**Arduino Timer1 Class**

**Overview**

|  |
| --- |
| TimerOne 과 관련된 Register를 초기화한다.  Pin과 PWM 주기를 설정한다.  PWM은 핀과 주기를 동시에 설정  : pinMode(TIMER1\_A\_PIN, OUTPUT);  : setPwmDuty(pin, duty);  setPwmDuty는 주기만 바꾼다  #include <TimerOne.h>  #define LEDPIN 13  bool on\_off = false;  void setup() {  // put your setup code here, to run once:  Timer1.initialize();  Timer1.setPeriod(1000000); //1hz  Timer1.attachInterrupt(ledTunOnOff);  pinMode(LEDPIN,OUTPUT);  }  void ledTunOnOff(){  on\_off = !on\_off;  if(on\_off){  digitalWrite(LEDPIN,HIGH);  }  else{  digitalWrite(LEDPIN,LOW);  }  }  void loop() {  // put your main code here, to run repeatedly:  } |

**Properties**

|  |
| --- |
| static unsigned short pwmPeriod;  static unsigned char clockSelectBits; |

**Header**

|  |
| --- |
| TimerOne\_h\_  : 사용자 정의 헤더  Arduino.h  : 아두이노 내부 헤더  config\known\_16bit\_timers.h  : 사용자 정의 헤더 |

**Function**

|  |
| --- |
| \_BV()  :<avr/sfr\_defs.h>에 정의되어 있는 compiler macro  :#define \_BV(bit)(1<<(bit))  void initialize(unsigned long microseconds=1000000)  void setPeriod(unsigned long microseconds)  void setPwmDuty(char pin, unsigned int duty)  void pwm(char pin, unsigned int duty)  void pwm(char pin, unsigned int duty, unsigned long microseconds)  void disablePwm(char pin) \_\_attribute\_\_((always\_inline))  void attachInterrupt(void (\*isr)())  void attachInterrupt(void (\*isr)(), unsigned long microseconds)  void detachInterrupt() |

**Identifier**

|  |
| --- |
| F\_CPU  :아두이노 내부 클럭 속도 (16Mhz)  TIMER1\_RESOLUTION  :Timer1 is 16bit (65536UL)  \_\_AVR\_\_  : 아트멜 AVR 8비트 RISC 단일칩 마이크로 컨트롤러  \_\_attribute\_\_  : Unix/Linux 환경의 GCC 컴파일러는 \_\_attribute\_\_라는 속성 옵션을 사용  : GCC 컴파일러에게 추가적인 에러체킹을 지시  \_\_attribute\_\_((always\_inline))  : 컴파일러가 함수의 characteristics에 관계없이 인라인 함수로 동작  : 인라인 함수는 함수의 코드를 복제해서 넣는다.  : 함수 호출 과정이 없어서 속도가 좀 더 빠르다 .  : 코드가 복제되므로 함수를 많이 사용하면 실행 파일의 크기가 커진다. |

**Code**

**TimerOne.h**

|  |
| --- |
| /\*  \* Interrupt and PWM utilities for 16 bit Timer1 on ATmega168/328  \* Original code by Jesse Tane for http://labs.ideo.com August 2008  \* Modified March 2009 by Jérôme Despatis and Jesse Tane for ATmega328 support  \* Modified June 2009 by Michael Polli and Jesse Tane to fix a bug in setPeriod() which caused the timer to stop  \* Modified April 2012 by Paul Stoffregen - portable to other AVR chips, use inline functions  \* Modified again, June 2014 by Paul Stoffregen - support Teensy 3.x & even more AVR chips  \*  \*  \* This is free software. You can redistribute it and/or modify it under  \* the terms of Creative Commons Attribution 3.0 United States License.  \* To view a copy of this license, visit http://creativecommons.org/licenses/by/3.0/us/  \* or send a letter to Creative Commons, 171 Second Street, Suite 300, San Francisco, California, 94105, USA.  \*  \*/  #ifndef TimerOne\_h\_  #define TimerOne\_h\_  #if defined(ARDUINO) && ARDUINO >= 100  #include "Arduino.h"  #else  #include "WProgram.h"  #endif  #include "config/known\_16bit\_timers.h"  #define TIMER1\_RESOLUTION 65536UL // Timer1 is 16 bit  // Placing nearly all the code in this .h file allows the functions to be  // inlined by the compiler. In the very common case with constant values  // the compiler will perform all calculations and simply write constants  // to the hardware registers (for example, setPeriod).  class TimerOne  {  #if defined(\_\_AVR\_\_)  public:  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  // Configuration  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  void initialize(unsigned long microseconds=1000000) \_\_attribute\_\_((always\_inline)) {  TCCR1B = \_BV(WGM13); // set mode as phase and frequency correct pwm, stop the timer  TCCR1A = 0; // clear control register A  setPeriod(microseconds);  }  void setPeriod(unsigned long microseconds) \_\_attribute\_\_((always\_inline)) {  const unsigned long cycles = (F\_CPU / 2000000) \* microseconds;  if (cycles < TIMER1\_RESOLUTION) {  clockSelectBits = \_BV(CS10);  pwmPeriod = cycles;  } else  if (cycles < TIMER1\_RESOLUTION \* 8) {  clockSelectBits = \_BV(CS11);  pwmPeriod = cycles / 8;  } else  if (cycles < TIMER1\_RESOLUTION \* 64) {  clockSelectBits = \_BV(CS11) | \_BV(CS10);  pwmPeriod = cycles / 64;  } else  if (cycles < TIMER1\_RESOLUTION \* 256) {  clockSelectBits = \_BV(CS12);  pwmPeriod = cycles / 256;  } else  if (cycles < TIMER1\_RESOLUTION \* 1024) {  clockSelectBits = \_BV(CS12) | \_BV(CS10);  pwmPeriod = cycles / 1024;  } else {  clockSelectBits = \_BV(CS12) | \_BV(CS10);  pwmPeriod = TIMER1\_RESOLUTION - 1;  }  ICR1 = pwmPeriod;  TCCR1B = \_BV(WGM13) | clockSelectBits;  }  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  // Run Control  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  void start() \_\_attribute\_\_((always\_inline)) {  TCCR1B = 0;  TCNT1 = 0; // TODO: does this cause an undesired interrupt?  resume();  }  void stop() \_\_attribute\_\_((always\_inline)) {  TCCR1B = \_BV(WGM13);  }  void restart() \_\_attribute\_\_((always\_inline)) {  start();  }  void resume() \_\_attribute\_\_((always\_inline)) {  TCCR1B = \_BV(WGM13) | clockSelectBits;  }  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  // PWM outputs  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  void setPwmDuty(char pin, unsigned int duty) \_\_attribute\_\_((always\_inline)) {  unsigned long dutyCycle = pwmPeriod;  dutyCycle \*= duty;  dutyCycle >>= 10;  if (pin == TIMER1\_A\_PIN) OCR1A = dutyCycle;  #ifdef TIMER1\_B\_PIN  else if (pin == TIMER1\_B\_PIN) OCR1B = dutyCycle;  #endif  #ifdef TIMER1\_C\_PIN  else if (pin == TIMER1\_C\_PIN) OCR1C = dutyCycle;  #endif  }  void pwm(char pin, unsigned int duty) \_\_attribute\_\_((always\_inline)) {  if (pin == TIMER1\_A\_PIN) { pinMode(TIMER1\_A\_PIN, OUTPUT); TCCR1A |= \_BV(COM1A1); }  #ifdef TIMER1\_B\_PIN  else if (pin == TIMER1\_B\_PIN) { pinMode(TIMER1\_B\_PIN, OUTPUT); TCCR1A |= \_BV(COM1B1); }  #endif  #ifdef TIMER1\_C\_PIN  else if (pin == TIMER1\_C\_PIN) { pinMode(TIMER1\_C\_PIN, OUTPUT); TCCR1A |= \_BV(COM1C1); }  #endif  setPwmDuty(pin, duty);  TCCR1B = \_BV(WGM13) | clockSelectBits;  }  void pwm(char pin, unsigned int duty, unsigned long microseconds) \_\_attribute\_\_((always\_inline)) {  if (microseconds > 0) setPeriod(microseconds);  pwm(pin, duty);  }  void disablePwm(char pin) \_\_attribute\_\_((always\_inline)) {  if (pin == TIMER1\_A\_PIN) TCCR1A &= ~\_BV(COM1A1);  #ifdef TIMER1\_B\_PIN  else if (pin == TIMER1\_B\_PIN) TCCR1A &= ~\_BV(COM1B1);  #endif  #ifdef TIMER1\_C\_PIN  else if (pin == TIMER1\_C\_PIN) TCCR1A &= ~\_BV(COM1C1);  #endif  }  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  // Interrupt Function  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  void attachInterrupt(void (\*isr)()) \_\_attribute\_\_((always\_inline)) {  isrCallback = isr;  TIMSK1 = \_BV(TOIE1);  }  void attachInterrupt(void (\*isr)(), unsigned long microseconds) \_\_attribute\_\_((always\_inline)) {  if(microseconds > 0) setPeriod(microseconds);  attachInterrupt(isr);  }  void detachInterrupt() \_\_attribute\_\_((always\_inline)) {  TIMSK1 = 0;  }  static void (\*isrCallback)();  private:  // properties  static unsigned short pwmPeriod;  static unsigned char clockSelectBits;  #elif defined(\_\_arm\_\_) && defined(CORE\_TEENSY)  #if defined(KINETISK)  #define F\_TIMER F\_BUS  #elif defined(KINETISL)  #define F\_TIMER (F\_PLL/2)  #endif  public:  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  // Configuration  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  void initialize(unsigned long microseconds=1000000) \_\_attribute\_\_((always\_inline)) {  setPeriod(microseconds);  }  void setPeriod(unsigned long microseconds) \_\_attribute\_\_((always\_inline)) {  const unsigned long cycles = (F\_TIMER / 2000000) \* microseconds;  if (cycles < TIMER1\_RESOLUTION) {  clockSelectBits = 0;  pwmPeriod = cycles;  } else  if (cycles < TIMER1\_RESOLUTION \* 2) {  clockSelectBits = 1;  pwmPeriod = cycles >> 1;  } else  if (cycles < TIMER1\_RESOLUTION \* 4) {  clockSelectBits = 2;  pwmPeriod = cycles >> 2;  } else  if (cycles < TIMER1\_RESOLUTION \* 8) {  clockSelectBits = 3;  pwmPeriod = cycles >> 3;  } else  if (cycles < TIMER1\_RESOLUTION \* 16) {  clockSelectBits = 4;  pwmPeriod = cycles >> 4;  } else  if (cycles < TIMER1\_RESOLUTION \* 32) {  clockSelectBits = 5;  pwmPeriod = cycles >> 5;  } else  if (cycles < TIMER1\_RESOLUTION \* 64) {  clockSelectBits = 6;  pwmPeriod = cycles >> 6;  } else  if (cycles < TIMER1\_RESOLUTION \* 128) {  clockSelectBits = 7;  pwmPeriod = cycles >> 7;  } else {  clockSelectBits = 7;  pwmPeriod = TIMER1\_RESOLUTION - 1;  }  uint32\_t sc = FTM1\_SC;  FTM1\_SC = 0;  FTM1\_MOD = pwmPeriod;  FTM1\_SC = FTM\_SC\_CLKS(1) | FTM\_SC\_CPWMS | clockSelectBits | (sc & FTM\_SC\_TOIE);  }  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  // Run Control  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  void start() \_\_attribute\_\_((always\_inline)) {  stop();  FTM1\_CNT = 0;  resume();  }  void stop() \_\_attribute\_\_((always\_inline)) {  FTM1\_SC = FTM1\_SC & (FTM\_SC\_TOIE | FTM\_SC\_CPWMS | FTM\_SC\_PS(7));  }  void restart() \_\_attribute\_\_((always\_inline)) {  start();  }  void resume() \_\_attribute\_\_((always\_inline)) {  FTM1\_SC = (FTM1\_SC & (FTM\_SC\_TOIE | FTM\_SC\_PS(7))) | FTM\_SC\_CPWMS | FTM\_SC\_CLKS(1);  }  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  // PWM outputs  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  void setPwmDuty(char pin, unsigned int duty) \_\_attribute\_\_((always\_inline)) {  unsigned long dutyCycle = pwmPeriod;  dutyCycle \*= duty;  dutyCycle >>= 10;  if (pin == TIMER1\_A\_PIN) {  FTM1\_C0V = dutyCycle;  } else if (pin == TIMER1\_B\_PIN) {  FTM1\_C1V = dutyCycle;  }  }  void pwm(char pin, unsigned int duty) \_\_attribute\_\_((always\_inline)) {  setPwmDuty(pin, duty);  if (pin == TIMER1\_A\_PIN) {  \*portConfigRegister(TIMER1\_A\_PIN) = PORT\_PCR\_MUX(3) | PORT\_PCR\_DSE | PORT\_PCR\_SRE;  } else if (pin == TIMER1\_B\_PIN) {  \*portConfigRegister(TIMER1\_B\_PIN) = PORT\_PCR\_MUX(3) | PORT\_PCR\_DSE | PORT\_PCR\_SRE;  }  }  void pwm(char pin, unsigned int duty, unsigned long microseconds) \_\_attribute\_\_((always\_inline)) {  if (microseconds > 0) setPeriod(microseconds);  pwm(pin, duty);  }  void disablePwm(char pin) \_\_attribute\_\_((always\_inline)) {  if (pin == TIMER1\_A\_PIN) {  \*portConfigRegister(TIMER1\_A\_PIN) = 0;  } else if (pin == TIMER1\_B\_PIN) {  \*portConfigRegister(TIMER1\_B\_PIN) = 0;  }  }  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  // Interrupt Function  //\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*  void attachInterrupt(void (\*isr)()) \_\_attribute\_\_((always\_inline)) {  isrCallback = isr;  FTM1\_SC |= FTM\_SC\_TOIE;  NVIC\_ENABLE\_IRQ(IRQ\_FTM1);  }  void attachInterrupt(void (\*isr)(), unsigned long microseconds) \_\_attribute\_\_((always\_inline)) {  if(microseconds > 0) setPeriod(microseconds);  attachInterrupt(isr);  }  void detachInterrupt() \_\_attribute\_\_((always\_inline)) {  FTM1\_SC &= ~FTM\_SC\_TOIE;  NVIC\_DISABLE\_IRQ(IRQ\_FTM1);  }  static void (\*isrCallback)();  private:  // properties  static unsigned short pwmPeriod;  static unsigned char clockSelectBits;  #undef F\_TIMER  #endif  };  extern TimerOne Timer1;  #endif |

**TimerOne.cpp**

|  |
| --- |
| */\**  *\* Interrupt and PWM utilities for 16 bit Timer1 on ATmega168/328*  *\* Original code by Jesse Tane for http://labs.ideo.com August 2008*  *\* Modified March 2009 by Jérôme Despatis and Jesse Tane for ATmega328 support*  *\* Modified June 2009 by Michael Polli and Jesse Tane to fix a bug in setPeriod() which caused the timer to stop*  *\* Modified Oct 2009 by Dan Clemens to work with timer1 of the ATMega1280 or Arduino Mega*  *\* Modified April 2012 by Paul Stoffregen*  *\* Modified again, June 2014 by Paul Stoffregen*  *\**  *\* This is free software. You can redistribute it and/or modify it under*  *\* the terms of Creative Commons Attribution 3.0 United States License.*  *\* To view a copy of this license, visit http://creativecommons.org/licenses/by/3.0/us/*  *\* or send a letter to Creative Commons, 171 Second Street, Suite 300, San Francisco, California, 94105, USA.*  *\**  *\*/*  #include *"TimerOne.h"*  TimerOne Timer1; *// preinstatiate*  unsigned short TimerOne::pwmPeriod = 0;  unsigned char TimerOne::clockSelectBits = 0;  void (\*TimerOne::isrCallback)() = NULL;  *// interrupt service routine that wraps a user defined function supplied by attachInterrupt*  #if defined(\_\_AVR\_\_)  ISR(TIMER1\_OVF\_vect)  {  Timer1.isrCallback();  }  #elif defined(\_\_arm\_\_) && defined(CORE\_TEENSY)  void ftm1\_isr(void)  {  uint32\_t sc = FTM1\_SC;  #ifdef KINETISL  **if** (sc & 0x80) FTM1\_SC = sc;  #else  **if** (sc & 0x80) FTM1\_SC = sc & 0x7F;  #endif  Timer1.isrCallback();  }  #endif |

**Reference**

|  |
| --- |
| # [Timer1 Clock Source - Developer Help (microchipdeveloper.com)](https://microchipdeveloper.com/8bit:timer1clk) |