underbrace{\frac{O_{cube}}{T_{cube} \cdot I_{cube}}}_{E_{cube}} \cdot \underbrace{\frac{T_{cube}}{T_{total}}}_{R_{cube}}$$

$$\textcircled{2} \quad E_{\text{component}} \leq \frac{R_{\text{threshold}}}{U_{\text{threshold}}} \quad \begin{array}{l} \downarrow \\ \text{Inefficient Component} \end{array} \quad \begin{array}{l} \downarrow \\ R_{\text{component}} < R_{\text{threshold}} \end{array} \quad \begin{array}{l} \downarrow \\ \text{Insufficient Parallelism} \end{array}$$



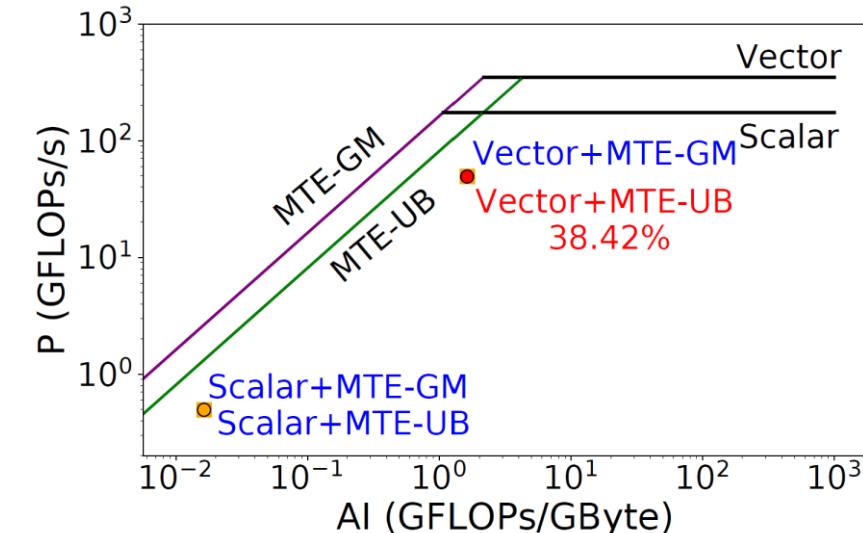
Pruning, Visualization and Analysis

Pruning results



- ✓ Component abstraction
- ✓ Remove irrelevant components
- ✓ Remove impossible combinations

Roofline Analysis of Add_ReLU Operator



$U_{component}$ of Vector+MTE-UB (38.42%):
Underutilization

$R_{component}$ of MTE-GM (58.68%):
Insufficient parallelism



Outline

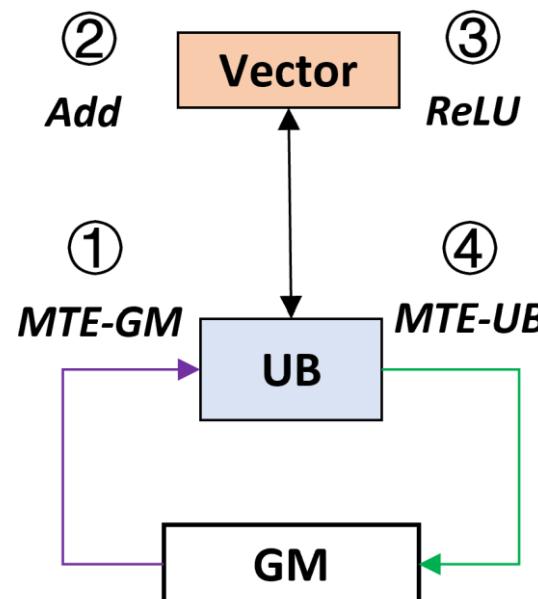


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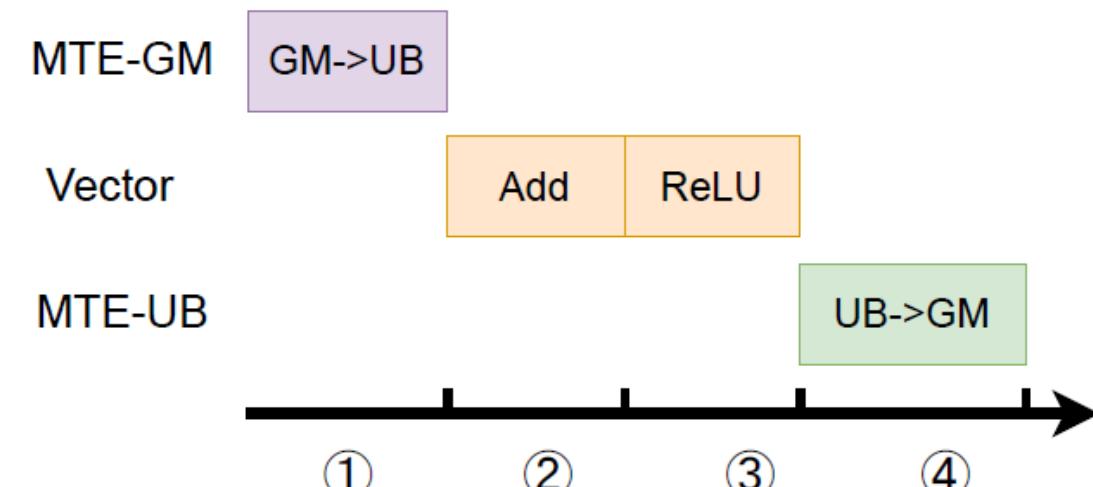


Case Study: Optimization of Add_ReLU Operator

$$\text{Add_ReLU}(x) = \text{ReLU}(x + c)$$



Data flow



Instruction timeline



Iteration 1: Reducing spatial dependency

Original Code

```

① ...
② ub_to_gm(gm_1, ub_1);
③ gm_to_ub(ub_1, gm_2);
④ ...

```

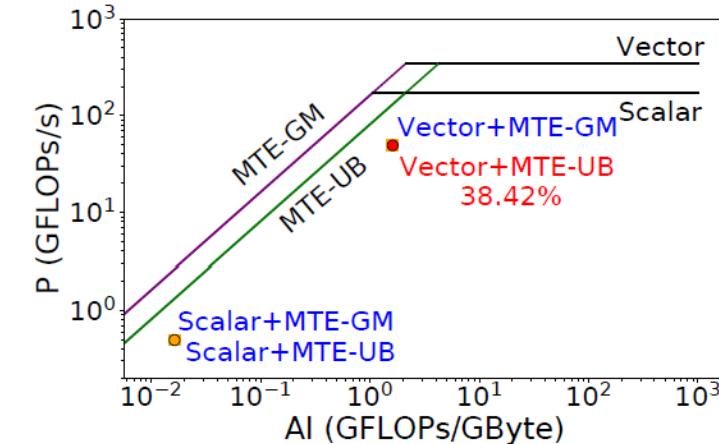


Optimized Code

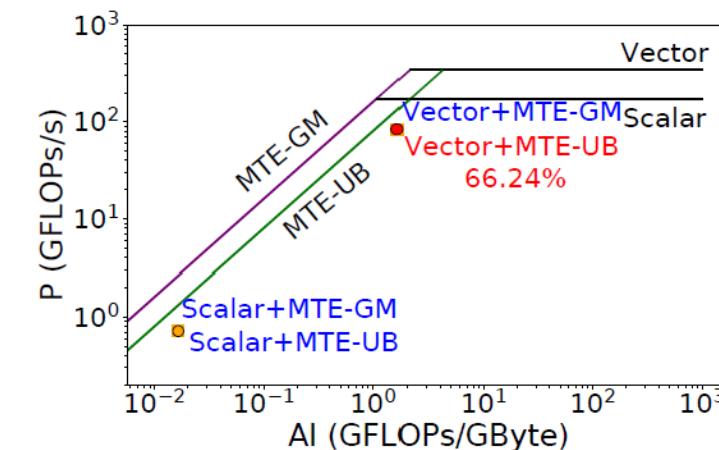
```

① ...
② ub_to_gm(gm_1, ub_2);
③ gm_to_ub(ub_1, gm_2);
④ ...

```



Insufficient parallelism
(38.42%)



MTE-UB bound
(66.24%)

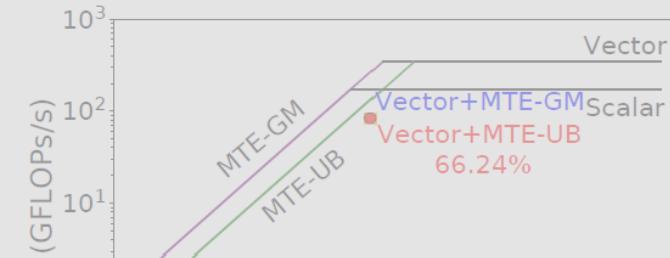




Iteration 2: Minimizing redundant transfer

Original Code

```
① for i = 1 to n do  
②   gm_to_ub(ub_1, c);  
③   ...
```



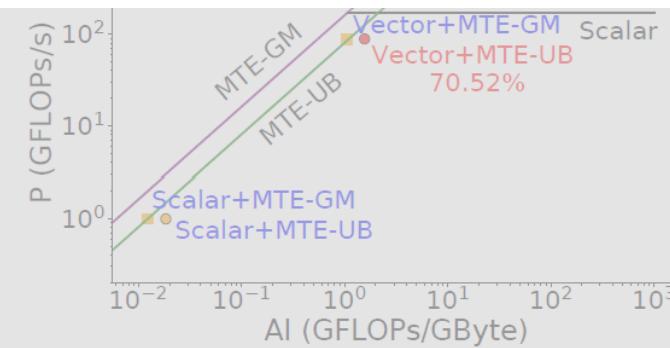
MTE-UB bound
(66.24%)

The single operator time reduced by **1.73x**.

The *component_utilization* up by **32.1%**.

The total inference latency down by **244.261 μs**.

```
① gm_to_ub(ub_1, c);  
② for i = 1 to n do  
③   ...  
④ end for
```



MTE-UB bound
(70.52%)





Optimization Experience

We summarize the common bottleneck causes and optimization strategies.

Bottleneck Cause	Compute Bound	MTE Bound	Insufficient Parallelism	Inefficient Compute	Inefficient MTE		
Strategy	Operator	Bottleneck Cause and Optimization Strategy					Speedup
		Compute Bound	MTE Bound	Insufficient Parallelism	Inefficient MTE	Inefficient Compute	
	Add_ReLU		MRT	RSD			1.72
	Depthwise		MRT	AIS,RUS,PP	ITG		1.26
	AvgPool					AIP	4.31
	Mul			RSD			1.34
	Conv2D		MRT	RSD			2.65
	FullyConnection				ITG		1.22
	MatMul		OF				1.10
	GeLU	EA					1.06

In MobileNetV3 inference, Our operator optimizations perform well with speedups of **1.06-4.31×**.

More cases can be found in the paper.



Outline

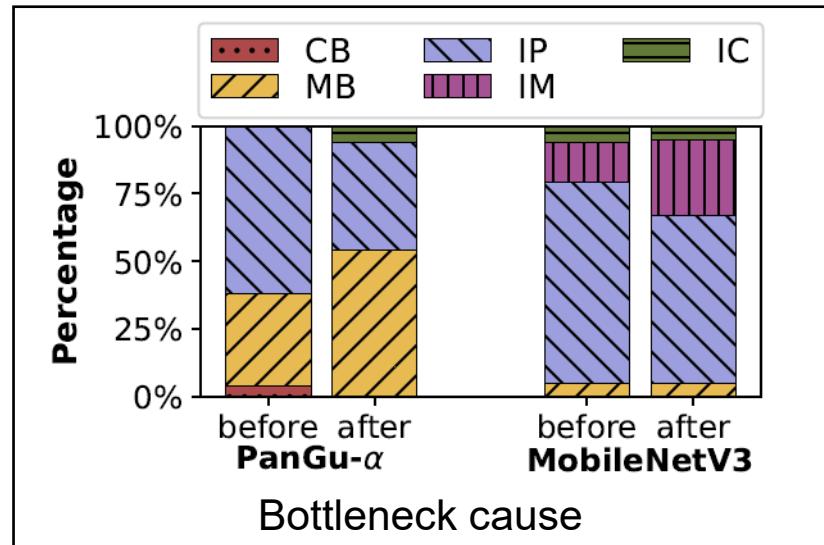


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Evaluation on End-to-End Optimization

Device: Ascend 910 (Training); Ascend 310 (Inference)

Workloads: 100B PanGu- α (Training); MobileNetV3 (Inference)



Training

The ratio of *insufficient parallelism* reduced by **21.38%**.

The *iteration time* speedup is **2.04x**.

Inference

The ratio of *insufficient parallelism* reduced by **11.61%**.

The *total time* speedup is **1.21x**.

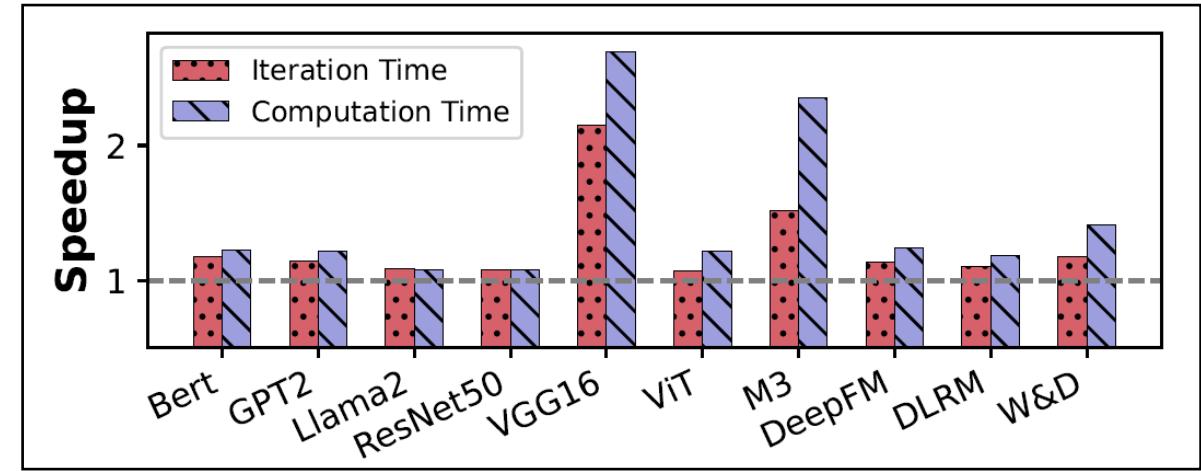




Overall Optimization Results

Type	Model	Parameter	Dataset	#NPUs
Vision	MobileNetV3(M3)	5.4M	ImageNet2012	8
	ResNet50	25.6M		
	ViT	86M		
	VGG16	138.4M		
NLP	Bert	110M	WikiText2	8
	GPT2	355M		
Recommendation	DeepFM	16.5M	Criteo	8
	Wide and Deep(W&D)	75.84M		
	DLRM	540M		
LLM	Llama 2	7B	WikiText2	8
	PanGu- α	100B	1.1TB Chinese Dataset	128

Our optimizations cover 11 different models.



Computation time speedups range from 1.08-2.7x.

Iteration time speedups range from 1.07-2.15x.



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Conclusion

1. We propose a component-based roofline model and underutilization analysis to identify the operator bottlenecks on Ascend.
2. Through in-depth operator optimization case studies, we guide users on how to complete optimization.
3. Based on extensive practical optimization experiments, we share our practical insights and valuable experiences.

Future Work

1. The component-based roofline model can extend to other DSAs like TPU.
2. Depth studies of hardware architecture, especially its interaction with the software.





Thanks

Q&A

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南 京 大 学

