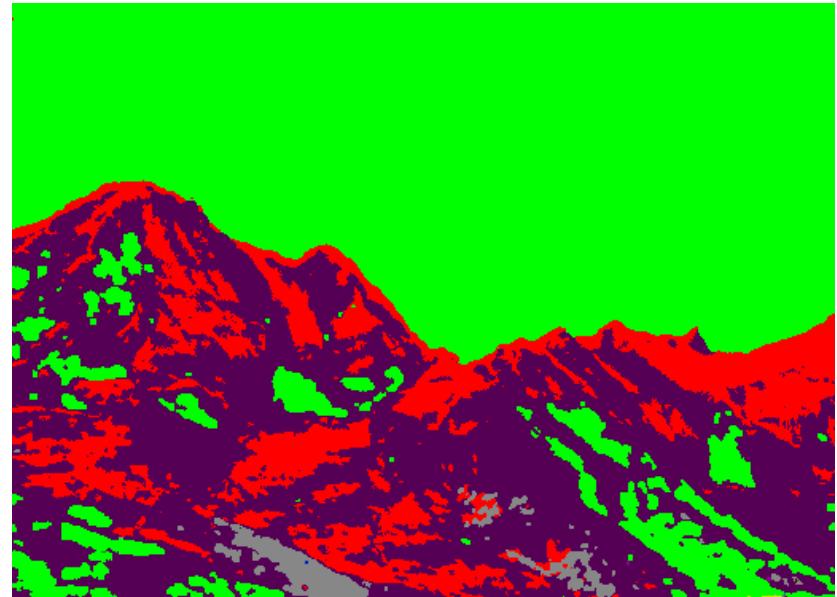
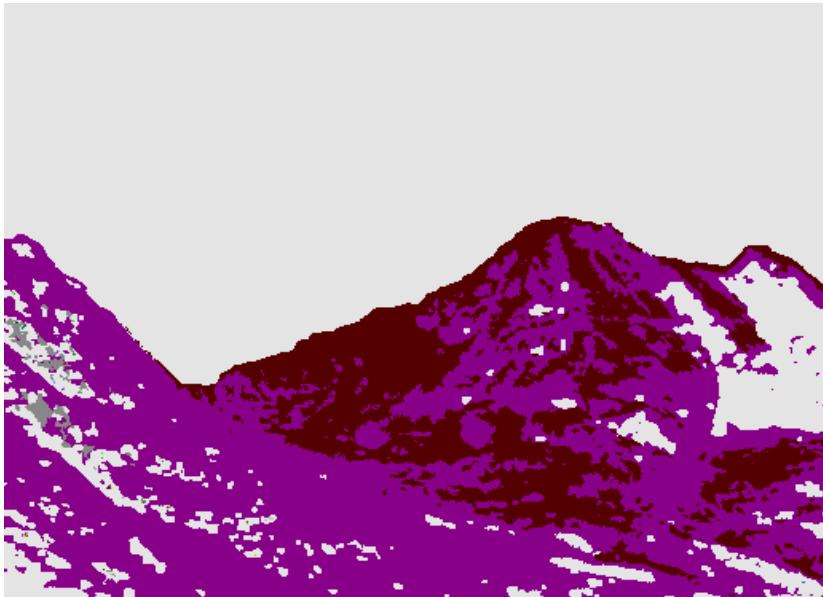
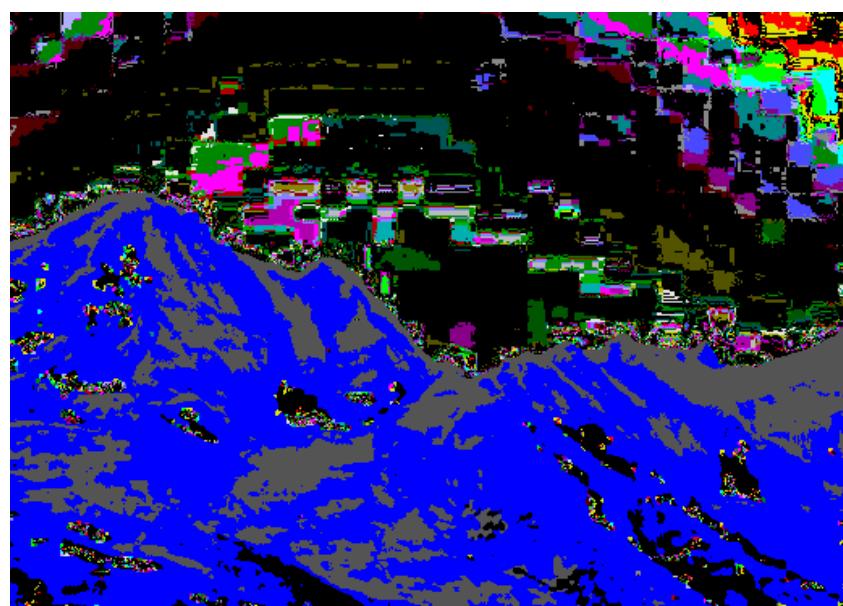
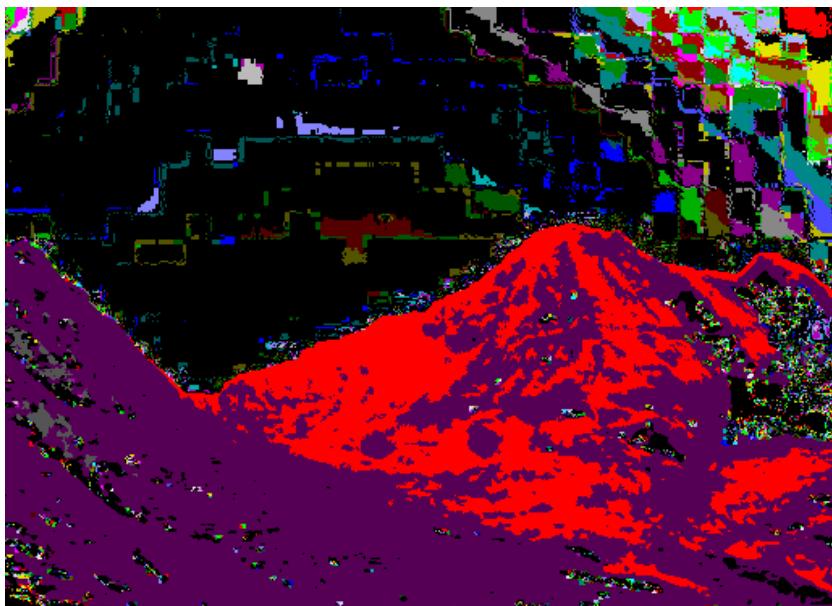


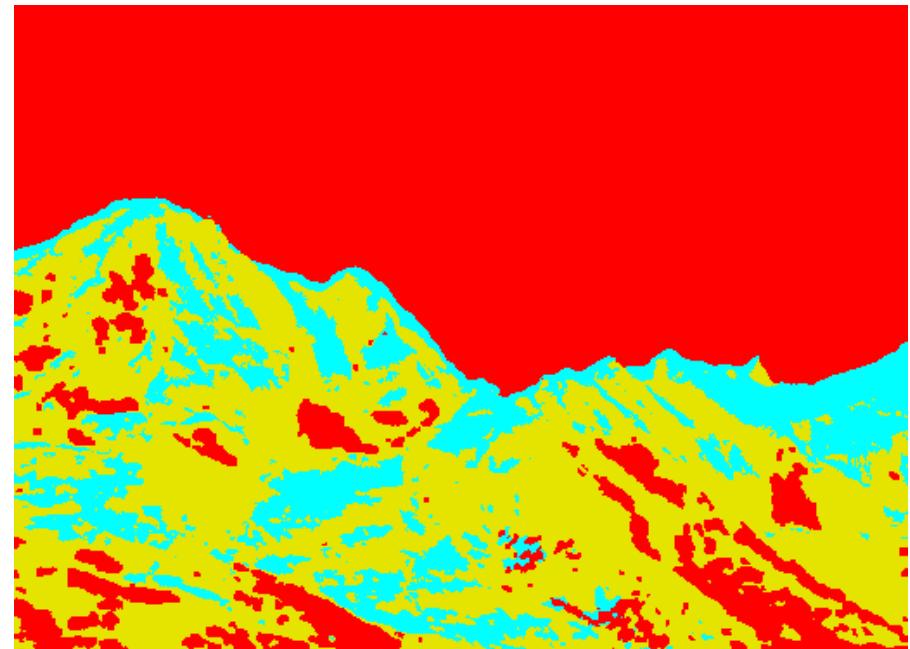
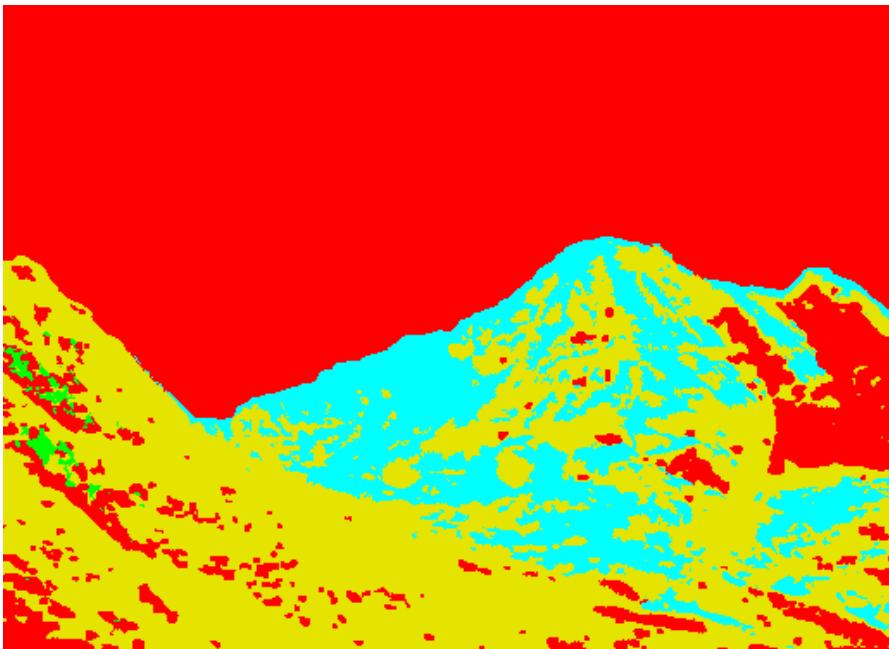
```
imageSegmentation.calculateUsingCIEXYAndClustering(gsImg1, true);
```



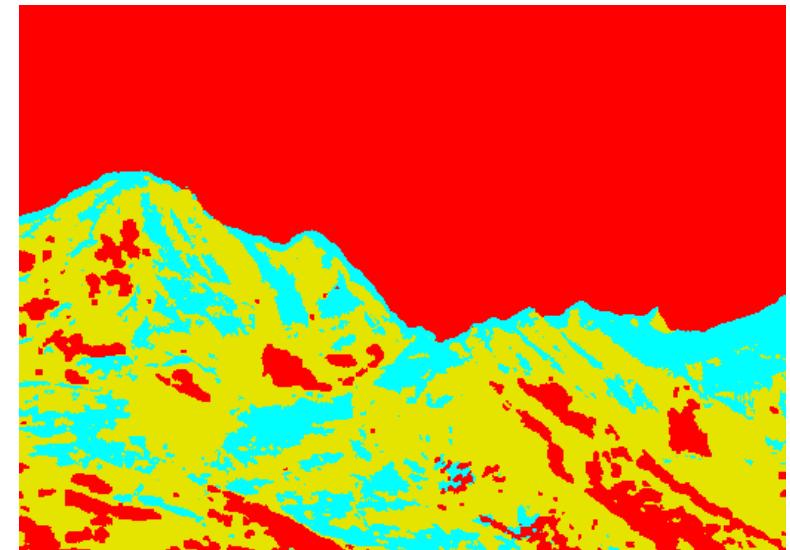
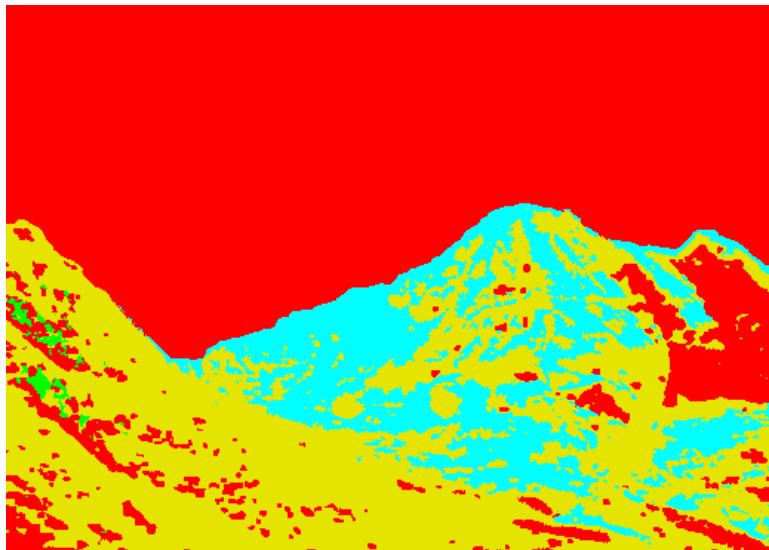
```
imageSegmentation.calculateUsingPolarCIEXYAndClustering(gsImg1, true);
```



```
imageSegmentation.calculateUsingPolarCIEXYAndFrequency(gslImg1, true);
```



```
imageSegmentation.calculateUsingPolarCIEXYAndFrequency(gslImg1, 0.2f, true);
```



```
int kBands = 2; imageSegmentation.applyUsingKMPP(gsImg1, kBands);
```



```
int kBands = 3; imageSegmentation.applyUsingKMPP(gsImg1, kBands);
```



```
int kBands = 8; imageSegmentation.applyUsingKMPP(gsImg1, kBands);
```



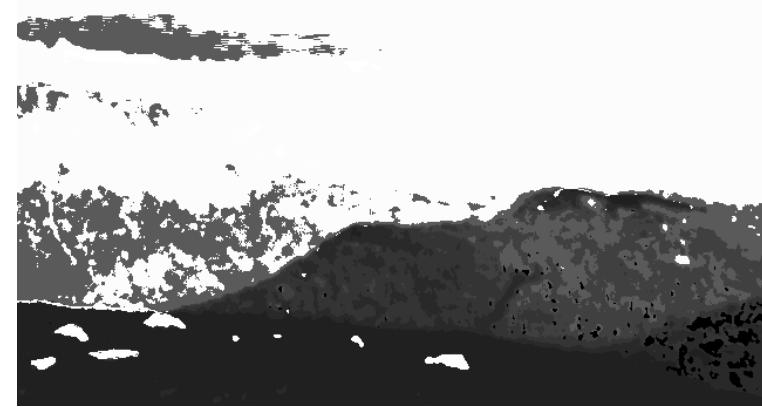
```
int kBands = 2; imageSegmentation.applyUsingCIEXYPolarThetaThenHistEq(gsImg1, kBands);
```



```
int kBands = 3; imageSegmentation.applyUsingCIEXYPolarThetaThenHistEq(gsImg1, kBands);
```



```
int kBands = 8; imageSegmentation.applyUsingCIEXYPolarThetaThenHistEq(gsImg1, kBands);
```



```
int kBands = 2; imageSegmentation.applyUsingCIEXYPolarThetaThenKMPPThenHistEq(gsImg1,  
kBands);
```



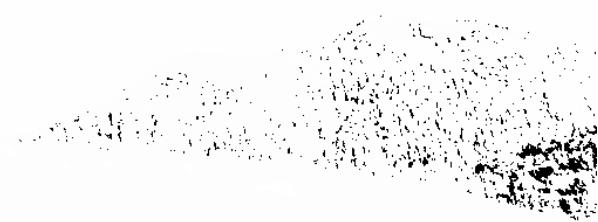
```
int kBands =3; imageSegmentation.applyUsingCIEXYPolarThetaThenKMPPThenHistEq(gsImg1,  
kBands);
```



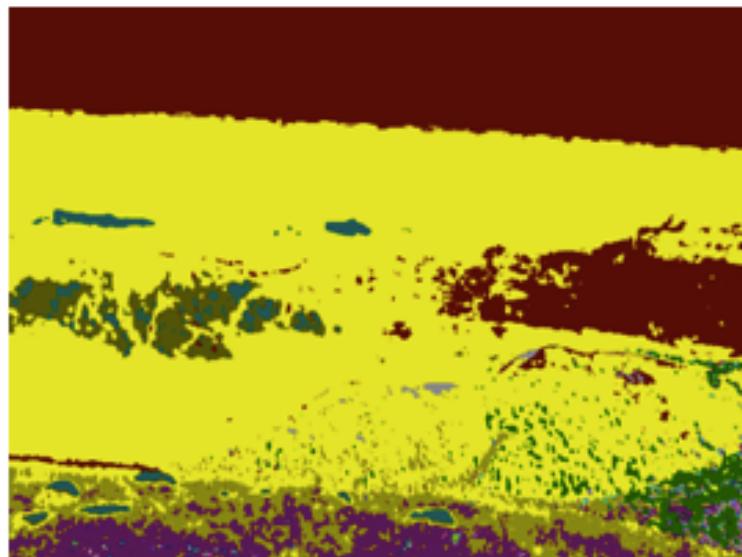
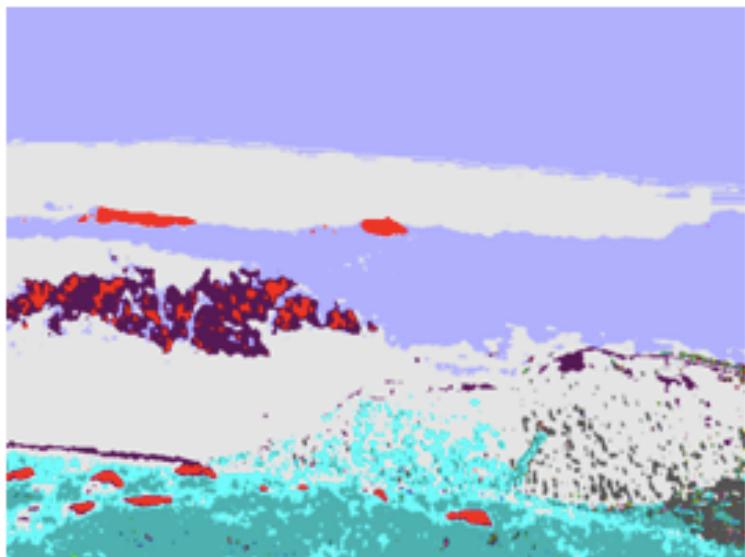
```
int kBands =8; imageSegmentation.applyUsingCIEXYPolarThetaThenKMPPThenHistEq
```



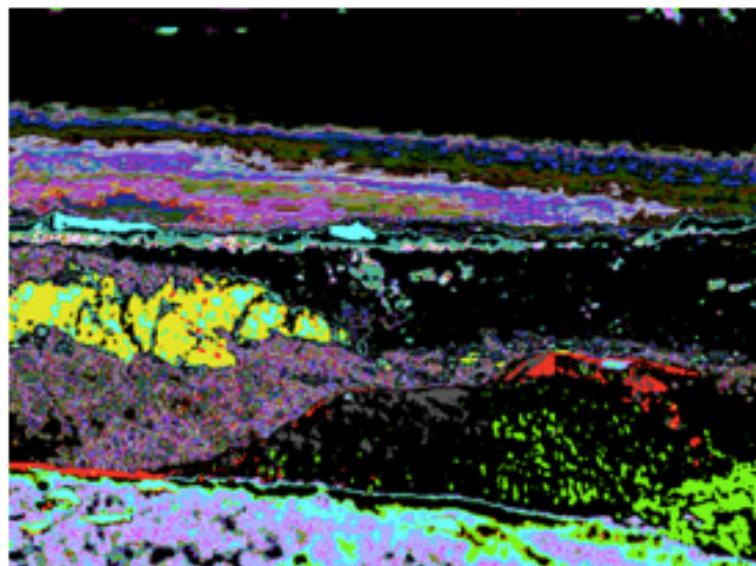
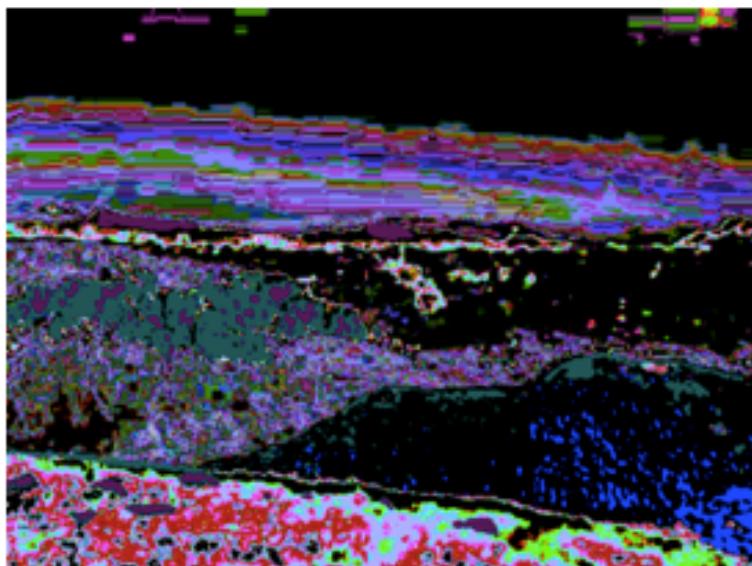
```
int kBands = 2; imageSegmentation.applyUsingCIEXYPolarThetaThenHistogram(gsImg1, kBands);
```



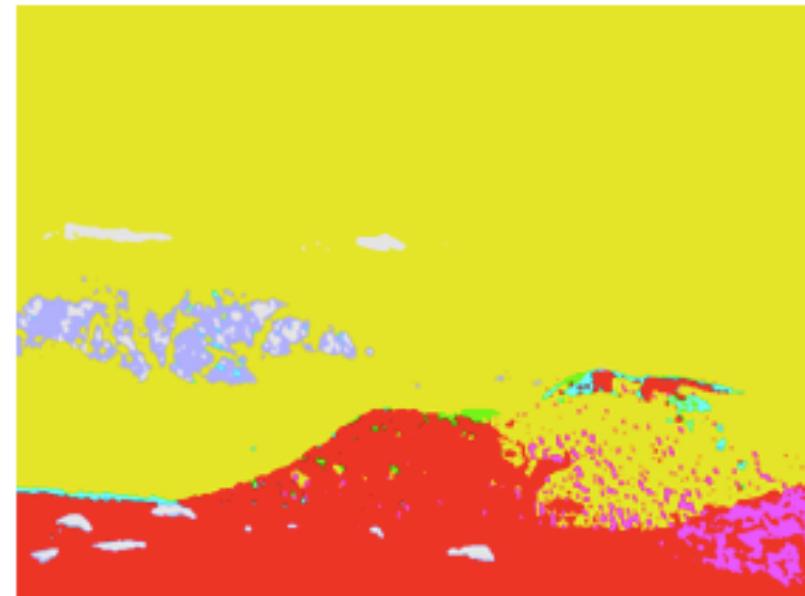
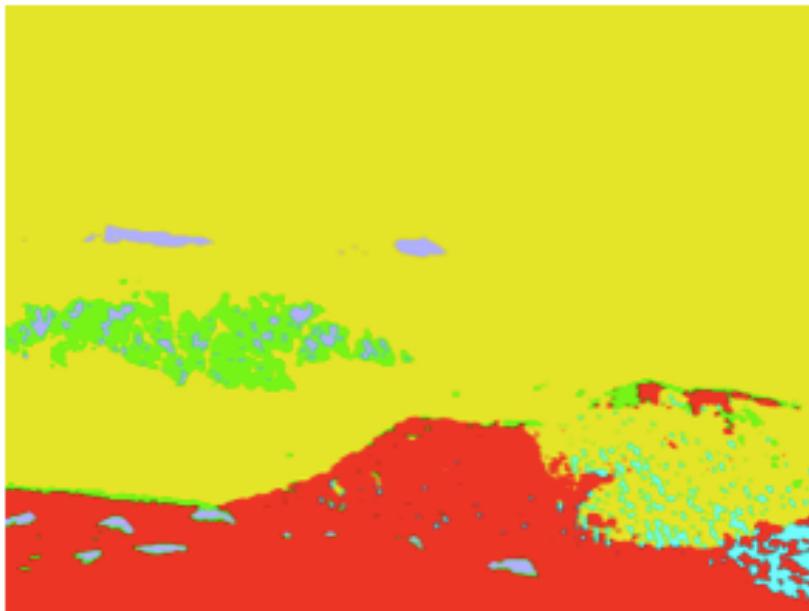
```
imageSegmentation.calculateUsingCIEXYAndClustering(gslImg1, true);
```



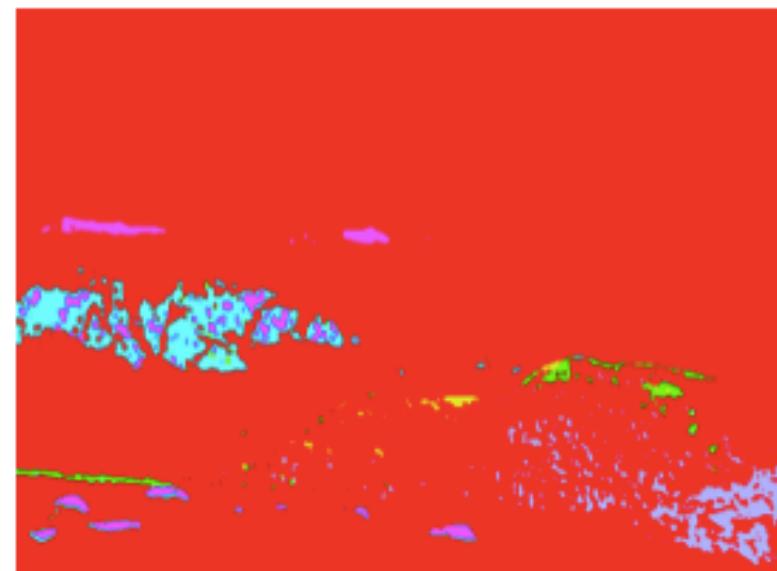
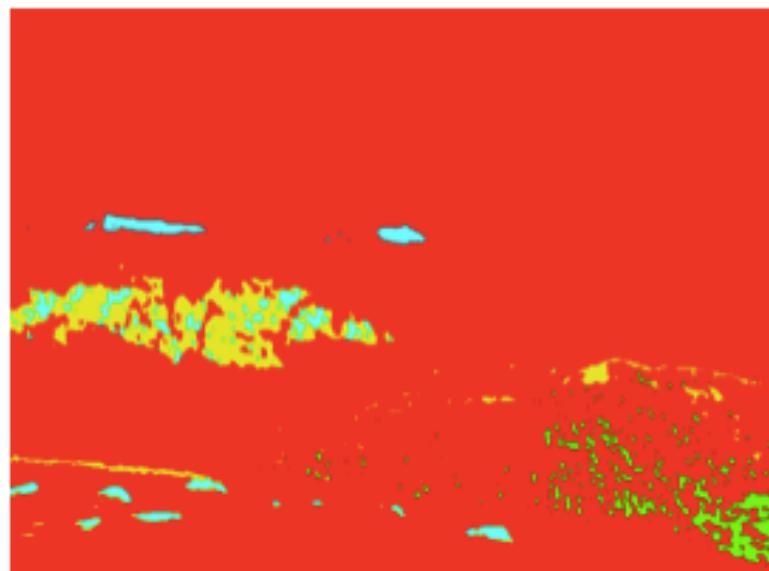
```
imageSegmentation.calculateUsingPolarCIEXYAndClustering(gslImg1, true);
```



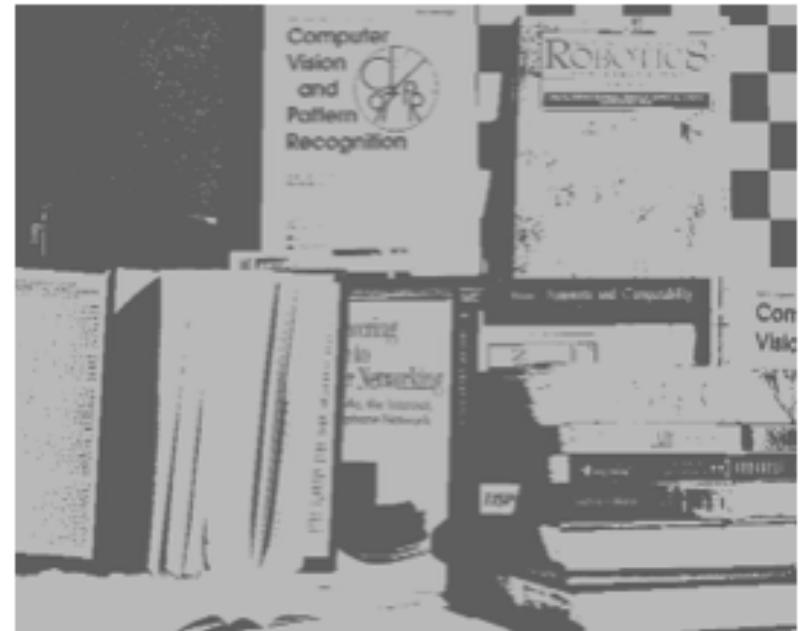
```
imageSegmentation.calculateUsingPolarCIEXYAndFrequency(gslImg1, true);
```



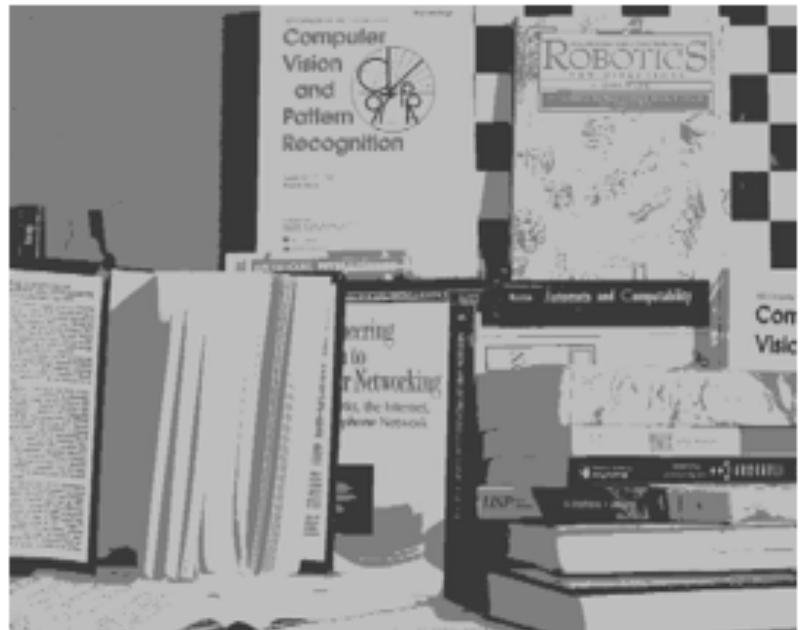
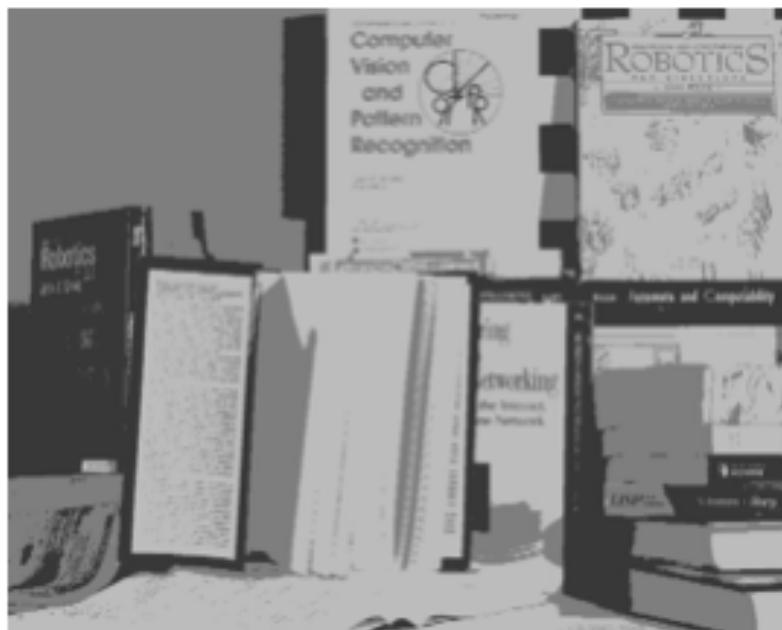
```
imageSegmentation.calculateUsingPolarCIEXYAndFrequency(gslImg1, 0.2f, true);
```



```
int kBands = 2; imageSegmentation.applyUsingKMPP(gslImg1, kBands);
```



```
int kBands = 3; imageSegmentation.applyUsingKMPP(gslImg1, kBands);
```



```
int kBands = 8; imageSegmentation.applyUsingKMPP(gsImg1, kBands);
```



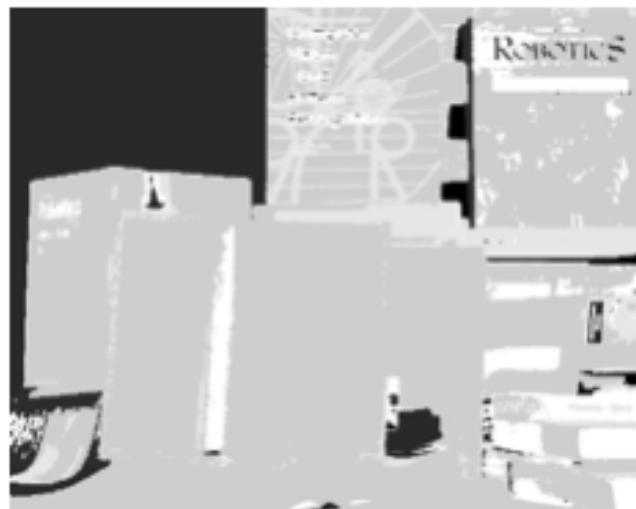
```
int kBands = 2; imageSegmentation.applyUsingCIEXYPolarThetaThenHistEq(gsImg1, kBands);
```



```
int kBands = 3; imageSegmentation.applyUsingCIEXYPolarThetaThenHistEq(gsImg1, kBands);
```



```
int kBands = 8; imageSegmentation.applyUsingCIEXYPolarThetaThenHistEq(gsImg1, kBands);
```



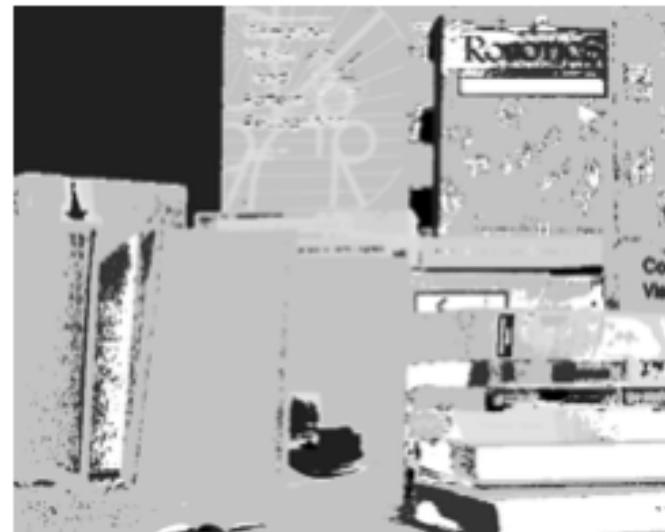
```
int kBands = 2; imageSegmentation.applyUsingCIEXYPolarThetaThenKMPPThenHistEq(gslImg1,  
kBands);
```



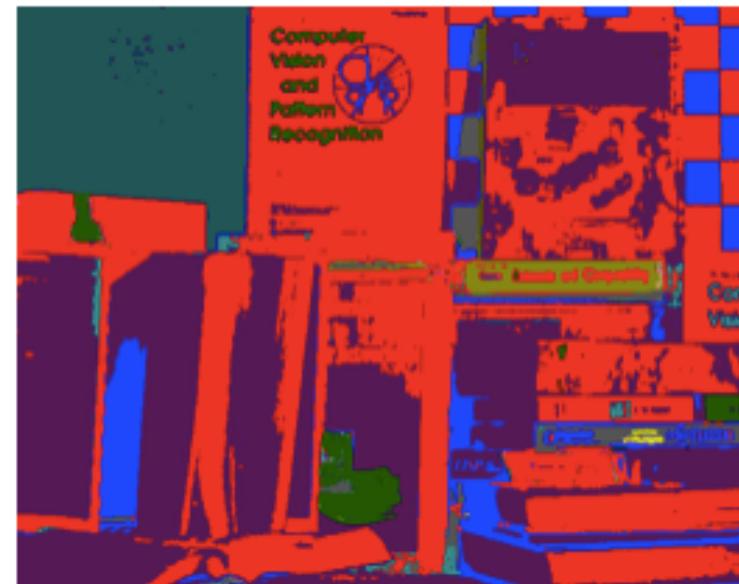
```
int kBands = 3; imageSegmentation.applyUsingCIEXYPolarThetaThenKMPPThenHistEq(gslImg1,  
kBands);
```



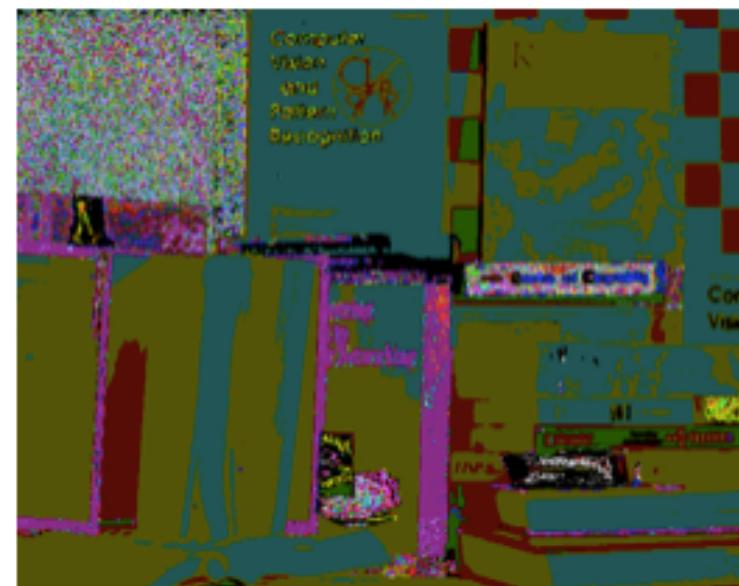
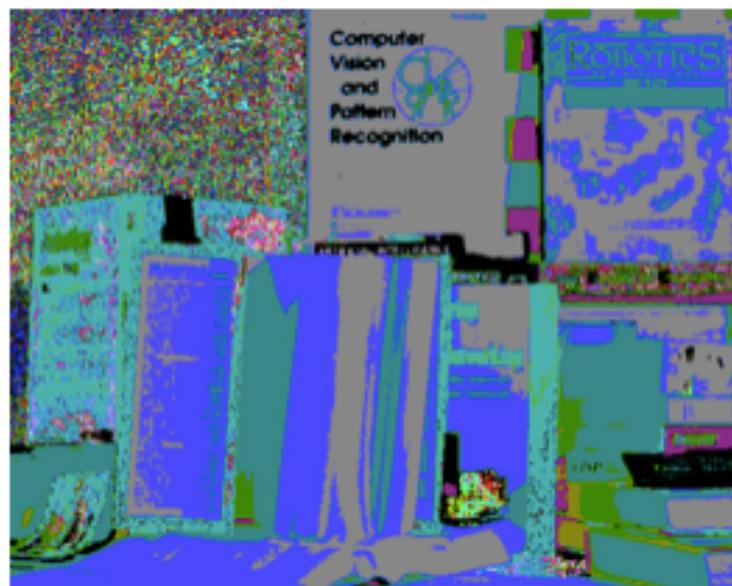
```
int kBands = 8; imageSegmentation.applyUsingCIEXYZPolarThetaThenKMPPThenHistEq(gsImg1,  
kBands);
```



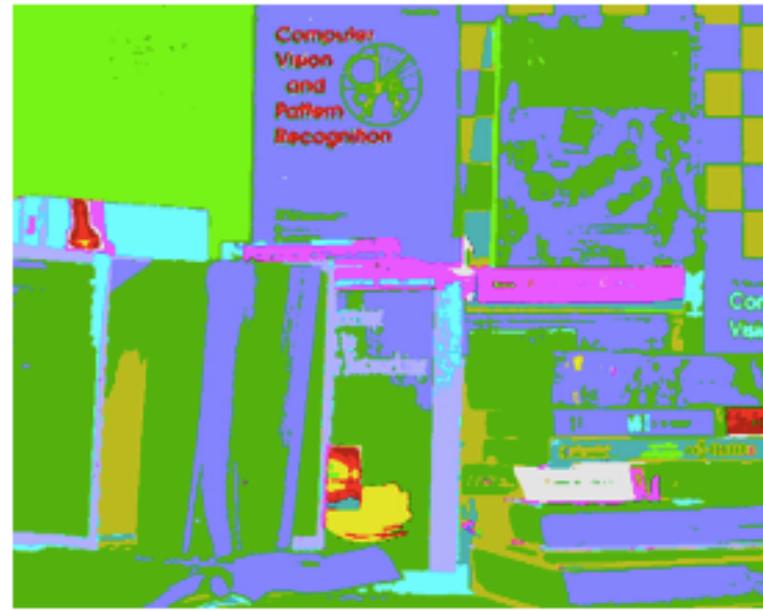
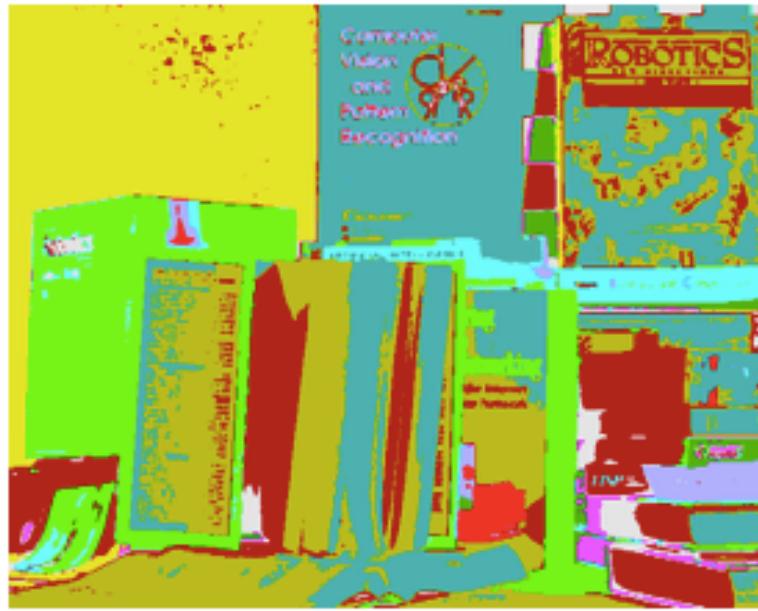
```
imageSegmentation.calculateUsingCIEXYAndClustering(gsImg1, true);
```



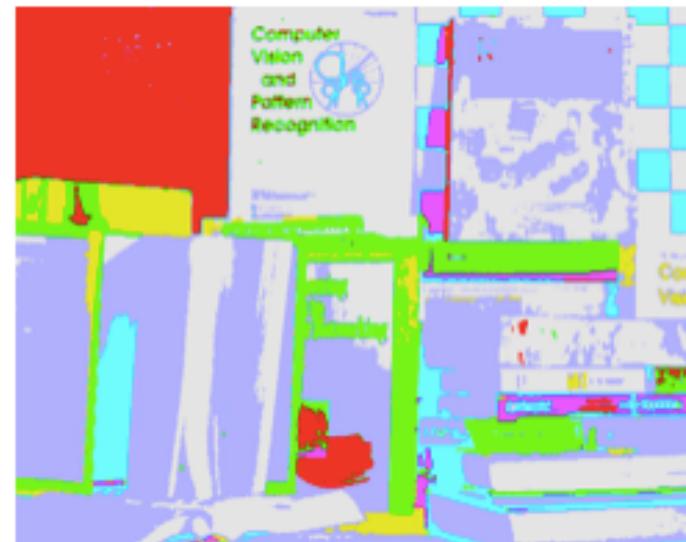
```
imageSegmentation.calculateUsingPolarCIEXYAndClustering(gsImg1, true);
```



```
imageSegmentation.calculateUsingPolarCIEXYAndFrequency(gsImg1, true);
```



```
imageSegmentation.calculateUsingPolarCIEXYAndFrequency(gsImg1, 0.2f, true);
```



```
int kBands = 2; imageSegmentation.applyUsingKMPP(gslImg1, kBands);  
zoom in
```

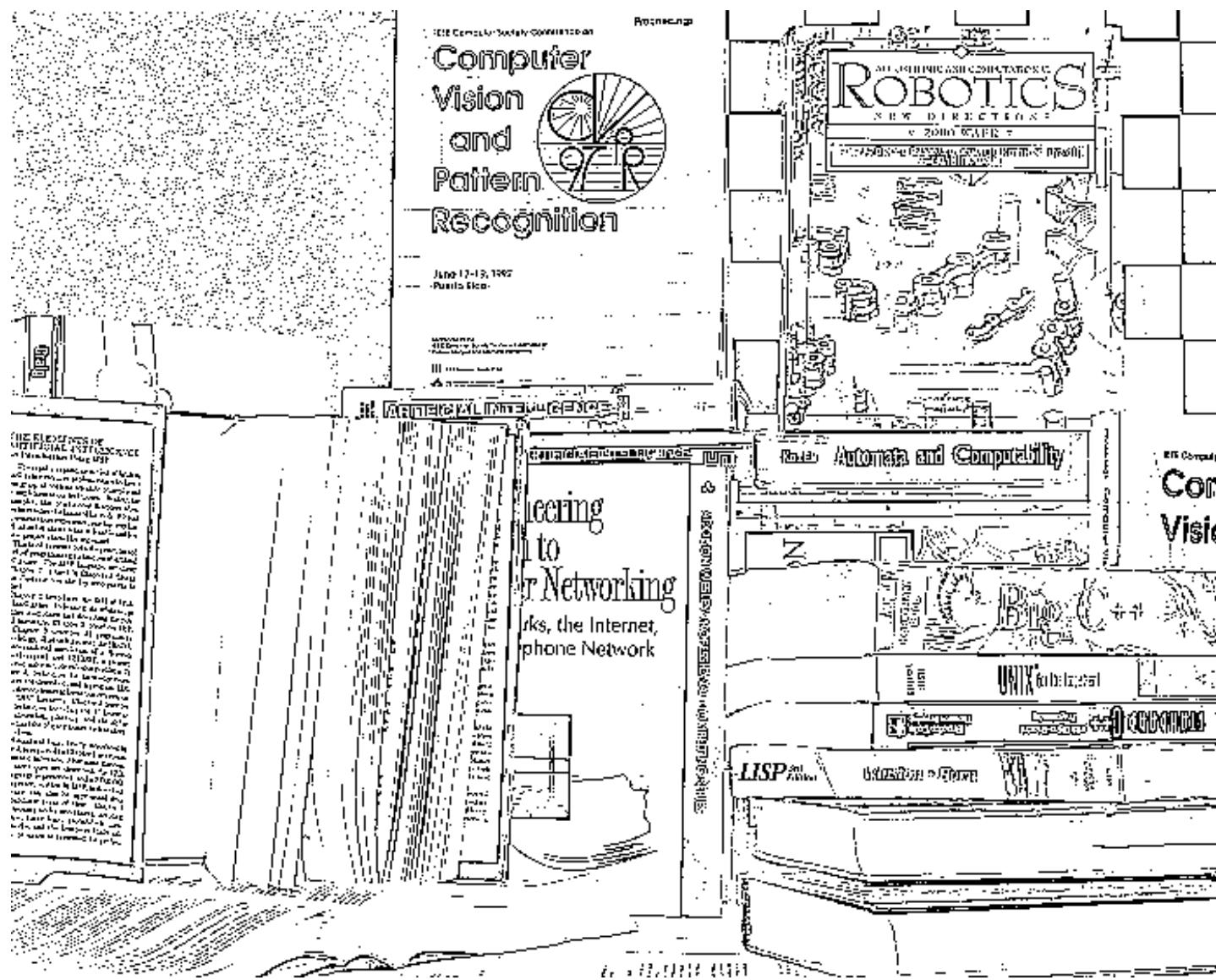
Computer
Vision
and
Pattern
Recognition



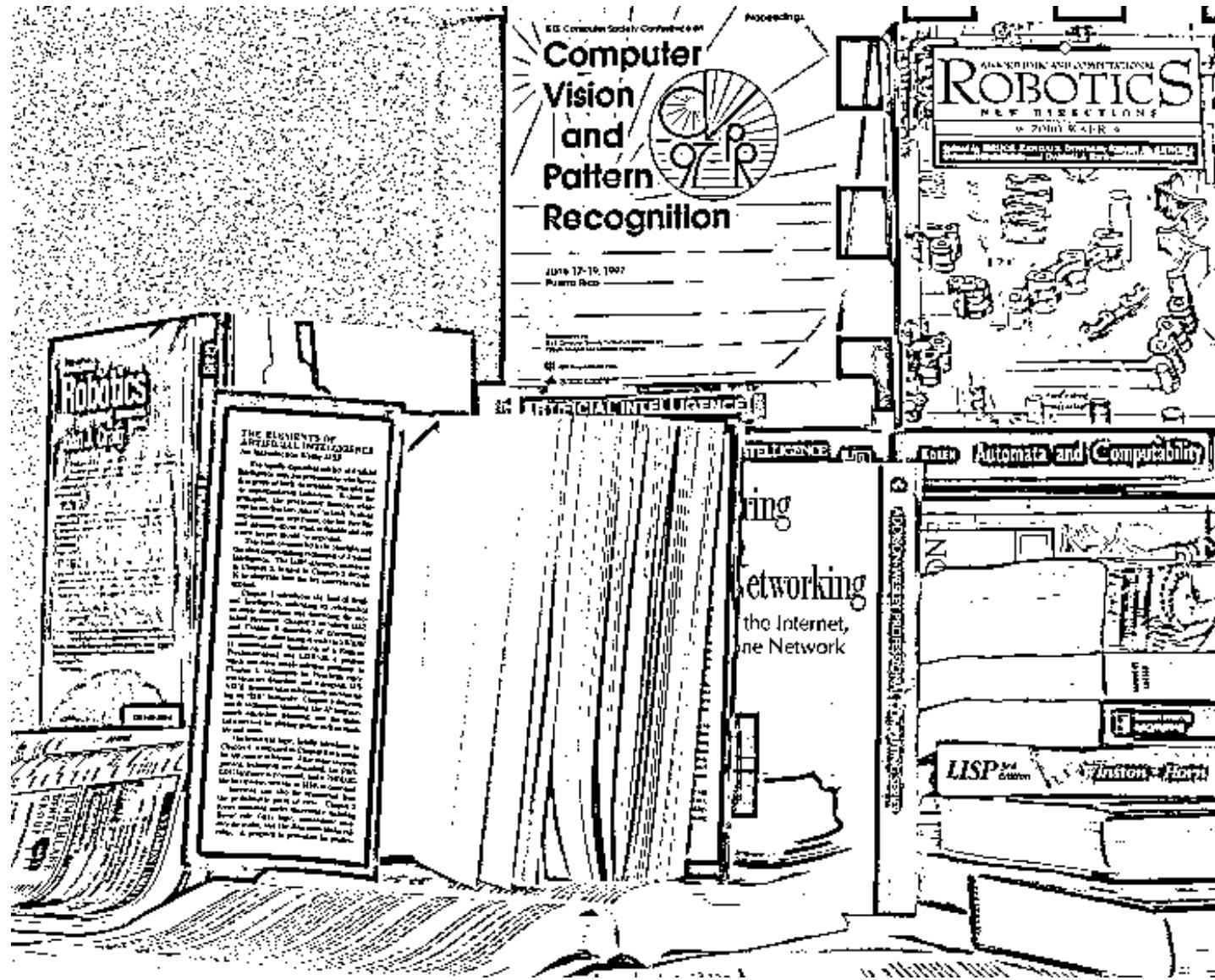
Computer
Vision
and
Pattern
Recognition



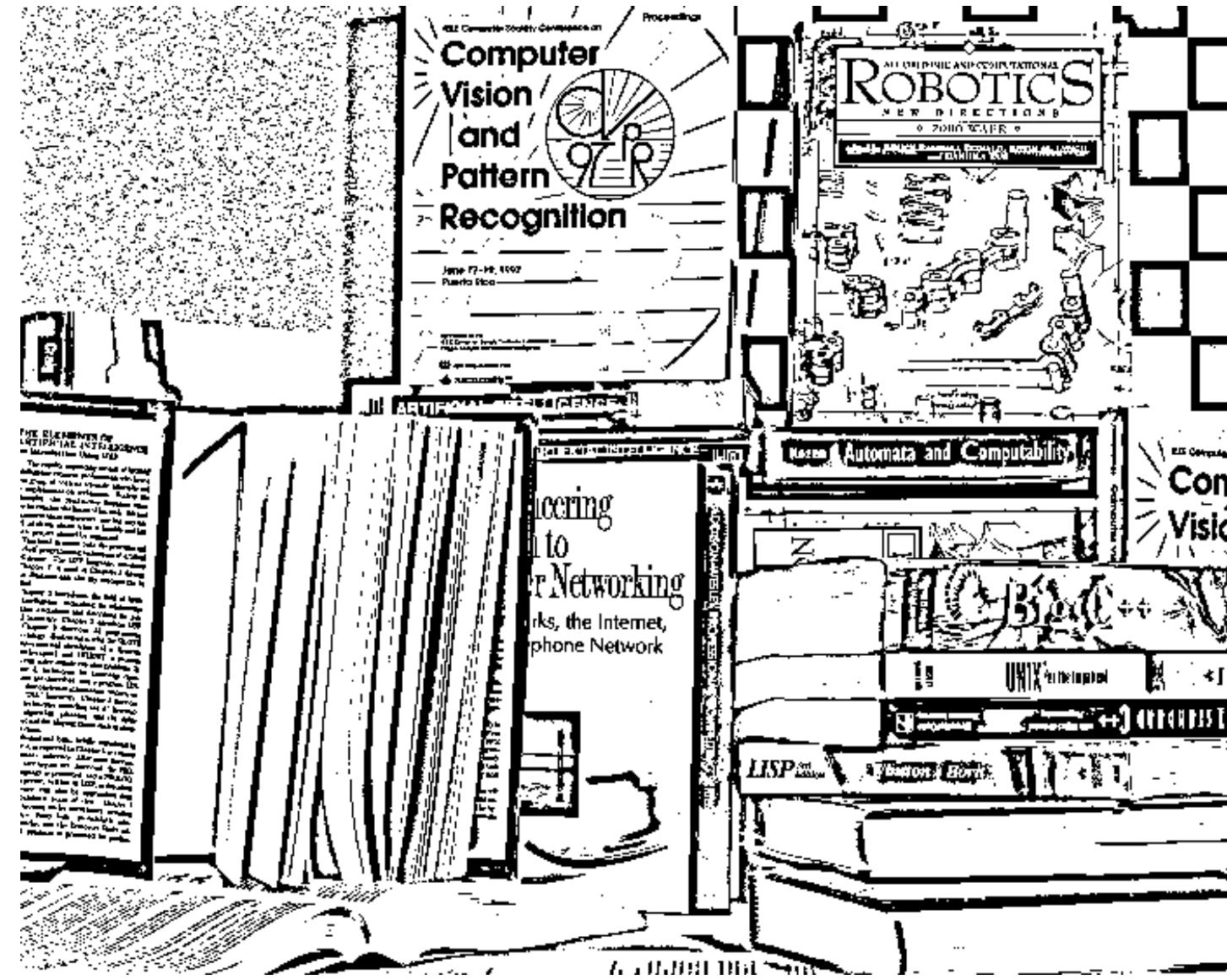
adaptive means, $h=1$



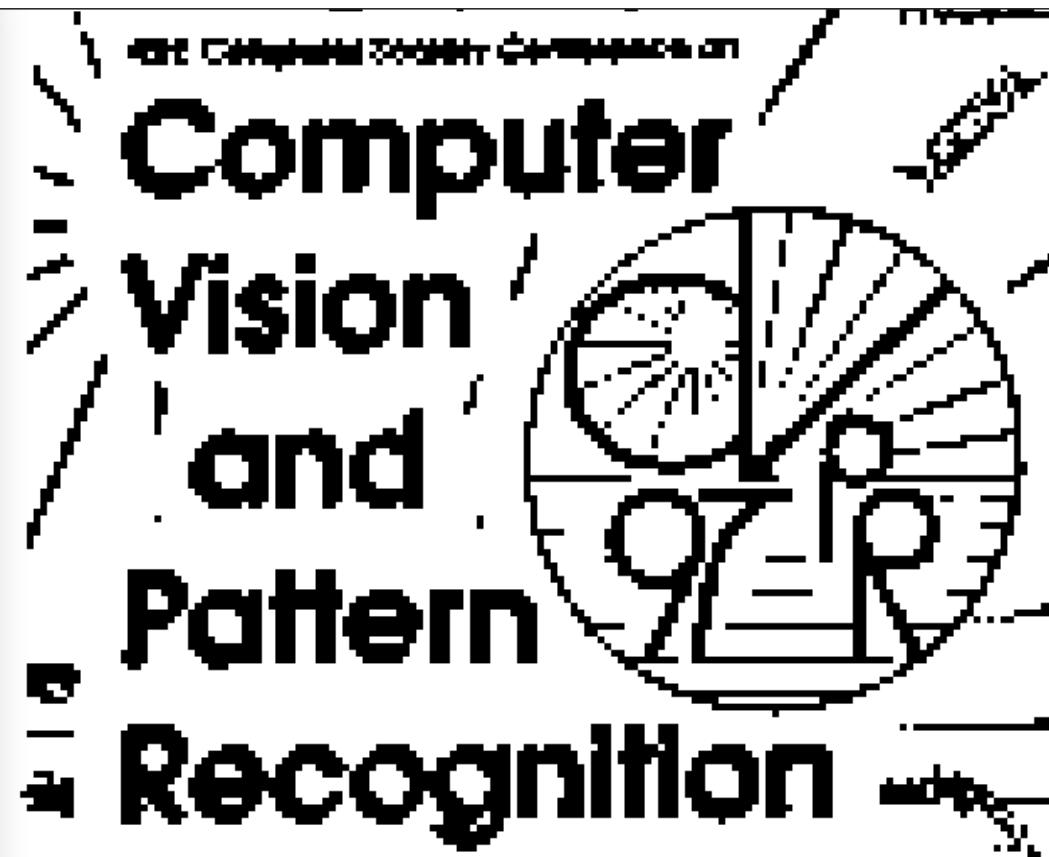
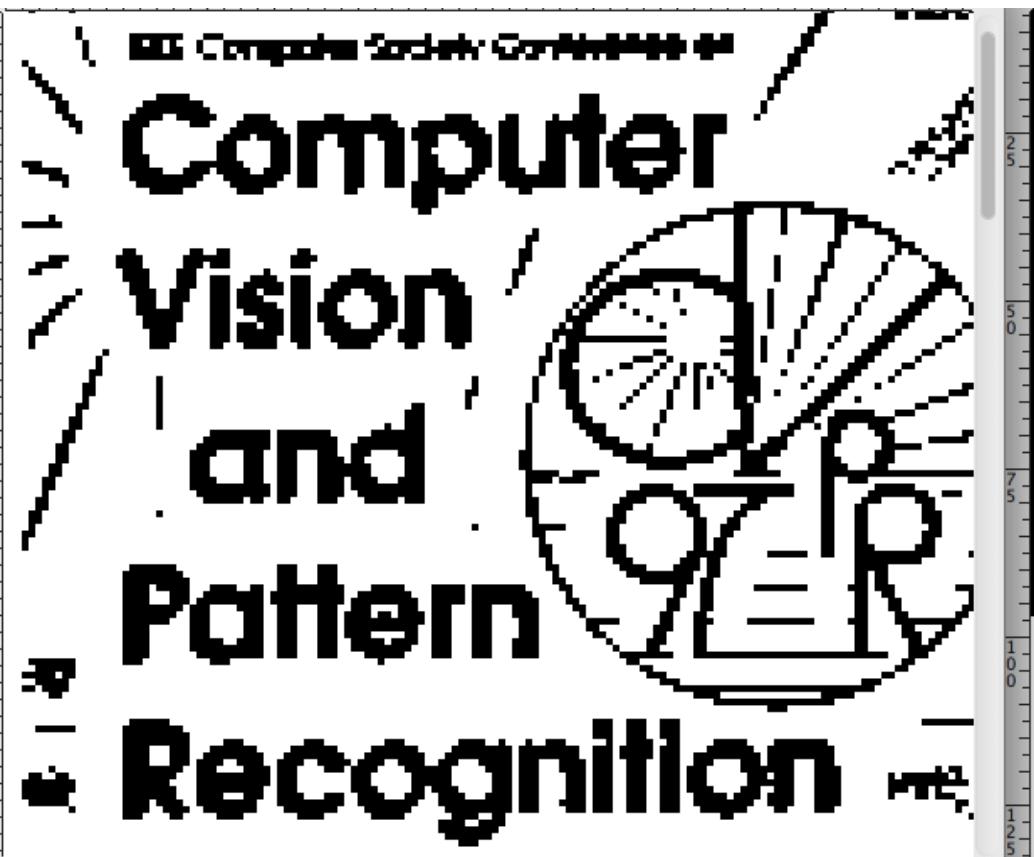
adaptive means, h=3



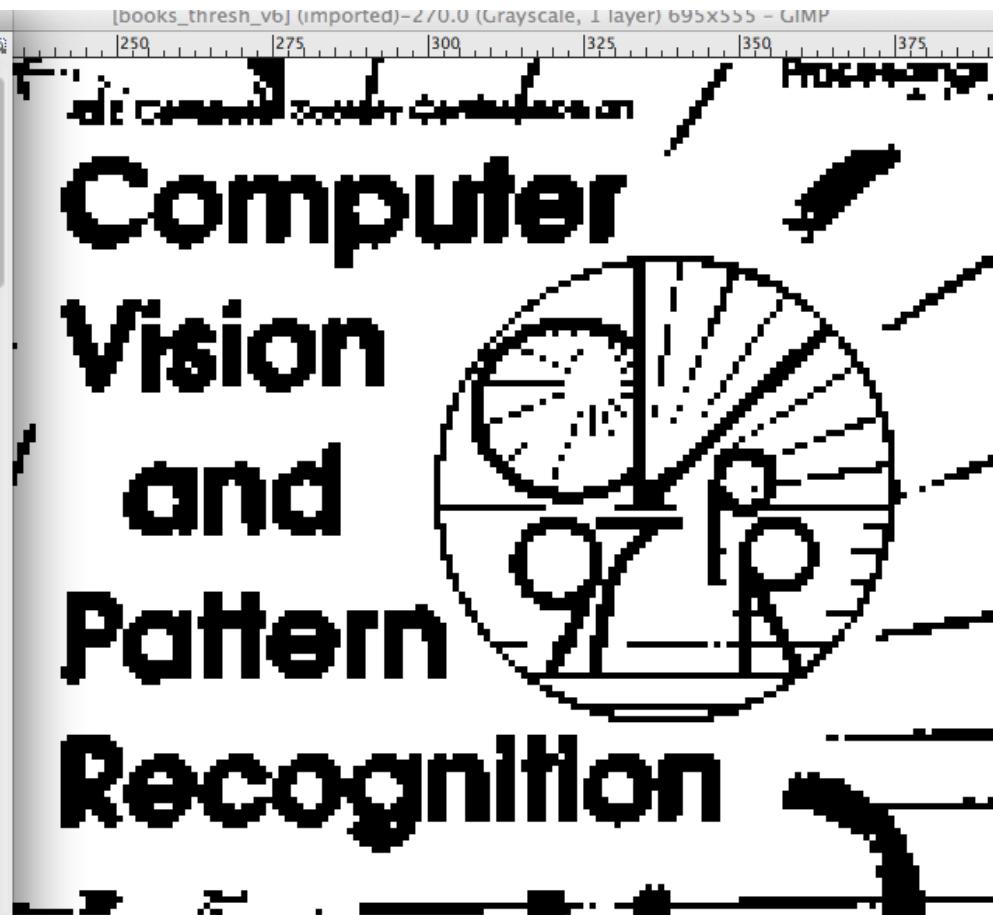
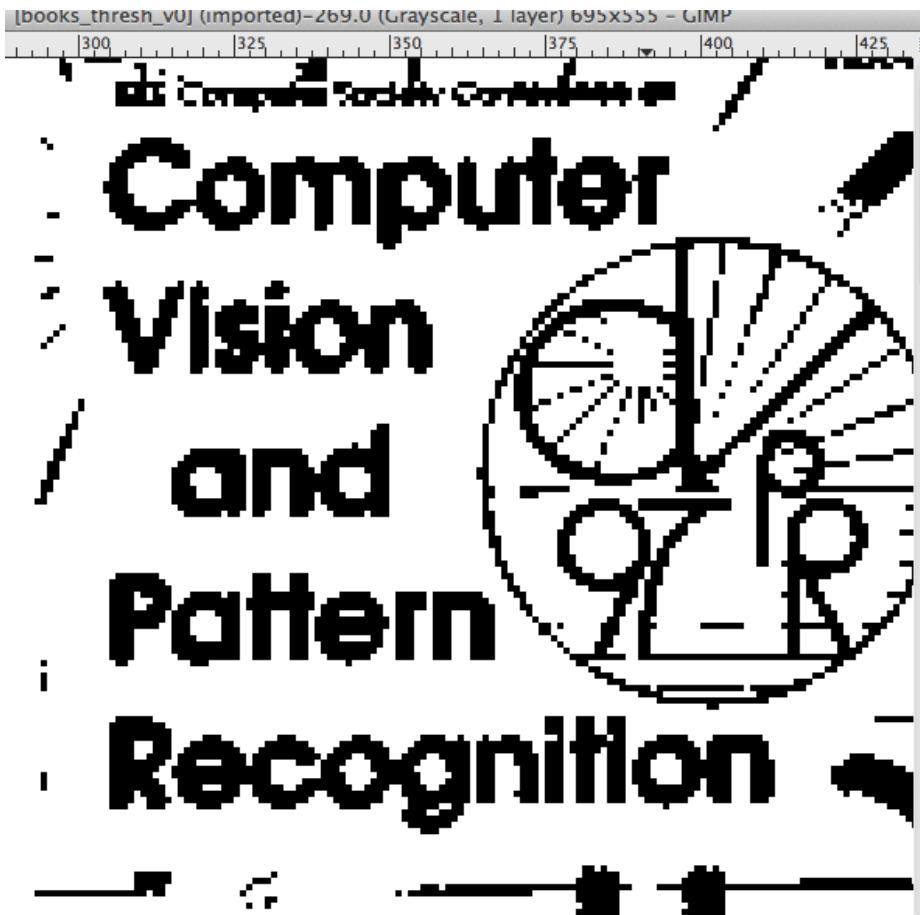
adaptive means, h=5



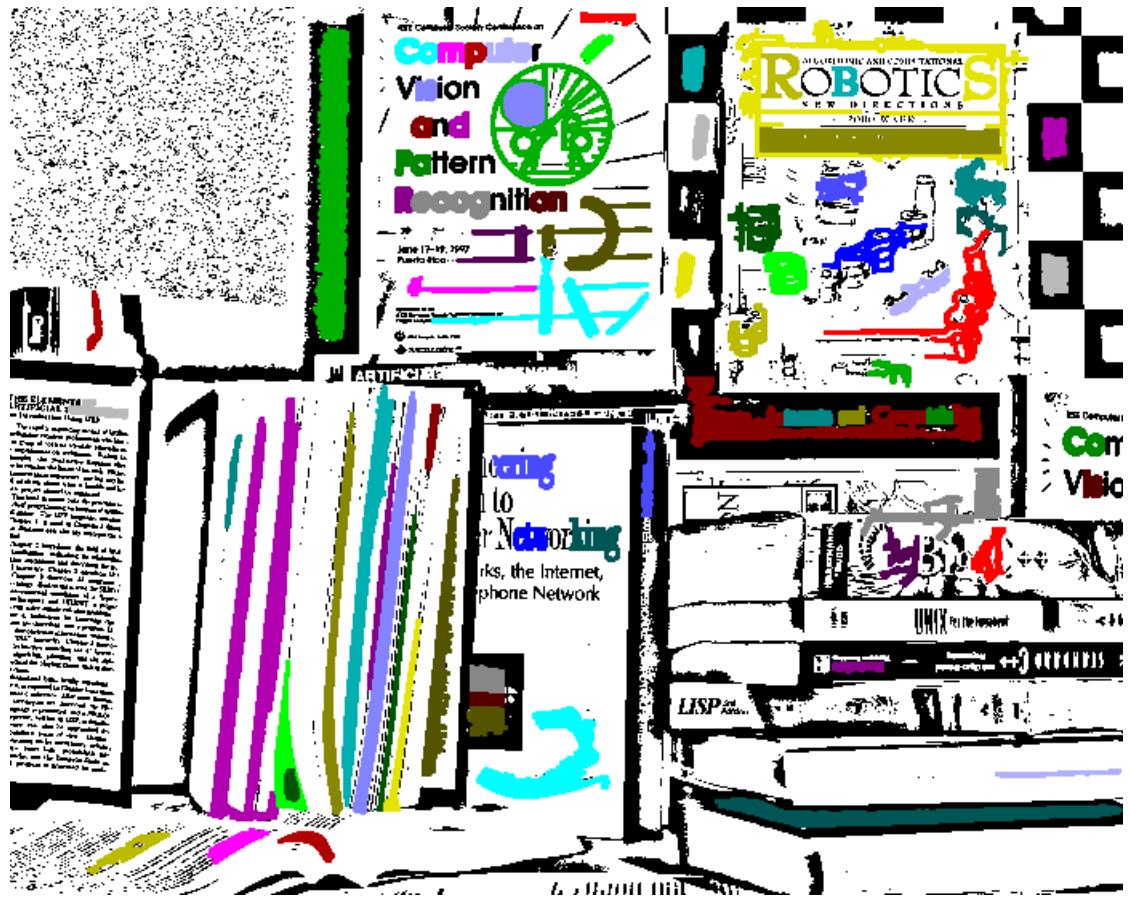
adaptive means, $h=7$



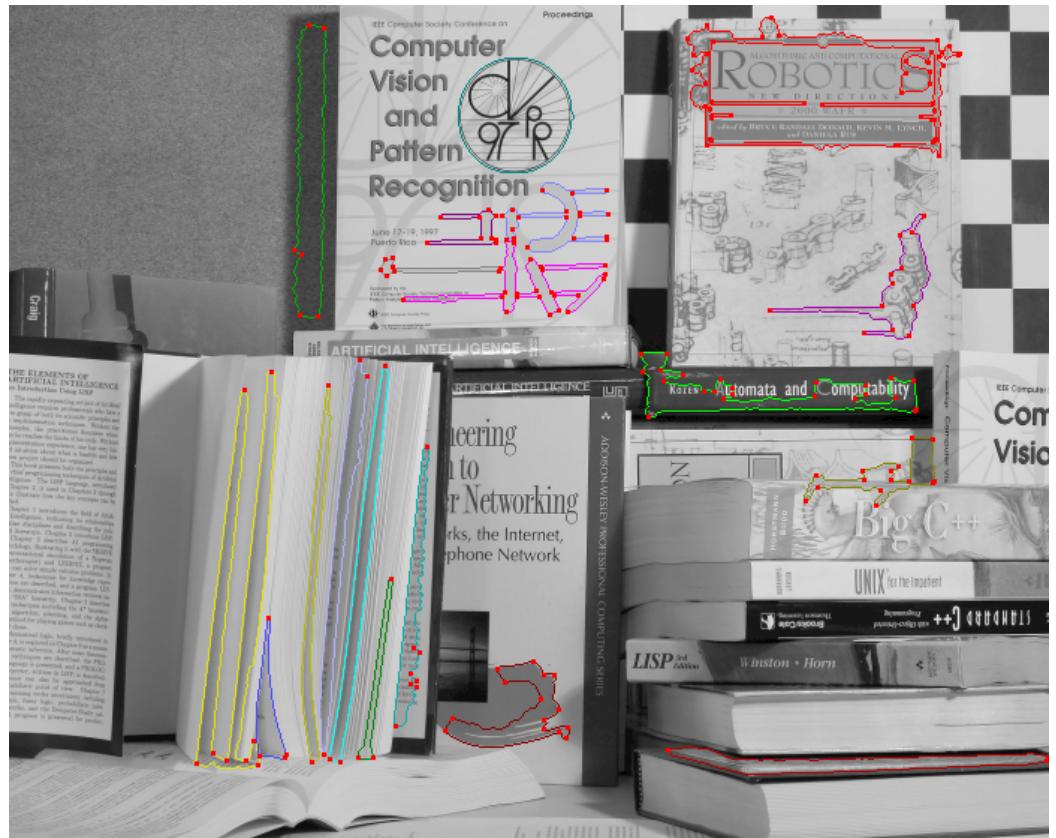
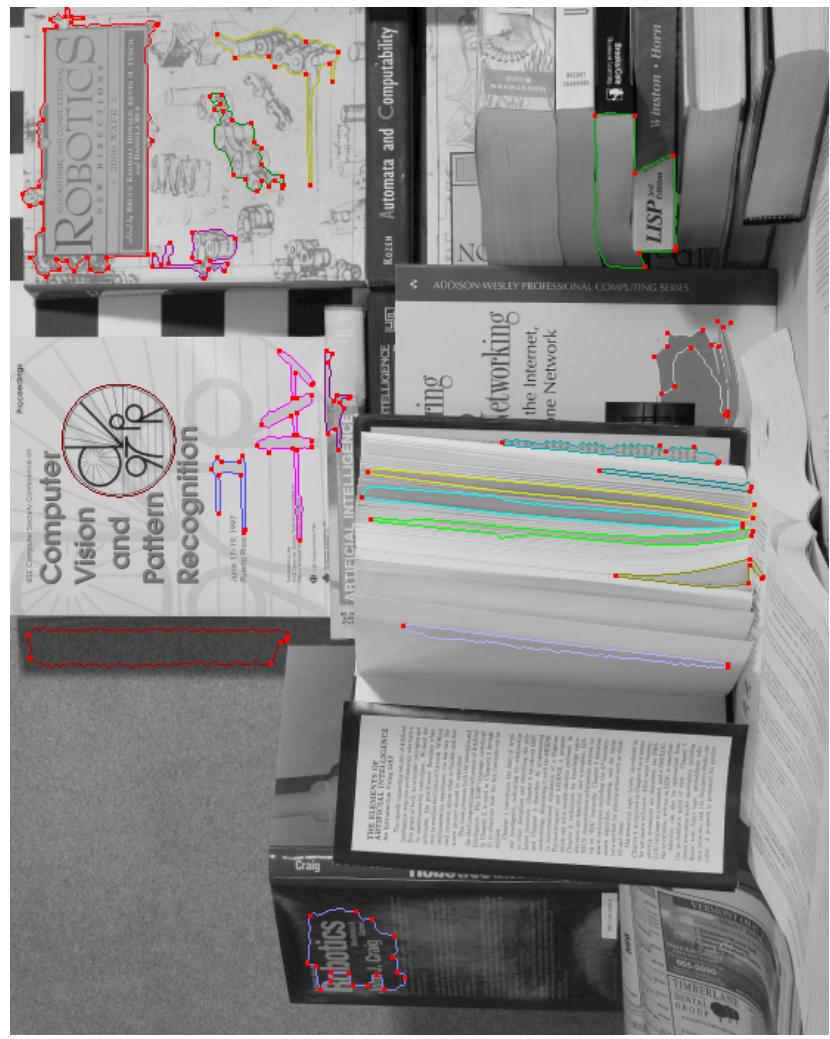
adaptive means, h=11 for adaptive to join close letters



adaptive means, h=11 blobs (extr using scale calc code)

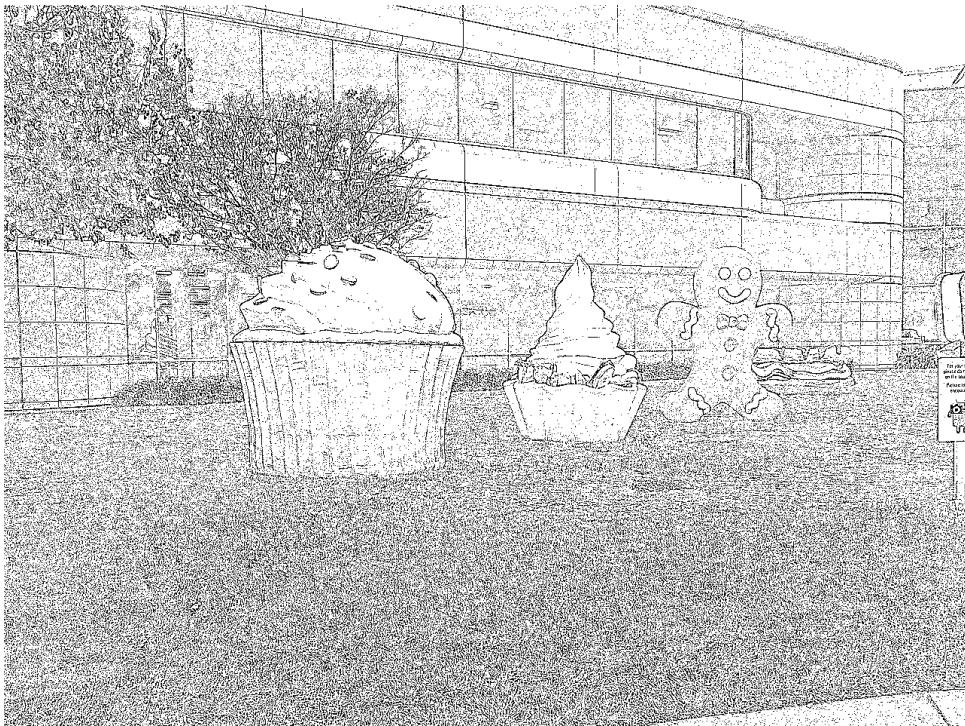


adaptive means, h=11 blob corners

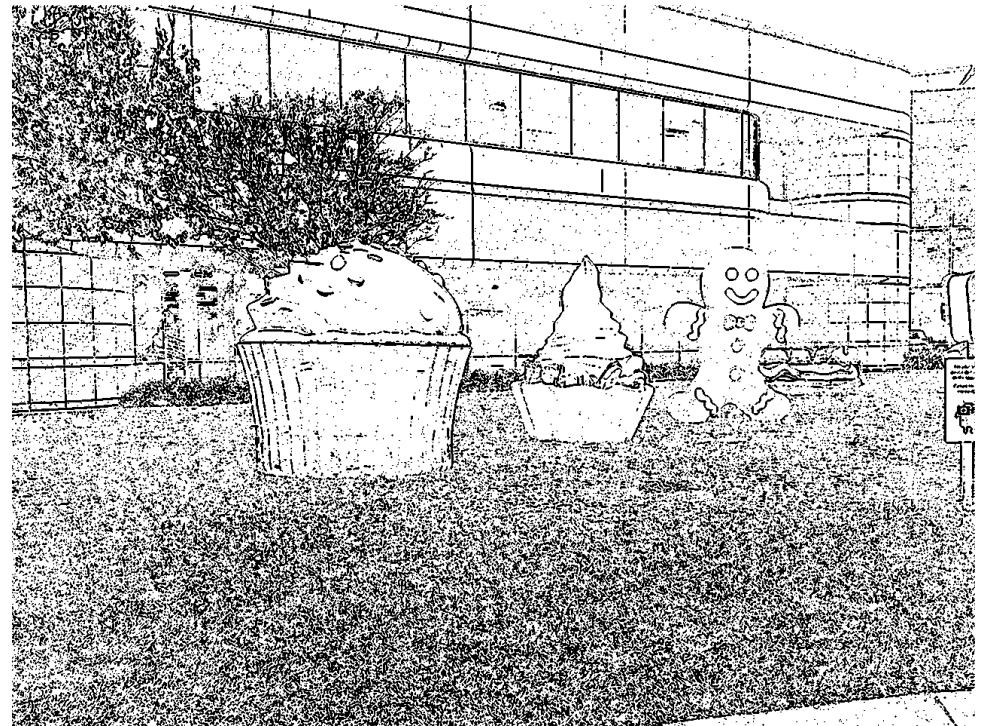


the letters are filtered out due to large nPerimeter compared to nInternal
adaptive means, h=3 was better for letters as blobs

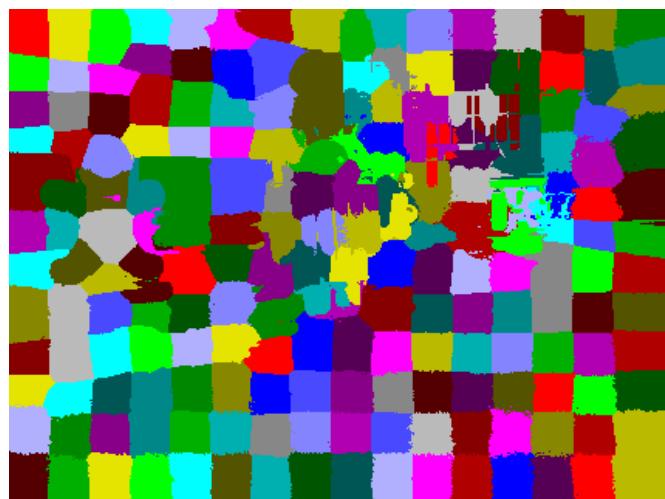
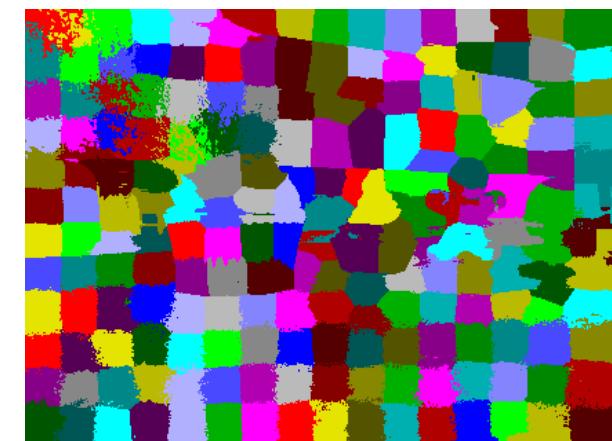
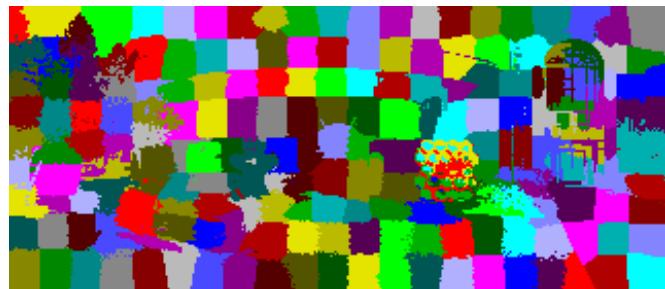
adaptive means, h=1



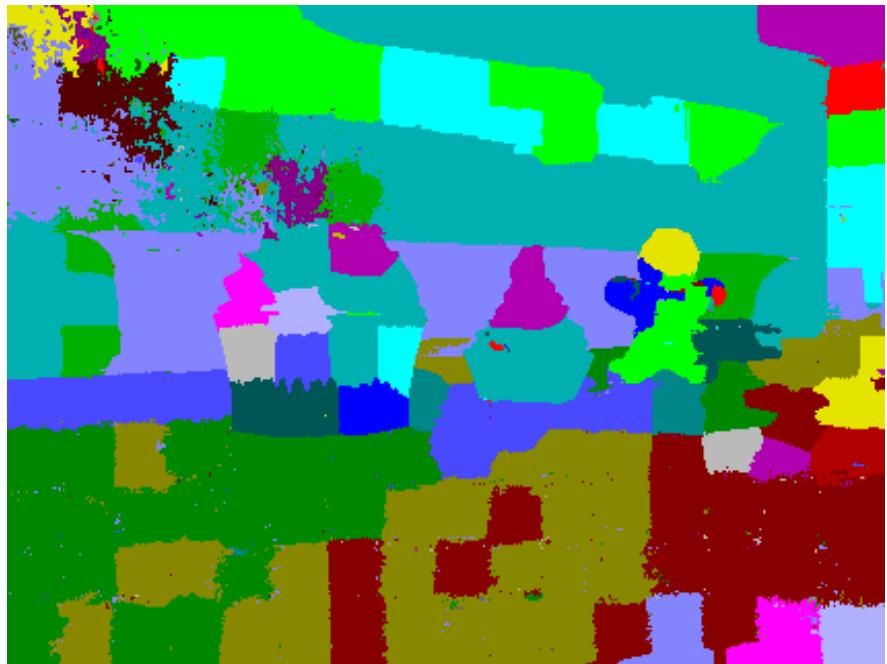
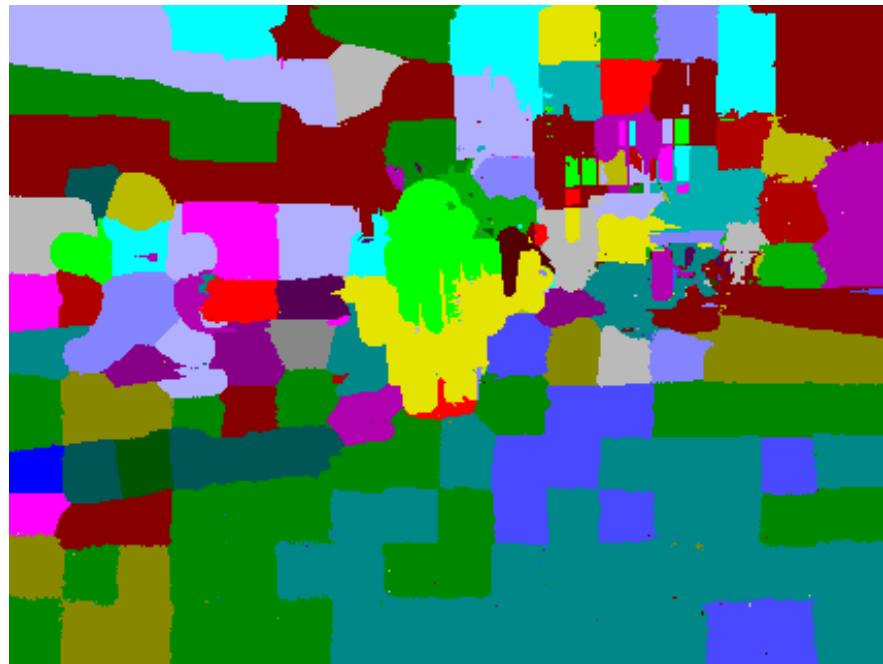
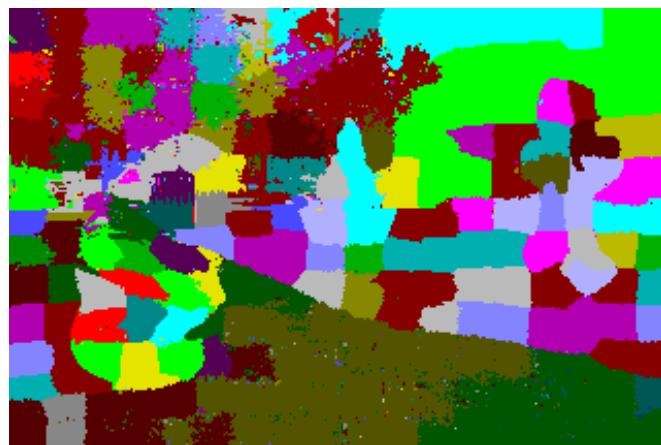
two median smooth with h=2



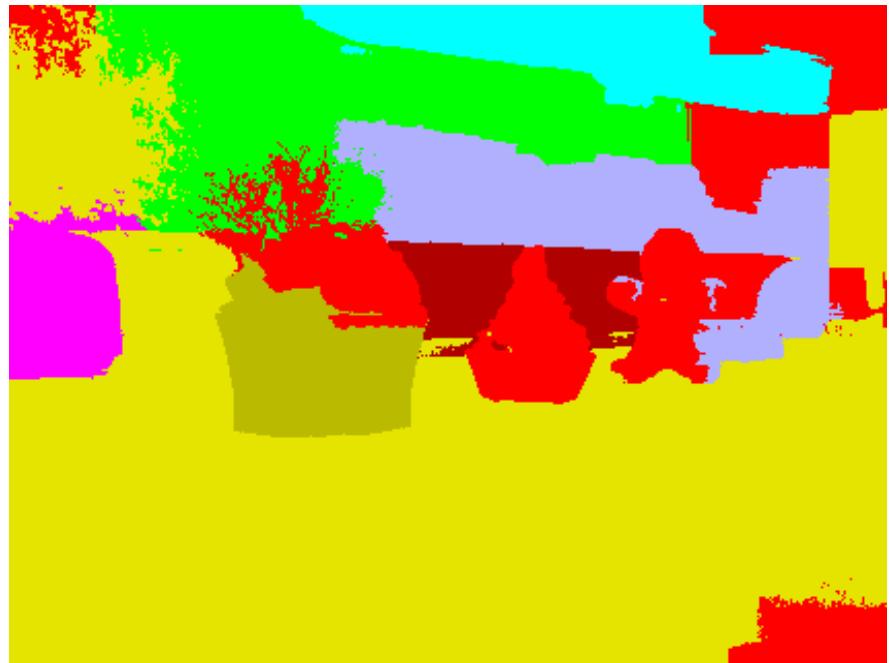
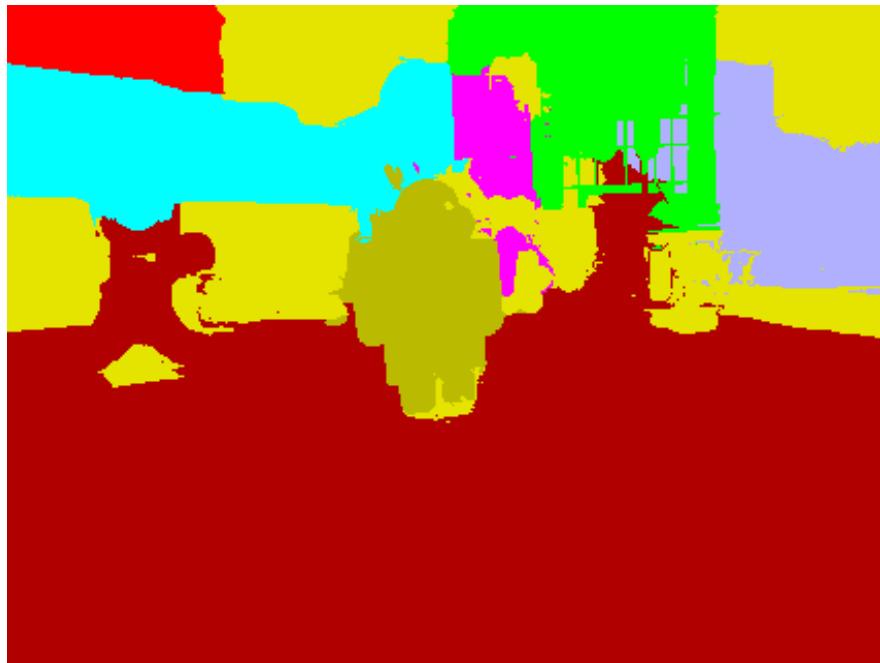
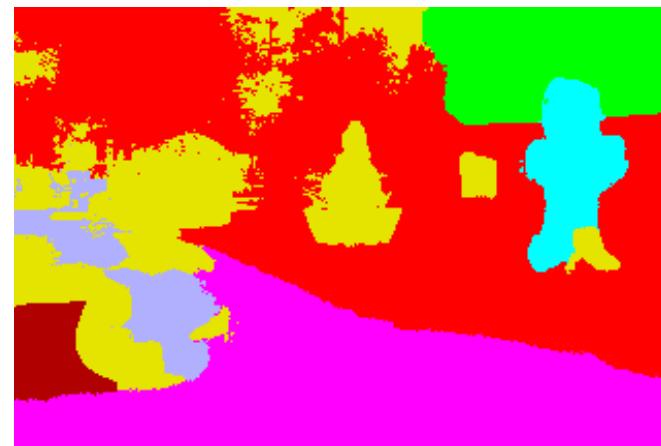
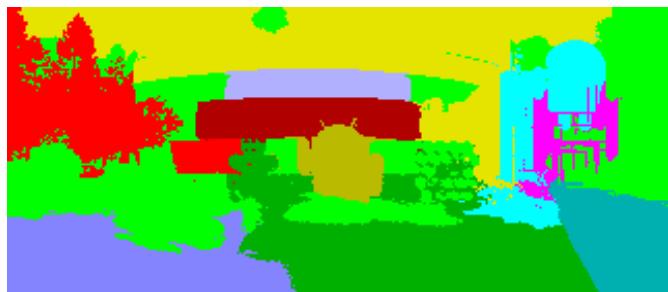
SLIC super pixels algorithm



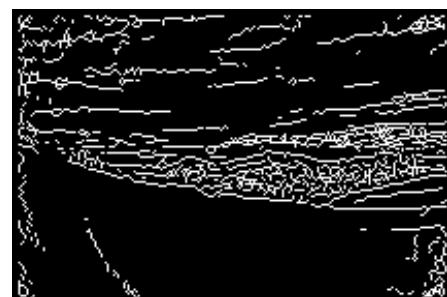
CIE XY Theta Clustering of the super pixels



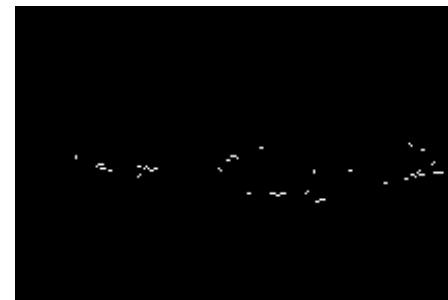
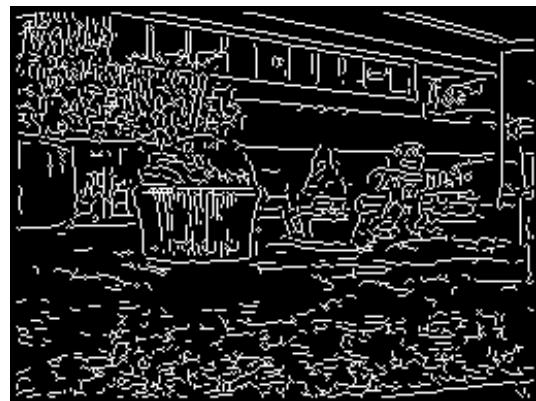
Normalized Cuts w/ HSV cs on the super pixels



canny greyscale



canny deltaE 2000



phase congruence

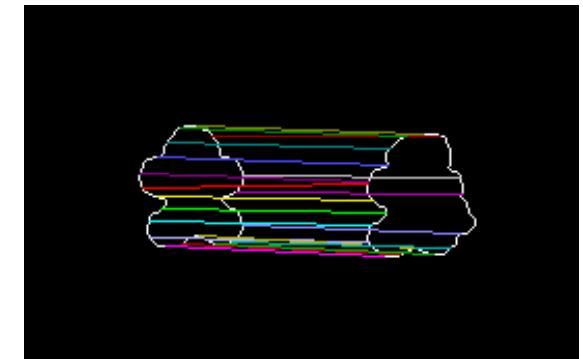
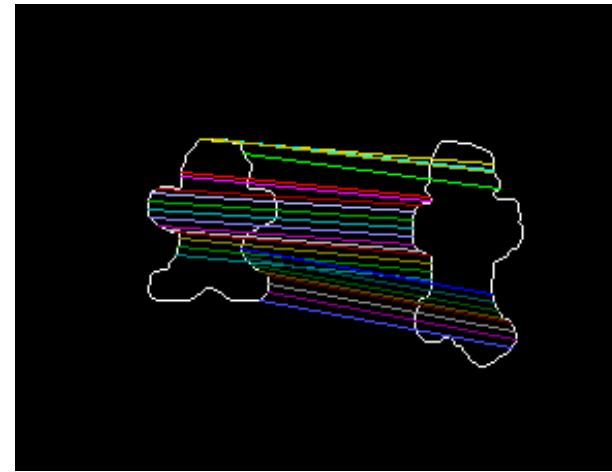
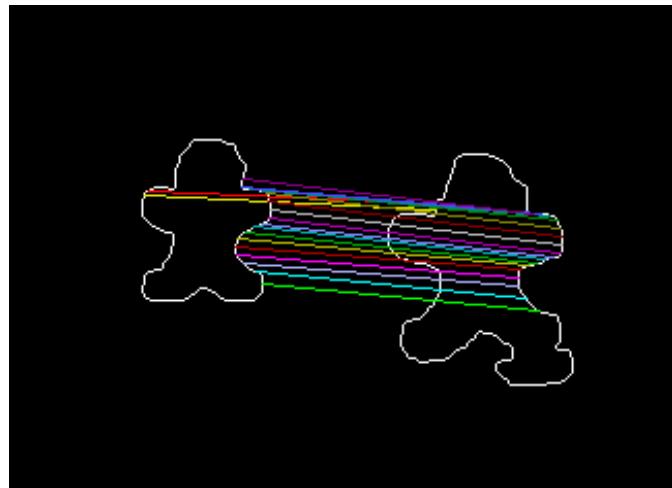
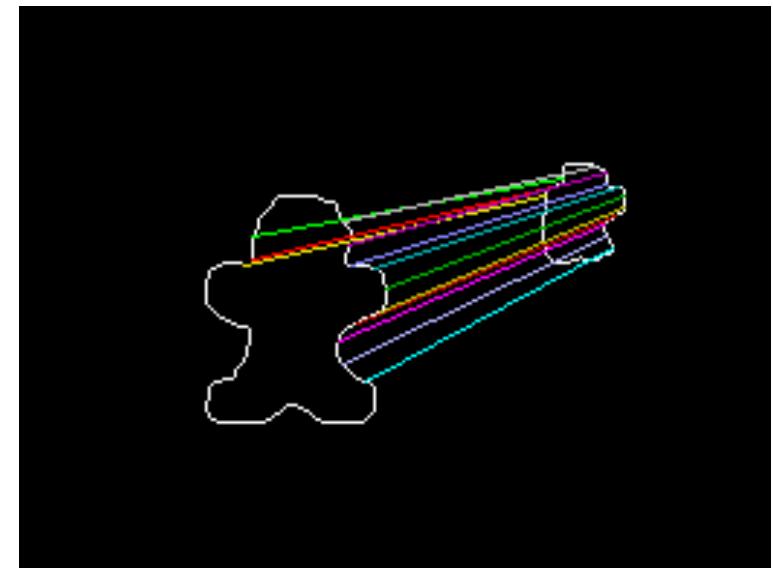
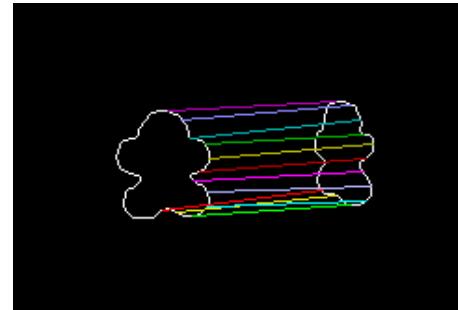
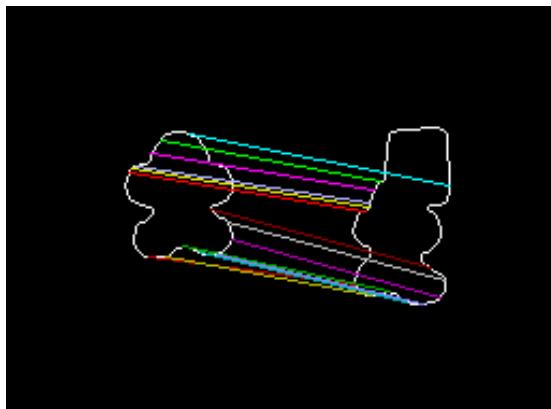


super pixels and moderate merging by HSV color



Partial Shape Matching of the gingerbread man

extract ordered borders of shapes, blur them by one or two sigma, then ordered bipartite matching algorithm using difference of chords as a descriptor.



Shape Finding in over-segmented images

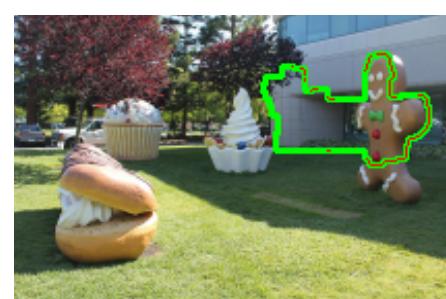
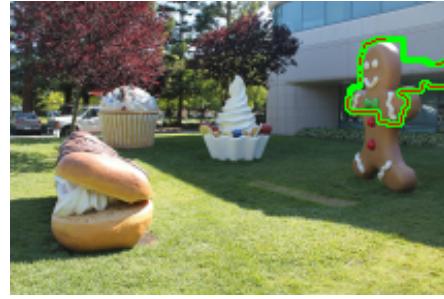
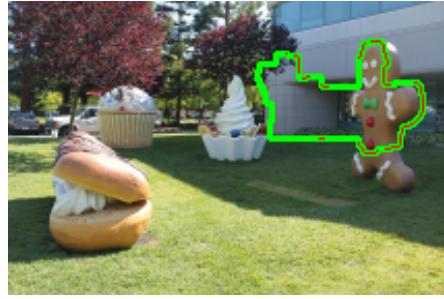
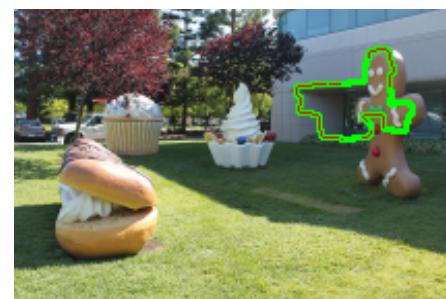
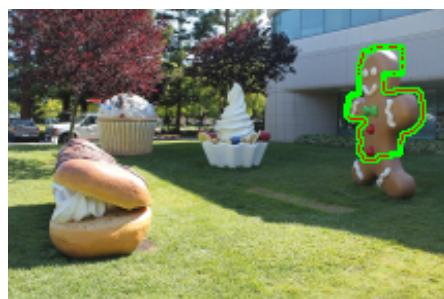
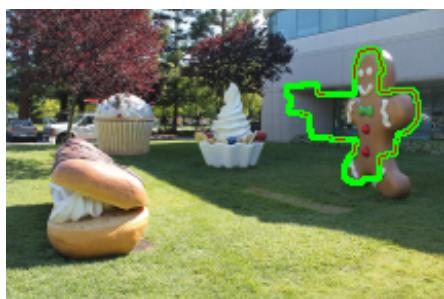
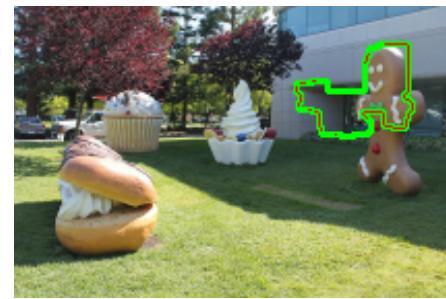
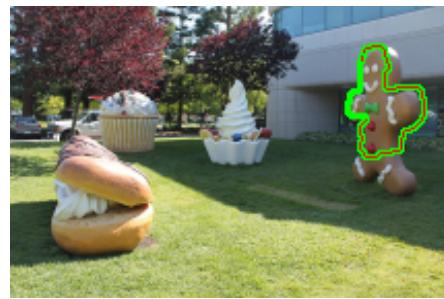
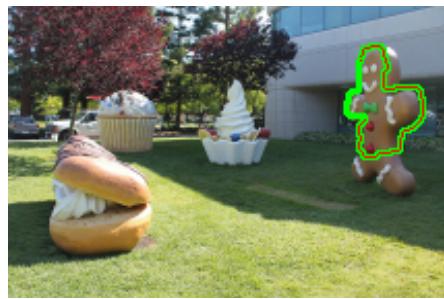
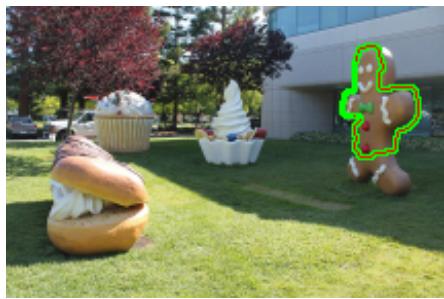
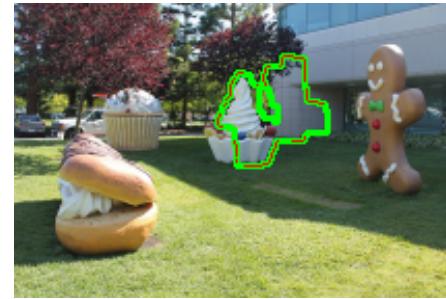
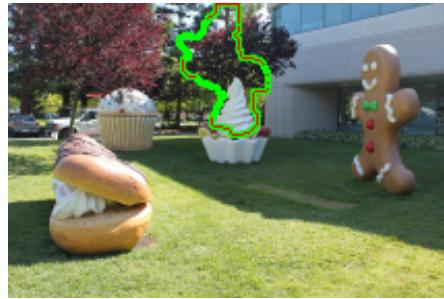
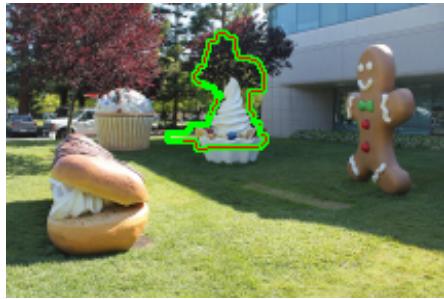
using the partial shape matcher and a search pattern (which will be improved), to make progress towards finding the gingerbread man.

Finding the gingerbread man with just descriptors within the test images which have different lighting, poses and background did not work well (*demonstrated in other notes) - could see that matching groups of points was necessary. Also found that if descriptors are used, they must exclude the background.

Shown below and on next page are a test image which has been processed to make super-pixels, then a merge of super-pixels by HSV color, then a CIE DeltaE 2000 color filter (difference from template gingerbread man) applied to remove some of the segmented cells.

The search results are preliminary and still a work in progress, but can see that if more information about color or texture is used, the true match will be found as top match. NOTE that a histogram of which segmented cells are present in the top k answers might be a way to find the true match without additional descriptors. see the *matched*.png images in the output (next).

top matches to template shape within a test image



best match

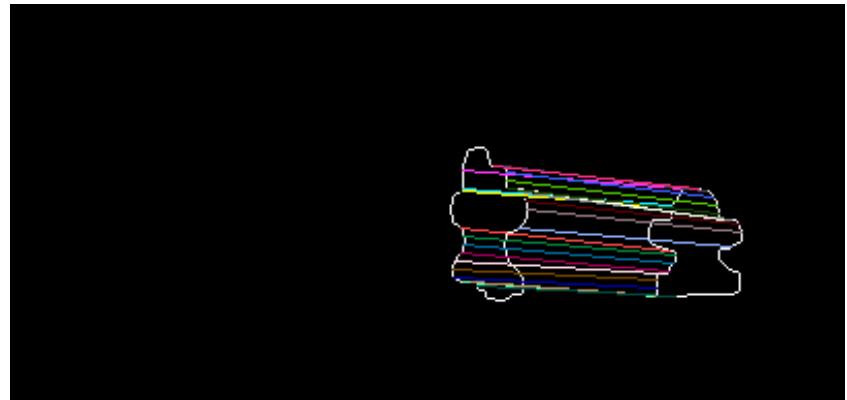
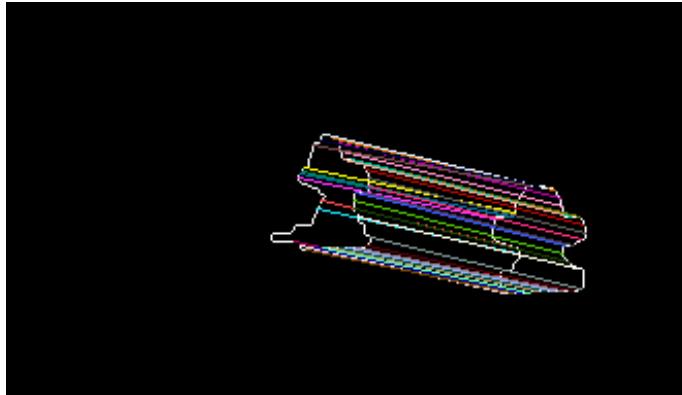
and true match



the min cost match to the template shape



the true match has higher cost. (due to scale, and pose)



Shape Finding in over-segmented images (cont)

Can see from rough results that searching over different template scales is necessary and additional information about color or texture might be necessary.

trying by just shape first to explore the ability to match just silhouettes. can see that the best match would not be found as a silhouette though, but should help in exploring reasons for false matches...