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高性能智能合约体系架构

——高性能链上DNN计算（推理）

SmartVM: A Smart Contract Virtual Machine for Fast on-Chain DNN Computations

Tao Li, **Yaozheng Fang**, Ye Lu* (luye@nankai.edu.cn), Jinni Yang, Zhaolong Jian, Zhiguo Wan, Yusen Li

[IEEE Transactions on Parallel and Distributed Systems](#), DOI: 10.1109/TPDS.2022.3177405

房耀政 南开大学

2023年1月

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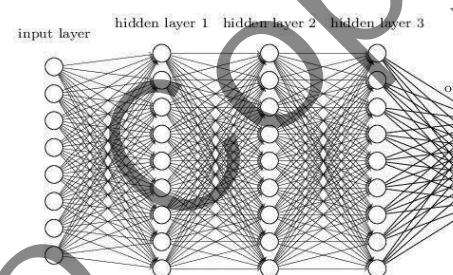
● 二、动机

● 三、SmartVM

● 四、实验

● 五、工作总结

► Blockchain & Artificial Intelligence



深度神经网络

迭代训练

| | | |
|---|---|---|
| 1 | 0 | 1 |
| 0 | 1 | 0 |
| 1 | 0 | 1 |

权重篡改等
安全问题

| | | |
|---|---|---|
| 1 | 0 | 0 |
| 0 | 1 | 0 |
| 0 | 0 | 1 |

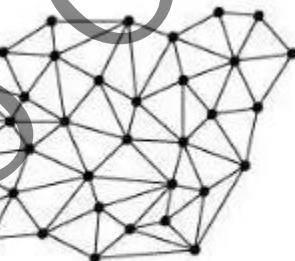
网络权重

动机

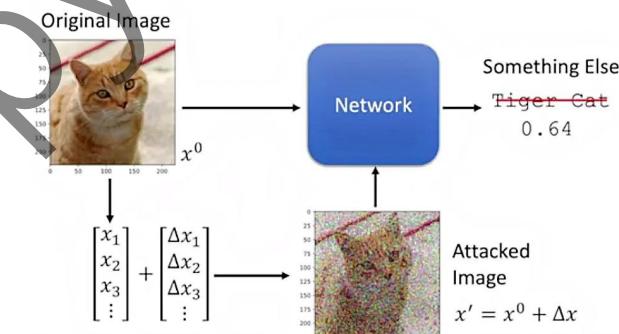
SmartVM

实验

工作总结



- ◆ 分布式数据库+状态复制机
- ◆ 存储（数据）防篡改、操作（计算）可共识
- ◆ 公开透明



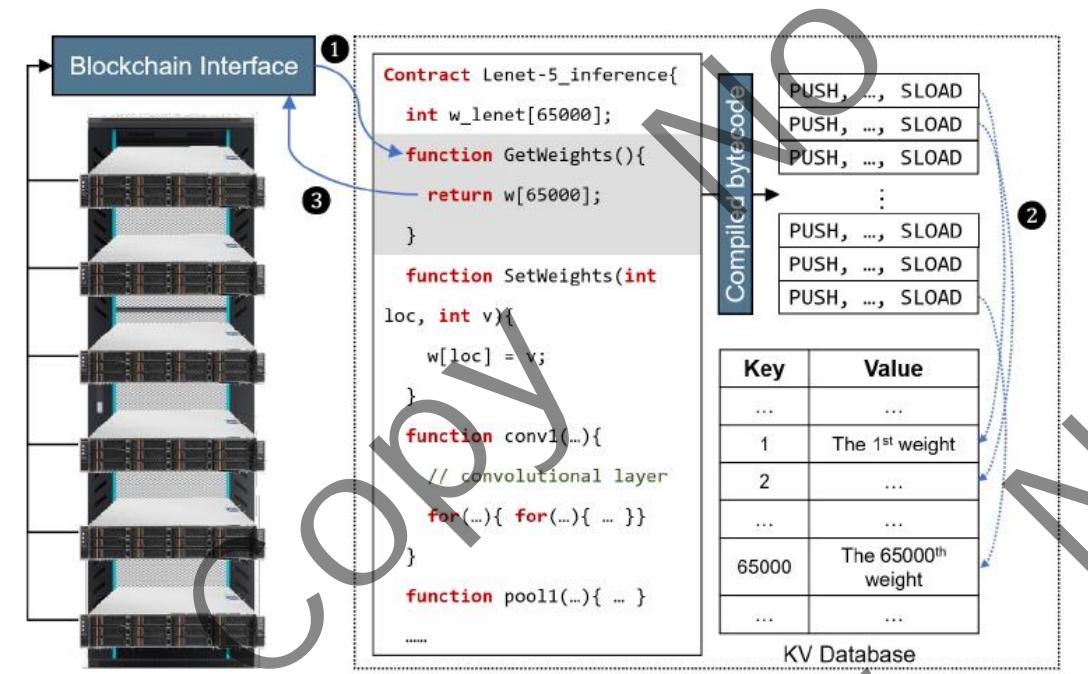
研究背景

南开大学
Nankai University

► Blockchain-based Artificial Intelligence (BC-AI)

区块链可以和分布式AI天然结合，构建安全、可信的分布式AI系统 (Blockchain-based AI Systems)

► Problems of off-chain DNN inference



① 合约方法调用，请求获取权重

② 字节码执行，按顺序从数据库中取权重

③ 权重数据返回传输

问题：

① 合约方法执行时字节码数量庞大，达千万条

② 权重分散存储，数万条记录，且CNN权重越来越多

③ 数据转移代价

EVM+Solidity组合：

LeNet网络数分钟，AlexNet网络近1小时；数据搬运代价高

Fig. 2: CNN Computing Process in Typical BC-AI.

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● 一、研究背景

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■ 智能组件的思考——构建分布式人工智能决策和协作平台



智能组件是一个新概念，最早由西安交通大学郑南宁院士于2018年科技部“科技创新2030-新一代人工智能重大专项”项目组的一次研讨会中提出。

[1] 袁勇, 欧阳丽炜, 王晓, 王飞跃, “基于区块链的智能组件：一种分布式人工智能研究新范式”，数据与计算发展前沿，2021, Vol. 3, No. 1, pp. 1-14.

Running Deep Learning on EVM

EVM

kladkogex

Jan '18

At my company we are starting an experimental project to extend EVM with basic deep learning capabilities.

This is not to train a neural network, but to use a pre-trained neural network inside a smart contract. Computation-wise using a pre-trained neural network is actually not so much more expensive than doing, say, RSA.

I understand that this may be a bit too heavy for the official Ethereum blockchain, so in our case we will run the EVM on a separate permissioned cluster with BFT-like consensus.

The current plan is that:

1. A pre-trained network is saved on the blockchain. We can use some of existing neural network serialization standards such as the ones used in [Keras framework](#) 36
2. The EVM will need to pull the neural network from the blockchain.
3. In the simplest case there we add a single **predict** instruction similar to [predict from Keras framework](#) 22. This instruction will take a fully qualified name of the neural network and an input data array, run the neural network and produce output data.

As an example input data could be an English-language string, and output will be a German translation of this string.

One problem that we will need to solve in the process is introducing deterministic floating point numbers such as IEEE 754-2008 into the EVM in some way.

If there are other people interested to run AI on EVM, we would be willing to cooperate on this to establish a standard that everyone uses ...

- ◆ 社区内的真实需求
- ◆ Distributed Uber
- ◆ Trusted analysis



Well - I think many people have expressed different ideas about running a neural network as a trusted application so that all parties agree to the outcome.

As a toy example, you can consider an example of a smart contract that is a decentralized Uber which pays to drivers based on their behavior. The smart contract needs to differentiate bad drivers from good drivers by running a neural network on driver historical behavior. Good drivers are get paid and bad drivers do not get paid.
What you do, you feed driver's trajectory into a neural network, and then the driver gets either paid in full or penalized based on her behavior ...

Another example is when a smart contract buys apples from a supplier and it needs to find out whether an apple is a good apple or a bad apple based on chemical analysis data. Essentially you feed into the neural network 100 data points of chemical analysis and the network tells you whether the apple is good or bad.

In general, I think to answer your question, anytime a smart contract runs on data, there is no need to use neural networks. On the other hand if a smart contract runs on Big Data, then, arguably, you need a neural network to extract important info from the data, as the data itself is too complex.

In the examples above the neural network does not need to be confidential or encrypted in anyway, it could be a pre-trained network which is trusted by all participants.

I am not saying EVM is a perfect place to run neural networks, on the other hand making it some kind of an simple extension to EVM/Solidity would draw many developers. Another possibility is to run a totally different thing and then feed the results into Ethereum somehow ...



- Moving computations rather than moving data!
- Convolutional Neural Network

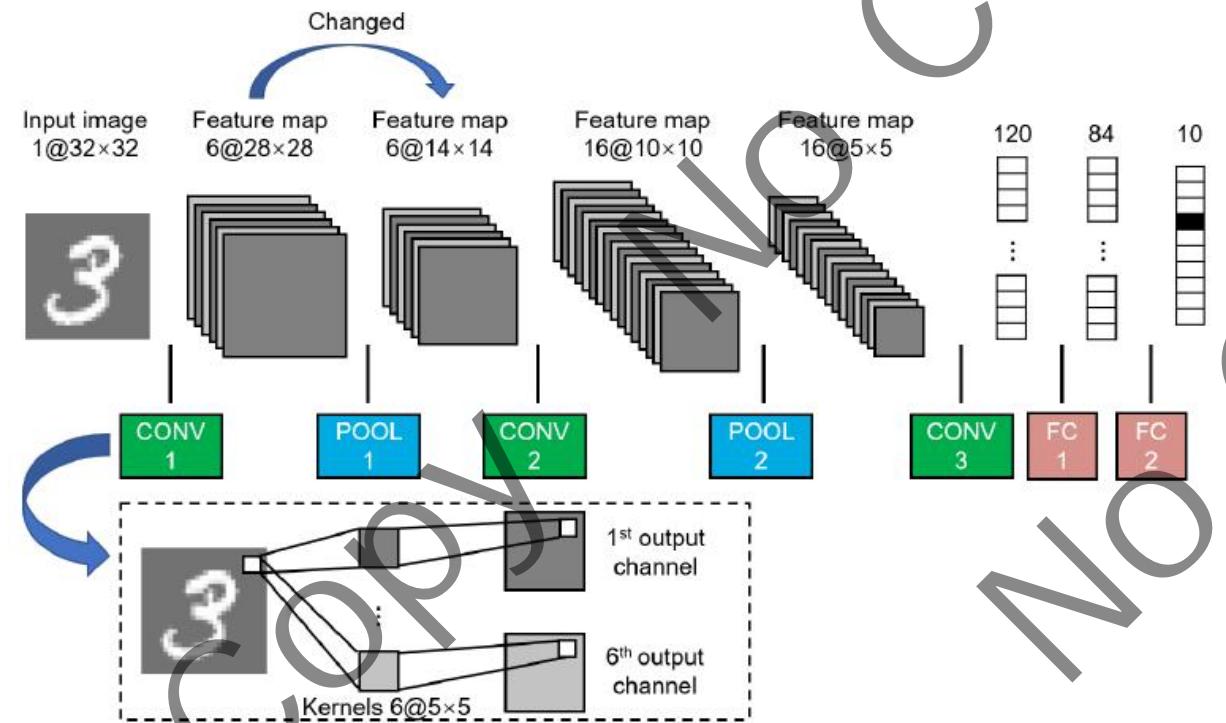
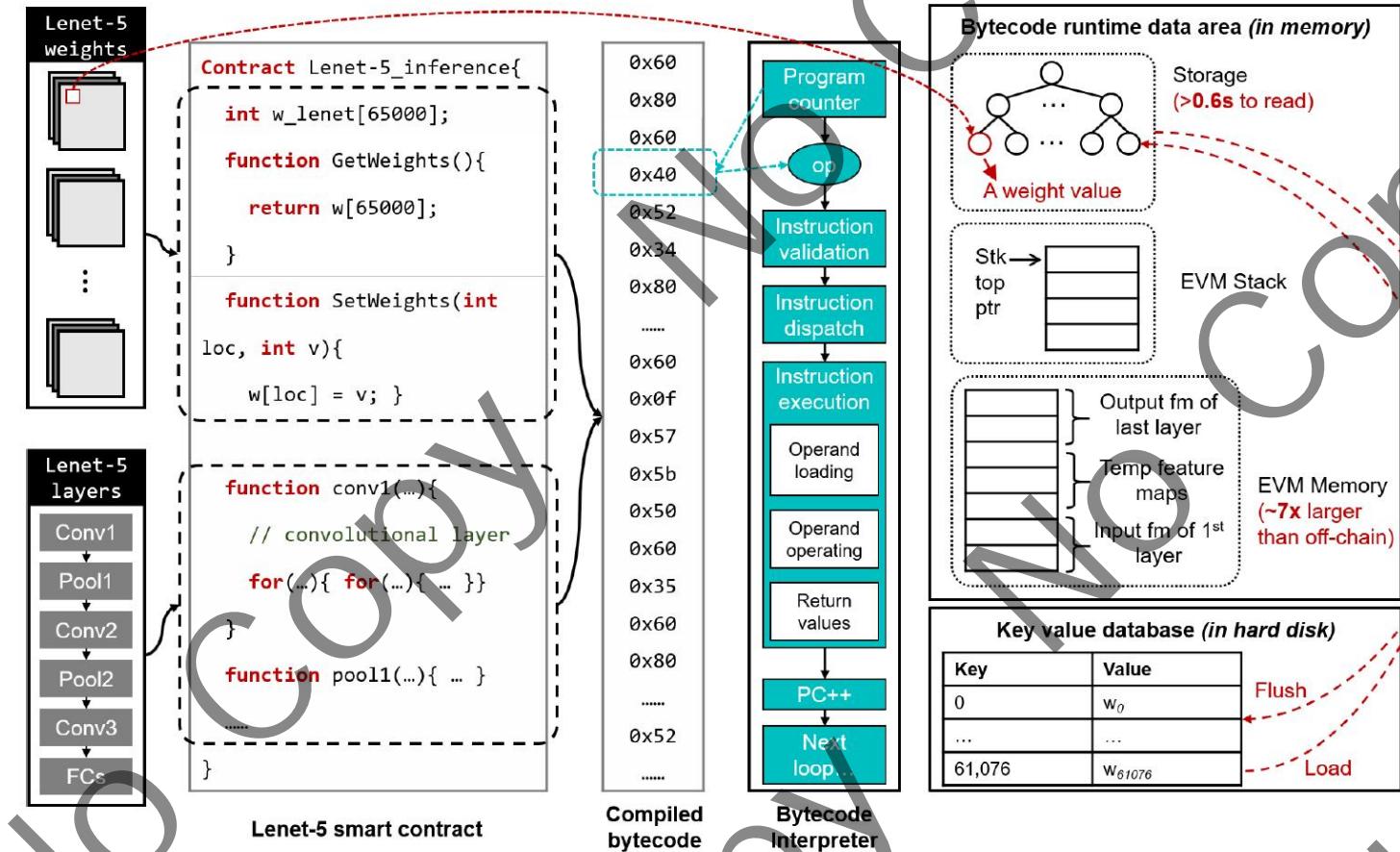


Fig. 1: LeNet-5 architecture of inference.

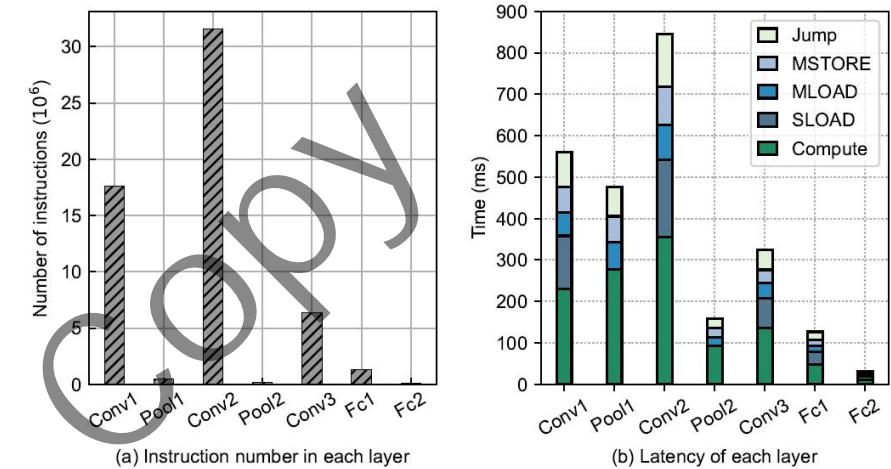
- ◆ 经过某层计算后，计算前后的特征图大小一般会不同
 - ◆ 例如，卷积层增大，池化层减小
- ◆ 各同类型层计算逻辑基本相同
 - ◆ 例如，Conv1和Conv2
- ◆ 权重获取和计算有先后顺序，且各通道相互独立
 - ◆ 例如，第1通道和第6通道

Moving computations rather than moving data!

Problems of on-chain CNN inference

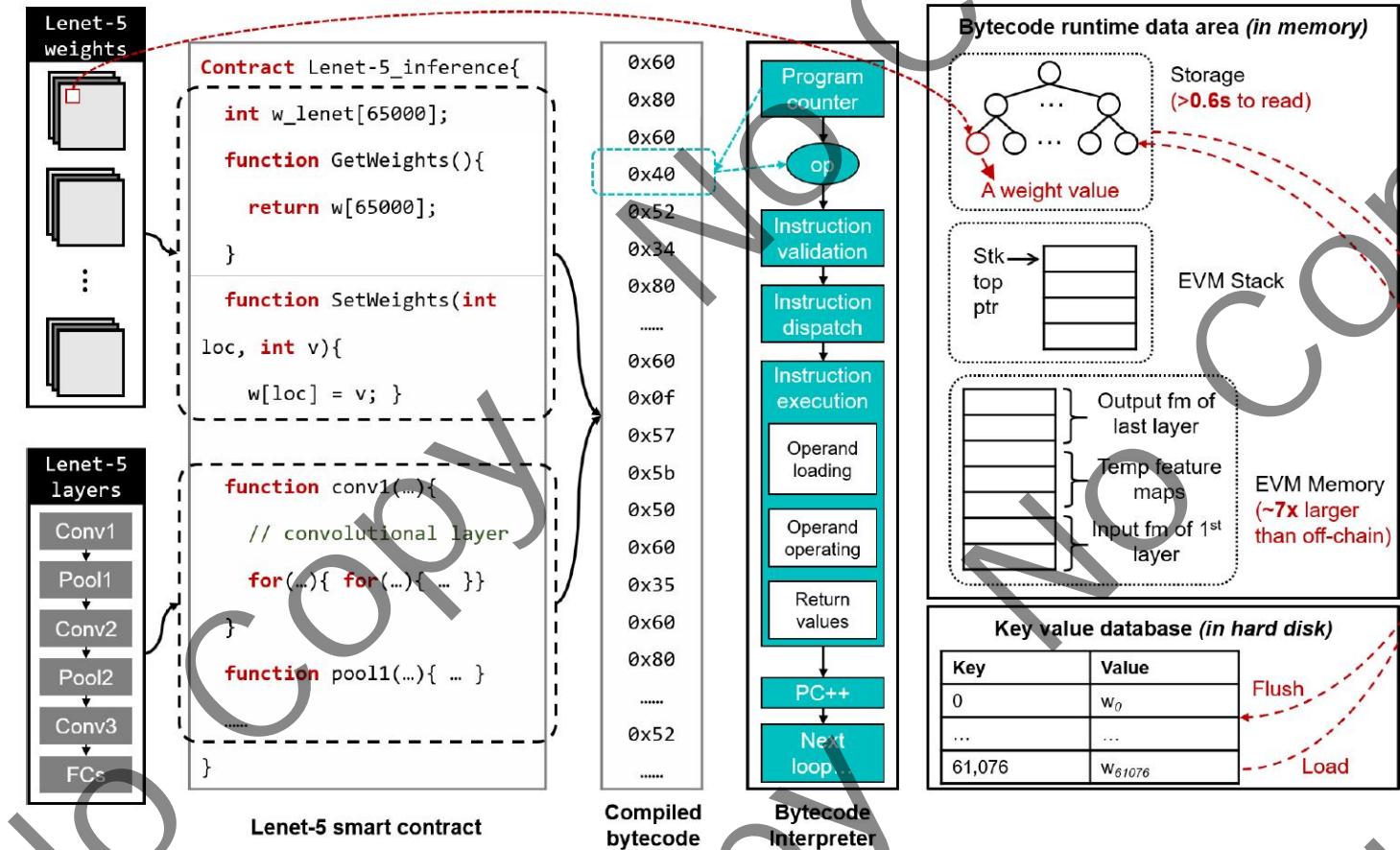


挑战一：通用指令集及特定指令缺失，
基于栈的虚拟机需要频繁处理栈数据，
导致CNN推理需执行上千万条指令

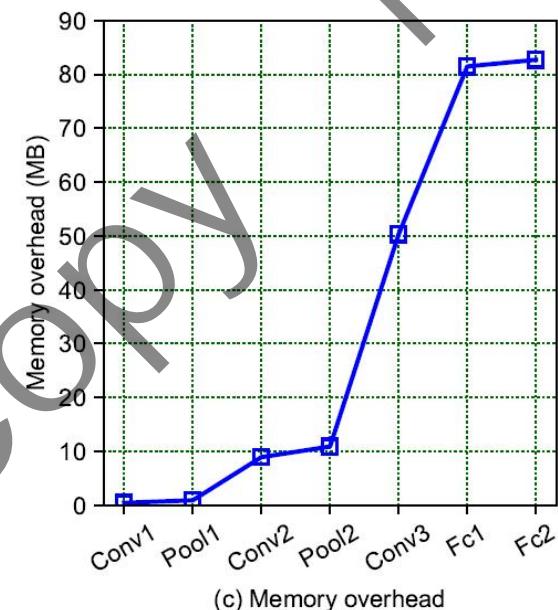


Moving computations rather than moving data!

Problems of on-chain CNN inference

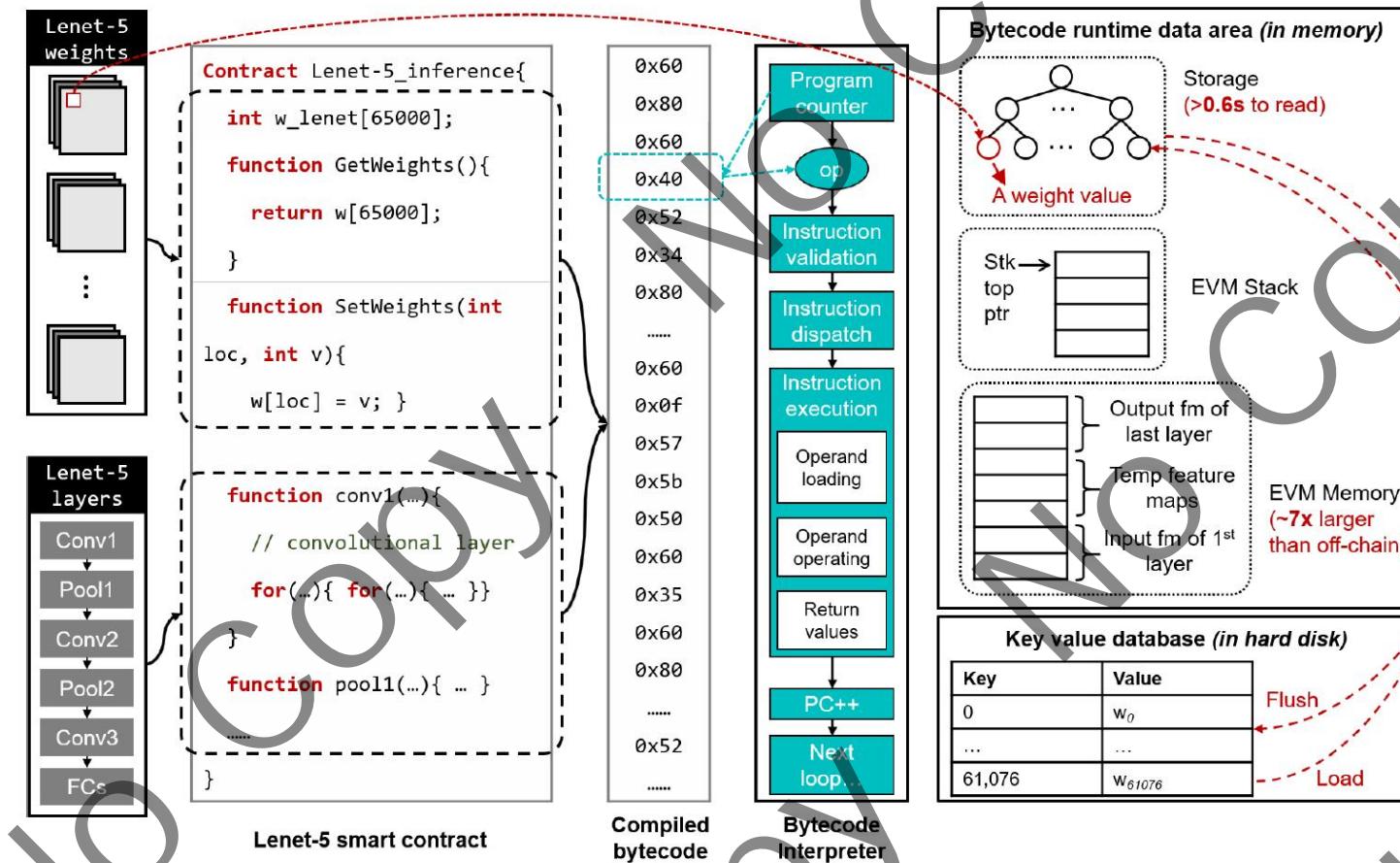


挑战二：内存管理欠缺，仅包括一个空闲指针管理(0x40)，导致CNN推理运行时大数据无法被有效管理

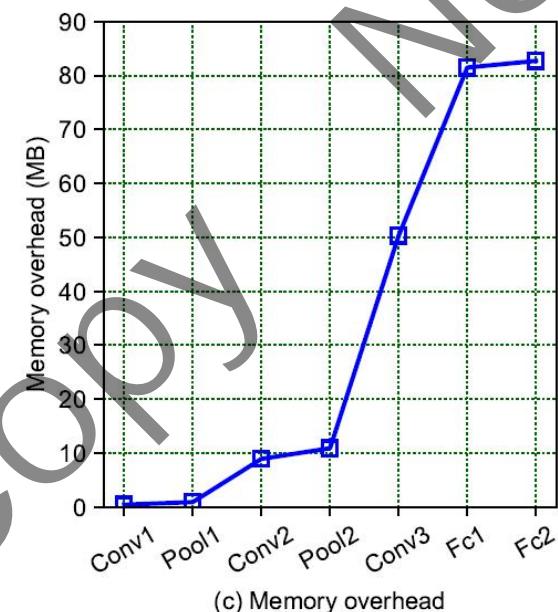


Moving computations rather than moving data!

Problems of on-chain CNN inference



挑战三：串行(for)单平台计算(CPU)无法匹配CNN并行度高的特点和需求



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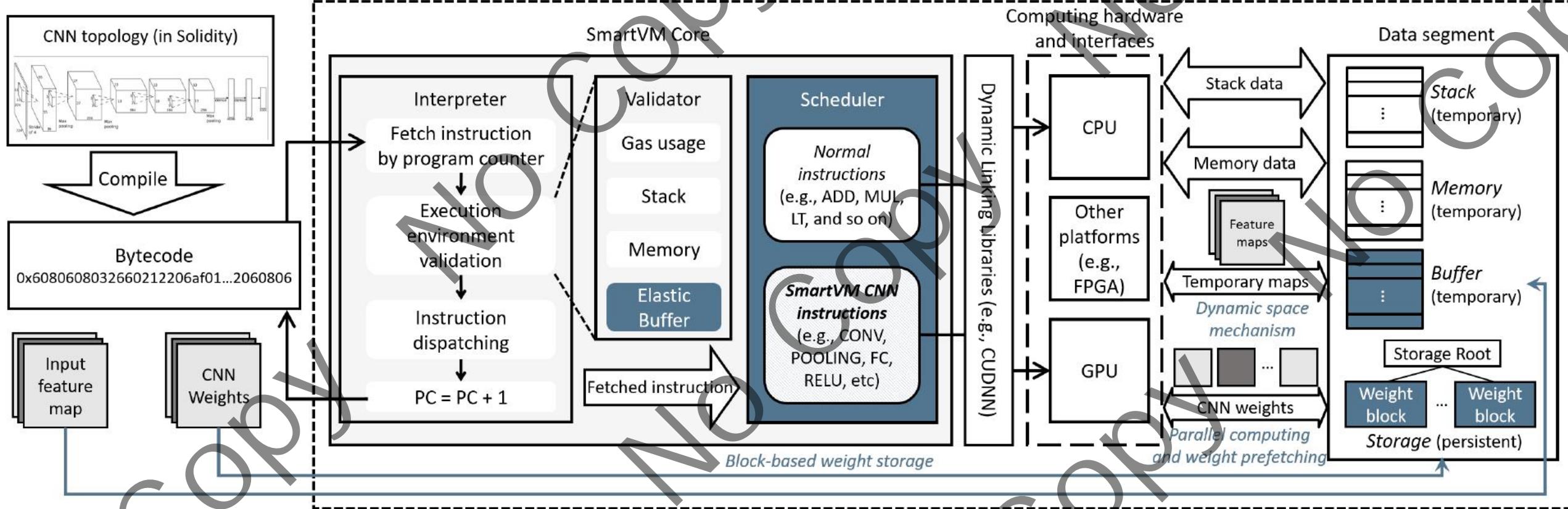
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► SmartVM Overview

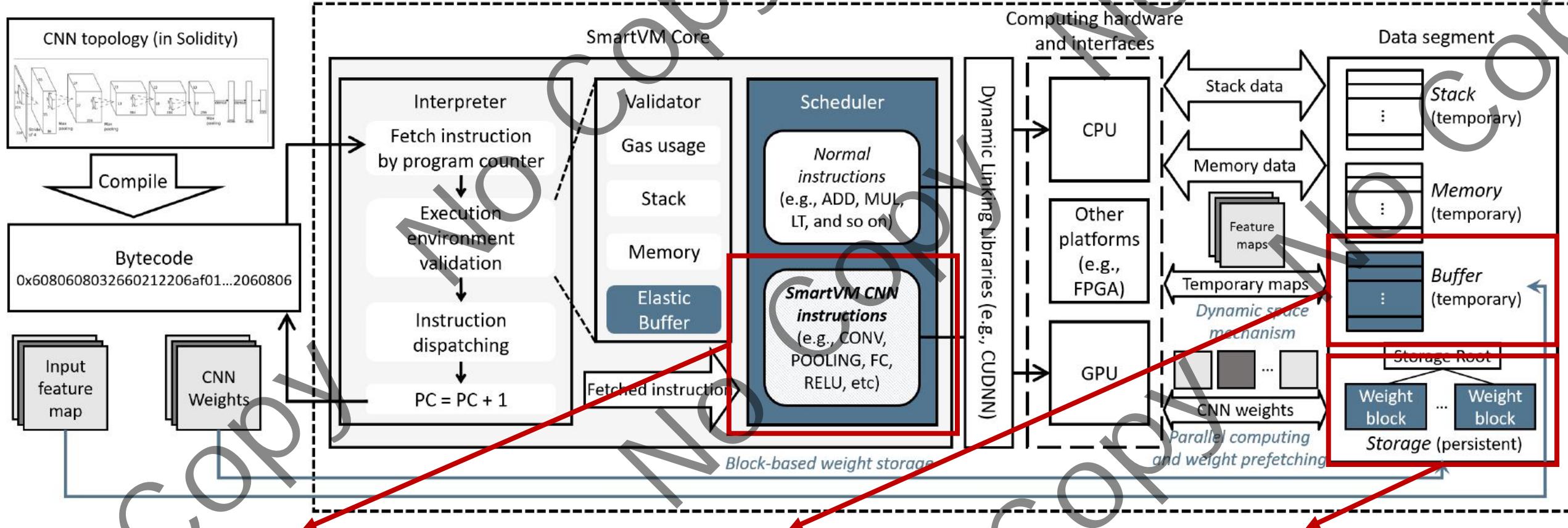


◆ CNN-oriented Instructions

◆ Dynamic Memory Management Method

◆ CNN Weight Prefetching and Parallel Computation

► SmartVM Overview



◆ CNN-oriented Instructions

◆ Dynamic Memory Management Method

◆ CNN Weight Prefetching and Parallel Computation

CNN-oriented Instructions

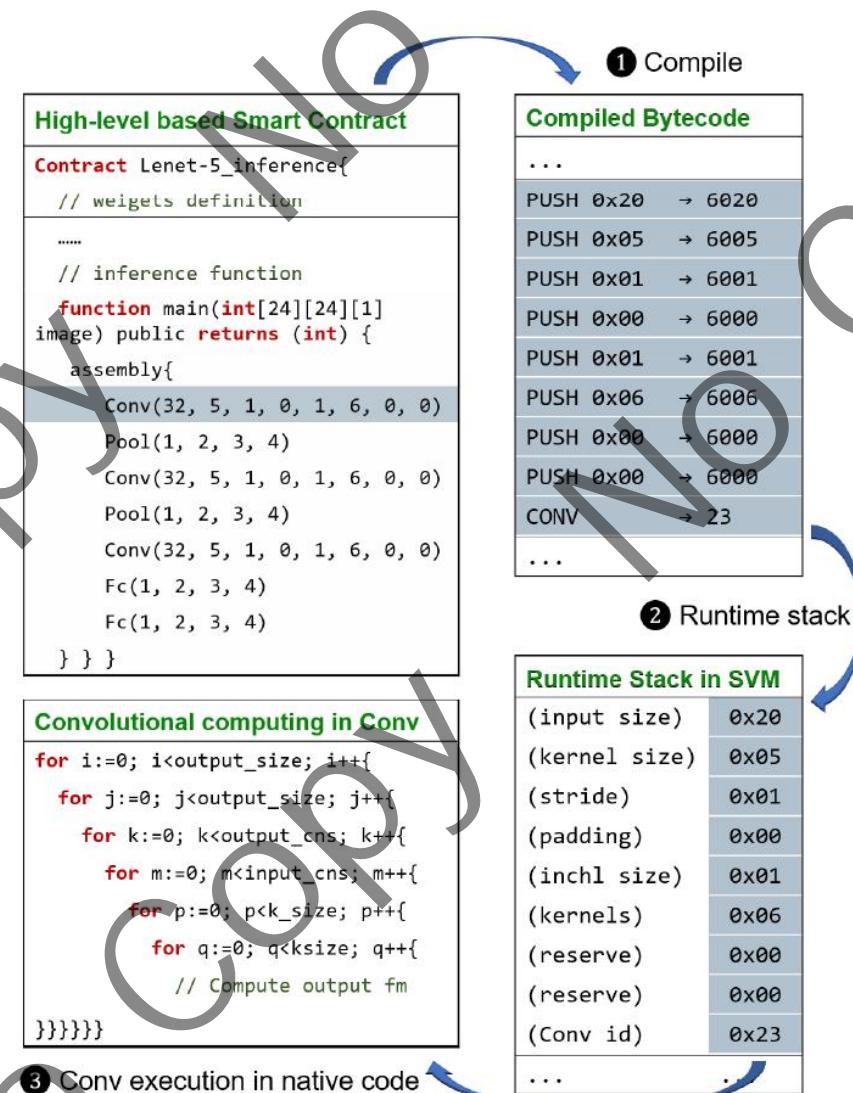
| Type | Name | Opcode | Description | Stack required (Key arguments) |
|--------------|-----------|--------|--|------------------------------------|
| (Pooling) | CONV_SING | 0x21 | Implement single channel convolution | 8 (Kernel, Output channel, Stride) |
| | CONV_MUL | 0x22 | Implement multi-channel convolution | 8 (Kernel, Output channel, Stride) |
| | CONV_3D | 0x23 | Implement 3D convolution | 8 (Kernel, Output channel, Stride) |
| | CONV_TPD | 0x24 | Implement transposed convolution | 8 (Kernel, Output channel, Stride) |
| | POOL_MAX | 0x25 | Implement max pooling | 5 (Stride, Input channel) |
| | POOL_AVG | 0x26 | Implement average pooling | 5 (Stride, Input channel) |
| | POOL_OL | 0x27 | Implement overlapping pooling | 5 (Stride, Input channel) |
| | FULL_CON | 0x28 | Implement full connected layer | 5 (Input channel, Output channel) |
| | MAT_MUL | 0x29 | Implement matmul | 2 (Addresses of two matrix) |
| (Active) | ACT_SM0 | 0x2a | Implement softmax function | 1 (Value) |
| | ACT_SM1 | 0x2b | Implement Sigmoid function | 1 (Value) |
| | ACT_RL | 0x2c | Implement ReLU function | 1 (Value) |
| | ACT_TANH | 0x2d | Implement Tanh function | 1 (Value) |
| | BUF_SCL0 | 0x2e | Increase Buffer's data with specific times | 1 (Specific times) |
| (Buffer) | BUF_SCL1 | 0x2f | Reduce Buffer's data with specific times | 1 (Specific times) |
| | BUF_BIAS | 0x30 | Add Buffer's data and bias | 1 (Base address of bias) |
| | MTOB | 0x31 | Transfer data from Memory to Buffer | 2 (Data offset) |
| | BTOM | 0x32 | Transfer data from Buffer to Memory | 2 (Data offset) |
| | BTOS0 | 0x33 | Transfer data from Buffer to Stack | 2 (Data offset, Size) |
| | BTOS1 | 0x34 | Transfer data from Buffer to Storage | 2 (Data offset, Size) |
| | BUF_CLS | 0x35 | Clean Buffer's data | 1 (Clean number) |
| | BUF_FIL | 0x36 | Fill Buffer's data with specific data | 1 (Specific filled data) |
| | BUF_INIT | 0x37 | Initial Buffer with specific size | 1 (Specific size) |
| (Buffer set) | BUF_ALLO | 0x38 | Allocate specific size to Buffer | 1 (Specific size) |
| | BUF_FREE | 0x39 | Free specific size from Buffer | 1 (Specific size) |
| | BUF_COPY | 0x3a | Copy a same Buffer | 2 (Start and end pointers) |

- ◆ 计算指令
 - ◆ Conv
 - ◆ Pool
 - ◆ FC
 - ...

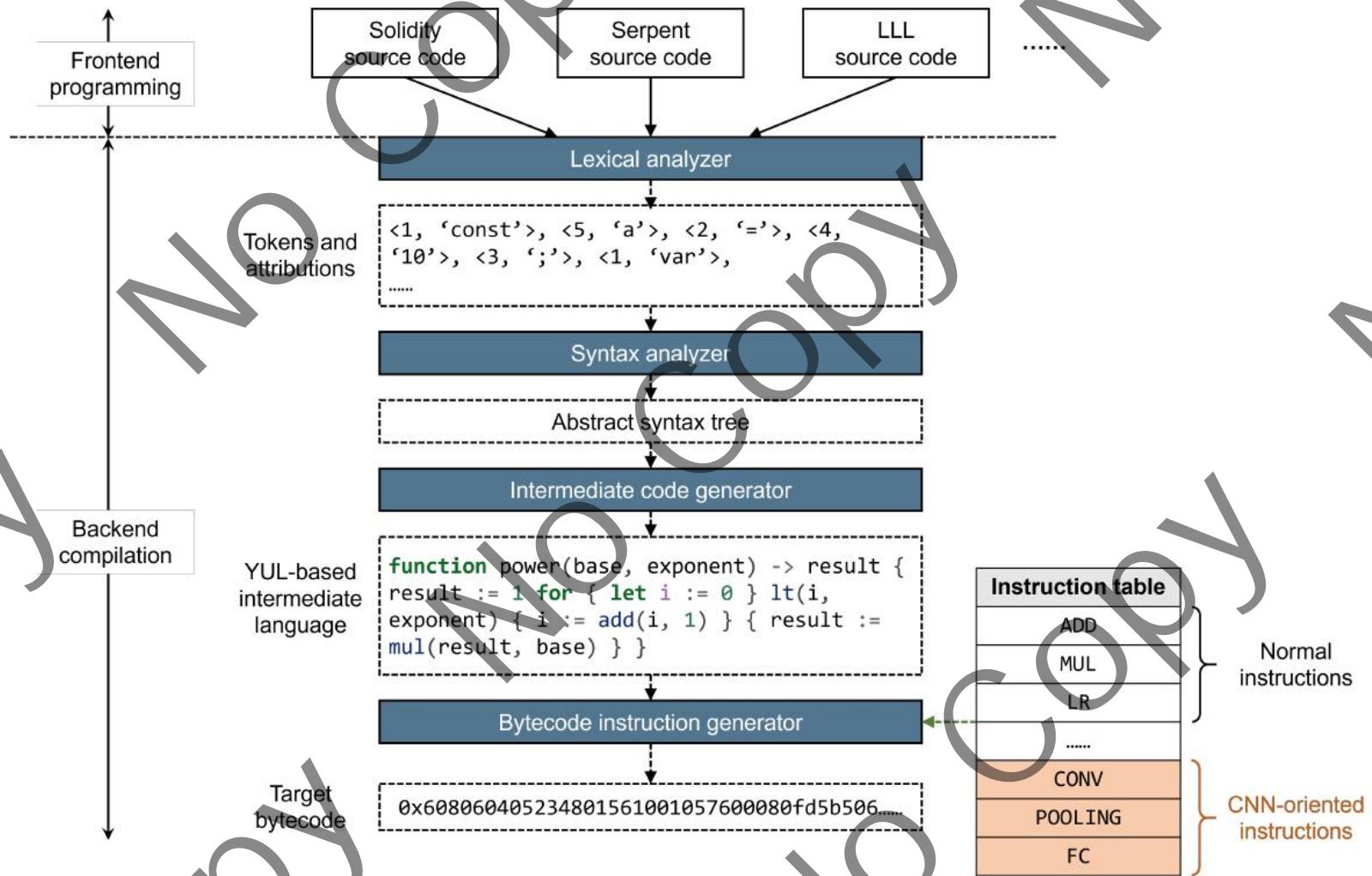
- ◆ 数据转移指令
 - ◆ Stg.
 - ◆ Stk.
 - ◆ Mem.
 - ◆ Buf.

CNN-oriented Instructions Workflow

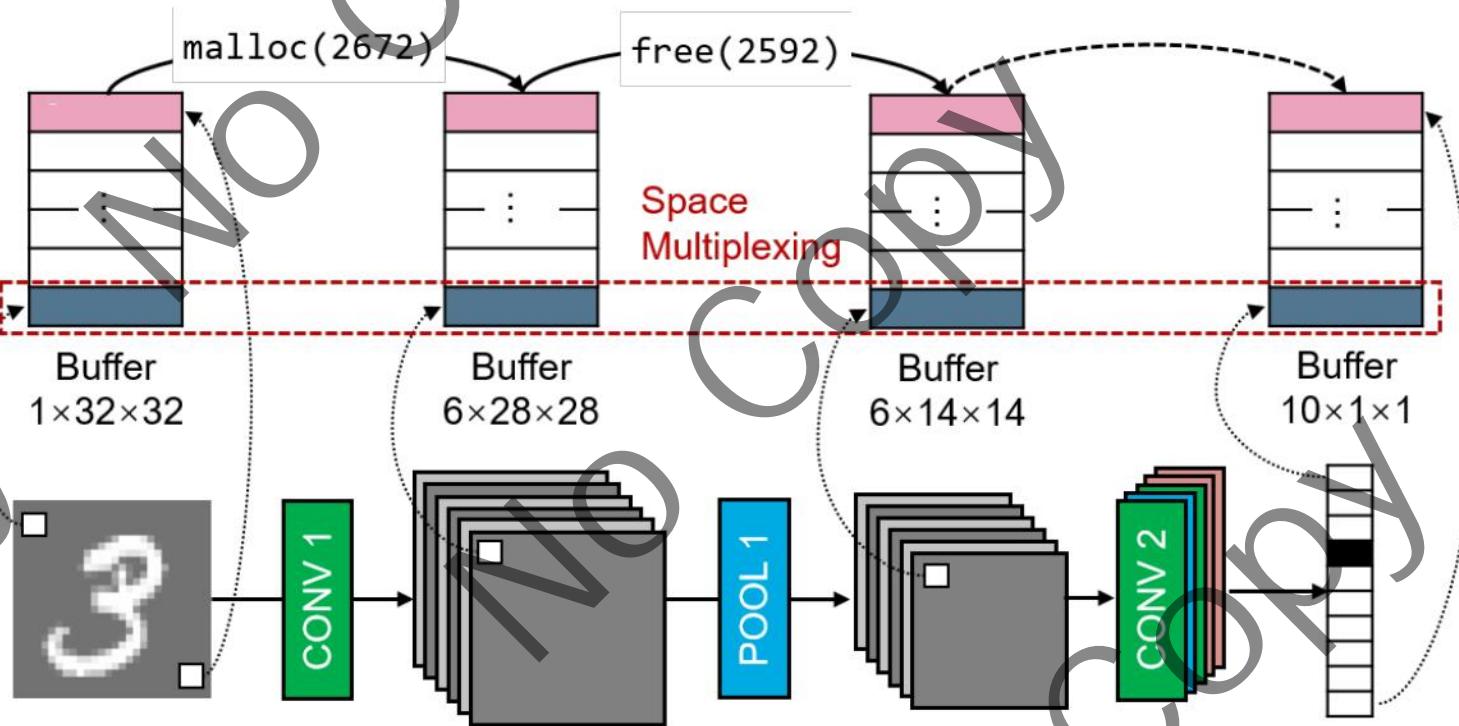
- ◆ 编译Implementation
 - ◆ 采取行内汇编的形式
 - ◆ 参数记录在栈中
 - ◆ $N * \text{Push} + 1 * \text{CNNI}$
- ◆ 运行时参数入栈
- ◆ Native Code执行循环



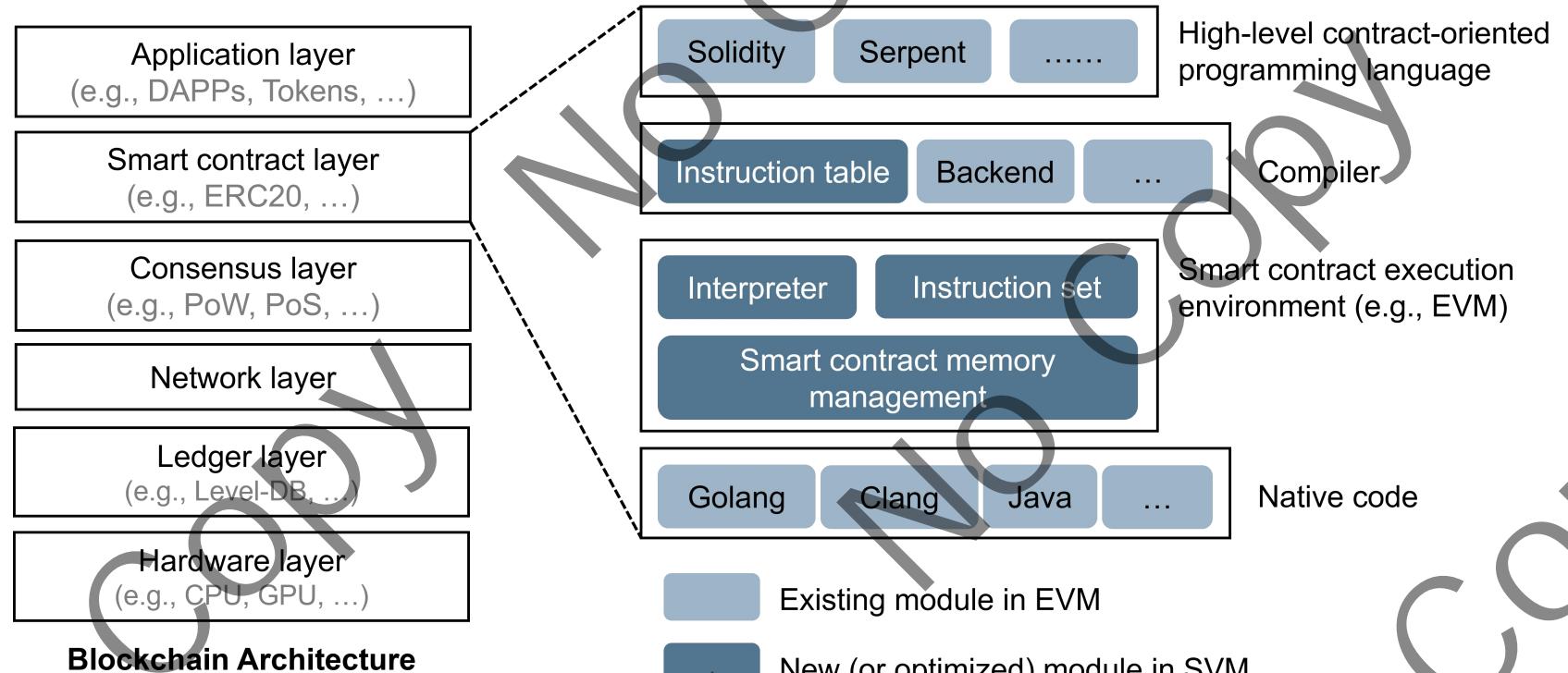
► Compiler for CNN-oriented Instructions (编译层次)



► Dynamic Memory Management Method



► Dynamic Memory Management Method



► CNN Weight Prefetching and Parallel Computation

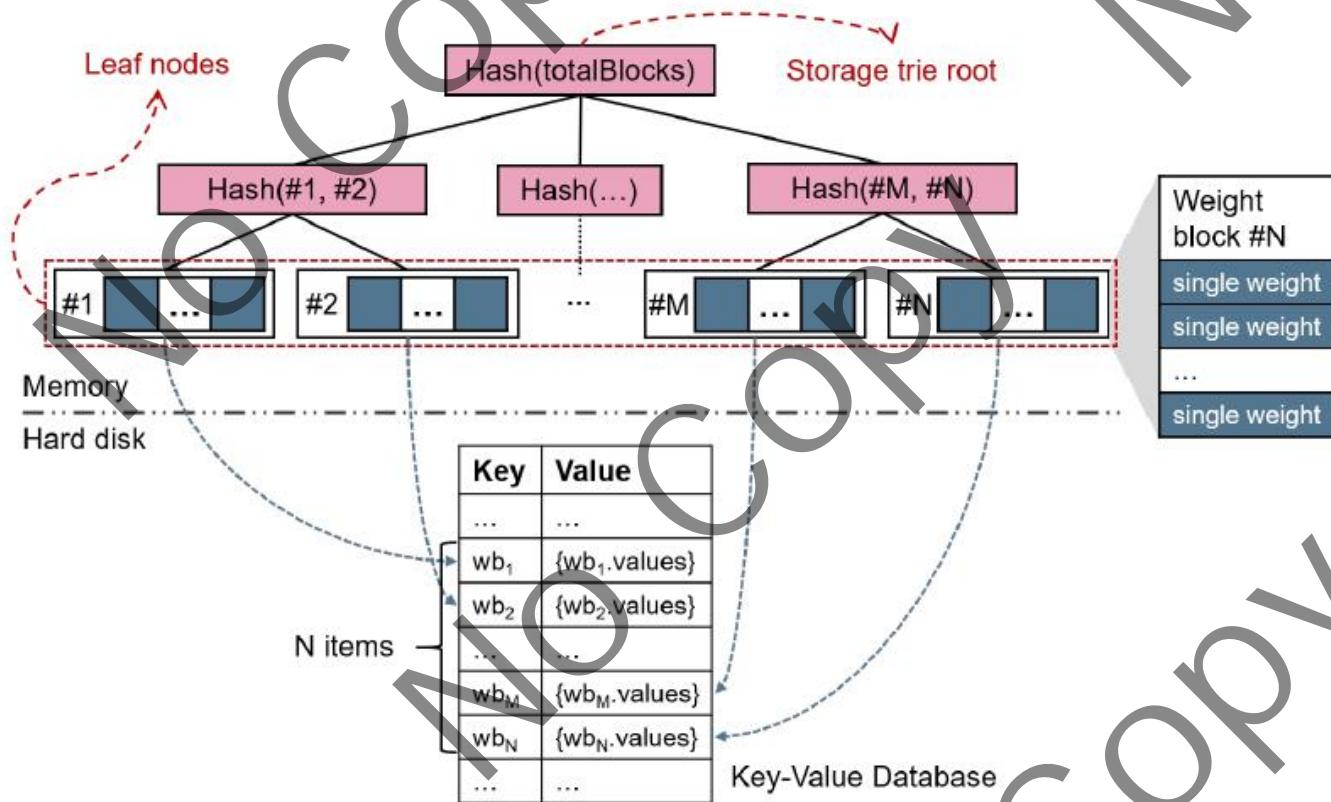


Fig. 9: The block-based weight storage.

► CNN Weight Prefetching and Parallel Computation

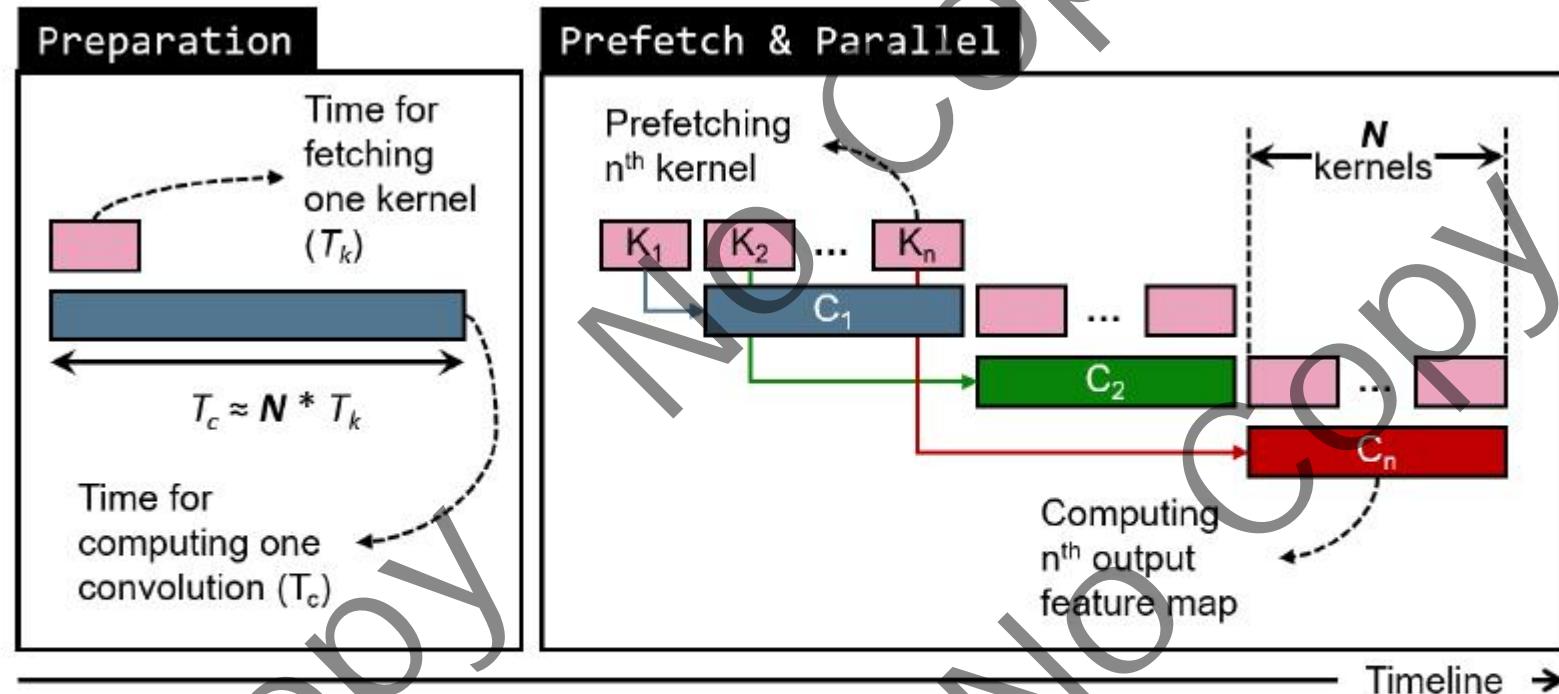


Fig. 10: The weights prefetching and parallel computation model in Conv instruction.

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► Setup

Code Length

Source code

Compiled bytecode

Latency

End-to-end

Weights fetching latency

Computing latency

Memory footprint

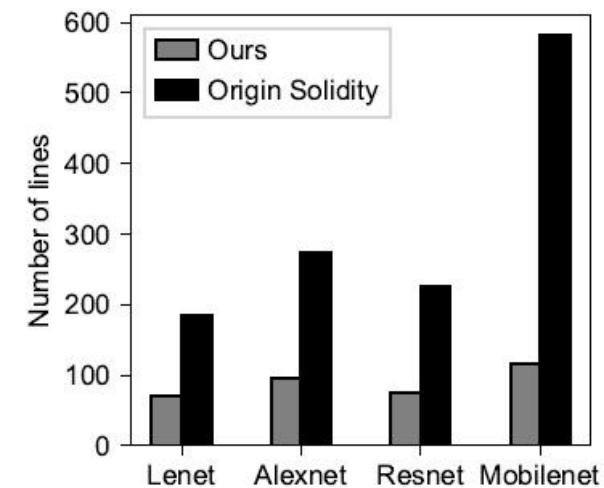
EVM Memory vs. Buffer

SmartVM vs. Native code

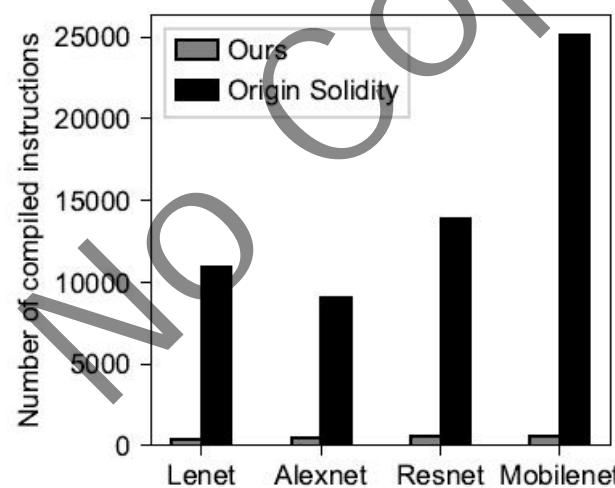
LeNet, AlexNet, ResNet18, MobileNet, and LSTM



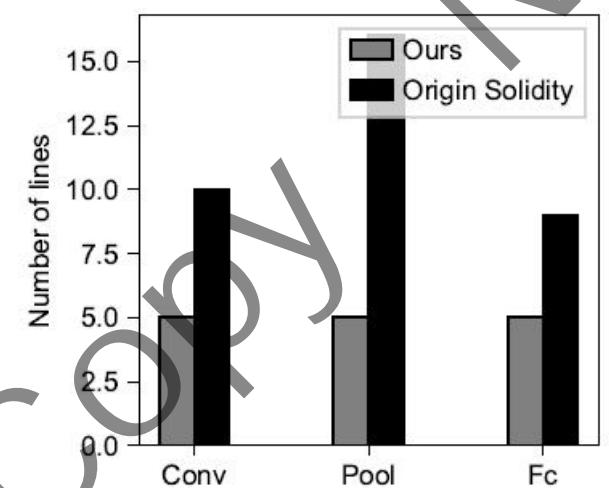
► Code length



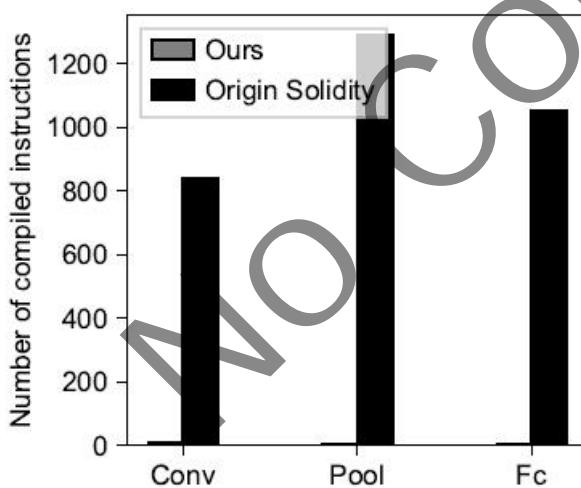
(a) Source code length



(b) Bytecode length



(c) Source code length for each layer



(d) Bytecode length for each layer

110 lines
vs.
600 lines

↓ 95%

► Code length

Native Solidity-based Lenet-5 inference contract

```

1 pragma solidity ^0.5.1;
2
3 contract lenet {
4
5   .....
6
7   function convolution1(uint input_size, uint kernel_size,
8     uint stride, uint padding, uint input_channel_number,
9     uint output_channel_number) public view
10    returns(int[24][24][6] memory output_fm){
11
12   uint output_size = (input_size - kernel_size + 2 * padding) / stride + 1;
13
14   for(uint i=0; i<output_size; i++){
15
16     for(uint j=0; j<output_size; j++){
17
18       for(uint k=0; k<output_channel_number; k++){
19
20         for(uint m=0; m<input_channel_number; m++){
21
22           for(uint p=0; p<kernel_size; p++){
23
24             for(uint q=0; q<kernel_size; q++){
25
26               output_fm[k][i][j] = output_fm[k][i][j] +
27                 conv1_kernel[k][m][p][q] * input_fm_conv1[m][stride * i +
28                   p][stride * j + q];
29
30           }}}}}}}
31
32   return output_fm;
33
34 }
35
36 .....
37 }
```

Compile

```
0x608060405234801561001057600080fd5b50612cce80610020600039600
0f3fe608060405260043610610164576000357c0100000000000000000000000
000000000000000000000000000000000000009004806310a0991a146101695
780631126904803603602081101561018c57600080fd5b810190808035906
020019092919050506113cb565b60405180828152602001915050604051
f35b34801561.....
```

Compiled bytecode of convolution1(...)
(~17,580,000 instructions)

Compiled results
are the same

Compiled results
are different

Solidity-based Lenet-5 inference smart contract (with function abstraction)

```

1 pragma solidity ^0.5.1;
2
3 import 'nnlib.sol';
4
5 contract lenet {
6
7   .....
8
9   function convolution1() public view
10    returns(int[24][24][6] memory output_fm){
11
12   network{
13
14     Conv(..., ...)
15
16   }
17
18   return output_fm;
19
20 }
21
22 .....
23 }
```

Compile

```
91a146101695780631126004803603602081101561018c5
7600080fd5b810190808035906020019092919050505061
13cb565b60405180828152602001915050604051f35b348
01561.....
```

Compiled bytecode of convolution1(...)
(~17,580,000 instructions)

Solidity-based Lenet-5 inference smart contract (with CNN-oriented instructions)

```

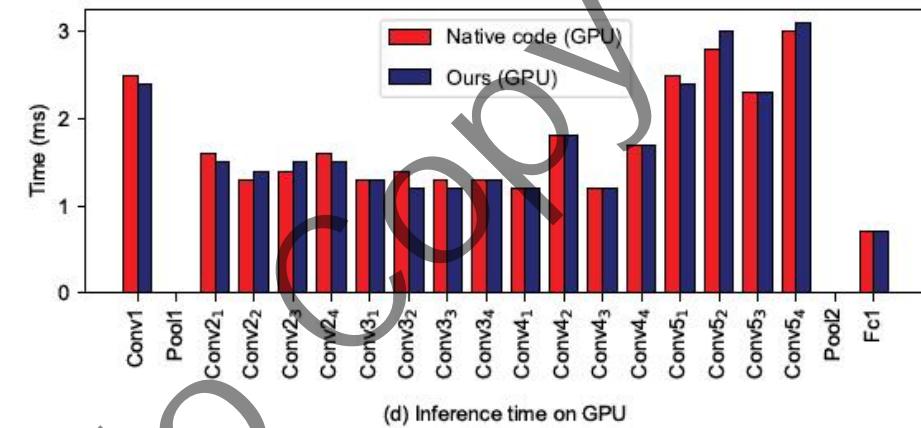
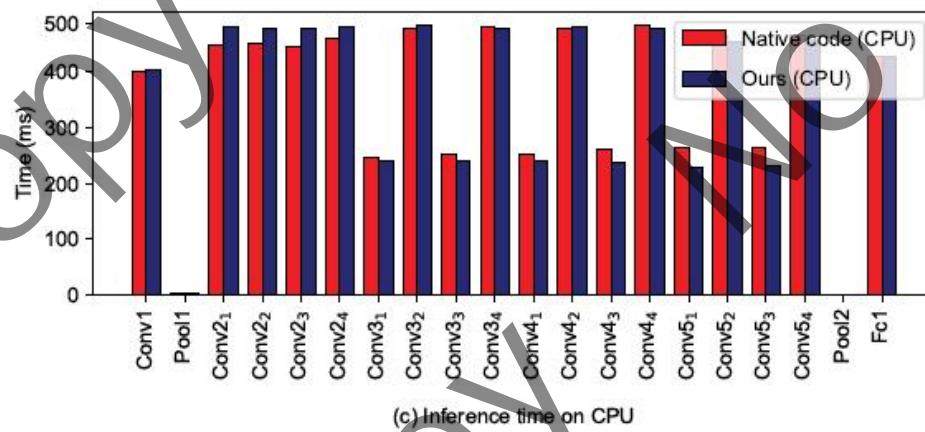
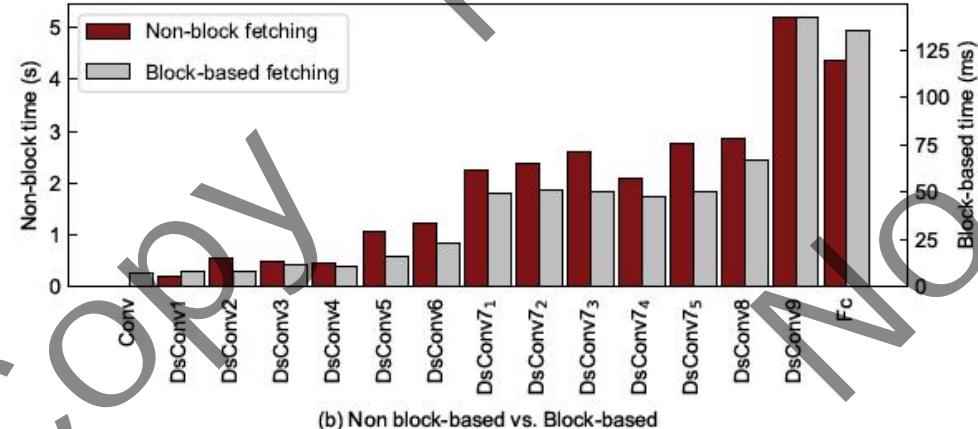
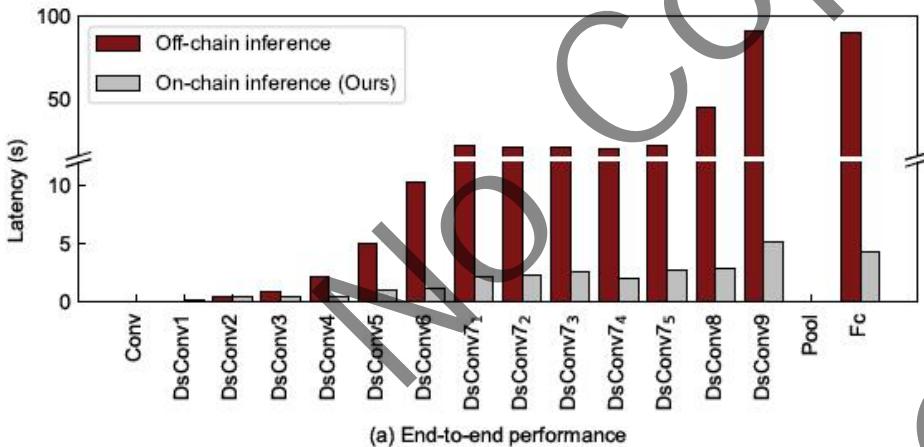
1 pragma solidity ^0.5.1;
2
3 contract lenet {
4
5   .....
6
7   function convolution1() public view
8    returns(int[24][24][6] memory output_fm){
9
10   assembly{
11
12     Conv(..., ...)
13
14   }
15
16   return output_fm;
17
18 }
19
20 .....
21 }
```

Compile

```
0x6080.....60206005600160066000600023.....
```

Compiled bytecode of convolution1(...)
(~30 instructions)

► Latency



► Latency

- ◆ CNN-oriented Instructions
 - ◆ 降低97.3%计算时延
- ◆ 基于块存储
 - ◆ 降低98.7%权重获取时延
- ◆ Pipeline method
 - ◆ 降低13.1%
- ◆ Overall
 - ◆ 93.6%

TABLE II
PIPELINE LATENCY.

| Network | Latency (ms) | | | |
|-----------|------------------|-----------|-----------|---------|
| | No pipeline | | Pipelined | |
| | Weights fetching | Computing | Total | Total |
| LeNet | 2 | 10 | 12 | 9.87 |
| Alexnet | 1228 | 4370.98 | 5598.98 | 4832.68 |
| ResNet18 | 328 | 7037 | 7365 | 6871 |
| MobileNet | 677.7 | 2826.47 | 3504.17 | 3005.52 |



► Memory/RAM footprint

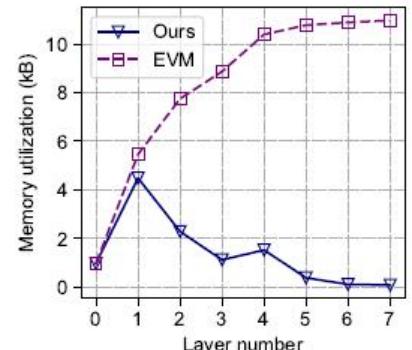
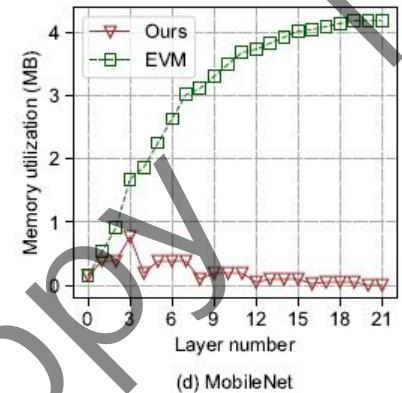
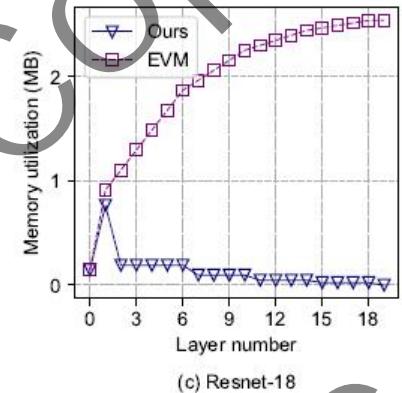
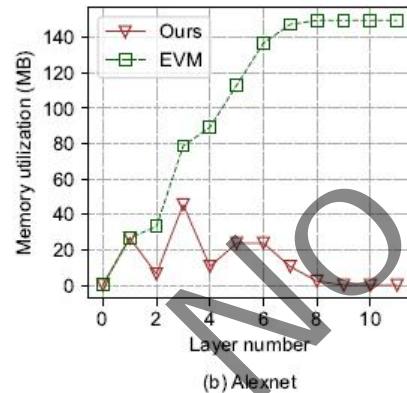
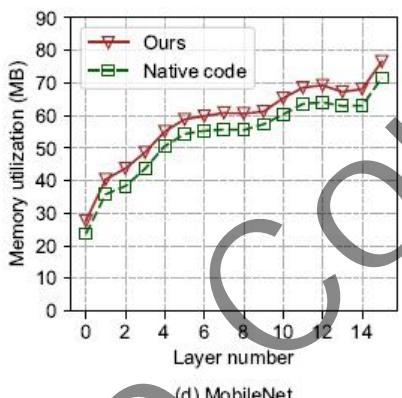
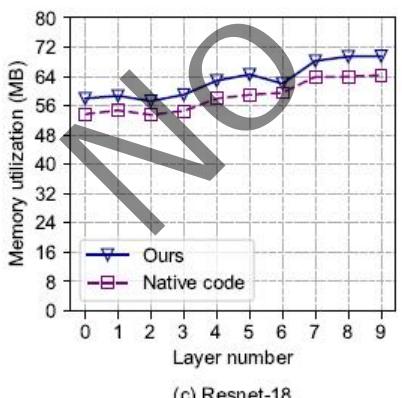
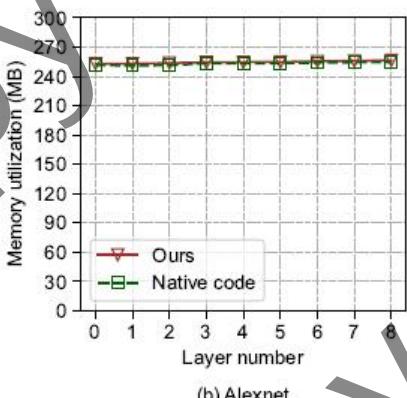
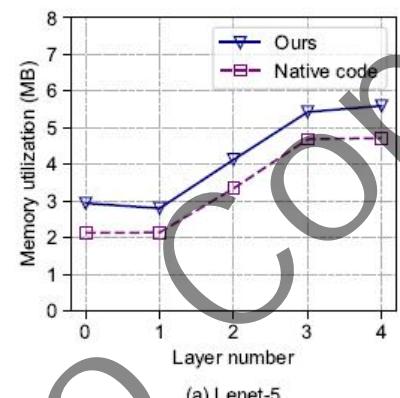


Fig. 16: RAM footprint comparison between SmartVM Buffer and EVM Memory.



- ◆ 内存分别降低84%, 90.8%, 94.3%, 及93.7%



- ◆ 内存占用近似（由于外部库调用，略高）

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● 三、SmartVM

● 四、实验

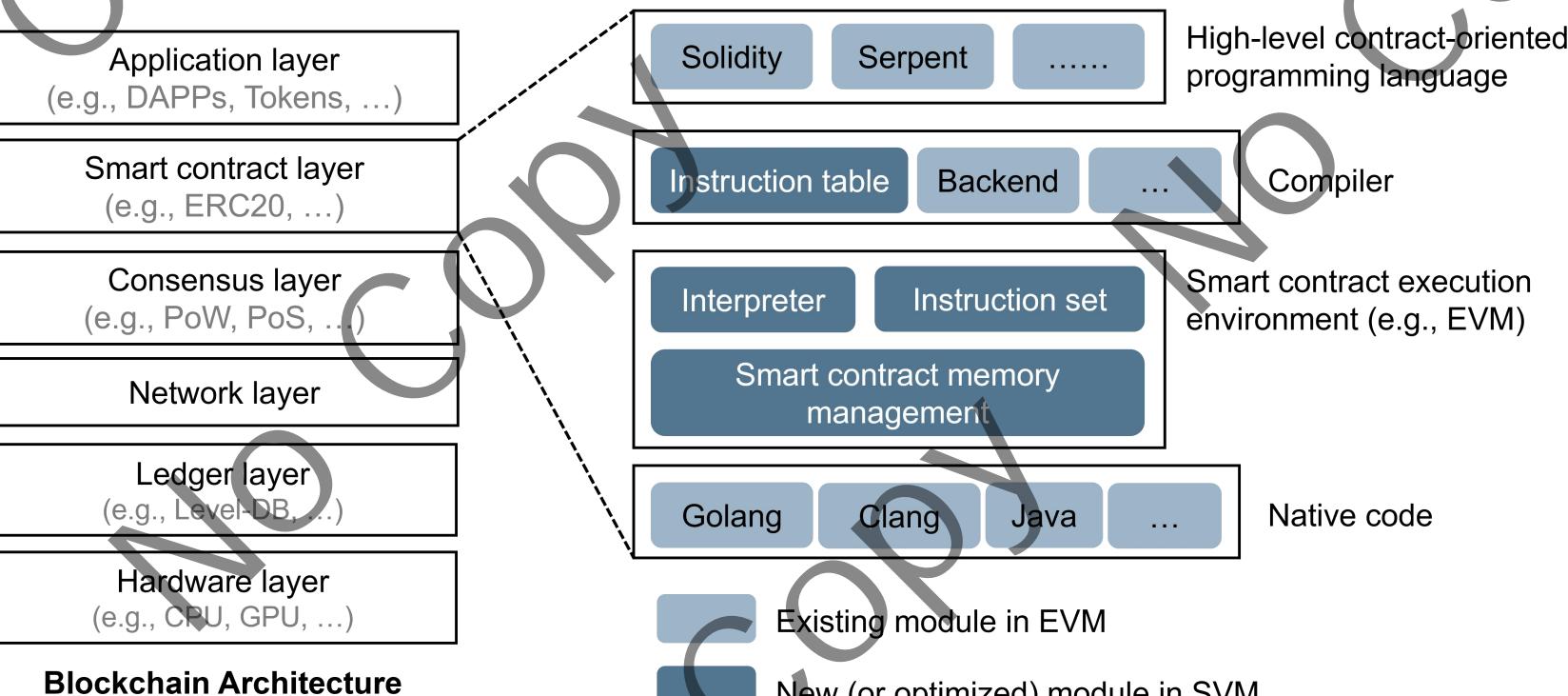
● 五、工作总结

Conclusion

- ◆ 从底层支持并加速了链上 CNN 推理
- ◆ 为 EVM 等合约执行环境提供了面向 CNN 推理的内存管理方法

未来方向：

- ◆ CNN compression for on-chain execution
- ◆ Data compression and direct data processing
- ◆ Parallel architecture





报告内容到此结束，谢谢！

Q & A

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