Random Moments for Sketched Mixture Learning

Nicolas Keriven¹², Rémi Gribonval², Gilles Blanchard³, Yann Traonmilin²

¹Université Rennes 1 ²Inria Rennes Bretagne-atlantique ³University of Potsdam

SPARS 2017

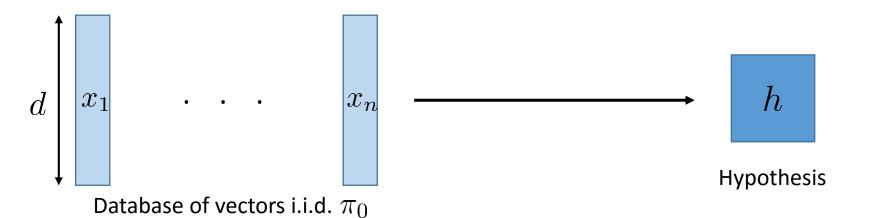


Outline

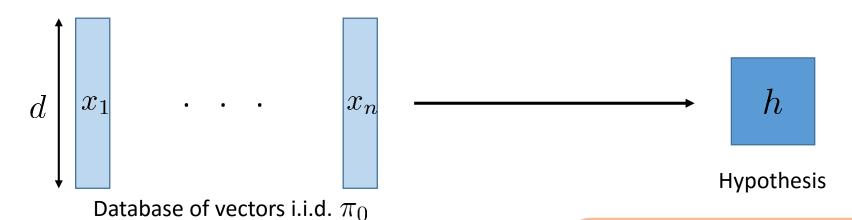
- (1) Introduction
- 2 Illustration
- (3) Main results
- 4 Conclusion



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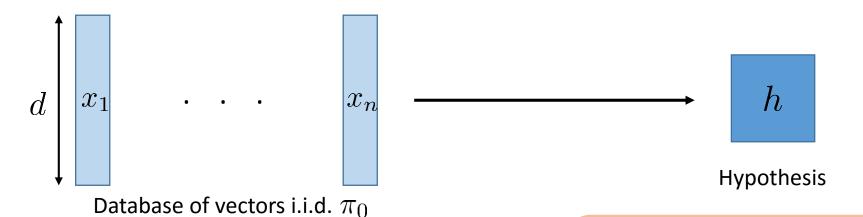






- PCA: $\mathbf{x} \in Span(h_1, ..., h_k)$
- Classification : $< h, \Phi(\mathbf{x}) >$
- Regression : $\mathbf{y} = h(\mathbf{x})$
- k-means : $h = \{c_l\}_{l=1}^k$
- Density estimation : $\mathbf{x} \sim \pi_h$





Loss function

$$\ell(x,h) \in \mathbb{R}$$

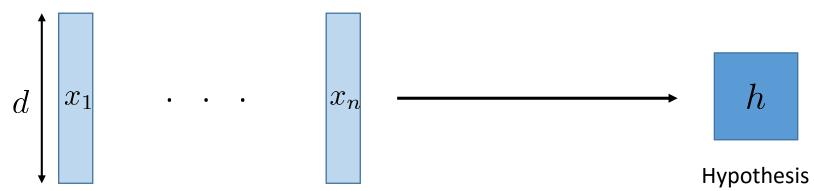
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Database of vectors i.i.d. π_0

Loss function

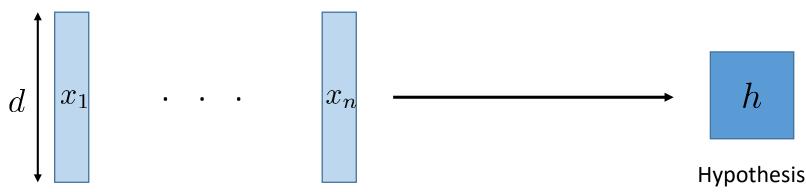
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Goal: Minimize Expected Risk

$$h^* = \arg\min_{h \in \mathcal{H}} \mathbb{E}_{x \sim \pi_0} \ell(x, h)$$

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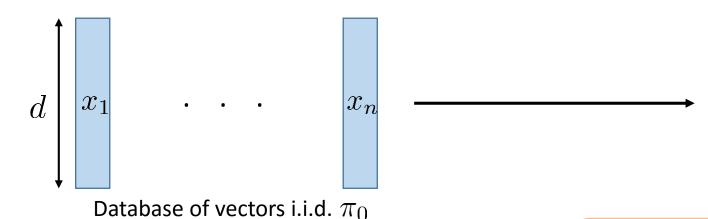
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$$lacktriangle$$
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Hypothesis

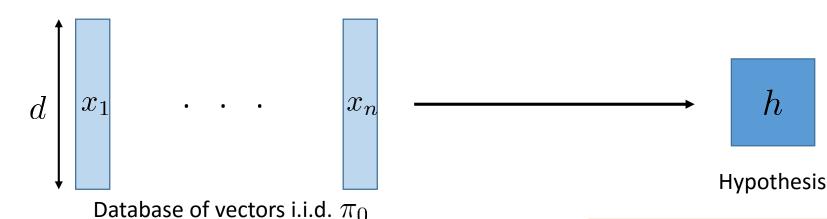
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Large d or n





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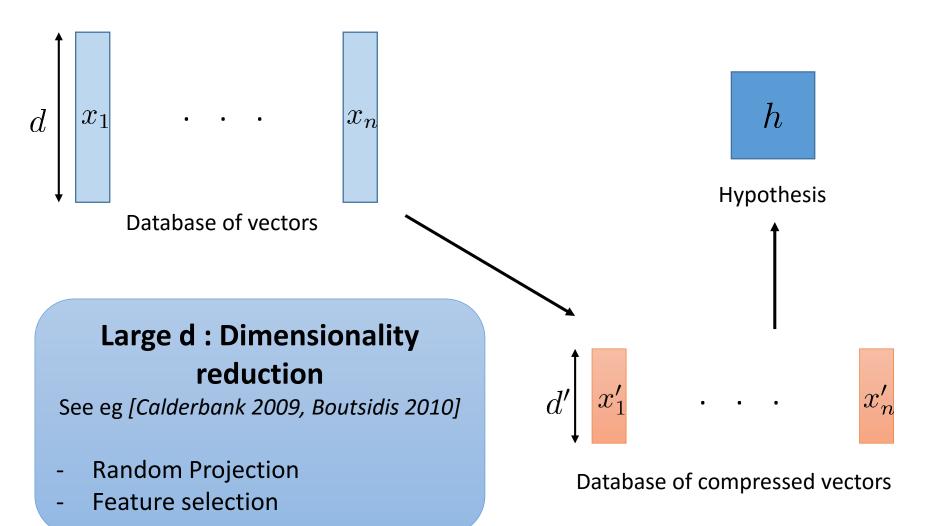
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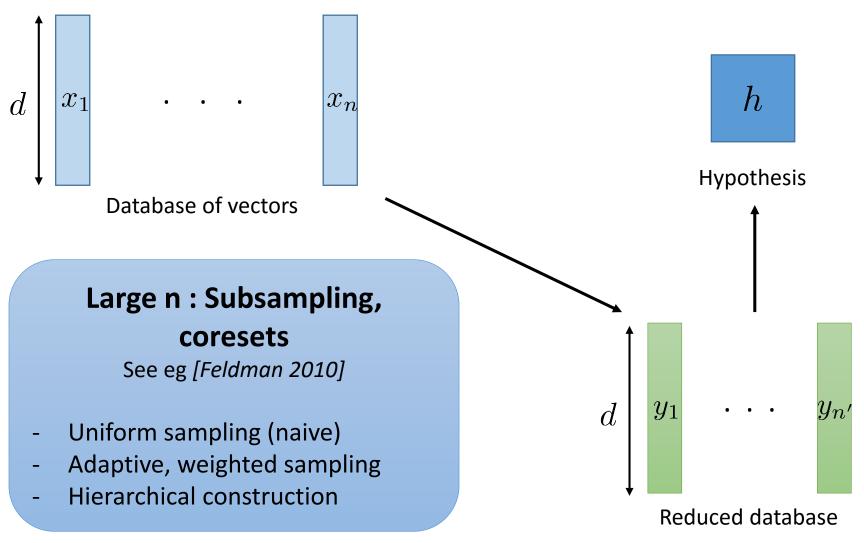
Compress the database before learning

Compressive Statistical Learning

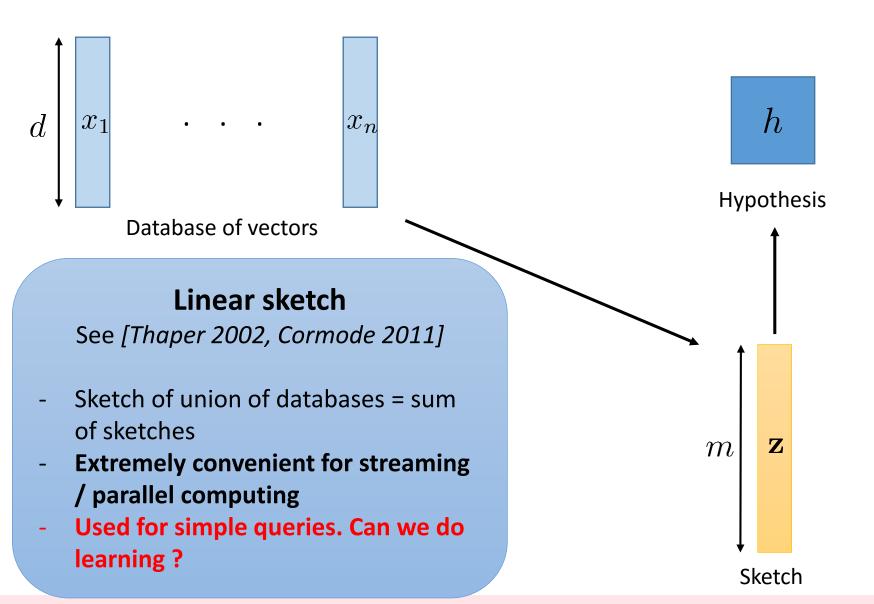




Compressive Statistical Learning



Compressive Statistical Learning





Linear sketch = Empirical generalized moments...

$$\mathbf{z} = \left(\frac{1}{n}\right) \sum_{i=1}^{n} \Phi(x_i)$$



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... i.e. linear measurements of underlying probability distribution

$$\mathbf{z} \approx \mathbb{E}_{x \sim \pi_0} \Phi(x) = \mathcal{A} \pi_0$$

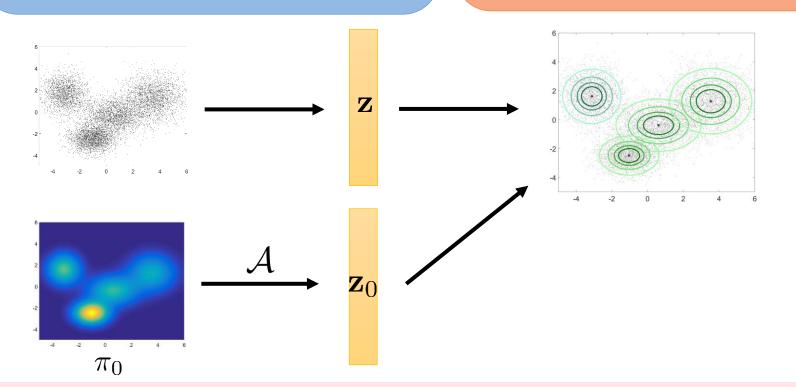


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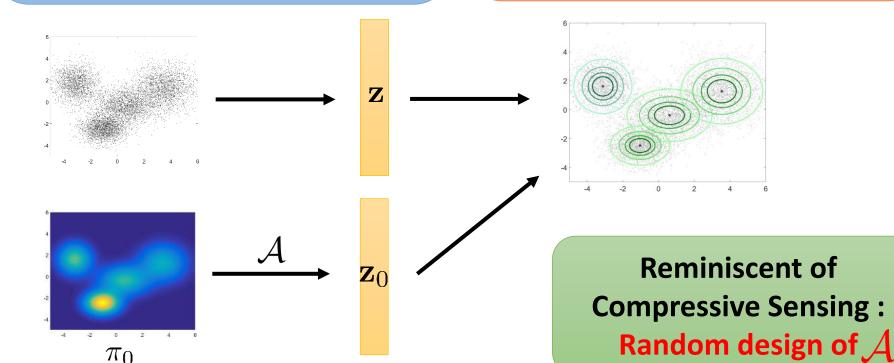


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- 2 Illustration (previous work)
- (3) Main results
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Experimental illustration

Compressive Learning-OMP algorithm [Keriven 2015,2016] (OMP + non-convex updates)

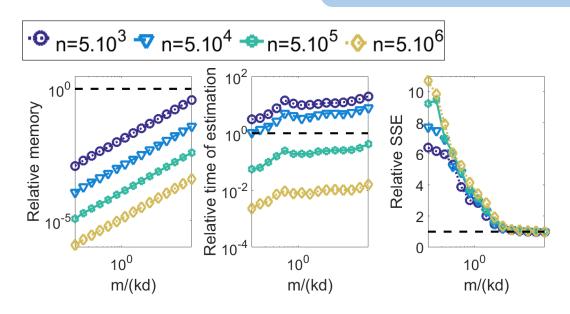


Experimental illustration

k-means (d=10, k=10)

Compressive Learning-OMP algorithm [Keriven 2015,2016]

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Comparison with

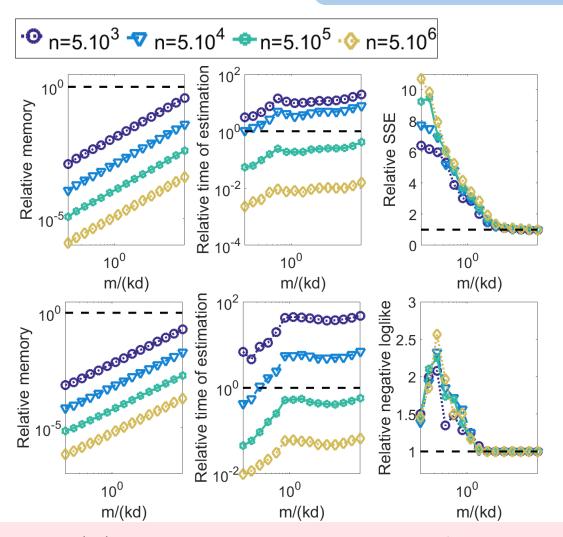
- Matlab's kmeans
- VLFeat's gmm
- Faster and more memory efficient on large databases
- Number of measurements does not depend on n



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GMMs (d=10, k=10)

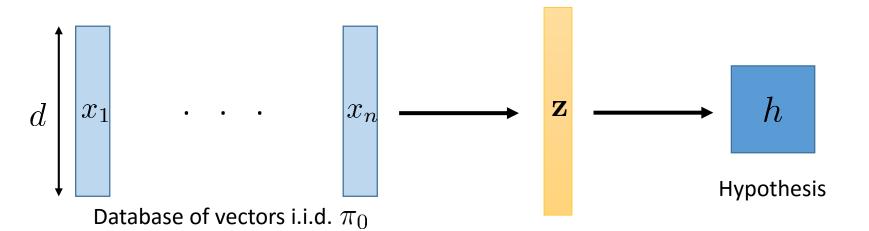


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Loss function

$$\ell(x,h)$$

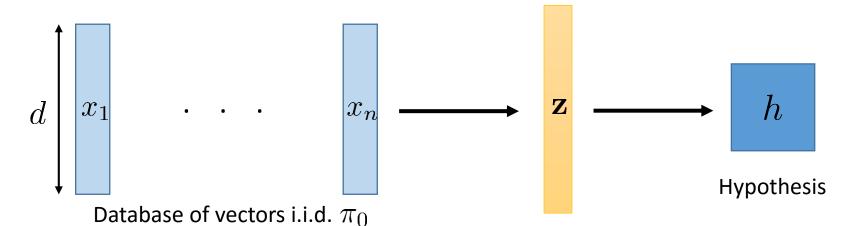
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Here:

- k-means
- GMM with known covariance



Hyp. class
$$h=\{c_1,...,c_k\}\subset\mathbb{R}^d$$



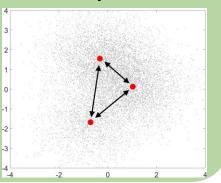
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 $\mathcal{H}_{k,arepsilon,M}$

• *M* - bounded domain

(centroids, not samples)





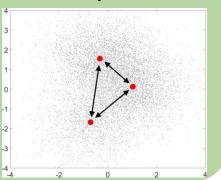
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• ε - separation



Loss function

$$\ell(x,h) = \min_{1 \le l \le k} ||x - c_l||_2^2$$



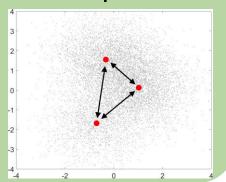
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$$\ell(x,h) = \min_{1 < l < k} ||x - c_l||_2^2$$

Sketching operator

$$\{\omega_1, ..., \omega_m\} \subset (\mathbb{R}^d)^m$$

$$\Phi(x) = \left[e^{-i\omega_j^T x} / c_{\omega_j} \right]_{j=1}^m$$

- (weighted) Random Fourier sampling
- « Smoothing » weights $\,c_{\omega} \propto \|\omega\|_2^2\,$

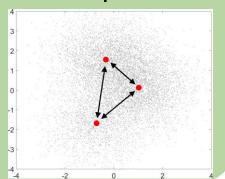
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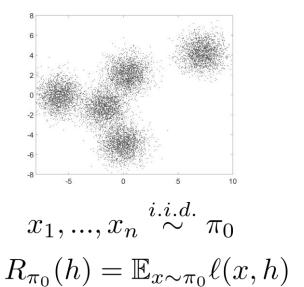
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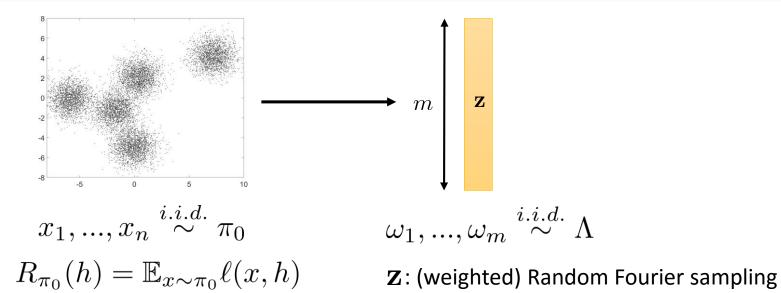
$$\omega_j \overset{i.i.d.}{\sim} \Lambda(\omega) \propto c_\omega^2 \mathcal{N}(0, \sigma^2 \mathbf{Id})$$

$$\sigma^2 \propto \varepsilon^{-1}$$

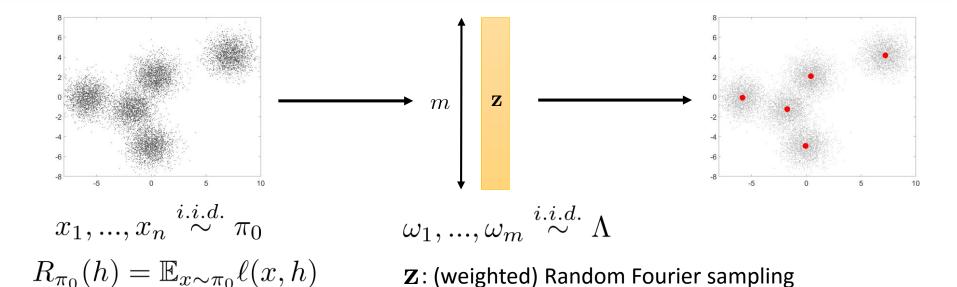
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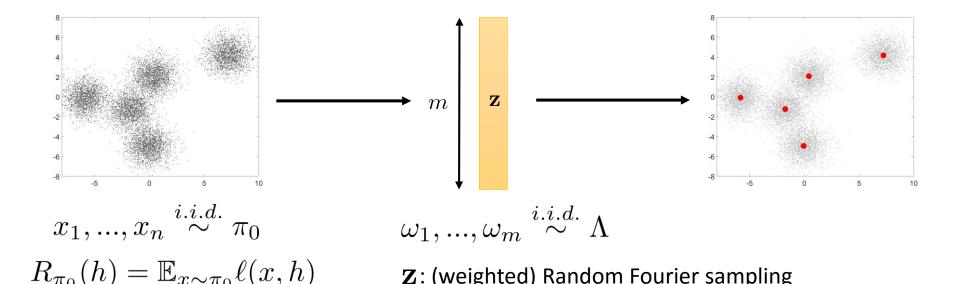


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$$\hat{h} = \min_{h \in \mathcal{H}_{k,\varepsilon,M}} \min_{\alpha \ge 0, \sum_{l} \alpha_{l} = 1} \|\mathbf{z} - \mathcal{A}(\sum_{l=1}^{k} \alpha_{l} \delta_{c_{l}})\|_{2}$$





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$$h^{\star} = \min_{h \in \mathcal{H}_{k,\varepsilon,M}} R_{\pi_0}(h)$$
 If $m \geq \mathcal{O}\left(k^2 d^2(\operatorname{polylog}(k,d) + \log(M/\varepsilon))\right)$

w.h.p. on
$$x_i, \; \omega_j$$
 $R_{\pi_0}(\hat{h}) \lesssim R_{\pi_0}(h^\star) + \mathcal{O}\left(\sqrt{1/n}\right)$

Z: (weighted) Random Fourier sampling

Hyp. class
$$h = \{(\mu_1, \alpha_1), ..., (\mu_k, \alpha_k)\} \subset \mathbb{R}^d \times \mathbb{R}_+$$



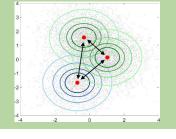
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$$\mathcal{H}_{k,arepsilon,M}$$

M - bounded domain

(means, not samples)





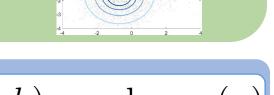
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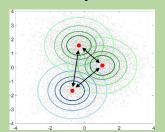
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GMM with known covariance \sum

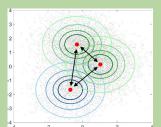
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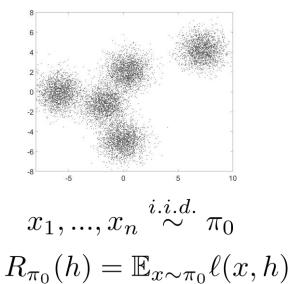
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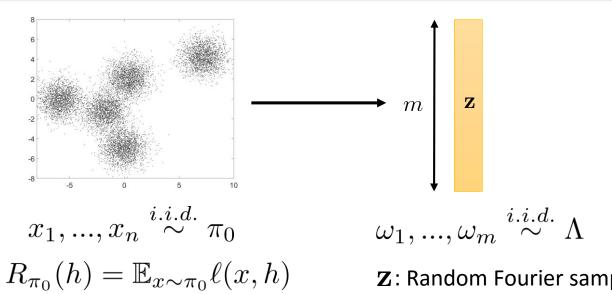
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$$\sigma^2$$
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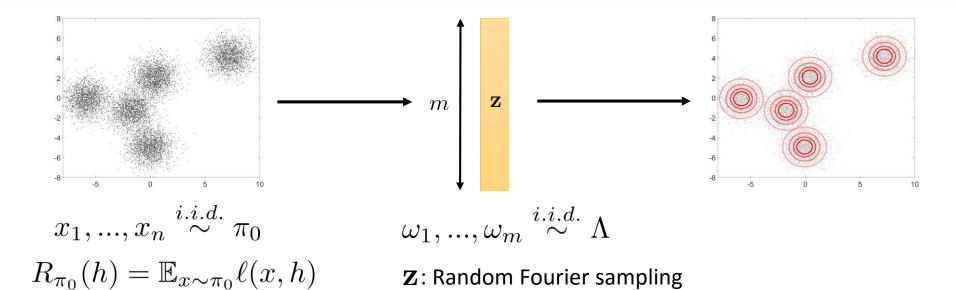






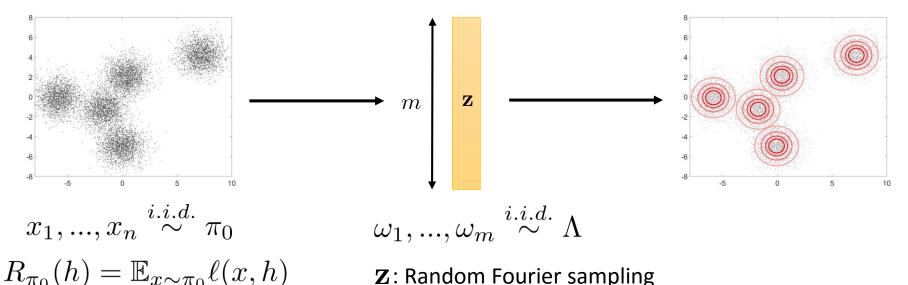
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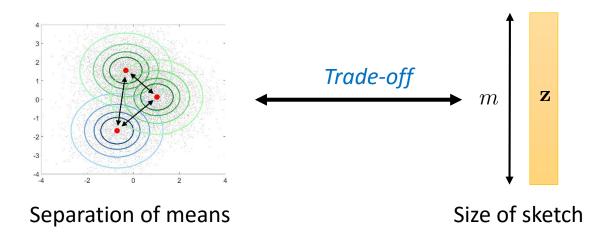
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$$h^\star = \min_{h \in \mathcal{H}_{k, \varepsilon, M}} R_{\pi_0}(h)$$
 Trade-off with ε_0 minimal separation

w.h.p.
$$\left[R_{\pi_0}(\hat{h}) - R_{\pi_0}(h^\star) \lesssim \sqrt{D_{KL}(\pi_0||\mathcal{H}_{k,arepsilon,M})} + \mathcal{O}\left(\sqrt{1/n}
ight)
ight]$$

If

GMM trade-off



More high frequencies

Separation of means	Number of measurements
$\mathcal{O}\left(\sqrt{d\log k}\right)$	$m \geq \mathcal{O}\left(k^2d^2 \cdot \mathrm{polylog}(k,d)\right)$
$\mathcal{O}\left(\sqrt{d + \log k}\right)$	$m \geq \mathcal{O}\left(k^3d^2 \cdot \mathrm{polylog}(k,d)\right)$
$\mathcal{O}\left(\sqrt{\log k}\right)$	$m \geq \mathcal{O}\left(k^2d^2e^d \cdot \mathrm{polylog}(k,d)\right)$



Sketch Size

Non-convex optimization. Greedy heuristic: CL-OMP [Keriven 2016]

In theory, at least

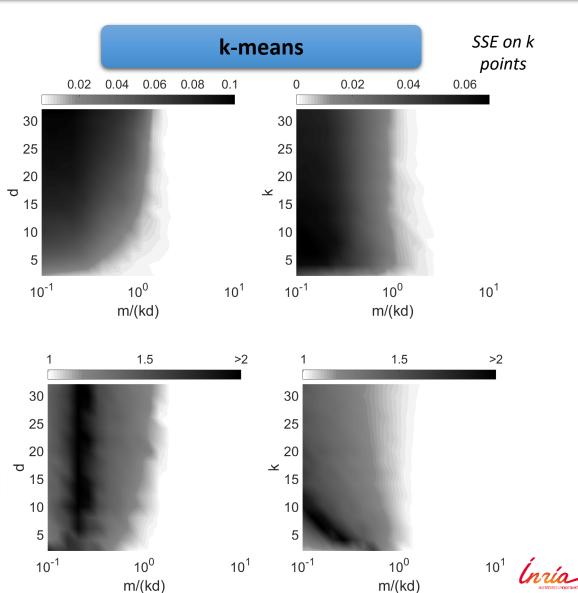
$$m \ge \mathcal{O}(k^2d^2)$$

Empirically

$$m \approx \mathcal{O}(kd)$$

GMMs, known cov.

Relative loglike



Key idea 1

Sketching operator =

Kernel mean embedding [Smola 2007]

+ Random Features [Rahimi 2007]

Step 1

Relate risk to kernel metric



Key idea 1

Sketching operator =

Kernel mean embedding [Smola 2007]

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Key idea 2

Compressive Sensing analysis

[Bourrier 2014]

Step 1

Relate risk to kernel metric

Step 2

 ${\cal A}$ satisfies the RIP



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Main difficulty

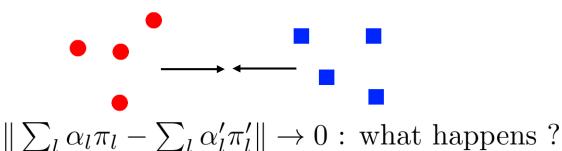
Controlling metrics between **mixtures** that get **close to each other** in infinite-dimensional space

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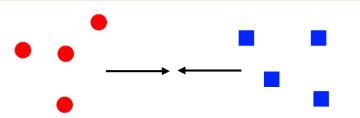
Key idea 2

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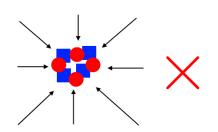


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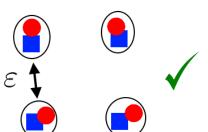
Relate risk to kernel metric

Step 2

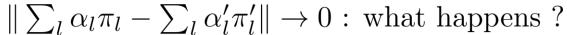
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No hypothesis



Separation hypothesis





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(3) Experimental illustration

(4) Conclusion



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Conclusions

Contributions

- Efficient sketched mixture learning framework, using random generalized moments
- Combination of many tools:
 - Kernel mean embedding
 - Random Fourier features
 - Analysis inspired by Compressive Sensing



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Outlooks

- Bridge gap theory / practice
- Other models (done in practice), with other sketching operators
- Non-linear sketches ? (neural networks...)

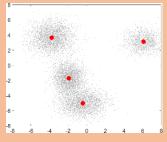


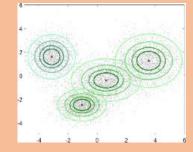
The SketchMLbox

SketchMLbox (sketchml.gforge.inria.fr)

- Mixture of Diracs (« K-means »)
- GMMs with known covariance
- GMMs with unknown diagonal covariance
- Soon:
 - Mixtures of multivariate alpha-stable (only known algorithm!)
 - Gaussian Locally Linear Mapping [Deleforge 2014]













Thank you!

- K., Bourrier, Gribonval, Perez. Sketching for Large-Scale Learning of Mixture Models ICASSP 2016
- K., Bourrier, Gribonval, Perez. **Sketching for Large-Scale Learning of Mixture Models** (extended version) *submitted to Information and Inference, arXiv:1606.0238*
- K., Tremblay, Gribonval, Traonmilin. Compressive K-means ICASSP 2017
- K., Tremblay, Gribonval. SketchMLbox (sketchml.gforge.inria.fr)
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Appendix : CLOMPR

```
Algorithm 2: Compressive mixture learning à la OMP: CLOMP (T = K) and CLOMPR (T = 2K)
  Data: Empirical sketch \hat{\mathbf{z}}, sketching operator \mathcal{A}, sparsity K, number of iterations T > K
  Result: Support \Theta, weights \alpha
  \hat{\mathbf{r}} \leftarrow \hat{\mathbf{z}}; \, \Theta \leftarrow \emptyset \; ;
  for t \leftarrow 1 to T do
         Step 1: Find a normalized atom highly correlated with the residual with a gradient descent
              \theta \leftarrow \text{maximize}_{\theta} \left( \text{Re} \left\langle \frac{AP_{\theta}}{\|AP_{\theta}\|_{2}}, \hat{\mathbf{r}} \right\rangle_{2}, \text{init} = \text{rand} \right);
         end
         Step 2: Expand support
          \Theta \leftarrow \Theta \cup \{\theta\};
         end
         Step 3: Enforce sparsity by Hard Thresholding if needed
               if |\Theta| > K then
                    \beta \leftarrow \arg\min_{\beta \geq 0} \left\| \hat{\mathbf{z}} - \sum_{k=1}^{|\Theta|} \beta_k \frac{AP_{\theta_k}}{\|AP_{\theta_k}\|_2} \right\|_2 Select K largest entries \beta_{i_1}, ..., \beta_{i_K};
                     Reduce the support \Theta \leftarrow \{\theta_{i_1}, ..., \theta_{i_K}\};
         Step 4: Project to find weights
              \alpha \leftarrow \arg\min_{\alpha \geq 0} \left\| \hat{\mathbf{z}} - \sum_{k=1}^{|\Theta|} \alpha_k \mathcal{A} P_{\boldsymbol{\theta}_k} \right\|_{\cdot}
         Step 5: Perform a gradient descent initialized with current parameters
               \Theta, \alpha \leftarrow \min \mathtt{minimize}_{\Theta, \alpha} \left( \left\| \hat{\mathbf{z}} - \sum_{k=1}^{|\Theta|} \alpha_k \mathcal{A} P_{\theta_k} \right\|_2, \mathtt{init} = (\Theta, \alpha), \mathtt{constraint} = \{\alpha \geq 0\} \right);
         end
        Update residual: \hat{\mathbf{r}} \leftarrow \hat{\mathbf{z}} - \sum_{k=1}^{|\Theta|} \alpha_k \mathcal{A} P_{\theta_k}
  Normalize \alpha such that \sum_{k=1}^{K} \alpha_k = 1
```

