

Peer Effects in Random Consideration Sets

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Abstract

This paper develops a dynamic model of discrete choice that incorporates peer effects into random consideration sets. We characterize the equilibrium behavior and study the empirical content of the dynamic model we build. In our set-up, the choices of friends provide the stochastic variation in the consideration sets that we exploit to recover the ranking of preferences of each person, the attention mechanism, and the set of connections between people in the network. The identification strategy we propose does not rely on the variation of the set of available options (or menus), which remain the same across all the observations.

JEL codes: C31, C33, D83, O33

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1 Introduction

This paper builds a dynamic model of peer effects where the choices of friends affect the set of options that each person ends up considering at the moment of choosing. That is, we offer a dynamic multinomial choice model where the peer effects operate via consideration sets. Due to limited consideration, in the spirit of boundedly rational choice models, people in our setting might disregard their most preferred alternatives for very long periods of time. In our model, the structure of the network affects the nature and the strength of these mistakes. We show that all parts of the model can be uniquely identified and estimated from a long sequence of choices. These parts include the ranking of preferences, the attention mechanism (or consideration probabilities), and the set of connections of each person.

More specifically, in our model, people are linked through a social network and they face a finite set of options or alternatives. At randomly chosen moments a given person can pick an option. The person sticks to this option till the revision opportunity arises again. We assume people are boundedly rational and do not consider all the available options at the moment of revising their selection. Instead, each person first forms a consideration set, and only then picks the most preferred option from it. The choices of friends affect the set of options each person ends up considering. This model leads to a sequence of joint choices of people in the network that evolve through time according to a continuous-time Markov process.

We initially show the dynamic system has a unique equilibrium. The equilibrium consists of an invariant distribution in the space of joint choices across people in the network. We show existence and uniqueness under the assumption that each option has (a priori) nonzero probability of being considered by each person irrespective of the choices of peers. This assumption captures the idea that a person can eventually pay attention to an alternative for various reasons that are outside the control of our model (e.g., watching an ad on television or receiving a coupon). It assures that we can move from any initial configuration of choices to any other one in finite time. We then show that the model primitives (i.e., the preferences, the attention mechanism, and the network structure) are uniquely identified up to the distribution

choices of agents.

In static single-agent consideration set models (e.g., Manzini and Mariotti (2014)) each choice problem involves a specific subset of available alternatives or menus. The distribution of choices across choice problems (or menus) is often assumed to be directly observed by the researcher. In our case, at the time of picking an option, the choice problems of a given person always entail the same set of available options but vary with the choices of the person's friends. In continuous time interdependent models, the researcher may not have access to the data at each time a person revises her selection. In this case, the distribution of choices across choice problems is not directly observed; it has to be inferred from the data. For this reason, our identification results are divided in two parts that we describe next.

First, we assume the conditional choice probabilities have been recovered from the data. Each of these probabilities informs us about the frequency of choices of a given person conditional on the choices of others (at the moment of revising her choice). We assume that a person is more likely to pay attention to a specific option if more of her friends are currently adopting it. Thus, changes in the choices of friends induce monotone stochastic variation in consideration sets. We exploit this variation to recover the set of connections between the people in the network and their ranking of preferences. We then use this information to recover the attention mechanism of each person, i.e., the probability of including a specific option in the consideration set as a function of the number of friends who are currently choosing it. Importantly, the identification strategy we pursue does not rely (as most of the theoretical work on consideration sets) on variation of the set of available options (or menus), which remain the same across all the observations (as we explained earlier).

Second, we study identification of the conditional choice probabilities. We consider two datasets: continuous-time data and discrete-time data with arbitrary time intervals. These two datasets coincide in that they provide long sequences of choices from people in the network. They differ in the timing at which the researcher observes these choices. In continuous-time datasets the researcher observes people's choices at real time. This allows the researcher

to record the precise moment at which a person revises her strategy and the configuration of choices at that time. We can think of this dataset as the “ideal dataset”. With the proliferation of on-line platforms and scanner this sort of data might indeed be available for some applications. In the discrete-time datasets the researcher observes the joint configuration of choices at fixed time intervals (e.g., the choice configuration is observed every Monday). The second dataset is more common in practice. These two datasets allow us to the conditional choice probabilities. In the case of discrete-time data we invoke insights from Blevins (2017, 2018). The reason for which even with discrete datasets we can still recover the conditional choice probabilities is that the transition rate matrix of continuous time models with independent revision times across people is rather parsimonious. In particular, the probability that two or more people revise their selected options at the same time is zero. This property translates into a transition rate matrix that has zeros in many known locations.

All previous results rely on deterministic preferences of people and existence of one alternative (the default) that is picked only if nothing else is considered. We then extend the model in two directions: the case of stochastic preferences (in addition to stochastic consideration sets) and the case with no default option. In the first case, the network structure and the attention mechanism are identified without any additional assumptions. The preference orders are identified if and only if each person has enough friends. In the model with no default option all the primitives are identified if there are more than three options in the set of available alternatives.

We show how our ideas work in practice with a simple model of restaurant choice. This application highlights the role of the network structure in shaping people mistakes. It shows, for example, that homophily reduces the frequency of mistakes. It also highlights some estimation aspects of our model. Finally, the example allows us to elaborate on interesting counterfactual predictions.

We finally relate our results with the existing literature. From a modeling perspective, our setup combines the dynamic model of social interactions of Blume (1993, 1995) with the

(single-agent) model of random consideration sets of Manzini and Mariotti (2014). By adding peer effects into the consideration sets we are able to use the choices of others as instruments to recover preferences. As we mentioned above, the literature on identification of single-agent consideration set models has mainly relied on variation of the set of available options or menus. The latter includes Aguiar (2017), Aguiar et al. (2016), Brady and Rehbeck (2016), Caplin et al. (2018), Cattaneo et al. (2017), Horan (2018), Lleras et al. (2017), Manzini and Mariotti (2014), and Masatoglu et al. (2012).¹ (See Aguiar et al. (2019) for a comparison of several consideration set models in an experimental setting.) Other papers have relied on the existence of exogenous covariates that shift preferences or consideration sets. The latter include Barseghyan et al. (2019), Conlon and Mortimer (2013), Dranganska and Klapper (2011), Gaynor et al. (2016), Goeree (2008), Mehta et al. (2003), and Roberts and Lattin (1991). Variation of exogenous covariates has also been used by Abaluck and Adams (2017) via an approach that exploits symmetry breaks with respect to the full consideration set model.

As we also mentioned, we can recover from the data the set of connections between the people in the network. In the context of linear models, a few recent papers have made progress in the same direction. Among them, Blume et al. (2015), Bonaldi et al. (2015), De Paula et al. (2018), and Manresa (2013). In the context of discrete-choice, Chambers et al. (2019) also identify the network structure but in their model peer effects do not affect consideration sets but preferences (among other differences).

The connection between the equilibrium behavior in our model and the Gibbs equilibrium is similar to the one in Blume and Durlauf (2003).

Let us finally mention two other papers that incorporate peer effects in the formation of consideration sets. Borah and Kops (2018) do so in a static framework and rely on variation of menus for identification. Lazzati (2018) considers a dynamic model but the time is discrete

¹See also Manski (1977) for a throughout formulation of the discrete choice model that incorporates the possibility that the decision maker only considers a sub-set of options.

and she focuses on two binary options that can be acquired together.

The rest of the paper is organized as follows. Section 2 presents the model and describes the equilibrium behavior. Section 3 studies the empirical content of the model. Section 4 extends the initial idea to contemplate random preferences (in addition to random consideration sets) and the case of no-default option. Section 5 presents some simulation and estimation results for a model of choosing a restaurant. Section 6 concludes, and all the proofs are collected in Section 7. Appendices I and II cover the Gibbs random field model and some simulation results, respectively.

2 The Model

2.1 Social Network, Consideration Sets, and Choices

Network and Choice Configuration There is a finite set of people connected through a social network. The network is described by a simple graph $\Gamma = (\mathcal{A}, e)$, where $\mathcal{A} = \{1, 2, \dots, A\}$ is the set of nodes (or people) and e is the set of edges. Each edge identifies two connected people and the direction of the connection. For each Person $a \in \mathcal{A}$, her set of friends (or reference group) is defined as follows

$$\mathcal{N}_a = \{a' \in \mathcal{A} : a' \neq a \text{ and there is an edge from } a \text{ to } a' \text{ in } \Gamma\}.$$

There is a set of alternatives $\overline{\mathcal{Y}} = \mathcal{Y} \cup \{o\}$, where $\mathcal{Y} = \{1, 2, \dots, Y\}$ is a finite set of options and o is a default option. Each Person a has a strict preference order \succ_a over the set of options $\overline{\mathcal{Y}}$. All people agree in that the default option is the least preferred. (We relax this modelling restriction in Section 4.) We refer to $\mathbf{y} = (y_a)_{a \in \mathcal{A}} \in \overline{\mathcal{Y}}^A$ as a choice configuration.

Choice Revision We model the revision of choices as a standard continuous-time Markov process. In particular, we assume that people are endowed with independent Poisson alarm clocks with rates $\boldsymbol{\lambda} = (\lambda_a)_{a \in \mathcal{A}}$.² At randomly chosen moments (exponentially distributed with

²See Blume (1993, 1995) for theoretical models that rely on Poisson alarm clocks and Blevins (2018) for a

mean $1/\lambda_a$) the alarm of Person a goes off.³ When this happens, the person selects the most preferred alternative among the ones she is actually considering. Formally, if $\mathcal{C} \subseteq \mathcal{A}$ is her consideration set, then the choice of Person a can be represented by an indicator function

$$R_a(v|\mathcal{C}) = 1(v \succ_a v' \text{ for some } v \in \mathcal{C} \text{ and for all } v' \in \mathcal{C})$$

that takes value 1 if v is the most preferred option in \mathcal{C} according to \succ_a . If, at the moment of choosing, the consideration set of Person a does not include any alternative in \mathcal{Y} , then the person simply selects the default option.

Peer Effects in the Formation of Consideration Sets In our model, whether Person a pays attention to a particular alternative depends on her own choice and the configuration of choices of her friends at the moment of revising her selection. We indicate by $Q_a(v|\mathbf{y})$ the probability that Person a pays attention to alternative $v \in \mathcal{Y}$ given a choice configuration \mathbf{y} . It follows that the probability of facing consideration set \mathcal{C} is given by

$$\prod_{v \in \mathcal{C}} Q_a(v|\mathbf{y}) \prod_{v \notin \mathcal{C}} (1 - Q_a(v|\mathbf{y})).$$

By combining preferences and stochastic consideration sets, the probability that Person a selects (at the moment of choosing) alternative $v \in \mathcal{Y}$ is given by

$$P_a(v|\mathbf{y}) = Q_a(v|\mathbf{y}) \prod_{v' \in \mathcal{Y}, v' \succ_a v} (1 - Q_a(v'|\mathbf{y})). \quad (1)$$

The probability of selecting the default option o is just $\prod_{v \in \mathcal{Y}} (1 - Q_a(v|\mathbf{y}))$.

Main Assumptions Our results build on three simple assumptions. Let $N_a^v(\mathbf{y})$ be the number of friends of Person a who select option v in choice configuration \mathbf{y} . Formally,

$$N_a^v(\mathbf{y}) = \sum_{a' \in \mathcal{N}_a} 1(y_{a'} = v).$$

nice discussion of the advantages of this type of revision process from an applied perspective.

³That is, each Person a is endowed with a collection of random variables $\{\tau_n^a\}_{n=1}^\infty$ such that each difference $\tau_n^a - \tau_{n-1}^a$ is exponentially distributed with mean $1/\lambda_a$. All these differences are independent across people and time.

We indicate by $|\mathcal{N}_a|$ the cardinality of \mathcal{N}_a . The three assumptions are as follows.

(A1) For each $a \in \mathcal{A}$, $v \in \mathcal{V}$, and $\mathbf{y} \in \overline{\mathcal{Y}}^A$, $1 > Q_a(v|\mathbf{y}) > 0$.

(A2) For each $a \in \mathcal{A}$, $|\mathcal{N}_a| > 0$.

(A3) For each $a \in \mathcal{A}$, $v \in \mathcal{V}$, and $\mathbf{y} \in \overline{\mathcal{Y}}^A$,

$$Q_a(v|\mathbf{y}) \equiv Q_a(v|y_a, N_a^v(\mathbf{y})) \text{ is strictly increasing in } N_a^v(\mathbf{y}).$$

Assumption A1 states that, for any choice configuration, the probability of considering each option is strictly positive and lower than one, independently on how many friends have selected that option. This assumption captures the idea that a person can eventually pay attention to an alternative for various reasons that are outside the control of our model (e.g., watching an ad on television or receiving a coupon). It also allows the person to eventually disregard any further consideration of a given option, including the one that she is currently adopting. From a technical perspective, it follows from A1 that each subset of options is (ex-ante) considered with nonzero probability. It guarantees equilibrium existence and uniqueness. Assumption A2 requires each person to have at least one friend. Assumption A3 states that the probability that a given person pays attention to a specific option depends on the current choice of the person and the number of friends that currently selected it. It also states that each person pays more attention to a particular option if more of her friends are adopting it.

Let us add a few comments about our model. First, it represents truly boundedly rational agents. The people in our framework do not solve a dynamic optimization problem and their choice sets may thereby not include their most preferred alternatives for long periods of time. Second, in our initial specification, the only source of randomness in choice is via consideration sets. In this sense, our initial model captures a single, though important, channel of possible mistakes in choices. The social network shapes the nature and the strength of these mistakes. We extend the analysis to random preferences in Section 4. In this extension, $R_a(\cdot|\mathcal{C})$ is not an indicator function but a distribution on \mathcal{V} .

2.2 Equilibrium

The independent identically distributed (i.i.d.) Poisson "alarm clocks", which lead the selection revision process, guarantee that at each time interval at most one person revises her selection almost surely. Thus, the transition rates between choice configurations that differ in more than one person changing actions are zero. The advantage of this fact for model identification is rather clear: there are fewer terms to recover. Blevins (2017, 2018) offers a nice discuss of this feature and its advantage over discrete time models. Formally, the transition rate from choice configuration \mathbf{y} to any different one \mathbf{y}' is as follows

$$m(\mathbf{y}' | \mathbf{y}) = \begin{cases} 0 & \text{if } \sum_{a \in \mathcal{A}} 1(y'_a \neq y_a) > 1 \\ \sum_{a \in \mathcal{A}} \lambda_a P_a(y'_a | \mathbf{y}) 1(y'_a \neq y_a) & \text{if } \sum_{a \in \mathcal{A}} 1(y'_a \neq y_a) = 1 \end{cases}. \quad (2)$$

In the statistical literature on continuous-time Markov processes these transition rates are the out of diagonal terms of the *transition rate matrix* (also known as the *infinitesimal generator matrix*). The rate of transition out from a given choice configuration \mathbf{y} is simply

$$m(\mathbf{y} | \mathbf{y}) = - \sum_{\mathbf{y}' \in \bar{\mathcal{Y}}^A \setminus \{\mathbf{y}\}} m(\mathbf{y}' | \mathbf{y}).$$

We will indicate by \mathcal{M} the transition rate matrix. In our model, the number of choice configurations is $(Y + 1)^A$. Thus, \mathcal{M} is a $(Y + 1)^A \times (Y + 1)^A$ matrix. There are many different ways of ordering the choice configurations and thereby writing the transition rate matrix. To avoid any sort of ambiguity in the exposition, we will let the choice configurations be ordered according to the lexicographic order with o treated as zero. Constructed in this way the first element of \mathcal{M} is (for instance) $\mathcal{M}_{11} = m((o, o, \dots, o)' | (o, o, \dots, o)')$. Formally, let $\iota(\mathbf{y}) \in \{1, 2, \dots, (Y + 1)^A\}$ be the position of \mathbf{y} according to the lexicographic order. Then,

$$\mathcal{M}_{\iota(\mathbf{y})\iota(\mathbf{y}')} = m(\mathbf{y}' | \mathbf{y}).$$

An equilibrium in our model is an invariant distribution $\mu : \bar{\mathcal{Y}}^A \rightarrow [0, 1]$, with $\sum_{\mathbf{y} \in \bar{\mathcal{Y}}^A} \mu(\mathbf{y}) = 1$, of the dynamic process with transition rate matrix \mathcal{M} . It indicates the likelihood of each

choice configuration \mathbf{y} in the long run. This equilibrium behavior relates to the transition rate matrix in a linear fashion

$$\mu\mathcal{M} = \mathbf{0}.$$

Proposition 1 states equilibrium existence and uniqueness.

Proposition 1 *If A1 is satisfied, then there exists a unique μ .*

The next example describes the equilibrium behavior of a simple specification of our model.

Example 1: There are two identical, connected people that select among two alternatives, namely, option 1 and the default option o . The rates for their Poisson alarm clocks are 1. We will also assume, to simplify the set up, that the probability of paying attention to a particular option only depends on the current choice of the other person. Thus, for $a = 1, 2$, we get that

$$P_a(1|\mathbf{y}) = Q(1|N_a^v(\mathbf{y})) \text{ and } P_a(o|\mathbf{y}) = 1 - Q(1|N_a^v(\mathbf{y})).$$

Note that we avoided the sub-index in Q because of the symmetry and dropped the dependence on the previous choice because of our simplifying assumption.

The transition rate matrix \mathcal{M} is as follows. (The columns are ordered as the rows.)

(o, o)	$-2Q(1 0)$	$Q(1 0)$	$Q(1 0)$	0
$(o, 1)$	$1 - Q(1 0)$	$-1 + Q(1 0) - Q(1 1)$	0	$Q(1 1)$
$(1, o)$	$1 - Q(1 0)$	0	$-1 + Q(1 0) - Q(1 1)$	$Q(1 1)$
$(1, 1)$	0	$1 - Q(1 1)$	$1 - Q(1 1)$	$-2 + 2Q(1 1)$

Recall that the invariant distribution of choices, or steady-state equilibrium, satisfies

$$\mu\mathcal{M} = \mathbf{0}.$$

After simple calculations, we get that the steady-state equilibrium is

$$\begin{aligned}\mu(o, o) &= \frac{[1 - Q(1|0)][1 - Q(1|1)]}{1 - Q(1|1) + Q(1|0)} \\ \mu(o, 1) = \mu(1, o) &= \frac{Q(1|0)[1 - Q(1|1)]}{1 - Q(1|1) + Q(1|0)} \\ \mu(1, 1) &= \frac{Q(1|0)Q(1|1)}{1 - Q(1|1) + Q(1|0)}\end{aligned}$$

The transition rate matrix \mathcal{M} is naturally more complex when there are more actions and/or more people. However, the structure of the zeros in \mathcal{M} is rather similar. As we mentioned earlier, this feature of the model facilitates identification and estimation. ■

Connection with Gibbs Random Field Models We end this section connecting our setup with the so called Gibbs random field models. These models have been widely used in Economics to study social interactions. (See Allen (1982), Blume (1993, 1995), and Blume and Durlauf (2003), among many others.)

The starting point of the Gibbs random field models is a set of conditional probability distributions. Each element of the set describes the probability that a given person selects each alternative as a function of the profile of choices of the other people. In our model, the set of conditional probabilities is $(P_a)_{a \in \mathcal{A}}$, with a generic element given by

$$P_a(v|\mathbf{y}) = Q_a(v|y_a, N_a^v(\mathbf{y})) \prod_{v' \in \mathcal{Y}, v' \succ_a v} (1 - Q_a(v'|y_a, N_a^v(\mathbf{y}))) \text{ for } v \in \mathcal{Y}.$$

A Gibbs equilibrium is defined as a joint distribution over the vector of choices \mathbf{y} , $P(\mathbf{y})$, that is able to generate $(P_a)_{a \in \mathcal{A}}$ as its conditional distribution functions.

Gibbs equilibria typically do not exist. (In the statistical literature, a similar existence problem is referred as the issue of compatibility of conditional distributions.) The existence of Gibbs equilibria depends on a great deal of homogeneity among people. In our model, it would also require $Q_a(v|y_a, N_a^v(\mathbf{y}))$ to be invariant with respect to y_a . When such a joint distribution exists, then it coincides with the invariant distribution μ of the dynamic revision process of our model. We show this claim in Appendix I and illustrate the idea with Example 1. (See Blume and Durlauf (2003) for a nice discuss.)

Example 1 (continued): The conditional distributions of choices in Example 1 satisfy the compatibility requirements. Thus, there exists a joint distribution on y_1, y_2 that is able to generate the conditional distributions of choices as its conditional distribution functions. In this simple case, the invariant distribution μ of the dynamic revision process coincides with the Gibbs equilibrium of the model. To see this notice that the marginal distributions of equilibrium choices are given by

$$\begin{aligned}\mu(o) &= \mu(o, o) + \mu(o, 1) = \mu(o, o) + \mu(1, o) = \frac{1 - Q(1|1)}{1 - Q(1|1) + Q(1|0)} \\ \mu(1) &= \mu(1, 1) + \mu(o, 1) = \mu(1, 1) + \mu(1, o) = \frac{Q(1|0)}{1 - Q(1|1) + Q(1|0)}.\end{aligned}$$

(Here again, we avoided sub-indices due to the symmetry across people.) Thus, the conditional distributions are

$$\begin{aligned}\mu(1, o) / \mu(o) &= Q(1|0) \text{ and } \mu(o, o) / \mu(o) = 1 - Q(1|0) \\ \mu(1, 1) / \mu(1) &= Q(1|1) \text{ and } \mu(o, 1) / \mu(1) = 1 - Q(1|1).\end{aligned}$$

That is, the pair of conditional distributions of choices coincides with the conditional probabilities generated by the steady-state equilibrium of the model. ■

3 Empirical Content of the Model

This section provides conditions under which the researcher can uniquely recover (from a long sequence of choices) the set of connections $\Gamma = (\mathcal{A}, e)$, the profile of strict preferences $(\succ_a)_{a \in \mathcal{A}}$, the attention mechanism $(Q_a)_{a \in \mathcal{A}}$, and the rates of the Poisson "alarm clocks" $(\lambda_a)_{a \in \mathcal{A}}$. We offer alternative conditions under which the model is identified. As it is the case with identification, we will abstract from small sample issues.

We separate the identification analysis in two parts. Let $(P_a)_{a \in \mathcal{A}}$ be the profile of choice probabilities of people in the network. Each $P_a(v|\mathbf{y}) : \bar{\mathcal{Y}} \times \bar{\mathcal{Y}}^A \rightarrow (0, 1)$ specifies the (ex-ante) probability that Person a selects option v when the choice configuration is \mathbf{y} . First,

we show that each set of conditional choice probabilities $(P_a)_{a \in \mathcal{A}}$ maps into a unique set of connections, profile of strict preferences, and attention mechanism. Thus, knowledge of the set of the conditional choice probabilities allows us to uniquely recover all the elements of the model. Second, we build identification of the conditional choice probabilities $(P_a)_{a \in \mathcal{A}}$ from a long sequence of choices.

3.1 Identification of the Model from $(P_a)_{a \in \mathcal{A}}$

Under assumptions A1-A3, changes in the choices of friends induce stochastic variation of the consideration sets. In addition, A3 guarantees this variation is monotonic in the sense that the probability of considering one option increases with the number of friends that are currently adopting it. This variation allows us to recover the set of connections between the people in the network and the ranking of preferences of each of them. We then sequentially identify the attention mechanism of each person moving from the most preferred alternative to the least preferred one. Proposition 2 formalizes these claims.

Proposition 2 *Under A1-A3, the set of connections $\Gamma = (\mathcal{A}, e)$, the profile of strict preferences $(\succ_a)_{a \in \mathcal{A}}$, and the attention mechanism $(Q_a)_{a \in \mathcal{A}}$ are point identified from $(P_a)_{a \in \mathcal{A}}$.*

The next example sheds light on the identification strategy in Proposition 2.

Example 2: Suppose there are three people $\mathcal{A} = \{1, 2, 3\}$ that select among two alternatives $\mathcal{Y} = \{1, 2\}$ and the default option o . The researcher knows P_1 , P_2 , and P_3 . Let us consider Person 1. Let \mathbf{y} be such that $y_1 = o$. The probability that Person 1 selects the default option o (given a profile of choices \mathbf{y} with $y_1 = o$) is

$$P_1(o|\mathbf{y}) = (1 - Q_1(1|o, N_1^1(\mathbf{y}))) (1 - Q_1(2|o, N_1^2(\mathbf{y}))).$$

Under A3, we get that $2 \in \mathcal{N}_1$ if and only if

$$P_1(o|o, o, o) > P_1(o|o, 1, o).$$

Similarly, $3 \in \mathcal{N}_1$ if and only if $P_1(o|o, o, o) > P_1(1|o, o, 1)$. Thus, we can learn (from the data) the set of friends of Person 1. Let us assume we get $\mathcal{N}_1 = \{2\}$. To recover the preferences of Person 1 note that

$$\begin{aligned} P_1(1|\mathbf{y}) &= Q_1(1|o, N_1^1(\mathbf{y})) && \text{if } 1 \succ_1 2 \\ P_1(1|\mathbf{y}) &= Q_1(1|o, N_1^1(\mathbf{y})) (1 - Q_1(2|o, N_1^2(\mathbf{y}))) && \text{if } 2 \succ_1 1 \end{aligned}.$$

Thus, $2 \succ_1 1$ if and only if

$$P_1(1|o, o, o) > P_1(1|o, 1, o).$$

Suppose that, indeed, we get that $2 \succ_1 1$. We can finally recover the attention mechanism (for $y_1 = o$) via the next four probabilities in the data

$$\begin{aligned} P_1(2|o, o, o) &= Q_1(2|o, 0) && P_1(2|o, 2, o) = Q_1(2|o, 1) \\ P_1(1|o, o, o) &= Q_1(1|o, 0) (1 - Q_1(2|o, 0)) && P_1(1|o, 1, o) = Q_1(1|o, 0) (1 - Q_1(2|o, 1)) \end{aligned}.$$

By considering two initial choice profiles \mathbf{y} with $y_1 = 1$ and $y_1 = 2$ (instead of $y_1 = o$), respectively, we can fully recover the attention mechanism of Person 1.

By a similar exercise we can recover the sets of friends, preferences, and the attention mechanisms for Persons 2 and 3. ■

3.2 Identification of $(\mathbf{P}_a)_{a \in \mathcal{A}}$

This section studies identification of the conditional choice probabilities and the rates of the Poisson alarm clocks from two different datasets. These two datasets coincide in that they consider long sequences of choices from people in the network. They differ in the timing at which the researcher observes these choices: In Dataset 1 the researcher observes people's choices at real time. This allows the researcher to record the precise moment at which a person revises her strategy and the configuration of choices at that time. In Dataset 2 the researcher simply observes the joint configuration of choices at fixed time intervals.

These two datasets are tightly connected. Let us assume the researcher observes people's choices at time intervals of length Δ and can consistently estimate $\Pr(\mathbf{y}^{t+\Delta} = \mathbf{y}' \mid \mathbf{y}^t = \mathbf{y})$ for

each pair $\mathbf{y}', \mathbf{y} \in \overline{\mathcal{Y}}^A$. We will capture these transition probabilities by a matrix $\mathcal{P}(\Delta)$. (Here again, we will assume that the choice configurations are ordered according to the lexicographic order when we construct $\mathcal{P}(\Delta)$.) The connection between $\mathcal{P}(\Delta)$ and the transition rate matrix \mathcal{M} described in Equation (2) is given by

$$\mathcal{P}(\Delta) = e^{(\Delta\mathcal{M})}.$$

The two datasets we consider differ regarding Δ : In the first dataset we let the time interval be very small. This is an "ideal dataset" that registers people's choices at the exact time in which any given person revises her choice. As we mentioned earlier, with the proliferation of on-line platforms and scanner this sort of data might indeed be available for some applications. In the second dataset we allow the time interval to be of arbitrary size. The next table formally describes the Datasets 1 and 2

Dataset 1 The researcher knows $\lim_{\Delta \rightarrow 0} \mathcal{P}(\Delta)$

Dataset 2 The researcher knows $\mathcal{P}(\Delta)$

In both cases, the identification question is whether (or under what additional restrictions) is it possible to uniquely recover \mathcal{M} from $\mathcal{P}(\Delta)$. The first result in this section is as follows.

Proposition 3 (Dataset 1) *The conditional choice probabilities $(P_a)_{a \in \mathcal{A}}$ and the rates of the Poisson "alarm clocks" $(\lambda_a)_{a \in \mathcal{A}}$ are identified from Dataset 1.*

The proof of Proposition 3 relies on the fact that when the time interval between the observations goes to zero, then we can recover \mathcal{M} . There are at least two well-known cases that produce the same outcome without assuming $\Delta \rightarrow 0$. One of them requires the length of the interval Δ to be below a threshold $\overline{\Delta}$. The main difficulty of this identification approach is that the value of the threshold depends on details of the model that are unknown to the researcher. The second requires the researcher to observe the dynamic system at two different intervals Δ_1 and Δ_2 that are not multiple of each other. (See, for example, Blevins (2017) and the literature therein.)

The next proposition states that, by adding an extra restriction, the transition rate matrix can be identified from people's choices even if these choices are observed at the endpoints of discrete time intervals. In this case, the researcher needs to know the rates of the Poisson alarm clocks or normalize them in empirical work.

Proposition 4 (Dataset 2) *If A2 is satisfied, the researcher knows $(\lambda_a)_{a \in \mathcal{A}}$, and \mathcal{M} has distinct eigenvalues that do not differ by an integer multiple of $2\pi i/\Delta$, then the conditional choice probabilities $(P_a)_{a \in \mathcal{A}}$ are generically identified from Dataset 2.*

The key element in proving Proposition 4 is that the transition rate matrix of our model is rather parsimonious. To see why, recall that, at any given time, only one person revises her selection with nonzero probability. This feature of the model translates into a transition rate matrix \mathcal{M} that has many zeros in known locations.

4 Extensions

4.1 Random Preferences

This section extends the previous model for randomness in preferences as well as in consideration sets. In this case, the choice rule $R_a(\cdot | \mathcal{C})$ from Section 2 is not an indicator function but a distribution on \mathcal{Y} . We naturally let $R_a(v | \mathcal{C}) = 0$ if $v \notin \mathcal{C}$.

Keeping unchanged the other parts of the model, the probability that Person a selects (at the moment of choosing) alternative $v \in \mathcal{Y}$ is given by

$$P_a(v | \mathbf{y}) = \sum_{\mathcal{C} \subseteq 2^{\mathcal{Y}}} R_a(v | \mathcal{C}) \prod_{v' \in \mathcal{C}} Q_a(v' | y_a, N_a^{v'}(\mathbf{y})) \prod_{v' \notin \mathcal{C}} (1 - Q_a(v' | y_a, N_a^{v'}(\mathbf{y}))). \quad (3)$$

The probability of selecting the default option o is (as before) $\prod_{v \in \mathcal{Y}} (1 - Q_a(v | y_a, N_a^v(\mathbf{y})))$.

The next example illustrates the random choice rule with the well-known logit model.

Example 3: If we use the logit model to represent the random preferences of Person a , then the probability that the person selects alternative 1 when alternative 2 is also part of her

consideration set would be given by

$$R_a(1|\{1, 2\}) = \frac{\exp(U_a^1)}{\exp(U_a^1) + \exp(U_a^2)}.$$

In this expression, U_a^1 and U_a^2 are the mean expected utilities that Person a gets from alternatives 1 and 2, respectively. ■

Under this alternative specification of the model, the identification of $(P_a)_{a \in \mathcal{A}}$ follows from the same arguments. We will thereby only focus on whether we can recover the set of connections, the choice rule, and the attention mechanism from the conditional choice probabilities. The main result is as follows.

Proposition 5 *Suppose A1-A3 are satisfied. Then, the set of connections $\Gamma = (\mathcal{A}, e)$ and the attention mechanism $(Q_a)_{a \in \mathcal{A}}$ are point identified from $(P_a)_{a \in \mathcal{A}}$. For each $a \in \mathcal{A}$, the random preferences R_a are also point identified if, and only if, in addition, we have that $|\mathcal{N}_a| \geq Y - 1$.*

Remark. The last result extends to the case in which the random preferences include the default option o with only one caveat. In this case, the attention mechanism can be recovered up to ratios of the form $Q_a(v|y_a, N_a^v(\mathbf{y})) / Q_a(v|y_a, 0)$. That is, we can only recover how much *extra* attention a person pays to each option as more of her friends select that option.

As in our previous results, under assumptions A1-A3, observed variation in the choices of friends induce stochastic variation of the consideration sets and this variation suffices to recover the connections between the people in the network and the attention mechanism. The only difference with respect to the case of deterministic preferences is that with random preferences we need a larger number of friends for each person, i.e., $|\mathcal{N}_a| \geq Y - 1$ for all $a \in \mathcal{A}$. The extra condition guarantees the matrix of coefficients for the R'_a s in expression (3) is full column rank. Indeed, we show that $|\mathcal{N}_a| \geq Y - 1$ is not only sufficient, but necessary, to this end. We illustrate the last result by a simple extension of Example 2 above.

Example 2 (continued): Let us keep all the structure of Example 2 except for people's preferences, which we now assume are random. The identification of the set of connections and

the attention mechanism follows from similar ideas. Thus, we will only focus on recovering R_1 , R_2 , and R_3 . Consider the following system of equations for Person 1

$$\begin{pmatrix} P_1(1|y_1, o, o) / Q_1(1|y_1, 0) \\ P_1(1|y_1, 2, o) / Q_1(1|y_1, 0) \end{pmatrix} = \begin{pmatrix} 1 - Q_1(2|y_1, 0) & Q_1(2|y_1, 0) \\ 1 - Q_1(2|y_1, 1) & Q_1(2|y_1, 1) \end{pmatrix} \begin{pmatrix} R_1(1|\{o, 1\}) \\ R_1(1|\{o, 1, 2\}) \end{pmatrix}$$

The fact that $R_1(1|\{1\})$ and $R_1(1|\{1, 2\})$ can be recovered follows because, by Assumption A3, we have that

$$\det \begin{pmatrix} 1 - Q_1(2|y_1, 0) & Q_1(2|y_1, 0) \\ 1 - Q_1(2|y_1, 1) & Q_1(2|y_1, 1) \end{pmatrix} = Q_1(2|y_1, 1) - Q_1(2|y_1, 0) > 0.$$

The extra condition, $|\mathcal{N}_a| \geq Y - 1$, and Assumption A3 guarantee that the matrix of coefficients for the R'_a s is always full column rank. ■

4.2 No-Default Option

In the initial benchmark model the default option displays two features: it is always considered by each person; and all people agree that it is the least preferred alternative. As a consequence, the default option ensures the consideration set is always non-empty and the default is only picked if nothing else is considered. In some settings such default option may not exist. This section models this possibility.

Let us assume there is no outside option o , so that $\bar{\mathcal{Y}} = \mathcal{Y}$. The formation process of the consideration set is as before, except that, since there is no the default option, we need to set what people do when no alternative is considered. We will simply assume that each person sticks to her previous choice if no alternative receives further consideration. Formally, the probability that Person a selects (at the moment of choosing) alternative $v \in \mathcal{Y}$ is given by

$$P_a(v|\mathbf{y}) = Q_a(v|\mathbf{y}) \prod_{v' \in \mathcal{Y}, v' \succ_a v} (1 - Q_a(v'|\mathbf{y})) + 1(v = y_a) \prod_{v' \in \mathcal{Y}} (1 - Q_a(v'|\mathbf{y})). \quad (4)$$

Proposition 6 *Suppose that A1-A3 are satisfied, and $|\mathcal{Y}| \geq 3$. Then, the set of connections $\Gamma = (\mathcal{A}, e)$, the profile of strict preferences $(\succ_a)_{a \in \mathcal{A}}$, and the attention mechanism $(Q_a)_{a \in \mathcal{A}}$ are point identified from $(P_a)_{a \in \mathcal{A}}$.*

5 Application: Choosing a Restaurant

This section simulates a sequence of choices for a simple version of our initial model that we apply to a problem of choosing a restaurant. The exercise has two aims. First, we illustrate how people's mistakes relate to the structure of the network. Second, we show how the main parts of the model can, indeed, be estimated from the sequence of choices.

5.1 Simulation

There are five people in the network. Their reference groups are as follows

$$\mathcal{N}_1 = \{2\}, \mathcal{N}_2 = \{1\}, \mathcal{N}_3 = \{1, 2\}, \mathcal{N}_4 = \{5\}, \text{ and } \mathcal{N}_5 = \{4\}.$$

Note that each person has at least one friend, so A2 is satisfied. Moreover, the network is directed since $3 \notin \mathcal{N}_1, \mathcal{N}_2$ and $1, 2 \in \mathcal{N}_3$. There are two possible restaurants at which individuals can have dinner. Restaurant 1 offers Mediterranean food and Restaurant 2 is a Steakhouse. Thus, $\mathcal{Y} = \{1, 2\}$. The default option o involves eating at home. The preferences of these people are as follows

$$2 \succ_1 1, 1 \succ_2 2, 2 \succ_3 1, 1 \succ_4 2, \text{ and } 1 \succ_5 2.$$

That is, Persons 2, 4, and 5 prefer Mediterranean food, and Persons 1 and 3 prefer the Steakhouse. We will assume the attention mechanism is invariant across people and alternatives. Also, to keep the exercise simple, as in Example 1, we will assume the probability of paying attention to a given option only depends on the choices of friends. In this case, we can avoid some sub-indices and let $Q(v|\mathbf{N}_a^v(\mathbf{y}))$ be the probability that person a pays attention to restaurant $v \in \mathcal{Y}$ if $\mathbf{N}_a^v(\mathbf{y})$ people of her reference group did so last time they selected where to dine. We initially let

$$Q(v|0) = \frac{1}{4}, \quad Q(v|1) = \frac{3}{4}, \text{ and } Q(v|2) = \frac{7}{8}.$$

The rates for their Poisson alarm clocks are 1.

The equilibrium behavior of this restaurant choice model is a joint distribution μ with support on 243 choice configurations (3^5). We simulated a long sequences of choices and calculated the equilibrium behavior. (See Appendix II for more details.) From the equilibrium behavior we can easily obtain the marginal distributions across people. (Each of them specifies the fraction of time that each person selects each alternative in the long run.)

$\mu_1(o) = 0.30$	$\mu_2(o) = 0.30$	$\mu_3(o) = 0.19$	$\mu_4(o) = 0.30$	$\mu_5(o) = 0.30$
$\mu_1(1) = 0.30$	$\mu_2(1) = 0.40$	$\mu_3(1) = 0.29$	$\mu_4(1) = 0.50$	$\mu_5(1) = 0.50$
$\mu_1(2) = 0.40$	$\mu_2(2) = 0.30$	$\mu_3(2) = 0.52$	$\mu_4(2) = 0.20$	$\mu_5(2) = 0.20$

Let us say that a person makes a mistake when her best alternative is not part of her consideration set, and thereby it is not chosen. From the previous marginals we can easily calculate the probabilities of making mistakes.

	Person 1	Person 2	Person 3	Person 4	Person 5
Probability of Mistakes	60%	60%	48%	50%	50%

Note that Persons 2 and 4 are identical in all respects except in the type of friend they have. In particular, Person 4 shares with her friend the same preferences. The opposite is true for Person 2. This difference leads Person 4 to make fewer mistakes. It becomes clear from this illustration that having friends with similar preference helps each person to consider more often her best alternative. It follows that homophily is good news in our model! In addition, note that Person 3, having more friends, makes also fewer mistakes.

To show a bit more how the network structure shapes people's mistakes, let us add two more connections in the model. In particular, let us assume that Person 3 is a friend of Persons 1 and 2. That is,

$$\mathcal{N}_1 = \{2, 3\}, \mathcal{N}_2 = \{1, 3\}, \mathcal{N}_3 = \{1, 2\}, \mathcal{N}_4 = \{5\}, \text{ and } \mathcal{N}_5 = \{4\}.$$

Repeating the previous exercise, the new network generates the following marginal distribu-

tions.

$\mu_1(o) = 0.12$	$\mu_2(o) = 0.12$	$\mu_3(o) = 0.12$	$\mu_4(o) = 0.30$	$\mu_5(o) = 0.30$
$\mu_1(1) = 0.21$	$\mu_2(1) = 0.42$	$\mu_3(1) = 0.22$	$\mu_4(1) = 0.50$	$\mu_5(1) = 0.50$
$\mu_1(2) = 0.67$	$\mu_2(2) = 0.46$	$\mu_3(2) = 0.66$	$\mu_4(2) = 0.20$	$\mu_5(2) = 0.20$

From these marginals, the probabilities of mistakes are as follows.

	Person 1	Person 2	Person 3	Person 4	Person 5
Probability of Mistakes	33%	54%	34%	50%	50%

The probabilities of making mistakes decrease for Persons 1, 2, and 3. But the change is larger for Persons 1 and 3 as they share the same preferences over the restaurants.

5.2 Estimation

This section uses the sequence of choices we simulated in the previous section to show that the main parts of the model can indeed be estimated. We will assume the researcher observes them at fixed time intervals, as in Dataset 2. Thus, identification follows by Proposition 4. Also, to make the analysis more tractable, we will impose three extra conditions: First, we will assume each person has at most two friends. Second, we will assume the attention mechanism is invariant across people and alternatives. Third, we will let the network to be undirected. Under these assumptions, the number of possible sets of connections among people or networks is 112.⁴ In addition, recall that there are 5 people in the population and two restaurants. Thus, the number of profiles of strict preferences $\succ = (\succ_a)_{a \in \mathcal{A}}$ is $2^5 = 32$. Finally, the attention mechanism has 3 parameters to estimate

$$\mathbf{Q} = (Q(v|0), Q(v|1), Q(v|2))'.$$

In line with A3, we will consider attention mechanisms that respect the monotonicity condition. That is, $Q(v|0) < Q(v|1) < Q(v|2)$.⁵ In addition, given Assumption A1, we let

⁴Without any restriction there are $2^{25} = 33,554,432$ possible network configurations.

⁵Technically speaking, for estimation purposes, we can only impose weak inequalities.

$Q(v|N_a^v(\mathbf{y})) \in (0, 1)$ for $N_a^v(\mathbf{y}) = 0, 1, 2$. Let us indicate by $\theta = (\Gamma, \succ, \mathbf{Q})$ an element in the space of possible parameters we want to estimate. Each of them induces a transition rate matrix $\mathcal{M}(\theta)$.

We normalize the intensity parameter λ_a to 1 for all $a \in \mathcal{A}$. Thus, for each θ , we can construct the transition rate matrix $\mathcal{M}(\theta)$ using equations (1) and (2). In turn, this information allows to calculate the so called transition matrix

$$\mathcal{P}(\theta, \Delta) = e^{\Delta \mathcal{M}(\theta)}.$$

We can use the latter to build the log-likelihood function $L_T(\theta) = \sum_{t=0}^{T-1} \ln \mathcal{P}_{\iota(\mathbf{y}_t), \iota(\mathbf{y}_{t+1})}(\theta, \Delta)$ where $\iota(\mathbf{y}) \in \{1, 2, \dots, \overline{\mathcal{Y}}^A\}$ is the position of \mathbf{y} according the lexicographic order, and $\mathcal{P}_{k,m}(\theta, \Delta)$ is the (k, m) -th element of the matrix $\mathcal{P}(\theta, \Delta)$. Finally, let us define the estimated parameters as

$$\hat{\theta}_T = \arg \max_{\theta} L_T(\theta).$$

For one simulated data generating process, with a sequence of $T = 15,000$ observations, the Maximum Likelihood estimates are as follows

Network	$\hat{\mathcal{N}}_1 = \{2\}, \hat{\mathcal{N}}_2 = \{1\}, \hat{\mathcal{N}}_3 = \{1, 2\}, \hat{\mathcal{N}}_4 = \{5\}, \text{ and } \hat{\mathcal{N}}_5 = \{4\}$
Preferences	$2 \hat{\succ}_1 1, 1 \hat{\succ}_2 2, 2 \hat{\succ}_3 1, 1 \hat{\succ}_4 2, \text{ and } 1 \hat{\succ}_5 2$
Attention Mechanism	$\hat{Q}(v 0) = 0.26, \hat{Q}(v 1) = 0.75, \text{ and } \hat{Q}(v 2) = 0.87$

In summary, the estimates correctly recover the set of connections and the strict preference order of each person in the network and closely approximates the attention mechanism. We estimated the attention mechanism assuming that the preference orders and the network structure are known. The estimator performs well in terms of the mean bias and the root

mean squared error, as the next table illustrates. (See Appendix II for more details.)

Table 1. Bias and Root Mean Squared Error (RMSE) ($\times 10^{-3}$)

Sample Size		$Q(v 0)$	$Q(v 1)$	$Q(v 2)$
1000	Bias	42.3	18.0	15.1
	RMSE	43.3	20.9	17.8
5000	Bias	9.4	2.7	0.3
	RMSE	10.2	5.6	4.4
10000	Bias	4.7	-0.6	-0.5
	RMSE	5.5	3.5	3.3
15000	Bias	3.5	-1.3	2.8
	RMSE	4.2	3.3	-0.3

Notes: The sample sizes correspond to $\Delta = 25$ for the sample size 1000, $\Delta = 5$ for the sample size 5000, $\Delta = 5/2$ for the sample size 10000, and $\Delta = 5/3$ for the sample size 15000. The number of replications is 1000.

6 Final Remarks

This paper offers a new model of interdependent choices that combines the dynamic model of social interactions of Blume (1993, 1995) with the (single-agent) model of random consideration sets of Manzini and Mariotti (2014). The model we build differs from most of the social interaction models, in that the choices of friends do not affect preferences but the sub-set of options that people end up considering. It allows us to show how the network structure can shape people's mistakes. From an applied perspective, in our model, changes in the choices of friends induce stochastic variation of the considerations sets. This feature allows us to recover (from a long sequence of choices) the main parts of the model without relying on variation of the set of alternative options or menus. Interestingly, we show that in addition of nonparametrically recovering the preference ranking of each person and the attention mechanism, we

also identify the set of connections or edges between the people in the network.

7 Proofs

Proof of Proposition 1: For an irreducible, finite-state, continuous Markov chain the steady-state μ exists and it is unique. Thus, we only need to prove that A1 implies that the Markov chain induced by our model is irreducible. First note that, under A1, for each $a \in \mathcal{A}$, $v \in \mathcal{Y}$, and $\mathbf{y} \in \overline{\mathcal{Y}}^A$, we have that

$$1 > P_a(v|\mathbf{y}) = Q_a(v|y_a, N_a^v(\mathbf{y})) \prod_{v' \in \mathcal{Y}, v' \succ_a v} (1 - Q_a(v'|y_a, N_a^v(\mathbf{y}))) > 0.$$

To show irreducibility, let \mathbf{y} and \mathbf{y}' be two different choice configurations. It follows from expression (2) that we can go from one configuration to the other one in less than A steps with positive probability. ■

Proof of Proposition 2: By A1, $P_a(\cdot|\mathbf{y})$ has full support for all \mathbf{y} . By A2 and A3, $P_a(v|\mathbf{y})$ is strictly decreasing in $N_a^{v'}(\mathbf{y})$ for each $v' \succ_a v$. Thus, we can recover \mathcal{N}_a . Since this is true for each $a \in \mathcal{A}$, we can get $\Gamma = (\mathcal{A}, e)$. In addition, from variation in $N_a^{v'}(\mathbf{y})$ for each $v' \neq v$, we can recover person a 's upper level set that corresponds to option v . That is,

$$\{v' \in \mathcal{Y} : v' \succ_a v\}.$$

By repeating the exercise with each alternative, we can recover \succ_a . Finally, suppose that y_a^* is the most preferred alternative for person a . Then,

$$P_a(y_a^*|\mathbf{y}) = Q_a(y_a^*|y_a, N_a^{y_a^*}(\mathbf{y})).$$

It follows that we can recover $Q_a(y_a^*|y_a, N_a^{y_a^*}(\mathbf{y}))$ for each $\mathbf{y} \in \overline{\mathcal{Y}}^A$. By proceeding in descending preference ordering we can then recover $Q_a(v|y_a, N_a^v(\mathbf{y}))$ for all $v \in \mathcal{Y}$ (and each $\mathbf{y} \in \overline{\mathcal{Y}}^A$). ■

Proof of Proposition 3: Since $\lim_{\Delta \rightarrow 0} \mathcal{P}(\Delta) = \mathcal{M}$, we can recover transition rate matrix from the data. Recall that

$$m(\mathbf{y}' | \mathbf{y}) = \begin{cases} 0 & \text{if } \sum_{a \in \mathcal{A}} 1(y'_a \neq y_a) > 1 \\ \sum_{a \in \mathcal{A}} \lambda_a P_a(y'_a|\mathbf{y}) 1(y'_a \neq y_a) & \text{if } \sum_{a \in \mathcal{A}} 1(y'_a \neq y_a) = 1 \end{cases}.$$

Thus, $\lambda_a P_a(y'_a | \mathbf{y}) = m(y'_a, \mathbf{y}_{-a} | \mathbf{y})$. It follows that we can recover $\lambda_a P_a(v | \mathbf{y})$ for each $v \in \overline{\mathcal{Y}}$, $\mathbf{y} \in \overline{\mathcal{Y}}^A$, and $a \in \mathcal{A}$. Note that, for each $\mathbf{y} \in \overline{\mathcal{Y}}^A$,

$$\sum_{v \in \overline{\mathcal{Y}}} \lambda_a P_a(v | \mathbf{y}) = \lambda_a \sum_{v \in \overline{\mathcal{Y}}} P_a(v | \mathbf{y}) = \lambda_a.$$

Then we can also recover λ_a for each $a \in \mathcal{A}$. ■

Proof of Proposition 4: This proof builds on Theorem 1 of Blevins (2017) and Theorem 3 of Blevins (2018). For the present case, it follows from the last two theorems, that the transition rate matrix \mathcal{M} is generically identified if, in addition to the conditions in Proposition 4, we have that

$$(Y + 1)^A - AY - 1 \geq \frac{1}{2}.$$

This condition is always satisfied if $A > 1$. Identification of \mathcal{M} follows because, by A2, $A \geq 2$. We can then uniquely recover $(P_a)_{a \in \mathcal{A}}$ from \mathcal{M} . See the proof of Proposition 3 ■

Proof of Proposition 5: Note that expression (3) can be rewritten as follows

$$P_a(v | \mathbf{y}) = \sum_{\mathcal{C} \subseteq \mathcal{Y}} R_a(v | \mathcal{C}) \prod_{v' \in \mathcal{C}} Q_a(v' | y_a, N_a^{v'}(\mathbf{y})) \prod_{v'' \notin \mathcal{C}} \left(1 - Q_a(v'' | y_a, N_a^{v''}(\mathbf{y}))\right) = \\ Q_a(v | y_a, N_a^v(\mathbf{y})) \sum_{\mathcal{C} \subseteq \mathcal{Y}, v \in \mathcal{C}} R_a(v | \mathcal{C}) \prod_{v' \in \mathcal{C} \setminus \{v\}} Q_a(v' | y_a, N_a^{v'}(\mathbf{y})) \prod_{v'' \notin \mathcal{C}} \left(1 - Q_a(v'' | y_a, N_a^{v''}(\mathbf{y}))\right).$$

Thus, by A2 and A3, we can state whether $a' \in \mathcal{N}_a$ by checking whether $P_a(v | y_1 = o, \dots, y_A = o)$ moves up when we change $y_{a'}$ from o to v for some v in \mathcal{A} . It follows that the network structure is identified.

Let \mathbf{y} be such that $N_a^v(\mathbf{y}) = 0$ and let us assume that at least one person (different from a) in \mathbf{y} selected the default option (i.e., there is at least one $y_{a'} = o$ with $a' \neq a$). Let \mathbf{y}' be such that

$$N_a^{v'}(\mathbf{y}) = N_a^{v'}(\mathbf{y}') \text{ for all } v' \neq v \text{ and } N_a^v(\mathbf{y}) = 1.$$

Note that

$$P_a(v | \mathbf{y}') / P_a(v | \mathbf{y}) = Q_a(v | y_a, 1) / Q_a(v | y_a, 0).$$

Also

$$P_a(o|\mathbf{y}')/P_a(o|\mathbf{y}) = (1 - Q_a(v|y_a, 1)) / (1 - Q_a(v|y_a, 0)).$$

Thus, by A3, $Q_a(v|y_a, 0)$ and $Q_a(v|y_a, 1)$ can be recovered from the data. By implementing a similar procedure for different values of $N_a^v(\mathbf{y})$ we can recover Q_a for each y_a . Finally, since this is true for any arbitrary a and y_a , then we can recover the attention mechanism $(Q_a)_{a \in \mathcal{A}}$.

We finally show that R_a is identified if and only if (in addition to A1-A3) we have that $|\mathcal{N}_a| \geq Y - 1$. We will present the idea for $v = 1$, agent a , and y_a . (The proof immediately extends to other agents and alternatives.) We want to recover $R_a(1|\mathcal{C})$ for all \mathcal{C} . To simplify the exposition we will write

$$\begin{aligned} |\mathcal{N}_a| &= N \\ Q_a(v|y_a, m) &= Q^1(v|m) \\ 1 - Q_a(v|y_a, m) &= Q^0(v|m) \end{aligned}$$

We have a set of equations indexed by \mathbf{y}

$$P_a(1|\mathbf{y})/Q_a(1|y_a, N_a^1(\mathbf{y})) = \sum_{\mathcal{C} \subseteq \mathcal{Y}, v \in \mathcal{C}} R_a(v|\mathcal{C}) \prod_{k \in \mathcal{C} \setminus \{v\}} Q^1(k|N_a^k(\mathbf{y})) \prod_{k \notin \mathcal{C} \setminus \{v\}} Q^0(k|N_a^k(\mathbf{y})).$$

To present the ideas more clear let $A(N, Y)$ be the matrix of coefficients in front of the R_a' s. The above system of equations has a unique solution if and only if $A(N, Y)$ has full column rank. The column of $A(N, Y)$ that corresponds to any given $\mathcal{C} \subseteq \mathcal{Y}$ consists of the elements of the following form

$$\prod_{k \in \mathcal{Y}} Q^{1(k \in \mathcal{C})}(k|N^k)$$

where $N^k \in \{0, 1, \dots, N\}$ and $\sum_k N^k \leq N$. The last claim in the proposition follows from the next lemma.

Lemma 1: Assume that A1-A3 hold. For all $Y \geq 2$ and $N \geq 1$

$$N \geq Y - 1 \iff A(N, Y) \text{ has full column rank.}$$

Proof.

Step 1. To illustrate how the idea works, note that $A(1, 2)$ and $A(1, 3)$ can be written as follows

$$A(1, 2) = \begin{pmatrix} Q^0(2|0) & Q^1(2|0) \\ Q^0(2|1) & Q^1(2|1) \end{pmatrix}$$

and

$$\begin{aligned} A(1, 3) &= \begin{pmatrix} Q^0(3|0) Q^0(2|0) & Q^0(3|0) Q^1(2|0) & Q^1(3|0) Q^0(2|0) & Q^1(3|0) Q^1(2|0) \\ Q^0(3|0) Q^0(2|1) & Q^0(3|0) Q^1(2|1) & Q^1(3|0) Q^0(2|1) & Q^1(3|0) Q^1(2|1) \\ Q^0(3|1) Q^0(2|0) & Q^0(3|1) Q^1(2|0) & Q^1(3|1) Q^0(2|0) & Q^1(3|1) Q^1(2|0) \end{pmatrix} \\ &= \begin{pmatrix} Q^0(3|0) A(1, 2) & Q^1(3|0) A(1, 2) \\ Q^0(3|1) A(1, 2) & Q^1(3|1) A(1, 2) \end{pmatrix} \end{aligned}$$

where $A(0, 2) = \begin{pmatrix} Q^0(2|0) & Q^1(2|0) \end{pmatrix}$.

Similarly, the matrix $A(N, Y + 1)$ can be written as follows

$$A(N, Y + 1) = \begin{pmatrix} Q^0(Y + 1|0) A(N, Y) & Q^1(Y + 1|0) A(N, Y) \\ Q^0(Y + 1|1) A(N - 1, Y) & Q^1(Y + 1|1) A(N - 1, Y) \\ Q^0(Y + 1|2) A(N - 2, Y) & Q^1(Y + 1|2) A(N - 2, Y) \\ \dots & \dots \\ Q^0(Y + 1|N) A(0, Y) & Q^1(Y + 1|N) A(0, Y) \end{pmatrix}.$$

Note that $A(K, Y)$ is a sub-matrix of $A(K + 1, Y)$ for all K (with the same number of columns). Thus, it is clear that $A(N, Y + 1)$ has full column rank only if $A(N, Y)$ and $A(N - 1, Y)$ have both full column rank, which is the same as to say $A(N - 1, Y)$ has full column rank. We next show that under A3, if $A(N - 1, Y)$ has full column rank, then $A(N, Y + 1)$ has full column rank too. To this end, let M be a matrix obtained deleting rows from $A(N - 1, Y)$ in such a way that $\det(M) > 0$. Then, by A3, we have

$$\det \begin{pmatrix} Q^0(Y + 1|0) M & Q^1(Y + 1|0) M \\ Q^0(Y + 1|1) M & Q^1(Y + 1|1) M \end{pmatrix} = (Q^1(Y + 1|1) - Q^1(Y + 1|0))^{2^{Y-1}} \det(M)^2 > 0.$$

In summary, we have that

$$A(N, Y + 1) \text{ has full column rank} \iff A(N - 1, Y) \text{ has full column rank.}$$

Step 2. Consider $(N, Y) = (1, 2)$. Note that

$$A(1, 2) = \begin{pmatrix} Q^0(2|0) & Q^1(2|0) \\ Q^0(2|1) & Q^1(2|1) \end{pmatrix}$$

has full column rank since $\det(A(1, 2)) = Q^1(2|1) - Q^1(2|0) > 0$. In addition, any $A(N, 2)$ with $N \geq 1$ will have full column rank because $A(1, 2)$ is a sub-matrix of $A(N, 2)$ with the same number of columns.

Finally, note that $A(1, 3)$ does not have full column rank since the number of columns is higher than the number of rows.

Step 3. From Step 1 we got that, for all $Y \geq 2$ and $N \geq 1$,

$$A(N, Y + 1) \text{ has full column rank} \iff A(N - 1, Y) \text{ has full column rank.}$$

From Step 2, we get that $A(N, 2)$ (with $N \geq 1$) has full column rank and $A(1, 3)$ does not have full column rank. The claim in Lemma 1 follows by combining these three results. ■

Proof of Proposition 6: This proof is divided in three steps.

Step 1. (Identification of the Set of Connections) Take any two different people with arbitrary designations a_1 and a_2 . Note that if $a_2 \notin \mathcal{N}_{a_1}$, then $P_{a_1}(v|\mathbf{y}) = P_{a_1}(v|\mathbf{y}')$ for any \mathbf{y} and \mathbf{y}' such that $y_a = y'_a$ for all $a \neq a_2$ and $y_{a_1} \neq v$. In addition, let $v_{a_1}^*$ be the best preferred alternative of a_1 . Then, by A1 and A3, for any \mathbf{y} such that $y_{a_1} \neq v_{a_1}^*$

$$P_{a_1}(v_{a_1}^*|\mathbf{y}) = Q_{a_1}(v_{a_1}^*|\mathbf{y})$$

is constant in y_{a_2} if and only if $a_2 \notin \mathcal{N}_{a_1}$. Altogether, $a_2 \notin \mathcal{N}_{a_1}$ if and only if $P_{a_1}(v|\mathbf{y})$ with $y_{a_1} \neq v$ is constant in y_{a_2} . As a result, we can identify whether a_2 is in the set of friends of a_1 . Since the choice of a_1 and a_2 was arbitrary, we can identify the set of connections Γ . Note that for this result we only need $|\mathcal{Y}| \geq 2$.

Step 2. (Identification of the Strict Preferences) Fix some Person a_1 . We will show the result for a set of alternatives $\mathcal{Y} = \{1, 2, 3\}$ of size 3. (The proof easily extends to the case

of more alternatives. The only cost is extra notation.) For arbitrary designation of the three options v_1, v_2, v_3 , and any $a_2 \in \mathcal{N}_{a_1}$ (by A2, $\mathcal{N}_{a_1} \neq \emptyset$) let

$$\Delta P(v_1, v_2, v_3) = P_{a_1}(v_1 | (v_3, \dots, v_3, v_2, v_3, \dots, v_3)) - P_{a_1}(v_1 | (v_3, \dots, v_3, v_3, v_3, \dots, v_3)),$$

where Person a_2 switches from v_2 to v_3 . Define $\text{sign}(v_1, v_2, v_3) \in \{-, +, 0\}$ be such that

$$\text{sign}(v_1, v_2, v_3) = \begin{cases} - & \text{if } \Delta P(v_1, v_2, v_3) < 0 \\ + & \text{if } \Delta P(v_1, v_2, v_3) > 0 \\ 0 & \text{if } \Delta P(v_1, v_2, v_3) = 0 \end{cases}.$$

Note that $\text{sign}(\cdot)$ can be computed from the data. Different preference orders over \mathcal{Y} will imply potentially different values for $\text{sign}(\cdot)$. Let N_{a_1} is the the cardinality of \mathcal{N}_{a_1} . For instance, if $1 \succ_{a_1} 2 \succ_{a_1} 3$, then we have that

$$\begin{aligned} \Delta P(1, 2, 3) &= Q_{a_1}(1|3, 0) - Q_{a_1}(1|3, 0) = 0 \\ \Delta P(1, 3, 2) &= Q_{a_1}(1|2, 0) - Q_{a_1}(1|3, 0) = 0 \\ \Delta P(3, 1, 2) &= Q_{a_1}(3|2, 0)(1 - Q_{a_1}(1|2, 1))(1 - Q_{a_1}(2|2, N_{a_1} - 1)) \\ &\quad - Q_{a_1}(3|2, 0)(1 - Q_{a_1}(1|2, 0))(1 - Q_{a_1}(2|2, N_{a_1})) \\ \Delta P(3, 2, 1) &= Q_{a_1}(3|1, 0)(1 - Q_{a_1}(1|1, N_{a_1} - 1))(1 - Q_{a_1}(2|1, 1)) \\ &\quad - Q_{a_1}(3|1, 0)(1 - Q_{a_1}(1|1, N_{a_1}))(1 - Q_{a_1}(2|1, 0)), \end{aligned}$$

Note that for $\Delta P(3, 1, 2)$ and $\Delta P(3, 2, 1)$ our monotonicity restriction is not informative enough: $\Delta P(3, 1, 2)$ and $\Delta P(3, 2, 1)$ can be positive, negative, or equal to zero. The following table displays the values $\text{sign}(\cdot)$ takes depending on the underlying preference order \succ_{a_1} for all distinct v_1, v_2 , and v_3 . If the sign of $\Delta P(v_1, v_2, v_3)$ is not uniquely determined by

a strict preference, then we write \sim .

order/ (v_1, v_2, v_3)	(1, 2, 3)	(1, 3, 2)	(2, 1, 3)	(2, 3, 1)	(3, 1, 2)	(3, 2, 1)
$1 \succ_{a_1} 2 \succ_{a_1} 3$	0	0	−	+	\sim	\sim
$1 \succ_{a_1} 3 \succ_{a_1} 2$	0	0	\sim	\sim	−	+
$2 \succ_{a_1} 1 \succ_{a_1} 3$	−	+	0	0	\sim	\sim
$2 \succ_{a_1} 3 \succ_{a_1} 1$	\sim	\sim	0	0	+	−
$3 \succ_{a_1} 1 \succ_{a_1} 2$	+	−	\sim	\sim	0	0
$3 \succ_{a_1} 2 \succ_{a_1} 1$	\sim	\sim	+	−	0	0

Note that we can always distinguish $1 \succ_{a_1} 2 \succ_{a_1} 3$ from say $3 \succ_{a_1} 2 \succ_{a_1} 1$ since $\text{sign}(2, 1, 3)$ is determined for both preference orders and gives different predictions. The only pairs of preference orders that may be observationally equivalent are the following three pairs: (i) $1 \succ_{a_1} 2 \succ_{a_1} 3$ and $1 \succ_{a_1} 3 \succ_{a_1} 2$; (ii) $2 \succ_{a_1} 1 \succ_{a_1} 3$ and $2 \succ_{a_1} 3 \succ_{a_1} 1$; and (iii) $3 \succ_{a_1} 1 \succ_{a_1} 2$ and $3 \succ_{a_1} 2 \succ_{a_1} 1$. Although we cannot uniquely identify the order, we can uniquely identify the most preferred alternative. For instance, if we know that $1 \succ_{a_1} 2 \succ_{a_1} 3$ or $1 \succ_{a_1} 2 \succ_{a_1} 3$ has generated the data, then 1 is the most preferred alternative for agent a_1 .

Assume, without loss of generality, that 3 is the most preferred alternative. Then we can identify $Q_{a_1}(3|y_{a_1}, \cdot)$ for any $y_{a_1} \neq 3$ since

$$Q_{a_1}(3|y_{a_1}, N_{a_1}^3(\mathbf{y})) = P_{a_1}(3|\mathbf{y}).$$

Hence, for \mathbf{y} with $y_{a_1} = 1$ we have that

$$\frac{P_{a_1}(2|\mathbf{y})}{1 - P_{a_1}(3|\mathbf{y})} = \begin{cases} Q_a(2|1, N_{a_1}^2(\mathbf{y})) & \text{if 2 is preferred to 1} \\ Q_a(2|1, N_{a_1}^2(\mathbf{y}))(1 - Q_a(1|1, N_{a_1}^1(\mathbf{y}))) & \text{if 1 is preferred to 2.} \end{cases}$$

Start with a \mathbf{y} such that $y_a = 3$ for all $a \neq a_1$ (and $y_{a_1} = 1$). Consider then changing the y_{a_2} from 3 to 1 for some $a_2 \in \mathcal{N}_{a_1}$. Then, by A3, $1 \succ_{a_1} 2$ if and only if $P_{a_1}(2|\mathbf{y}) / (1 - P_{a_1}(3|\mathbf{y}))$ strictly decreases in the data.

Step 3. (Identification of the Attention Mechanism) Fix some a_1 and let $y_{a_1}^*$ be the most preferred alternative of person a_1 . Then we can identify $Q_{a_1}(y_{a_1}^*|y_{a_1}, N_{a_1}^{y_{a_1}^*}(\mathbf{y}))$ for any \mathbf{y} such that $y_{a_1}^* \neq y_{a_1}$ since

$$Q_{a_1}(y_{a_1}^*|y_{a_1}, N_{a_1}^{y_{a_1}^*}(\mathbf{y})) = P_{a_1}(y_{a_1}^*|\mathbf{y}).$$

By proceeding in decreasing preference order we can recover $Q_{a_1}(y'_{a_1}|y_{a_1}, N_{a_1}^{y'_{a_1}}(\mathbf{y}))$ for any y'_{a_1} and \mathbf{y} such that $y'_{a_1} \neq y_{a_1}$. Moreover, we can identify

$$\prod_{v' \neq y_{a_1}} \left(1 - Q_a \left(v'|y_{a_1}, N_{a_1}^{v'}(\mathbf{y})\right)\right)$$

Next note that for any \mathbf{y} such that $y_{a_1}^* = y_{a_1}$

$$Q_{a_1}(y_{a_1}^*|y_{a_1}, N_{a_1}^{y_{a_1}^*}(\mathbf{y})) = \frac{P_{a_1}(y_{a_1}^*|\mathbf{y}) - \prod_{v' \neq y_{a_1}^*} \left(1 - Q_a \left(v'|y_{a_1}^*, N_{a_1}^{v'}(\mathbf{y})\right)\right)}{1 - \prod_{v' \neq y_{a_1}^*} \left(1 - Q_a \left(v'|y_{a_1}^*, N_{a_1}^{v'}(\mathbf{y})\right)\right)}.$$

Hence, we can identify $Q_{a_1}(y_{a_1}^*|y_{a_1}, N_{a_1}^{y_{a_1}^*}(\mathbf{y}))$ for all \mathbf{y} . Let $y_{a_1}^{**}$ be the second best alternative of person a_1 , then for any \mathbf{y} such that $y_{a_1}^{**} = y_{a_1}$ similarly to the case with $y_{a_1}^*$ we can identify $Q_{a_1}(y_{a_1}^{**}|y_{a_1}, N_{a_1}^{y_{a_1}^{**}}(\mathbf{y}))$ since

$$Q_{a_1}(y_{a_1}^{**}|y_{a_1}, N_{a_1}^{y_{a_1}^{**}}(\mathbf{y})) = \frac{P_{a_1}(y_{a_1}^{**}|\mathbf{y}) - \prod_{v' \neq y_{a_1}^{**}} \left(1 - Q_{a_1} \left(v'|y_{a_1}^{**}, N_{a_1}^{v'}(\mathbf{y})\right)\right)}{1 - Q_{a_1}(y_{a_1}^*|y_{a_1}, N_{a_1}^{v'}(\mathbf{y})) - \prod_{v' \neq y_{a_1}^{**}} \left(1 - Q_{a_1} \left(v'|y_{a_1}^{**}, N_{a_1}^{v'}(\mathbf{y})\right)\right)},$$

and thus we recover $Q_{a_1}(y_{a_1}^{**}|y_{a_1}, N_{a_1}^{y_{a_1}^{**}}(\mathbf{y}))$ for all \mathbf{y} . By proceeding in decreasing preference order we can recover $Q_{a_1}(y'_{a_1}|y_{a_1}, N_{a_1}^{y'_{a_1}}(\mathbf{y}))$ for any y'_{a_1} and \mathbf{y} . Since the choice of a_1 was arbitrary we can identify $(Q_a)_{a \in \mathcal{A}}$.

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8 Appendix I: Gibbs Random Field Model

The starting point of the Gibbs random field models is a set of conditional probability distributions. In our model, the set of conditional probabilities is $(P_a)_{a \in \mathcal{A}}$, with a generic element given by

$$P_a(v|\mathbf{y}) = Q_a(v|y_a, N_a^v(\mathbf{y})) \prod_{v' \in \mathcal{Y}, v' \succ_a v} (1 - Q_a(v'|y_a, N_a^v(\mathbf{y}))) \text{ for } v \in \mathcal{Y}.$$

A Gibbs equilibrium is defined as a joint distribution over the vector of choices \mathbf{y} , $P(\mathbf{y})$, that is able to generate $(P_a)_{a \in \mathcal{A}}$ as its conditional distribution functions.

Gibbs equilibria typically do not exist. (In the statistical literature, a similar existence problem is referred as the issue of compatibility of conditional distributions.) The existence of Gibbs equilibria depends on a great deal of homogeneity among people. In our model, it would also require $Q_a(v|y_a, N_a^v(\mathbf{y}))$ to be invariant with respect to y_a .

(G1) For each $a \in \mathcal{A}$, $v \in \mathcal{Y}$, and $\mathbf{y} \in \bar{\mathcal{Y}}^A$, $Q_a(v|\mathbf{y}) \equiv Q_a(v|N_a^v(\mathbf{y}))$.

Together with assumption A1, this extra condition allows a simple characterization of the invariant distribution μ .

Proposition 7 *If A1 and G1 are satisfied, then there exists a unique μ . Also, μ satisfies*

$$\mu(\mathbf{y}) = \frac{1}{\sum_{a \in \mathcal{A}} \lambda_a} \sum_{a \in \mathcal{A}} \lambda_a P_a(y_a|\mathbf{y}) \mu_{-a}(\mathbf{y}_{-a}) \text{ for each } \mathbf{y} \in \bar{\mathcal{Y}}^A.$$

Proof of Proposition 7: The characterization of μ follows as the invariant distribution satisfies the balance condition $\sum_{\mathbf{y}' \in \bar{\mathcal{Y}}^A} \mu(\mathbf{y}') m(\mathbf{y} | \mathbf{y}') = 0$ for each $\mathbf{y} \in \bar{\mathcal{Y}}^A$. The next steps

show this claim.

$$\begin{aligned}
\sum_{\mathbf{y}' \in \bar{\mathcal{Y}}^A} \mu(\mathbf{y}') m(\mathbf{y} | \mathbf{y}') &= 0 \\
\mu(\mathbf{y}) \left(- \sum_{\mathbf{y}' \in \bar{\mathcal{Y}}^A \setminus \{\mathbf{y}\}} m(\mathbf{y}' | \mathbf{y}) \right) + \sum_{\mathbf{y}' \in \bar{\mathcal{Y}}^A \setminus \{\mathbf{y}\}} \mu(\mathbf{y}') m(\mathbf{y} | \mathbf{y}') &= 0 \\
-\mu(\mathbf{y}) \sum_{a \in \mathcal{A}} \sum_{y'_a \in \bar{\mathcal{Y}} \setminus \{y_a\}} \lambda_a P_a(y'_a | \mathbf{y}) + \sum_{a \in \mathcal{A}} \sum_{y'_a \in \bar{\mathcal{Y}} \setminus \{y_a\}} \mu(y'_a, \mathbf{y}_{-a}) \lambda_a P_a(y_a | y'_a, \mathbf{y}_{-a}) &= 0 \\
-\mu(\mathbf{y}) \sum_{a \in \mathcal{A}} \lambda_a (1 - P_a(y_a | \mathbf{y})) + \sum_{a \in \mathcal{A}} \sum_{y'_a \in \bar{\mathcal{Y}} \setminus \{y_a\}} \mu(y'_a, \mathbf{y}_{-a}) \lambda_a P_a(y_a | y'_a, \mathbf{y}_{-a}) &= 0 \\
\frac{1}{\sum_{a \in \mathcal{A}} \lambda_a} \sum_{a \in \mathcal{A}} \lambda_a \left\{ \sum_{y'_a \in \bar{\mathcal{Y}}} \mu(y'_a, \mathbf{y}_{-a}) P_a(y_a | y'_a, \mathbf{y}_{-a}) \right\} &= \mu(\mathbf{y}) \\
\frac{1}{\sum_{a \in \mathcal{A}} \lambda_a} \sum_{a \in \mathcal{A}} \lambda_a P_a(y_a | \mathbf{y}) \mu_{-a}(\mathbf{y}_{-a}) &= \mu(\mathbf{y}).
\end{aligned}$$

In moving from the fifth line to the sixth one we used the fact that, in our model, $P_a(y_a | y'_a, \mathbf{y}_{-a}) = P_a(y_a | \mathbf{y}_{-a})$ for any $y'_a \in \bar{\mathcal{Y}}^A$. From Proposition 1, μ satisfies

$$\mu(\mathbf{y}) = \frac{1}{A} \sum_{a \in \mathcal{A}} P_a(y_a | \mathbf{y}) \mu_{-a}(\mathbf{y}_{-a}) \text{ for each } \mathbf{y} \in \bar{\mathcal{Y}}^A. \quad (5)$$

We only need to show that if $(P_a)_{a \in \mathcal{A}}$ is a set of compatible conditional distributions, then $\mu = P$ solves (5). If we let $\mu = P$, then right hand side of (5) is

$$\frac{1}{A} \sum_{a \in \mathcal{A}} P_a(y_a | \mathbf{y}) \sum_{v \in \bar{\mathcal{Y}}} P(v, \mathbf{y}_{-a}) = \frac{1}{A} \sum_{a \in \mathcal{A}} P(\mathbf{y}) = \frac{A}{A} P(\mathbf{y}) = P(\mathbf{y}).$$

In addition, the left hand side of (5) is

$$\mu(\mathbf{y}) = P(\mathbf{y}).$$

Thus $\mu(\mathbf{y}) = P(\mathbf{y})$ solves (5) for each $\mathbf{y} \in \bar{\mathcal{Y}}^A$. ■

As we mentioned earlier, the existence of Gibbs equilibria also require the set of conditional probabilities $(P_a)_{a \in \mathcal{A}}$ to be compatible. We formalize this idea next.

Definition: We say $(P_a)_{a \in \mathcal{A}}$ is a set of compatible conditional distributions if there exists a joint distribution $P: \bar{\mathcal{Y}}^A \rightarrow [0, 1]$, with $\sum_{\mathbf{y} \in \bar{\mathcal{Y}}^A} P(\mathbf{y}) = 1$, such that

$$P_a(y_a | \mathbf{y}) = P(\mathbf{y}) / \sum_{y_a \in \bar{\mathcal{Y}}} P(\mathbf{y}) \text{ for each } \mathbf{y} \in \bar{\mathcal{Y}}^A.$$

The technical conditions required for a set of conditional distributions to be compatible are discussed in Kaiser and Cressie (2000). Their analysis implies that compatibility demands strong symmetric restrictions. In particular, in the two people, two actions case, Arnold and Press (1989) show that compatibility holds if and only if the next equality is satisfied

$$\frac{1 - Q_1(1|0)}{Q_1(1|0)} \frac{Q_1(1|1)}{1 - Q_1(1|1)} = \frac{1 - Q_2(1|0)}{Q_2(1|0)} \frac{Q_2(1|1)}{1 - Q_2(1|1)}.$$

The last result states that, under specific conditions, the Gibbs equilibrium coincides with μ . A similar connection is discussed in Blume and Durlauf (2003).

Proposition 8 *Assume A1 and G1 hold. If $(P_a)_{a \in A}$ is a set of compatible conditional distributions, then $P_a(y_a|\mathbf{y}) = \mu(\mathbf{y}) / \mu_{-a}(\mathbf{y}_{-a})$ for each $\mathbf{y} \in \bar{\mathcal{Y}}^A$.*

Appendix II: Simulation for Section 5

This appendix describes how we generated the observations for the restaurant model

Let $\lambda = \sum_{a \in \mathcal{A}} \lambda_a$. We generate the data according to an iterative procedure for a fixed time period \mathcal{T} . The k -th iteration of the procedure is as follows:

- (i) Given \mathbf{y}_{k-1} set $\mathbf{y}_k = \mathbf{y}_{k-1}$;
- (ii) Generate a draw from the exponential distribution with mean $1/\lambda$ and call it x_k ;
- (iii) Randomly sample an agent from the set \mathcal{A} , such that the probability that a is picked is λ_a/λ ;
- (iv) Given the agent selected in the previous step and the current choice configuration \mathbf{y}_k construct a consideration set using Q_a ;
- (v) If the consideration set is empty, then set $y_{a,k} = 0$. Otherwise pick the best alternative according to the preference order of agent a from the consideration set and assign it to $y_{a,k}$.

Given the initial configuration of choices \mathbf{y}_0 we applied the above algorithm till we reached $\sum_k x_k > \mathcal{T}$ (On average the length of the sequence is $\lambda\mathcal{T}$). Define $z_k = \sum_{l \leq k} x_l$. The continuous time data is $\{(y_k, z_k)\}$. The discrete time data is obtained from the continuous time data by splitting the interval $[0, \mathcal{T}]$ into $T = \lceil \mathcal{T}/\Delta \rceil$ intervals and recording the configuration of the network at every time period $t = i\Delta, i = 0, 1, \dots, \lceil \mathcal{T}/\Delta \rceil$.

To elaborate a bit more on the estimation of the attention mechanism, we also generated 1000 data samples over the period of $[0, 25000]$ and then for $\Delta \in \{5/3, 5/2, 5, 25\}$ constructed discrete data sets (the sample size $\{1000, 5000, 10000, 15000\}$). The network structure and the preference orders were assumed to be known. (Its values are as the ones in Section 5.) So only optimization over the consideration probabilities was performed. The results of the

simulations are presented in the next table (Table 1 in Section 5).

Table. Bias and Root Mean Squared Error (RMSE) ($\times 10^{-3}$)

Sample Size		$Q(v 0)$	$Q(v 1)$	$Q(v 2)$
1000	Bias	42.3	18.0	15.1
	RMSE	43.3	20.9	17.8
5000	Bias	9.4	2.7	0.3
	RMSE	10.2	5.6	4.4
10000	Bias	4.7	-0.6	-0.5
	RMSE	5.5	3.5	3.3
15000	Bias	3.5	-1.3	2.8
	RMSE	4.2	3.3	-0.3

Notes: The sample sizes correspond to $\Delta = 25$ for the sample size 1000, $\Delta = 5$ for the sample size 5000, $\Delta = 5/2$ for the sample size 10000, and $\Delta = 5/3$ for the sample size 15000. The number of replications is 1000.