# toysim user manual

| Title        | toysim (ArchC functional simulator for the Princeton TOY machine) |
|--------------|---|
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| Rev. history |   |
| v0.0.2       | 2014-10-30  |
|              | Project cleaned-up and updated for Github.                        |
| v0.0.1       | 2010-12-11  |
|              | First public version.   |

## 1. Introduction

This is the ArchC (http://www.archc.org) functional simulator model for the Princeton TOY processor. The Princeton TOY machine is a 16-bit educational RISC processor with only two orthogonal encodings. A description of the basic ISA is available in the form of the TOY reference card.

This model has the system call emulation functions implemented, so it is a good idea to turn on the ABI option. It should be noted that this capability is currently untested.

# 2. File listing

The toysim distribution includes the following files:

| /toysim     | Top-level directory                      |
|-------------|--|
| AUTHORS     | List of toysim authors.                  |
| LICENSE     | The modified BSD license governs toysim. |
| README.html | HTML version of README.                  |
| README.pdf  | PDF version of README.                   |
| README.rst  | This file.                               |
| VERSION     | Current version of the project sources.  |
| defines_gdb | Macro definitions for GDB integration.   |

| toy.ac            | Register, memory and cache model for TOY.  |  |
|-------------------|--|--|
| toy_gdb_funcs.cpp | GDB support for the TOY simulator.   |  |
| toy_isa.ac        | Instruction encodings and assembly formats.  |  |
| toy_syscall.cpp   | OS call emulation support for TOY (untested).  |  |
| toy_isa.cpp       | Instruction behaviors.   |  |
| modifiers         | Instruction encoding and decoding modifiers.   |  |
| rst2docs.sh       | Bash script for generating the HTML and PDF versions of the documentation (README).                    |  |
| run_tools.sh      | Script for automating the build of the simulator and the associated binary utilities (binutils) port.  |  |
| /tests            | Tests subdirectory   |  |
| run-tests.sh      | Run a selected benchmark.  |  |
| /fibo             | Fibonacci series benchmark directory   |  |
| Makefile          | Makefile for building the benchmark.   |  |
| ac_start.s        | Startup file (prior main()) for TOY.   |  |
| fibo.asm          | Fibonacci benchmark using the alternative Princeton TOY assembly syntax (defined for the ArchC model). |  |
| /popcount         | Population count benchmark directory   |  |
| Makefile          | Makefile for building the benchmark.   |  |
| popcount.asm      | Population count benchmark using the original assembly syntax (needs to be converted).                 |  |

#### 3. Usage

To generate the interpreted simulator, the acsim executable is ran:

```
$ acsim toy.ac [-g -abi -gdb]  # (create the simulator)
$ make -f Makefile.archc  # (compile)
$ ./toy.x --load=<file-path> [args] # (run an application)
```

To generate the compiled application simulator, the accsim executable is ran:

The [args] are optional arguments for the application. There are two formats recognized for application <file-path>:

- ELF binary matching ArchC specifications
- hexadecimal text file for ArchC

In order to generate the binary utilities port (binutils port), the acbingen.sh driver script must be used. This should be called as follows:

\$ acbingen.sh -atoy -i'pwd'/../toysim-tools/ toy.ac

for generating the binutils port executables. This includes the following tools:

- addr2line
- ar
- as
- c++filt
- gdb (the GDB port is also generated in the same directory)
- gdbtui
- 1d
- nm
- objcopy
- objdump
- ranlib
- readelf
- size
- strings
- strip

## 4. Notes

The assembly instruction syntax followed by the ArchC-based simulator for TOY is quite different than the original syntax. The following table summarizes the differences of the two syntax variations.

| Original syntax                   | ArchC-compatible syntax |
|-----------------------------------|-------------------------|
| R[d] <- imm8                      | lda rd, imm8            |
| R[d] <- mem[imm8]                 | ld rd, imm8             |
| R[d] -> mem[imm8]                 | st rd, imm8             |
| $R[d] \leftarrow mem[R[t]]$       | ldi rd, rt              |
| $mem[R[t]] \leftarrow R[d]$       | sti rd, rt              |
| $R[d] \leftarrow R[s] + R[t]$     | add rd, rs, rt          |
| $R[d] \leftarrow R[s] - R[t]$     | sub rd, rs, rt          |
| $R[d] \leftarrow R[s] & R[t]$     | and rd, rs, rt          |
| $R[d] \leftarrow R[s] \land R[t]$ | xor rd, rs, rt          |
| $R[d] \leftarrow R[s] \ll R[t]$   | shl rd, rs, rt          |
| $R[d] \leftarrow R[s] \gg R[t]$   | shr rd, rs, rt          |

| R[d] <- pc; pc <- imm8      | jal rd, imm8 |
|-----------------------------|--------------|
| pc <- R[d]                  | jr rd        |
| if $(R[d] == 0)$ pc <- imm8 | jz rd, imm8  |
| if $(R[d] > 0)$ pc <- imm8  | jp rd, imm8  |
| pc <- pc                    | halt         |

Supported pseudo-instructions include:

- nop (no operation)
- move (move register)
- neg (negate)
- li (load immediate)
- la (load address)

# 5. Prerequisites

- ArchC installation (tested on Cygwin/Win7-64bit and Linux)
- Standard UNIX-based tools: make, gcc.

#### 6. Contact

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