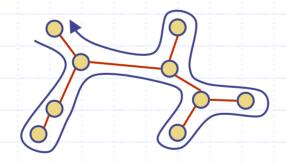
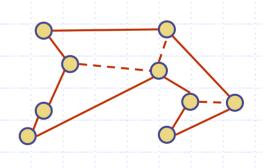
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Outline and Reading

- Overview of the assignment
- Review
 - Adjacency matrix structure (§12.2.3)
 - Kruskal's MST algorithm (§12.7.1)
- Partition ADT and implementatio
- ◆ The decorator pattern (§12.3.1)
- The traveling salesperson problem
 - Definition
 - Approximation algorithm

Graph Assignment

Goals

- Learn and implement the adjacency matrix structure an Kruskal's minimum spanning tree algorithm
- Understand and use the decorator pattern

Your task

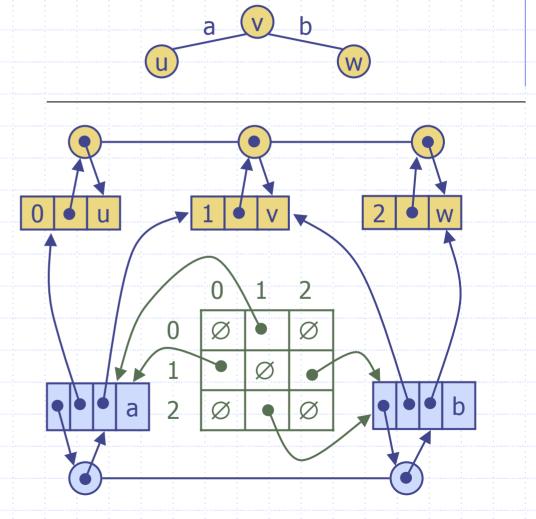
- Implement the adjacency matrix structure for representing a graph
- Implement Kruskal's MST algorithm

Frontend

 Computation and visualization of an approximate traveling salesperson tour

Adjacency Matrix Structure

- Edge list structure
- Augmented vertex objects
 - Integer key (index) associated with vertex
- 2D-array adjacency array
 - Reference to edge object for adjacent vertices
 - Null for non nonadjacent vertices

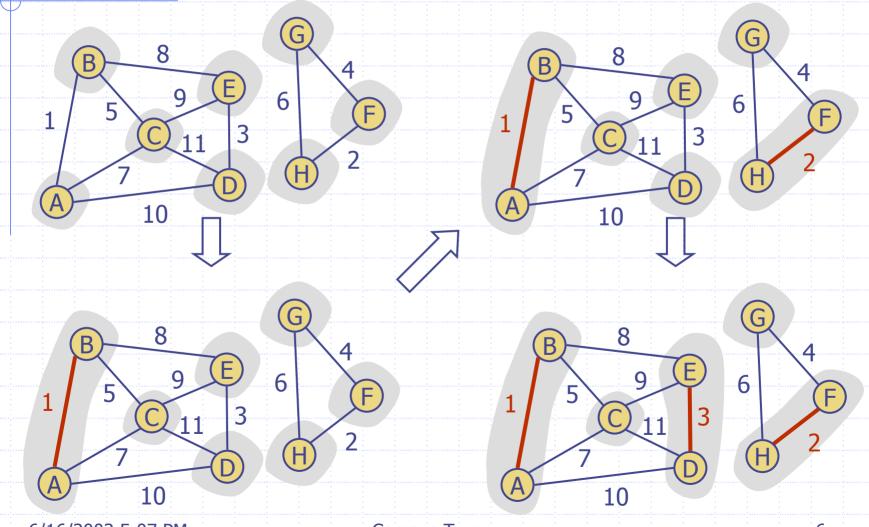


Kruskal's Algorithm

- The vertices are partitioned into clouds
 - We start with one cloud per vertex
 - Clouds are merged during the execution of the algorithm
- Partition ADT:
 - makeSet(o): create set {o}and return a locator for object o
 - find(l): return the set of the object with locator l
 - union(A,B): merge sets Aand B

```
Algorithm KruskalMSF(G)
Input weighted graph G
Output labeling of the edges of a
   minimum spanning forest of G
Q \leftarrow new heap-based priority queue
for all v \in G.vertices() do
   l \leftarrow makeSet(v) \{ elementary cloud \}
   setLocator(v,l)
for all e \in G.edges() do
   Q.insert(weight(e), e)
while \neg Q.isEmpty()
   e \leftarrow Q.removeMin()
   [u,v] \leftarrow G.endVertices(e)
   A \leftarrow find(getLocator(u))
   B \leftarrow find(getLocator(v))
    if A \neq B
      setMSFedge(e)
      { merge clouds }
      union(A, B)
```

Example

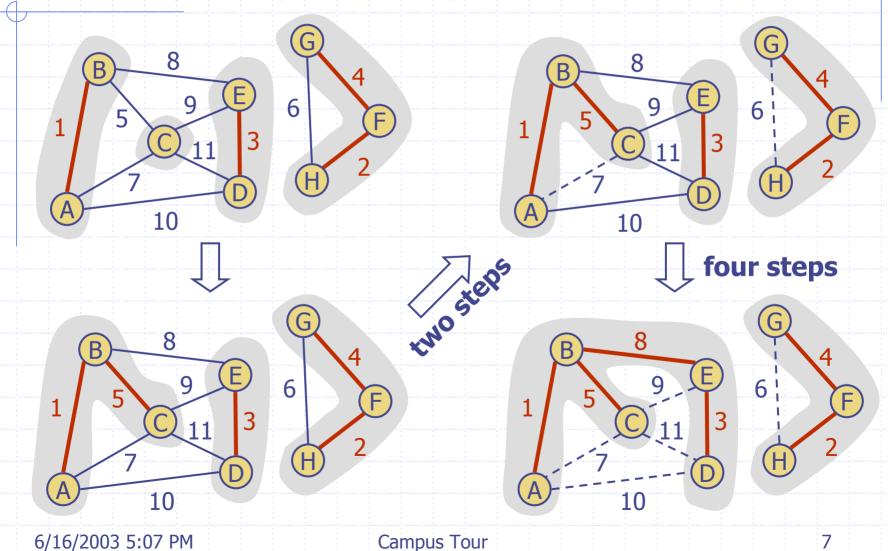


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Example (contd.)



Partition Implementation

- Partition implementation
 - A set is represented the sequence of its elements
 - A position stores a reference back to the sequence itself (for operation *find*)
 - The position of an element in the sequence serves as locator for the element in the set
 - In operation union, we move the elements of the smaller sequence into to the larger sequence
- Worst-case running times
 - **■** *makeSet*, *find*: *O*(1)
 - union: $O(min(n_A, n_B))$

- Amortized analysis
 - Consider a series of k Partiton
 ADT operations that includes
 n makeSet operations
 - Each time we move an element into a new sequence, the size of its set at least doubles
 - An element is moved at most
 log₂ n times
 - Moving an element takes *O*(1) time
 - The total time for the series of operations is $O(k + n \log n)$

Analysis of Kruskal's Algorithm

- Graph operations
 - Methods vertices and edges are called once
 - Method endVertices is called m times
- Priority queue operations
 - We perform *m insert* operations and *m removeMin* operations
- Partition operations
 - We perform n makeSet operations, 2m find operations and no more than n-1 union operations
- Label operations
 - We set vertex labels n times and get them 2m times
- \bullet Kruskal's algorithm runs in time $O((n + m) \log n)$ time provided the graph has no parallel edges and is represented by the adjacency list structure

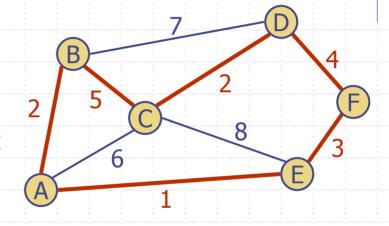
Decorator Pattern

- Labels are commonly used in graph algorithms
 - Auxiliary data
 - Output
- Examples
 - DFS: unexplored/visited label for vertices and unexplored/ forward/back labels for edges
 - Dijkstra and Prim-Jarnik: distance, locator, and parent labels for vertices
 - Kruskal: locator label for vertices and MSF label for edges

- The decorator pattern extends the methods of the Position ADT to support the handling of attributes (labels)
 - has(a): tests whether the position has attribute a
 - get(a): returns the value of attribute a
 - set(a, x): sets to x the value of attribute a
 - destroy(a): removes attribute
 a and its associated value (for cleanup purposes)
- The decorator pattern can be implemented by storing a dictionary of (attribute, value) items at each position

Traveling Salesperson Problem

- A tour of a graph is a spanning cycle (e.g., a cycle that goes through all the vertices)
- A traveling salesperson tour of a weighted graph is a tour that is simple (i.e., no repeated vertices or edges) and has has minimum weight
- No polynomial-time algorithms are known for computing traveling salesperson tours
- The traveling salesperson problem (TSP) is a major open problem in computer science
 - Find a polynomial-time algorithm computing a traveling salesperson tour or prove that none exists



Example of traveling salesperson tour (with weight 17)

TSP Approximation

- We can approximate a TSP tour with a tour of at most twice the weight for the case of Euclidean graphs
 - Vertices are points in the plane
 - Every pair of vertices is connected by an edge
 - The weight of an edge is the length of the segment joining the points
- Approximation algorithm
 - Compute a minimum spanning tree
 - Form an Eulerian circuit around the MST
 - Transform the circuit into a tour

