Graph Query Processing

When it comes to Graphs

- Semi-structured
 - No schema
 - No constraints yet
- No standard query languages
 - A variety of queries used in practice
 - Nontrivial
- What is the complexity of the following problems?
 - Subgraph isomorphism
 - Simple path: given a graph G, a pair (s, t) of nodes in G, and a regular expression R, it is to decide whether there exists a simple path from s to t that satisfies R.
- Query optimization techniques, indexing, updates, ...

Basic Graph Queries And Algorithms

- Graph search (traversal)
- PageRank
- Nearest neighbors
- Keyword search
- Graph pattern matching (a full treatment of itself)

Path Query

Reachability

- Input: A directed graph G and a pair of nodes s and t in G
- Question: Does there exist a path from s to t in G?

Distance

- Input: A directed weighted graph G, and a node s in G
- Output: The length of shortest paths from s to all nodes in G

Regular Path

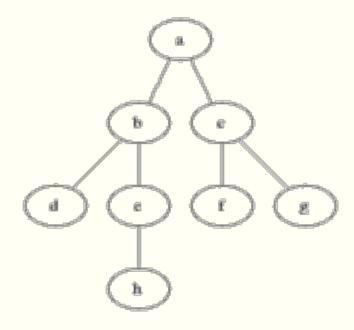
- Input: A node-labeled directed graph G, a pair of nodes s and t in G, and a regular expression R
- Question: Does there exist a (simple) path p from s to t that satisfies R?

Reachability Queries

- Reachability
 - Input: A directed graph G and a pair of nodes s and t in G
 - Question: Does there exist a path from s to t in G?
- Application: (a routine operation)
 - Social graph: Are two people related for security reasons?
 - Biological Networks: find genes that are (directly or indirectly) influenced by a given molecule
 - Nodes: Molecules, reations or physical interactions
 - Edge: Interactions

Breadth-first Search

- BFS (G, s, t):
 - Let Q be a queue
 - Q.enqueue(s)
- → While Q is not empty
 - v = Q.dequeue()
 - If <u>v</u> is the goal (i.e. <u>t</u>), return <u>True</u>
 - For all edges from v to w in G.adjacentEdges(v) do
 - If w is not labelled as discovered:
 - Label w as discovered
 - w.parent = v
 - Q.enqueue(w)
 - Return false



BFS Complexity

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 - Let Q be a queue
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 - w.parent = v
 - Q.enqueue(w)
 - Return false

Class: NL-Complete

Complexity:

Space:
$$O(|V| + |E|)$$

Time:
$$O(|V| + |E|)$$

If you want to review complexity theory, here is a video https://www.youtube.com/watch?v=ZADqzLRDIOQ

2-Hop Covers: Strike a balance

2 Hop Labels

- Let G = (V, E) be a directed graph.
- lacktriangle A 2-hop reachability labeling of G assigns to each vector $v \in V$ a label

$$L(v) = (L_{in}(v), L_{out}(v))$$

- such that $L_{in}(\overline{v})$, $L_{out}(v) \subseteq V$ and there is a path from every $x \in L_{in}(v)$ to v and from v to every $x \in L_{out}(v)$.
- Thus, node \mathscr{E} can reach node υ iff.

$$L_{out}(\underline{u}) \cap L_{in}(\underline{v}) \neq \phi$$
• Testing:

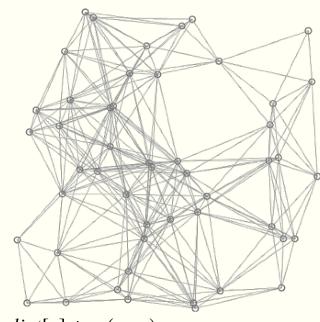
- - Better than O(|V| + |E|)
 - Space: $O\left(\left|V\right|\cdot\left|E\right|^{\frac{1}{2}}\right)$

Distance Queries

- Distance
 - Input: A directed weighted graph G, and a node s in G
 - Output: The length of shortest paths from s to all nodes in G
- Application: Transportation Networks

Distance Queries

- Dijkstra (G, s, w):
 - Create vertex set Q
 - For each vertex $v \in V$
 - $dist[v] = \infty$
 - prev[v] = undefined
 - Q.add(v)
 - dist[s] = 0
 - While Q is not empty:
 - u = vertex in Q with minimum distance dist[u]
 - Remove u from Q
 - Update the distance of each neighbor v of u to (if it is smaller) dist[v] = dist[u] + w(u, v)
- $_{\blacksquare}$ Complexity: If Q is a list, $O\!\left(\,\left|\,E\,\right|\,+\,\left|\,V\right|^{\,2}\right)$
- \blacksquare Complexity with the right data structure: $O\Big(\,\big|\,E\,\big|\,+\,\big|\,V\big|\log\big|\,V\big|\,\Big)$



Page Rank

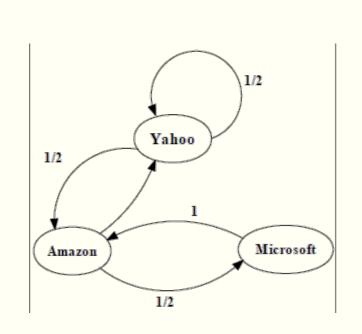
To Measure the "Quality" of a web page

- Input: A directed graph <u>G</u> modeling the web, in which nodes represent Web pages, and edges indicate hyperlinks
- Output: For each node v in graph G, $\underline{P(v)}$ is the likelihood that a random walk over G will arrive at v

lacktriangle Intuition: How a random walk can reach v

- The more pages link to v
- The more popular those pages that link to v
- Then, v has a higher chance to be visited

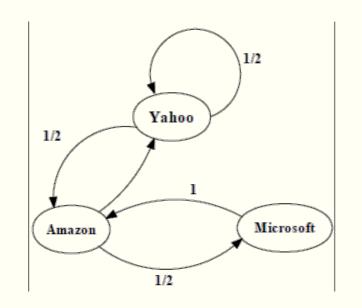
An example of Simplified PageRank



$$\begin{bmatrix} \underline{\text{yahoo}} \\ \text{Amazon} \\ \text{Microsoft} \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

$$\begin{bmatrix} \frac{1/3}{1/2} \\ \frac{1}{6} \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 & 0 \\ 1/2 & 0 & 1 \\ 0 & 1/2 & 0 \end{bmatrix} \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

An example of Simplified PageRank (Cont'd)



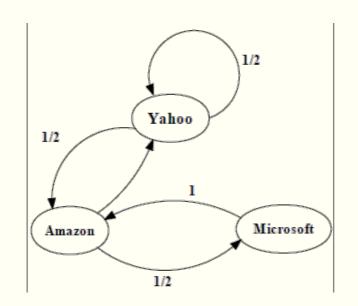
$$M = \begin{bmatrix} 1/2 & 1/2 & 0 \\ 1/2 & 0 & 1 \\ 0 & 1/2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} yahoo \\ Amazon \\ Microsoft \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

$$\begin{bmatrix} 5/12 \\ 1/3 \\ 1/4 \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 & 0 \\ 1/2 & 0 & 1 \\ 0 & 1/2 & 0 \end{bmatrix} \begin{bmatrix} 1/3 \\ 1/2 \\ 1/6 \end{bmatrix}$$

$$\uparrow \qquad \qquad \uparrow$$

An example of Simplified PageRank (Cont'd)

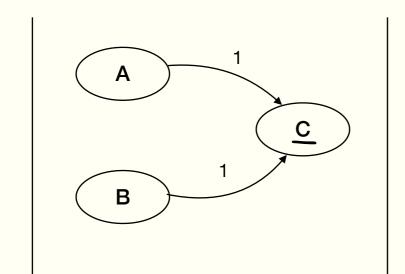


$$M = \begin{bmatrix} 1/2 & 1/2 & 0 \\ 1/2 & 0 & 1 \\ 0 & 1/2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} yahoo \\ Amazon \\ Microsoft \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

$$\begin{bmatrix} 3/8 \\ 11/24 \\ 1/6 \end{bmatrix} \begin{bmatrix} 5/12 \\ 17/48 \\ 11/48 \end{bmatrix} \dots \begin{bmatrix} 2/5 \\ 2/5 \\ 1/5 \end{bmatrix}$$

Example of Simplified PageRank



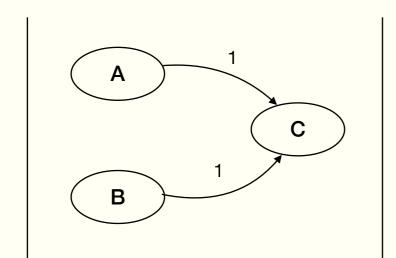
$$\begin{array}{cccc}
A & \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \underline{1} & \underline{1} & 0 \end{bmatrix}
\end{array}$$

$$\begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

$$\begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 2/3 \end{bmatrix}$$

$$\begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 2/3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Example of PageRank - Damping Factor



$$M = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

$$\begin{bmatrix} A \\ B \\ C \end{bmatrix} = \underbrace{(1 - \alpha)} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix} + \alpha \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

 $(1 - \alpha)$: Damping factor

Page Rank: (Cont'd)

Random jump to
$$v$$
: $\alpha \left(\frac{1}{|V|} \right)$

- lacktriangle i.e. The chance of hitting node v among all pages
- α : random jump factor (teleportation factor)

Hyperlink to
$$v: (1 - \alpha) \sum_{u \in L(v)} P(u)/C(u)$$

- (1α) : Damping factor
- L(v): The set of page that link to v
- C(u): The out-degree of node u (the number of links on u)
- $P(\underline{u})$: The probability of u being visited itself
- $\sum_{u \in L(v)} P(u)/C(u)$: The chances of one to click a hyperlink at a page u and reach v

Page Rank: (Cont'd)

• According to intuition, the likelihood that a page v is visited by a random walk:

$$\alpha \left(\frac{1}{|V|}\right) + (1 - \alpha) \sum_{u \in L(v)} P(u)/C(u)$$

- Recursive computation: For each page $v \in V(G)$,
 - $\quad \hbox{Compute } P(v) \text{ by using } P(u) \text{ for all } u \in \ L(v)$
- Until
 - Converge: no change to any P(v)
 - After a fixed number of iterations

K-Nearest Neighbor

- Nearest neighbor (kNN)
 - Input: A set S of points in a space M, a query point p in M, a distance function $\underline{dist(u, v)}$, and a positive integer k
 - Output: Find top-k points in S that are closest to p based on dist(p, u)
 - Note: The distance can be Euclidean distance, hamming distance, Cosine distance, etc.

Applications

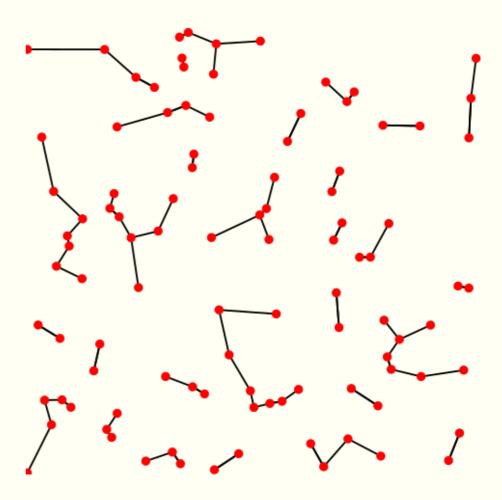
- POI recommendation: Find me top-k restaurants close to where I am
- Classification: classify an object based on its nearest neighbors
- Regression: property value as the average of the values of its k nearest neighbors

Methods:

Linear search, space partitioning, locality sensitive hashing, compression/clustering based search

K-Nearest Neighbor Graph

- Graph constructed based on knearest neighbor nodes
- Node p is connected to node q if dist(p, q) is among the k-smallest distances of node p to all other nodes.
- NNG (Nearest Neighbor Graph) is a special case of *k*-NNG with *k*=1



kNN Join

- Input: Two datasets \underline{R} and \underline{S} , a distance function $\underline{dist(R,\ S)}$, and a positive integer k
- Output: pairs(r, s), for all $r \in R$ and $s \in S$, and is one of the k-nearest neighbors of r.
- A naïve algorithm
 - lacksquare Scanning S once for each object in R
 - $O(|R| \cdot |S|)$: expensive when both datastes are large

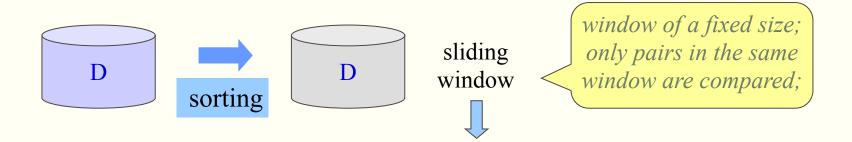
Blocking and Windowing

Blocking

D partitioning pairs in the same block are compared

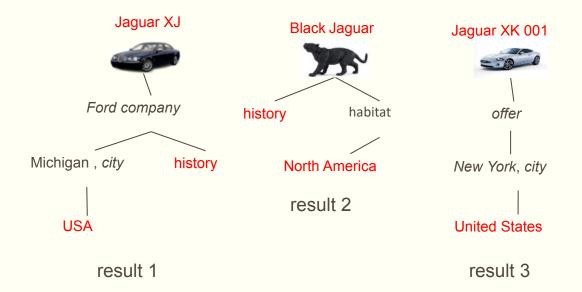
GORDER: An Efficient Method for KNN Join Processing. VLDB 2004.

Windowing



Keyword Search

- Input: A list Q of keywords, a graph G, a positive integer k
- lacksquare Output: top-k "matches" of Q in G
- Example: Query: ['Jagur', 'America', 'history']



- What makes a match?
- √ How to sort the matches?
- √ How to efficiently find top-k matches?



Keyword Search: Steiner Tree (Semantics)

- Input: A list Q of keywords, a graph G, a weight function w(e) on the edges on G, and a positive integer k
- Output: <u>top-k</u> Steiner trees that match Q
- Match: a subtree *T* of *G* such that
 - lacksquare Each keyword in Q is contained in a leaf of T
- Ranking:
 - The total weight of T (the sum of w(e) for all edges e in T)
- Complexity:
 - NP-Complete

Semantics: distinct-root (tree)

- Input: A list Q of keywords, a graph G, a weight function w(e) on the edges on G, and a positive integer k
- lacksquare Output: top-k distinct trees that match Q
- Match: a subtree *T* of *G* such that
 - $\qquad \qquad \textbf{Each} \ \, \textbf{keyword in} \ \, \textbf{\textit{Q}} \ \, \textbf{is contained in a leaf of} \, \, T \\$
- Ranking:
 - Dist(r,q): from the root of T to a leaf q
 - The sum of distances from the root to all leaves of T
- Diversification:
 - Each match in the top-k answer has a distinct root
- Complexity:

$$O\left(\left| Q \right| \left(\left| V \right| \log \left| V \right| + \left| E \right| \right) \right)$$

Semantics: Steiner graphs

- Input: A list Q of keywords, an undirected (unweighted) graph G, a positive integer r, and a positive integer k
- lacktriangle Output: find all r-radius Steiner graphs that match Q
- lacktriangle Match: a subgraph G of G such that it is
 - r-radius: the shortest distance between any pair of nodes in G is at most r (at least one pair with the distance)
 - Each key word is contained either in a content node (containing the key word) or a Steiner node (on a simple path between a pair of content nodes)
- Computation: M^r , the r-th power of adjacency graph of G

Answering Keyword Queries

A host of techniques

- Backward search
- Bidirectional search
- Bi-level indexing

References:

- G. Bhalotia, A. Hulgeri, C. Nakhe, S. Chakrabarti, and S. Sudarshan. Keyword searching and browsing in databases using BANKS. ICDE 2002.
- V. Kacholia, S. Pandit, S. Chakrabarti, S. Sudarshan, R. Desai, and H. Karambelkar. Bidirectional expansion for keyword search on graph databases. VLDB 2005.
- H. He, H. Wang, J. Yang, and P. S. Yu. BLINKS: ranked keyword searches on graphs. SIGMOD 2007.

Reading List

- SoQL: an SQL-like language to retrieve paths
- CRPQ: extending conjunctive queries with regular path expressions
 - R. Ronen and O. Shmueli. SoQL: A language for querying and creating data in social networks. ICDE, 2009.
 - P. Barceló, C. A. Hurtado, L. Libkin, and P. T. Wood. Expressive languages for path queries over graph-structured data. In PODS, 2010
- SPARQL: for RDF data
 - http://www.w3.org/TR/rdf-sparql-query/

Unfortunately, no "standard" query language for graphs, yet