



Classification of agricultural land use by ensemble of convolutional neural networks

Nathaniel Newlands and Etienne Lord

nathaniel.newlands@canada.ca, researcher

etienne.lord@canada.ca, researcher



Agriculture et
Agroalimentaire Canada

Agriculture and
Agri-Food Canada

Canada

Introduction

What is the correct temporal and spatial resolution for precision agriculture?

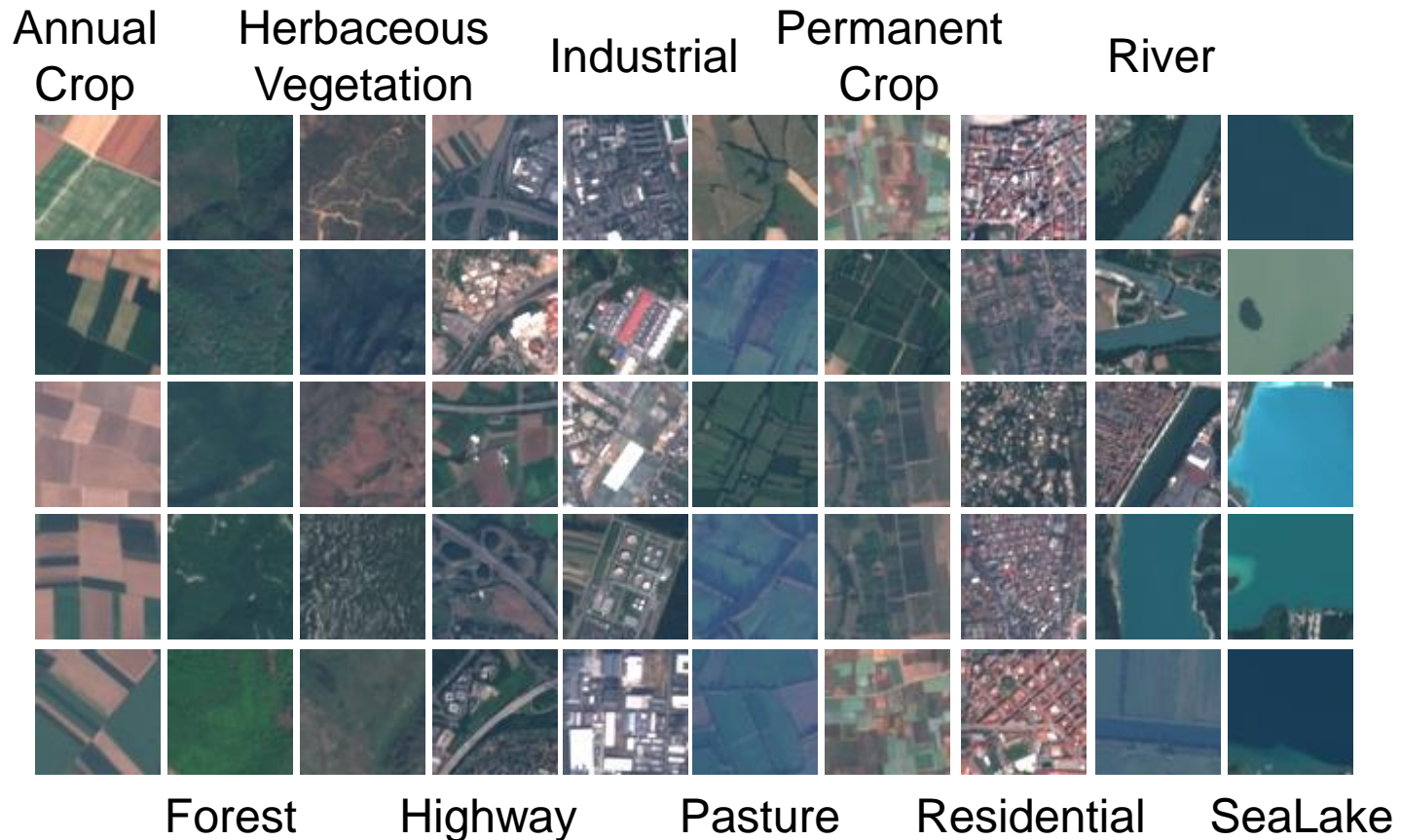
Our goal is to follow crop development and spot early anomalies

• Agriculture and Agri-Food Canada
St-Jean-sur-Richelieu RDC

Google image

EuroSat (sentinel-2)

10 land use and land cover classes including 27,000 images



Helber P, Bischke B, Dengel A, Borth D. Eurosat: A novel dataset and deep learning benchmark for land use and land cover classification. arXiv preprint arXiv:1709.00029. 2017 Aug 31.

Goals is evolution of land use

However, they only verified single band or RGB classification accuracy

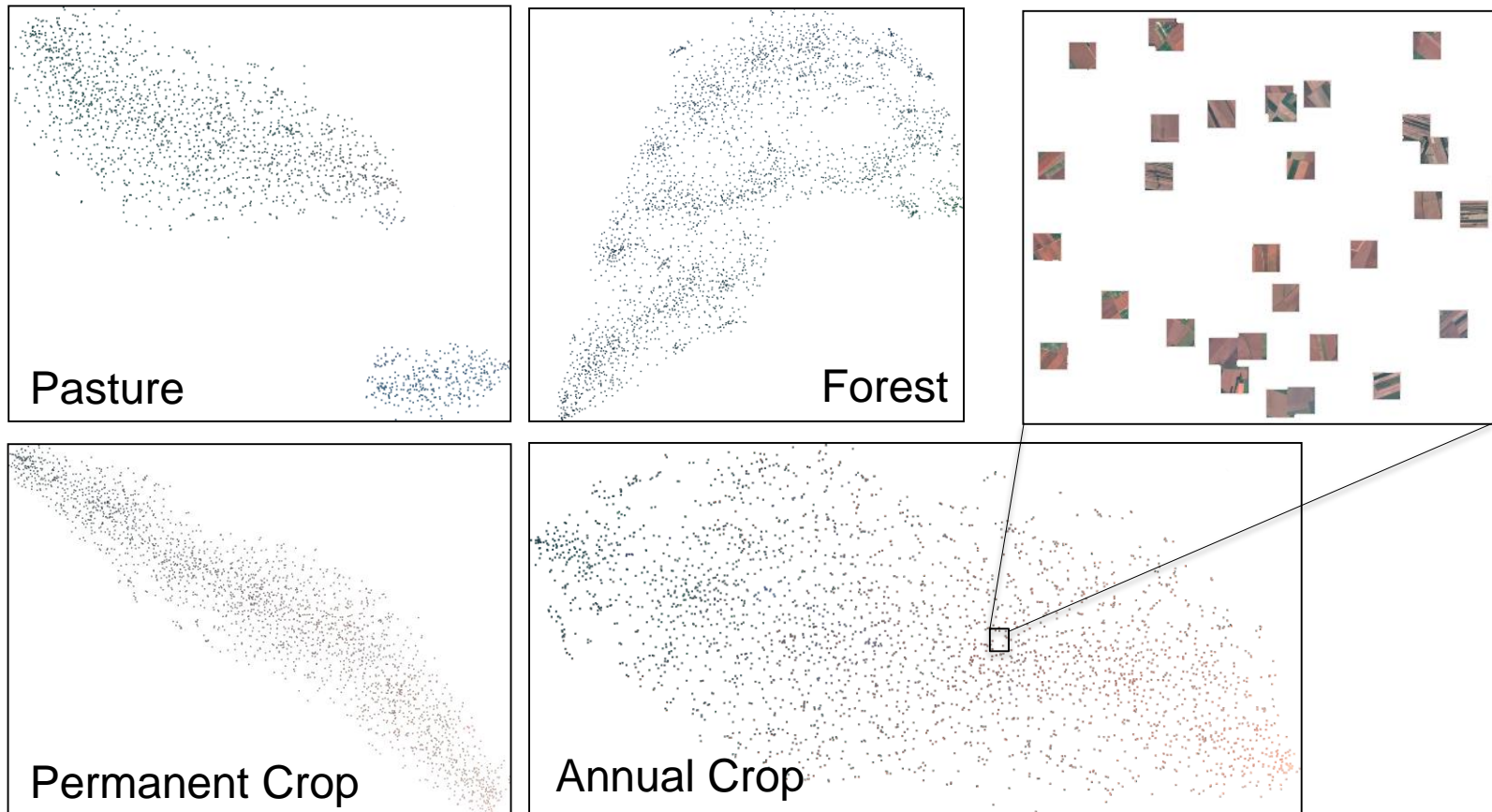


Helber et al. (2017) used a ResNet-50-based convolutional neural network.

t -SNE clustering

t-Distributed Stochastic Neighbor Embedding is a dimensionality reduction method*.

The dataset images show diverse distributions over the RGB bands

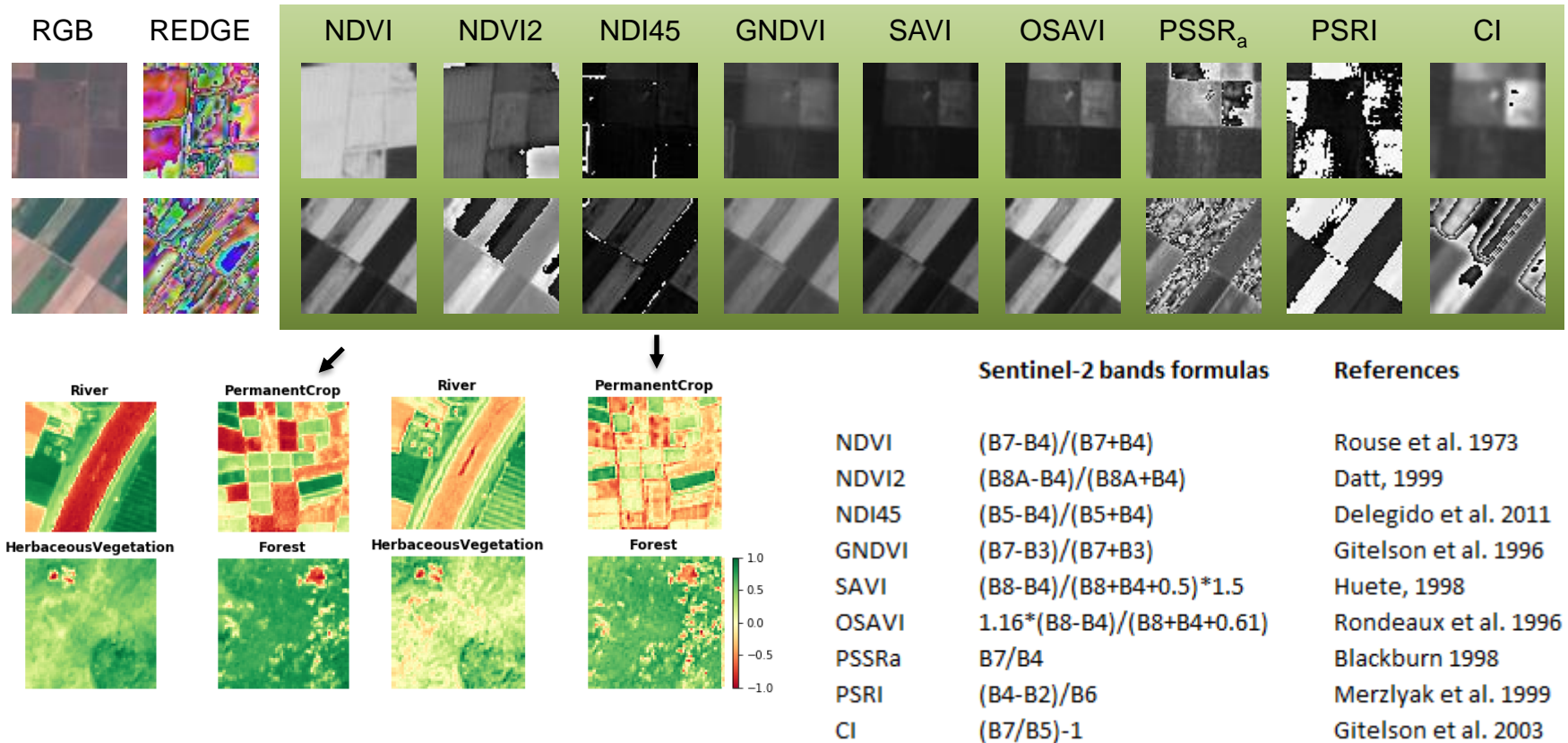


***As opposed to PCA, there is no reduction in the signal in the pairwise similarity search.**

Chan DM, Rao R, Huang F, Canny JF. t-SNE-CUDA: GPU-Accelerated t-SNE and its Applications to Modern Data. In 2018 30th International Symposium on Computer Architecture and High Performance Computing (SBAC-PAD) 2018 Sep 24 (pp. 330-338). IEEE.

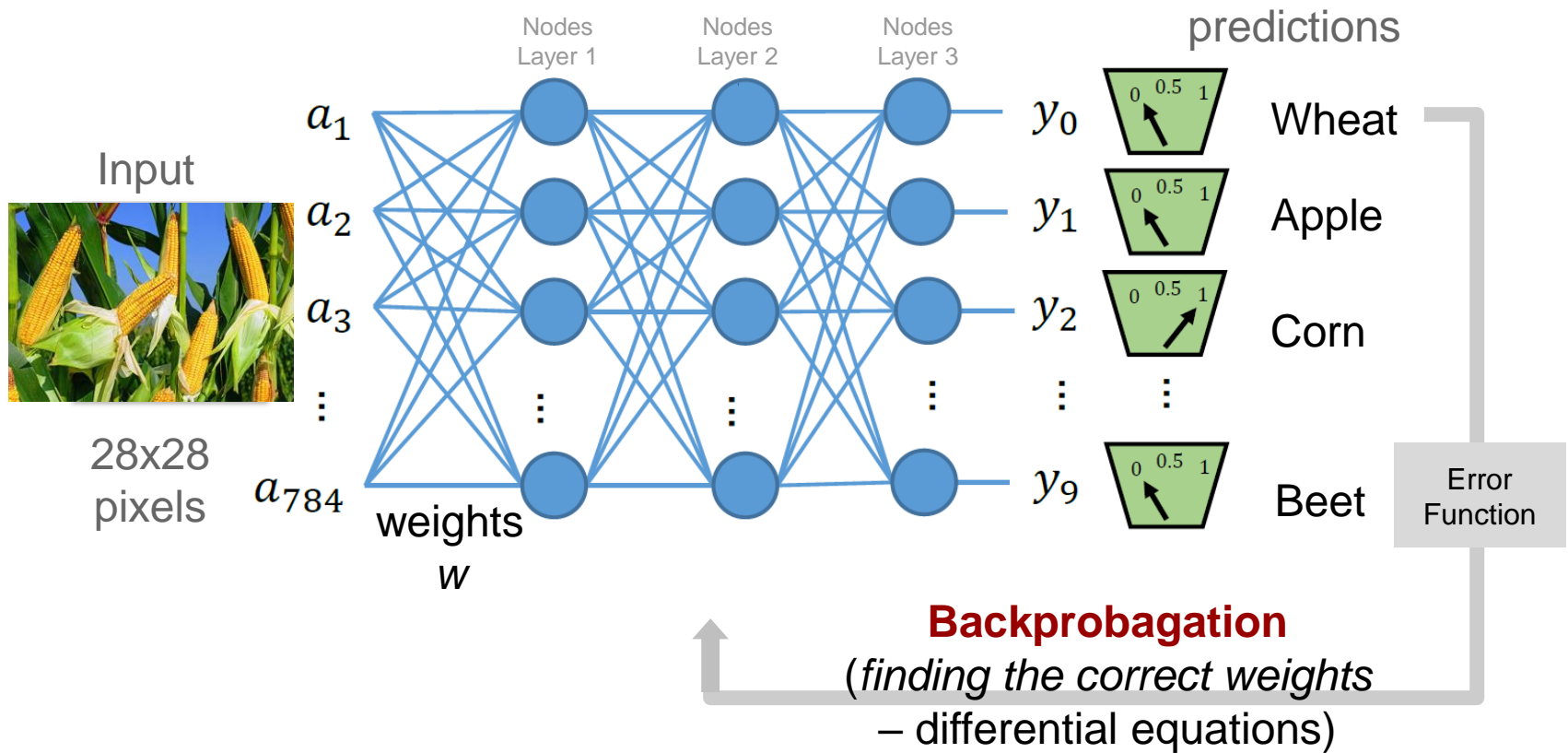
Vegetation Indices

Xue and Su (2017) reviewed 108 common vegetation indices, we selected 9



Deep Learning

Simple model of a deep neural network



Convolutional neural networks

Each layer “learn” a different representation of the data

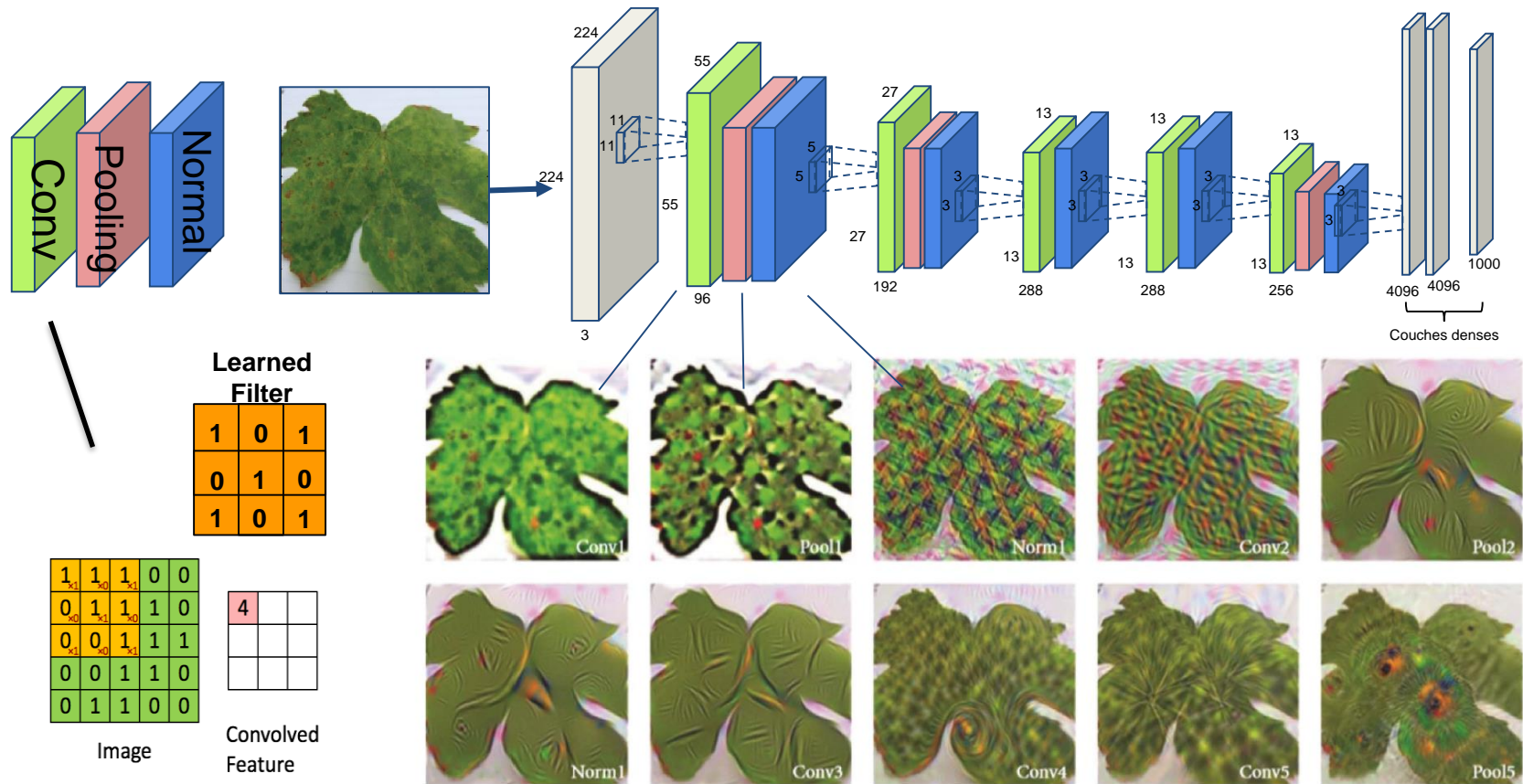
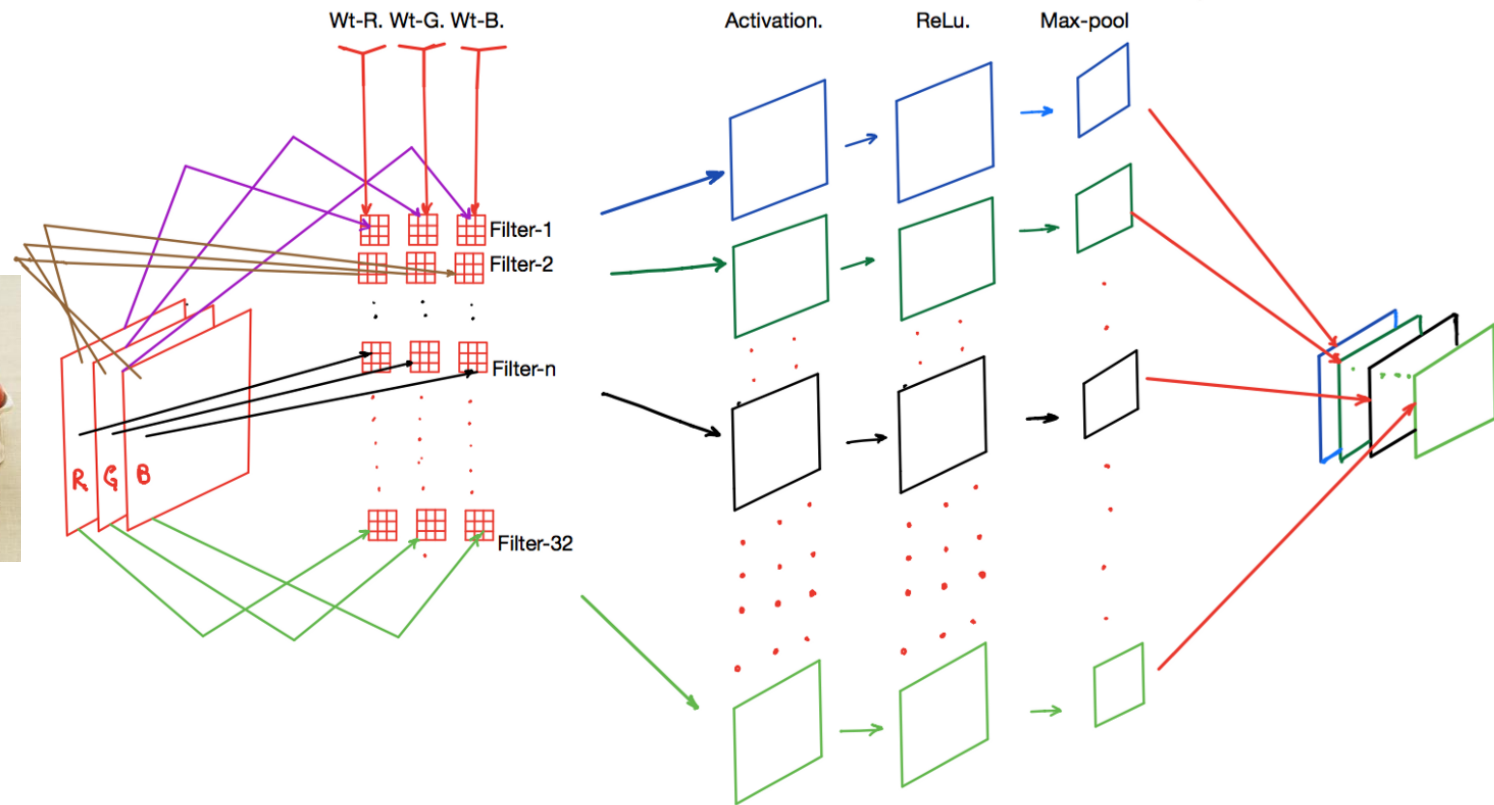


Fig. 2. Visualization of the output layers images after each processing step of the CaffeNet CNN (i.e. convolution, pooling, normalization) at a plant disease identification problem based on leaf images.

Source: Sladojevic et al. (2016).

Convolution layers

A layer where **filters are learned** and applied to each input data. The inverse operation is the **deconvolution**. In this layer, we want to "**learn**" some characteristics of the input data (shape, pattern, etc.).



Convolution layers

Filters are basically "multiplicative" masks applied to the different part of an image.

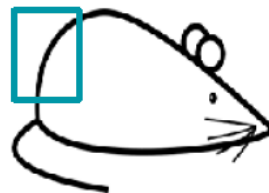
Filter

0	0	0	0	0	30	0
0	0	0	0	30	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	0	0	0	0

Pixel representation of filter



Visualization of a curve detector filter



Visualization of the receptive field

0	0	0	0	0	0	30
0	0	0	0	50	50	50
0	0	0	20	50	0	0
0	0	0	50	50	0	0
0	0	0	50	50	0	0
0	0	0	50	50	0	0
0	0	0	50	50	0	0

Pixel representation of the receptive field

*

0	0	0	0	0	30	0
0	0	0	0	30	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	0	0	0	0

Pixel representation of filter

Multiplication and Summation = $(50*30)+(50*30)+(50*30)+(20*30)+(50*30) = 6600$ (A large number!)



Visualization of the filter on the image

0	0	0	0	0	0	0
0	40	0	0	0	0	0
40	0	40	0	0	0	0
40	20	0	0	0	0	0
0	50	0	0	0	0	0
0	0	50	0	0	0	0
25	25	0	50	0	0	0

Pixel representation of receptive field

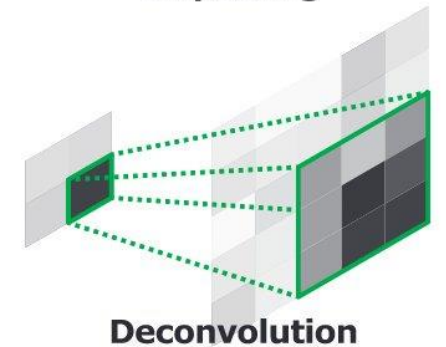
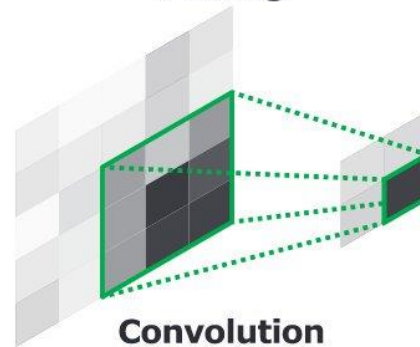
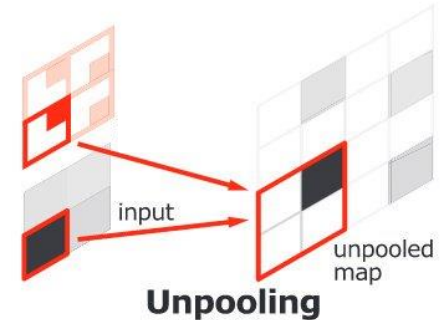
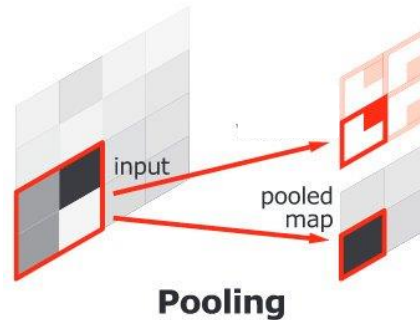
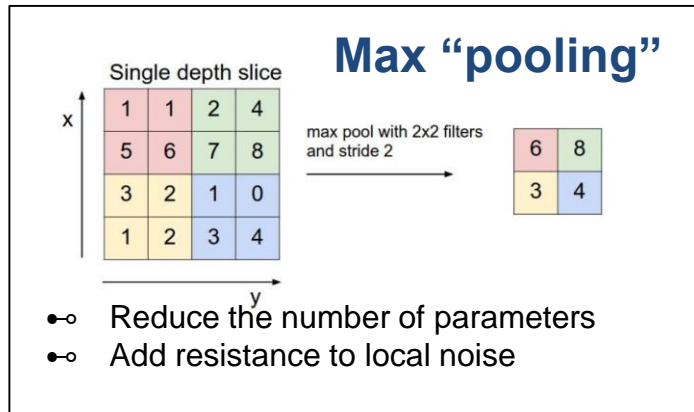
*

0	0	0	0	0	30	0
0	0	0	0	30	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	0	0	0	0

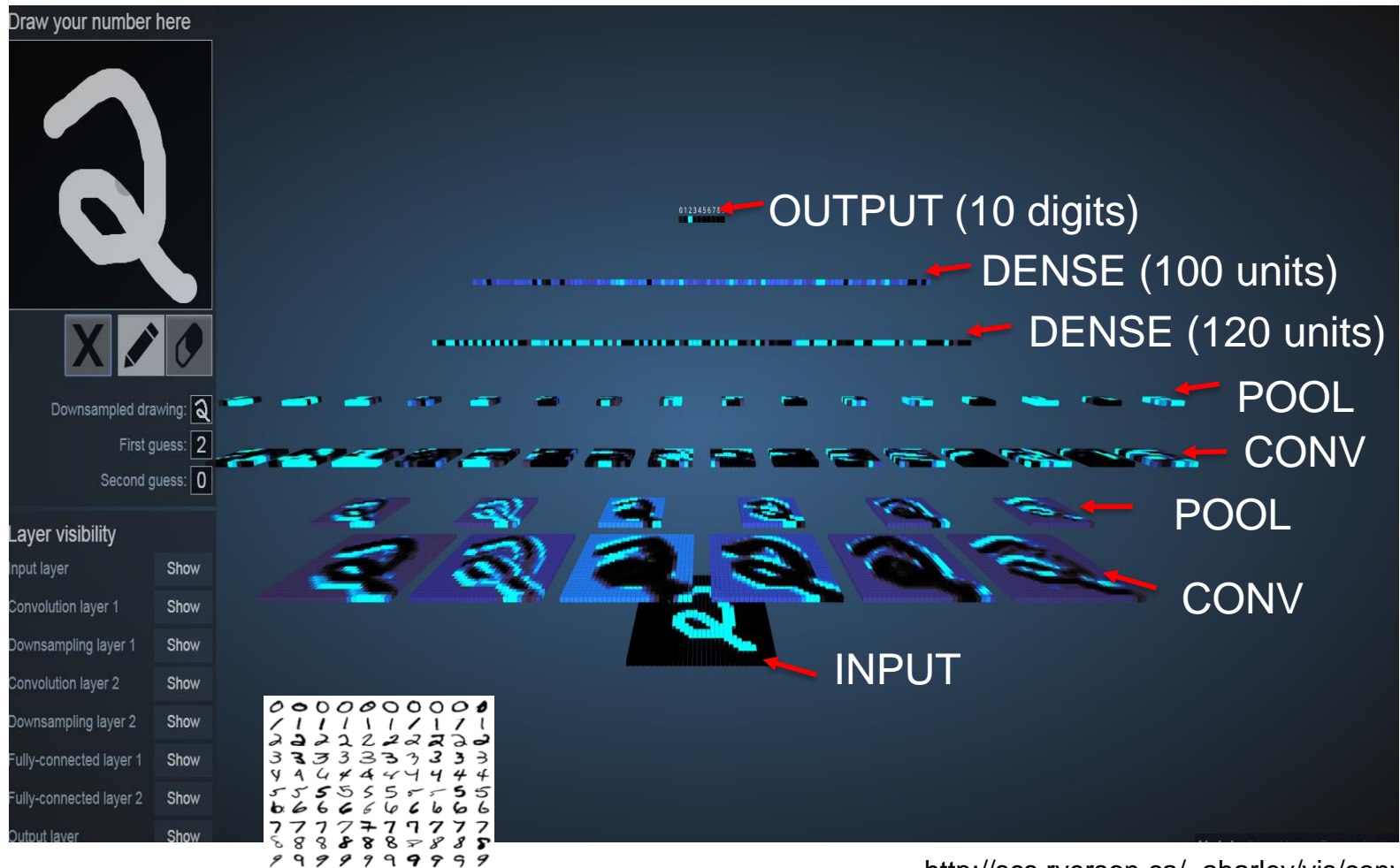
Pixel representation of filter

Multiplication and Summation = 0

Other layer types



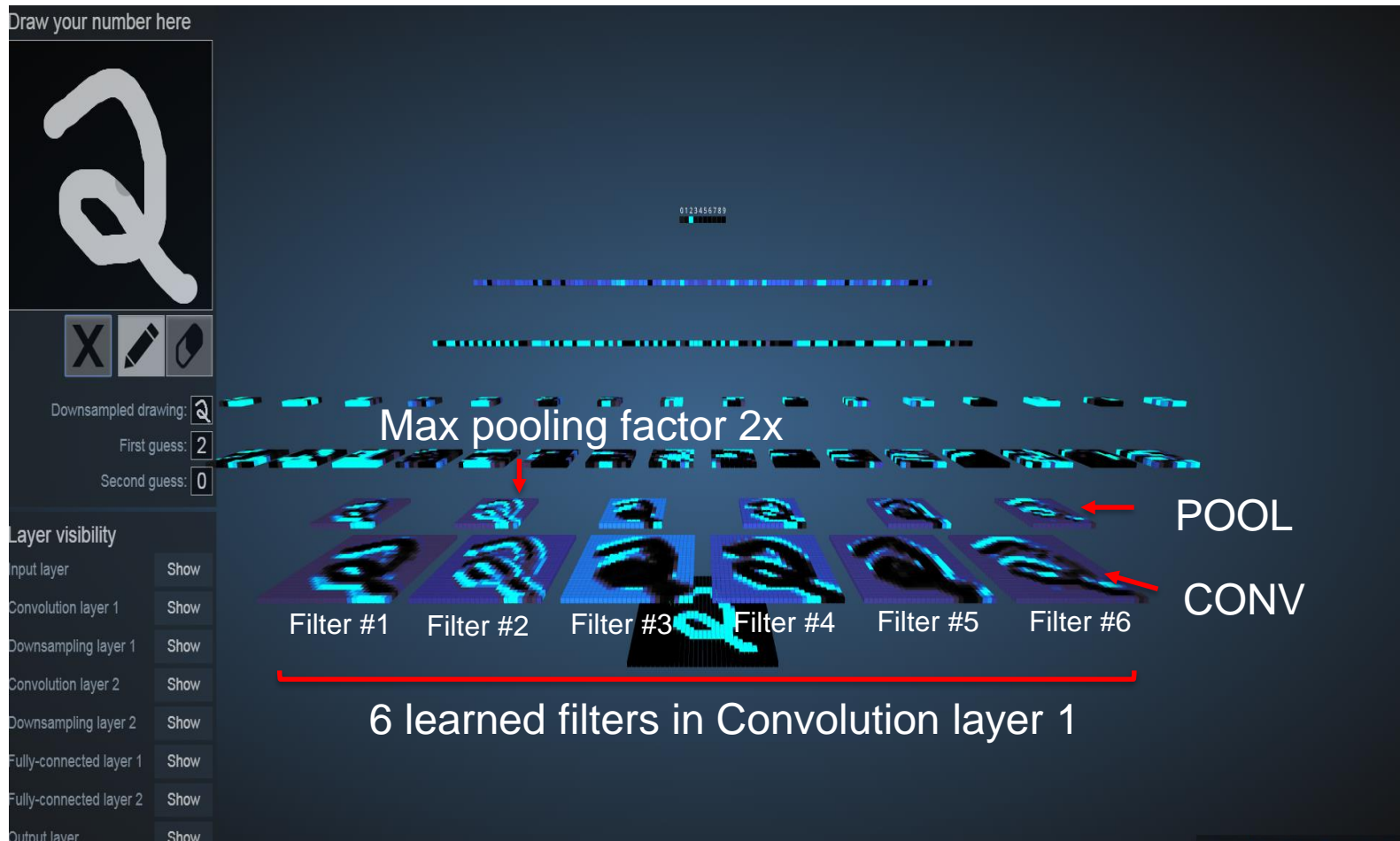
Convolution MNIST example (1/5)



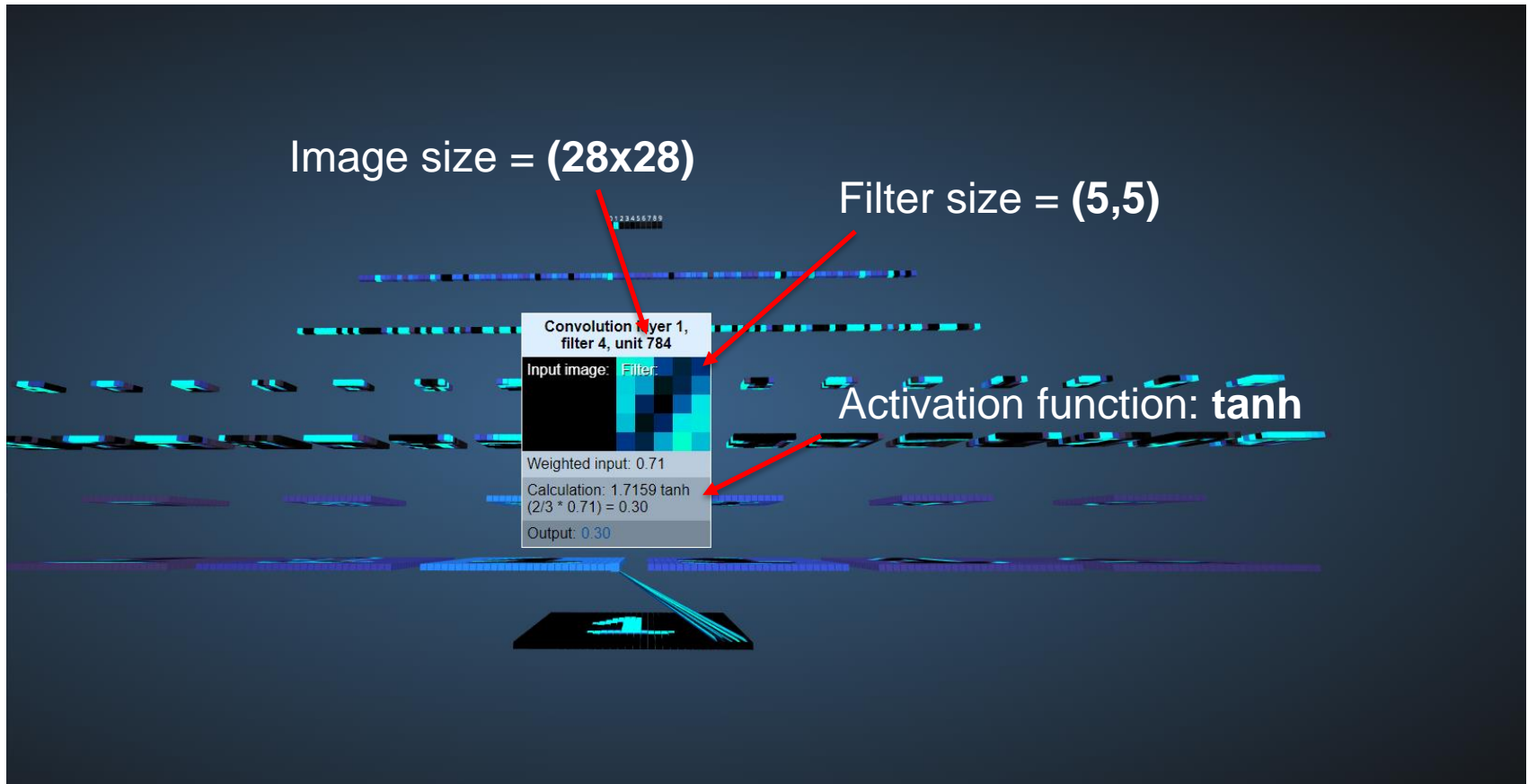
yann.lecun.com/exdb/mnist

<http://scs.ryerson.ca/~aharley/vis/conv/>

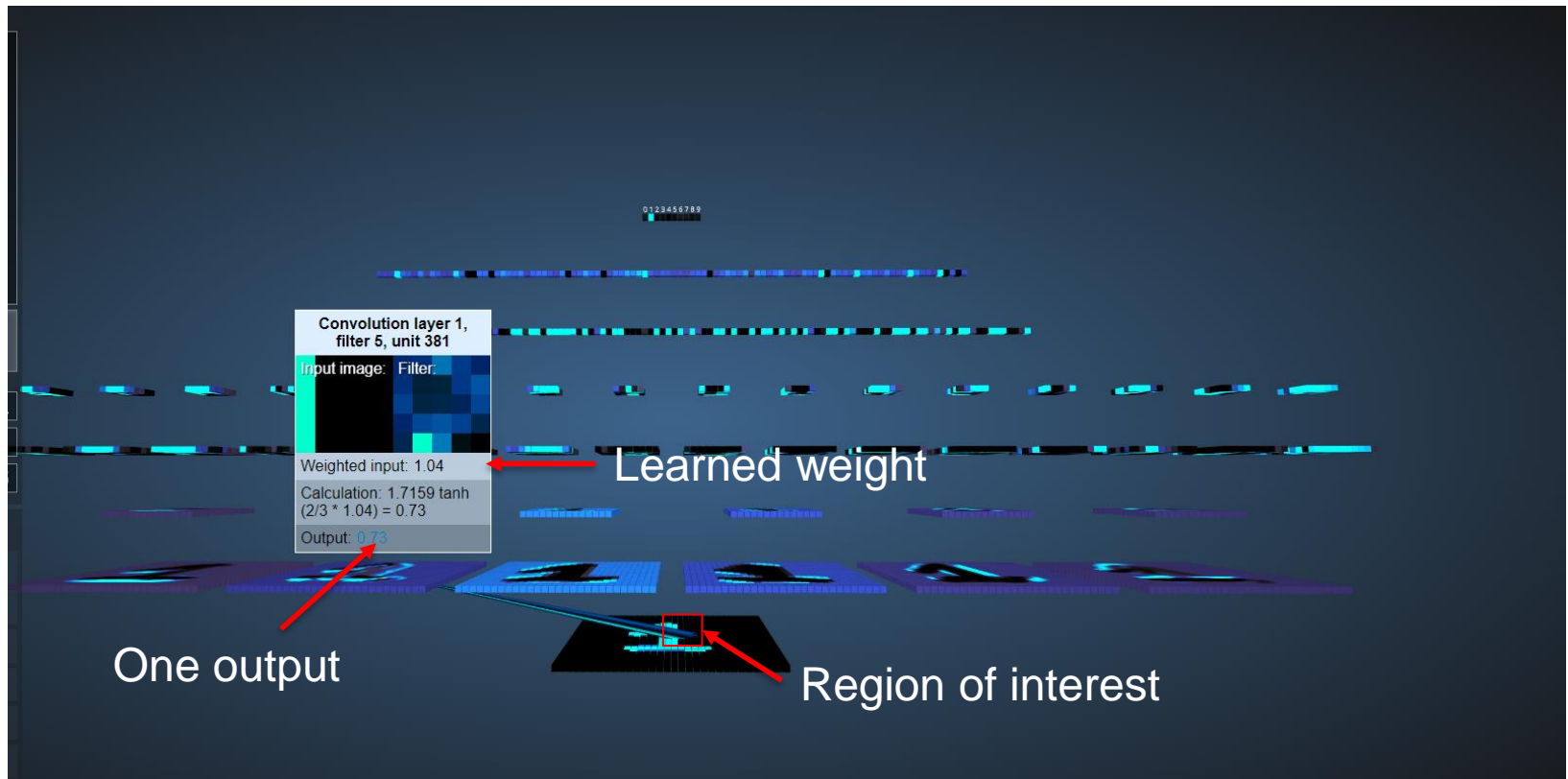
Convolution MNIST example (2/5)



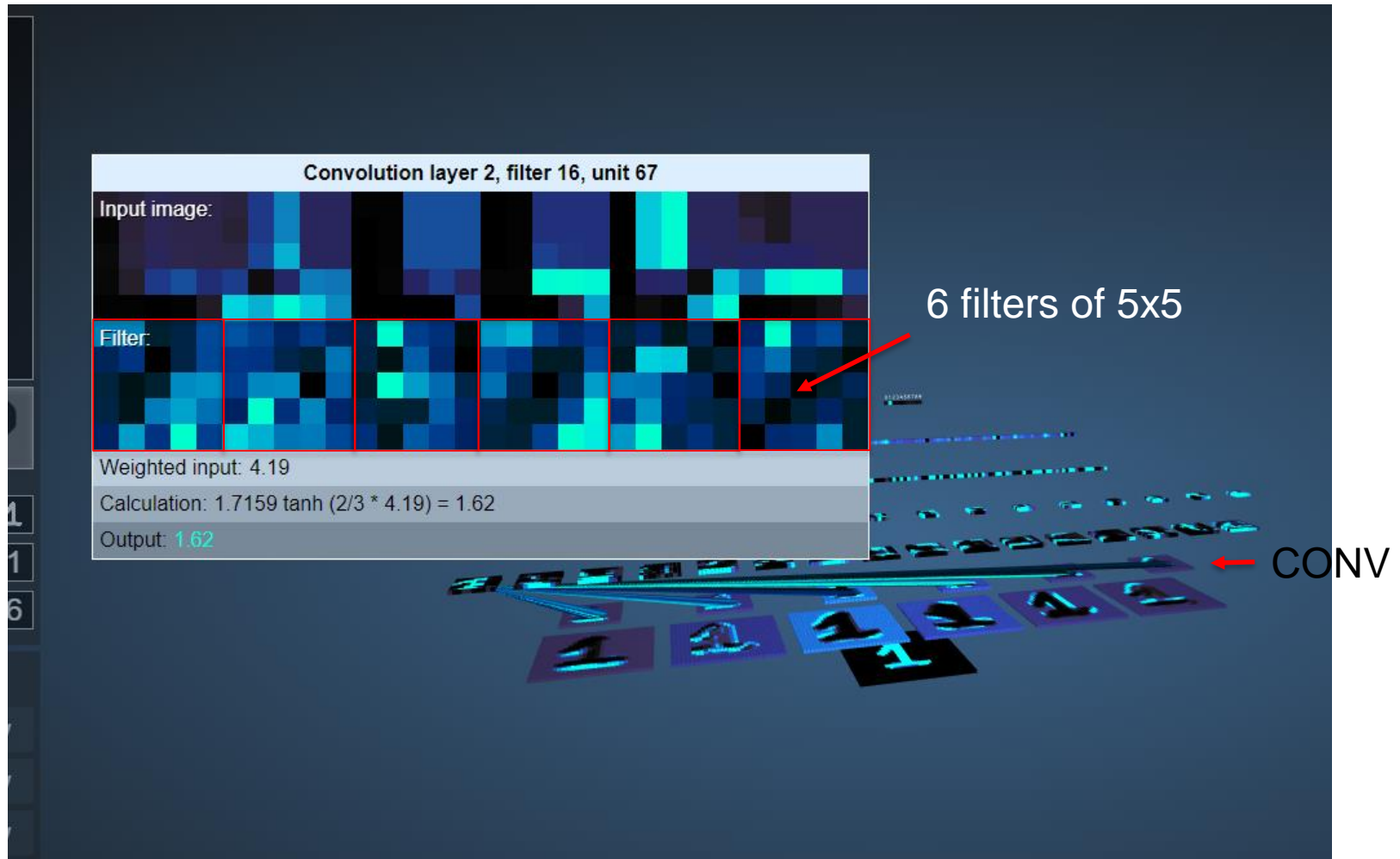
Convolution MNIST example (3/5)



Convolution MNIST example (4/5)



Convolution MNIST example (5/5)



Replicating with Keras



```
model = Sequential()
model.add(Conv2D(6, (5,5), input_shape=(28,28)))
model.add(Activation('tanh'))
model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Conv2D(16, (5,5)))
model.add(Activation('tanh'))
model.add(MaxPooling2D(pool_size=(2, 2)))

# Last layers
model.add(Flatten()) # We flatten to convert 2D to 1D
model.add(Dense(120))
model.add(Activation('tanh'))
model.add(Dense(100))
model.add(Activation('tanh'))
model.add(Dense(10)) # One last cell, the digits 0 to 9
model.add(Activation('tanh'))
```

Number of filters

Filter size

Image size

Activation function

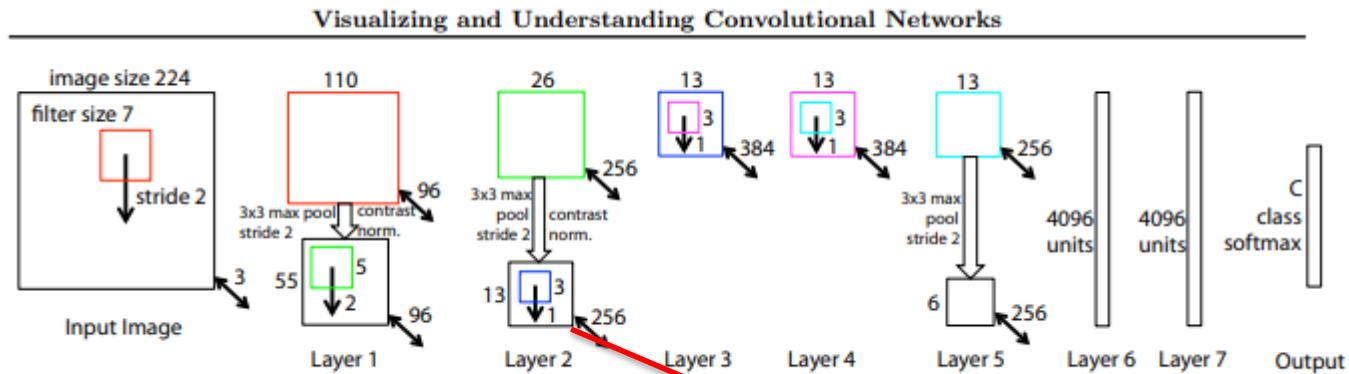
Pool (2x)

LAST LAYERS

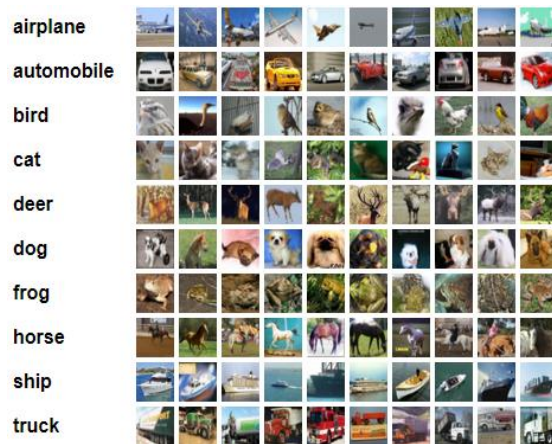
LAYER 2

LAYER 1

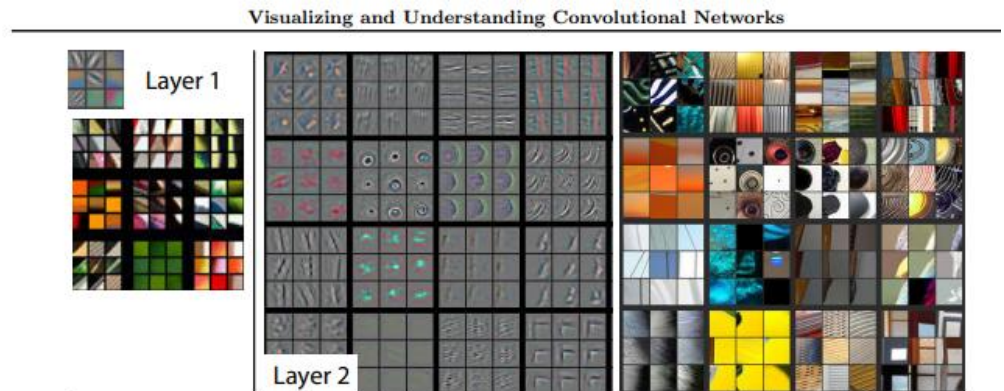
Learning characteristics (1/2)



CIFAR

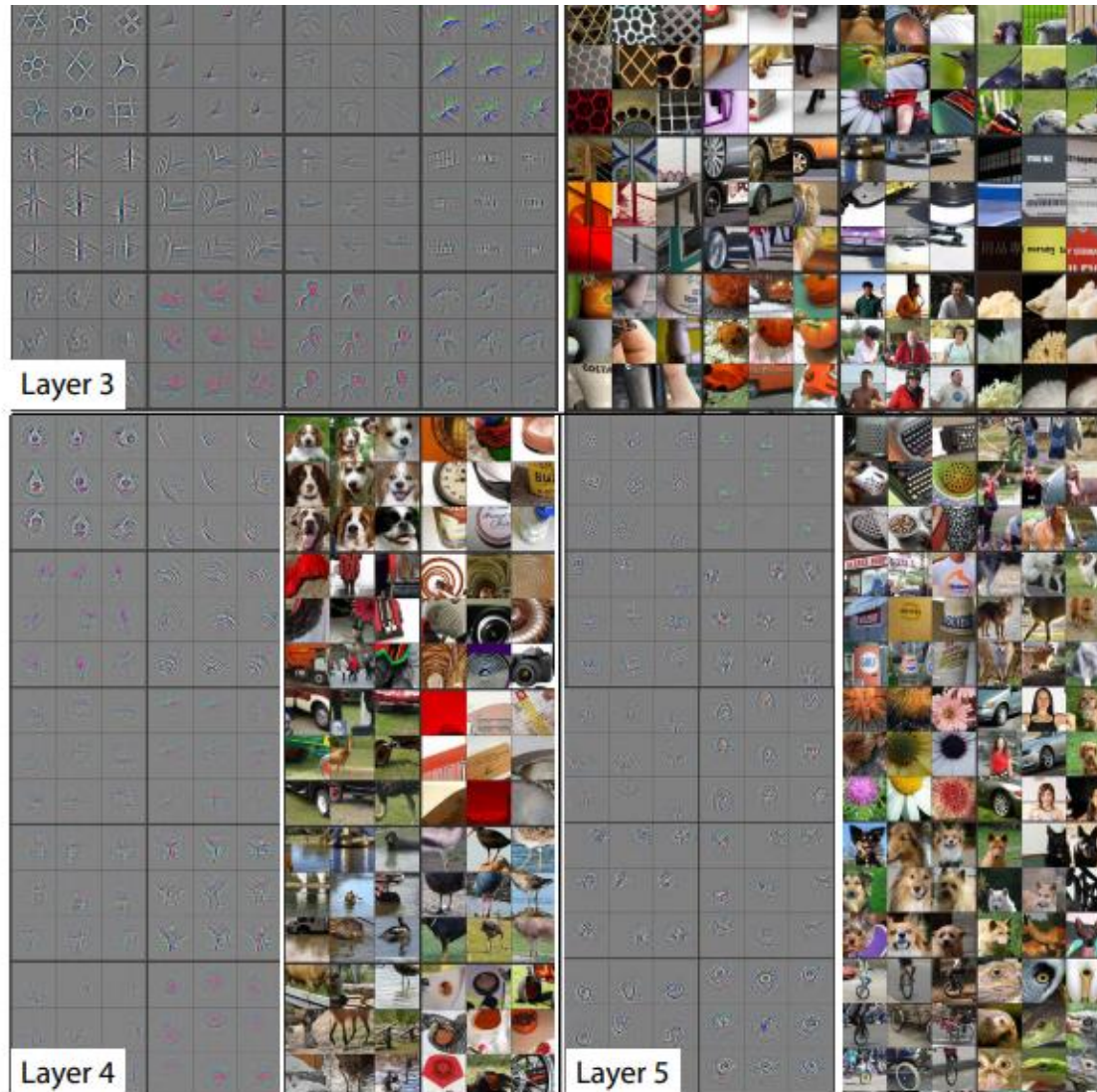


www.cs.utoronto.ca/~kriz/cifar.html



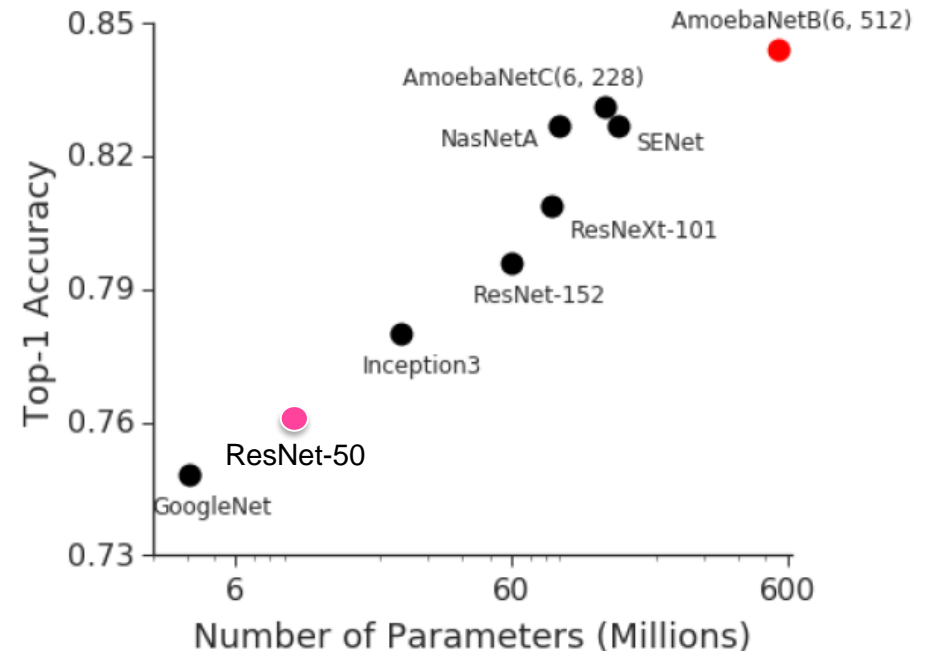
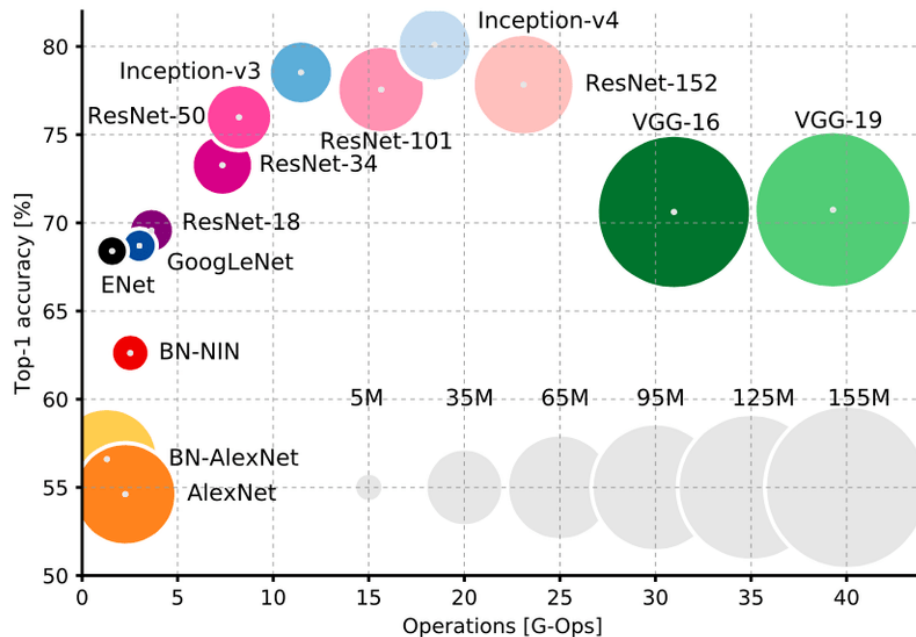
Zeiler, M. D., & Fergus, R. (2014, September). Visualizing and understanding convolutional networks. In *European conference on computer vision* (pp. 818-833). Springer, Cham.

Learning characteristics (2/2)



Transfer learning with ResNet-50

Trade-off between accuracy and number of parameters

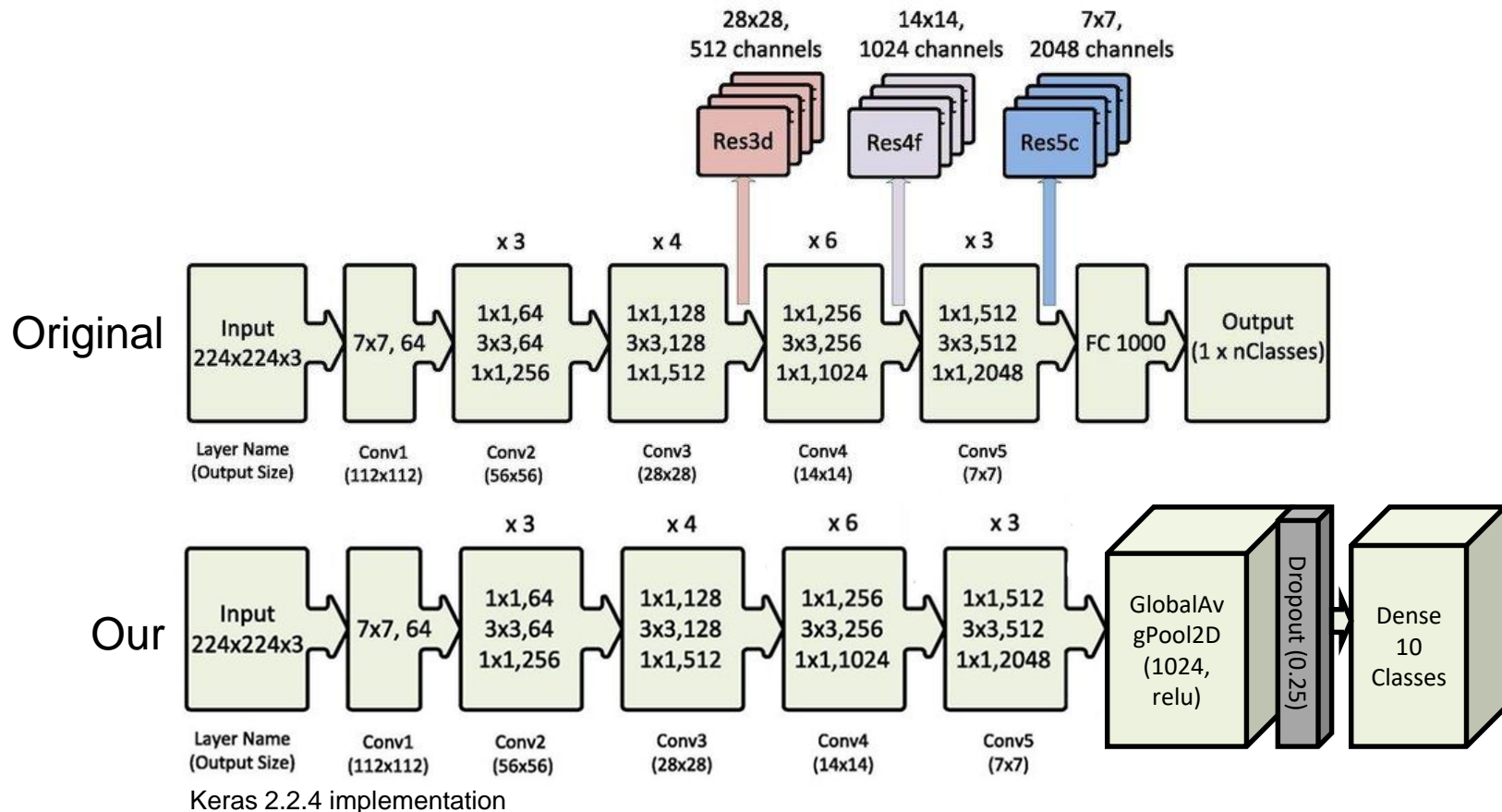


Canziani A, Paszke A, Culurciello E. An analysis of deep neural network models for practical applications. arXiv preprint arXiv:1605.07678. 2016 May 24.

Kornblith S, Shlens J, Le QV. Do better imagenet models transfer better?. arXiv preprint arXiv:1805.08974. 2018 May 23.

ResNet-50 convolutional network

We use transfer learning and added some final layers



Experimental conditions

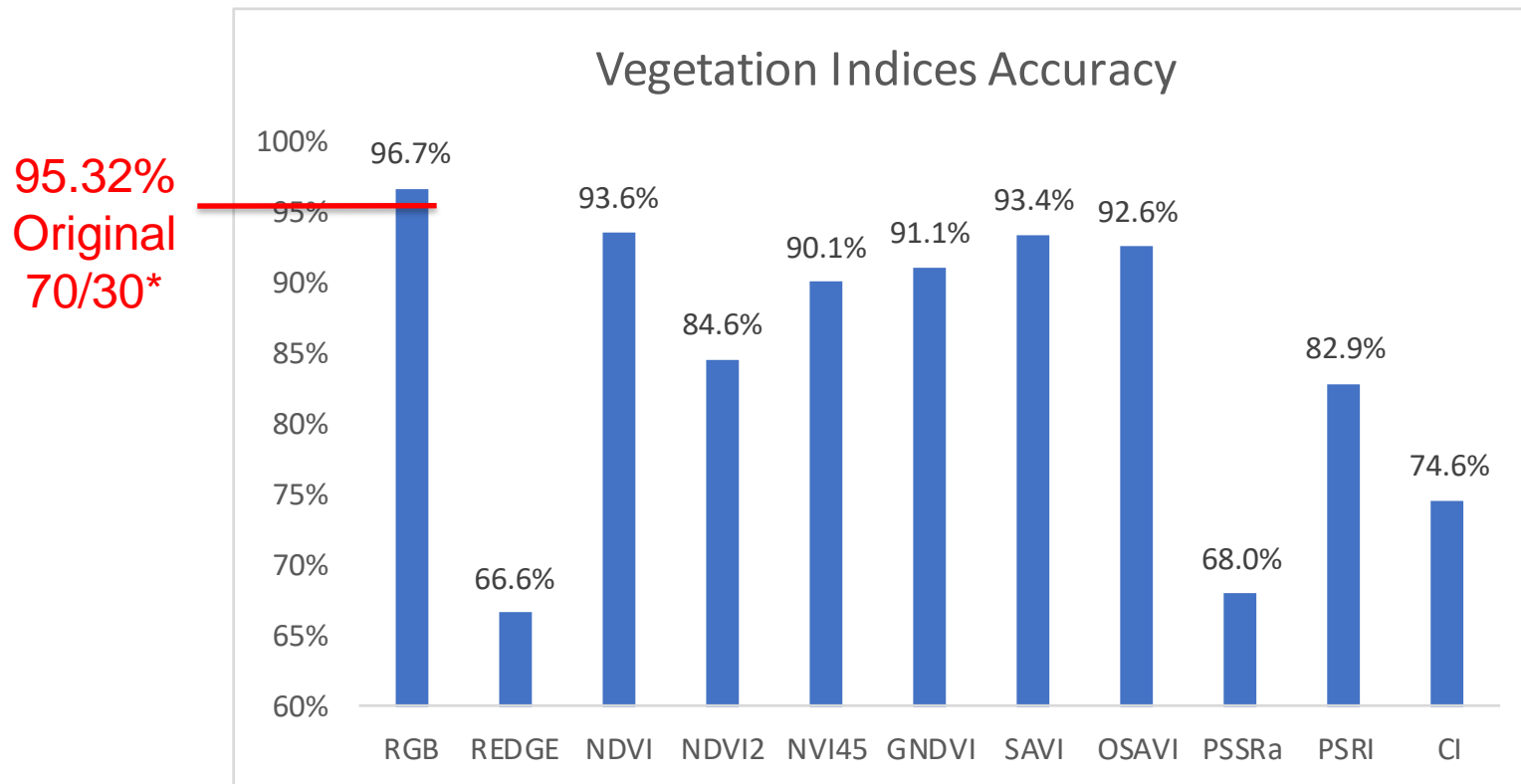
	Training	Validation	
Original article (Helber et al. 2017)	80%	20%	
	Training	Validation	Test
Our	70%	15%	15%
	18900, 10 classes	4050	4050 images

~25 min for each indices with GTX 1050 Ti.

Epochs 1-10: Learning rate: 0.01
Epochs 11-30: Learning rate: 0.0001
Total params: 25,696,138
Total Trainable params: **25,643,018**
Total Non-trainable params: 53,120
API: Keras v2.2.4 with Tensorflow
ResNet-50 on ImageNet with RMSProp
Some image transformations and dropout

Results for convolutional networks

We achieve higher classification accuracy than original article for RGB bands



*98.57% for 80/20 training/test with ResNet-50.

Results for some Vegetation Indices

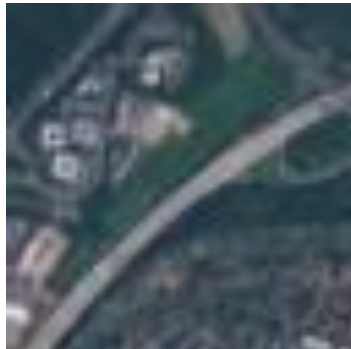
Some classes should have multi-labels

RGB

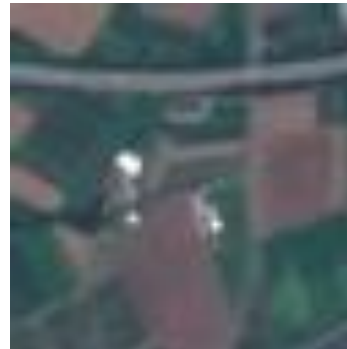
True label	Predicted label									
	AnnualCrop	Forest	Herbaceous	Highway	Industrial	Pasture	PermanentCrop	Residential	River	SeaLake
	AnnualCrop	429	0	0	0	4	2	0	0	4
	Forest	2	440	1	0	0	3	0	0	1
	Herbaceous	2	2	426	0	0	3	2	0	1
	Highway	1	3	3	348	8	1	2	1	7
	Industrial	2	0	0	5	371	0	1	1	0
	Pasture	5	0	3	1	0	253	2	0	3
	PermanentCrop	16	0	32	4	1	1	328	0	0
	Residential	0	0	1	0	10	0	0	419	0
	River	3	1	0	17	2	0	0	0	397
	SeaLake	0	1	0	0	0	0	0	1	472

Predicted label

Highway



Highway



GNDVI

True label	Predicted label									
	AnnualCrop	Forest	Herbaceous	Highway	Industrial	Pasture	PermanentCrop	Residential	River	SeaLake
	AnnualCrop	415	0	1	2	0	13	6	0	1
	Forest	2	429	0	0	0	16	0	0	0
	Herbaceous	4	13	383	1	1	21	9	3	1
	Highway	6	1	3	339	7	3	2	9	4
	Industrial	2	0	0	0	362	0	1	15	0
	Pasture	6	4	1	0	0	255	1	0	0
	PermanentCrop	15	1	20	0	2	10	329	5	0
	Residential	0	0	1	0	13	0	0	416	0
	River	4	1	0	18	3	4	0	0	390
	SeaLake	1	2	0	0	0	1	0	0	470

Predicted label

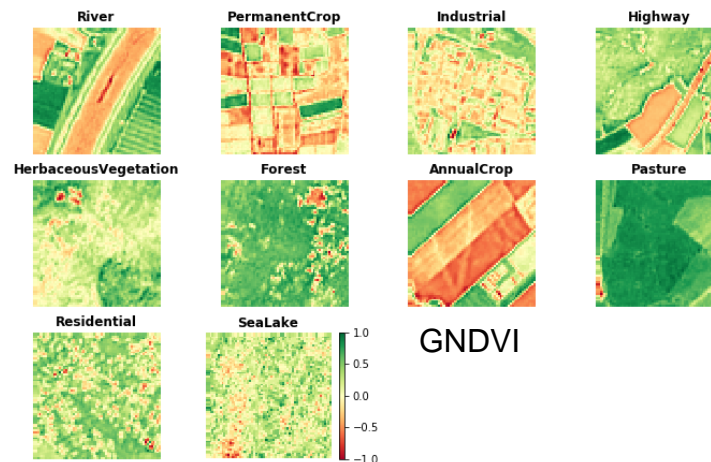
River



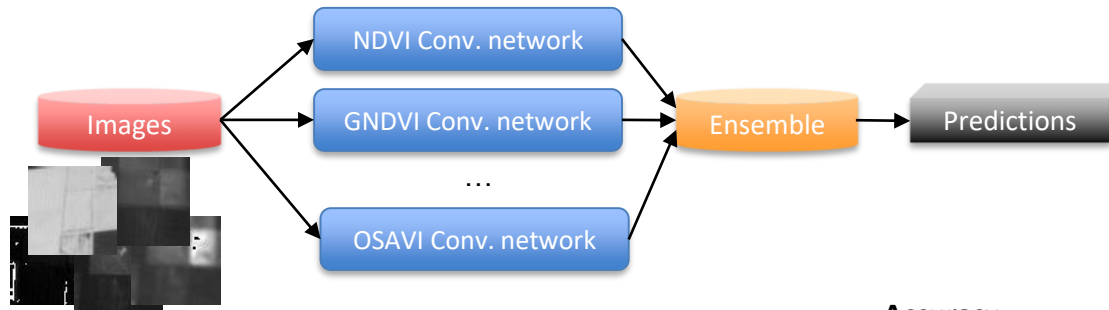
Results for every classes

Some vegetation indices have higher accuracy for some classes

	RGB	REDGE	NDVI	NDVI2	NDI45	GNDVI	SAVI	OSAVI	PSSRa	PSRI	CI
AnnualCrop	0.98	0.79	0.96	0.92	0.90	0.95	0.91	0.94	0.73	0.89	0.81
Forest	0.98	0.75	0.95	0.91	0.99	0.96	0.96	0.97	0.73	0.92	0.70
Herbaceous	0.98	0.62	0.95	0.86	0.80	0.88	0.82	0.96	0.59	0.81	0.70
Highway	0.93	0.42	0.92	0.80	0.84	0.91	0.96	0.95	0.50	0.62	0.70
Industrial	0.98	0.64	0.94	0.89	0.95	0.95	0.94	0.95	0.92	0.77	0.78
Pasture	0.94	0.32	0.80	0.83	0.81	0.95	0.77	0.85	0.31	0.70	0.54
PermanentCrop	0.86	0.42	0.90	0.72	0.85	0.86	0.83	0.77	0.57	0.74	0.42
Residential	0.97	0.71	0.98	0.88	0.97	0.97	0.97	0.98	0.58	0.88	0.87
River	0.95	0.79	0.93	0.80	0.87	0.93	0.94	0.91	0.80	0.95	0.88
SeaLake	1.00	0.99	0.98	0.99	0.99	0.99	0.99	0.93	0.94	0.90	0.97



Ensemble of convolutional networks



												Accuracy
True label	AnnualCrop	2866	22	10	20	3	30	27	0	4	17	98.17%
	Forest	0	2899	14	2	0	13	3	4	0	65	99.03%
	Herbaceous	10	261	2601	12	9	34	40	25	3	5	98.03%
	Highway	7	1	2	2467	7	0	1	1	14	0	98.44%
	Industrial	2	0	1	20	2450	0	0	22	5	0	98.92%
	Pasture	15	102	25	32	5	1627	138	3	5	48	91.40%
	PermanentCrop	44	5	90	19	11	7	2310	14	0	0	90.48%
	Residential	0	1	1	5	23	0	2	2968	0	0	99.50%
	River	2	0	1	54	3	1	0	0	2432	7	96.96%
	SeaLake	3	1	0	1	1	0	0	1	17	2976	96.17%
		AnnualCrop	Forest	Herbaceous	Highway	Industrial	Pasture	PermanentCrop	Residential	River	SeaLake	
Predicted label												

*RGB and Rededge convolutional network not included, over the whole dataset of 27,000 images.

Selection of 3 vegetation indices

Using 3 Vegetation Indices improved the overall classification accuracy by **10.7%** (OSAVI, NDVI, GNDVI) and **18.3%** (NDVI, NDVI2, NDI45) over RGB classification

	OSAVI GNDVI	NDVI NDI45	NDVI NDVI2	All	RGB
AnnualCrop	0.982	0.986	0.956	0.977	
Forest	0.990	0.982	0.966	0.984	
HerbaceousVegetation	0.980	0.978	0.867	0.977	
Highway	0.984	0.973	0.987	0.930	
Industrial	0.989	0.980	0.980	0.976	
Pasture	0.914	0.928	0.814	0.944	
PermanentCrop	0.905	0.962	0.924	0.859	
Residential	0.995	0.997	0.989	0.974	
River	0.970	0.975	0.973	0.945	
SeaLake	0.962	0.986	0.992	0.996	

Conclusions

- The EuroSat sentinel-2 dataset is a good starting point for transfer learning in agriculture/geomatic.
- Other interesting datasets are:
 - UC Merced Land Use Dataset
(<http://weegee.vision.ucmerced.edu/datasets/landuse.html>)
 - Crop/Weed Field Image Dataset
(<https://github.com/cwfid/dataset>)
- Using an ensemble of convolutional neural networks improve the overall accuracy of classification for single class data.