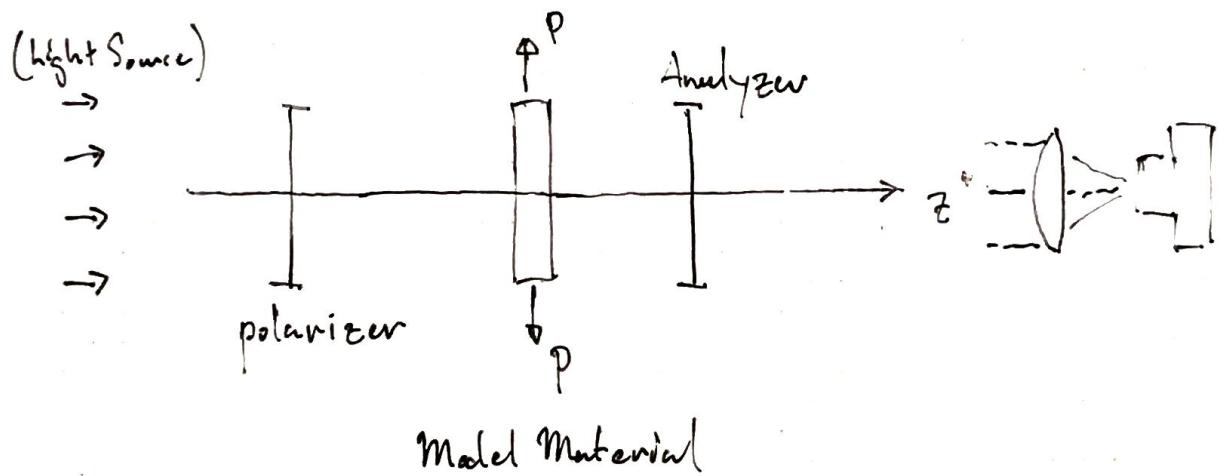


## Experimental Mechanics Final Presentation

- Slide Outline First
- Break outline into dendritic growth has no good analogue in the physical process of Laser Metal Project. Modulus of the steel very hard.
  - + Need Supporting Equations from some site
  - + I couple of slides?
  - + Compare scale of dendritic growth to minimum length scale of the AFM
- Set Up with: FEM Research processes on pg ②
  - + Processes of Dendritic Growth linked to solidification of both unary and multicomponent liquid, examples like ice, ...
    - i) Pure liquid
    - ii) Solid Nucleus of Spherical Shape grows into the liquid
      - Begin in the free vacuum or (free growth)
      - iii) Liquid Solid Interface grows where regions before the boundary becomes super-cooled
        - There is a great visualization video in 3D → gif
        - Note how the boundary is not a clean line but wavy
        - Relate to "Φ" or state parameter and phase field approach
        - Change of the State as a product of the environment
      - iv) Its distinctive shape comes from how the crystal anisotropy allows for solidification in energy favorable direction
        - State → Propagates in shape preserving manner → "dot of flux?"
        - Energy favorable directions
        - As the dendrite growth goes on, heat energy goes into the dendrite

# Experimental Mechanics: 9 October 2018

- Lecture #11: Photoelasticity; Fringes (Isoclinic vs. Isochromatic)
- Photoelastic Materials
- Analysis of Fringe Patterns
- Linear Polarimeter



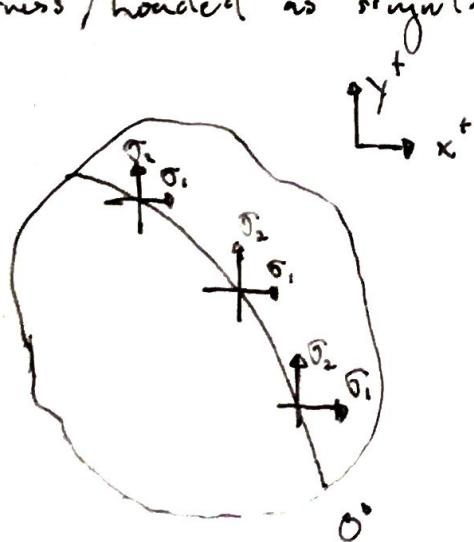
$$I = K \underbrace{\sin^2\left(\frac{\Delta}{2}\right)}_{\text{on}} \underbrace{\sin^2(2\alpha)}_{\text{on}} = 0$$

- if  $\sin^2 2\alpha$ : Isoclinic; or principal stress in line w/pol.
- "  $\sin^2 \frac{\Delta}{2}$ : Isochromatic;  $\frac{\Delta}{2}$

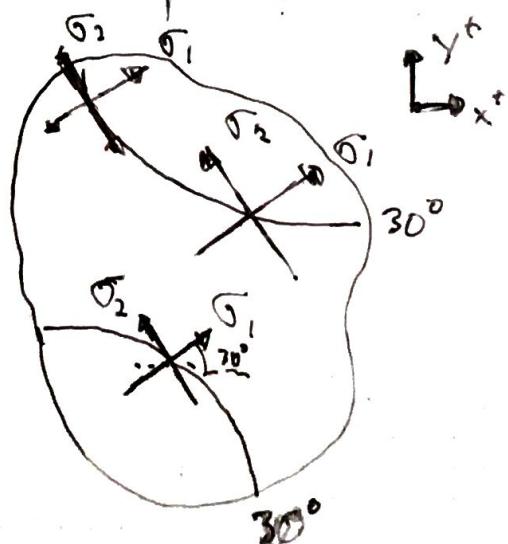
- Isoclinic:  $I = 0$  because  $\sin^2 2\alpha = 0$

$$2\alpha = n\pi, \quad n = 1, 2, 3, \dots$$

- Principal stresses in axis of polarizer
- Isoclinic parameter: rotate polarizer to varied orientation to create a full field map of stress
- Overlay of outline of isoclinic fringe counts 2D stress direction
- Isoclinics must pass through isotropic or singular point;  $\sigma_1 = \sigma_2$
- Isoclinic of at least one parameter will have coincided with axis of symmetry.
- Stress/handed as singular: . isoclinic of all parameters



a) Polarizer set to  $0^\circ$



b) Polarizer set to  $30^\circ$

- Interference:  $I = 0$  because  $\sin^2 \frac{\Delta}{2} = 0$

$$\Delta_2 = n\pi; n = 1, 2, 3 \dots$$

$$n = \frac{\Delta}{2\pi} = \frac{hc}{\lambda} (\sigma_1 - \sigma_2)$$

- $n$ : fringe order
- $\Delta$ : relative retardation ( $c[\sigma_1 - \sigma_2]$ )  $\frac{\Delta}{\lambda}$  is an integer multiple of  $\lambda$  of light

- Give lines of principal stress difference  $\sigma_1 - \sigma_2$ , we know  $\tilde{\sigma}_{avg} = \frac{\sigma_1 + \sigma_2}{2}$  by Mohr's Circle

Remember Wave Plates before & after model material @  $\pm 45^\circ$   
isoclinics will be removed

- Ultimately, want to know  $n^{th}$  order of fringe order
  - Might be done by translating boundary lines
  - Through movement of fine water boundary.
  - With white light,  $0^{th}$  order is black and successive ones are
  - Isotropic ( $\sigma_1 = \sigma_2$ ) will always be black

- Sample Pieces has been "model material", as few materials are isotropic and stress induced birefringence.
  - Still, can be loaded to see a full field stress distribution by applying stressca geometries.
  - Generally a polycarbonate:
    - + Homolite 100
    - + Polycarbonate
  - Epoxy Resin
  - Urethane Rubber
- } for Creep
- } Older Materials

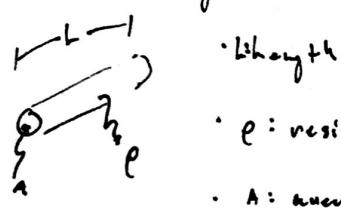
Notes on

• Electrical Resistance Strain Gauge : (ER)

⇒  $R$  ( $\epsilon$ , material) : resistance is a function of strain and material

⇒ Wheatstone bridges used for  $4R \rightarrow \Delta V$

• Strain Sensitivity



- Length
- $\rho$ : resistivity [ $\Omega \cdot m$ ]
- $A$ : area

⇒ with increased  $\epsilon$ , increased  $R$

⇒  $R = \rho \frac{L}{A}$ , but is it from " $\rho$ "  
or from " $L/A$ "

$$R = \rho \frac{L}{A} \Rightarrow dR = \frac{1}{A} \left( L d\rho + \rho dL - L \frac{dA}{A} \right)$$

$$\frac{dR}{R} = \frac{d\rho}{\rho} + \frac{dL}{L} - \frac{dA}{A}$$

$$A = \frac{1}{4} \pi d^2$$

$\underbrace{\epsilon}_{\text{Poisson's Ratio or change in}}$

$$\text{transverse cross section: } \nu = -\frac{\epsilon_y}{\epsilon_x}$$

$$dL = d_0 \left( 1 - \nu \frac{dh}{h} \right)$$

$$\frac{dA}{A} = -2\nu \frac{dh}{h} + \nu^2 \left( \frac{dh}{h} \right)^2 \approx -2\nu \frac{dh}{h}$$

$$\frac{dR}{R} = \frac{d\rho}{\rho} + \epsilon + 2\nu \epsilon$$

$$S_e = \frac{\frac{dR}{R}}{\epsilon} = \underbrace{1 + 2\nu}_{\text{change in dimensions}} + \underbrace{\frac{d\rho/\rho}{\epsilon}}_{\text{change in specific resistance}} : \text{Strain Sensitivity}$$

$\left\{ \begin{array}{l} \text{dependent of the} \\ \text{free electrons of material} \end{array} \right\}$

$$\epsilon [1.4, 1.7] \quad \epsilon' [1, 3]$$

Notes on

- Midterm Presentation and Report
  - ⇒ Use Dr. KZ's research w/ as more familiar
  - ⇒ 5 pages use TeX/LaTeX format
- Electrical Resistance Strain Gage Analysis

$\left\{ \begin{array}{l} \text{Guest Speaker} \\ 18 \text{ Oct} \end{array} \right\}$

$$\Rightarrow \frac{\Delta R}{R} = S_g \epsilon_a \quad \text{Unknown strain, } \epsilon_a \text{ to be found}$$

↳ Gauge property (see 17 Sept)

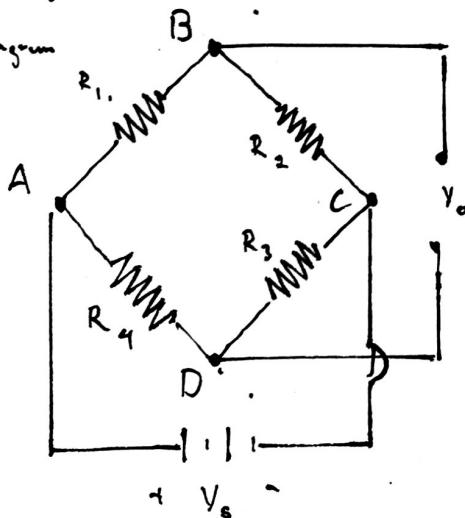
⇒ Convert  $\Delta R/R$  into  $\Delta V$ , read by instrument called Wheatstone Bridge

• Wheatstone Bridge Equations

⇒ Equations for circuit sensitivity & effective range

⇒ Can go down to low resistance  $\epsilon [3, 5] \mu\epsilon$

⇒ Diagram



$$\left. \begin{aligned} V_{AB} &= \frac{R_1}{R_1 + R_2} V_s \\ V_{AD} &= \frac{R_3}{R_3 + R_4} V_s \end{aligned} \right\} V_o = V_{BD} = V_{AB} - V_{AD}$$

$$V_o = \frac{R_1(R_3 + R_4) - R_3(R_1 + R_2)}{(R_1 + R_2)(R_3 + R_4)} V_s$$

$$\text{for } V_o = 0 : R_1 R_3 + R_2 R_4 = R_1 R_4 + R_2 R_3 = 0$$

$$\underline{R_1 R_3 = R_2 R_4}$$

⇒ Place Strain Gage on any resistor, we convert  $\epsilon \rightarrow \Delta V$

$$V_o (R_i) \rightarrow \Delta V_o = f(R_i + AR_i) \rightarrow \Delta V_o = \frac{R_1 R_2}{(R_1 + R_2)^2} \left( \frac{\Delta R_1}{R_1} - \frac{\Delta R_2}{R_2} - \frac{\Delta R_3}{R_3} + \frac{\Delta R_4}{R_4} \right) V_s$$

↓  
Neglect  
H.O.T.

- Generally only one "R" is replaced so is "active"
- Linear function of  $\Delta R$  because we neglect higher order terms
- Bridge Sensitivity
- " $S_c$ " or sensitivity of bridge over by constant  $V_s$  & single active arm
- $$\left. \begin{array}{l} S_c = \frac{\Delta V_o}{\Delta R / R_1} = \frac{r}{(1+r)^2} V_s \\ + \Delta V_s \text{ for only } \Delta R_1 \\ + r = \frac{R_1 R_2}{R_1 + R_2} \end{array} \right\}$$
- $$V_s = I_T (R_1 + R_2) = I_T R_T (1+r)$$
- $$V_s = (1+r) \sqrt{P_T R_T}$$
- $$\underbrace{(1+r)}_{\text{current efficiency}} \underbrace{\sqrt{P_T R_T}}_{\text{physical characteristics}}$$
- $S_c = \frac{r}{1+r} \sqrt{P_T R_T}$
- $\downarrow$  circuit efficiency generally less than 70%
- $P_T : \text{power dissipated as heat}$
- $R_T : \text{Total resistance}$

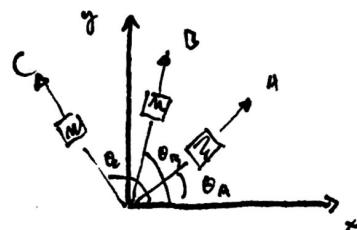
$$P_T R_T : 6 [1, 1000] \text{ W} \cdot \Omega, \text{ commercially}$$

- Strain Analysis
- What is known affects gage placement
- Stress Biaxial
- (i) Uniaxial Stress: 1 gage in stress axis

if  $E$  is known:  $\sigma_{xx} = \sigma_1 = E \epsilon_{xx}$

- (ii) Principal direction known but unknown magnitude: rectangular rosette in principal direction
- (iii) Stress field unknown: 3 element rosettes needed

→ 3 Element Rosette in general



measuring  $\varepsilon_x, \varepsilon_y, \varepsilon_c$

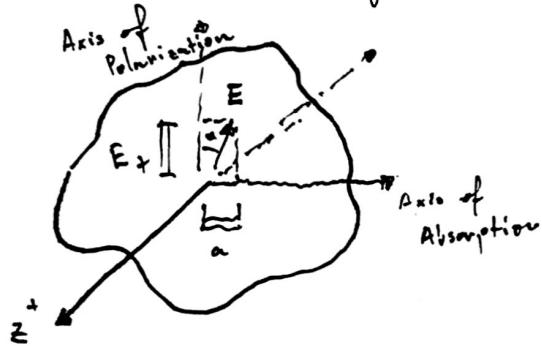
$\varepsilon_{xx} + \varepsilon_{yy} !$  by Mohr's Circle

Experimental Mechanics: 1 Oct 2017

### Notes on Birefringence

- Polariscopes: use linear polarizers through a transparent nematic material
- Plane polarizer for plane wave; circularly with wave plane
- Linear or Plane Polarizers

→ Thin material between light source and screen



$\vec{E}$ : light vector

$E_t$ : transmitted light

$E_a$ : absorbed light

$\alpha$ : angle b/w  $\vec{E}$  & axis of polarization

→ Equation for Light Vector:  $\vec{E} = a \cos \frac{2\pi}{\lambda} (z_0 - ct) \Rightarrow a \cos(\omega t)$

+ initial phase ( $\delta$ ) of light can be neglected

$$+ f = c/\lambda ; \omega = 2\pi f$$

→ Break into  $E_t$  and  $E_a$

$$+ E_a = a \cos(\omega t) \sin \alpha$$

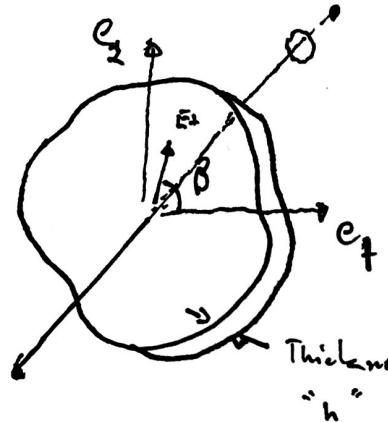
$$+ E_t = a \cos(\omega t) \cos \alpha$$

### Polaroid Filters



- Wannie Photor: transmits 2 orthogonal light vectors with different velocities

→ Wave plate after linear polarizer



- $\beta$ : angle
- $e_1$ : index of refraction axis ( $\pm 1$ ) / fast axis  
→  $n_1$ : index of refraction
- $c_f$ : velocity of propagation
- Labeled: so that  $c_1 > c_2$

$$+ E_{T_1} = E_1 \cos \beta = a \cos(\omega t) \cos \alpha \cos \beta = k \cos \omega t \cos \beta \quad ; \quad k = a \cos \alpha$$

$$+ E_{T_2} = E_2 \sin \beta = k \cos \omega t \sin \beta$$

$$+ \delta: \text{phase shift due to } c_1 \neq c_2 \text{ in w.r.t. air}$$

$$\left. \begin{array}{l} \delta_1 = h n_1 - h n \\ \delta_2 = h n_2 - h n \end{array} \right\} \delta = h (n_2 - n_1); \text{ relative phase difference}$$

linear

$$\Delta = \frac{2\pi}{\lambda} \delta = \frac{2\pi}{\lambda} h (n_2 - n_1) : \text{Angular phase shift}$$

→ Classification

$$+ \text{Quarter wave: } \Delta = \frac{\pi}{2}$$

$$+ \text{Half wave: } \Delta = \pi, 2\pi, \dots$$

→ Results in

$$\left. \begin{array}{l} + E_{T_1}' : k \cos \beta \cos \omega t \\ + E_{T_2}' : k \sin \beta \cos (\omega t - \Delta) \end{array} \right\} E_T' = \sqrt{E_{T_1}'^2 + E_{T_2}'^2} \Rightarrow |E_T'| = k \cos \tan \gamma$$

$$\rightarrow \text{Angle relative to } e_1: \tan \gamma = \frac{E_{T_2}'}{E_{T_1}'} = \frac{\cos(\omega t - \Delta)}{\cos(\omega t)} \tan \beta$$

• Conditioned Light using wave plates and linear polarizers

→ 3 defined cases

→ Plane Polarized Light:  $\beta = 0$ ;  $\Delta$  has no restriction

$$E'_+ = k \cos(\omega t)$$

$$\gamma = 0$$

→ Circularly Polarized light:  $\Delta = \pi/2$ ;  $\beta = \pi/4$  for left  $\therefore \beta = 3\pi/4$  for right

$$\left. \begin{array}{l} E'_+ = \frac{\sqrt{2}}{2} k \\ \gamma = \omega t \end{array} \right\} \text{Constant Magnitude, helical shape}$$

→ Elliptically Polarized: quarter wave plate ( $\Delta = \pi/2$ )

$$\left\{ \beta \neq \frac{n\pi}{2}, n \in \mathbb{Z} \right\}$$

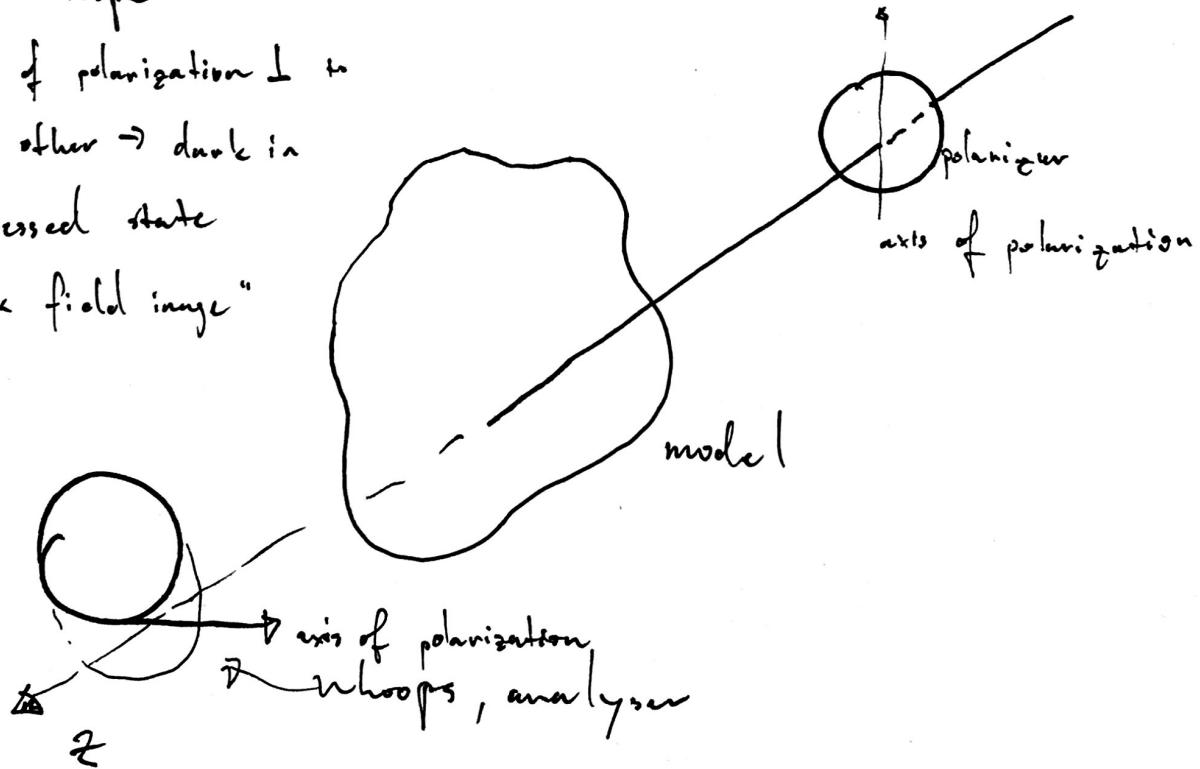
• Plane Polariscopes

→ Axis of polarization  $\perp$  to

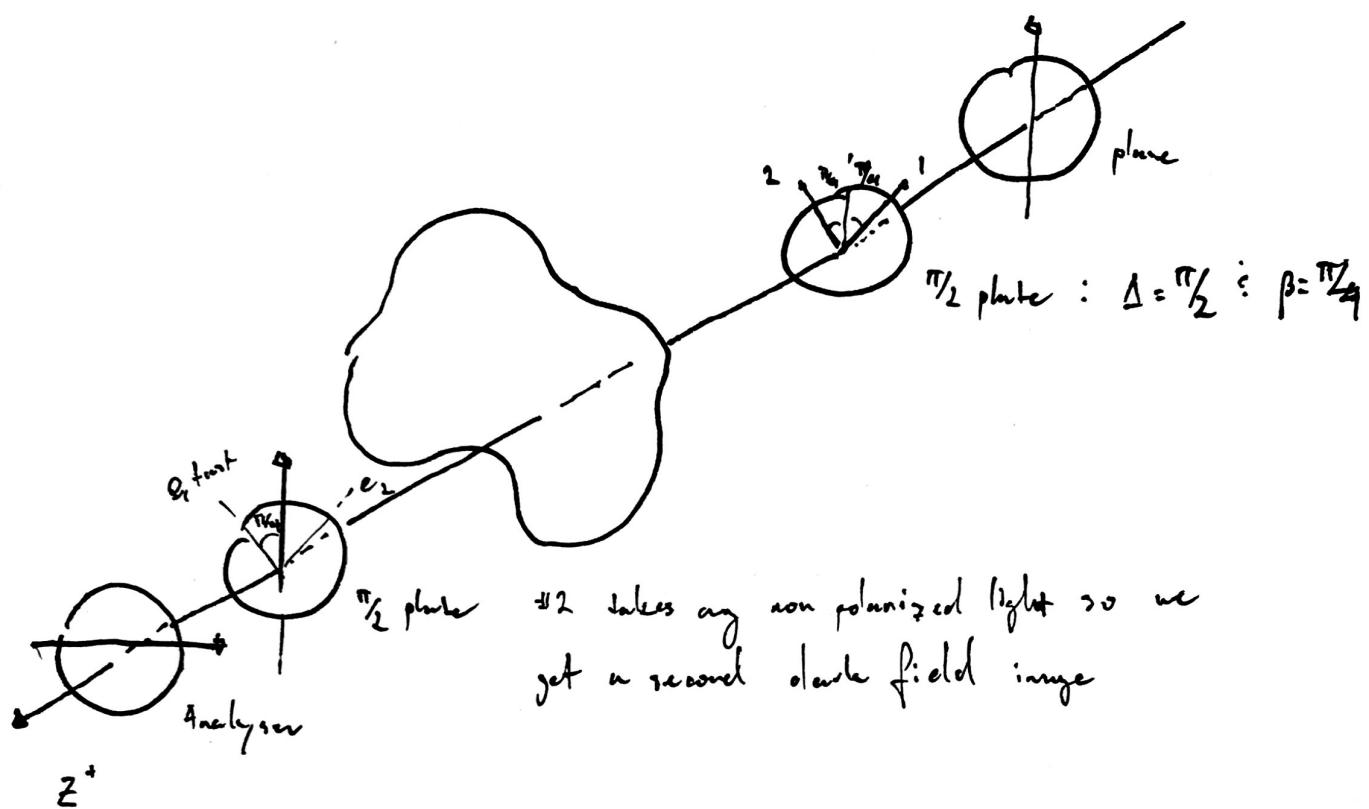
each other  $\rightarrow$  dark in

unstressed state

"dark field image"



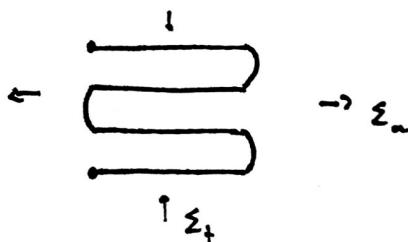
## Circular Polarizer



- Most commonly used is advance on constantine w/  $S_a \approx 2.1$ 
  - $\rightarrow 93\% Ni, 5\% Cu$  is nice because of linear for elastic  $\Sigma$  and even into plastic
  - $\rightarrow$  High " $\rho$ " and insensitive to  $\Delta T$

- Gauge Construction

- needs to be relatively long ( $\sim 0.1\text{ m}$ ) but we want  $\Sigma$  at a specific location
- Put onto grid pattern



• 1930's Ruge / Simmons : wire on paper  
 • 1950's Sanduski : foil attached on metallic foil  
 currently bonded to plastic for durability / insulation

- need special apposiation for bonding to specimen specimen
- $\rightarrow L_{gauge} \in [200\mu\text{m}, 100\text{mm}]$

- Average

$\rightarrow$  Linear Array :  $[MM_1MM_2MM_3]$  for capturing a line of  $\Sigma$

$\rightarrow$  Rosettes

- $\rightarrow 90^\circ$  Rosette :  $\begin{bmatrix} M_1 & M_2 \\ M_3 & M_1 \end{bmatrix}$  if we know principal strain
- $\rightarrow 45^\circ$  Rosette :  $\begin{bmatrix} M_1 & M_2 \\ M_3 & M_1 \end{bmatrix}$  ;  $60^\circ$   $\begin{bmatrix} M_1 & M_2 \\ M_3 & M_1 \end{bmatrix}$

- Gauge Sensitivity and Gauge Factor

$\rightarrow$  why a gage adds transverse component " $\epsilon_t$ " which we don't want to measure

$\rightarrow S_A = \frac{\Delta \epsilon}{\epsilon} \approx \frac{\Delta \epsilon / R}{\Sigma}$  must be transformed for biaxial strain

$$\rightarrow \frac{\Delta \epsilon / R}{\Sigma} = S_a \epsilon_a + S_t \epsilon_t + \cancel{S_{at}}^{\text{Shear sensitivity}} = S_a (\epsilon_a + K_t \epsilon_t) ; \epsilon_t = -\omega \epsilon_a$$

$\left. \begin{array}{c} \text{Axial} \\ \text{Sensitivity} \end{array} \right\} \quad \left. \begin{array}{c} \text{Transverse} \\ \text{Sensitivity} \end{array} \right\} \quad \left. \begin{array}{c} \cancel{\text{Shear sensitivity}} \\ \text{Shear sensitivity} \end{array} \right\}$

$K_t = \frac{S_t}{S_a}$  on transverse sensitivity factor

$\rightarrow S_g$  = Gauge factor

$$\frac{\Delta \epsilon / R}{\Sigma} = S_g \epsilon_a = S_a \epsilon_a (1 - \nu K_t) ; S_g = S_a (1 - \nu K_t) \sim [S_g, S_a, K_t] \in \begin{bmatrix} 1.26 \pm 2.13, \\ 1.93 \pm 2.14 \\ -4.2 \pm 1.8 \end{bmatrix}$$

- Error comes from only considering axial strain, knowing there is some transverse strain

$$\frac{\Delta R}{R} : \frac{S_g \varepsilon_a}{1 - \nu K_t} \left( 1 + K_t \frac{\varepsilon_t}{\varepsilon_a} \right) \rightarrow \varepsilon_a : \frac{\Delta R/R}{S_g} \frac{1 - \nu K_t}{1 + K_t (\varepsilon_t / \varepsilon_a)} \text{ is true axial strain}$$

apparent  $\varepsilon_a' = \frac{\Delta R/R}{S_g} \rightarrow \varepsilon_a = \varepsilon_a' \frac{1 - \nu K_t}{1 + K_t (\varepsilon_t / \varepsilon_a)}$

$\Rightarrow$  that % error from neglecting transverse component

$$\xi = \frac{\varepsilon_a - \varepsilon_a'}{\varepsilon_a} (100) = \cancel{K_t} \frac{(1 - \nu K_t)(\varepsilon_t / \varepsilon_a + \nu)}{1 - \nu K_t} ? \quad \left\{ \begin{array}{l} \varepsilon_t / \varepsilon_a \text{ is a prescribed} \\ \text{value from problem;} \\ \text{independent of } \nu \end{array} \right.$$