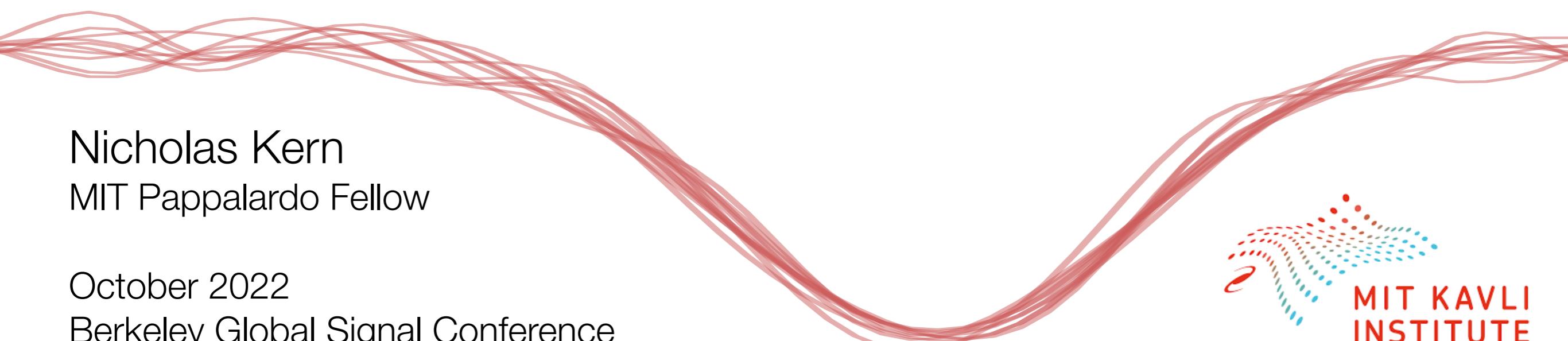


Pushing Inference to the Sky: A Differentiable Forward Model for the 21 cm Global Signal (work in progress..)



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Berkeley Global Signal Conference



1. How does performing inference on the sky help?

- More faithful accounting of beam, FGs, and their degeneracies
- Fully exploit correlations in the data between LSTs

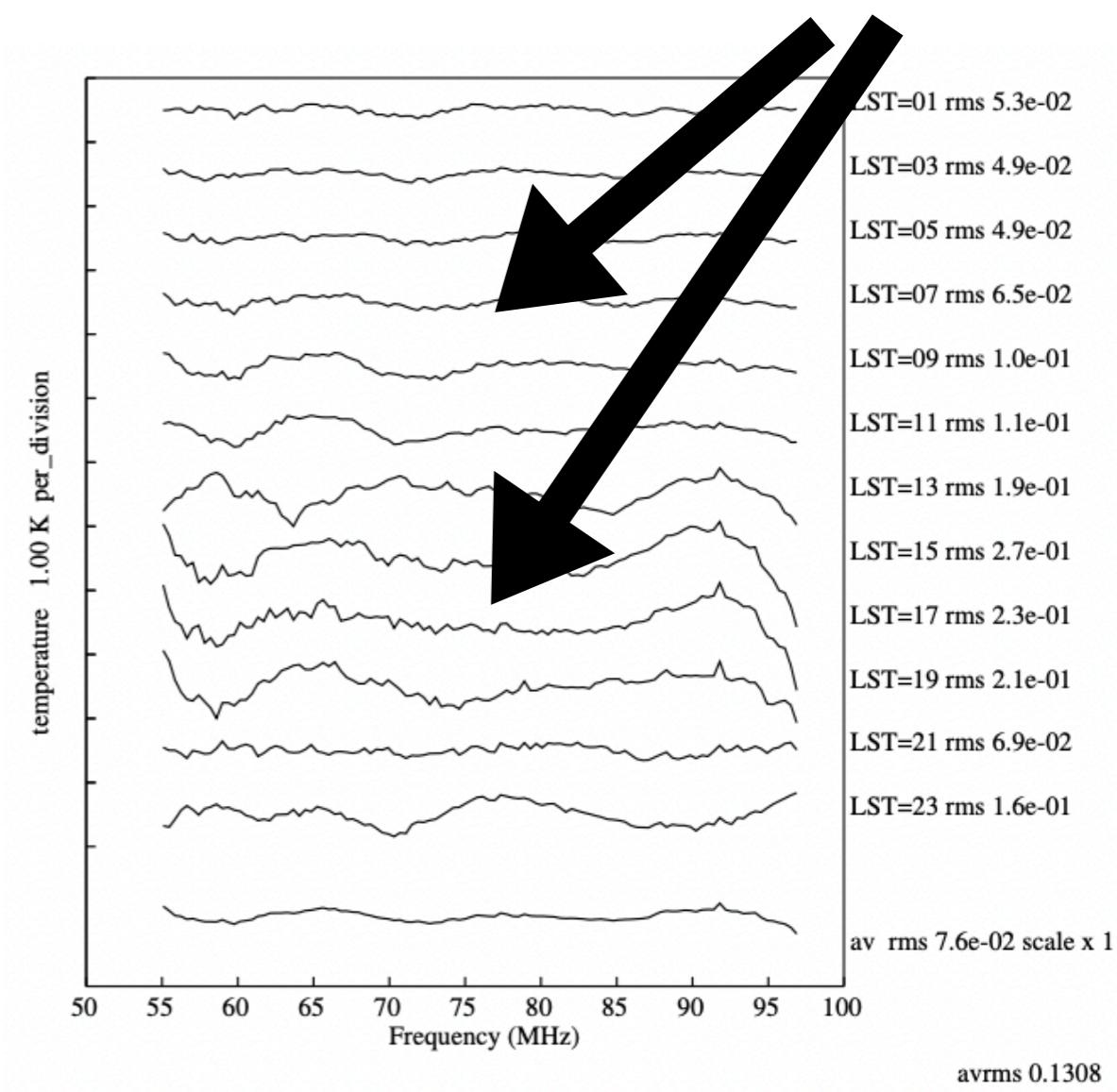
2. Is detection theoretically possible?

- Even in ideal circumstances, 21 cm global signal extraction is **highly degenerate** with FG spectral modes (c.f. Liu et al. 2012)
- Forward modeling of **flexible** but **regularized** sky + instrument models is key to a robust 21 cm GS constraint

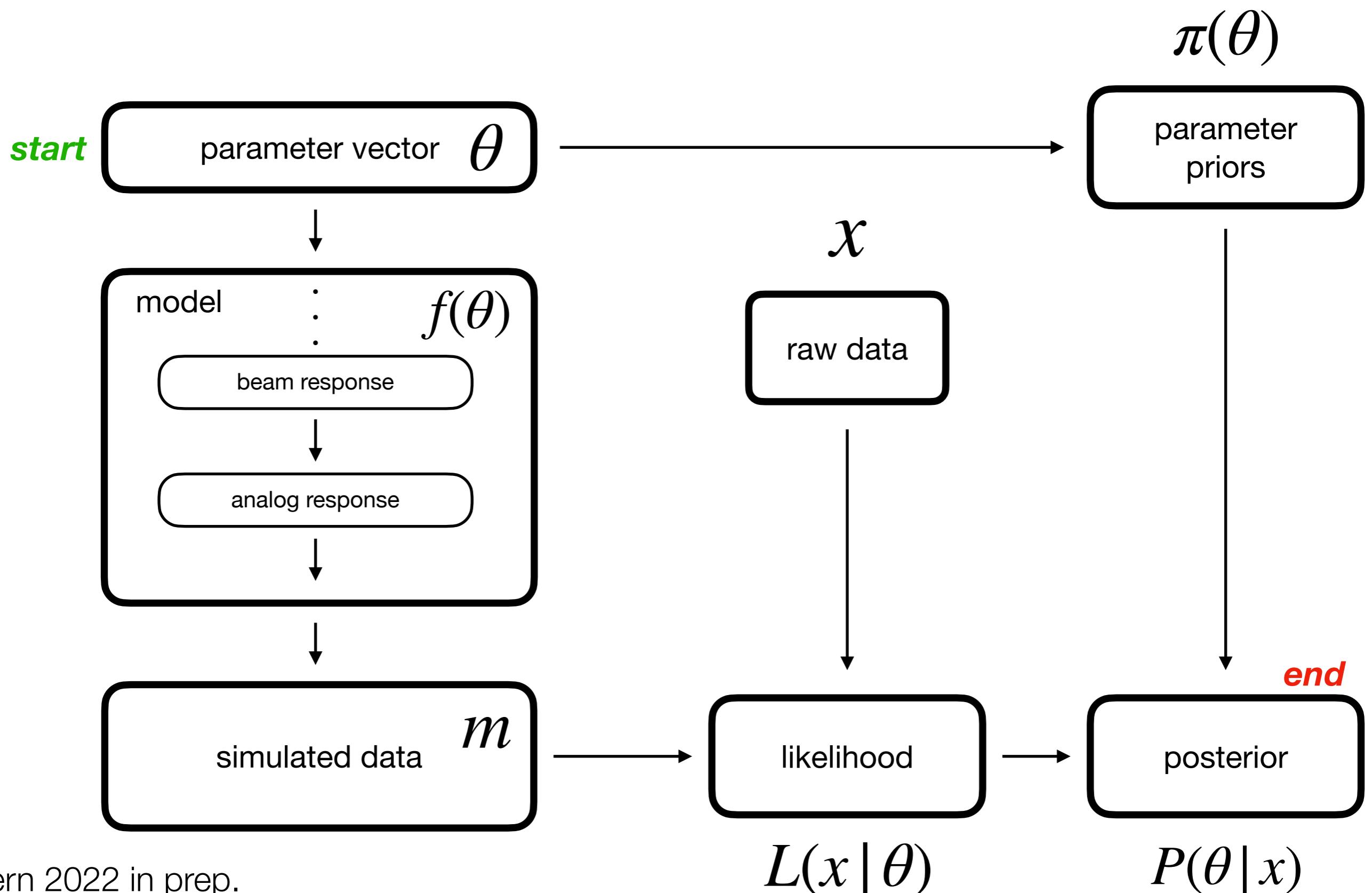
Why an end-to-end forward model?

- Robust signal extraction must understand the joint posterior between the **beam**, **FG**, and **21 cm** signal
- This requires a data model that **starts on the sky**, as opposed to a spectrum-based data model
- Including the visibility sky integral in our data model allows us to fully (and properly) exploit correlations between LSTs

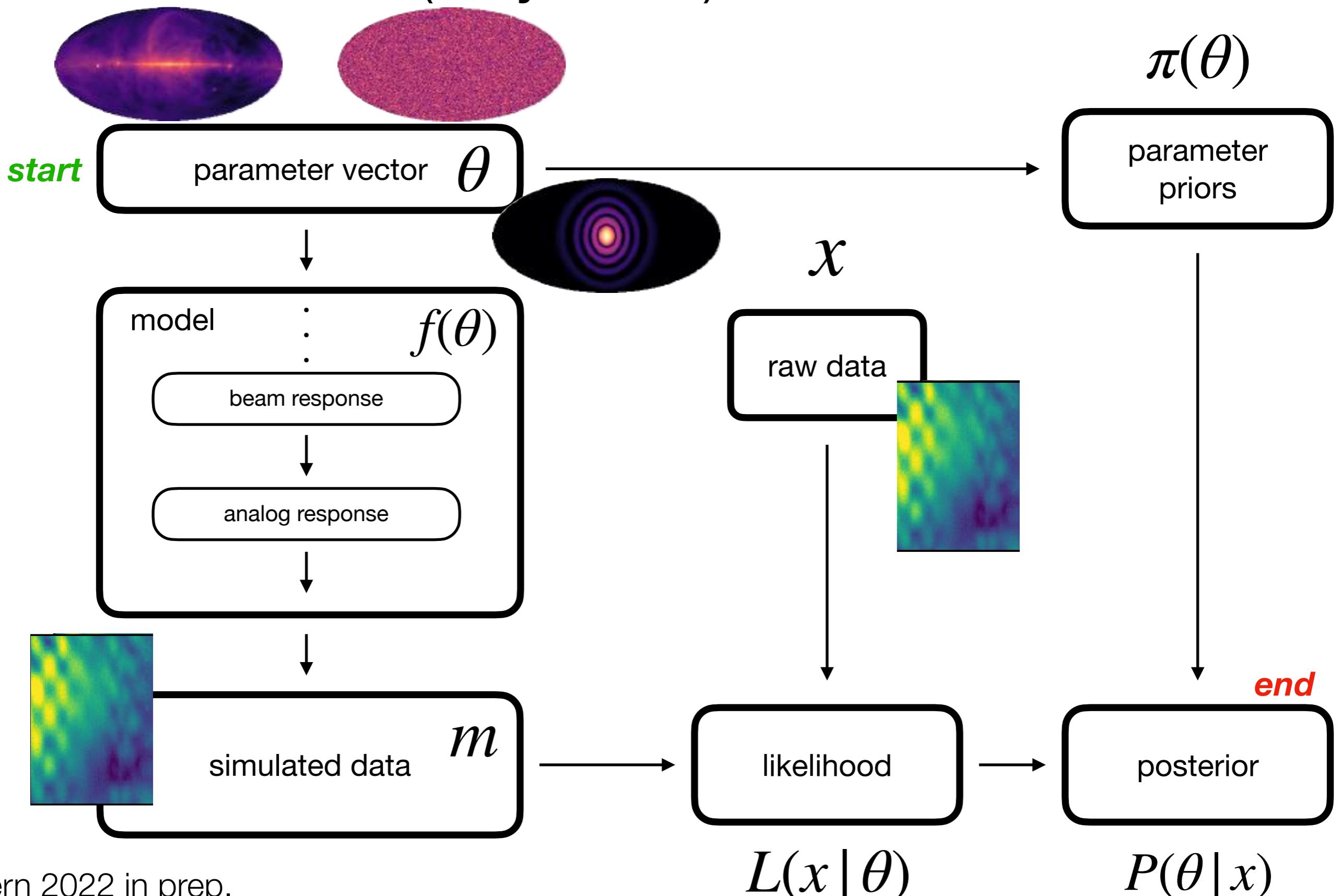
fully exploit
correlations between LSTs



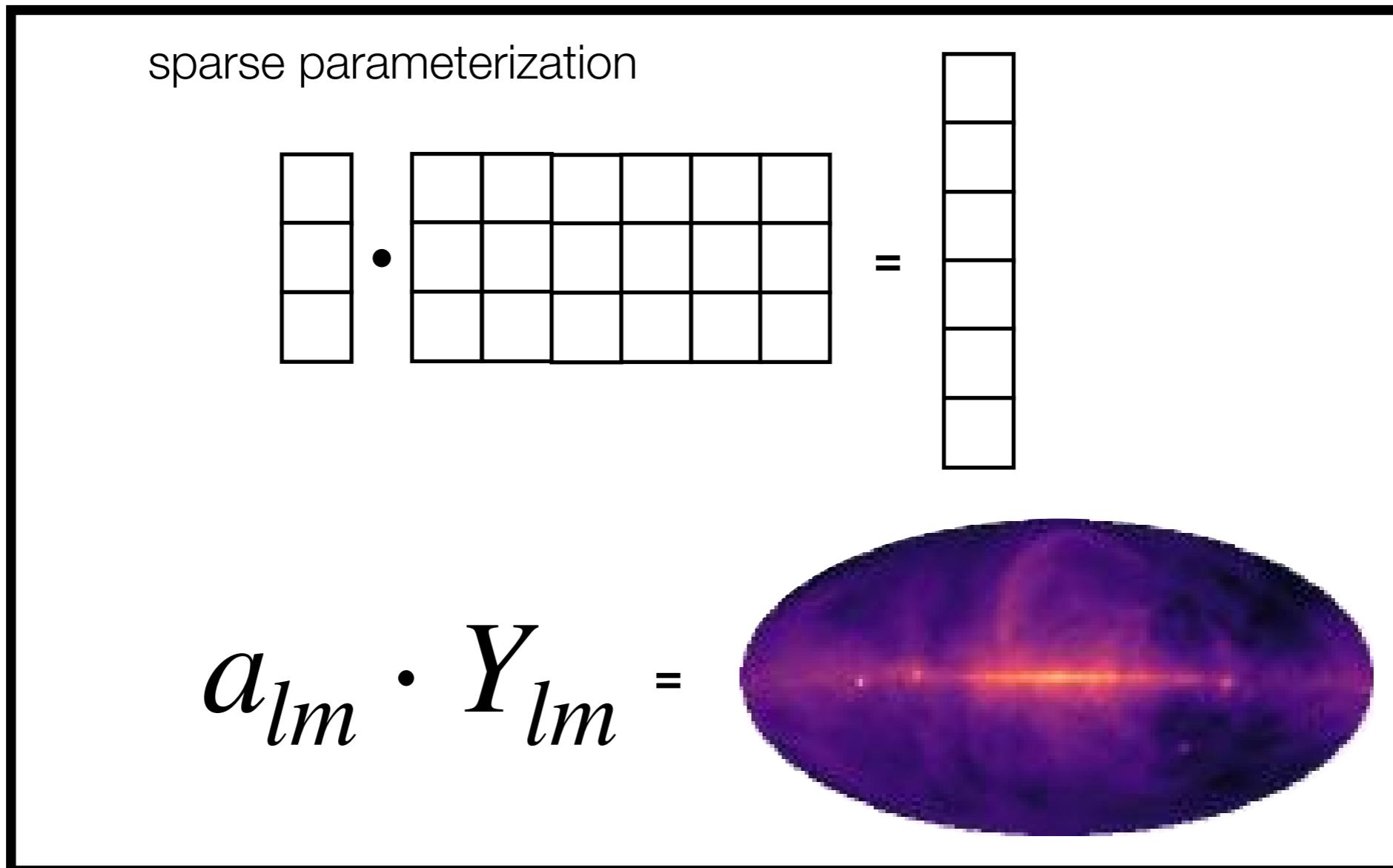
What is a (Bayesian) forward model?



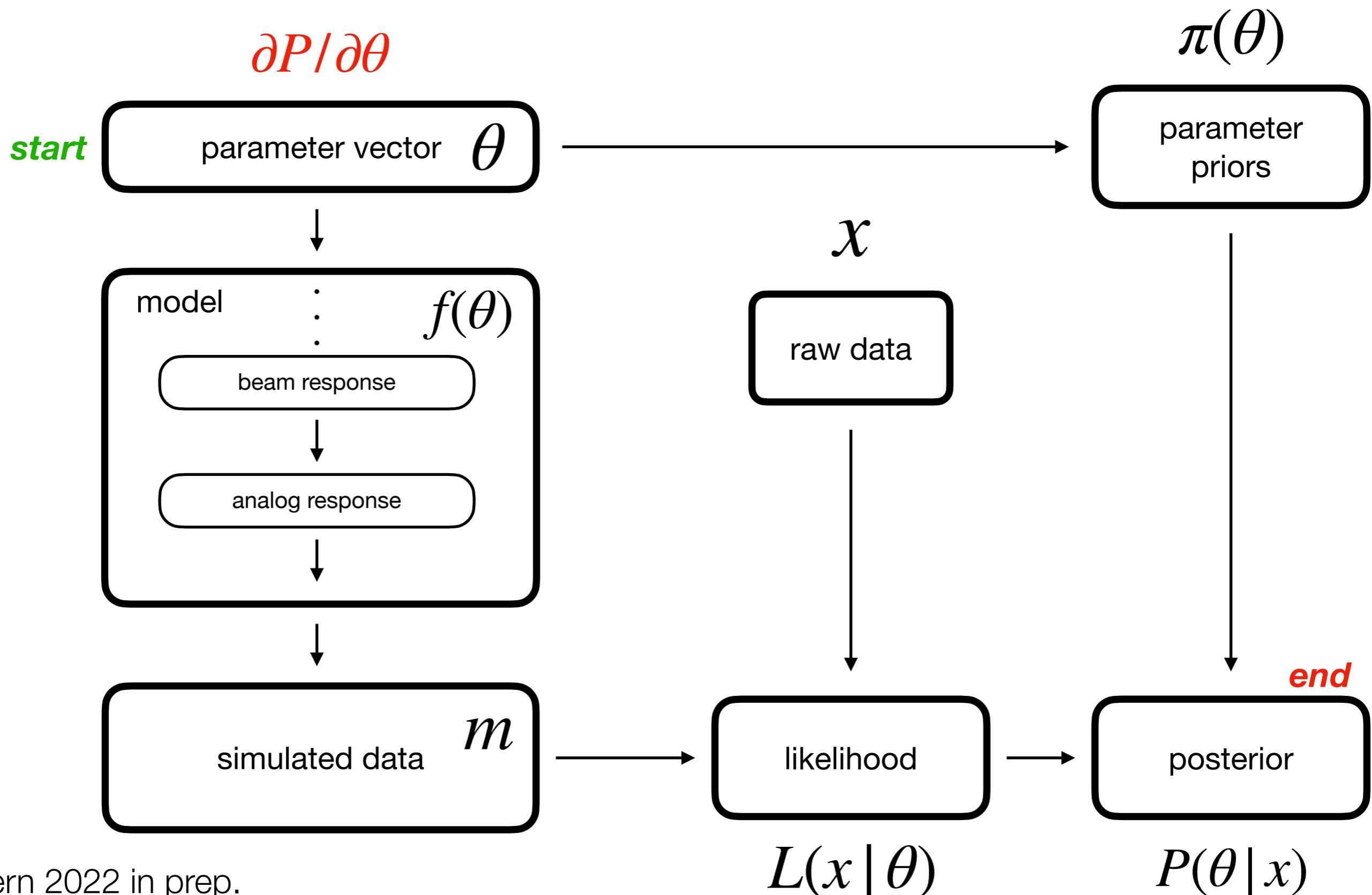
What is a (Bayesian) forward model?



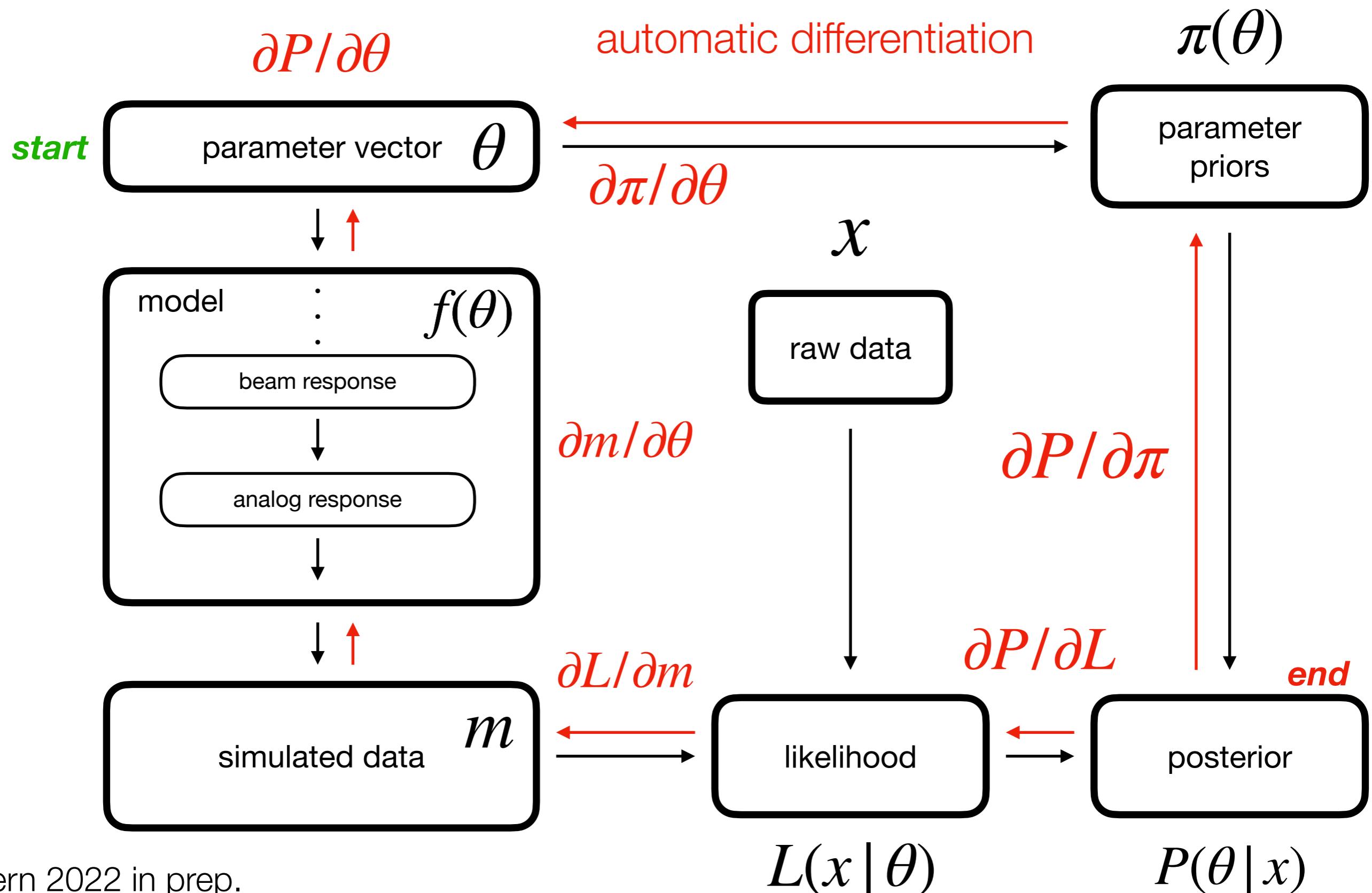
What is a (Bayesian) forward model?



How to make it differentiable?

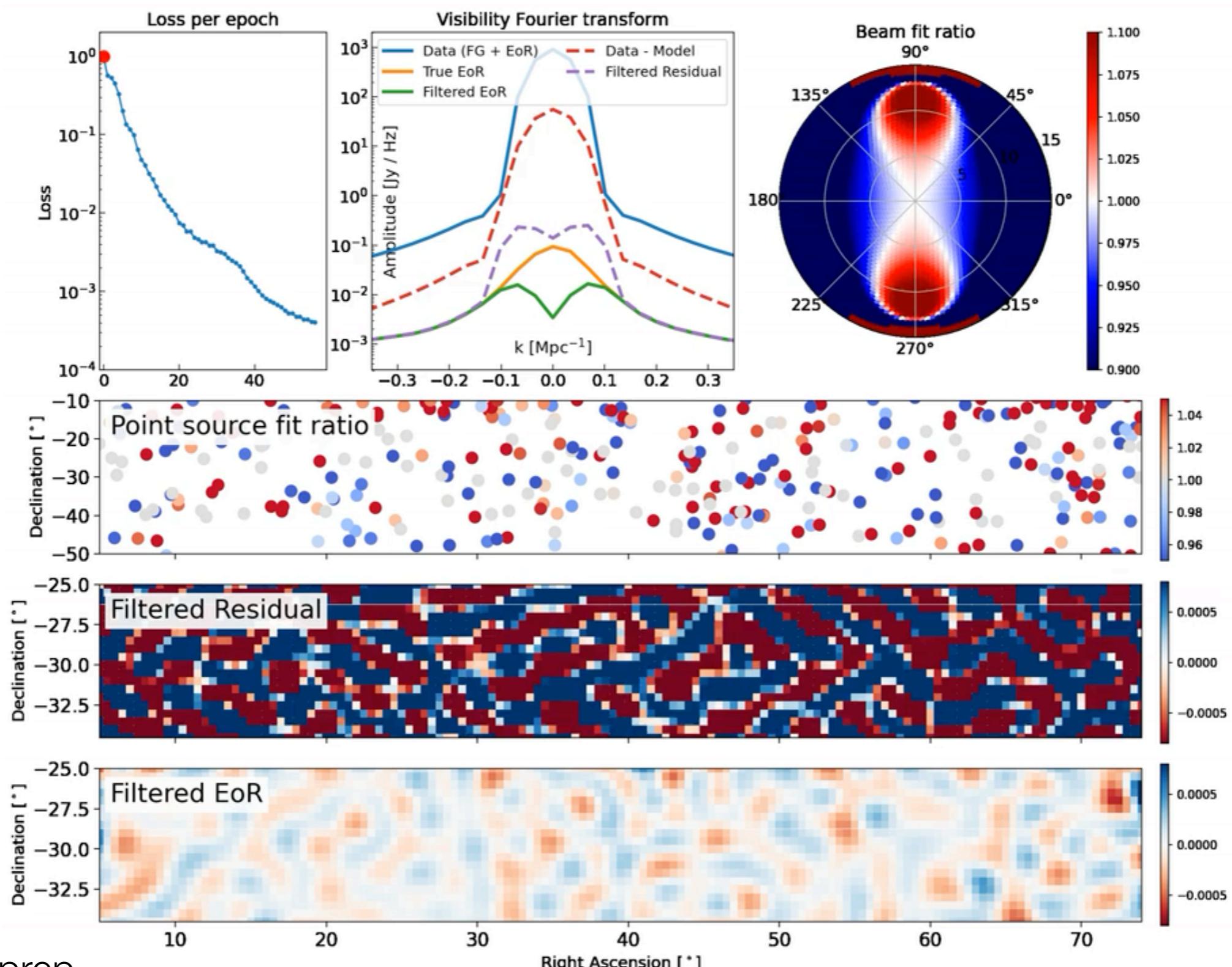


How to make it differentiable?



Example with an interferometer

point source + beam optimization



For now: testing degeneracies

For now: testing degeneracies

Posterior expansion via the Fisher matrix (aka the -Hessian)

$$F_{ij} = - \frac{\partial^2 \ln P}{\partial \theta_i \partial \theta_j}$$

Can compute the Hessian exactly via automatic diff.

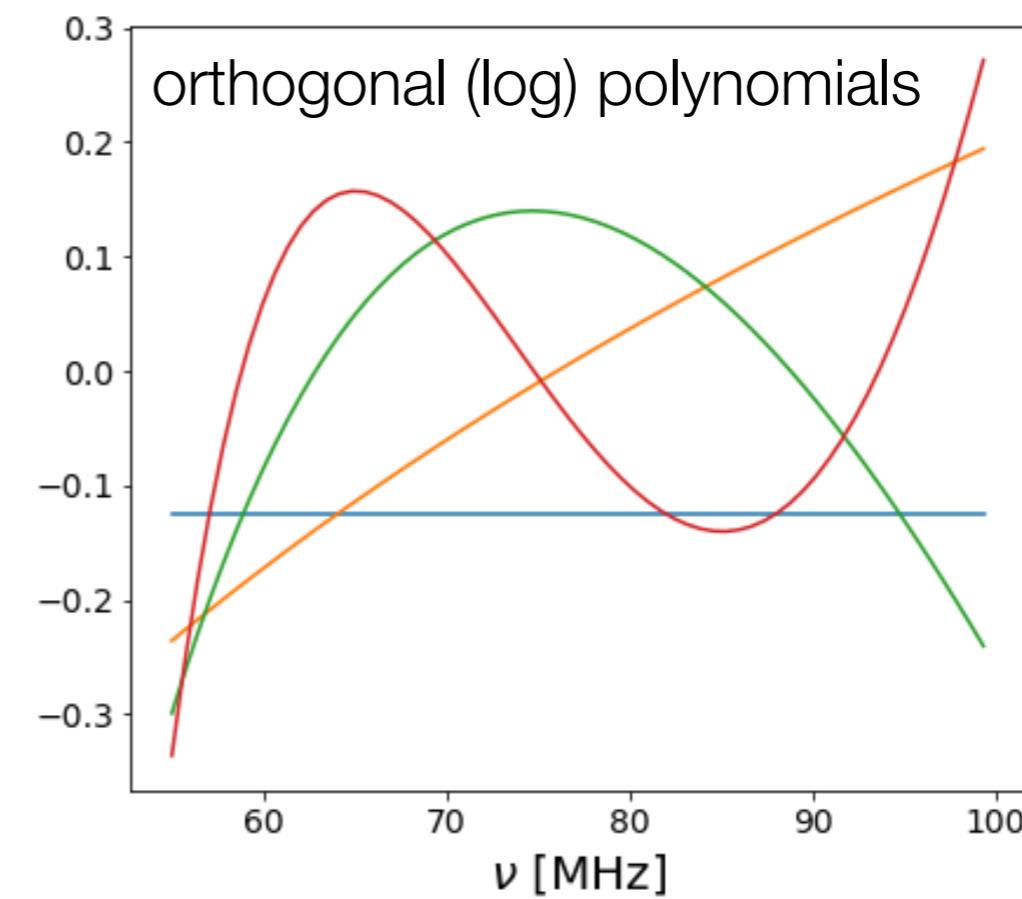
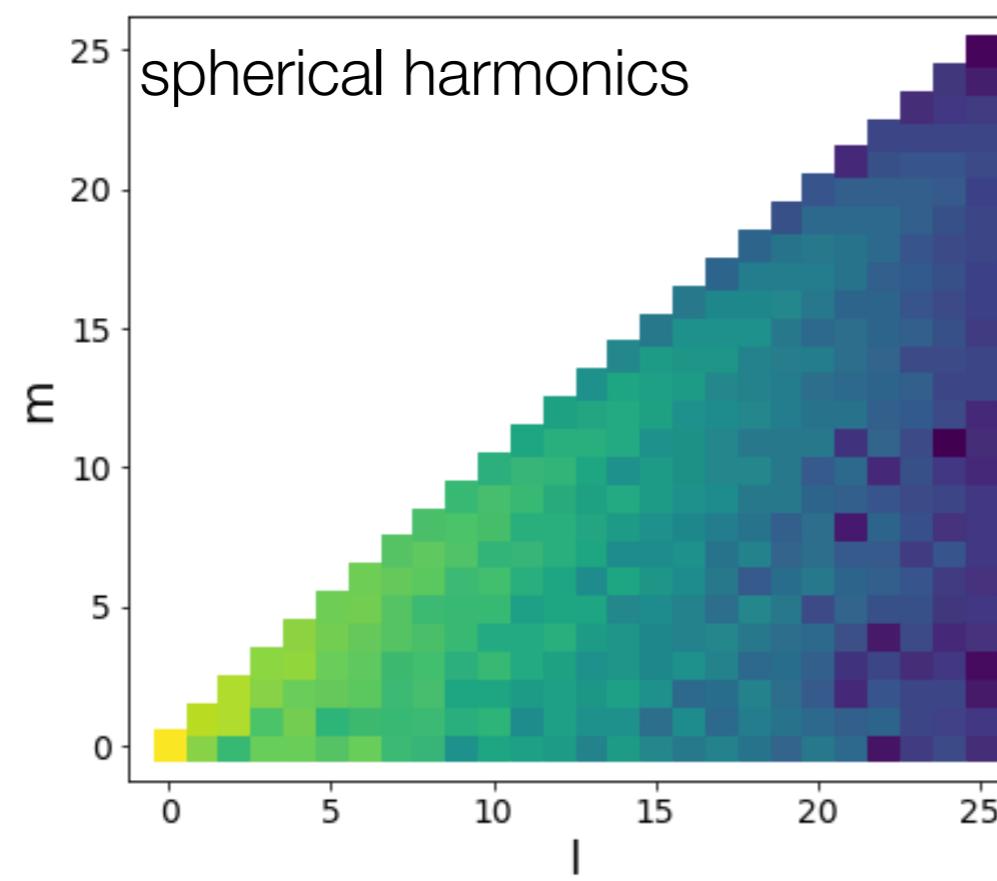
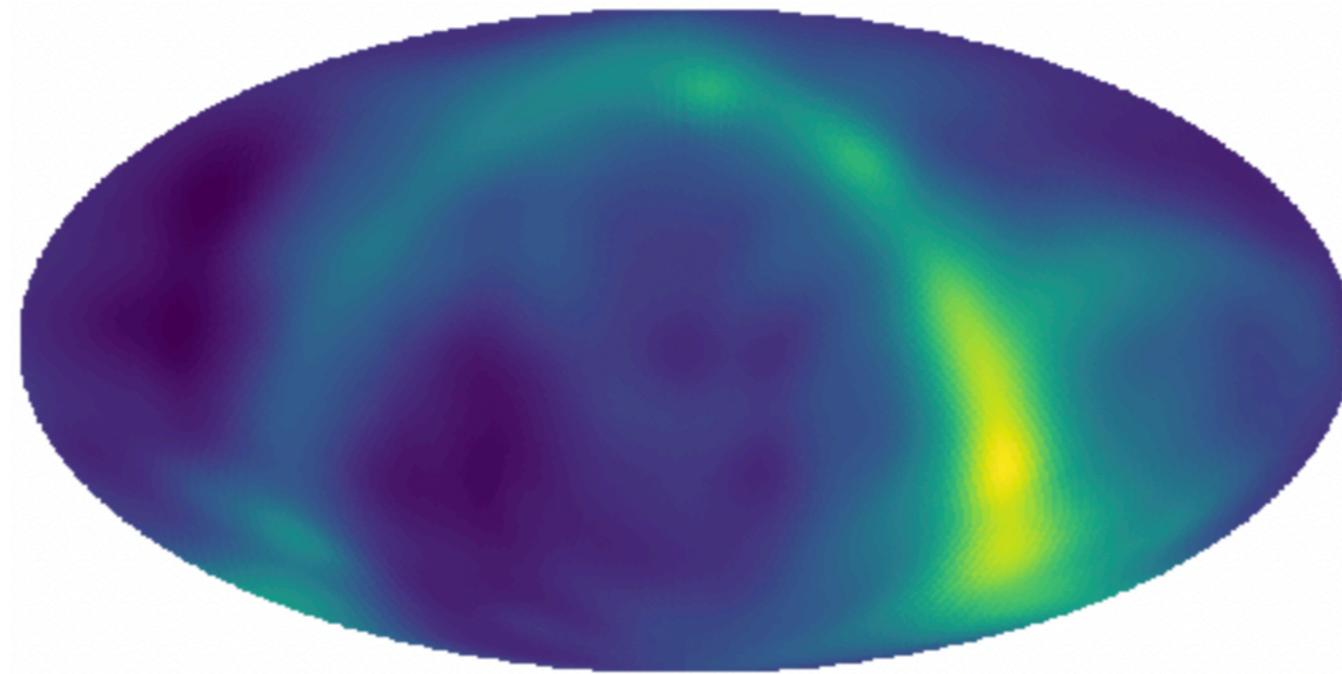
$$C_{ij} = [F^{-1}]_{ij}$$

T ₂₁	TxF	TxB
	FG	FxB
		B

The full F inverse accounts for degeneracies between T21, FG, and beam.

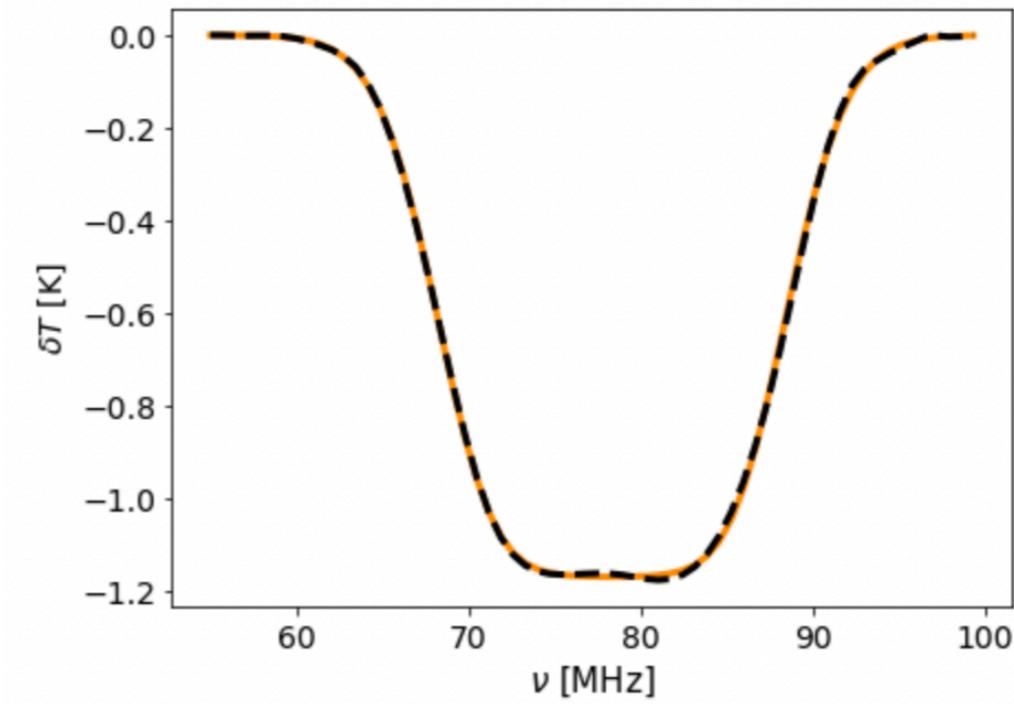
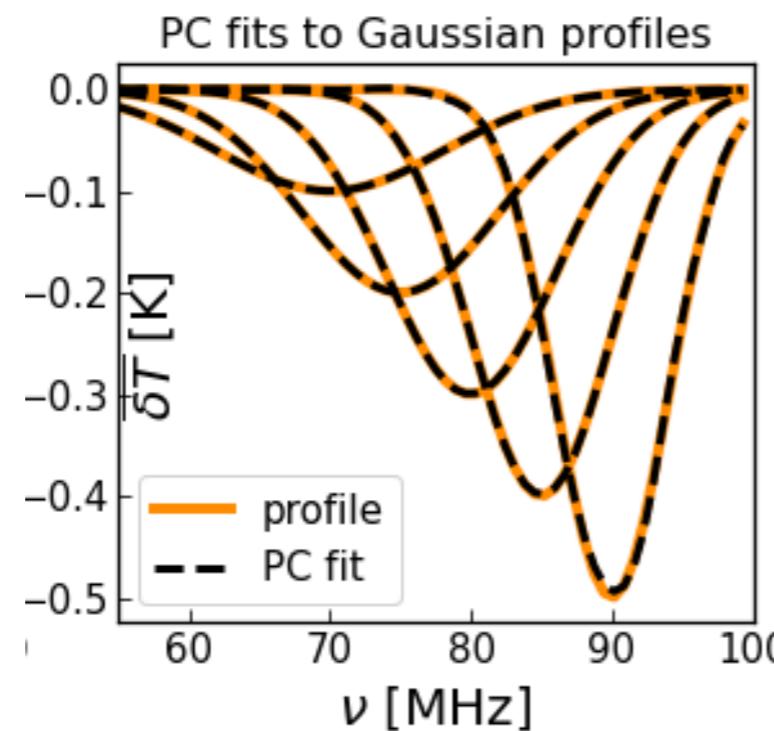
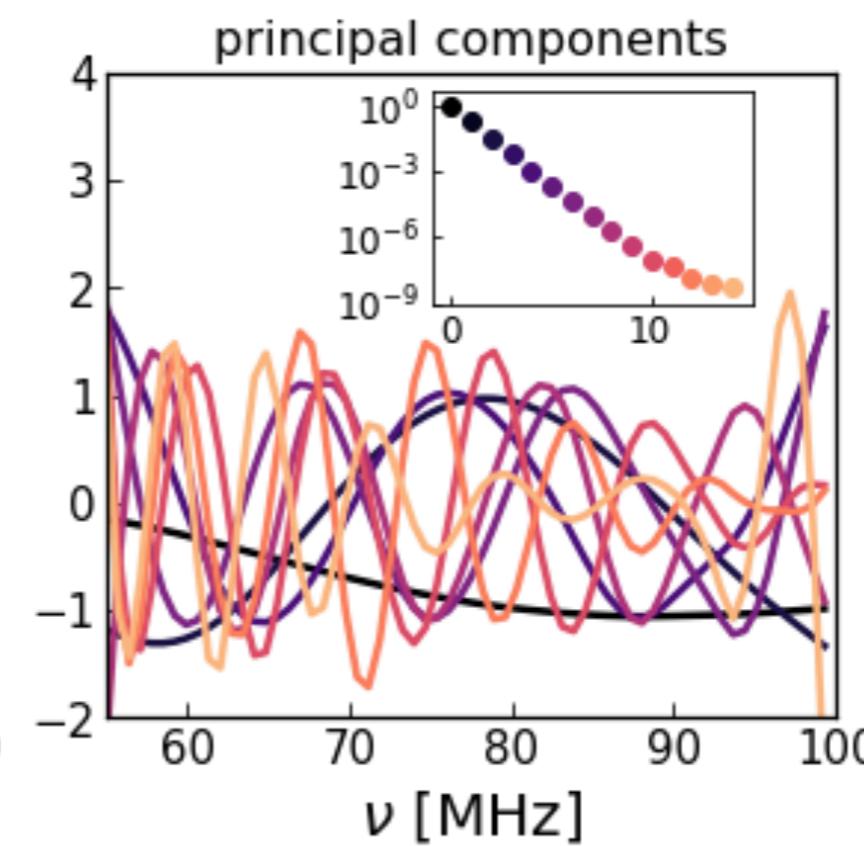
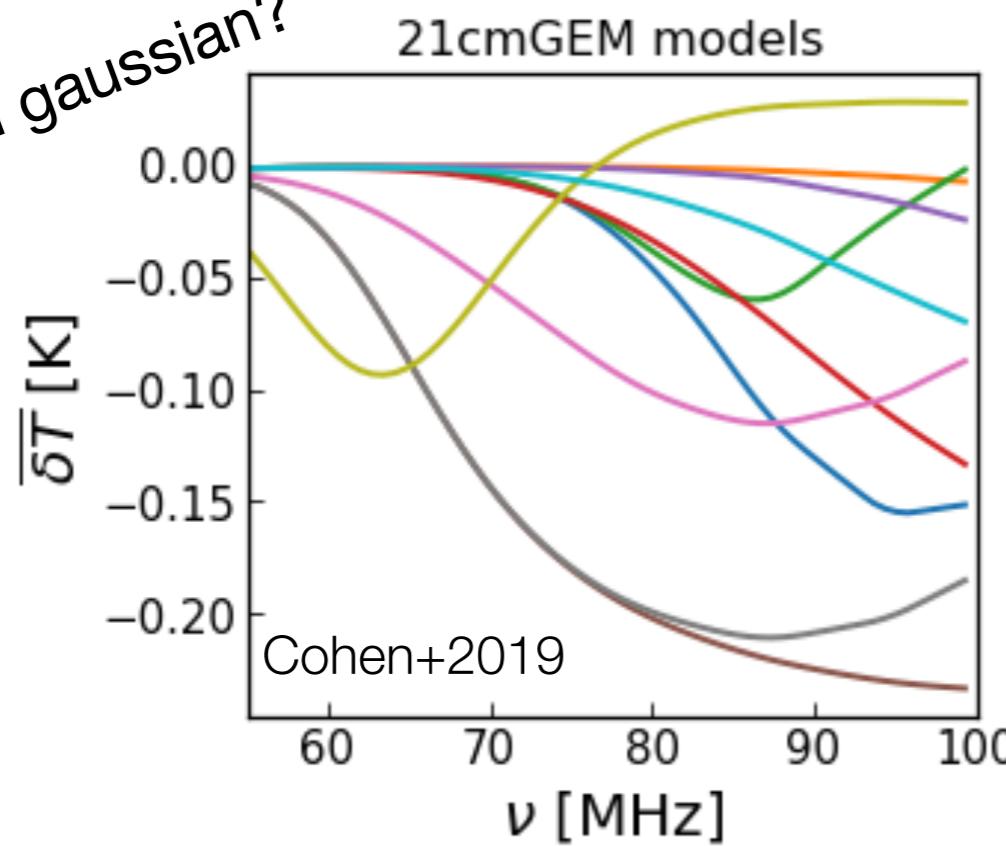
No noise and no front-end calibration in these tests.

Foreground parameterization

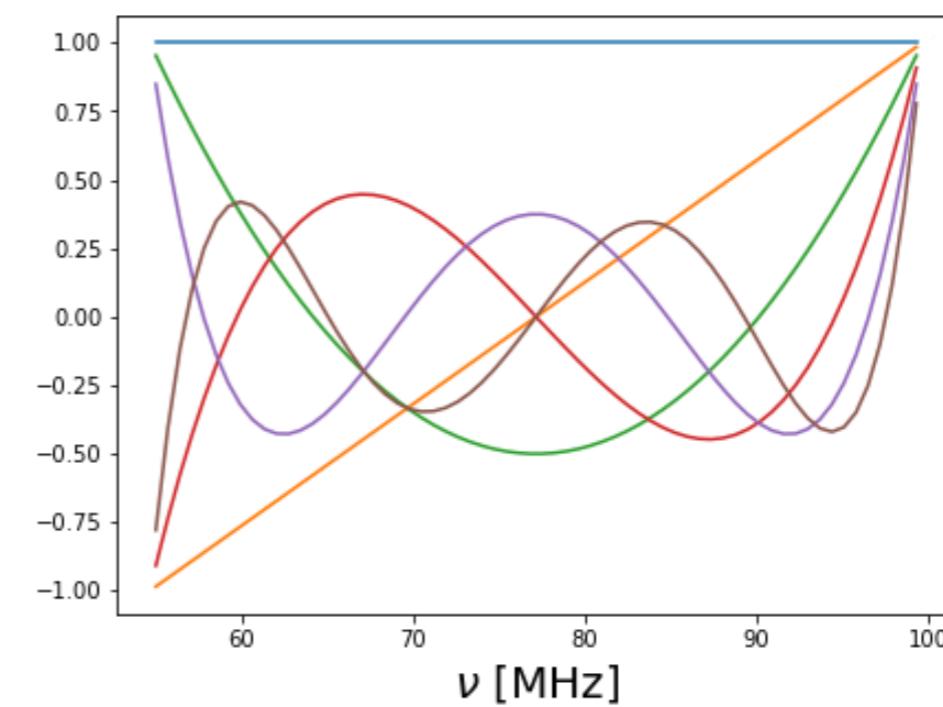
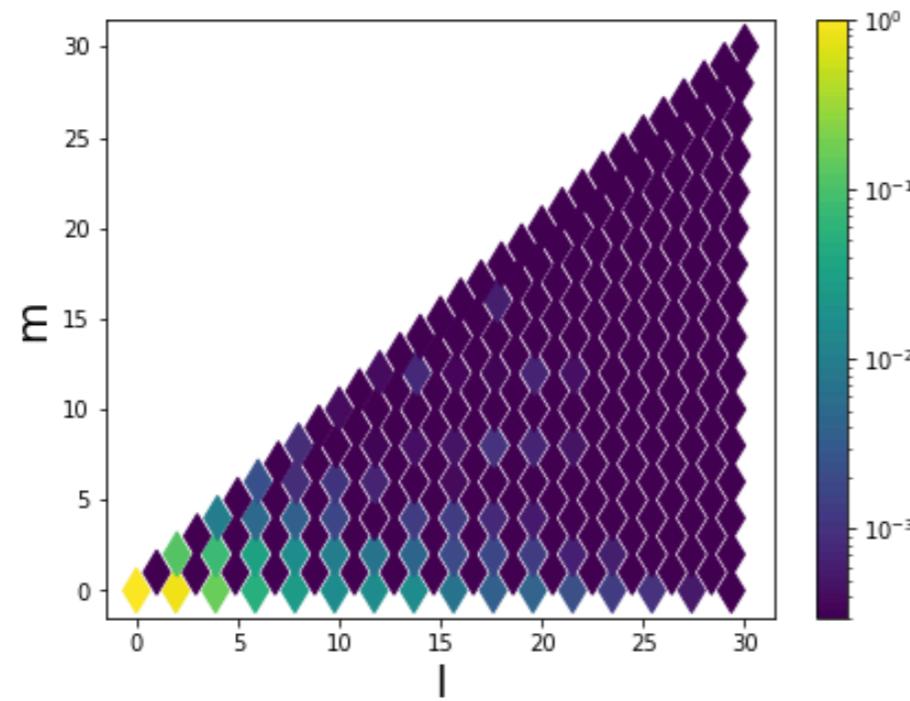
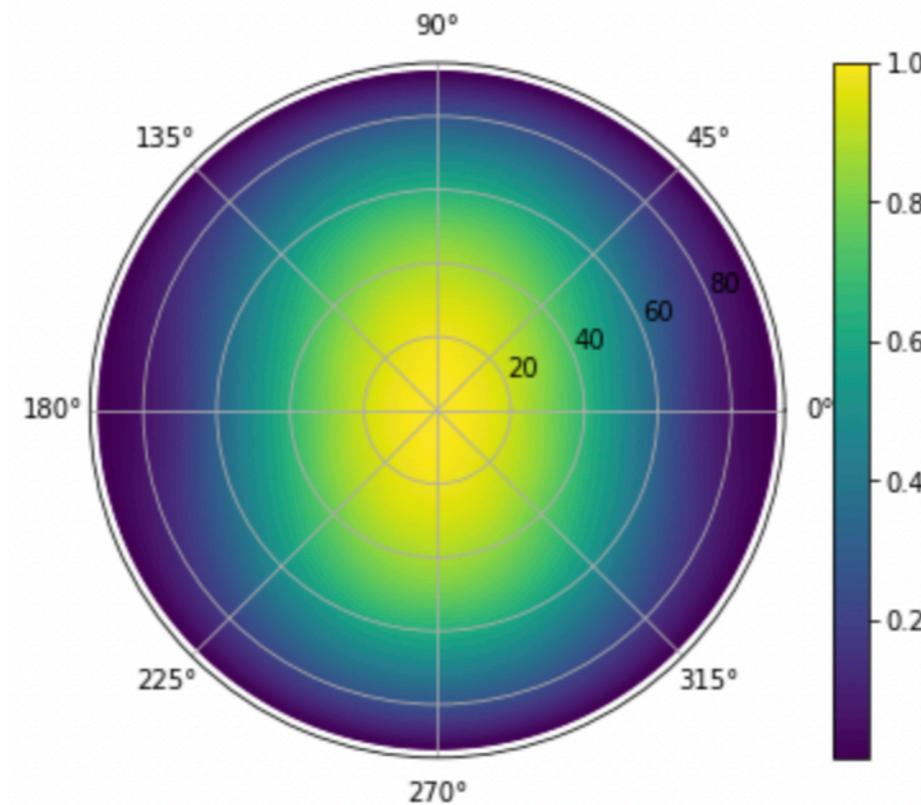


21 cm parameterization

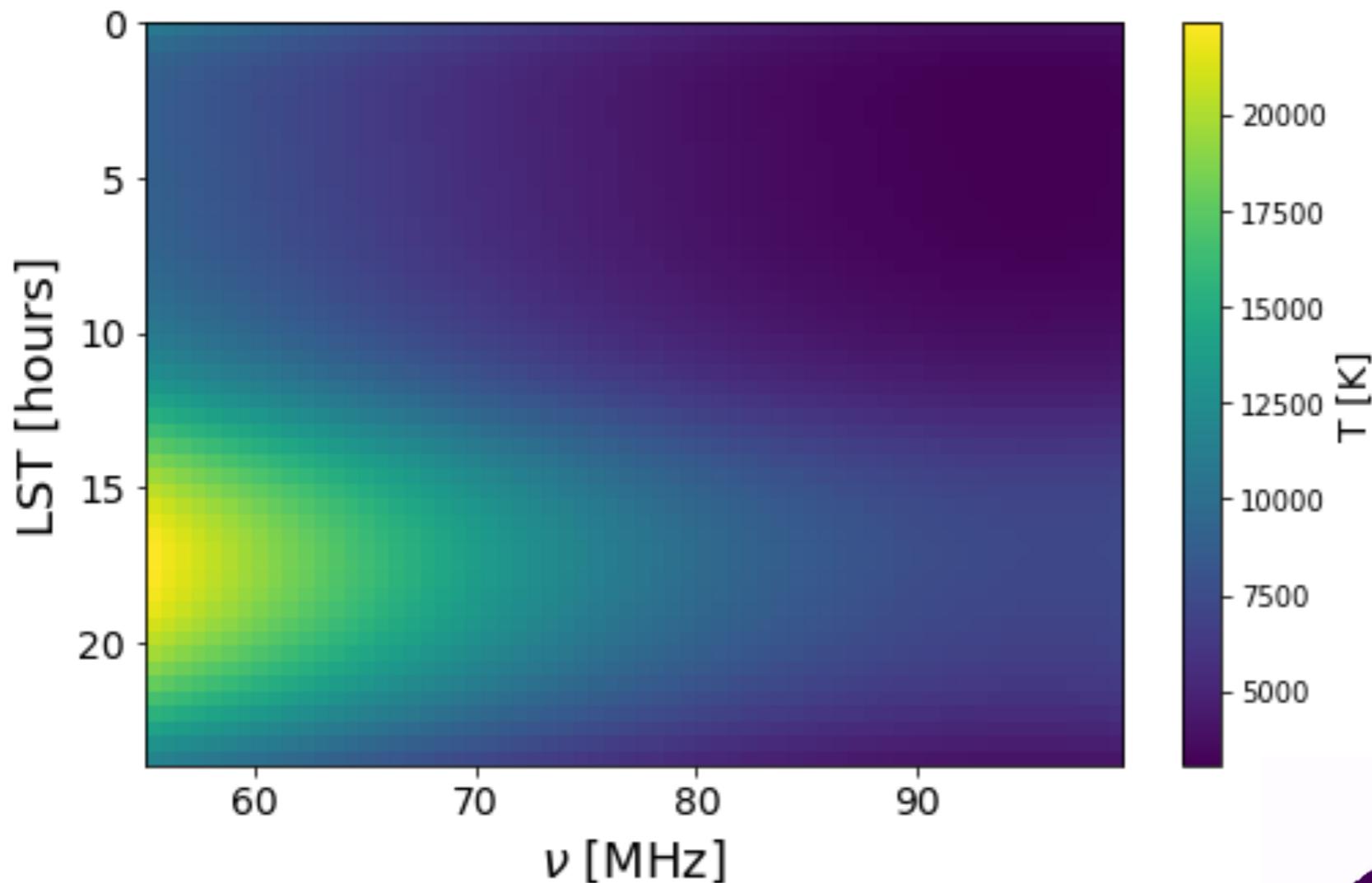
flattened gaussian?



Instrument parameterization: EDGES beam



Mock observation setup

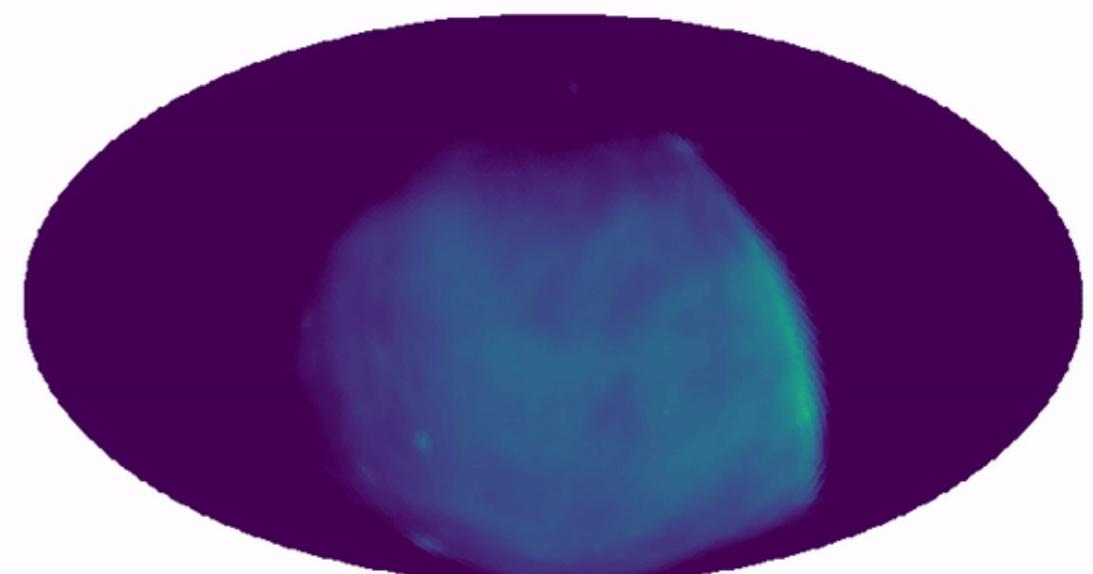


Nfrequency = 64

Ntimes = 50

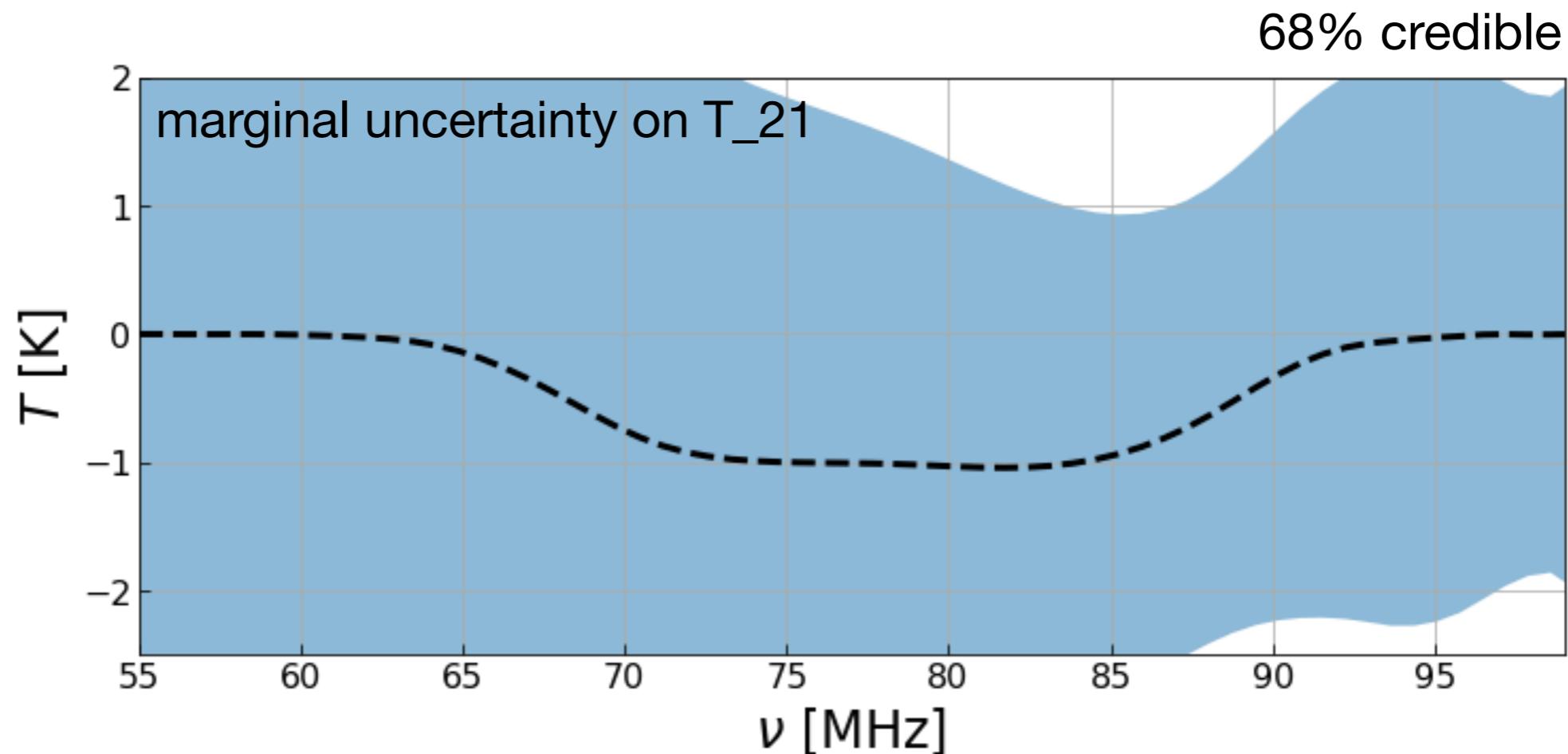
Npixel = 12288 (NSIDE=32)

no noise, no calibration



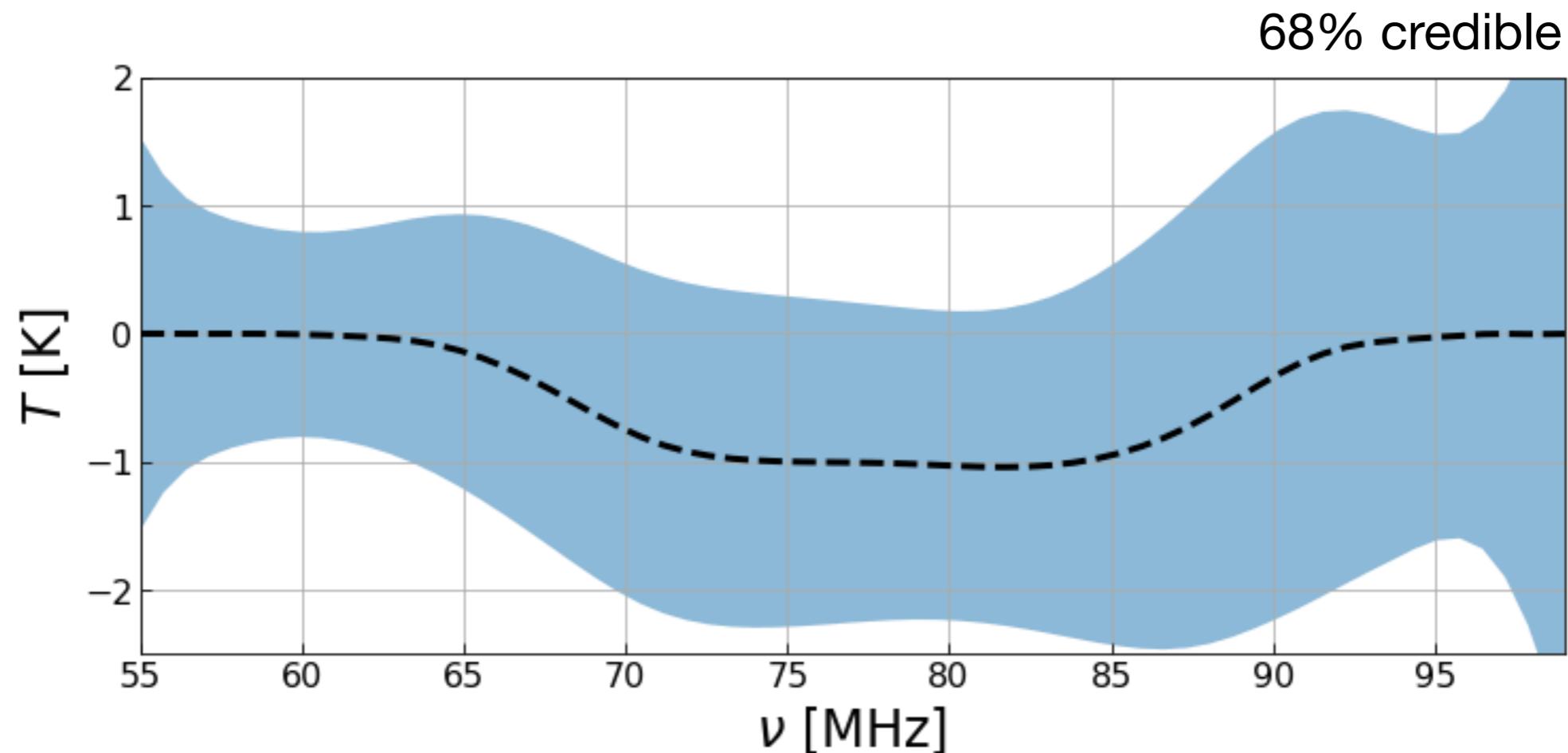
Testing for degeneracies

- **T_21** (no prior), **Beam** (no prior), FG (known)
- 1 LST



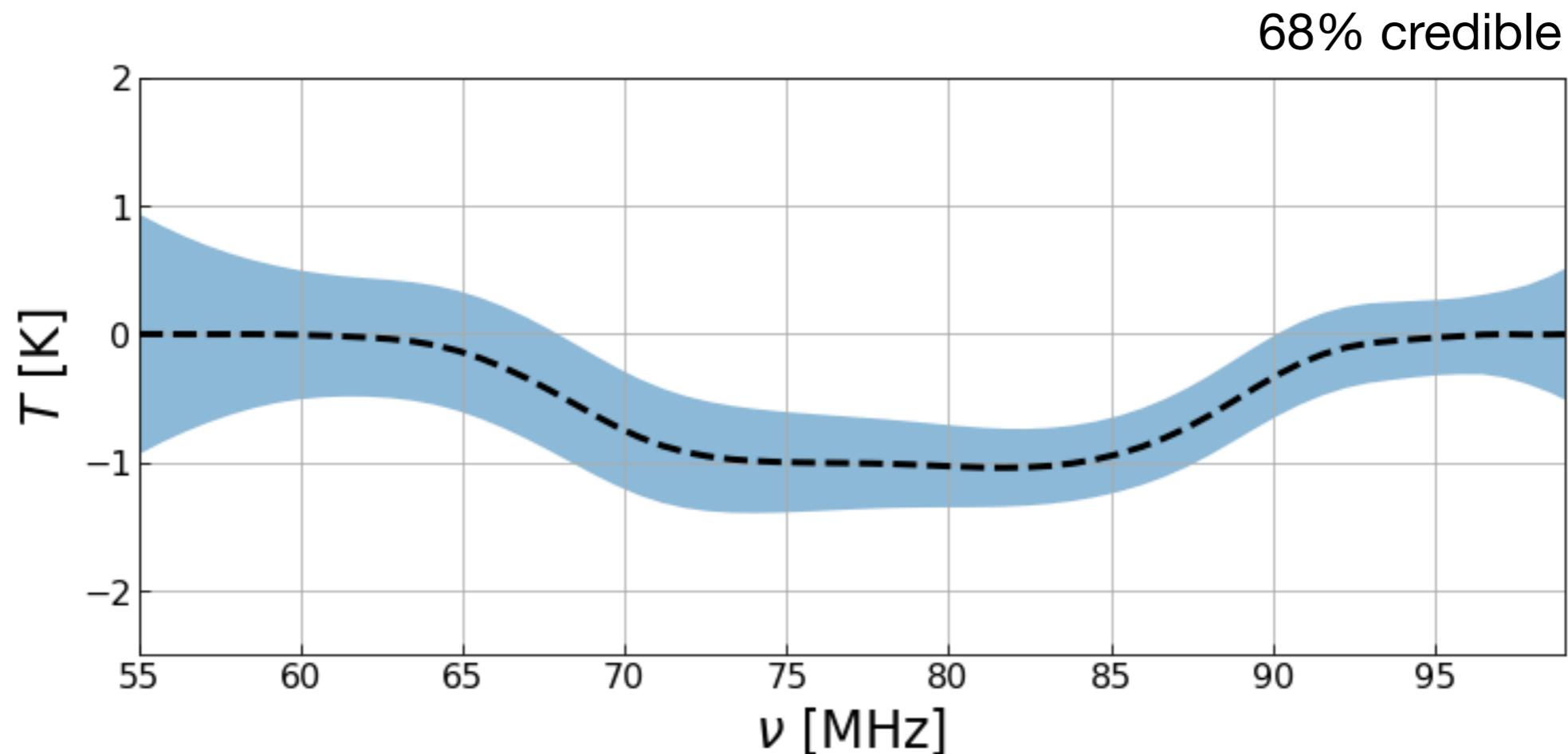
Testing for degeneracies

- **T_21** (2 K prior), **Beam** (1% prior), FG (known)
- 1 LST



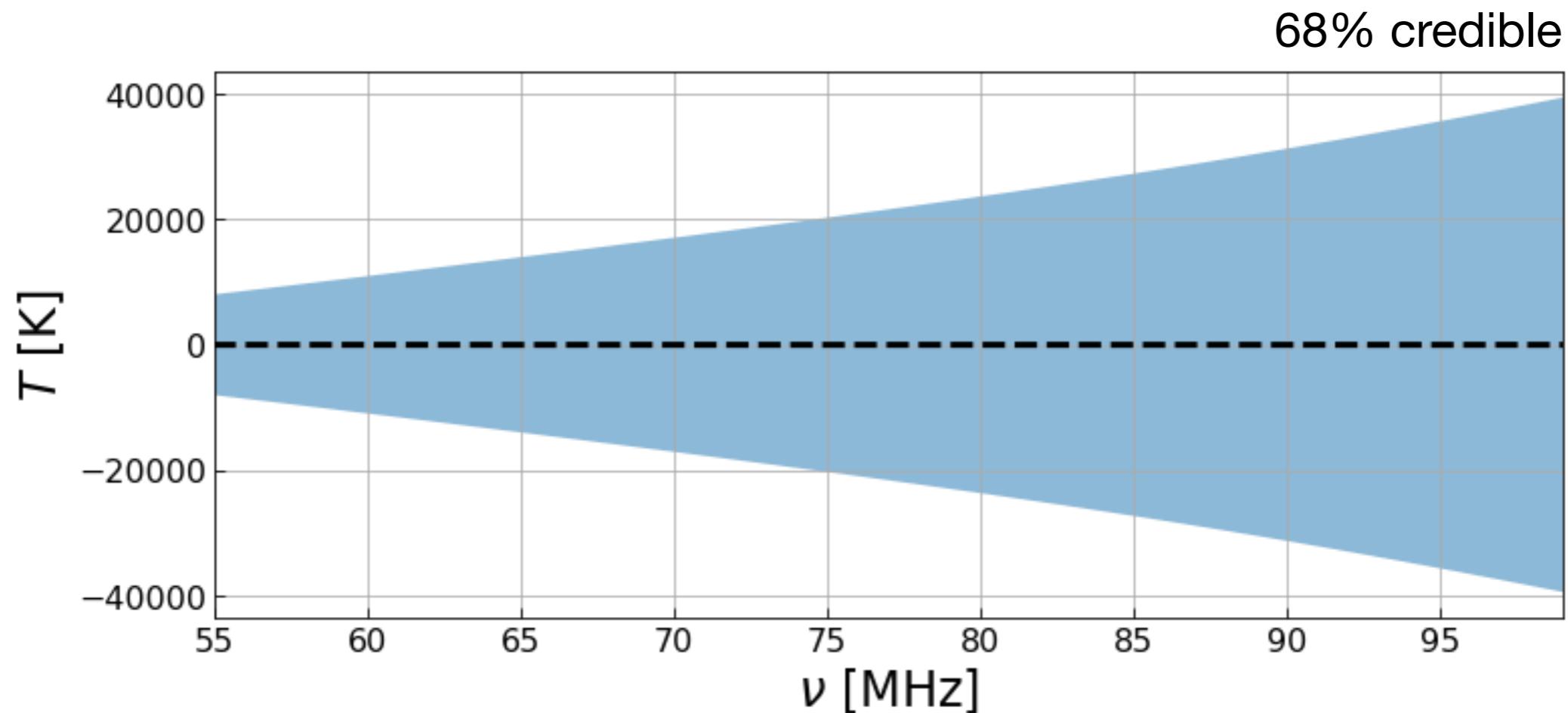
Testing for degeneracies

- **T_21** (2 K prior), **Beam** (1% prior), FG (known)
- 24 hours LST



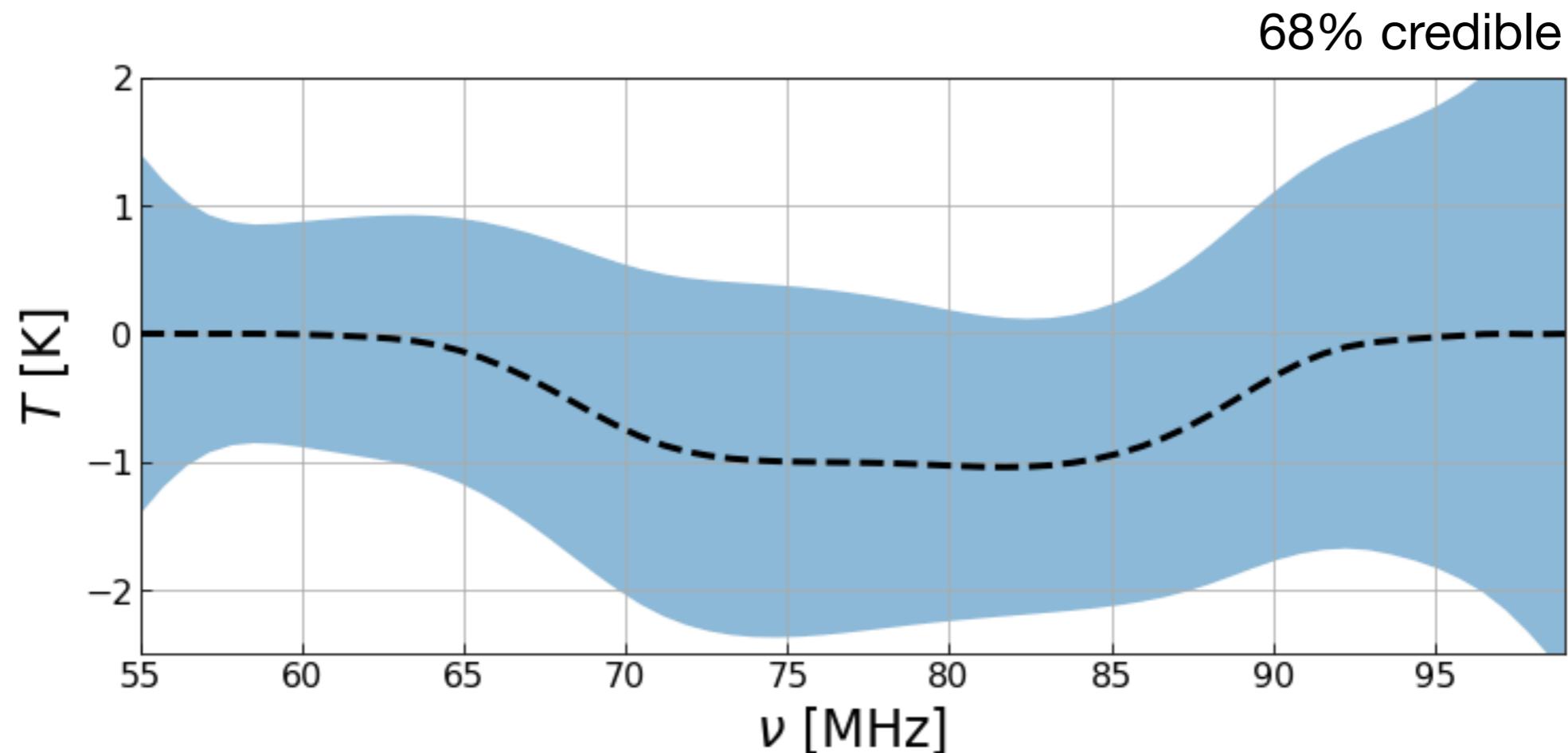
Testing for degeneracies

- **FG** (no prior), **T_21** (no prior), Beam (known)
- 24 hours LST



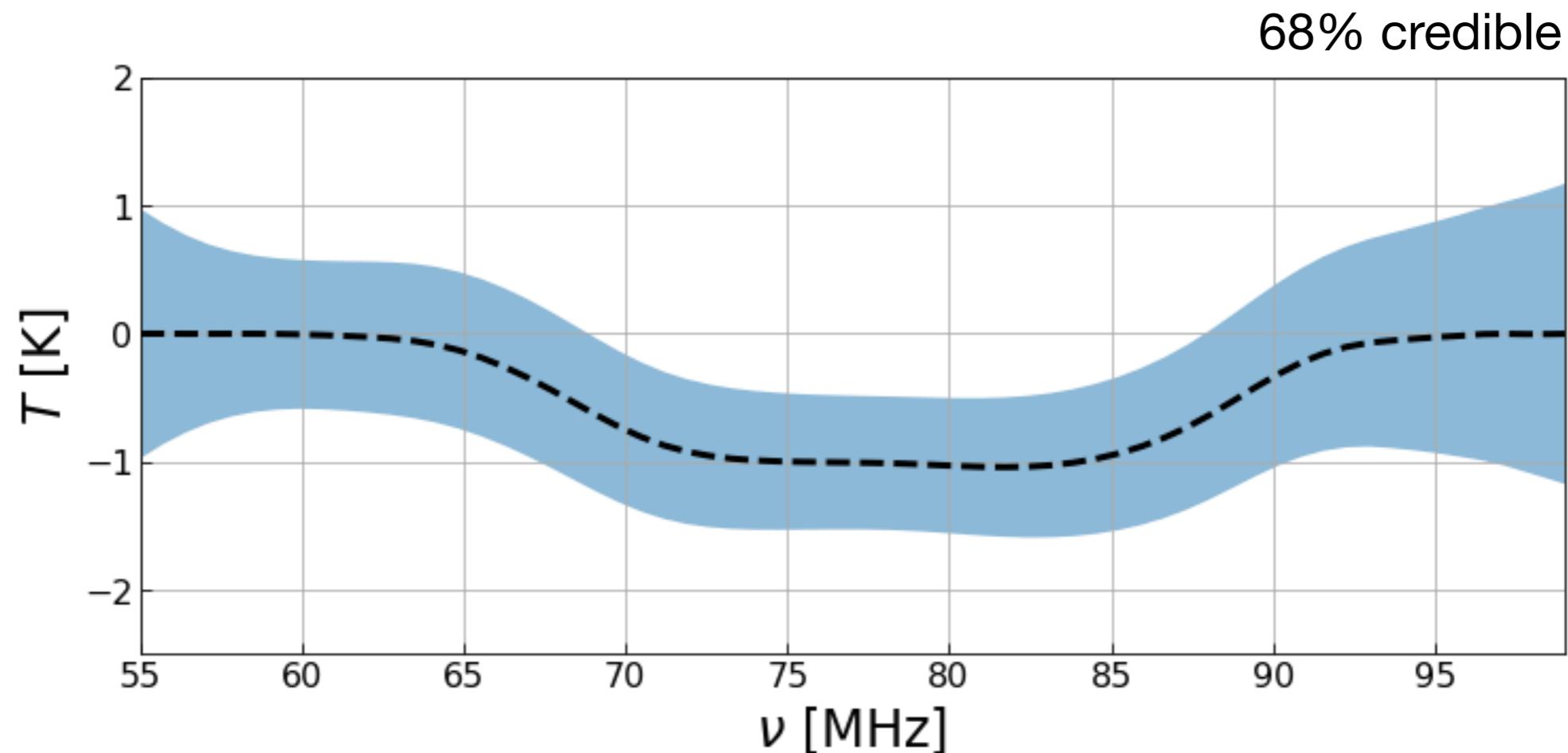
Testing for degeneracies

- **FG** (10% prior), **T_21** (2 K prior), Beam (known)
- 24 hours LST



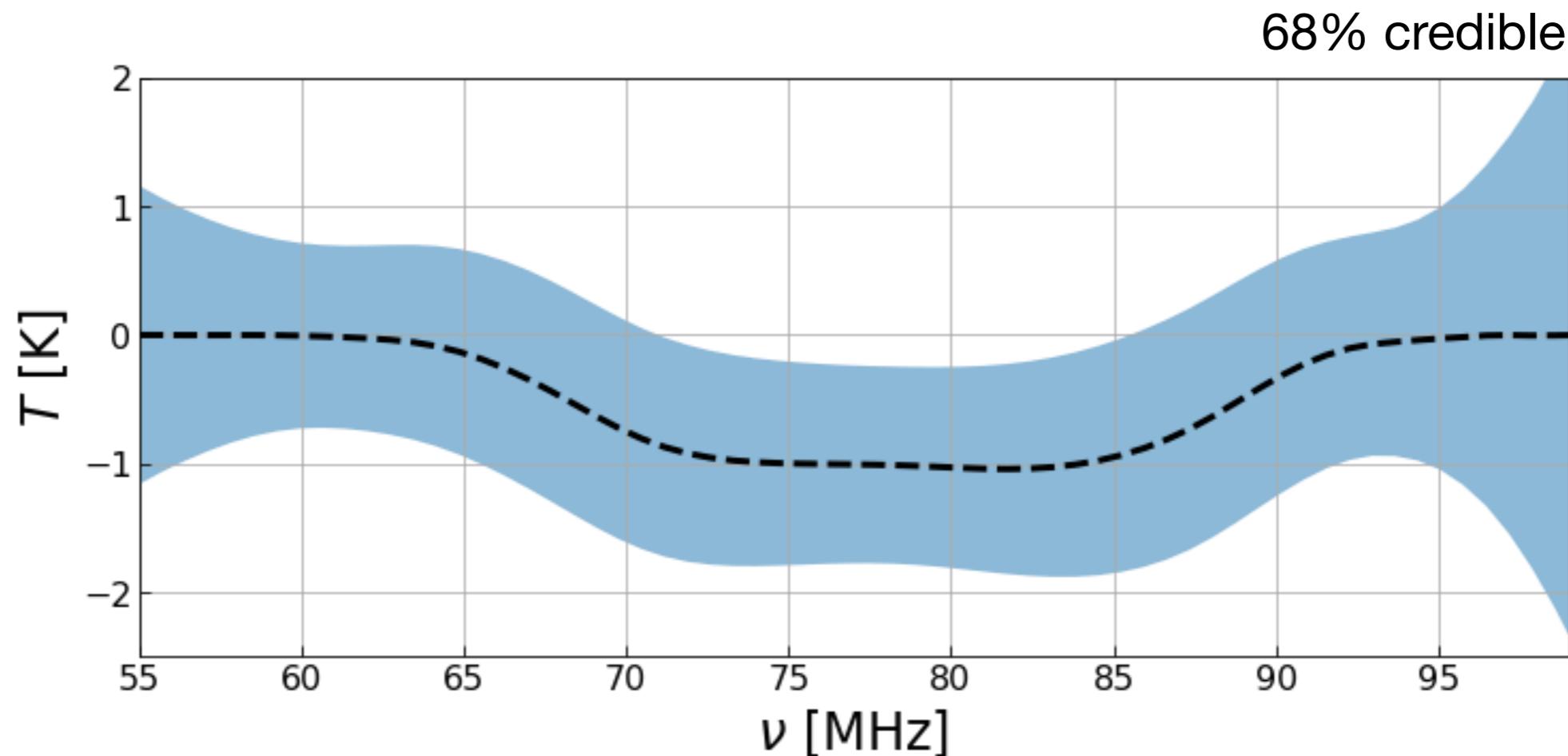
Testing for degeneracies

- **FG** (10% prior, $m>0$), **T_21** (2 K prior), Beam (known)
- 24 hours LST



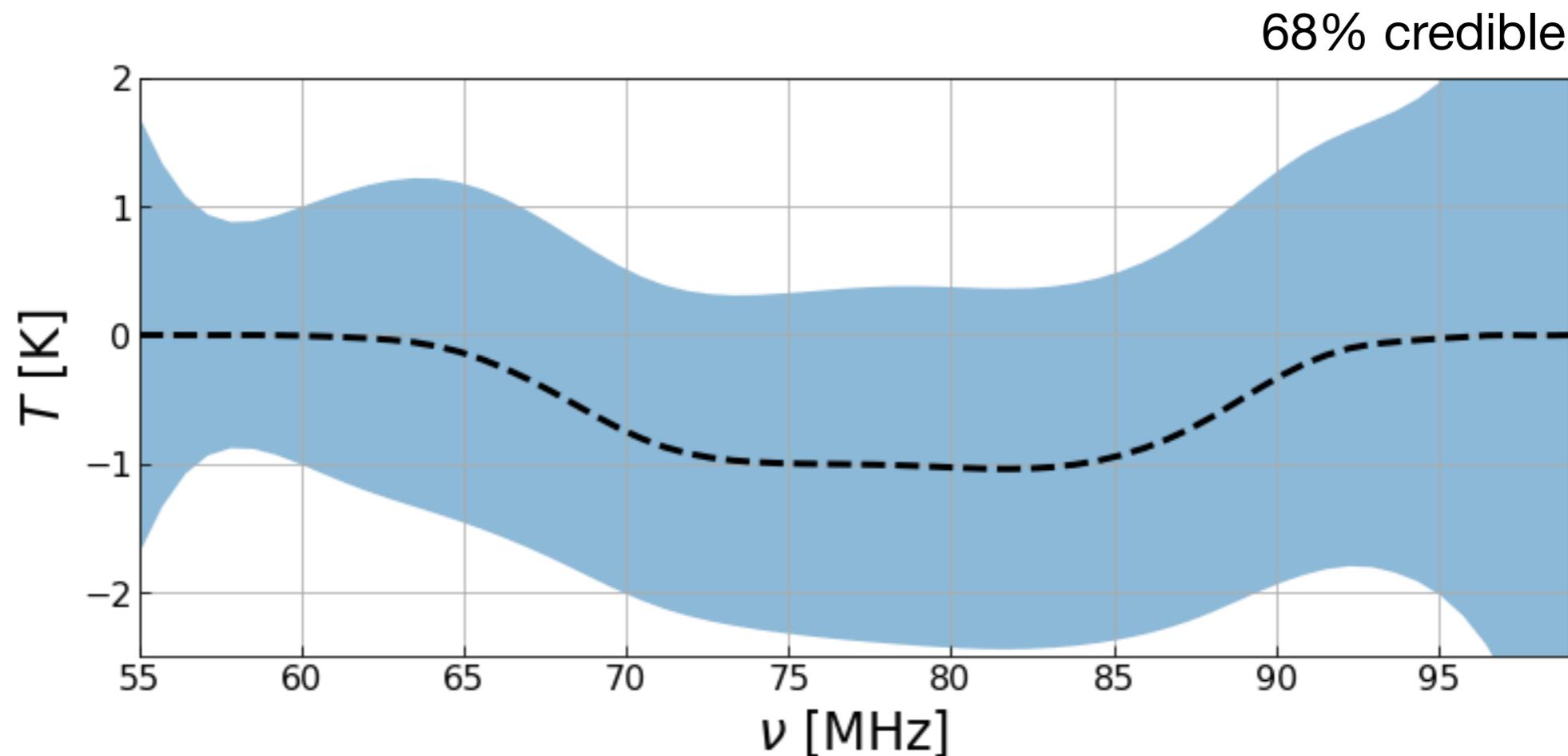
Testing for degeneracies

- **FG** (10% prior, $m > 0$), **T_21** (2 K prior), **Beam** (1 % prior)
- 24 hours LST



Testing for degeneracies

- **FG** (10% prior, $m > 0$), **T_21** (2 K prior), **Beam** (1% prior)
- 1 LST



Some avenues for progress?

- Down-weight $m=0$ angular modes with a FG spatial covariance (e.g. Liu et al. 2012)

Do we even know this covariance accurately?

Requires more complex observations (smaller beams, steerable pointing)

- Set a prior on the global signal with a $P(k)$ detection

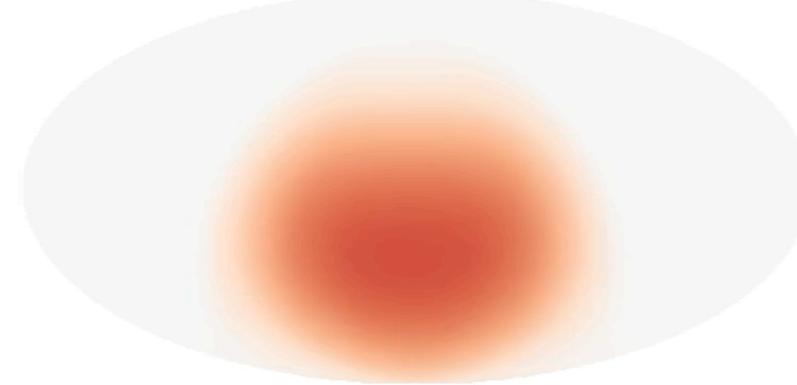
This is model dependent

Summary

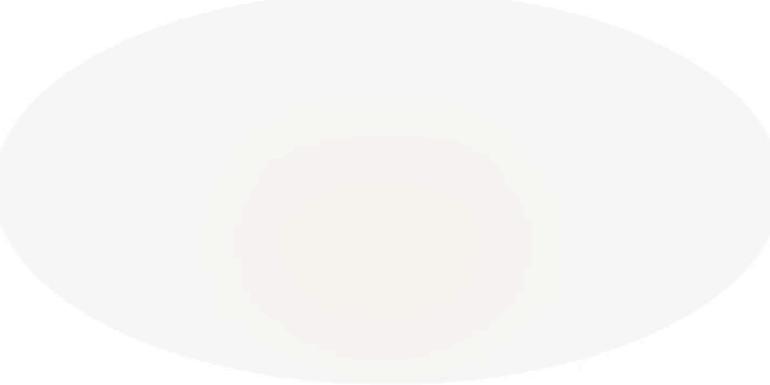
- Forward modeling is key to a deeper understanding of **degeneracies** between the signal and systematics, and for fully leveraging the **statistical power** in the data (e.g. multi-LSTs). More results on optimization and sampling to come soon...
- Even in ideal circumstances (i.e. perfect front-end calibration, perfect beam knowledge, and multi-LSTs), “detection” of a 21 cm global signal is complicated by degenerate FG modes

Cool features: gradient maps

Snapshot gradient



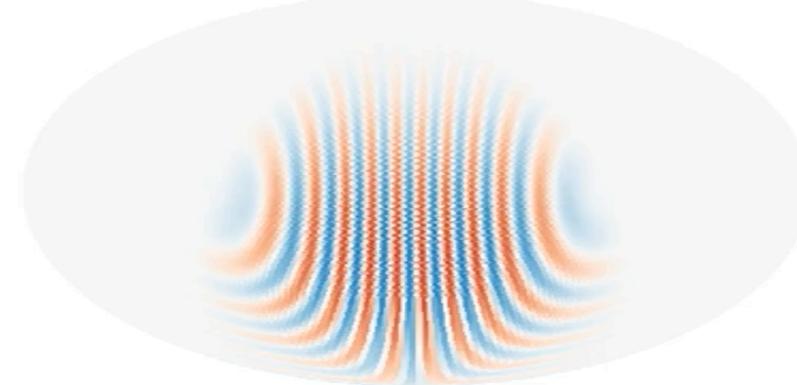
Accumulated gradient



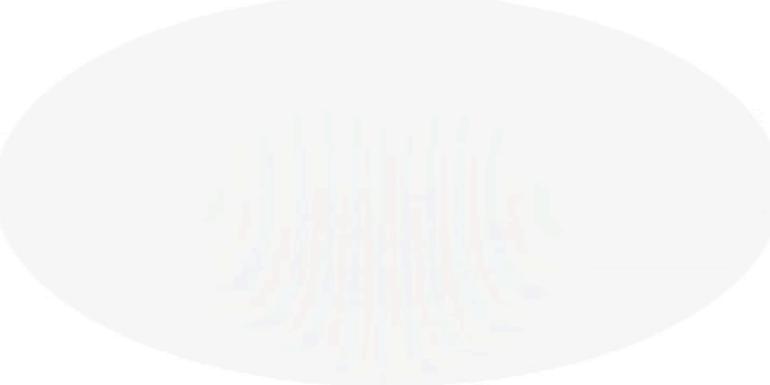
Perturbation



Snapshot gradient



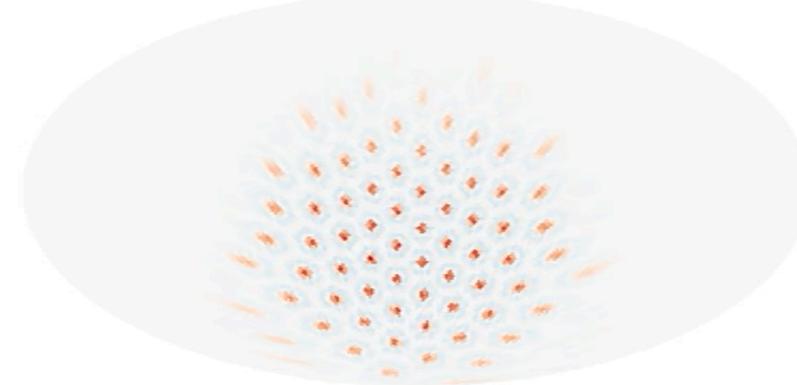
Accumulated gradient



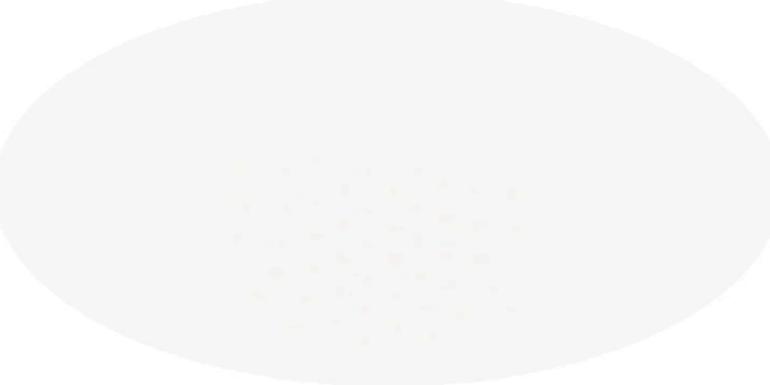
Perturbation



Snapshot gradient



Accumulated gradient



Perturbation



Performance

